



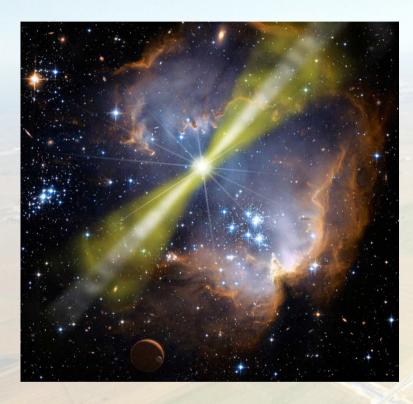
Computing issues in experimental gravitational wave research: Virgo computing

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Content



Artists's view of a gramma-ray burst

Credit: NASA/Swift/Mary Pat Hrybyk-Keith and John Jones

(... a possible source of gravitational waves)

Gravitational waves

What are to so called gravitational waves?

Virgo experiment

• A one slide introduction to the Virgo experiment

Computing model walkthrough

Scale, type and strategies in Virgo computing

Data transfer

Transfer of measurement data to CCs

Analysis types

Computing needs of analysis workflows

Pipeline execution problems

Problems related to pipeline execution

GPU perspectives

How GPUs can help us in cheaper computing

Cloud solution

Why a computing cloud would be excellent for Virgo

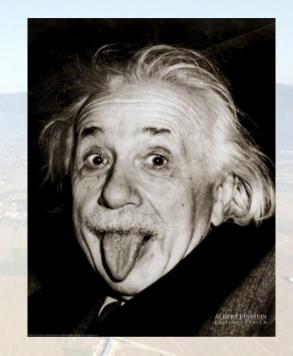
Future plans

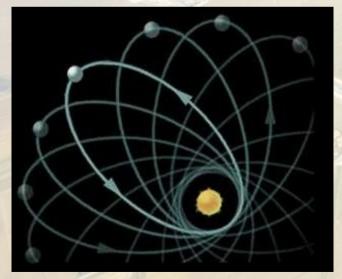
Things we would like to work on in the future

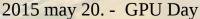
About gravitational waves

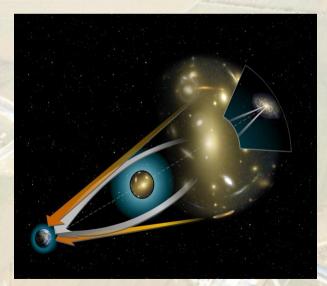
- Several predictions of Einstein's general relativity has already been confirmed experimentally, like
 - advance of perihelium
 - gravitational lensing
 - change of elapse of time in strong gravitational fields, etc...
- but we have only indirect (but very good) proof for the existence of gravitational waves

The direct detection of GWs are the goal of the VIRGO experiment.

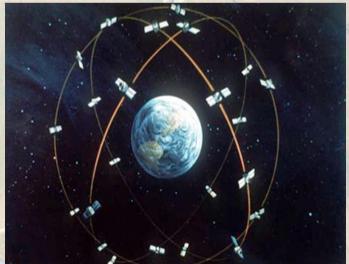






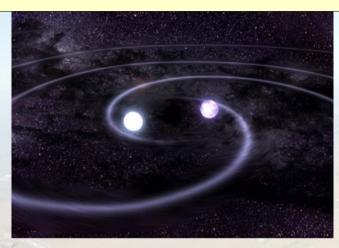


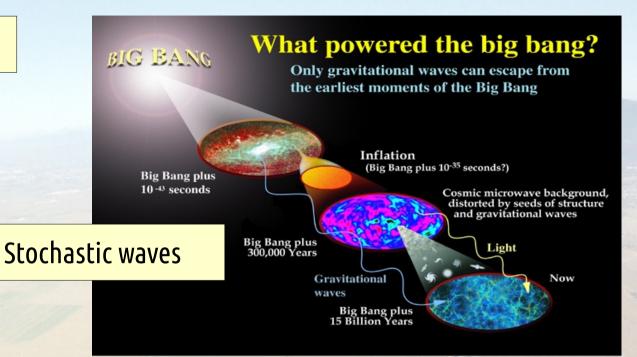
Gergely, DEBRECZENI - GRB forecastin



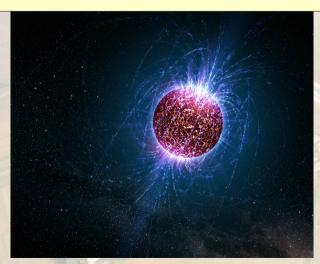
Classification of GW sources

Compact Binary Coalescence





Pulsars, neutron starts



Bursts, supernovaes

2015 may 20. - GPU Day

Gergely, DEBRECZENI - GRB forecastin

The Virgo experiment

• The Virgo detector is located in the site of the European Gravitational Observatory (EGO) in Cascina, near Pisa, Italy.

- Construction finished in 2003
- It is now a european collaboration including France, Italy, Hungary, Netherland, Poland
- Working together with LIGO (Laser Interferometer Gravitational-wave Observatory), synchronized observations and coordinated analysis
- So far, approixmately c.c 20 month of data taking
- Currently under upgrade, will start to collect scientific data in early 2016



The Virgo Computing Model in 1 slide

- 1) Data is taken by the 3 detector (Virgo + 2 LIGO detector)
- 2) Online (low-latency) analysis happens on the measurement site.
- 3) Data is stored at site temporarly in a circular buffer (typicaly for 6 month)
- 4) All data is transferred with c.c. 1 day latency to external CCs and stored in 3 different location (Lyon, CNAF, Ligo site)
- 5) For **offline** analysis Virgo uses its two main CCs and the INFN Grid sites, while LIGO uses dedicated Condor clusters and XEDE supercomputer resources
- 6) Offline analysis based on Condor DAG, Pegasus DAX and shared file system based workflows and/or simple EMI Grid submission mechnisms.
- 7) No collaboration-wide unified job scheduler is used. Multiple solutions.
- 8) Analysis code must undergo serious review, coordinated prioritisation and optimisation efforts. Reviewed code is tagged, freezed.

Type of measurement data

- The measurement data is a **simple time series**, sampled at 20 kHz, then downsampled to 16 kHz and 4 kHz.
- There are hundreds of auxiliary environmemntal channels, some of them with much lower frequencies and sampling rate.
- Amount of data is a few hundred TB / yr but its arithmetic complexity is much higher than that of the HEP experiments.
- Depending on the source to be examined / discovered many different kind of analysis is crunching this data with computing requirements differing by order of magnitued.
- Different analysis requiring different input data size and computing architectures
- Gravitational wave analysis is compute intensive not data intensive

Data transfer

- Measurement data produced in Cascina on the Virgo site.
- Low latency online analysis happens in place and data is stored temporarly on site using a circular buffer of length of several month.
- For **offline analysis** this data must be transferred to the computer centers.
- For this purpose a transfer tool was developed by EGO Computing department. Existing out-of-the box solutions such as FTS were too heavy to maintain.
- It uses the
 - lcg-tools to transfer data to CNAF
 - and the iRod client installation for IN2P3
- The amount of data is not overwhelming, in principle data transfer should not be a challange
- Data from LIGO detectors does also get copied to our CCs. This data consist(ed) of small file which must be merged to bigger ones in order to fit better for HPSS storage. Now this problem had been solved

Data transfer issues

- Virgo is using different data transfer tools for different data transfers. Each of them is easy and works reliably, however the need for using multiple backend needs extra manpower and development.
- A preffered solution would be to use the LDR (LIGO Data Replicator) data transfer framework all over in the LIGO-Virgo collaboration which can communicate with legacy GSIFTP backends and perform reliable data transfer.
- GSIFTP is not available in IN2P3 which is a problem, probably will be solved soon

Data file and metadata catalogs

- Some analysis is using the LFC (Lightweight File Catalog). Its use is easy and we found no problem with it.
- The Disckcache software is used to catalog files available in a given CC and respond to queries of the pipelines with physical location of files.
- Typical query includes GPS times, detector name, channel name -> there is not too much metadata that can be assigned to measurement data.
- No file metadata catalog is used so far, there is not too much need for that. Many information is in file names and can be easily queried.

Analysis pipelines

- CW (Continuos waves) Rotating, assymetric neutron stars
 - The most compute intense pipeline, practically can consume all available resources.
 Sensitivity goes like 1/sqrt(T), where T is the duration of data chunk in question. As a result one must restrict parameter space explored -> computing contraints yields scientific limitation.
- CBC (Compact Binary Coalescence) Gravitational waves emitted by coalescing binarie neutron stars or binary black holes
 - Very compute intensive, theoretical templates are tested againts the measurement data by means of matched filter. With the decrease of low frequency cutoff compute costs grows exponentially.
- Burst Explosions, supernovas, unmodelled tranzient sources
 - Very similar but more generic than CBC. Sensitivity is comparable (~c.c 30% less).
- Stochastic Search for stochastic gravitational waves of galactic or primordial origin
 - Important from physics point of view, but has negligible compute cost.

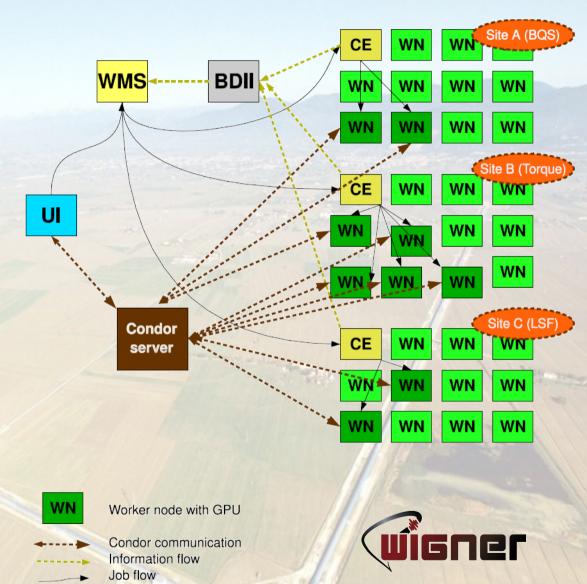
Analysis pipeline problems

- LIGO and Virgo collaboration is working closely together.
- However LIGO collaboration is larger by a factor of > x10
- As a result many important pipeline development is dominated by LIGO colleagues and are tailored to LIGO resources
- As a consequance those pipelines cannot be executed out of the box on our resources, but requires quite some porting effort.
- This effort is not a one time action, but needs continouse attention -> very expensive in terms of time and manpower...that Virgo cannot afford.
- Many attempts have been made to overcome this difficulty including
 - the set up of a pilot pool framework
 - using the Pegasus scheduler
 - examining the possibility of using the Dirac jobmission framework
 - thinking on virtualized Condor cluster, i.e. a Cloud

The Virgo Pilot Pool - I

The Virgo Pilot Pool properties:

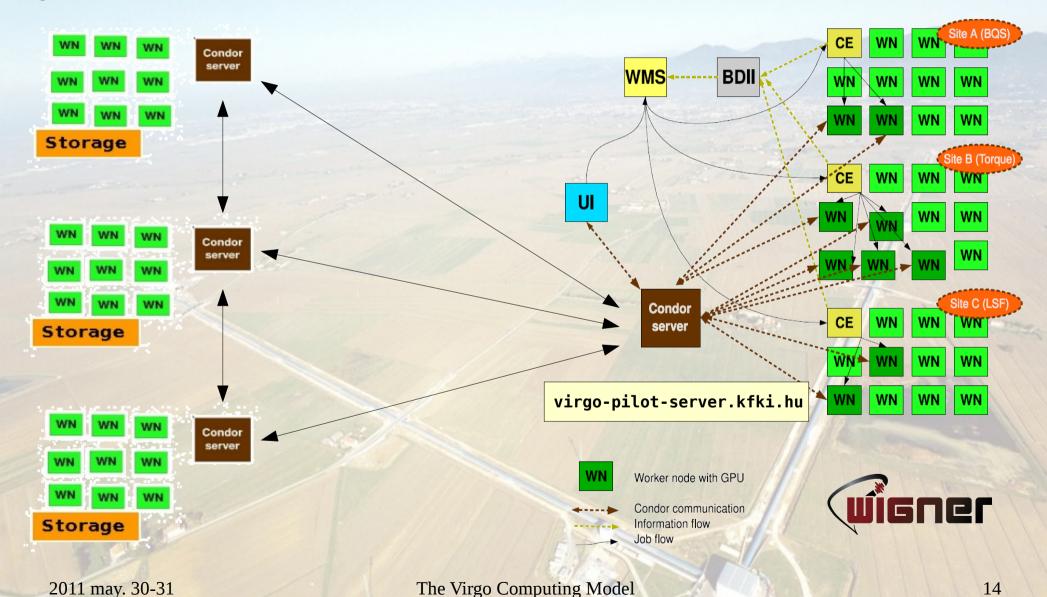
- Homogen infrastructure over the inhomogen Grid
- Less administrative interaction/delay
- User transparent mechanisms
- Low latency submission
- Global priorities
- Late-binding to resources
- No stucked-in jobs
- Improved job failure rate due to pilot prechecks
- Interactive login
- Smooth interaction interoperability with LDG/OSG.



The Virgo Pilot Pool - II

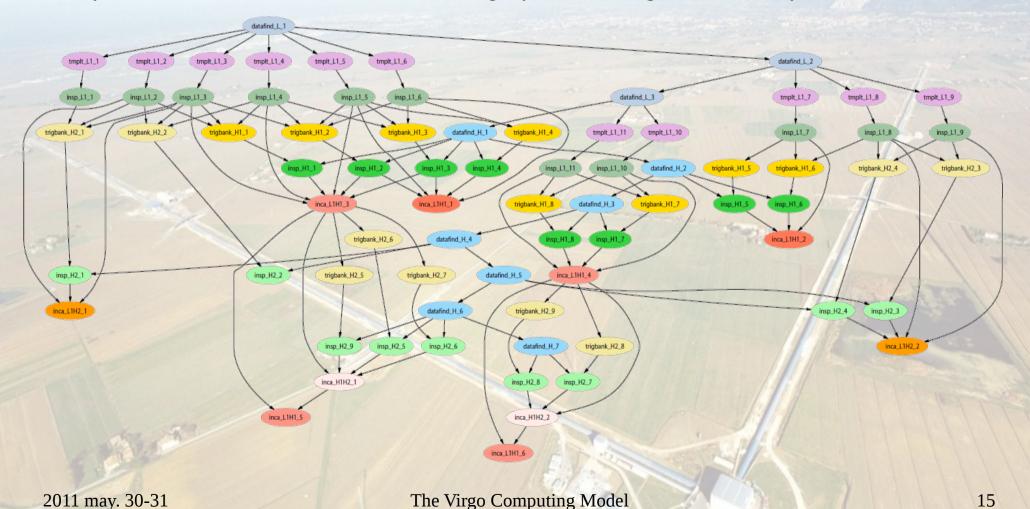
Ligo clusters

Virgo EGI sites



The Virgo Pilot Pool - III

- Mapping of abstract workflows like DAGs/DAXes to the Grid is now easily possible with the Virgo Pilot server.
- Complex and relational workflow handling is/was missing from Cream/WMS.



Cloud 4 Virgo

- Out of the above possibilities each of them has some serious drawbacks except the Cloud solution
- Having an OpenStack based virutal Cloud Condor installation at CNAF would solve almost all our problem including,
 - pipeline porting
 - architectural difference respect to LIGO clusters
 - training of people and the must to learn multiple submission mechanisms
 - real sharing of our resources
 - ease of GPU access and GPU CPU matching, allocation problems
 - better monitoring of user jobs

GPUs for analysis

- Many search algorithm can be accelerated by making use of operation level paralellizability offered by various many-core hardwares such as GPUs. Such examples are:
 - FFT, vector operations, reduce, max finding, clustering in CBC analysis pipelines
 - FFT, 2D thresholding, differential Hough map creation, integration, peak finding, etc.. in CW analysis
- There are multiple tool developed to allow easier use of GPUs by less advanced programmers, such as:
 - GWTools An OpenCL based templates C++ generic algorithm library for GW searches
 - pyCBC CUDA based set of Python algorithm used in CBC analysis
 - CB Compute Backend offers a unified host code for CUDA and OpenCL, so there is no need to write the code twice for NVidia and AMD cards
- GPUs will play crucial role in the following years probably even for the discovery
- •Typical full-pipeline accelerations experienced are ranging from x30 to x120

Optimisation, prioritisation

- The LIGO Virgo analysis software stack went through on a serious process of review, benchmarking and optimisation.
- The process was triggered by the NSF review of LIGO request for XEDE resources
- It has a very positive effect on the quality, organisation and performance of the code used for analysis in the Collaborations.
- Analysis type based compute resource request estimation, logging and accounting and prioritisation is just under introduction in the collaborations
- A common unit of measure for called "Service Unit" SU has been introduced, since we observed that HS06 numbers are not alway accurate enough in reflecting the ratios of performances of a specific CPU cores for specific analysis. 1 SU corresponds to the performance of an Intel Xeon E5-2650 core.
- LVCN the LIGO Virgo Computing Network was estableshed

LVCN supply table

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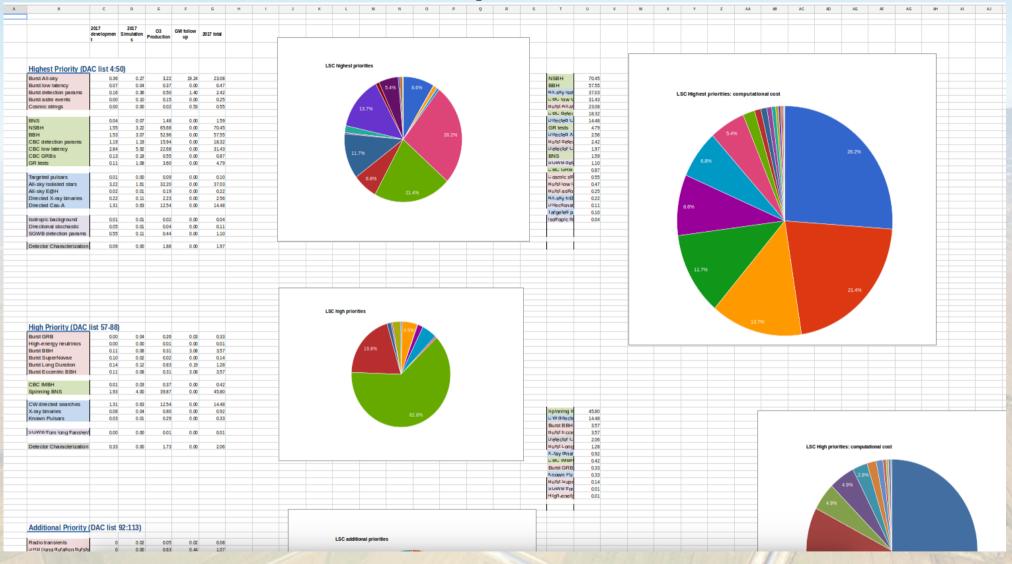
An example for demand - supply - benchmark matchmaking sheet

LVCN pipeline needs

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27 SURST HCN Trapped search - Offine High-energy rectaffors SURS Hen Note of High-energy rectaffors CWR25 Major Superhove High-energy rectaffors CWR25 Major Superhove High-energy rectaffors CWR25 Major Superhove High-energy rectaffors High	25	Code Group	Search	Pie Name	Software	job schedu	Tb/yea	2015	2016	2017	2015	2016	2017	01	02	03	01	02	0	3 Start	End	taking	(hours)	(albert.einstein)		
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3 BURST All-sky long-duration burst- offline (tot) Burst Long Duration See Burst Lab		50,,0,								•	23,000	61,000	61 000	35,000	152,000	225 000		128 000	101 000	,						
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An example for pipeline computing requirements collection

LVCN priorities



Different analysis with different prioritites

Uncertainties of compute and storage estimates

Storage estimates are derived from detector bandwidth and expected duration of observation times known in advance, so there not too much uncertainties here.

As for the compute needs the source of uncertainties are as follows:

- Which pipelines will be ported to GPUs and when
- How successfully the sharing of resources will happen with LIGO collaboration
- Possibility of Condor CLOUD installation
- Available budget for computing in EGO
- Currently Virgo is providing only c.c 8% of the total computing power for the LVC collaboration. This cannot be mainteined on the long term, there is a need for massive increase.

The Compute Backend (CB)

The problem

- For several reason (cost efficiency, manpower, future hardwares, etc..) the analysis code has to be generic
- It is always a subject of debate which language to use to program GPUs.
- Double coding for multiple interface is a waste of time and manpower.

The solution:

- THE COMPUTE BACKEND (CB) IS ADDRESSING THIS PROBLEM BY PROVIDING UNIFIED INTERFACE FOR VARIOUS GPU PROGRAMING LANGUAGES, SUCH AS CUDA AND OPENCL!
- It levreages the burden of host-side double coding and the very same code can be used to run on CUDA (NVidia) or OpenCL (AMD, Intel, Samsung, etc...) devices...

Compute Backend (CB) features:

- C and C++ API (fortran, python and c# on the way...)
- CUDA and OpenCL backends (ComputeGl, RenderScript considered)
- Single host-side code for multiple backend
- Runs under Linux/Windows/MacOS
- Compatible with CMake, Autoconf, MSVC, etc.
- Academic license is available
- User support around the clock

Compute Backend is available on

http://x-perception.com

The Compute Backend - the CAPI

```
#include <stdio.h>
#include <stdlib.h>
#include <cb.h>
int main() {
  // Auxiliary variables
  int err;
  int i;
  // Sets the log level
  cb log level = 5;
  // Get some buffer
  unsigned int num elements = 1024;
  unsigned int size = num_elements * sizeof(float);
  // ... and also on the host side
  float * h buffer1 = (float *) malloc(size);
  float * h buffer2 = (float *) malloc(size);
  float * h buffer3 = (float *) malloc(size);
  // ... fill up the buffers
  for (i = 0; i < num elements; i++) {h buffer1[i] = 4; h buffer2[i] = 11;}
  // The C API
  // A compute backend
  cb backend backend;
  cb program prog;
  cb kernel kernel1, kernel2, kernel3;
  cb buffer buffer1, buffer2, buffer3;
  // Get the compute backend
  err = cbGetComputeBackend(&backend);
  // Get a program
  err = cbGetProgram(&backend, "/home/me/testt", &prog);
  // Get the kernel
  err = cbGetKernel(&prog, "test kernel", &kernel1);
  err = cbGetKernel(&prog, "simple kernel", &kernel2);
  err = cbGetKernel(&prog, "buffer kernel", &kernel3);
```

```
err = cbCreateBuffer(&backend, CB READ WRITE, size, NULL, &buffer1);
  err = cbCreateBuffer(&backend, CB_READ_WRITE, size, NULL, &buffer2);
  err = cbCreateBuffer(&backend, CB_READ_WRITE, size, NULL, &buffer3):
  // Send some data to device
  err = cbWriteBuffer(&backend.gueues[0], &buffer1, size, h buffer1, true);
  err = cbWriteBuffer(&backend.gueues[0], &buffer2, size, h_buffer2, true);
  // Set the kernel sizes
  cbExtent g size = cbSetExtent(1,1024);
  cbExtent | size = cbSetExtent(1, 32);
  // Execute the kernel
  cbParam b1 arg = cbBuffer(&buffer1);
  cbParam b2 arg = cbBuffer(&buffer2);
  cbParam b3 arg = cbBuffer(&buffer3);
  cbParam n arg = cbInt(100);
  err = cbExecuteKernel(&backend.gueues[0], &kernel3, g size, I size, 4,
&b1 arg, &b2 arg, &n arg, &b3 arg);
  // Read back the result
  err = cbReadBuffer(&backend.gueues[0], &buffer3, size, h buffer3, true);
  // Printing the result
  for (i = 0; i < 10; i++) printf("%f", h buffer3[i]);
  printf("\n\n");
  // Releasing stuff
  free(h buffer1);
  free(h buffer2);
  free(h buffer3);
  // Exit
  return err;
```

The Compute Backend - the C++ API

```
#include <stdio.h>
#include <stdlib.h>
#include <iostream>
#include <cb.hpp>
int main() {
  // Sets the log level
  cb \log |eve| = 5;
  int err:
  int i;
  // Get some buffer on the host side
  unsigned int num elements = 1024;
  unsigned int size = num_elements * sizeof(float);
  float * h buffer1 = new float[num elements];
  float * h buffer2 = new float[num elements];
  float * h buffer3 = new float[num elements];
  // ... fill in the buffers
  for (i = 0; i < num elements; i++) \{h buffer1[i] = 4; h buffer2[i] = 11; \}
  // Construction Backend, Program, Kernel and Buffers
  cb::Backend bck:
  cb::Program prg(bck, "/home/me/test");
  cb::Kernel TestKernel(prg, "test kernel");
  cb::Kernel SimpleKernel(prg, "simple_kernel");
  cb::Kernel BufferKernel(prg, "buffer kernel");
  // Initializing the buffers
  cb::Buffer b1(bck, CB READ WRITE, size, NULL);
  cb::Buffer b2(bck, CB READ WRITE, size, NULL);
  cb::Buffer b3(bck, CB READ WRITE, size, NULL);
  // Send data to device
  b1.Write(bck.GetQueue(), h buffer1);
  b2.Write(bck.GetQueue(), h buffer2);
  // Set the kernel sizes
  cb::Extent g(num elements);
  cb::Extent I(32);
```

```
// Create kernel arguments
cbParam buff1 arg = cbBuffer(b1);
cbParam buff2 arg = cbBuffer(b2);
cbParam buff3 arg = cbBuffer(b3):
cbParam numarg = cbInt(100);
// Execute the buffer kernel
BufferKernel(bck.GetOueue(), g, l, 4, &buff1 arg, &buff2 arg, &numarg, &buff3 arg);
// Read back the result
b3.Read(bck.GetOueue(), h buffer3);
// Some output for checking the result
for (int i = 0; i < 10; i++) {
  std::cout << h buffer1[i] << " " << h buffer2[i] << " " << h buffer3[i];
// Releasing stuff
delete h buffer1:
delete h buffer2:
delete h buffer3;
// Exiting
exit(0);
```

```
Compile for CUDA:

cd build cmake -DOPENCL_BACKEND=1 ../ make

Compile for OpenCL:

cd build cmake -DCUDA_BACKEND=1 ../ make
```

Summary

- Computing model and operation of gravitational wave experiments are well understood and establised
- There are multiple problem to be faced and solved due to the usage of loosely coupled resources and distinct administration.
- The community goes under a change, evolution that was experienced in HEP c.c 12 year ago...
- We should use those tools developed and experiences accumulated since then...
 and avoid the mistakes