Chiral three-nuclear forces up to N⁴LO

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LENPIC

Low Energy Nuclear Physics International Collaboration



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Golak, Skibinski, Topolniki, Witala





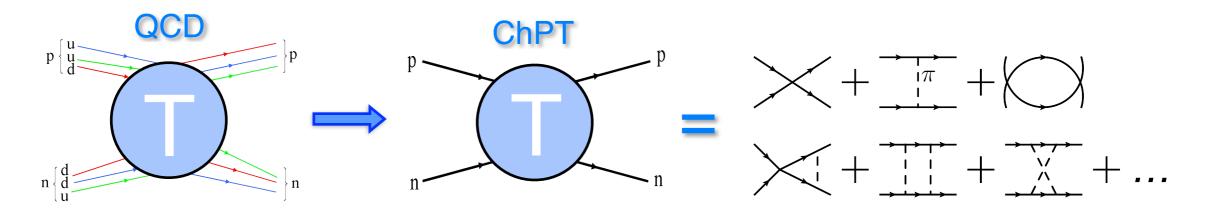




Outline

- Nuclear forces in chiral EFT
- 3NF's upto N⁴LO
- PWD of the three-nucleon forces
- Summary & Outlook

ChPT pros and cons



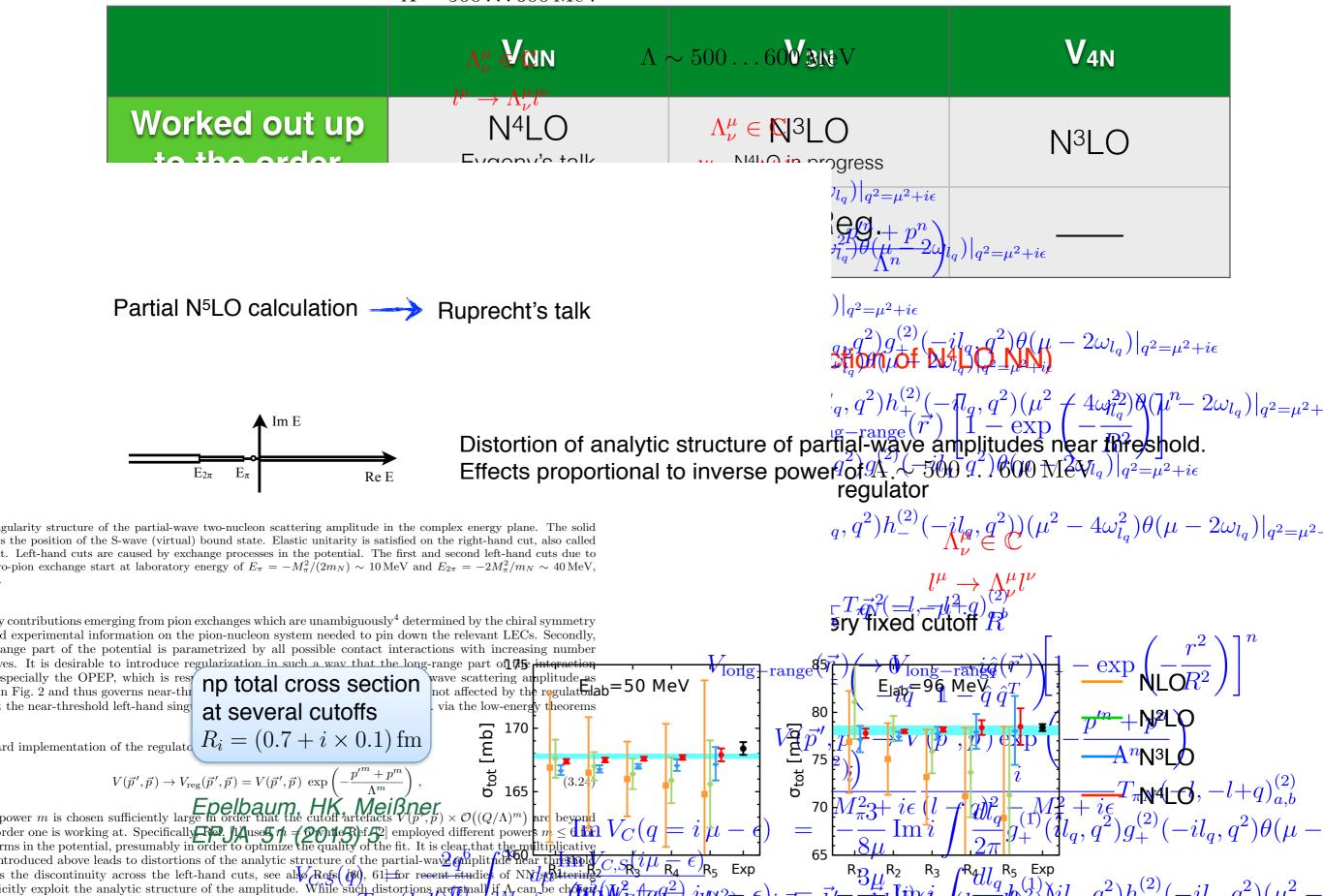
ChPT as an effective field theory of QCD

- is the most general field theory with pions, nucleons (deltas) as dofs in line with the symmetries of QCD
 - is systematically improvable
- gives a unified description of $\pi\pi$, π N, NN, (axial) vector currents etc.
- / naturally explains the hierarchy $V_{2N} >> V_{3N} >> V_{4N}$
- predicts the long range behavior of nuclear forces

allows doing precision physics with/from light nuclei

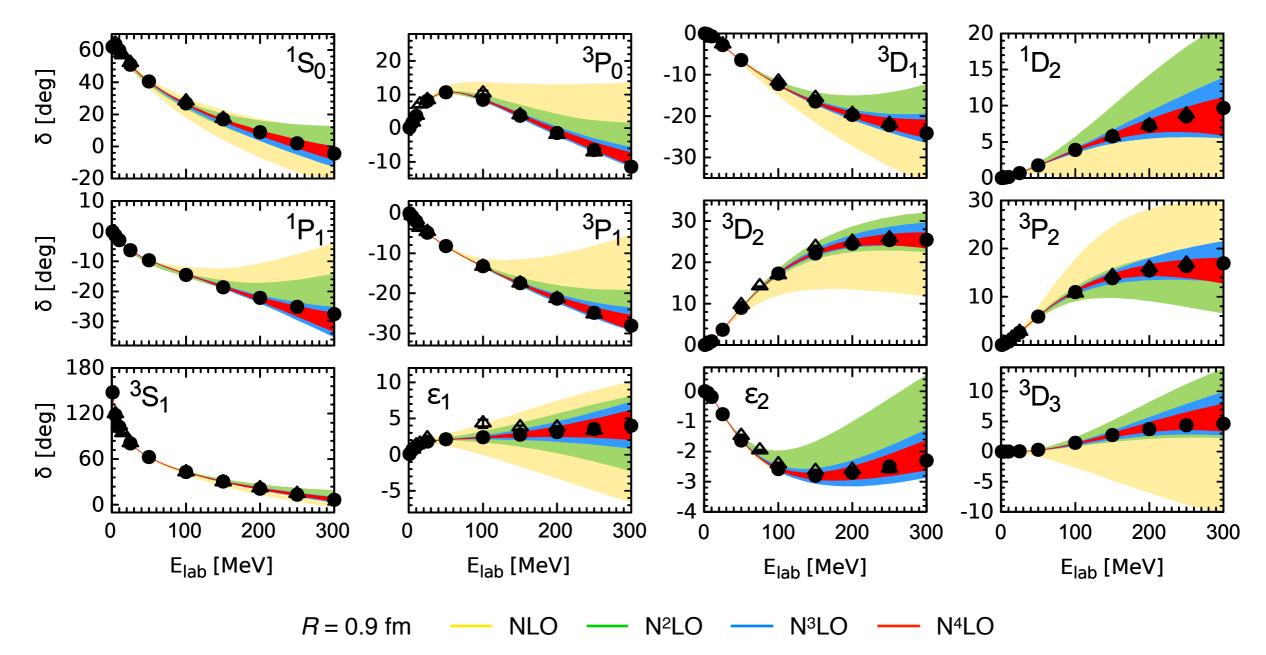
- number of free parameters (LEC) increases with increasing order in ChPT
- does not provide an explanation on the size of a particular LEC
- is only applicable in the low energy region
- convergence radius of ChPT is a priori unknown

ChPT nuclear forces



Phase shifts and mixing angles

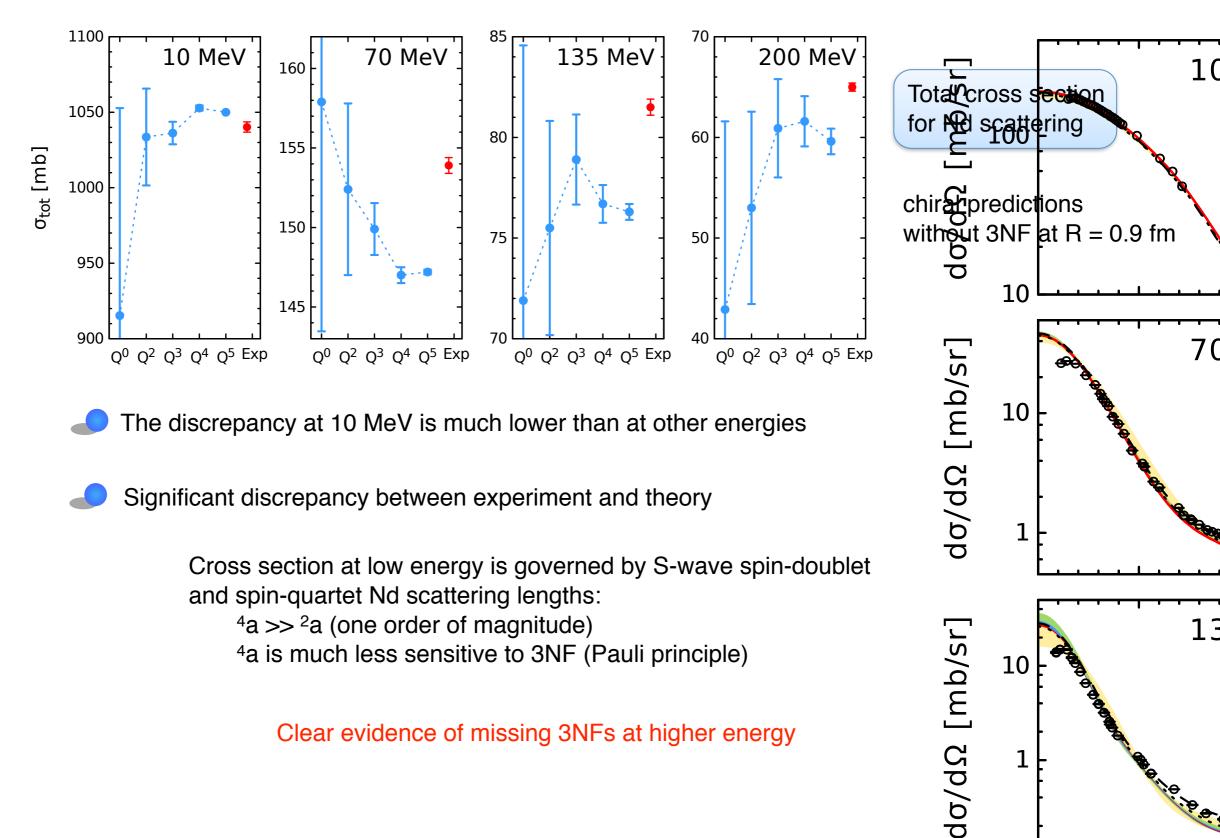
Epelbaum, HK, Meißner, arXiv: 1412.4623



- Good convergence of chiral expansion
 - \triangleright Error bands are consistent with each other \longrightarrow strong support of chiral uncertainty estimation
 - Excellent agreement with NPWA data

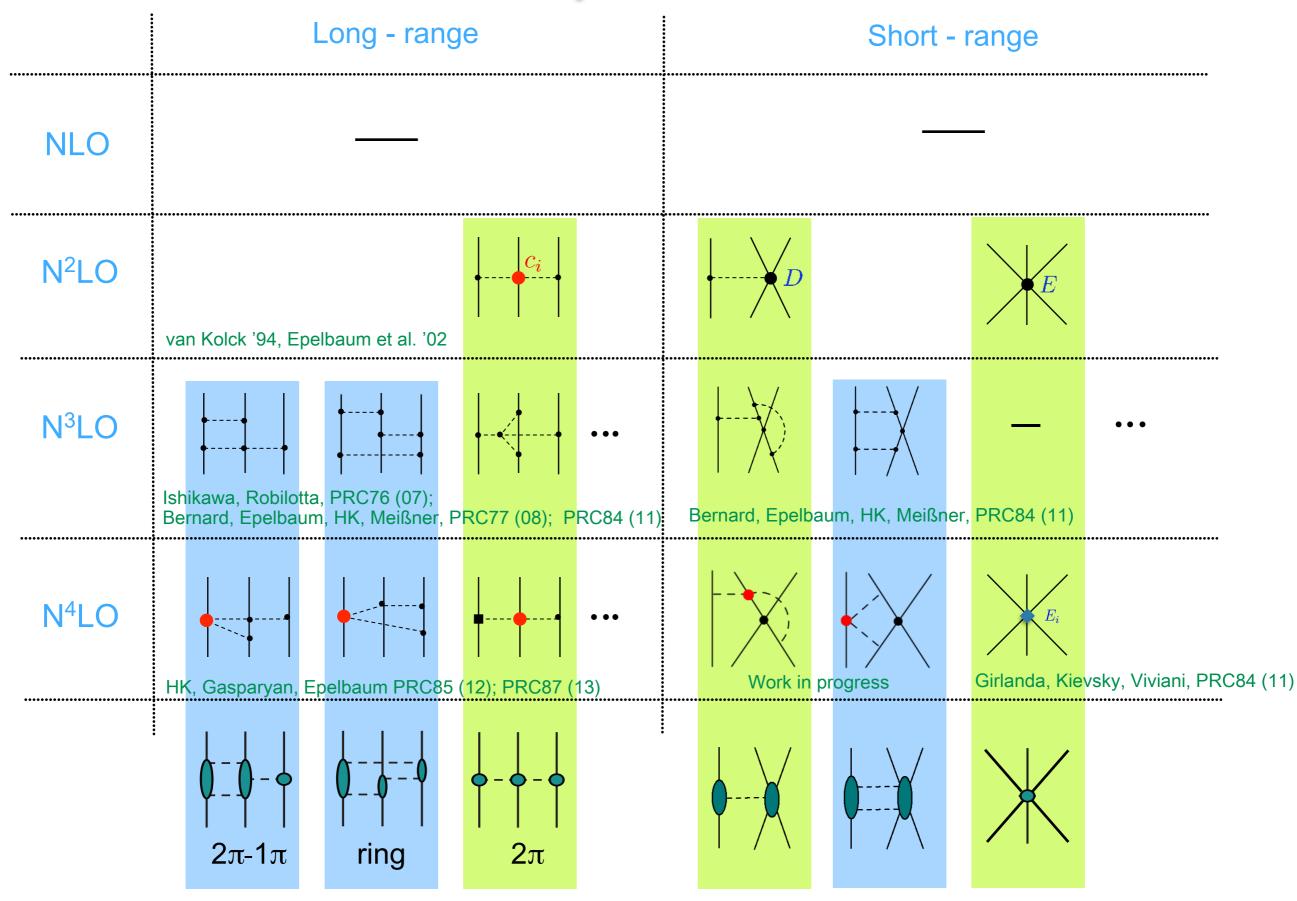
Role of the 3NFs

LENPIC collaboration: Binder et al. arXiv:1505.07218



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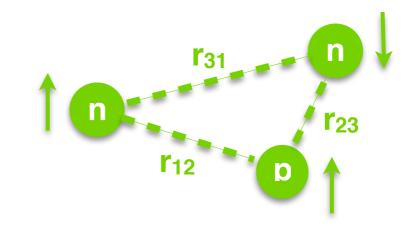
3NF up to N⁴LO



Most general structure of a local 3NF

Up to N⁴LO, the computed contributions are local \longrightarrow it is natural to switch to r-space. A meaningful comparison requires a complete set of independent operators

 $\tilde{\mathcal{G}}_1 = 1$ $ilde{\mathcal{G}}_2 ~=~ oldsymbol{ au}_1 \cdot oldsymbol{ au}_3$ $\tilde{\mathcal{G}}_3 = \vec{\sigma}_1 \cdot \vec{\sigma}_3$ $\tilde{\mathcal{G}}_4 = \boldsymbol{\tau}_1 \cdot \boldsymbol{\tau}_3 \, \vec{\sigma}_1 \cdot \vec{\sigma}_3$ $\widetilde{\mathcal{G}}_5 = \boldsymbol{\tau}_2 \cdot \boldsymbol{\tau}_3 \, \vec{\sigma}_1 \cdot \vec{\sigma}_2$ $\tilde{\mathcal{G}}_6 = \boldsymbol{\tau}_1 \cdot (\boldsymbol{\tau}_2 \times \boldsymbol{\tau}_3) \, \vec{\sigma}_1 \cdot (\vec{\sigma}_2 \times \vec{\sigma}_3)$ $\tilde{\mathcal{G}}_7 = \boldsymbol{\tau}_1 \cdot (\boldsymbol{\tau}_2 \times \boldsymbol{\tau}_3) \, \vec{\sigma}_2 \cdot (\hat{r}_{12} \times \hat{r}_{23})$ $\hat{\mathcal{G}}_{8} = \hat{r}_{23} \cdot \vec{\sigma}_{1} \, \hat{r}_{23} \cdot \vec{\sigma}_{3}$ $\tilde{\mathcal{G}}_9 = \hat{r}_{23} \cdot \vec{\sigma}_3 \, \hat{r}_{12} \cdot \vec{\sigma}_1$ $\tilde{\mathcal{G}}_{10} = \hat{r}_{23} \cdot \vec{\sigma}_1 \, \hat{r}_{12} \cdot \vec{\sigma}_3$ $\mathcal{G}_{11} = \boldsymbol{\tau}_2 \cdot \boldsymbol{\tau}_3 \, \hat{r}_{23} \cdot \vec{\sigma}_1 \, \hat{r}_{23} \cdot \vec{\sigma}_2$ $\tilde{\mathcal{G}}_{12} = \boldsymbol{\tau}_2 \cdot \boldsymbol{\tau}_3 \hat{r}_{23} \cdot \vec{\sigma}_1 \hat{r}_{12} \cdot \vec{\sigma}_2$ $\mathcal{G}_{13} = \boldsymbol{\tau}_2 \cdot \boldsymbol{\tau}_3 \, \hat{r}_{12} \cdot \vec{\sigma}_1 \, \hat{r}_{23} \cdot \vec{\sigma}_2$ $\hat{\mathcal{G}}_{14} = \boldsymbol{\tau}_2 \cdot \boldsymbol{\tau}_3 \hat{r}_{12} \cdot \vec{\sigma}_1 \hat{r}_{12} \cdot \vec{\sigma}_2$ $\mathcal{G}_{15} = \boldsymbol{\tau}_1 \cdot \boldsymbol{\tau}_3 \, \hat{r}_{13} \cdot \vec{\sigma}_1 \, \hat{r}_{13} \cdot \vec{\sigma}_3$ $\mathcal{G}_{16} = \boldsymbol{\tau}_2 \cdot \boldsymbol{\tau}_3 \hat{r}_{12} \cdot \vec{\sigma}_2 \hat{r}_{12} \cdot \vec{\sigma}_3$ $\tilde{\mathcal{G}}_{17} = \boldsymbol{\tau}_1 \cdot \boldsymbol{\tau}_3 \, \hat{r}_{23} \cdot \vec{\sigma}_1 \, \hat{r}_{12} \cdot \vec{\sigma}_3$ $\tilde{\mathcal{G}}_{18} = \boldsymbol{\tau}_1 \cdot (\boldsymbol{\tau}_2 \times \boldsymbol{\tau}_3) \, \vec{\sigma}_1 \cdot \vec{\sigma}_3 \, \vec{\sigma}_2 \cdot (\hat{r}_{12} \times \hat{r}_{23})$ $\tilde{\mathcal{G}}_{19} = \boldsymbol{\tau}_1 \cdot (\boldsymbol{\tau}_2 \times \boldsymbol{\tau}_3) \, \vec{\sigma}_3 \cdot \hat{r}_{23} \, \hat{r}_{23} \cdot (\vec{\sigma}_1 \times \vec{\sigma}_2)$ $\tilde{\mathcal{G}}_{20} = \boldsymbol{\tau}_1 \cdot (\boldsymbol{\tau}_2 \times \boldsymbol{\tau}_3) \, \vec{\sigma}_1 \cdot \hat{r}_{23} \, \vec{\sigma}_3 \cdot \hat{r}_{12} \, \vec{\sigma}_2 \cdot (\hat{r}_{12} \times \hat{r}_{23})$



Building blocks:

 $\boldsymbol{ au}_1, \ \boldsymbol{ au}_2, \ \boldsymbol{ au}_3, \ \vec{\sigma}_1, \ \vec{\sigma}_2, \ \vec{\sigma}_3, \ \vec{r}_{12}, \ \vec{r}_{23}$

Constraints:

Locality

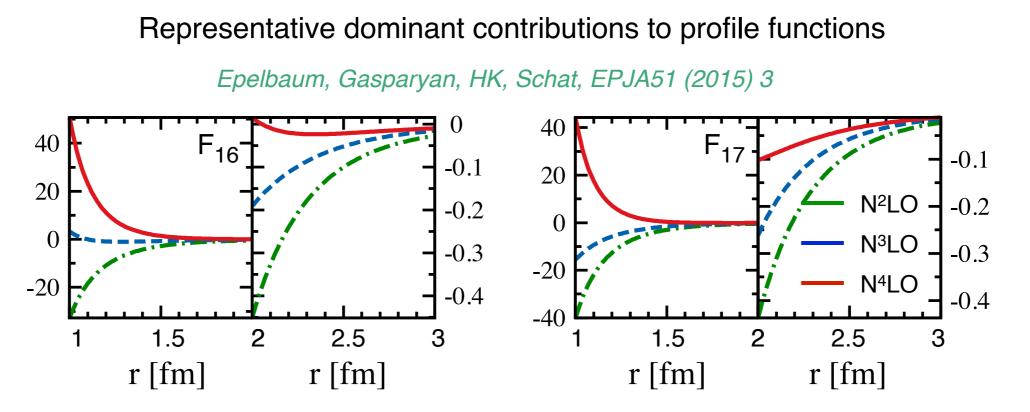
Isospin symmetry

Parity and time-reversal invariance

$$\longrightarrow V_{3N} = \sum_{i=1}^{20} \tilde{\mathcal{G}}_i F_i(r_{12}, r_{23}, r_{31}) + 5 \text{ perm.}$$

Epelbaum, Gasparyan, HK, PRC87 (2013) 054007 Schat, Phillips, PRC88 (2013) 034002 Epelbaum, Gasparyan, HK, Schat, EPJA51 (2015) 3

Long-range 3NF up to N⁴LO



- All 22 profile functions start to contribute at N⁴LO
- Solution Large N⁴LO contributions due to sizable c_i 's (hidden Δ dofs)
- No statement about convergence possible

 \longrightarrow explicit Δ treatment needed to clarify convergence issue

Quantitative statements are only possible once observables are calculated

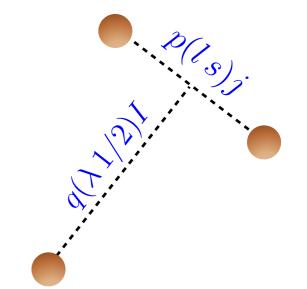
Partial wave decomposition

Golak et al. Eur. Phys. J. A 43 (2010) 241

Faddeev equation is solved in the partial wave basis

 $|p,q,\alpha\rangle \equiv |pq(ls)j(\lambda\frac{1}{2})I(jI)JM_J\rangle |(t\frac{1}{2})TM_T\rangle$

Too many terms for doing PWD by hand Automatization



Numerically expensive due to many channels and 5-dim. integration

PWD matrix-elements can be used to produce matrix-elements in harmonic oscillator basis

Straightforward implementation of high order 3nf's in many-body calc. within No-Core Shell Model

PWD for local forces

$$\langle m'_{s} | \vec{\sigma} \cdot \vec{p} \, | m_{s} \rangle = \sum_{\mu=-1}^{1} p \, Y_{1\mu}^{*}(\hat{p}) \sqrt{\frac{4\pi}{3}} \langle m'_{s} | \vec{\sigma} \cdot \vec{e}_{\mu} \, | m_{s} \rangle$$
 momentum-independent part
$$\langle m'_{s_{1}} m'_{s_{2}} m'_{s_{3}} | V | m_{s_{1}} m_{s_{2}} m_{s_{3}} \rangle = \sum_{\mu' s} (m'_{s_{1}} m'_{s_{2}} m'_{s_{3}} | \text{Spin matrices } \& \vec{e}_{\mu} \, 's | m_{s_{1}} m_{s_{2}} m_{s_{3}}) (Y_{1\mu}' s)$$
$$\times V((\vec{p}' - \vec{p})^{2}, (\vec{q}' - \vec{q})^{2}, (\vec{p}' - \vec{p}) \cdot (\vec{q}' - \vec{q}))$$

$$\langle p'q'\alpha'|V|pq\alpha\rangle = \sum_{m_{l}...} (\text{CG coeffs.}) \int d\hat{p}'d\hat{q}'d\hat{p}\,d\hat{q}\,Y^{*}_{l'_{1}m'_{1}}(\hat{p}')Y^{*}_{l'_{2}m'_{2}}(\hat{q}')Y^{*}_{l_{1}m_{1}}(\hat{p})Y^{*}_{l_{2}m_{2}}(\hat{q})$$

$$\times V((\vec{p}'-\vec{p})^{2}, (\vec{q}'-\vec{q})^{2}, (\vec{p}'-\vec{p})\cdot(\vec{q}'-\vec{q})) \rightarrow \text{Speed up factors} > 1000$$

Unregularized 3NF matrix elements can be used to generate locally regularized 3NFs

 $\langle p'q'\alpha'|V|pq\alpha\rangle \rightarrow \sum_{n} \langle p'q'\alpha'|V|n\rangle\langle n|R|pq\alpha\rangle$ with $\langle p'q'\alpha'|R|pq\alpha\rangle$ matrix element of local regulator

Hebeler, HK, Epelbaum, Golak, Skibinski PRC91 (2015) 4

Summary

Chiral 3NF's are studied up to N³LO / partly up to N⁴LO

- Optimized version of PWD for local 3NF's
- Stored matrix elements can be used within local regularization

Outlook

Solution N⁴LO Δ -less/N³LO- Δ calc. of shorter range part of 3NF

Generation of matrix-elements for 3NF's up to N⁴LO Δ-less/N³LO-Δ Due to optimized PWD should not cost much