Singular stochastic PDE and Dynamical field theory models

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Plan of the presentation

Singular stochastic partial differential equations

Dynamical models

Linear process

Probabilistic weak solution

D=2 The weak solution of J-L, P.K.M in the limit $\kappa
ightarrow \infty$

Stationary O-U process

Euclidean formalism

Singular stochastic PDE

SSPDE : Non-linear Langevin equations "whose solutions" are supposed to generate Markov processes with Euclidean field theory measures as invariant measures.

A priori ill defined problem.

- ► EFT measures require renormalization to be defined. They are realized on spaces with distributions D'(ℝ^d) or S'(ℝ^d).
- ► The SSPDE = Non-linear Langevin equations having coefficients inherited from EFT measures. These are typically distributions. Nonlinear ↔ pointwise products ↔ renormalization.

If "solutions" exist, Markov process is distribution valued.

How to proceed ? Follow Dirac's advice. Introduce cut-offs, solve the equations and then take limits.

What sort of solutions ?

Different points of view :

Probabilistic weak solutions/ Martingale solutions : With cut-offs these are also strong solutions and Martingale solutions exist. This leads to Functional integral/RG point of view to construction of semigroup/invariant measures.

This is the point of view I will adopt.

What sort of solutions ?

Pathwise approaches

Dynamical solutions of super-renormalizable Euclidean Field theories. Counter-terms : those of super-renormalizable EFT's. (massive $\phi_d^4 \ d = 2, 3.$)

a) M. Hairer (theory of regularity structures), M. Gubinelli *et. al.* (paracontrolled distributions) : These are theories of multiplication of distributions with counter-terms. Verified in low order perturbation theory. The remainder is controlled as a fixed point problem in a Banach space.

What sort of solutions ?

▶ b) Antti Kupiainen : RG approach directly on the equation

UV cut-off noise, finite volume. Rescale to unit cut-off with enlarged volume. This gives rise to a sequence of effective equations with rescaling at each step \rightarrow Perturbative part + remainder. The limit of the sequence of remainders has been proved to exist by solving a Banach fixed point problem.

These are all : short time solutions with the upper bound on time dependent on noise.

Long time solution, D = 2 by J.C. Mourrat and H.Weber. BUT : Hairer gives optimal regularity for paths, and initial conditions.

An example

Scalar field theory in dimension D, $\phi(x)$, $x \in \mathbb{R}^{D}$.

 $C_0(x-y) =$ Fourier transform of $\hat{C}_0(k) = \frac{1}{k^2 + m^2}$. $\kappa \cdot UV$ cut-off

$$\hat{C}_\kappa(k) = rac{1}{(k^2+m^2)(1+rac{k^2}{\kappa^2})^p}$$
 for sufficciently large p.

The random gaussian field ϕ in \mathbb{R}^d with covariance C_0 is a distributon for D > 2. For p sufficiently large, ϕ distributed according to C_x is locally sufficiently differentiable.

$$\mathrm{d}\mu_{\kappa}(\phi) = \frac{1}{Z_{\kappa}(\Lambda)} \int \mathrm{d}\mu_{C_{\kappa}}(\phi) \, e^{-V_{\kappa}(\phi,\Lambda)}.$$

 $V_{\kappa}(\phi, \Lambda) = \int_{\Lambda} d^{D}x \{\lambda : \phi^{4} :_{C_{\kappa}} (x) + \text{counterterms}_{\kappa}\}$ $\Lambda_{L} : \text{ cube side, periodic b.c., } \Lambda_{L} = \mathbb{R}^{D} / (L\mathbb{Z}^{D}). \ C_{\kappa} : \text{ periodized}$ COVARIANCO SSPDE

Linear process

Dynamical models

Nonlinear Langevin equations

Large class of equations available, such that if solutions exist, they have the same invariant measure.

Example : Let $0 < \rho \leq 1$.

$$\begin{split} \mathrm{d}\tilde{\phi}_t &= \mathrm{d}W_t - \frac{1}{2} \left(C_x^{-\rho} \tilde{\phi}_t + \lambda C^{1-\rho} : \tilde{\phi}_t^3 :_{C_{\kappa}} \right) \mathrm{d}t, \\ \tilde{\phi}_0 &= \phi, \end{split}$$

values in subspace of $\mathcal{D}'(\Lambda_L)$, (sufficiently differentiable functions). f, g are test functions in $\mathcal{D}(\Lambda_L)$.

$$E(W_t(f), W_t(g)) = (f, C^{1-\rho}g) \min(t, s).$$

Canonical choice $\rho = 1$.] Also counter-terms in the drift are

Dynamical models

If the solutions exist, then there is a generator $L_{\kappa,p}$ and it is easy to see

$$L_{\kappa,\rho} = \frac{1}{2} \int \mathrm{d}x \,\mathrm{d}y \, C^{1-\rho}(x-y) \left(\frac{\delta}{\delta \phi(x)} \frac{\delta}{\delta \phi(y)} - \frac{\delta S}{\delta \phi(x)} \frac{\delta}{\delta \phi(y)} \right).$$

is symmetric with respect to $L^2(\mathrm{d}\mu_{\kappa,\Lambda})$ and formally,

$$\int \mathrm{d}\mu_{\kappa,\Lambda}(\phi)\,e^{tL_{\kappa,\rho}}\,F(\phi)=\int \mathrm{d}\mu_{\kappa,\Lambda}(\phi)\,F(\phi).$$

F : bounded C^2 cylindrical function.

Each choice of $\rho \in (0, 1]$ will, if equation can be solved, lead to Markov processes with same invariant measure $\mu_{\kappa,\Lambda}$.

Linear process

Linear processes

$$\begin{split} \mathrm{d}\phi_t &= \mathrm{d}W_t - \frac{1}{2}\,C_{\kappa}^{-\rho}\phi_t\mathrm{d}t,\\ \phi_t &= \phi \end{split}$$

This is an Ornstein-Uhlenbeck process/Langevin equation.

This has a unique solution

$$\phi_t = e^{-t/2}\phi_0 + \int_0^t e^{-\frac{1}{2}(t-s)C_{\kappa}^{-\rho}} \,\mathrm{d}W_{\kappa}.$$

The O-U process has continuous sample paths. Generator :

$$\mathcal{L}_{\kappa}^{(0)} = \frac{1}{2} \int \mathrm{d}x \int \mathrm{d}y \left[\mathcal{C}_{\kappa}^{1-\rho}(x-y) \frac{\delta^2}{\delta \phi(x) \delta \phi(y)} - \mathcal{C}_{\kappa}^{-\rho}(x-y) \phi(x) \frac{\delta}{\delta \phi(y)} \right]$$

.

Linear process

Linear processes

Transition probability :
$$p_t(\phi, \mathcal{B}) = \mu_{C_{t,\kappa}} \left(B - e^{-\frac{t}{2}C_{\kappa}^{-\rho}} \phi \right)$$
,
 \mathcal{B} : Borel set in $\mathcal{D}'(\Lambda_L)$.
 $C_{t,\kappa} = (1 - e^{-t C_{\kappa}^{-\rho}})C_{\kappa}$.

 $\mu_{C_{\kappa}}$: invariant measure.

 P^{OU}_{ϕ} : O-U measure on path space : $\mathcal{C}^{0}([0,\infty),\mathcal{D}'(\Lambda_{L})).$

In terms of the linear process, the full process must solve the integral equation :

$$\tilde{\phi}_t = \phi_t - \frac{\lambda}{2} \int_0^t \mathrm{d}s e^{-(t-s)C_\kappa^{-\rho}} C_\kappa^{1-\rho} : \tilde{\phi}_s^3 :_{C_\kappa} .$$

Probabilistic weak solution

Girsanov formula :

$$e^{t L_{\kappa}} F(\phi) = E_{\phi_0 = \phi}^{(w)} \left(F(\phi_t) \ e^{\xi_0^{t,\kappa}} \right) \tag{(*)}$$

O-U process : ϕ_t is a measurable function of w_t .

$$\xi^{0,(\kappa)} = -\frac{\lambda}{2} \int_0^t \left(:\phi_s^3:_{C_\kappa}, \mathrm{d} w_s \right) - \frac{\lambda^3}{8} \int_0^t \mathrm{d} s \left(:\phi_s^3:_{C_\kappa}, C^{1-\rho}:\phi_s^3:_{C_\kappa} \right).$$

Because of the cut-off κ Ito's formula applied to $e^{\xi_0^{t,\kappa}}$ shows

$$E^{(w)}(e^{\xi_0^{t,\kappa}}) = 1.$$
 (**)

Martingale property :

$$E^{(w)}(e^{\xi^{t,\kappa}_s}|\mathcal{F}_s) = 1, \ E^{(w)}(e^{\xi^{t,\kappa}_0}|\mathcal{F}_s) = e^{\xi^{s,\kappa}_0}$$

Probabilistic weak solution

Because of (**) in the previous slide, the Gaussian representation of (*) defines a semigroup with transition probabilities,

$$\hat{p}_t(\phi, \mathcal{B}) = E_{\phi}^{(w)}\left(\mathcal{X}\left(\phi_t \in \mathcal{B}\right) \, e^{\xi_0^{t,\kappa}}
ight),$$

satisfies Chapman-Kolmogoroff equation (semigroup property). \implies new probability measure \hat{P}_{ϕ} on $C_0([0, T]), \mathcal{D}'(\Lambda) = \Omega_T$. \hat{P}_{ϕ} solves the non-linear integral equation in weak sense.

$$Z_t = \hat{\phi}_t + \frac{\lambda}{2} \int_0^t \mathrm{d}s \, e^{-(t-s) \, C_\kappa^{-\rho}} C_\kappa^{1-\rho} \, : \hat{\phi}_s^3 :_{C_\kappa}, \quad \hat{\phi}_t \in \Omega_T$$

Under \hat{P}_{ϕ} , Z_t has probability distribution of an O-U process.

The drift is a gradient vector field.

Therefore we can get rid of the stochastic integral in the Girasanov exponent ξ_0^t , using Ito's formula.

The result is :

$$\begin{split} \xi_t &= -\frac{1}{2} \, V_\kappa(\phi_t) + \frac{1}{2} \, V_\kappa(\phi_0) - \int_0^t \mathrm{d}s \, \tilde{V}_\kappa(\phi_s), \\ \tilde{V}_\kappa(\phi_s) &= \frac{\lambda}{4} : \left(\phi_s^3, \, C_\kappa^{-\rho} \, \phi_s\right)_{L^2(\Lambda)} : c_\kappa + \frac{\lambda^2}{8} \left(: \, \phi_s^3 : c_\kappa, \, C_\kappa^{1-\rho} : \, \phi_s^3 : c_\kappa \right)_{L^2} \\ &- \frac{3\lambda}{4} : \left(\phi_s, \, C_\kappa^{1-\rho} \phi_s\right)_{L^2(\Lambda)}, \end{split}$$

$$\left(e^{t\,L_{\kappa}}\right)(\phi)=E_{\phi_{0}=\phi}\left(F(\phi_{t})\,e^{-\frac{1}{2}\,V_{\kappa}(\phi_{t})+\frac{1}{2}\,V_{\kappa}(\phi_{0})-\int_{0}^{t}\mathrm{d}s\tilde{V}_{\kappa}(\phi_{s})}\right).$$

$$\begin{split} & \left(G, e^{t L_{\kappa}} F\right)_{L^{2}(\mathrm{d}\mu_{\kappa},\lambda,\Lambda_{L})} \\ &= \int \mathrm{d}\mu_{\kappa,\frac{\lambda}{2},\Lambda_{L}}(\phi) \, G(\phi) E_{\phi_{0}=\phi} \, \left(F(\phi_{t})e^{-\frac{1}{2} \, V_{\kappa}(\phi_{t}) - \int_{0}^{t} \mathrm{d}s \tilde{V}_{\kappa}(\phi_{s})}\right) \end{split}$$

ULTRAVIOLET CUT-OFF REMOVAL $(\kappa \to \infty)$.

D=2 The weak solution of Jona-Lasinio, Mitter in the limit $\kappa o \infty(1985)$

Here the parameter $\rho: 0 \le \rho \le 1$ plays an important role. In other words we are studying a modified non-linear Langevin (Glauber) dynamics. The initial choice of ρ is very restricted for technical reasons : $0 < \rho < \frac{1}{10}$. Progressively, this restriction was removed by Rozovskii and Mikulevicius (1998) : $0 < \rho < 1$ and then $\rho = 1$. A strong solution was given by G. da Prato and Debussche (2003) for $\rho = 1$ in a very important work which introduced new technology (use of Besov spaces). Finally (2015) J-C Mourrat and H.Weber have extended da Prato's work to prove global in time (and also in space) pathwise solutions.

Estimates [J-L,M (CMP-1985), M(Spain-1986)], $\kappa \to \infty$

1) D = 2 $C_{\kappa} \xrightarrow{\kappa \to \infty} C$ (for massive covariance).

 $: \phi^{n} :_{\mathcal{C}} (f) \in L^{p}(\mathrm{d}\mu_{\mathcal{C}}), \ \forall p : 1 \leq p \leq \infty.$

2) The O-U transition probability $\mu_{C_t}(\phi, \cdot)$ is absolutely continuous with respect to $\mu_C(\cdot)$, μ_C a.e. in ϕ . The Radon-Nikodym derivarive is in $L^2(d\mu_C)$, μ_C a.e. in ϕ .

If $h \in L^{2p}(\mathrm{d}\mu_{\mathcal{C}})$, the trivially,

$$E_{\phi}(|h(\phi_t)|^p) < \infty, \ 1 \leq p < \infty.$$

So $h(\phi_t) \in L^p(\mathrm{d}P_{\phi}, \Omega)$.

> 3) ϕ_t is continuous in t, P_{ϕ} a.s., μ_C a.e. in ϕ . Moreover the O-U semigroup is *hypercontractive*.

> Using Riemann sum approximation, with $\kappa
> ightarrow \infty$

$$\int_0^t \mathrm{d}s \, h(\phi_s) \in L^p(\mathrm{d}P_\phi, \Omega), \ \mu_C \text{ a.e. in } \phi.$$

Therefore provided $0 < \rho < 1$

$$E_{\phi}\left(\int_{0}^{t} \mathrm{d} s\left(:\phi^{3}:_{C},C^{1-\rho}:\phi^{3}:_{C}\right)_{L^{2}}\right) < \infty,$$

 μ_C a.e. in ϕ .

Ito isometry

$$E_{\phi}\left[\left(\int_{0}^{t} (:\phi_{s}^{3}:,\mathrm{d}W_{s})\right)^{2}\right] = E_{\phi}\left(\int_{0}^{t}\mathrm{d}s(:\phi^{3}:_{C},C^{1-\rho}:\phi^{3}:_{C})_{L^{2}}\right) < \infty,$$

 μ_C a.e. in ϕ .

Because of the above, $\xi_0^{t,\infty}$ exists as a random variable.

4) We know

$$E_{\phi}(e^{\xi_0^{t,\kappa}}) = 1, \qquad \mu_C \text{ a.e.}$$

By Fatou's lemma

$$E_{\phi}(e^{\xi_0^{t,\infty}}) \leq 1, \qquad \mu_C \text{ a.e.}$$

For a martingale/weak solution we have to prove

$$E_{\phi}\left(e^{\xi_{0}^{t,\infty}}\right)\stackrel{?}{=}1.$$

5)

$$e^{\xi_0^{t,\infty}} = e^{\xi_0^{t,\infty}} - e^{\xi_0^{t,\kappa}} + e^{\xi_0^{t,\kappa}}.$$

$$|E_{\phi}(e^{\xi_{0}^{t,\infty}}) - 1| \leq |E\left(e^{\xi_{0}^{t,\infty}} - e^{\xi_{0}^{t,\kappa}}
ight)| \qquad (***)$$

$$\begin{aligned} &|E\left(e^{\xi_{0}^{t,\infty}}-e^{\xi_{0}^{t,\kappa}}\right)| \leq E_{\phi}\left(|\xi_{0}^{t,\infty}-\xi_{0}^{t,\kappa}||\left(e^{\xi_{0}^{t,\infty}}+e^{\xi_{0}^{t,\kappa}}\right)|\right) \\ &\leq \left(E_{\phi}(|\xi_{0}^{t,\infty}-\xi_{0}^{t,\kappa}|^{2})^{\frac{1}{2}}\left[\left(E_{\phi}\left(e^{2\xi_{0}^{t,\infty}}\right)\right)^{\frac{1}{2}}+\left(E_{\phi}\left(e^{2\xi_{0}^{t,\kappa}}\right)\right)^{\frac{1}{2}}\right] \end{aligned}$$

It is easy to show $|\xi_0^{t,\kappa} - \xi_0^{t,\kappa}| \to 0$ in $L^2\left(\mathrm{d} P_{\phi}^W, \Omega\right)$, μ_C a.e. in ϕ .

6) Lemma

Suppose $0 < \rho < \frac{1}{10}$. Then

$$E_{\phi}\left(e^{2\xi_{0}^{t,\infty}}
ight)<\infty,\qquad\mu_{C}$$
 a.e. in $\phi.$

 $e^{2\xi_0^{t,\infty}}$ is uniformly bounded in $L^2(\mathrm{d} P_\phi^W,\Omega)$.

7) Therefore taking $\kappa
ightarrow \infty$ in (* * *) we have

$$E_{\phi}\left(e^{\xi_{0}^{t,\infty}}
ight)=1.$$

Proof of the lemma

The idea is to undo the stochastic integral in $\xi_0^{t,\infty}$ since the drift perturbation is a gradient. To undo the stochastic integral we use the Ito's formula. Then we see that each term exists as a random variable in $L^2(dP_{\phi}^W, \Omega)$, μ_C a.e. in ϕ provided $0 < \rho < \frac{1}{2}$.

Then we use the method of Nelson and Glimm from the earliest days of constructive QFT. For the stability estimate to work we need to restrict : $0 < \rho < \frac{1}{10}$.

$$\int \mathrm{d}\mu(\phi) \, E_{\phi}\left(e^{2\xi_0^{t,\infty}}\right) = \int \, \mathrm{d}\mu_C(\phi) \, E_{\phi}\left(e^{-V(\phi_t) - 2\int_0^t \mathrm{d}s \tilde{V}(\phi_s)}\right)$$

Where

$$\begin{split} 2\tilde{V}(\phi_{s}) &= \frac{\lambda}{2} : \left(\phi_{s}^{3}, C^{-\rho}\phi_{s}\right)_{L^{2}(\Lambda)} : c + \frac{\lambda^{2}}{4} \left(:\phi_{s}^{3}:c, C^{1-\rho}:\phi_{s}^{3}:c\right)_{L^{2}} \\ &- \frac{3\lambda}{2}: \left(\phi_{s}, C^{1-\rho}\phi_{s}\right) : c \\ &\leq \left(\int \mathrm{d}\mu_{C}(\phi)E_{\phi}(e^{-2V(\phi_{t})})\right)^{\frac{1}{2}} \left(\int \mathrm{d}\mu_{C}(\phi)E_{\phi}(e^{-4\int_{0}^{t}\mathrm{d}s\,\tilde{V}(\phi_{s})})\right)^{\frac{1}{2}} \\ & \left(****\right) \end{split}$$

1) The first factor in (* * **) is easily proven to be finite.

$$\begin{split} \int \mathrm{d}\mu_{\mathcal{C}}(\phi) E_{\phi}(e^{-2V(\phi_t)}) &= \int \mathrm{d}\mu_{\mathcal{C}}(\phi) \, e^{t \, L_0} \, e^{-2V(\phi)} \\ &= \int \mathrm{d}\mu_{\mathcal{C}}(\phi) e^{-2V(\phi)} \, < \, \infty, \end{split}$$

by Nelson's estimate (have used that μ_C is invariant measure of O-U process).

2)

$$\int \mathrm{d}\mu_{\mathcal{C}}(\phi) E_{\phi}^{(w)}(e^{-4\int_{0}^{t}\mathrm{d}s\,\tilde{V}(\phi_{s})}) \leq \int \mathrm{d}\mu_{\mathcal{C}}(\phi) e^{-4t\,\tilde{V}(\phi)}.$$

(ϕ_s a.s. continuous, Riemann sum approximation, Hölder's inequality)

 $ilde{V}(\phi)$: The non-local ϕ^6 term is a positive random variable, can be dropped.

The negative sign mas term is dominated by the Gaussian measure, for small $\lambda.$

We are left with the estimate provided by the following proposition.

Proposition

For
$$0 < \rho < \frac{1}{10}$$

$$\int d\mu_C(\phi) e^{-pt\lambda G(\phi)} < \infty$$
$$G(\phi) =: (\phi^3, C^{-\rho}\phi)_{L^2}):_C, \qquad \text{in } L^p(d\mu_C) \text{ for } 0 < \rho < \frac{1}{2}.$$

► Step 1

 $(\phi^3, C^{ho}\phi)_{L^2(\Lambda)} \ge \int_{\Lambda} \mathrm{d}^2 x \phi^4(x), \quad 0 <
ho < 1.$

Proved using spectral representation and Young's inequality.

► Step 2

 $\kappa \to \infty$.

UV cut-off field (cut-off Fourier modes)

$$\phi_{\kappa}(x) = \int_{|k| \leq \kappa} \frac{\mathrm{d}^2 k}{(2\pi)^2} \, \mathrm{e}^{\mathrm{i}k \cdot x} \hat{\phi}(k).$$

$$C_{\kappa}(x, y)$$
 is μ_{C} covariance of ϕ_{κ} .
 $G_{\kappa}(\phi) = G(\phi_{\kappa})$.
 $G_{\kappa} \to G$ in $L^{p}(d\mu_{C})$ for $0 < \rho < \frac{1}{2}$.
Undo Wick ordering in G_{κ} . The Wick constants $\to \infty$ when

Using Step 1 and and estimates of Wick constants get

$$G_{\kappa} \geq -\mathrm{const} \ imes \left(\kappa^{4
ho} \left(\ln \kappa\right)^2\right)$$

Step 3

Define $\tilde{G}_{\kappa} = G - G_{\kappa}$.

Then :

$$\int \,\mathrm{d} \mu_{\mathcal{C}} |\tilde{\mathcal{G}}_{\kappa}|^{2j} \leq (j!)^4 \, b^j \left((\ln \kappa)^m \, \kappa^{-2+4\rho} \right)^j \qquad \forall j, \text{ some } m > 0.$$

Hypercontractivity to reduce $L^{p}(d\mu_{C})$ estimates to $L^{2}(d\mu_{C})$ estimates, then Feynman graph computation.

Step 4

$$\mu_{\mathcal{C}}\left(\{\mathcal{G} \leq -\operatorname{const}\left(\kappa^{4\rho}(\ln \kappa)^{2}\right) - 1\}\right) \leq \mu_{\mathcal{C}}\left(\{|\tilde{\mathcal{G}}_{\kappa}|^{2j} \geq 1\}\right)$$
$$\leq \int \mathrm{d}\mu_{\mathcal{C}} |\tilde{\mathcal{G}}_{\kappa}|^{2j} \leq (j!)^{4} b^{j}(\ln \kappa)^{m} (\kappa^{-2+4\rho})^{j}$$

Then Stirling's approximation and optimal κ -dependent choice of j gives

$$\mu_{\mathcal{C}}\left(\{G \leq -\operatorname{const}\left(\kappa^{4\rho}(\ln \kappa)^{2}\right) - 1\}\right) \\ \leq e^{-\operatorname{const}\left(\kappa^{\frac{2-4\rho}{4}}(\ln \kappa)^{-\frac{m}{4}}\right)}$$

Step 5

$$\kappa_n = 2^n \to \infty$$
, $C_{\kappa_n} = \operatorname{const} \kappa_n^{4\rho} (\ln \kappa_n)^2$.

$$\begin{split} \int \mathrm{d}\mu_{\mathcal{C}} e^{-\mathcal{G}} &= \int \mathrm{d}\mu_{\mathcal{C}} e^{-\mathcal{G}} \left(\mathcal{X} \{ \mathcal{G} > -\mathcal{C}_{\kappa_0} - 1 \} + \mathcal{X} \{ \mathcal{G} \leq -\mathcal{C}_{\kappa_0} - 1 \} \right) \\ &\leq \qquad e^{\mathcal{C}_{\kappa_0} + 1} + \mathcal{I}_0 \end{split}$$

Step 5 continued

$$\begin{split} \mathcal{I}_{0} &= \int \mathrm{d}\mu_{C} e^{-G} \mathcal{X} \{ G \leq -C_{\kappa_{0}} - 1 \} \\ &= \int \mathrm{d}\mu_{C} e^{-G} \sum_{n=0}^{\infty} \mathcal{X} \{ -C_{\kappa_{n}+1} - 1 < G \leq -C_{\kappa_{n}} - 1 \} \\ &\leq \sum_{n=0}^{\infty} e^{C_{\kappa_{n+1}} + 1} \mu_{C} \{ G \leq -C_{\kappa_{n}} - 1 \} \\ &\leq \sum_{n=0}^{\infty} e^{C_{\kappa_{n+1}} + 1} e^{-\mathrm{const} \left(\kappa^{\frac{2-4\rho}{4}} (\ln \kappa)^{-\frac{m}{4}} \right)}, \end{split}$$

and using the definition of C_{κ_n} , this series converges for $\rho < \frac{1}{10}$.

Stationary O-U process

 $ilde{P}$: measure on path space $\Omega = \mathcal{C}^0([0,\infty),\mathcal{D}').$

$$ilde{P}(B) = \int \, \mathrm{d} \mu_{\mathcal{C}_\kappa}(\phi) \; ilde{P}_\phi(B), \qquad ilde{P}_\phi: \mathsf{O} ext{-}\mathsf{U} ext{ measure}.$$

- Stationarity : $E^{\tilde{P}}\left(\phi_t(f)\phi_s(g)\right) = E^{\tilde{P}}\left(\phi_{t-s}(f)\phi_0(g)\right), \quad t > s.$
- Symmetry : $E^{\tilde{P}}(\phi_t(f)\phi_s(g)) = E^{\tilde{P}}(\phi_t(g)\phi_s(f))$.
- Covariance : $E^{\tilde{P}}(\phi_t(f)\phi_s(g)) = C_{\kappa}(f, e^{-\frac{t-s}{2}C_{\kappa}^{-\rho}}g).$

Because of stationarity : path space $\Omega \to \tilde{\Omega} = \mathcal{C}^0$ (($-\infty, \infty$), \mathcal{D}') All of this is true when $\kappa \to \infty$.

Side remark

A Euclidean formalism for the canonical choice $\rho = 1$. $x = (x_1, ..., x_D) \in \mathbb{R}^D$ $x_0 \in \mathbb{R}$, $\tilde{x} = (x_0, x) \in \mathbb{R} \times \Lambda_L \subset \mathbb{R}^{D+1}$, $\phi(\tilde{x}) = \phi(x_0, x)$, $x_0 =$ "time coordinate" = "Langevin time etc. Define :

$$ilde{\mathcal{C}}_\kappa(ilde{x}, ilde{y}) = \int rac{\mathrm{d} k_0}{2\pi} \, \int rac{\mathrm{d}^D k}{(2\pi)^D} \; rac{\mathrm{e}^{\mathrm{i} k_0 (x_0-y_0) + \mathrm{i} (k,x-y)_{\mathbb{R}^D}}}{k_0^2 + \hat{\mathcal{C}}^{-2}(k)}.$$

 $\mu_{\tilde{C}_{\kappa}}$: Gaussian measure, covariance \tilde{C}_{κ} on $\mathcal{D}'(\mathbb{R} \times \Lambda_L)$.

Side remark

 $\mathcal{D}_+(\mathbb{R} \times \Lambda_L)$: positive time subspace.

$$f_t(\tilde{x}) = f(x)\delta(x_0 - t), \ t > 0, \ \in \ \mathcal{D}_+(\mathbb{R} \times \Lambda_L).$$

Take t > s. Then an easy computation shows

$$\int \mathrm{d}\mu_{\tilde{C}_{\kappa}} \phi(f_t) \phi(f_s) = \left(f, C_{\kappa} e^{-|t-s|C_{\kappa}^{-1}}g\right)_{L^2}$$
$$= E^{\tilde{P}_{\rm OU}}(\phi_t(f)\phi_s(g)).$$

Thus the analogy is

- \tilde{C}_{κ} : Euclidean covariance.
- C_{κ} : Fock space covariance.

"Time" reflection θ :

$$f_t(\tilde{x}) = f(x) \, \delta(x_0 - t) \quad \in \mathcal{D}_+(\mathbb{R} \times \Lambda_L), \ (heta f_t)(\tilde{x}) = f(x) \delta(x_0 + t).$$

Reflection positivity :

$$\begin{split} \langle \phi(f_t), \phi(f_t) \rangle &= \int \mathrm{d}\mu_{\tilde{C}} \ (\theta\phi)(f_t)\phi(f_t) = \int \mathrm{d}\mu_{\tilde{C}} \ \phi(\theta f_t)\phi(f_t) \\ &= E_{\mathrm{OU}}^{\tilde{P}} \left(\phi_t(f) \phi_{-t}(f)\right) \ge 0. \end{split}$$

You can apply the O-S construction of Hilbert space, semigroup etc. This could be the beginning of an Euclidean formalism for the non linear process.

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