Memory effects in quantum dynamics: from applications to foundations

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Is quantum theory exact? FQT2015

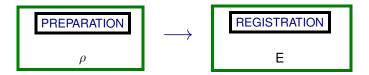
From foundations to open quantum systems and back

2 Classical processes: divisibility and distinguishability



Foundations of quantum mechanics

Statistical structure of quantum theory



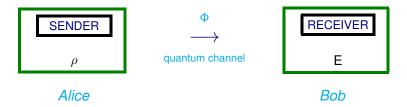
- Single particle statistical experiment
- State as equivalence class of preparation procedures
 ρ ∈ *T*(*H*) normed space with ||*A*||₁ = *Tr*|*A*|
- Observable as equivalence class of registration procedures B ∈ B(H) normed space with ||A|| = sup_{||φ||=1} ||Aφ||
- Statistics of experiment

$$\mu_{\rho}^{B}(M) = \operatorname{Tr} \rho E^{B}(M)$$

Quantum mechanics as a theory of probability

Quantum information

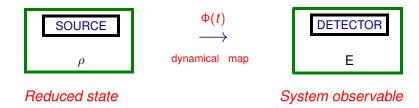
Quantum systems as information carriers



- Quantum information and communication standpoint
- Relevance of general state transformations
- Relevance of possibly detrimental noise and decoherence
- Quantum systems unavoidably linked to a macroscopic background

Open quantum systems

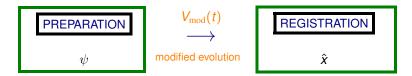
Quantum systems as relevant degrees of freedom



- Open quantum system standpoint
- Relevance of general state transformations
- Relevance of noise and decoherence
- Quantum systems unavoidably linked to a macroscopic background
- Measurement interaction as archetype

Modifications of quantum mechanics

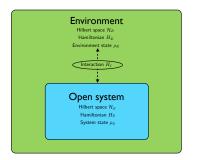
Statistical structure of quantum theory



- Modification of Schrödinger time evolution to solve measurement problem
- Single particle statistical experiment
- Statistics of experiment $\mu_{\rho}^{\hat{x}}(M) = \text{Tr } \rho E^{\hat{x}}(M)$
- Quantum mechanics as a theory of probability

• Quantum system interacting with environment

[Davies, 1976; Holevo, 2001; Breuer & Petruccione, 2002]



 Bipartite setting H ∈ L(H_S ⊗ H_E) ρ_{SE} ∈ T(H_S ⊗ H_E) System observables only determined by ρ_S(t) = Tr_E ρ_{SE}(t)

$$\frac{d}{dt}\rho_{s}(t) = -\frac{i}{\hbar}\operatorname{Tr}_{E}[H,\rho(t)] \qquad \rho_{s}(0) = \operatorname{Tr}_{E}\rho_{sE}(0)$$

Quantum dynamical map

Reduced dynamics

$$\begin{array}{c|c} \rho(\mathbf{0}) = \rho_{s}(\mathbf{0}) \otimes \rho_{E} & \xrightarrow{\text{unitary evolution}} & \rho(t) = e^{-\frac{i}{\hbar}Ht}(\rho_{s}(\mathbf{0}) \otimes \rho_{E})e^{+\frac{i}{\hbar}Ht} \\ & & & \downarrow \\ & & & \downarrow \\ & & & \downarrow \\ & & & \uparrow \\ & & & \rho_{s}(\mathbf{0}) & \xrightarrow{\text{dynamical map}} & \rho_{s}(t) = \Phi(t)\rho_{s}(\mathbf{0}) \end{array}$$

Quantum dynamical map

$$\rho_{\mathcal{S}}(\mathbf{0}) \mapsto \rho_{\mathcal{S}}(t) = \Phi(t)\rho_{\mathcal{S}}(\mathbf{0}) = \operatorname{Tr}_{\mathcal{E}}(e^{-\frac{i}{\hbar}Ht}(\rho_{\mathcal{S}}(\mathbf{0}) \otimes \rho_{\mathcal{E}})e^{+\frac{i}{\hbar}Ht})$$

$$\Phi = \{\Phi(t), t \in \mathbb{R}_{+} | \Phi(\mathbf{0}) = \mathbb{I}\}$$

Completely positive trace preserving map

Quantum Markov process

Semigroup composition law

 $\Phi(t)\Phi(s) = \Phi(t+s)$ $t, s \ge 0 \Rightarrow \Phi(t) = \exp(\mathcal{L}t)$

- Markov condition Separation of time scales $\tau_{\rm E} \ll \tau_{\rm S}$
- Quantum dynamical semigroups

[Gorini & al. JMP 1976; Lindblad, CMP 1976]

Quantum Markov process fixed by master equation

$$\frac{d}{dt}\rho_{\mathcal{S}}(t) = \mathcal{L}\rho_{\mathcal{S}}(t)$$

with generator in Lindblad form $\gamma_k \ge 0$

$$\mathcal{L}\rho_{s}(t) = -\frac{i}{\hbar}[H_{eff}, \rho_{s}(t)] + \sum_{k} \gamma_{k} \Big[A_{k}\rho_{s}(t)A_{k}^{\dagger} - \frac{1}{2} \{A_{k}^{\dagger}A_{k}, \rho_{s}(t)\} \Big]$$

Master equation in Lindblad form

Motivations and goals

- Microscopic derivation of reduced dynamical evolutions
- Mathematical characterization of quantum dynamical map
- Definition and characterization of quantum memory
- Relevance of initial correlations
- Decoherence and quantum to classical transition
- Decoherence versus alternative quantum theories

Back to foundations

- Open quantum system theory provides useful tool for study and extension of dynamical reduction models
 - Modifications of unitary dynamics
 - Dissipative dynamical reduction models

[Bassi & al. PRA 2005; Smirne & al. PRA 2014; Smirne & Bassi Sci Rep 2015]

Non-Markovian dynamical reduction models

[Bassi & Ferialdi PRL 2009, PRA 2009; Ferialdi & Bassi PRL 2012]

Modifications of open quantum system dynamics

[Bahrami & al. PRL 2014; Bassi & al. PRL 2005]

• Open quantum system theory describes decoherence effects typically undistinguishable from dynamical reduction models

[Bassi & al. RMP 2012]



From foundations to open quantum systems and back

2 Classical processes: divisibility and distinguishability



Quantum non-Markovianity

Classical stochastic processes

- Statistical description of classical system by means of stochastic process X(t), t ≥ 0 taking values in {x_i}_{i∈ℕ}
- Stochastic process characterized by hierarchy of joint probability distributions

$$P_n(x_n, t_n; x_{n-1}, t_{n-1}; \ldots; x_1, t_1)$$
 $t_n \ge t_{n-1} \ge \ldots \ge t_1 \ge 0$

obeying Kolmogorov consistency condition

$$\sum_{x_m} P_n(x_n, t_n; \ldots; x_m, t_m; \ldots; x_1, t_1) = P_{n-1}(x_n, t_n; \ldots; x_1, t_1)$$



Andrej Kolmogorov (1903-1987)

Classical Markovian processes

- Lack of memory in the dynamics described by means of Markov property
- Conditional probabilities of Markovian process

$$P_{1|n}(x_{n+1}, t_{n+1}|x_n, t_n; \ldots; x_1, t_1) \equiv \frac{P_{n+1}(x_{n+1}, t_{n+1}; \ldots; x_1, t_1)}{P_n(x_n, t_n; \ldots; x_1, t_1)}$$

obey the constraint

 $P_{1|n}(x_{n+1}, t_{n+1}|x_n, t_n; \ldots; x_1, t_1) = P_{1|1}(x_{n+1}, t_{n+1}|x_n, t_n) \quad n \ge 2$



Andrej Markov (1856-1922)

Classical Markovian processes

 Markovian process determined by initial distribution and conditional transition probability

$$P_1(x_0,0)$$
 $T(x,t|y,s) \equiv P_{1|1}(x,t|y,s)$

via

$$P_1(x_1, t_1) = \sum_{x_0} T(x_1, t_1 | x_0, 0) P_1(x_0, 0)$$
$$P_n(x_n, t_n; \dots; x_1, t_1) = \prod_{i=1}^{x_0} T(x_{i+1}, t_{i+1} | x_i, t_i) P_1(x_1, t_1)$$

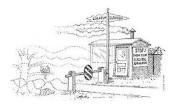
Consistency is ensured by Chapman-Kolmogorov equation

$$T(x,t|y,s) = \sum_{z} T(x,t|z,\tau) T(z,\tau|y,s)$$



Sydney Chapman (1888-1970)

- T(x, t|y, s) and $P_1(x, t)$ basic quantities in the description of classical Markov processes to be taken as possible starting point for quantum generalization
- Signatures of Markovian process at the level of probability density and conditional transition probability







• Finite dimensional system

$$egin{array}{rcl} P_1(x,t) & o & P(t) & ext{probability vector} \ T(x,t|y,s) & o & \Lambda(t,s) & ext{stochastic matrix} \end{array}$$

 Chapman-Kolmogorov equation expresses divisibility property

$$\Lambda(t, s) = \Lambda(t, \tau) \Lambda(\tau, s) \qquad \forall t \ge \tau \ge s \ge 0$$

lack of memory in time evolution of probability vector

$$P(t) = \Lambda(t,\tau)P(\tau)$$

Kolmogorov distance between probability distribution

$$K(Q, P) = \frac{1}{2} \sum_{n} |Q_n - P_n|$$
$$\underbrace{0}_{Q=P} \leq K(Q, P) \leq \underbrace{1}_{Q \perp P}$$

 Kolmogorov distance monotone contraction with respect to action of divisible stochastic matrix

$$K(P^1(t+s), P^2(t+s)) \leq K(P^1(t), P^2(t)) \qquad \forall t, s \geq 0$$

thanks to

$$\Lambda(t, s)_{n,m} \ge 0$$
 $\sum_{n} \Lambda(t, s)_{n,m} = 1$

[B.V. & al., NJP 2011]

 Kolmogorov distance provides a notion of distinguishability of classical states

[Fuchs & de Graaf, IEEE 1999]

 General expression quantifying best strategy in assessing statistical distinguishability of different states

 P_1 with a priori probability p_1

 P_2 with a priori probability p_2

according to statistical decision theory is given by

$$P_{success} = \frac{1}{2}(1 + K(P^1, P^2; p_1, p_2))$$

with

$$K(P^1, P^2; p_1, p_2) = \sum_n \left| p_1 P_n^1 - p_2 P_n^2 \right|$$

obeying

$$|\underbrace{p_1 - p_2}_{P^1 = P^2}| \le K(P^1, P^2; p_1, p_2) \le \underbrace{1}_{P^1 \perp P^2}$$

- Divisibility and distinguishability distinct notions but ...
- Direct connection between distinguishability and divisibility thanks to theorem by Kossakowski

[Kossakowski, Bull. Acad. Polon. Sci. Math. 1972; RMP 1972]

Consider trace preserving map Λ

 $\Lambda:\ell_1(\mathbb{C})\mapsto\ell_1(\mathbb{C})$

A positive iff contraction on all hermitian elements

$$\begin{split} \Lambda[P] &\geq 0 & \forall P \in \ell_1(\mathbb{C}), \ P \geq 0 \\ & & \\ \|\Lambda[X]\| \leq \|X\| & \forall X \in \ell_1(\mathbb{C}), \ X = X^{\dagger} \\ & \text{with } \|X\| = \sum_n |X_n| \end{split}$$



Andrzej Kossakowski

 Signatures of Markovianity at the level of probability distribution and conditional transition probability merge

$$\Lambda(t, s) = \Lambda(t, \tau) \Lambda(\tau, s) \qquad \forall t \ge \tau \ge s \ge 0$$

where each element is a positive trace preserving transformation, i.e. a stochastic matrix

 Necessary but not sufficient criteria for lack of memory in classical process as can be shown by means of example

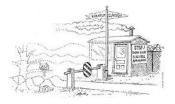
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2 Classical processes: divisibility and distinguishability



Quantum non-Markovianity

• Have we learnt something about classical Markovian and non-Markovian processes which might be helpful to us when we cross the quantum boundary?







Quantum non-Markovianity

System observables take the place of random variables

$$X = \sum_{x_n} x_n |\varphi_{x_n}\rangle \langle \varphi_{x_n}|$$

 Values at different times fixed once we specify measurement scheme, e.g. projective measurements

$$\mathcal{M}_{x}\rho_{SE} = \left(|\varphi_{x}\rangle\langle\varphi_{x}|\otimes\mathbb{1}_{E}\right)\rho_{SE}\left(|\varphi_{x}\rangle\langle\varphi_{x}|\otimes\mathbb{1}_{E}\right)$$

in between given time evolution

$$\mathcal{U}_t \rho_{SE} = U_t \rho_{SE} U_t^{\dagger}$$

Natural definition

1

$$\mathsf{P}_{n}(x_{n}, t_{n}; x_{n-1}, t_{n-1}; \ldots; x_{1}, t_{1}) \equiv \operatorname{Tr} \left\{ \mathcal{M}_{x_{n}} \mathcal{U}_{t_{n}-t_{n-1}} \ldots \mathcal{M}_{x_{2}} \mathcal{U}_{t_{2}-t_{1}} \mathcal{M}_{x_{1}} \mathcal{U}_{t_{1}} \rho_{SE}(\mathbf{0}) \right\}$$

But Kolmogorov consistency condition does not hold

$$\sum_{x_m} P_n(x_n, t_n; \ldots; x_m, t_m; \ldots; x_1, t_1) \neq P_{n-1}(x_n, t_n; \ldots; x_1, t_1)$$

- Divisibility / distinguishability viewpoint provided sufficient condition for classical non-Markovian process captured at the level of the one-point probability density
- Quantum counterpart of classical notion
- Kolmogorov distance as a special instance of trace norm distance for $\mathcal{T}(\mathcal{H}_s) \to \ell_1(\mathbb{C})$

$$K(P^{1}(t), P^{2}(t)) = \frac{1}{2} \sum_{n} \left| P_{n}^{1}(t) - P_{n}^{2}(t) \right|$$

$$(1)$$

$$D(\rho_{S}^{1}(t), \rho_{S}^{2}(t)) = \frac{1}{2} \operatorname{Tr} \left| \rho_{S}^{1}(t) - \rho_{S}^{2}(t) \right|$$

$$= \frac{1}{2} \left\| \rho_{S}^{1}(t) - \rho_{S}^{2}(t) \right\|$$

Quantum non-Markovianity

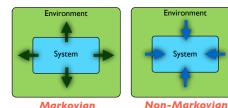
- Consider behavior of distinguishability in time of $\rho_S^{1,2}(t)$ upon the action of quantum dynamical map Φ_t
- Non-Markovianity defined as revival in time of the distinguishability among different initial states

$$\sigma(t) \equiv \frac{1}{2} \frac{d}{dt} \left\| \Phi_t \left(\rho_S^1(0) - \rho_S^2(0) \right) \right\| > 0$$

Leading to an actual measure of non-Markovianity

$$\mathcal{N}(\Phi) = \max_{\rho_S^1(0) \perp \rho_S^2(0)} \int_{\sigma > 0} dt \ \sigma(t)$$





- Divisibility of stochastic matrices as a special instance of divisibility for quantum dynamical map Φ_t
- Let Φ_t admit linear inverse and consider

$$\Phi(t, \boldsymbol{s}) = \Phi_t \Phi_{\boldsymbol{s}}^{-1} \qquad \forall t \geq \boldsymbol{s}$$

The process is said divisible if

$$\Phi(t, \boldsymbol{s}) = \Phi(t, \tau) \Phi(\tau, \boldsymbol{s}) \qquad \forall t \geq \tau \geq \boldsymbol{s} \geq \boldsymbol{0}$$

with $\Phi(t_2, t_1)$ a positive map $\forall t_2 \ge t_1$

CP-divisibility corresponds to

$$\Phi(t, s) = \Phi(t, \tau) \Phi(\tau, s) \qquad \forall t \ge \tau \ge s \ge 0$$

with $\Phi(t_2, t_1)$ a CP map $\forall t_2 \ge t_1$

- Starting point for a definition of non-Markovianity of an open quantum system dynamics
- CP however also takes care of correlations with ancillary system, and we are looking for characterization involving the system only

[Wolf & al., PRL 2008; Rivas & al., PRL 2010; Rep. Prog. Phys. 2014]

- Theorem by Kossakowski allows to identify divisibility and monotonic decrease of distinguishability also in the quantum case [Kossakowski, Bull. Acad. Polon. Sci. Math. 1972; RMP 1972]
- Consider a trace preserving map Φ

 $\Phi:\mathcal{T}(\mathcal{H}_{\mathcal{S}})\mapsto\mathcal{T}(\mathcal{H}_{\mathcal{S}})$

 $\Phi \text{ positive map iff } \Phi \text{ contraction on all self-adjoint} \\ \text{trace class operators}$

$$\Phi[T] \ge 0 \qquad \forall T \in \mathcal{T}(\mathcal{H}_s), \ T \ge 0$$

$$\|\Phi[T]\| \le \|T\| \qquad \forall T \in \mathcal{T}(\mathcal{H}_s), \ T = T^{\dagger}$$
with $\|T\| = \sum_{n} |t_n|$

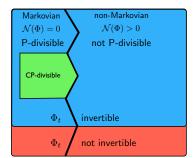
 We are thus led to consider as non-Markovian quantum processes those dynamical evolutions s.t.

$$\Sigma(t) = rac{d}{dt} \| \Phi_t(p_1
ho_S^1 - p_2
ho_S^2) \|_1 \ge 0 \quad ext{for some } t \ge 0$$

equivalent to P-divisibility (if the inverse does exist) so that

$$\mathcal{N}_{P}(\Phi) = \max_{p_{i}, p_{S}^{i}} \int_{\Sigma > 0} dt \ \Sigma(t)$$

[Breuer & al., arXiv 2015; Wißmann & al., arXiv 2015]



Applications & foundations

- Relevance of non-Markovianity for applications
 - Experimental observation

[Liu & al., Nature Phys. 2011]

Criterion for the detection of initial correlations

[Laine & al., EPL 2010; Smirne & al., PRA 2011; Li & al., PRA 2011]

 Determination of complex system properties via quantum probe approach

[Apollaro & al., 2011; Haikka & al., PRA 2012; Smirne & al., PRA 2013; Benedetti & al., PRA 2014]

Criteria for the determination of quantum correlations

[Gessner & al., PRL 2011; Cialdi & al., PRA 2014]

- Possible relevance of non-Markovianity for foundations
 - Modification of quantum mechanics arising from colored noises or general non-Markovian dynamical evolutions

[Bassi & Ferialdi PRL 2009, PRA 2009; Ferialdi & Bassi PRL 2012]

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