



Tutorial on Fermi-LAT data analysis

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Sexten 2017

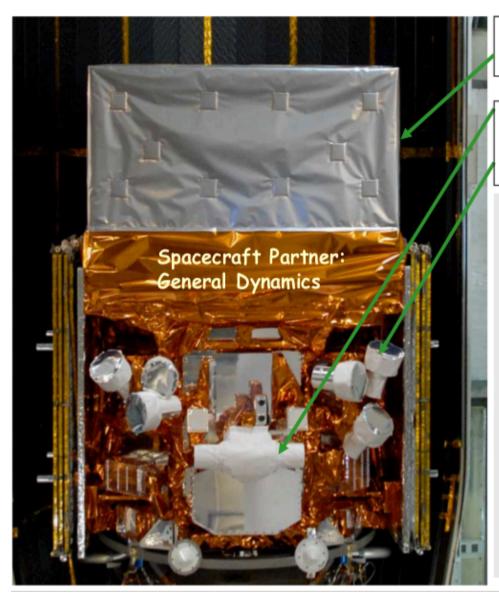
Outline



- Overview of the Fermi Large AreaTelescope
 - How it works
 - LAT data
 - LAT performance
- Fermi Science Tools
 - General Introduction
- Maximum Likelihood Overview
 - Source modeling
- One study case:
 - Crab Nebula: PSR and Nebula analysis



The observatory



Large AreaTelescope (LAT) 20 MeV - >300 GeV

Gamma-ray Burst Monitor (GBM)
NaI and BGO Detectors
8 keV - 30 MeV

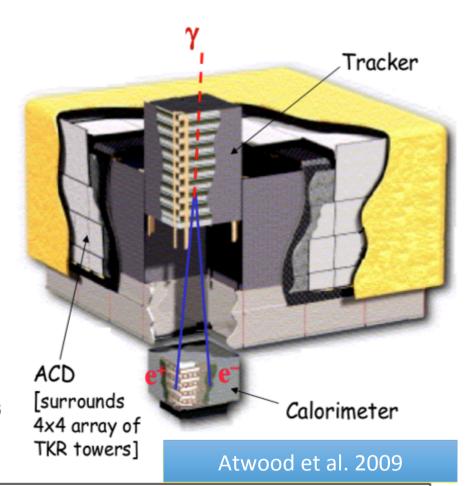
KEY FEATURES

- Huge field of view
 - -LAT: 20% of the sky at any instant; in sky survey mode, expose all parts of sky for ~30 minutes every 3 hours. GBM: whole unocculted sky at any time.
- Huge energy range, including largely unexplored band 10 GeV -100 GeV. Total of >7 energy decades!
- Large leap in all key capabilities.
 Great discovery potential.



How the LAT works

- Precision Si-strip Tracker (TKR) Measure the photon direction; gamma ID.
- Hodoscopic Csl Calorimeter (CAL) Measure the photon energy; image the shower.
- Segmented Anticoincidence
 <u>Detector (ACD)</u> Reject
 background of charged
 cosmic rays; segmentation
 removes self-veto effects at
 high energy.
- <u>Electronics System</u> Includes flexible, robust hardware trigger and software filters.



Systems work together to identify and measure the flux of cosmic gamma rays with energy 20 MeV - >300 GeV.



Operating Mode

Primary observing mode is Sky Survey

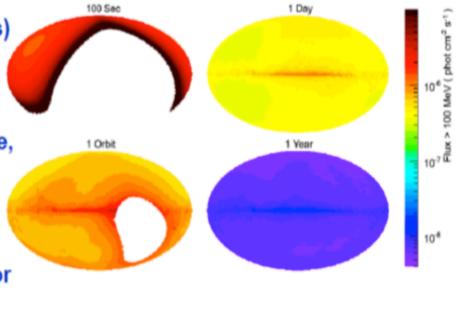
Full sky every 2 orbits (3 hours)

 Uniform exposure, with each region viewed for ~30 minutes every 2 orbits

 Best serves majority of science, facilitates multiwavelength observation planning

 Exposure intervals commensurate with typical instrument integration times for sources

 EGRET sensitivity reached in days



- Pointed observations when appropriate (selected by peer review in later years) with automatic earth avoidance selectable. Target of Opportunity pointing.
- Autonomous repoints for onboard GRB detections in any mode.



What do you need for the analysis

LAT DATA ARE PUBLIC!!

•Data ...of course!

- -LAT detected events
- –Spacecraft related stuff
- –Extras (Backgrounds, catalog sources, timing..)

Fermi Science Tools

- http://fermi.gsfc.nasa.gov/ssc/data/analysis/software/

Other ancillary tools

- ftools, HEASOFT, DS9 etc..
- http://heasarc.gsfc.nasa.gov/docs/software.html

•Lots and lots of scripts!

- Fermi tools are already scriptable
- You can also use your favourite scripting language... but ..
- Science Tools can be imported as Python modules!



LAT data analysis references



Fermi Data Analysis: starting points

Fermi Science Support Center: http://fermi.gsfc.nasa.gov/ssc/

Fermi Newsletters: http://fermi.gsfc.nasa.gov/ssc/resources/newsletter/

Fermi Data Access: http://fermi.gsfc.nasa.gov/cgi-bin/ssc/LAT/LATDataQuery.cgi

Fermi Science Tools Reference Manual:

http://fermi.gsfc.nasa.gov/ssc/data/analysis/scitools/references.html

Fermi Analysis Threads:

http://fermi.gsfc.nasa.gov/ssc/data/analysis/scitools/ http://fermi.gsfc.nasa.gov/ssc/data/analysis/documentation/Cicerone/

Fermi - LAT Likelihood Algorithm description

http://fermi.gsfc.nasa.gov/ssc/data/analysis/documentation/Cicerone_Likelihood/

Cash W. 1979, ApJ 228, 939

Mattox J. R. et al 1996, ApJ 461, 396

Protassov et al. 2002, ApJ 57, 545

LAT Performance Page: http://www-glast.slac.stanford.edu/software/IS/glast_lat_performance.htm

The Large Area Telescope on the Fermi Gamma-Ray Space Telescope Mission, W.B. Atwood, et. al., ApJ, 2009, 695, 1071

1071.

The On-orbit Calibrations for the Fermi Large Area Telescope, A.A. Abdo, et al. arXiv:0904.2226v1



How to access LAT Data

http://fermi.gsfc.nasa.gov/ssc/data/analysis/

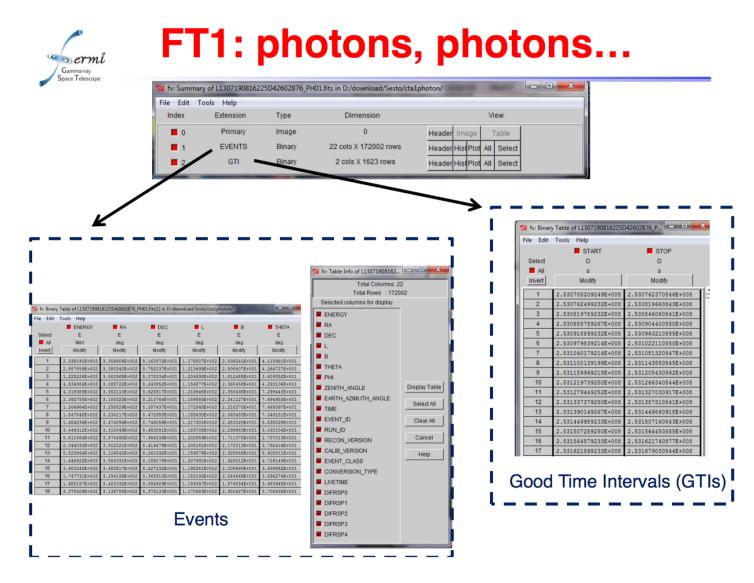


Gamma-ray Space Telescope

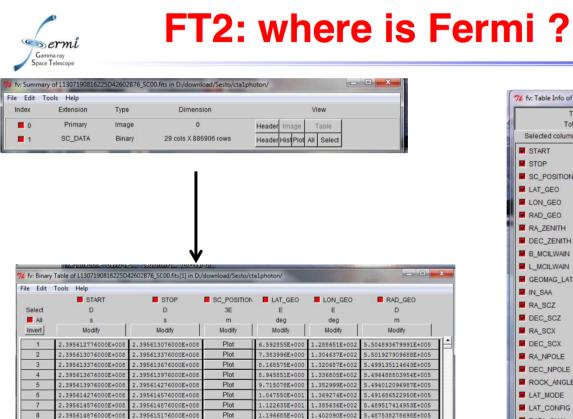
LAT Data

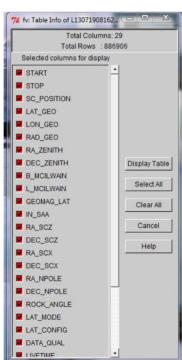
- LAT data products can be downloaded by the FSSC website
- -LAT Data server http://fermi.gsfc.nasa.gov/cgi-bin/ssc/LAT/LATDataQuery.cgi
- –Archive of weekly files
- -ftp://legacy.gsfc.nasa.gov/fermi/data/
- Two main data products (stored in FITS format)
- –Events file (FT1)
- -i. e. "what the LAT sees"
 - (photons, their energy, coordinates, time, event classes etc..)
- -Spacecraft files (FT2)
- -i. e. "where the LAT is"
 - (position, angles..)











spacecraft Data

L.269626E+00

1.341378E+00

1.411865E+001

1.481007E+001

1.548726E+001

1.435296E+002

1.452058E+002

1.468931E+002

.485701226070E+005

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1.485919E+002 5.479706011147E+005

Plot

Plot

Plot

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2.395615476000E+008

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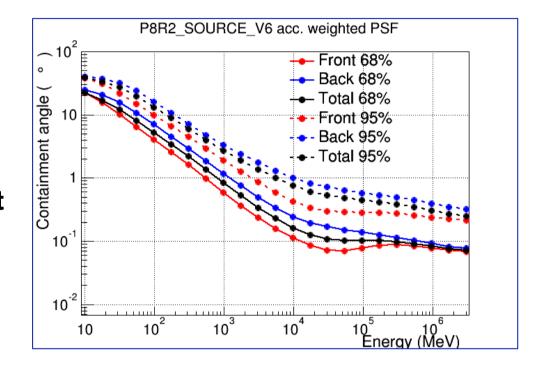
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Extras - IRFs

- LAT Instrument Response Functions (IRFs)
- -Point Spread Function (PSF)
- -Effective Area
- -Energy Resolution
- Highly dependent on energy
- and arrival direction of incident
- •photon



•Fundamental for analysis!!

•http://www.slac.stanford.edu/exp/glast/groups/canda/lat_Performance.htm



Pass8 data



Pass8 data



Data

- ▶ Data Policy
- ▶ Data Access
- ▶ Data Analysis
 - + System Overview
 - + Software Download
 - + Documentation
 - + Cicerone
 - + Analysis Threads
 - + User Contributions
- ▶ Caveats
- Newsletters
- ▶ FAQ

Using LAT's New Pass 8 Data

The FSSC is now serving Pass 8 LAT data for analysis. The new version of LAT data provides a number of improvements over the reprocessed Pass 7 data, and is considered the best dataset for all types of LAT analysis. As of the release date (June 24, 2015) reprocessed Pass 7 data is no longer being served. However, existing Pass 7 reprocessed data has been archived and is available from the FSSC's FTP server.

Pass 8 provides a full reprocessing of the entire mission dataset, including improved event reconstruction, a wider energy range, better energy measurements, and significantly increased effective area. In addition, the events have been evaluated for their measurement quality in both position and energy. This allows the user to select a subset of the events if appropriate to improve analysis results. To support the use of these data selections, there have been some structural changes to the *Fermi* Science Tools.

Here we discuss the changes to the data and tools, and how they affect your analysis.

Pass 8 Bottom Line



Pass 8 contains a lot of changes, and the rest of this page may seem overwhelming. If you just want to get started doing a standard LAT analysis, here's the bottom line:

- Recommended event class for source analysis is "P8 Source" class (evclass=128).
- Add evtype parameter to your gtselect call (convtype parameter is deprecated).
 Recommended event type for source analysis is "FRONT+BACK" (evtype=3).
- Recommended zenith angle cut to eliminate Earth limb events ("zmax") is 90 degrees for events at 100 MeV and above.
- Recommended source list for analysis is the 3FGL Catalog. A python script is available at the User-Contributed Tools page that creates XML model files using the 3FGL catalog FITS file.

http://fermi.gsfc.nasa.gov/ssc/data/analysis/documentation/Pass8_usage.html



What does Pass mean?

- Each pass corresponds to a version of the Fermi LAT data
- It implies a whole package:
 - Intrument simulation
 - Reconstruction code
 - Event selection
 - Instrument Response Functions (IRFs)
 - Systematic uncertainties
 - Isotropic template (which includes the cosmic-ray residual background)
 - And sometimes more (Galactic diffuse model, Earth limb template, Sun+Moon template)
- It's only when we have validated the whole package that we can release it to the public.

Gamma-ray Space Telescope

Pass8 introduction

From Pass 6 to Pass 8

- Pass 6 (launch time)
 - Pass 6 reconstruction
 - Pass 6 selection
 - Based on pre-launch instrument simulation
 - First data revealed the issue of out-of-time pile-up (aka ghosts)
 - New: instrument simulation with ghosts -> correct IRFs
- Pass 7
 - Pass 6 reconstruction
 - New: Pass 7 selection optimized with simulations with ghosts
- Pass 8
 - New: improved instrument simulation
 - New: Pass 8 reconstruction, as ghost-proof as possible
 - New: Pass 8 selection

Pass8 Introduction



Pass 8 improvements

- Ghost handling
 - Tracker: ignoring ghost hits
 - ACD: partial deghosting
 - Calorimeter: clustering and cluster classification
- Improved direction measurement
 - Tree-based track finder
- Improved energy measurement
 - Extension of the energy range: from ~10 MeV to ~3 TeV
- Improved track/ACD matching information
 - Using the uncertainty of the tracker direction
- Improved event selection
 - Using the ROOT TMVA package (tmva.sourceforge.net)
- Additional sub-classes of events

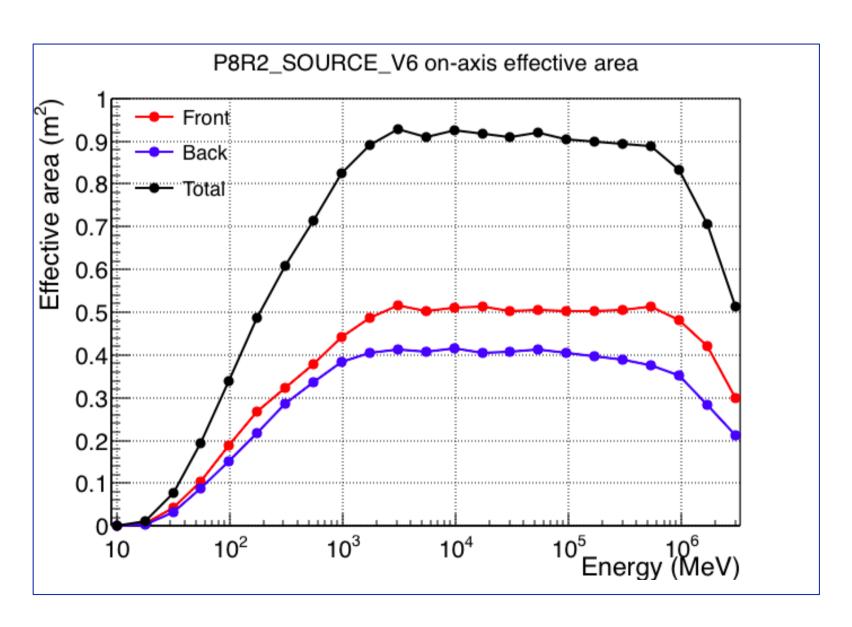


Pass8 performance

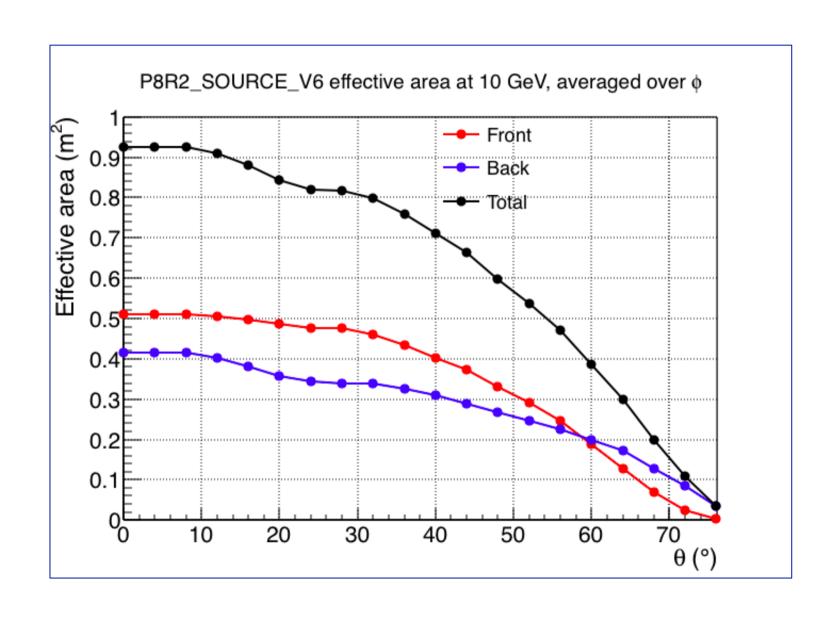
http://www.slac.stanford.edu/exp/glast/groups/canda/lat_Performance.htm



Effective Area

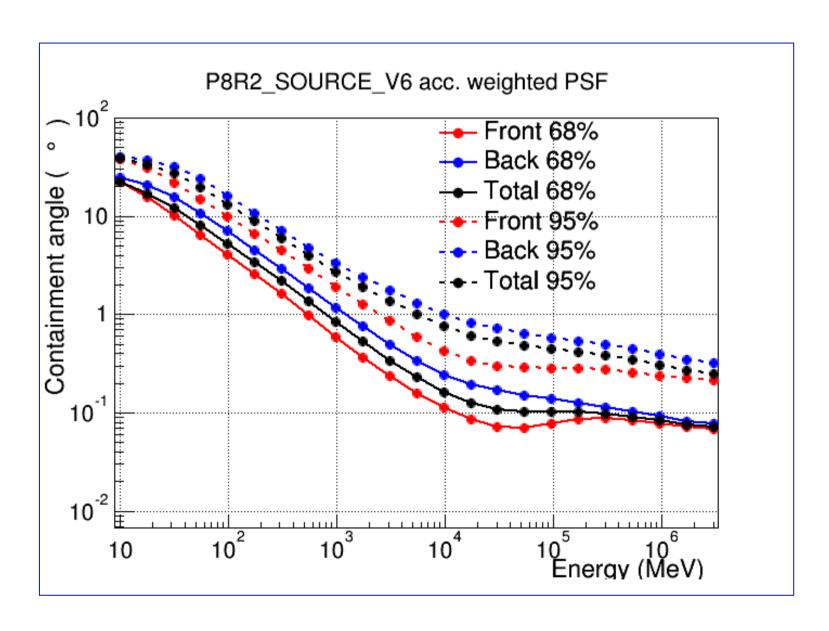


Pass8 Effective Area

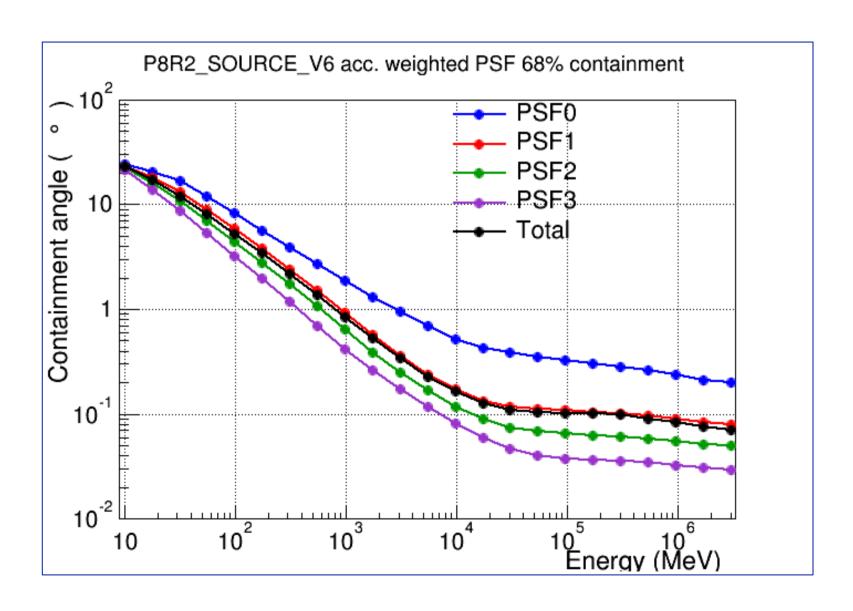




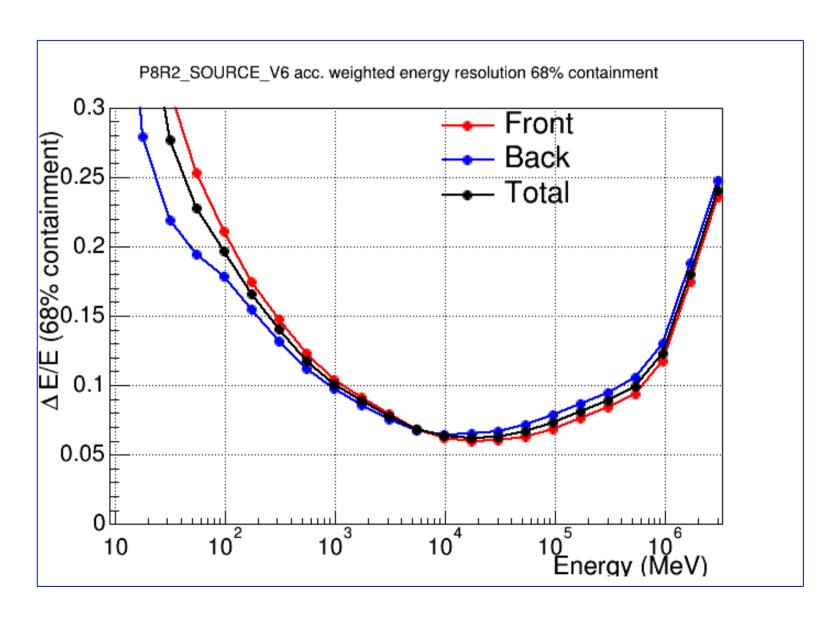
Point Spread Function



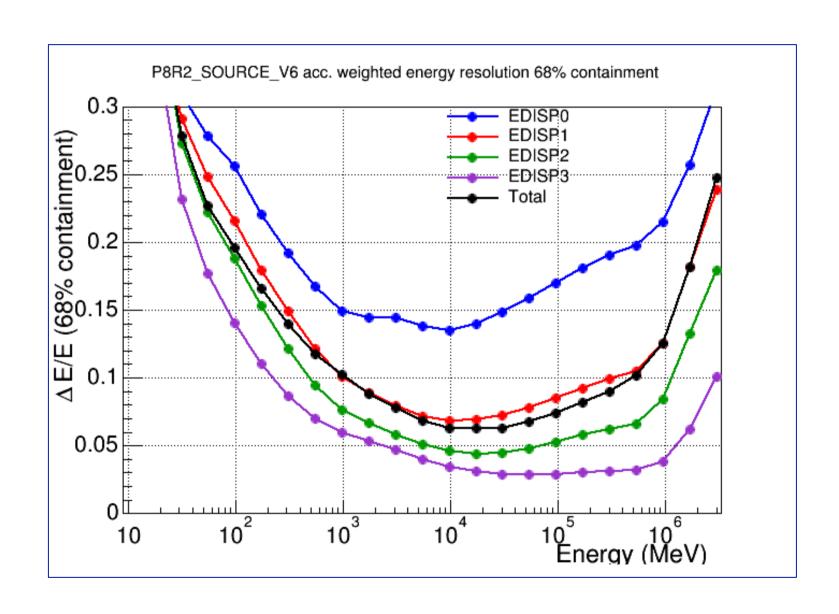
Point Spread Function



Energy resolution



Energy resolution



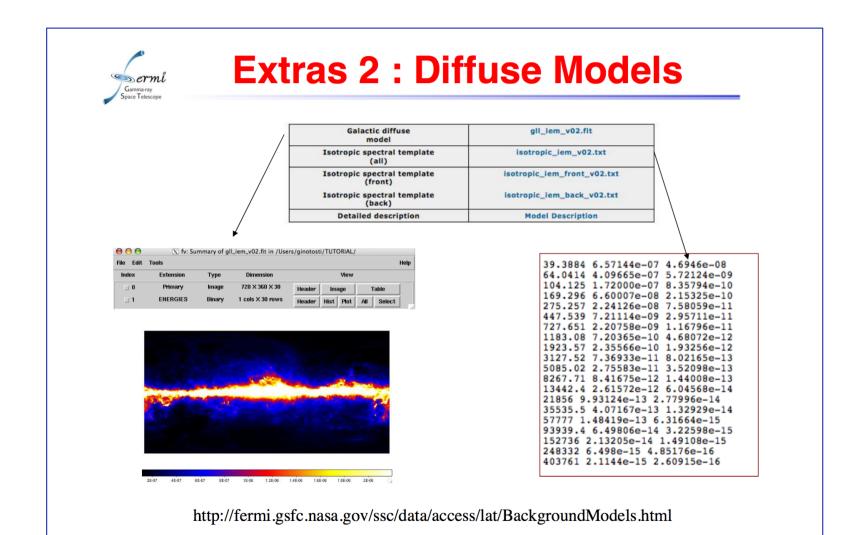


Extras

- Diffuse models (.txt & FITS files)
- —To correctly take into accounts the galactic and extagalactic backgrounds
- -http://fermi.gsfc.nasa.gov/ssc/data/access/lat/BackgroundModels.html
- Source Catalogs (3FGL, 3FHL, PSRs, GRB, SNR ...)
- Region of Interest model definition (stored in XML files)
 - More on this later ...
- Choose the proper combination of
 - event classes based on the probability of being a photon and background level
 - TRANSIENT (for very short events)
 - SOURCE (suggested for source analysis)
 - CLEAN and ULTRACLEAN (lowest particle contamination for diffuse sources analysis)
 - Event types based on conversion point or PSF or Energy reconstruction

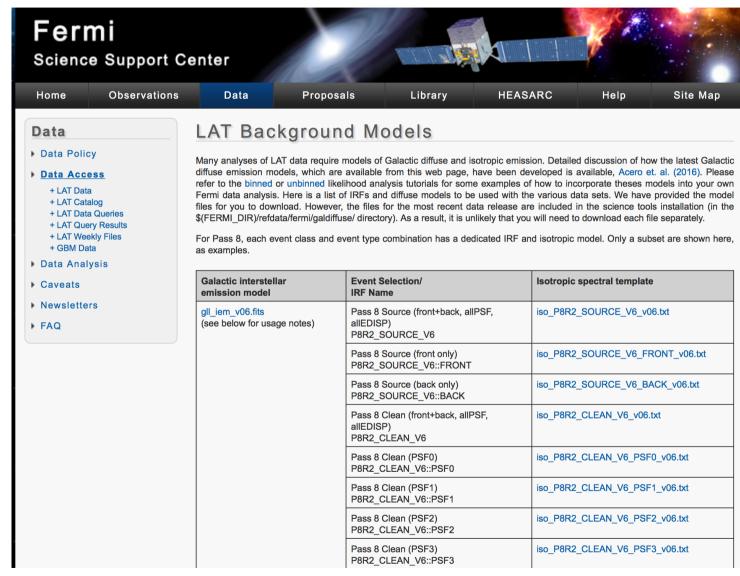


LAT background models



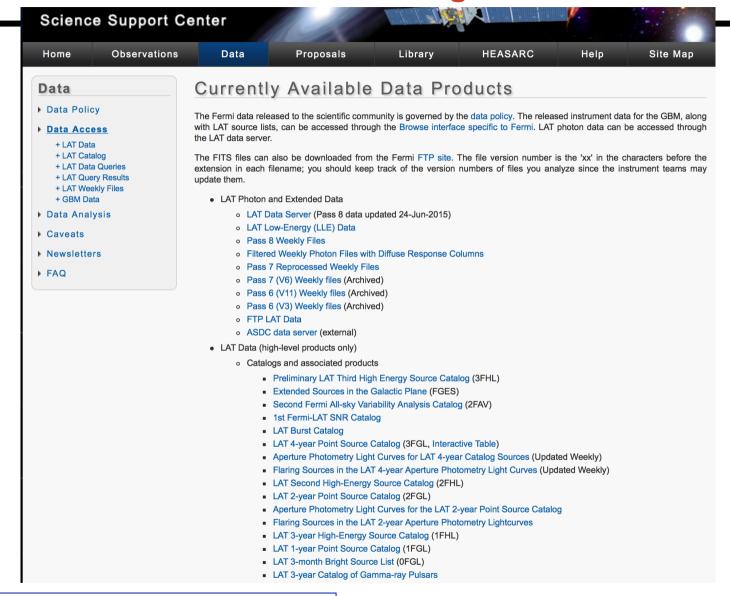


LAT background models





LAT catalogs



https://fermi.gsfc.nasa.gov/ssc/data/access/



Event types

P8R2 Event Type Name	Event Type Partition	Event Type Value (evtype)	
FRONT	Conversion Type	1	
BACK	Conversion Type	2	
PSF0	PSF	4	
PSF1	PSF	8	
PSF2	PSF	16	
PSF3	PSF	32	
EDISP0	EDISP	64	
EDISP1	EDISP	128	
EDISP2	EDISP	256	
EDISP3	EDISP	512	



Event classes

P8R2 IRF name	Event Class (evclass)	Class Hierarchy	Photon File	Extended File
P8R2_ULTRACLEANVETO_V6	1024	Standard	X	Х
P8R2_ULTRACLEAN_V6	512	Standard	Х	Х
P8R2_CLEAN_V6	256	Standard	Х	Х
P8R2_SOURCE_V6	128	Standard	Х	Х
P8R2_TRANSIENT010_V6	64	Standard		Х
P8R2_TRANSIENT020_V6	16	Standard		Х
P8R2_TRANSIENT010E_V6	64	Extended		Х
P8R2_TRANSIENT020E_V6	8	Extended		Х
P8R2_TRANSIENT015S_V6	65536	No-ACD		Х



Recommendations

Event Selection Recommendations (P8R2)

Analysis Type	Minimum Energy (emin)	Maximum Energy (emax)	Max Zenith Angle (zmax)	Event Class (evclass)	IRF Name
Galactic Point Source Analysis	100 (MeV)	500000 (MeV)	90 (degrees)	128	P8R2_SOURCE_V6
Off-plane Point Source Analysis	100 (MeV)	500000 (MeV)	90 (degrees)	128	P8R2_SOURCE_V6
Burst and Transient Analysis (<200s)	100 (MeV)	500000 (MeV)	100 (degrees)	16	P8R2_TRANSIENT020_V6
Galactic Diffuse Analysis	100 (MeV)	500000 (MeV)	90 (degrees)	128	P8R2_SOURCE_V6
Extra-Galactic Diffuse Analysis	100 (MeV)	500000 (MeV)	90 (degrees)	1024	P8R2_ULTRACLEANVETO_V6
Impulsive Solar Flare Analysis	100 (MeV)	500000 (MeV)	100 (degrees)	65536	P8R2_TRANSIENT015S_V6

Gamma-ray Space Telescope

Caveats

Caveats About Analyzing LAT Pass 8 Data

These caveats are relevant for the P8R2 version of the Pass 8 photon dataset. They are an updated version of previous sets of caveats for analysis of Pass 7 reprocessed (P7REP), Pass7 (P7_V6) and Pass 6 (P6_V3 and P6_V11) event selections and Instrument Response Functions (IRFs).

The LAT team is still working to validate all aspects of Pass 8 data and analysis. As a consequence it is expected that, in the coming year, the range of application of Pass 8 data will be increased, the tools and files will be improved and the systematic uncertainties will be decreased. These caveats will be modified accordingly.

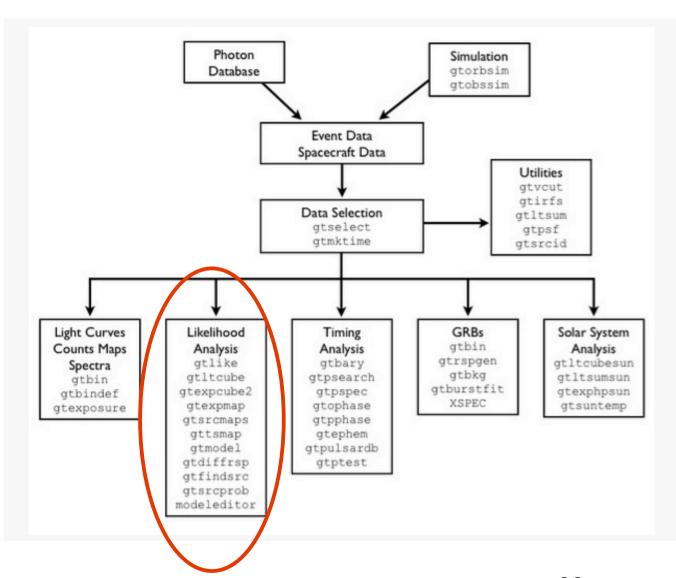
The P8R2_V6 IRFs are defined between 5.62 MeV and 3.16 TeV but that does not mean that they have been fully validated over this whole energy range. Following the Pass 7 validation effort, the LAT team has started performing studies in order to check the consistency and precision of the instrument simulation and the instrument response representation provided by the IRFs. These studies are based on the analysis of Vela (E < 10 GeV), bright AGN (3 GeV < E < 100 GeV) and the Earth limb (E > 10 GeV). They include:

- comparing the distributions of reconstructed quantities between data and the simulation of the instrument for a given selection (e.g. SOURCE class)
- comparing the fraction of events of a loose selection (e.g. TRANSIENT020 class) that are accepted in a more stringent selection (e.g. SOURCE class) in data and as predicted by the instrument simulation or the IRFs
- comparing the fraction of events in each event type for a given selection in data and as predicted by the instrument simulation or the IRFs
- comparing the radial profiles of a point source in data and as predicted by the IRFs

http://fermi.gsfc.nasa.gov/ssc/data/analysis/LAT_caveats.html



Overview of Fermi Science Tools





Maximum Likelihood Overview



Maximum likelihood technique

Given a set of observed data:

- → Produce a model that accurately describes the data, including parameters that we wish to estimate
- → derive the probability (density) for the data given the model (PDF)
- treat this as a function of the model parameters (likelihood function)
- maximize the likelihood with respect to the parameters - ML estimation.



Maximum likelihood ingredients

Data: $X = \{x_i\} = \{x_1, x_2, ..., x_N\}$

Model parameters: $\Theta = \{\theta_i\} = \{\theta_1, \theta_2, ..., \theta_M\}$

Likelihood: $\mathcal{L}(\Theta|X) = P(X|\Theta)$

Conditional probability rule

P(A,B) = P(A)P(B|A) = P(A)P(B)for independent events:

For independent data:

$$P(X|\Theta) = P(\{x_i\}|\Theta) = P(x_1|\Theta)P(x_2,..,x_N|\Theta) = \cdots$$
$$= P(x_1|\Theta)P(x_2|\Theta)\cdots P(x_N|\Theta) = \prod_i P(x_i|\Theta)$$

the detected counts in each bin.



Maximum likelihood estimation

Parameters can be estimated by maximizing likelihood.

→ Easier to work with log-likelihood:

$$\ln \mathcal{L}(\Theta) = \ln \mathcal{L}(\Theta|X) = \sum_{i} \ln P(x_{i}|\Theta)$$

Estimates of $\{\hat{\theta}_k\}$ from solving simultaneous

equations:

$$\left. \frac{\partial \ln \mathcal{L}}{\partial \theta_j} \right|_{\{\hat{\theta}_k\}} = 0$$

equations:
$$\frac{\left. \frac{\partial \ln \mathcal{L}}{\partial \theta_j} \right|_{\{\hat{\theta}_k\}} = 0 }{\left. \frac{\partial \ln \mathcal{L}}{\partial \theta_j} \right|_{\{\hat{\theta}_k\}} } = 0$$
 For one parameter, if we have:
$$\mathcal{L}(\theta) \sim e^{-\frac{(\theta - \hat{\theta})^2}{2\sigma_{\theta}^2}}$$
 Gaussian approximation

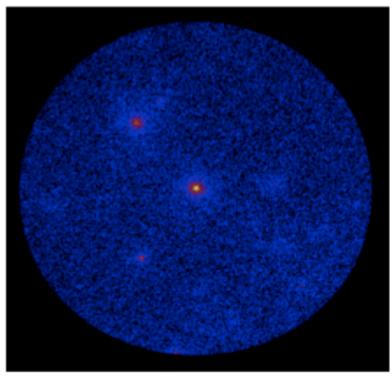
then:
$$\frac{\partial^2 \ln \mathcal{L}}{\partial \theta^2} \bigg|_{\hat{\theta}} = -\frac{1}{\sigma_{\theta}^2}$$

so 2nd derivative is related to "errors"



The Challenge

- Gamma-ray data is a list of counts (photons) reconstructed in the detector.
- Qualitative exploration of the data suggests the presence of sources (spatial clustering).
- Quantitative analysis requires evaluating the significance of a 'model' of our region.



Count Map



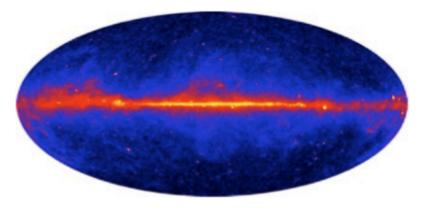
The Procedure

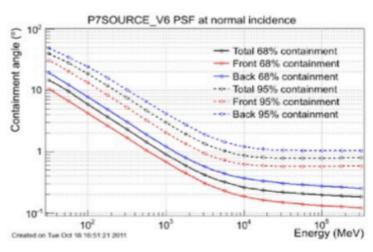
- Basically the initial 'model' is a guess of the various parameters of the sources in our region:
 - location
 - spectral shape
 - flux
 - etc.
- The guess can be easier if you have a starting point like the 2FGL (3FGL).
- We quantify (using the Likelihood Method) the statistical significance of the model and vary the parameters to determine the most likely parameter values.



Why Model Fitting?

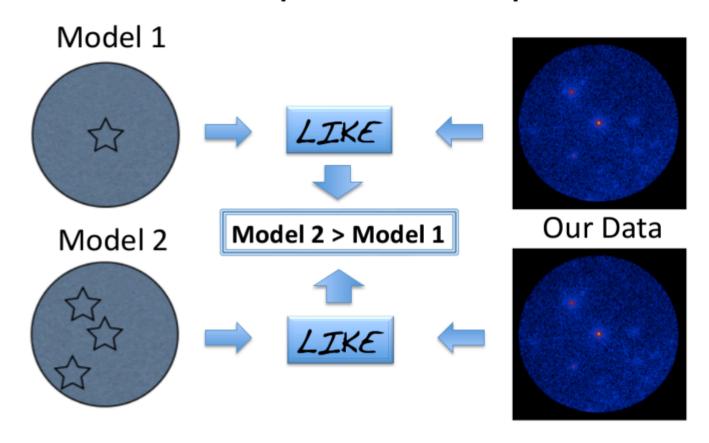
- We use the Likelihood method because the LAT data are limited by statistics, a bright diffuse background and a broad PSF.
- The model construction defines the questions we want to ask which means:
 - It will not answer a question you are not asking (ie. unknown parameters).
- The Likelihood will not tell you if a fit is 'good'. If the model does not represent your data well, the results will also not represent reality well.





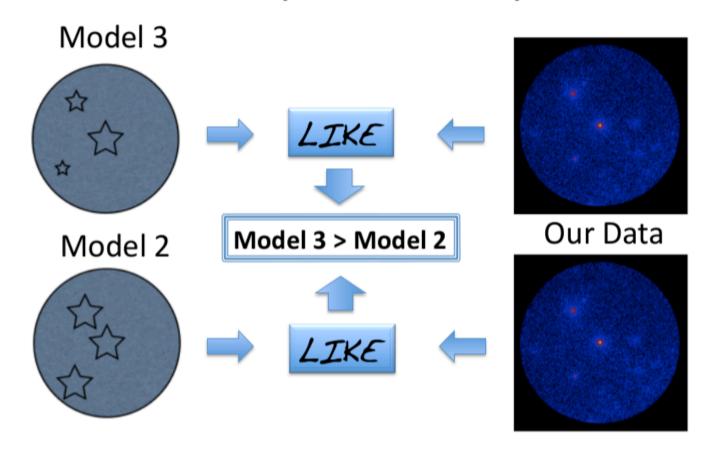


A Graphical Example





A Graphical Example





Likelihood Analysis

- The likelihood ∠ is the probability of obtaining your data given an input model.
- In our case, the input model is the distribution of gammaray sources on the sky and includes their intensity and spectra.
- One will maximize \(\mathcal{L} \) to get the best match of the model to the data. Given a set of data, one can bin them in multidimensional (energy, sky pixels, ...) bins.
- \mathcal{L} is the product of the probabilities of observing the detected counts in each bin.

$$\mathcal{L} = \prod p_k$$



Write L as a function of the source model

- The source model is folded with the IRFs in order to obtain the predicted number of counts
- The IRFs can be decomposed into three funtions: Effective Area (proj area of the detector * efficiency), Energy Dispesion, Point Spread Function

- Small number of counts in each bin --> Poisson distribution
- Bin size infinitesimally small
- Assume only steady source for standard analysis

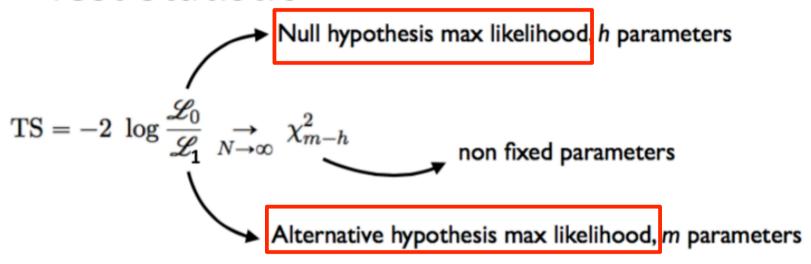
The function to maximize is:

$$\log \mathcal{L} = \sum_{j} \log M(E'_{j}, \hat{p}'_{j}, t_{j}) - N_{\text{pred}}$$

where the sum is performed over photons in the ROI. The predicted number of counts is $N_{\rm pred} = \int_{\rm POI} dE' d\hat{p}' \, dt M(E',\hat{p}',t)$



Test Statistic



- In the limit of a large number of counts, Wilk's Theorem states that the TS for the null hypothesis is asymptotically distributed as χ_n^2 where n is the number of parameters characterizing the additional source.
- As a basic rule of thumb, the square root of the TS is approximately equal to the detection significance for a given source.



Summarizing

- Observed a photon from a location, at a time, with an energy.
- Assume a model:



 Calculate the probability of that photon being detected assuming our model:

$$M(E', \hat{p}', t) = \int_{SR} dE d\hat{p} R(E', \hat{p}', t; E, \hat{p}) S(E, \hat{p}, t)$$

Calculate the total number of predicted counts assuming our model.

$$N_{\text{pred}} = \int_{\text{ROI}} dE' d\hat{p}' dt M(E', \hat{p}', t)$$

Adjust the model until this is maximized:

$$\log \mathcal{L} = \sum_{j} \log M(E'_{j}, \hat{p}'_{j}, t_{j}) - N_{\text{pred}}$$

Calculate the TS:

$$TS = -2 \log \frac{\mathscr{L}_0}{\mathscr{L}_1} \underset{N \to \infty}{\longrightarrow} \chi_{m-h}^2$$



Keep in mind that ...

- Many variables may be calculated BEFORE selecting the models
- Very important to have a reliable model
- Absolute value of likelihood meaningless!
 - Likelihood function has no meaning itself, e.g., it is not a probability. Its usefulness comes from theorems such as the LRT.
- Comparison between model w/ and w/o source to reject null hypothesis = no source (TS large → reject null hypothesis)