

Atmospheric Research for Climate and Astroparticle Detection

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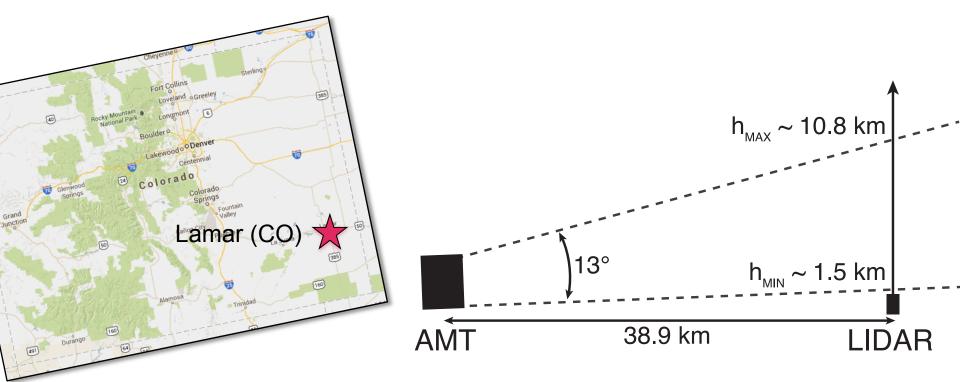




Aim of the project

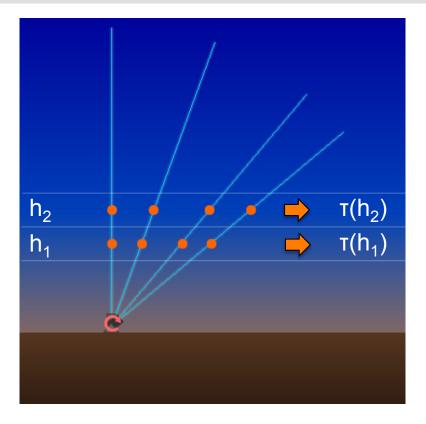
Perform measurements of the aerosol attenuation of UV light in atmosphere **simultaneously and on the same air mass** using the typical techniques mainly used in cosmic ray observatories:

Distant Laser Facility - Elastic and Raman LIDAR



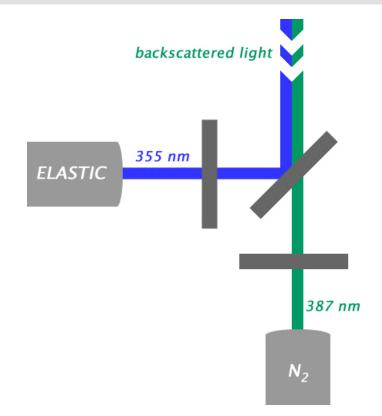
Four techniques compared

ELASTIC LIDAR Multi-angle analysis



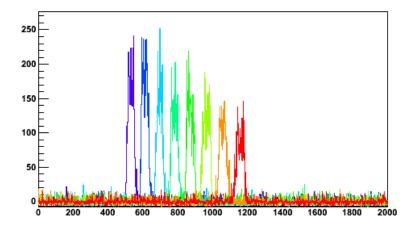
Hp: horizontally homogeneous atmosphere. Faster method.

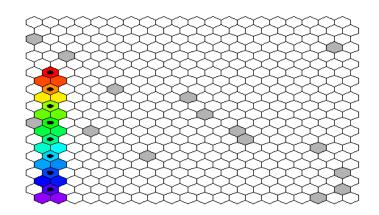
RAMAN LIDAR Vertical and inclined shots



2 equations for two unknowns. It needs a powerful laser.

Four techniques compared





LIDAR+AMT Data Normalized Analysis

Comparison of measured light profiles with reference clear night profiles (~ molecular atmosphere)

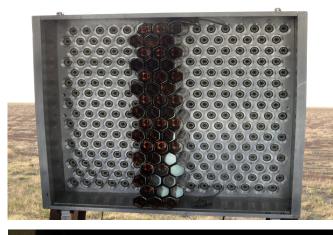
Selection cross-checked with lidar measurements.

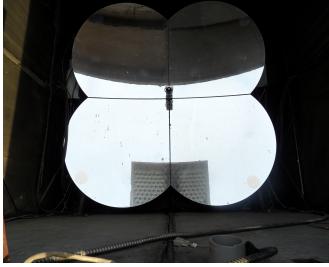
LIDAR+AMT Laser Simulation Analysis

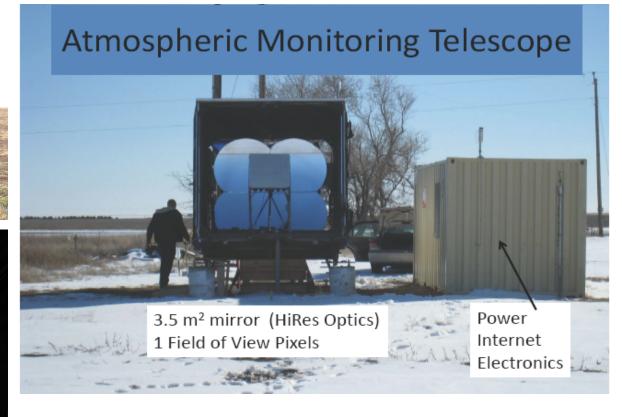
Comparison of measured light profiles with modeled atmosphere.

Aerosol attenuation described by a parametric model (2-3 parameters).

Atmospheric Monitoring Telescope (AMT)







Camera inherited from HiRes owned by Colorado School of Mines three columns of 16 PMTs, UV bandpass filter

AMT installation



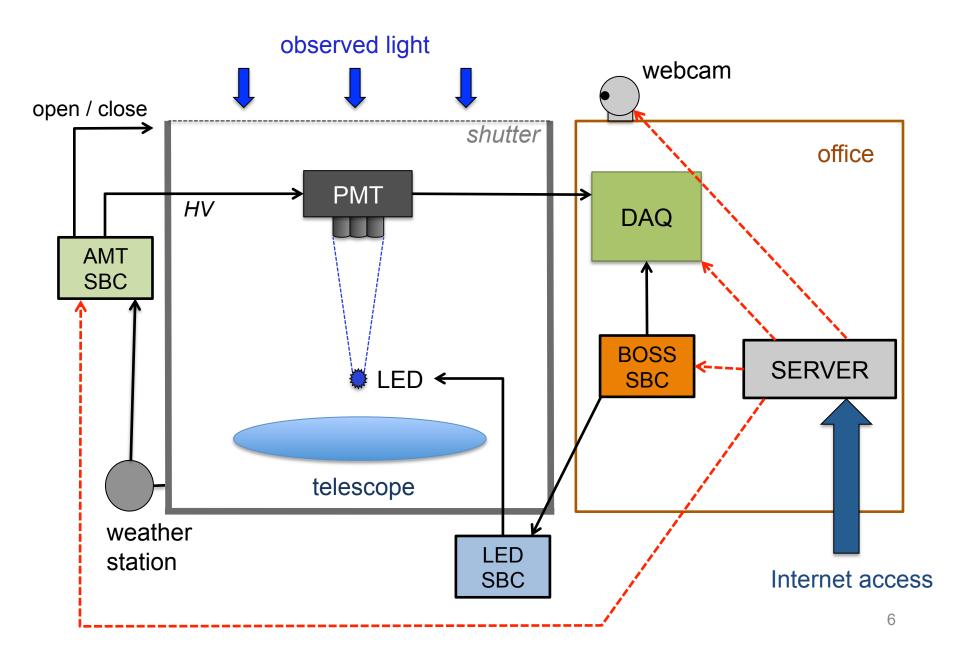




April - May 2014

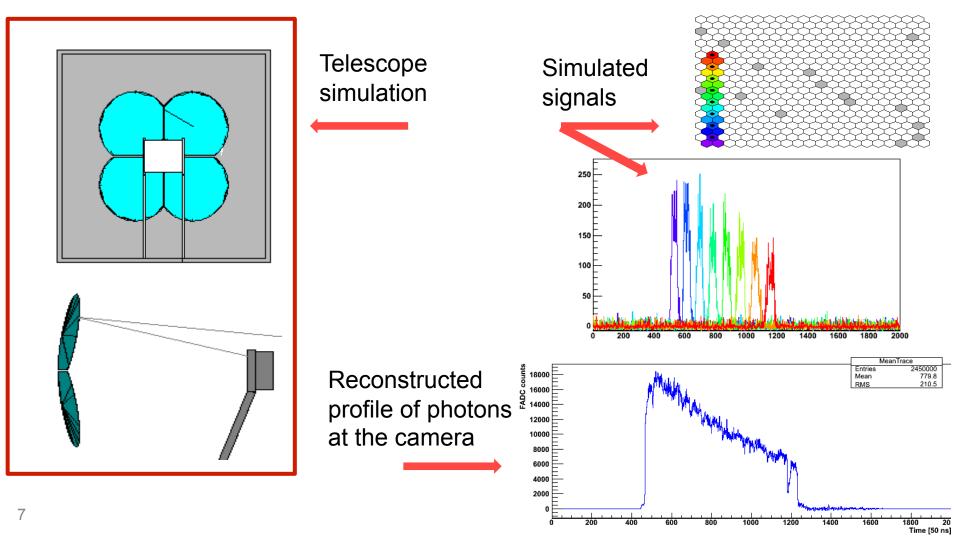
L. Wiencke, M. Coco, J. Eser, M. Buscemi and L. Valore

AMT system

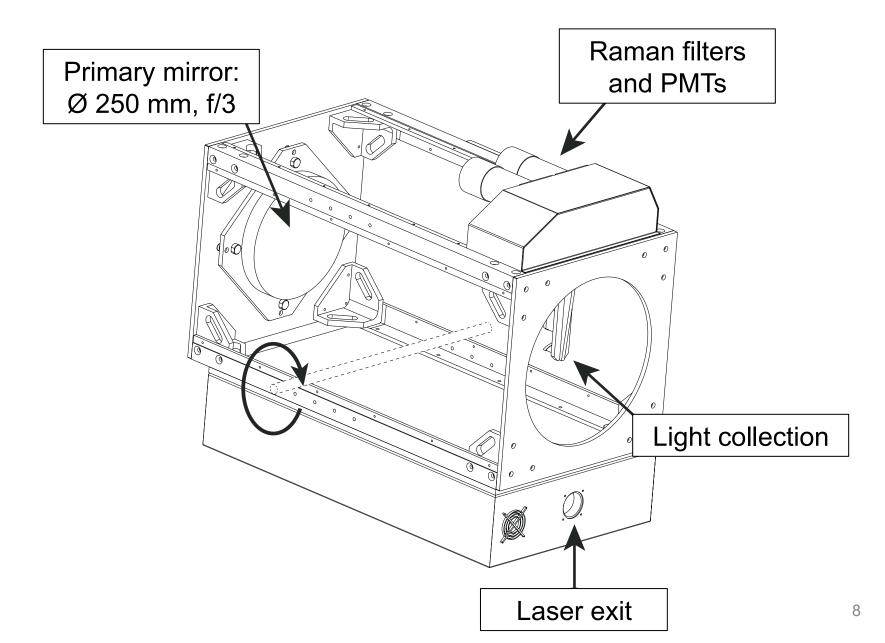


AMT simulation

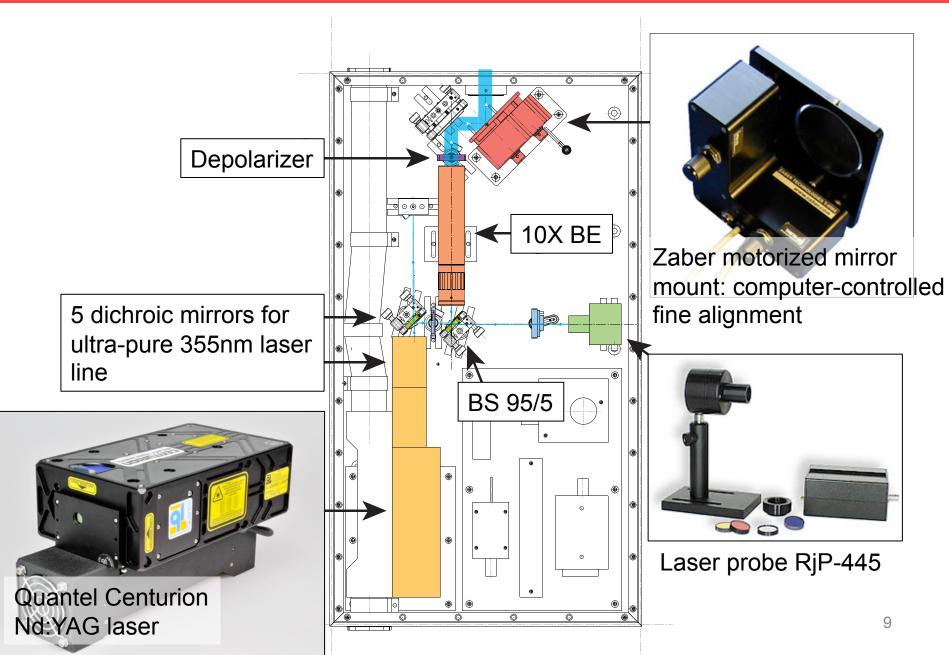
Simulation of the telescope via Geant4 + simulation of the laser track and transmission in atmosphere using the Auger software



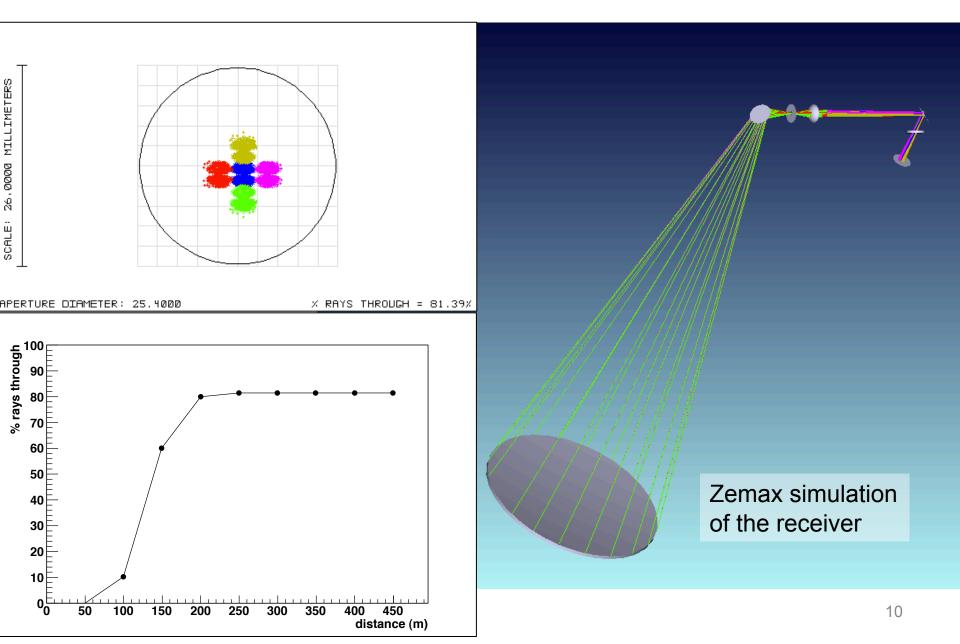
Raman LIDAR design



Laser bench



Receiver design



Data acquisition

E	Beam Splitter	Materion	Transmit avg > 90% 380-420 nm, Reflect > 90% at 354.7 nm $25.4 \ge 36 \text{ mm}, 45^{\circ}$ incidence angle	
F	Bandpass Filter	Materion	notch @ 386.7 ± 0.15 nm, OD 10 @ 354.7 , 532 , 1064 nm	
G	Bandpass Filter	Materion	notch @ 354.7 ± 0.15 nm	
			Signals are amplified 20X and then sampled with the CAEN digitizer DT5751 (1Vpp - 10bit – 1GS/s) Software-based signal processing (charge integration, photon counting)	

Steerable Raman LIDAR

Steerable Raman lidar based on a Nd:YAG laser (6mJ - λ=355nm) Acquisition tests in L'Aquila at CETEMPS: Simultaneous sampling with an EARLINET Raman lidar

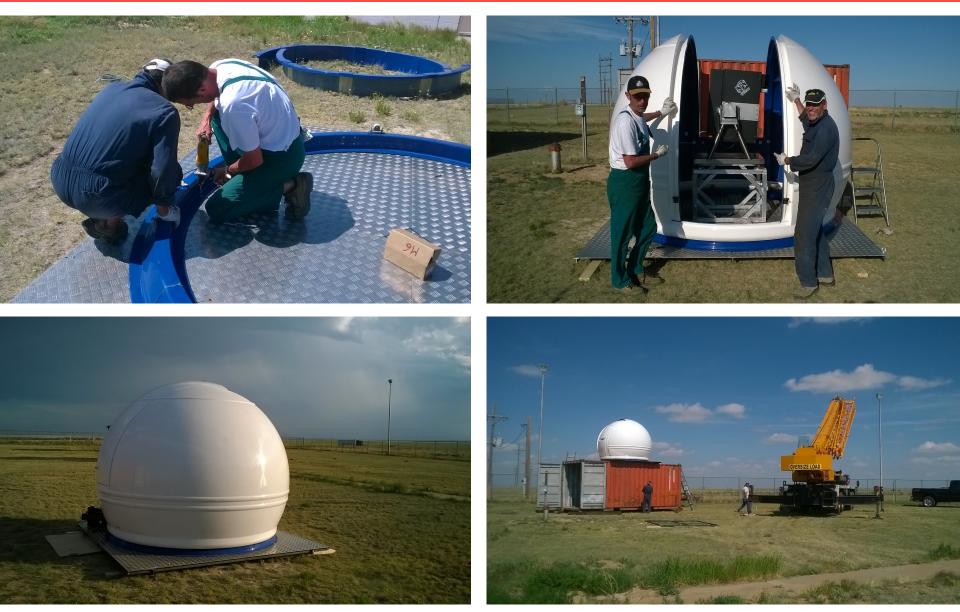
Steering tests in Torino:

Steering tests in Torino: Checking optical stability with red lasers

Receiver alignment

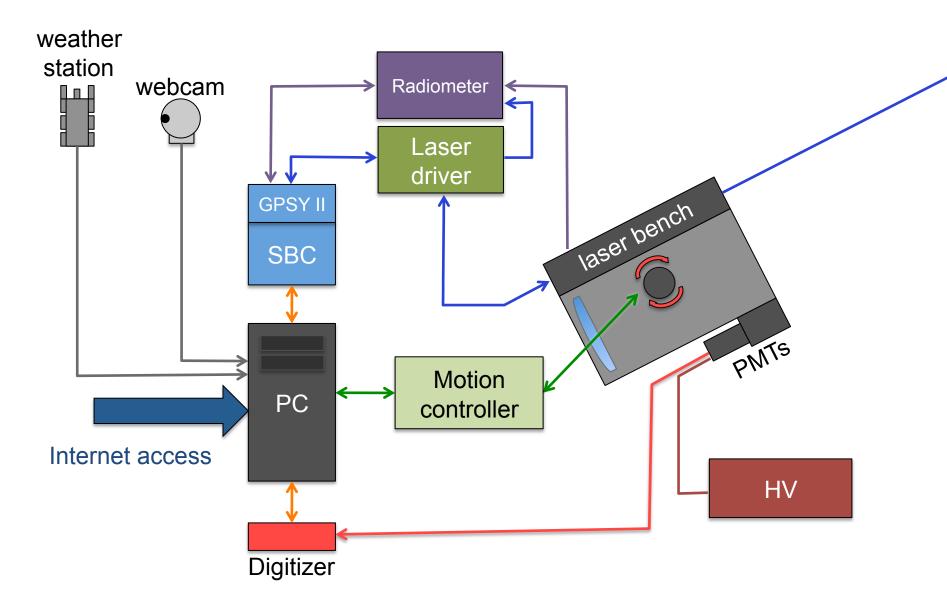


Lidar installation



May - June 2014 A. Tonachini, G. Dughera, M. Marengo

Lidar system



Built for remote operation



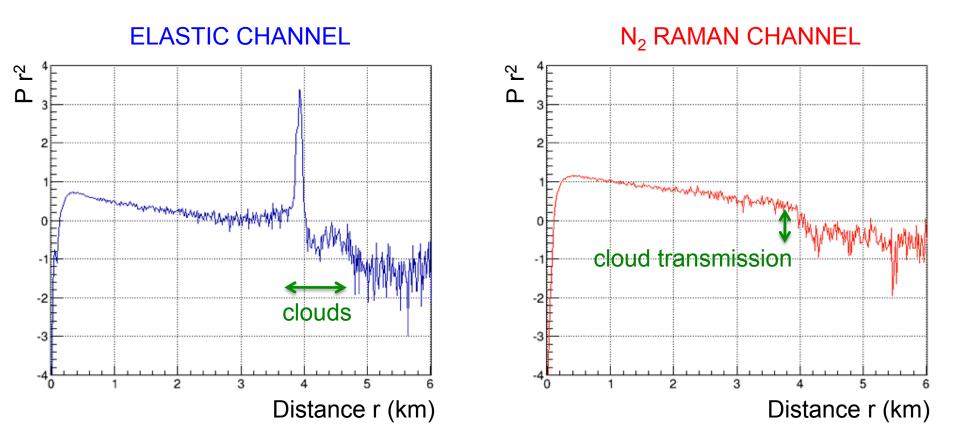




weather station

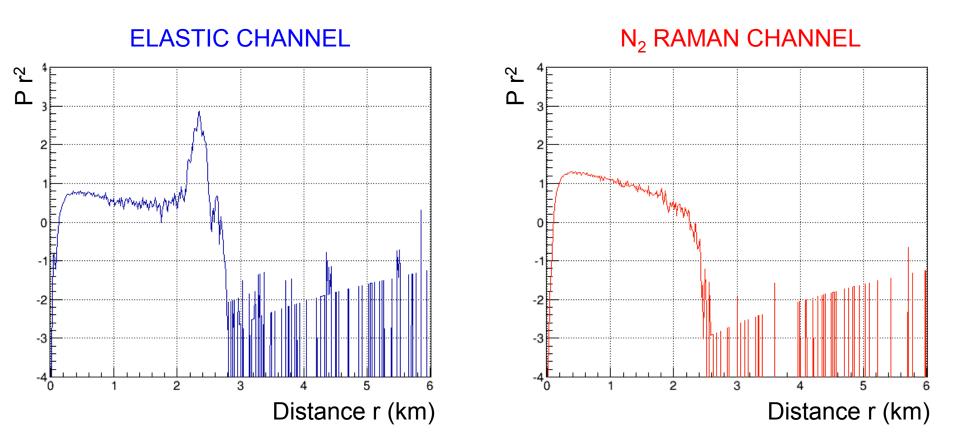
Lidar data

Vertical scan: signals are the sum of 25k laser shots.



Lidar data

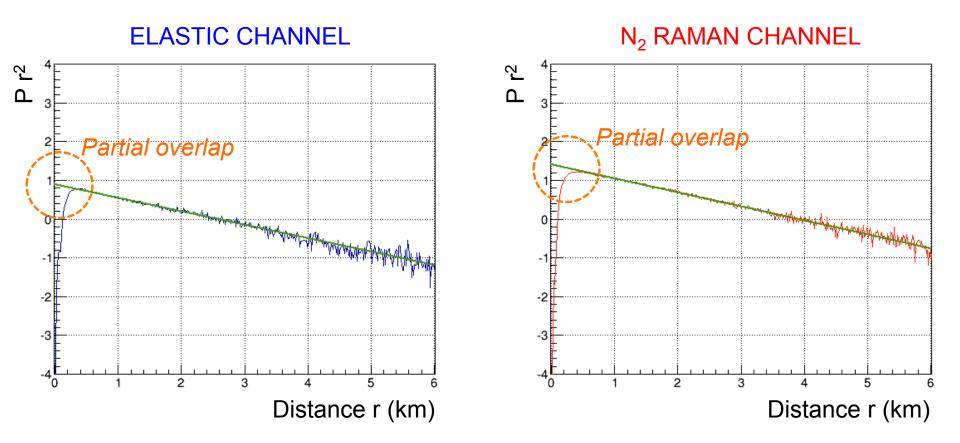
Vertical scan: signals are the sum of 5k laser shots.



Extreme case: high peak in elastic channel, no contamination on Raman channel

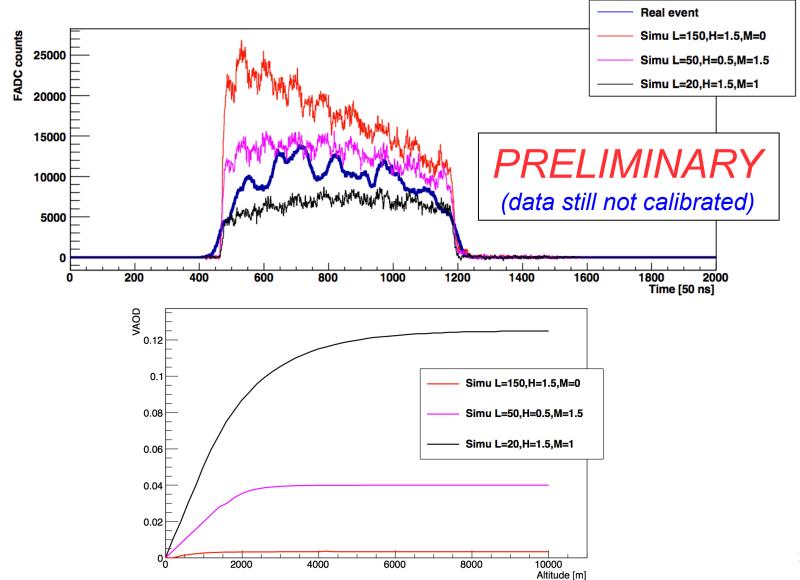
Lidar data

Horizontal scan: signals are the sum of 100k laser shots.

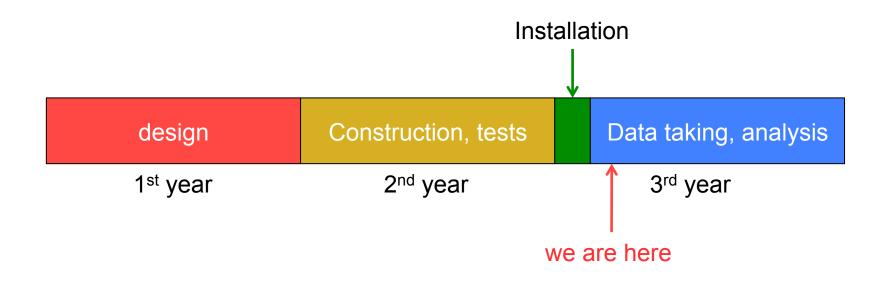


AMT data

Sum of 250 side scattering laser events compared to different simulated events.



Outlook



We are working to stabilize the acquisition Data analysis has just started Analysis comparisons will start soon!

Future plans: from ARCADE to CTA

In late 2015 the Raman lidar of ARCADE will be improved:

- new HV control
- new PMTs
- additional H₂O Raman channel

Extensive tests of the upgraded system in L'Aquila

This lidar will be a reference for the Raman lidars designed for CTA and will perform a first characterization of CTA sites.