STIX

The Spectrometer/Telescope for Imaging X-ray on Solar Orbiter

Flight design, challenges and trade-offs

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—— for the STIX collaboration ——

13th Pisa Meeting on Advanced Detectors

29 May 2015, Elba



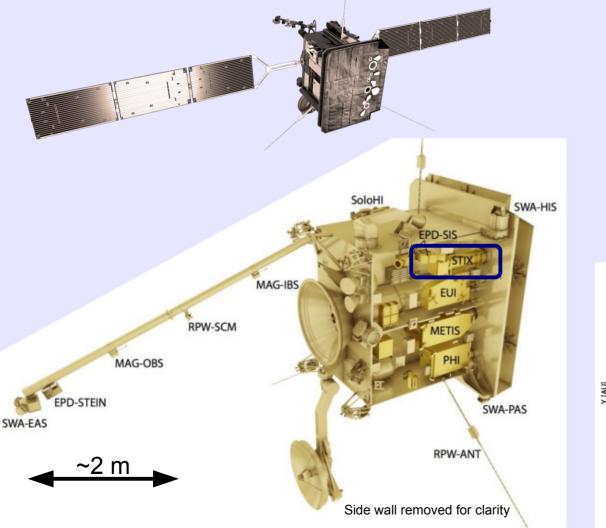


University of Applied Sciences Northwestern Switzerland

ESA Solar Orbiter

"How does the Sun create and control the heliosphere?"

- Sun-heliosphere interaction
- Energetic solar phenomena
- Solar transients, heliospheric variability
- Solar wind accelerating mechanisms
- Solar wind plasma, coronal magnetic fields
- Solar dynamo working principle

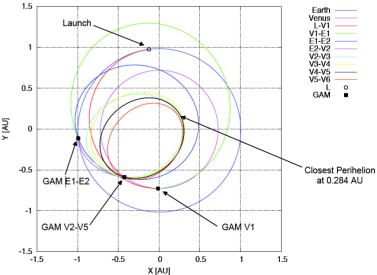


remote-sensing and in-situ

10 instruments

Mass **1.8 t** Power **180 W** Telemetry **150 kbps** (@ 1 AU)

Launch October **2018** Mission duration **4+3 years**



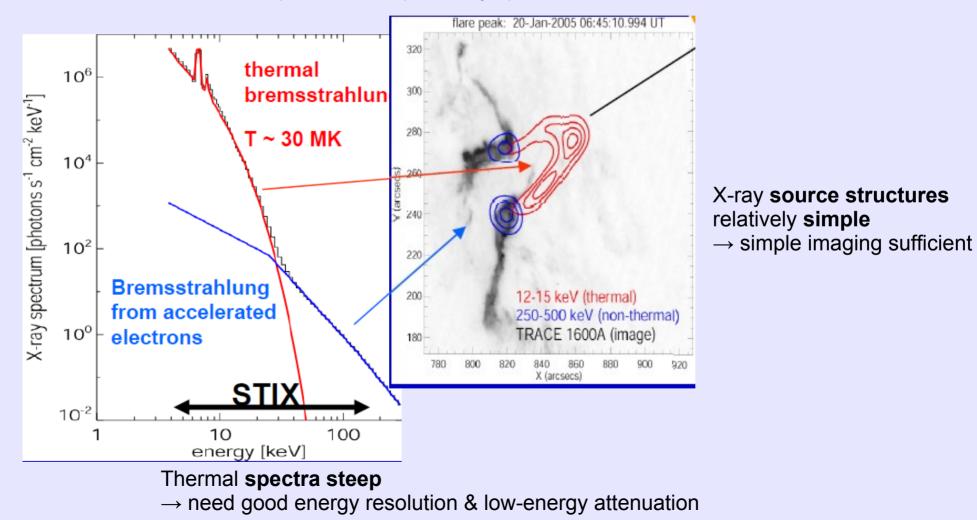
STIX Science Goal

Imaging of the Sun in 4-150 keV X-rays determines

intensity, spectrum, timing and location of energetic electrons near the Sun.



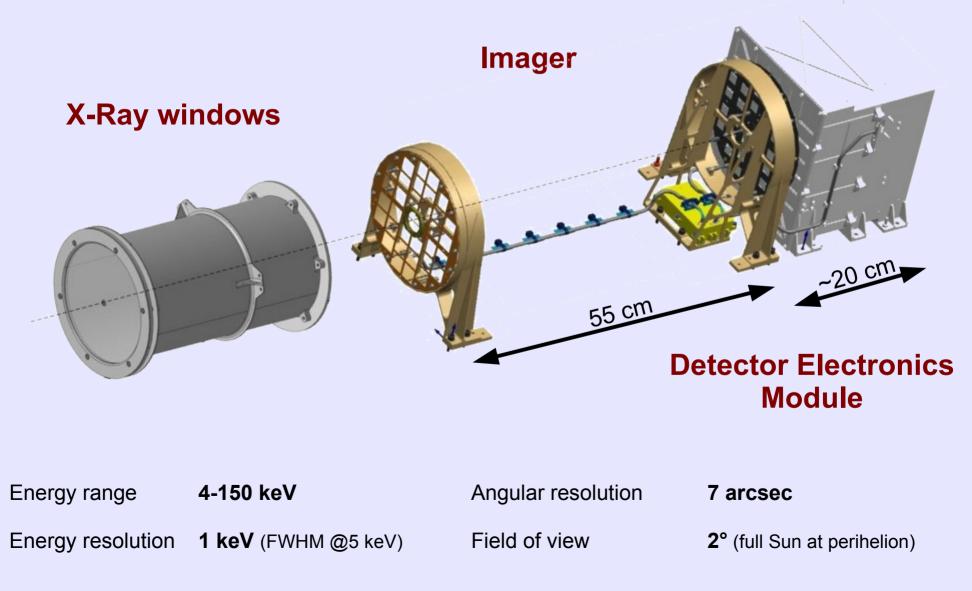
electron transport into interplanetary space



STIX Design

Instrument allocation 8 W power, 7 kg mass and 700 bits/s telemetry

 \rightarrow only indirect Fourier imaging feasable at X-ray energies for required parameters



STIX imaging principle

Pairs of X-ray opaque grids with slightly different pitch and orientation

 \rightarrow Moiré transmission pattern

Large-scale Moiré structure encodes source direction (Fourier component)

 \rightarrow Coarse pixels sufficient for high angular resolution

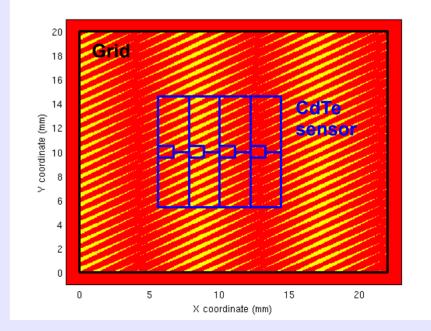
Number of grid pairs determines allowable source complexity

ExamplePitch 666 / 690 μ m, angle 60° / 64° \rightarrow Moire period 10 mm

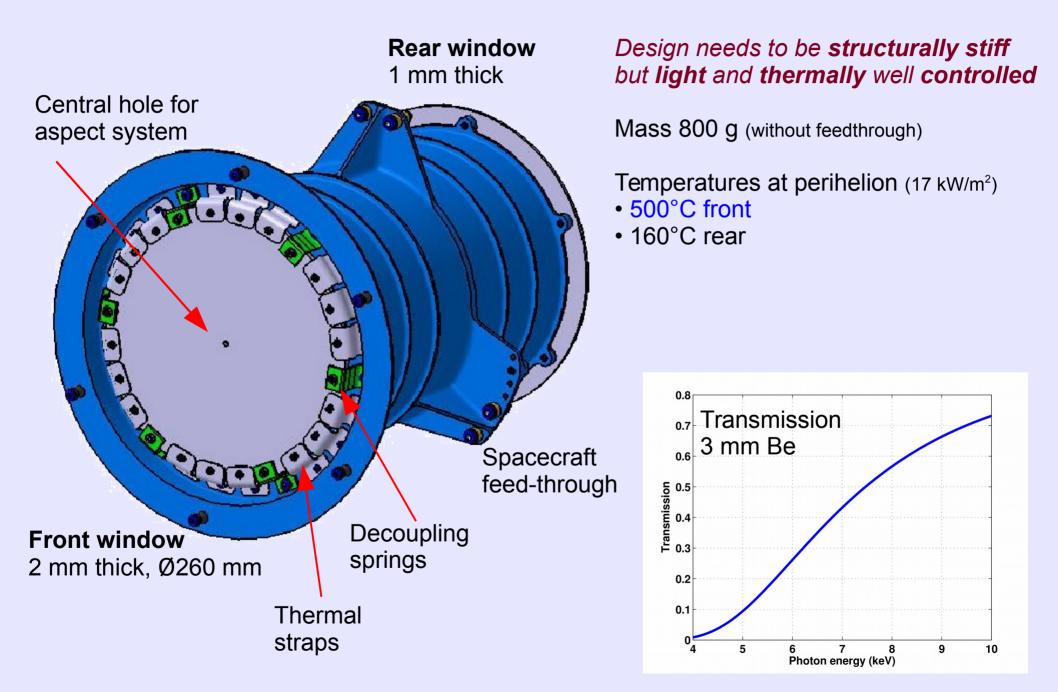
Pixel count rate differences encode source direction

Angular resolution $\approx \frac{1}{2}$ grid pitch / grid separation

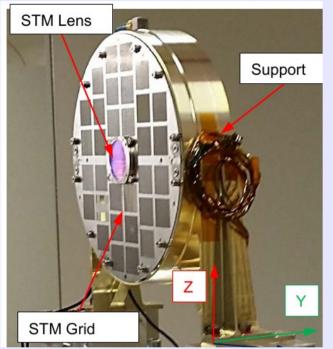
Orientation of Fourier component and of Moire pattern decoupled



Beryllium X-ray windows



Imager



Front grid

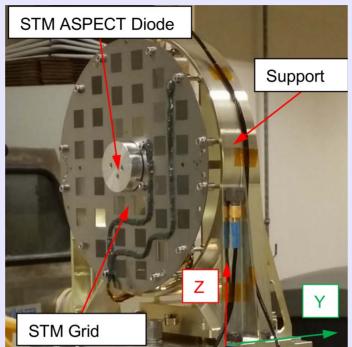
32 Tungsten grid pairs

Thickness 400 µm Pitch 38 µm – 1 mm

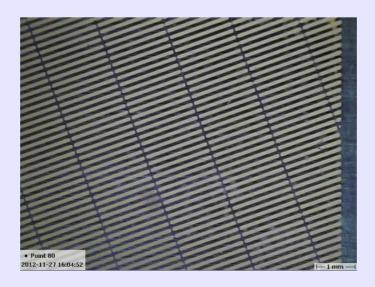
30 Fourier components/3 directions 2 special counters

Produced from etched and stacked Tungsten foils

Oliver Grimm



Rear grid



Design needs to **prevent relative twist** of grids, be structurally **stiff** and **light**

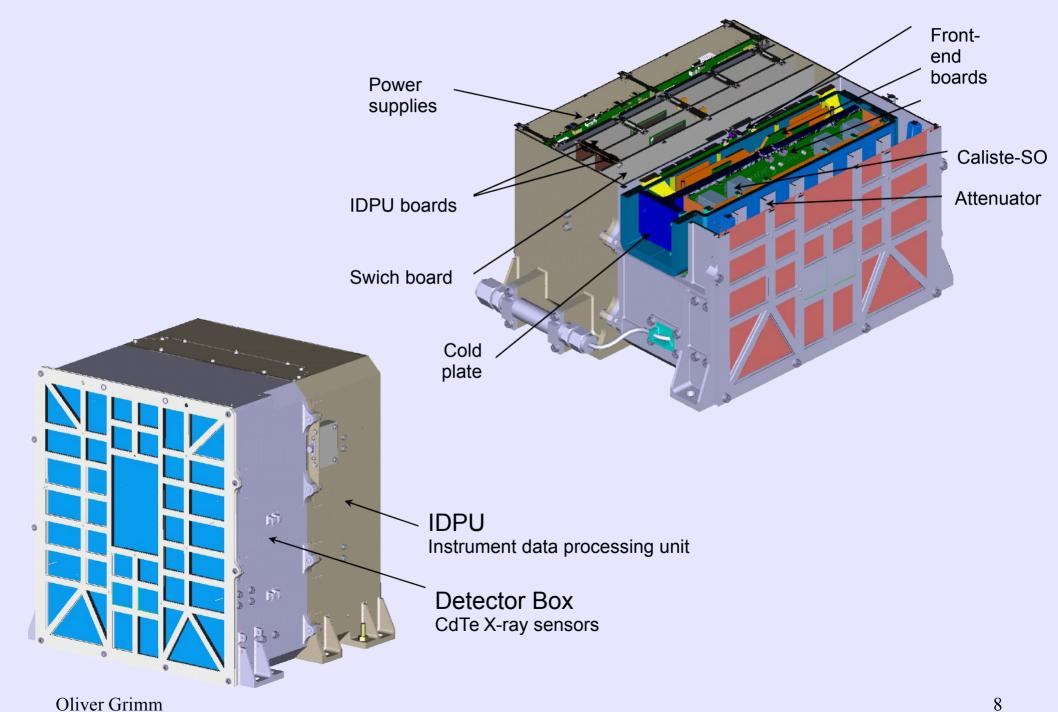
Grid separation 55 cm

Mass ~1.6 kg

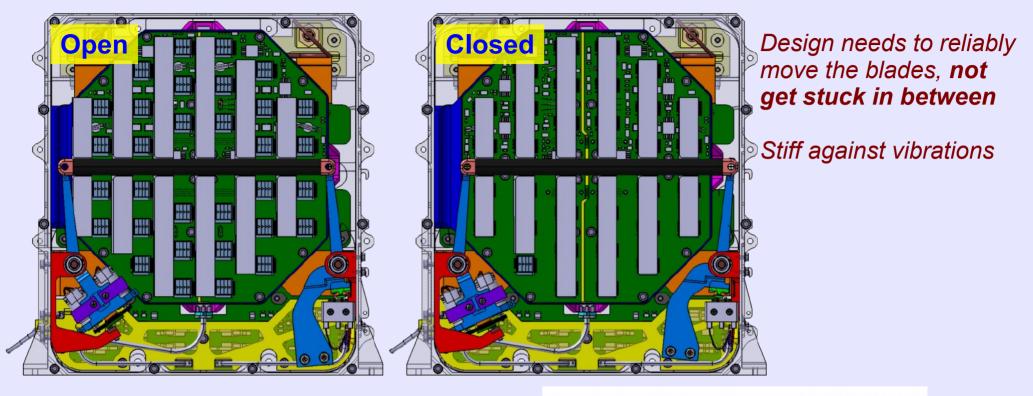
Aspect system

- images Sun onto photodiodes
- detects solar rim
- establishes line of sight to 4 arcsec

Detector Electronics Module (DEM)

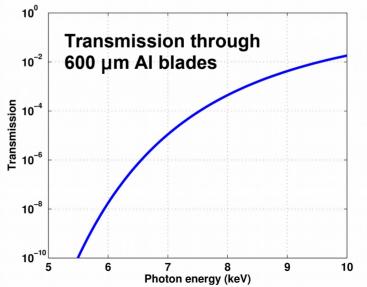


Mechanical attenuator

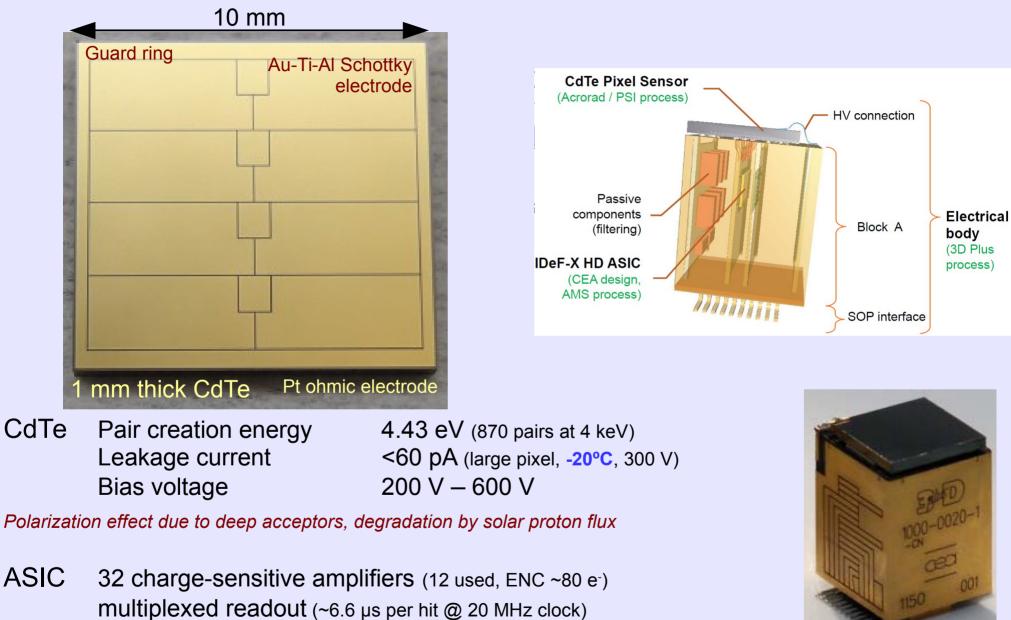


Design life 20'000 cycles

Movement open-closed 2 seconds No launch lock (balanced mechanism) Both position stable without motor power Autonomous insertion based on count rates



CdTe, Caliste-SO hybrid

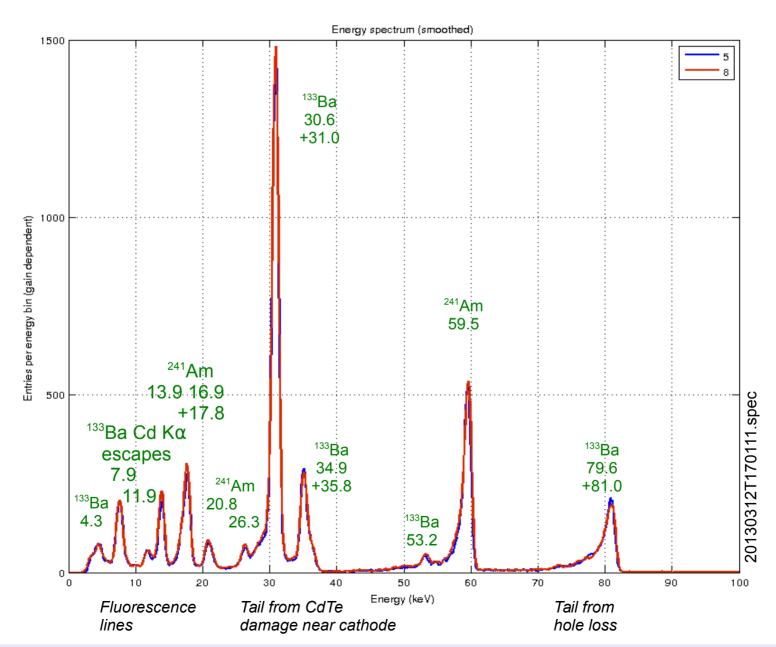


~1 mW (per active channel)

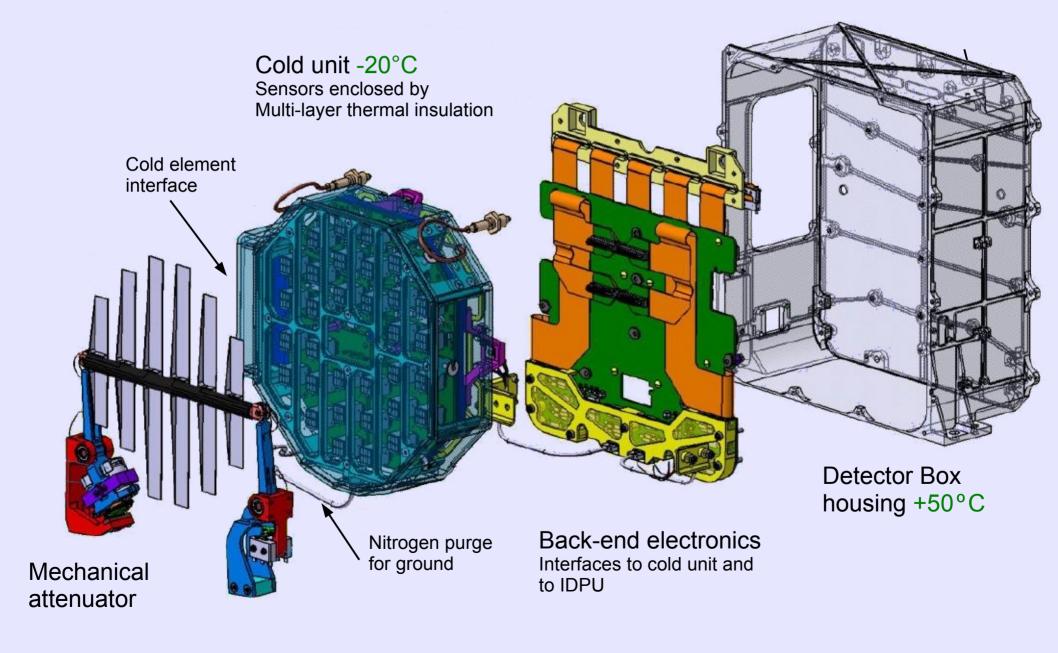
Not optimized for high-rate application in STIX

Spectrum with ¹³³Ba and ²⁴¹Am simultaneously

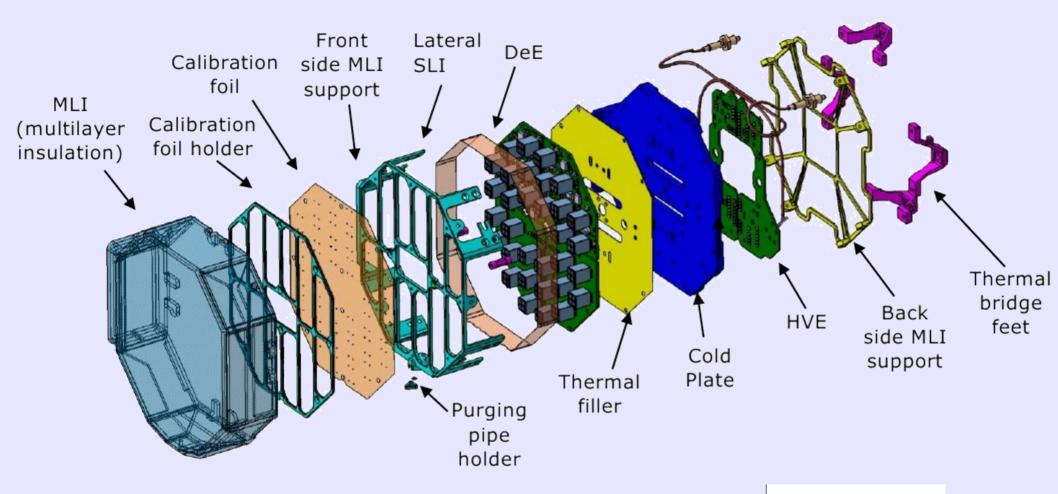
-200 V, -21°C, total leakage current 1.4 nA, threshold 1.8 keV, peaking time 4.7 μs Energy calibration with 31 and 81 keV lines



Detector Box



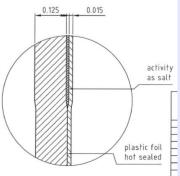
Cold unit



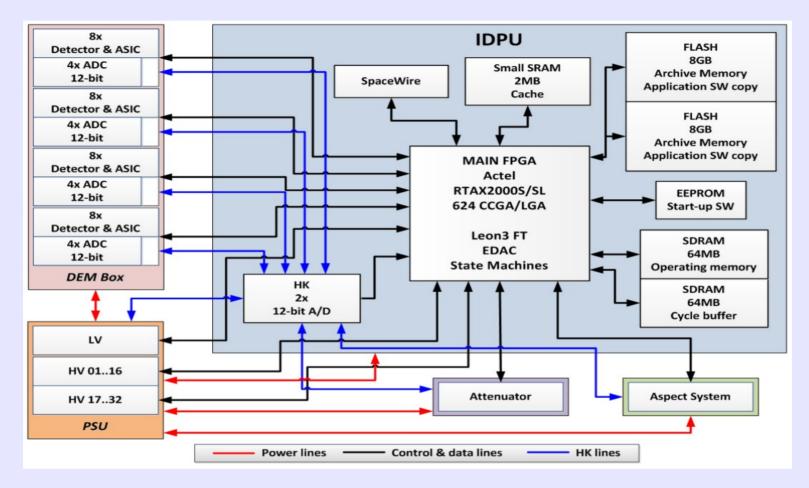
Radioactive source for energy calibration

Calibration changes due to charge collection degradion, ASIC response change with changing leakage current, ASIC gain / offset have small temperature dependence

Barium-133 (t¹/₂=10.5 years), 128 dots with \approx 3 Bq activity between plastic foils Require 100 eVrms calibration precision



FPGA instrument control



Event rates up to 10⁶ s⁻¹ during strong Solar flares, 700 bps average downlink

Flight software runing on LEON3 processor synthesized on FPGA

Several month of science data can be stored on-board

 \rightarrow provides telemetry flexibility by allowing off line data selection and downlinking

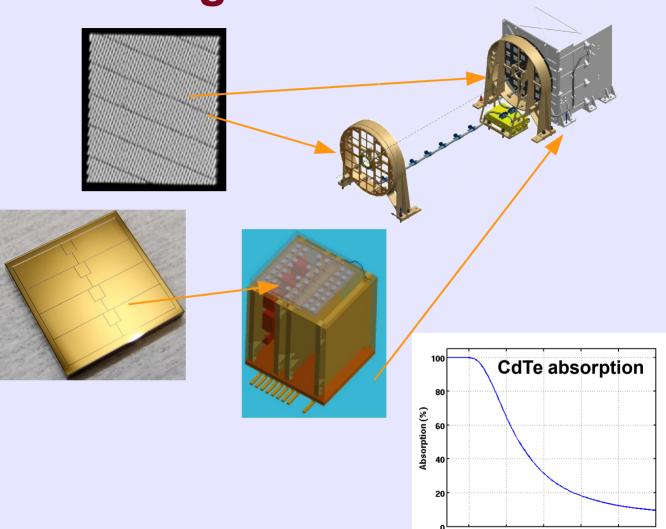
STIX at a glance

X-ray windows Thermal protection

32 Tungsten grid-pairs Pitch 38 μ m – 1 mm, 400 μ m thick

32 Caliste-SO hybrids 32 CdTe, 10x10x1 mm³, ASIC Cooled to < -20°C

Data processing/control Based on single FPGA



50

100

150

Energy (keV)

200

250

300

Flight instrument delivery to ESA October 2016

Launch October 2018

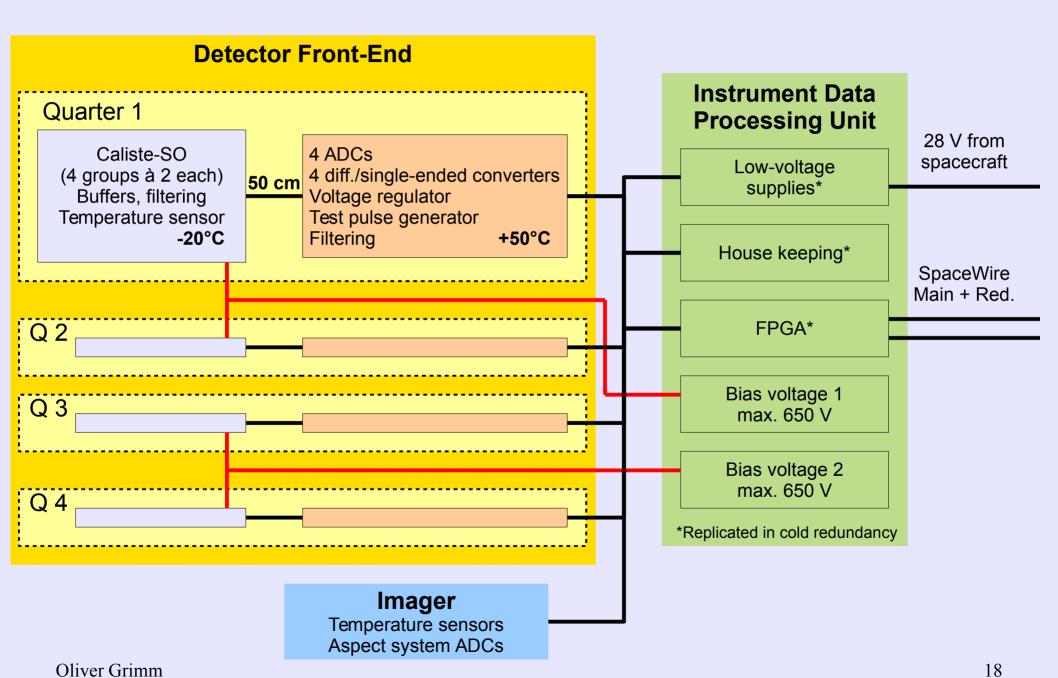
Science phase starting 2021

Extra slides

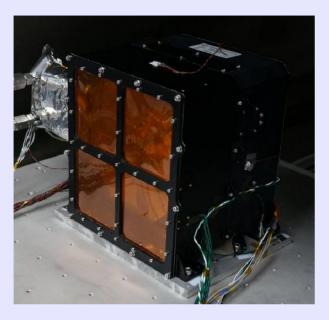
Main design challenges

Operation under vacuum	\rightarrow	Thermal & electronics design Heat transport only through conduction or radiation Incoming solar flux 17 kW/m ² Heat rejection only by radiation to space (power limit) CdTe: need (passive) cooling to -20°C in +50°C environment
Launch environment	\rightarrow	Mechanical design
		Shocks and vibration, eigenfrequencies > 140 Hz Mass limit
Radiation environment	\rightarrow	Component selection
		10 year mission duration Total ionizing dose (TID) ~30 krad not too severe CdTe: Non-ionizing dose (NIEL) degrades performance
Space-qualified design	\rightarrow	Component selection, redundancy
		Limited choice, ofter larger or more power demanding
Large distance from Earth	\rightarrow	Operations concept, fault tolerance Telemetry rate limited \rightarrow data compression, selection Autonomous operation up to 80 days \rightarrow failure detection

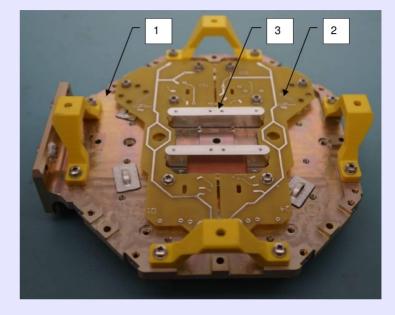
Simplified STIX block diagram



DEM structural thermal model (STM)

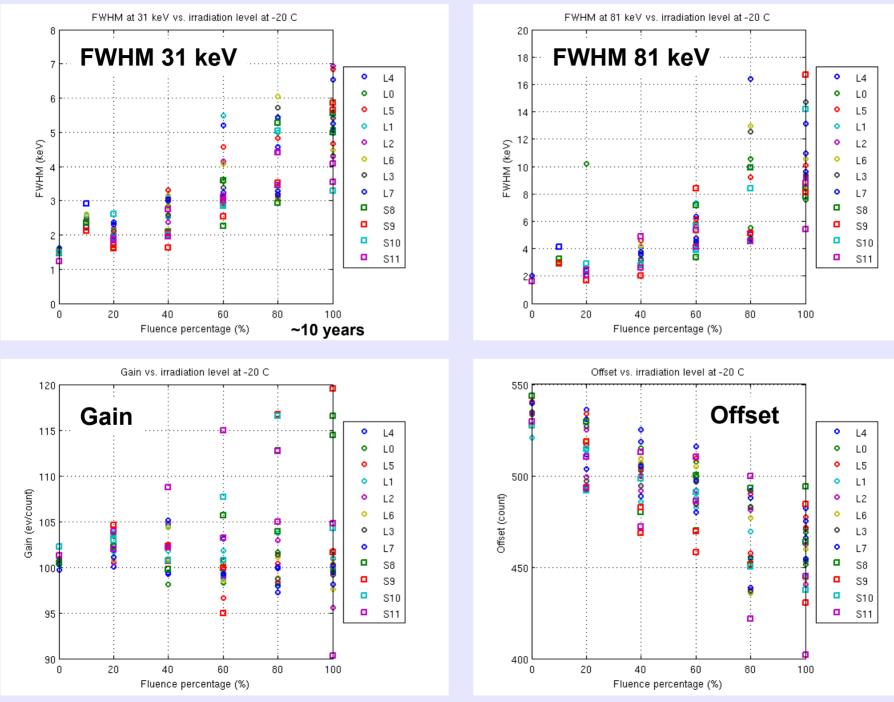




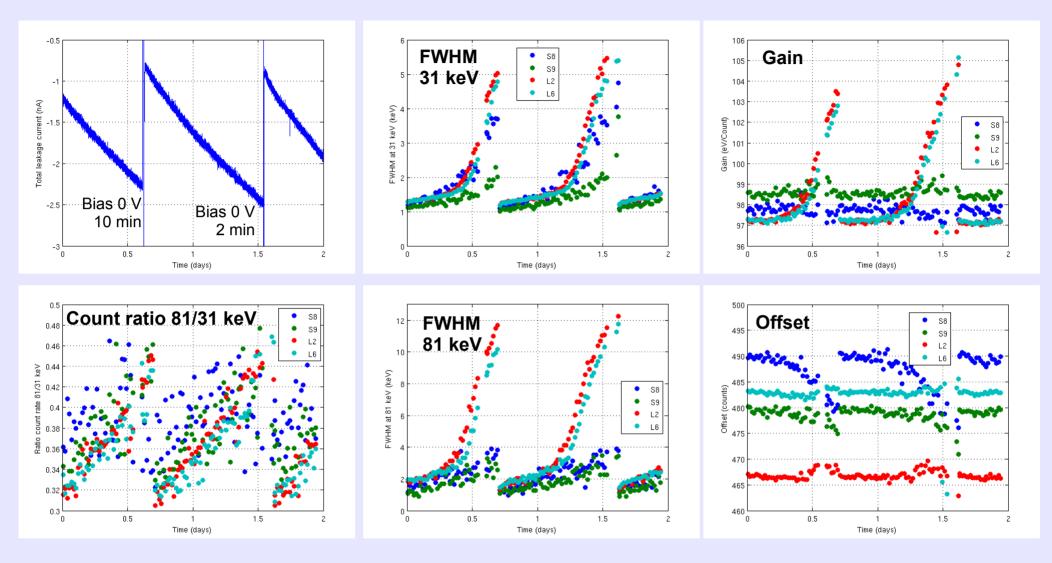




Proton irradiation: main results



Long term stability – polarization effect



Sensor kept stable at +4°C and 200 V (except bias reset), non-irradiated crystals

Time scale for FWHM doubling: $+4^{\circ}C \rightarrow$ ~0.5 days $-6^{\circ}C \rightarrow$ ~1 week $-17^{\circ}C \rightarrow$ ~1 month