UNIVERSITÄT DORTMUND

• 1.8m² active silicon

support structures

lifetime dose

and fluence

· low-mass carbon fiber

→ 2.96% X₀ per layer

• 500kGy and 1015 nea/cm2

bi-phase cooling system

→ operation below 0° C

integrated into local

support structures

• 16.4x60.8 mm² silicon sensor

• pixel size 50x400 um²

• operated at 150V bias

50 um pitch bump-bonding

· 250 nm CMOS technology

routing power and data lines

connection to external systems

· solder or indium

2x8 readout ASICs

flexible kapton PCB

· 18x160 cells each

wire-bonded to Flex

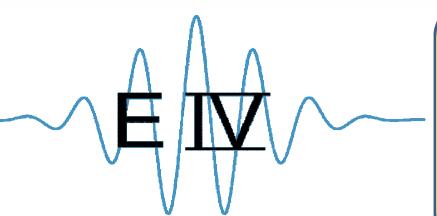
passive components

TTC data to FEs

module control chip (MCC)

• n⁺-in-n DOFZ

· 250 um thick

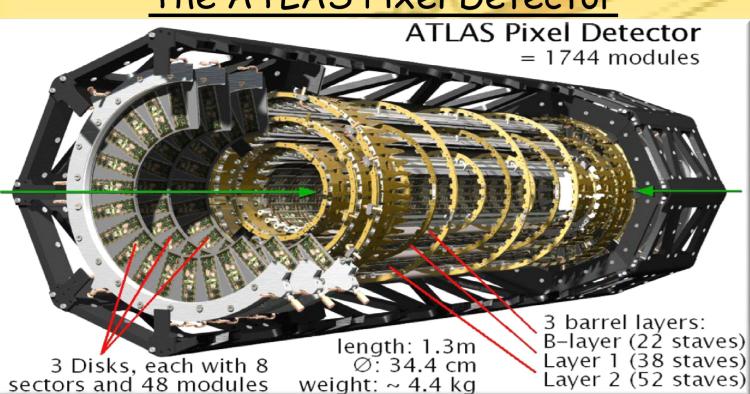


Commissioning of the ATLAS Pixel Detector

Dr. Jens Weingarten, Exp. Physik IV, TU Dortmund







- collision frequency 40MHz
- 2us trigger latency → on-detector buffering
- detect 1000 tracks at every bunchcrossing
- → robust pattern recognition excellent secondary
- vertex resolution → inner radius
- 50.5mm

decoupling capacitors

MCC pigtai

preamplifier.

Sensor

connects

- 1744 modules, 46080 pixel each → 80 million
- pixels total
- spatial resolution 15um (R- ϕ), 115um (z)
- 3 track points to $|\eta| = 2.5$
- · zero-suppressed, semi-analog readout
- → on-chip data reduction

The Pixel Module is the smallest functional unit of the

pixel detector. It is a sensor-readout hybrid assembly,

ATLAS Pixel Module

dimensions: ~ 2 × 6.3 cm² weight: ~ 2.2 g

The amplifer-discriminator part of each single pixel can be

tested, employing an integrated charge generator. A DAC-

fF or 32fF), to inject a well-known charge into the

controlled voltage step is applied to an injection capacitor (8

comprising 46080 electronics channels.

The Pixel Module

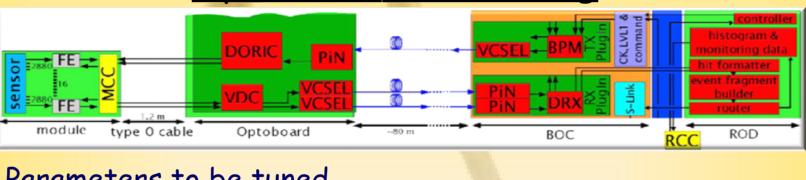
Commissioning in 2008

- Phase 0: april
- connection sign-off
- · first pixel cooling loop commissioning
- → interrupted by catastrophic cooling plant failure that made substantial repairs and improvements to the cooling system necessary

•Phase 1: august

- · cooling loop commissioning
- optolink operation (incl. optoboard cooling and heating)
- Phase 2: september october
 - · optolink tuning
 - definition of largest possible set of modules
- ATLAS combined cosmics data taking
- Phase 3: november december
- optolink tuning
- module tuning
- · debugging of module problems
- ID combined cosmics data taking
- various detector studies

Optolink Commissioning



Parameters to be tuned

• uplink (less trivial): laser power on-detector;

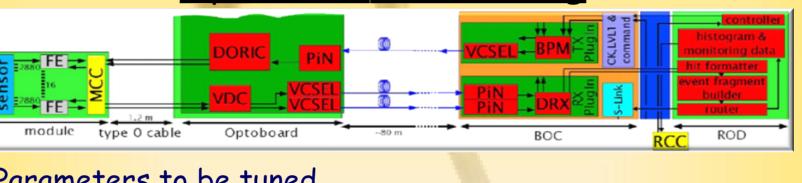
→ maximize error-free region (E

- optoboard temperature
- bitsequence
- · readout bandwidth

Tuning procedure uses

Tuning procedure takes ~1h for full detector

- → 96% of the links have been tuned sucessfully by the automated procedure
- → links bad after verification (and some retuning) disabled from calibration/data taking



20

errors

(EFR)

15

sampling phase

10

• downlink (optional):

MSR, laser power

off-detector PIN diode threshold; off-detector sampling clock phase

0-1-0-1 pattern to check for transmission errors

Threshold Adjustment

Discriminator thresholds can be adjusted individually (LSB~75e, dyn. range 7 bit)

Goal: threshold at 4000e

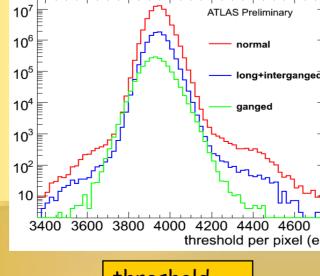
Measurement

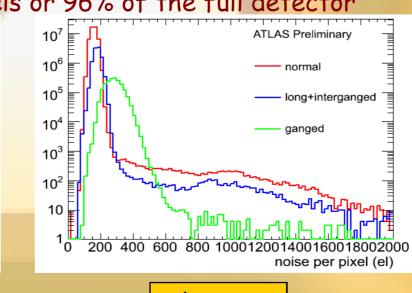
- inject varying charge to amplifier
- register fraction of hits
- fit gaussian error-function
- → threshold & noise

ideal: step (S-curve fit) noise calculation Threshold and noise of a pixel 000 7000 8000 9000 injected charge [e⁻]

Doing this measurement on the full detector takes ~1.5h

→ Results for 75 million pixels or 96% of the full detector



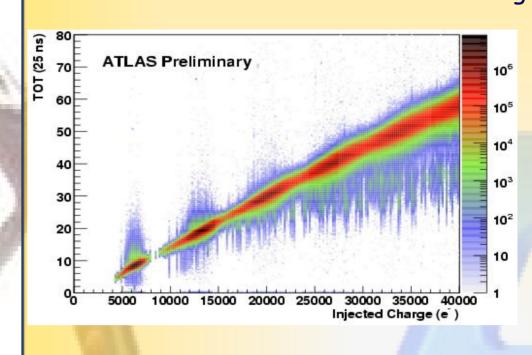


threshold mean 3950e 40e RMS

noise mean 165e RMS 30e

Charge calibration - TOT tuning

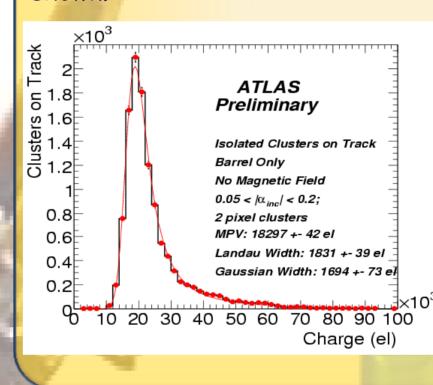
The feedback capacitance of the charge-sensitive preamplifier is discharged by a constant, adjustable current. This results in a nearly linear dependence between the 'timeover-threshold' (TOT) and the input charge. TOT is measured in units of the bunch-crossing clock (25ns).



To calibrate the TOT an increasing charge is injected in the preamplifier input and the TOT response is parameterized. An accurate parametrization is needed to convert TOT to charge which is used to improve the position resolution of clusters.

To minimize the spread of the TOT response to a given charge, the feedback current is adjusted for every pixel. A charge of 20.000e (MIP signal) is injected and the TOT is tuned to a response of 30 BC.

→ after tuning RMS < 1 BC</p> For both measurements results from 96% of all pixels are shown.



ATLAS → ToT after Tuning ToT (BC)

The charge distribution for clusters associated to a cosmic muon track in the pixel detector (left) peaks at the expected value of 20.000e, validating the chosen parametrization of the TOT.

The contribution of noise hits, which show a small charge, is very small.

Run 88463

first pixel track

Cosmic Data Taking

 first joined ATLAS combined data taking on sept. 4.

Wrong trigger timing → no hits on tracks

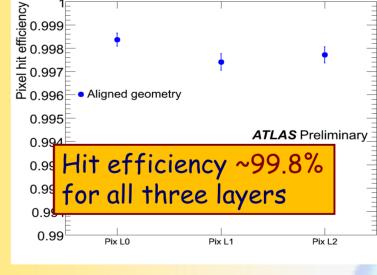
• LHC first beam: sept. 10

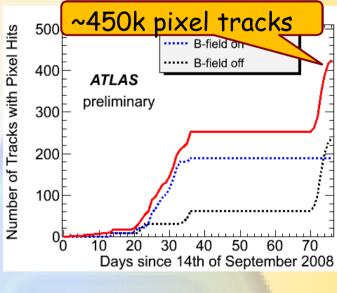
 next data taking sept. 14, improved timing → first pixel tracks reconstructed

until then not much time for module debugging

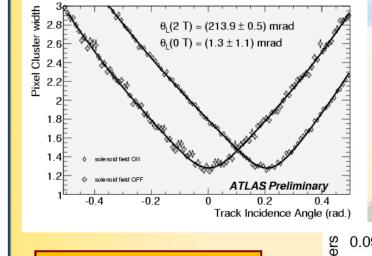
→ many modules disabled this improved with time and detailed module

studies





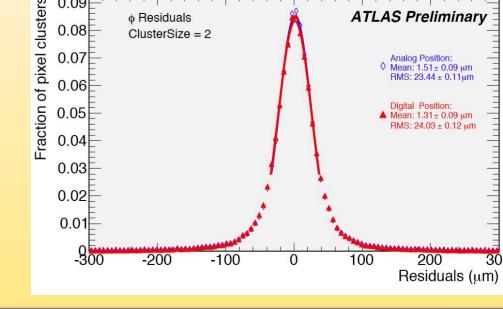
Studies using cosmics data



after the latest improvements in tracking algorithms, material treatment etc. → resolution 23.4um in short pixel

(reminder: pitch/ $\sqrt{12}$ ~ 14um)





Commissioning Program

- 1. Adjust optical link parameters for correct communication
- 2. Verify communication using hits injected in the digital FE-electronics → leads to a sample of modules with good communication (GoodOpto)
- 3. Threshold scan with and without sensor bias determine threshold per pixel, threshold dispersion across one module
 - and electronics noise verify sensor bias connection → tune thresholds if dispersion across the module too large
- 4. TOT scan injecting 20ke into the preamplifier
 - determine TOT mean and sigma > tune feedback current if TOT dispersion across the module too
- 5. derive TOT-vs-charge calibration for offline use
- 6. timing scans to facilitate synchronisation between sub-detectors
- 7. debugging of module problems



für Bildung

und Forschung

Bundesministerium