

# Multi-wavelength polarization Lidar characterization of mineral dust at Dunhuang (PRC)

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## Outline

- Project background
- Lidar «AMPLE» design
- Lidar system calibration and test
- Some results from the field measurements



# Background



Beijing



# Background:



Etna



# Background:



## CHINA-ITALY LASER REMOTE SENSING TECHNOLOGY RESEARCH CENTER



CNISM - Beijing Research Institute for Telemetry

consorzio nazionale interuniversitario per le scienze fisiche della materia

## Background:

1. **Joint research project between the National Consortium of Italian Universities for the Physical Science of the Matter (CNISM) and the Beijing Research Institute for Telemetry - BRIT**

**AMPLE -**

**Aerosol Multiwavelength Polarization Lidar Experiment**

2. **Cooperation between CNISM and INGV-Catania, INAF-Catania**

## AMPLE design:

1. **High dynamic signal range** – for high dense aerosol measurement
2. **Depolarization measurements** – for distinguishing the particle shape
3. **Multiwavelength channel** – for particle dimension evaluation
4. **Raman capability** – for quantity measurement
5. **Scanning capability** – for 3D mapping
6. **Compact** - for mobile measurements

# AMPLE specification:

## 1. **Laser source:**

- Diode pumped Nd:YAG (Bright Solutions)
- Fundamental , 2nd and 3th harmonics
- Pulse rep. rate: 1000 Hz
- Output power:  
0.6 W @ 355nm; 1.5 W @ 532nm; 1 W @ 1064nm
- Pulse width ~ 1 ns
- Linear polarization > 100:1

# AMPLE specification:

## 2. Receiver system:

- Elastic channels @ 355nm, 532nm and 1064nm
- Raman channels @ 386nm (N<sub>2</sub>), 407nm (water vapor) and 607nm (N<sub>2</sub>)
- Depolarization @ 355nm and 532nm

Total photon counting

- Telescope: 20 cm Cassegrain
- Field of View: 1 mrad

## AMPLE specification:

### 3. Scanning system:

- Elevation range: from  $-10^{\circ}$  to  $100^{\circ}$  ;
- Azimuth range: from  $-110^{\circ}$  to  $110^{\circ}$  ;
- Scanning speed: max  $20^{\circ}$  /s ;
- Scanning angle error:  $< 0.2^{\circ}$

4. **Weight**  $< 100$  kg

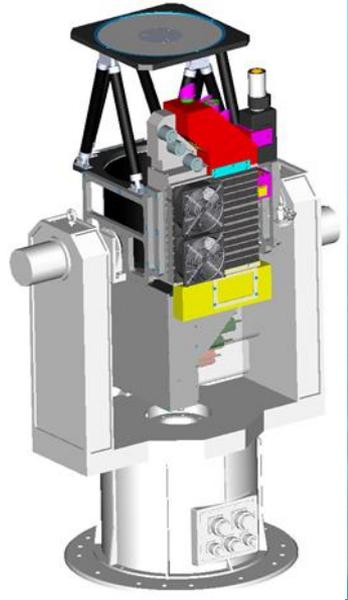
5. **Power consumption**  $< 700$  W



# AMPLE specification:

## 4. Output:

- Aerosol backscattering coefficient
  - @ 355nm, 532nm and 1064nm (day and night);
- Aerosol extinction coefficient
  - @ 355nm, 532nm (night);
- Aerosol depolarization ratio
  - @ 355nm and 532nm (day and night);
- Water vapor mixing ratio (night);
- Spatial resolution: 15m (raw), 60-180m (final);
- Temporal resolution: 2s (raw), 1-30 min (final)



# Lidar system calibration and test

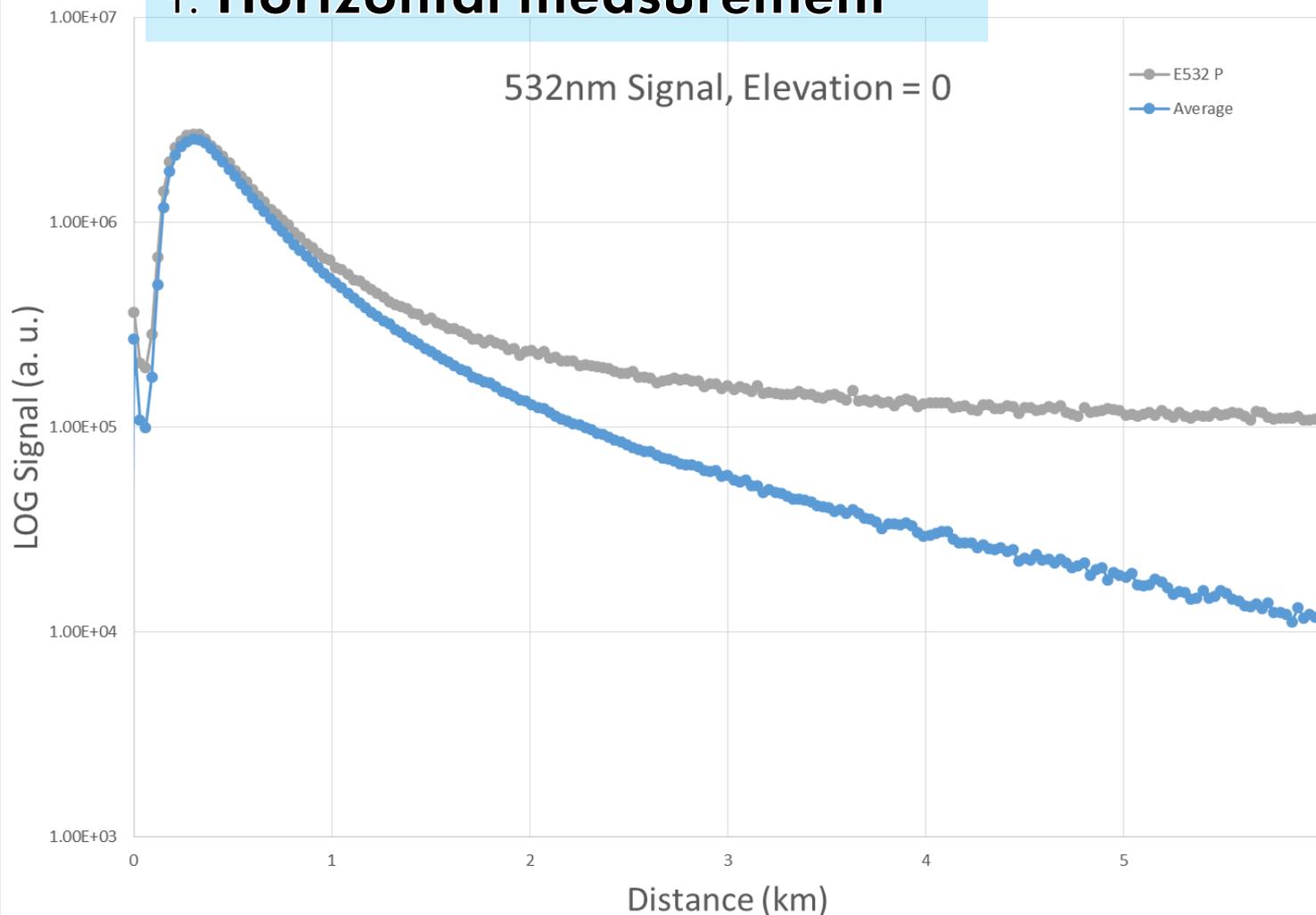
- Overlap function
- Multiwavelength channel calibration
- Depolarization calibration
- Water vapor Mixing Ratio test
- Comparison with Sun-photometer

# Lidar system calibration and test

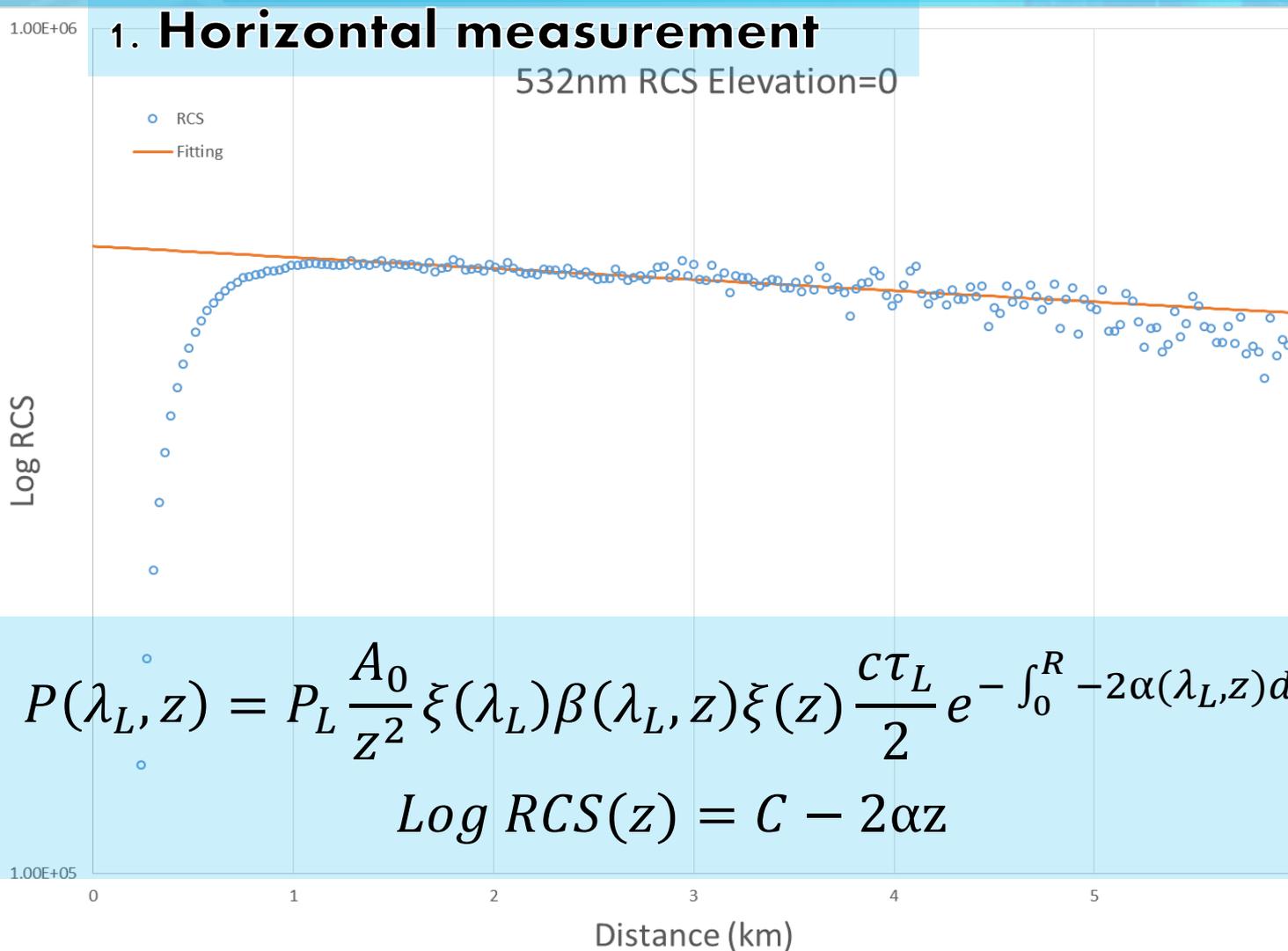
- **Overlap function**
  - **Horizontal measurement**
  - **Iterative from backscatter measurements both Raman and Elastic**



### 1. Horizontal measurement



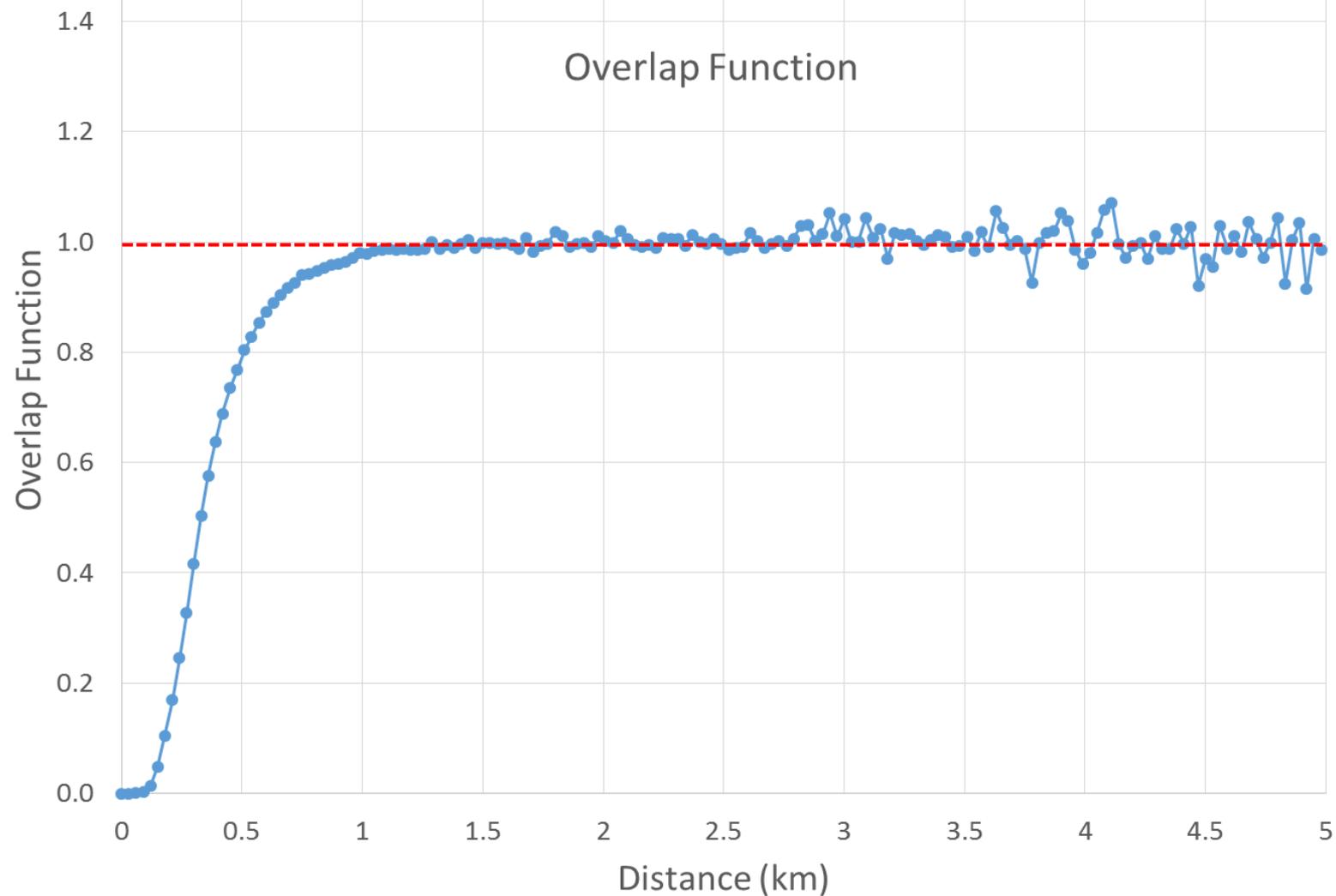
## Overlap function determination



# 1. Horizontal measurement

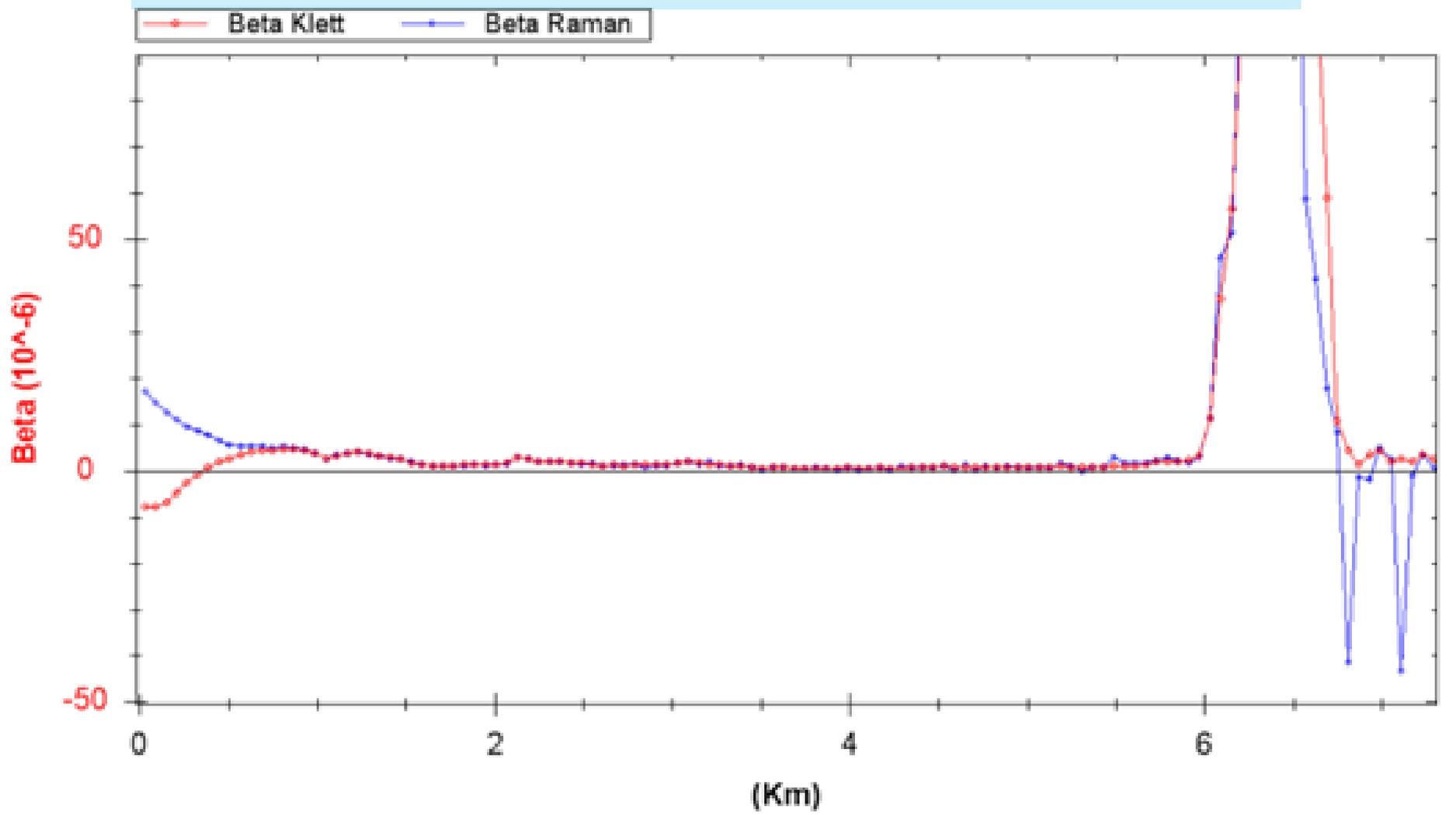


For lidar system overlap function determination



## 2. From Raman and Klett aerosol backscatter iterative

### For lidar system overlap function determination

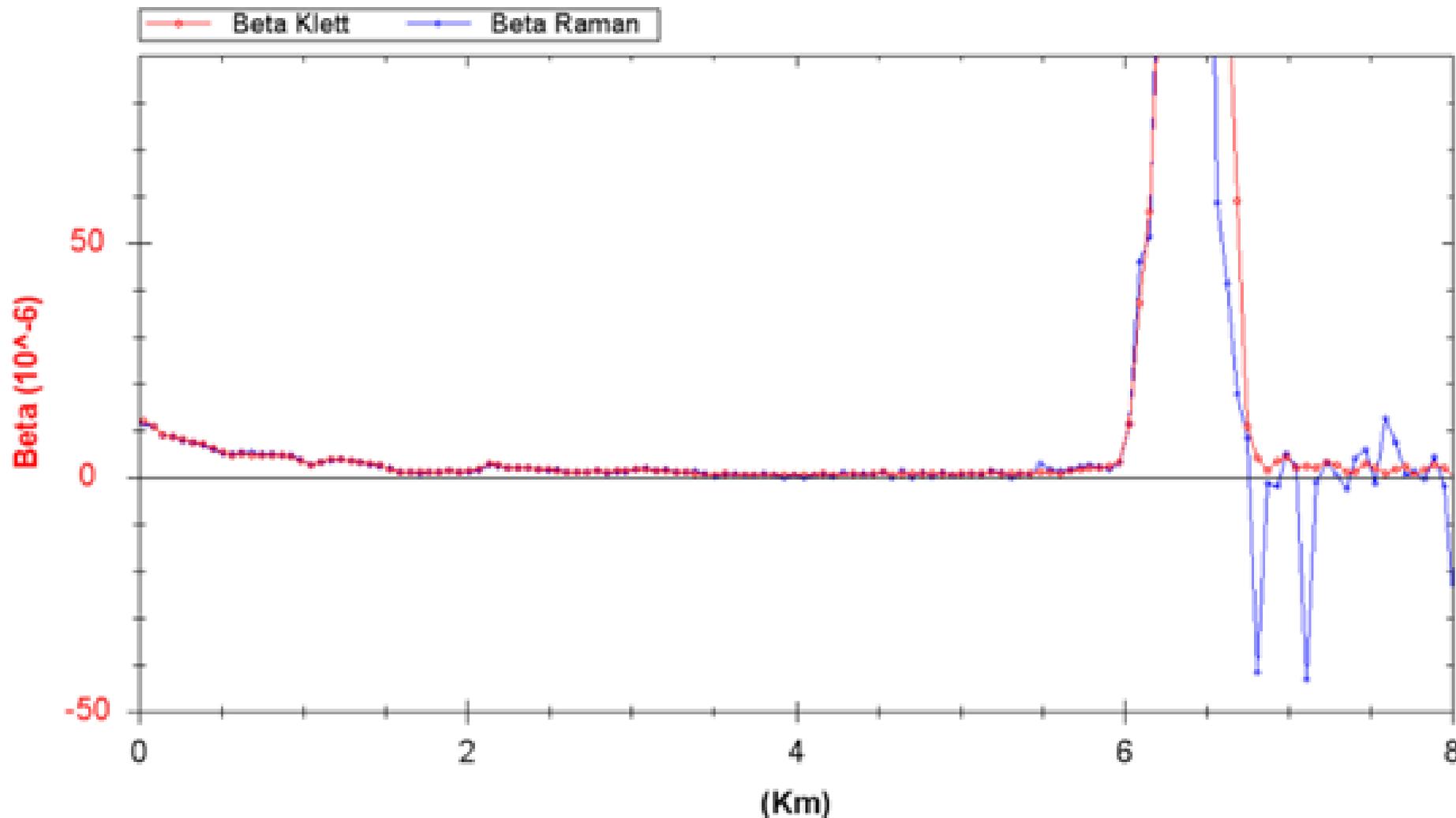




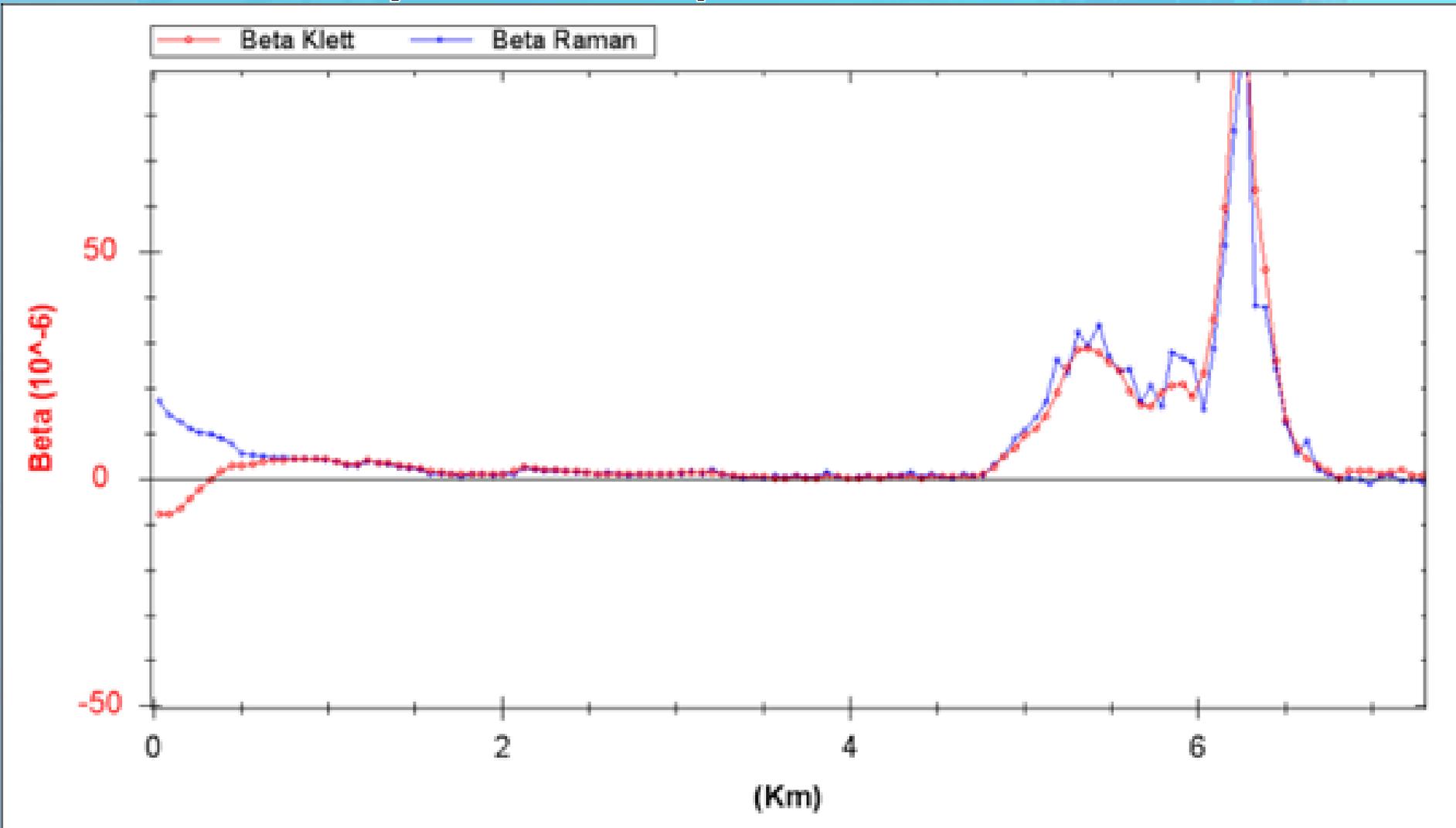
## 2. From Raman and Klett aerosol backscatter iterative



### For lidar system overlap function determination



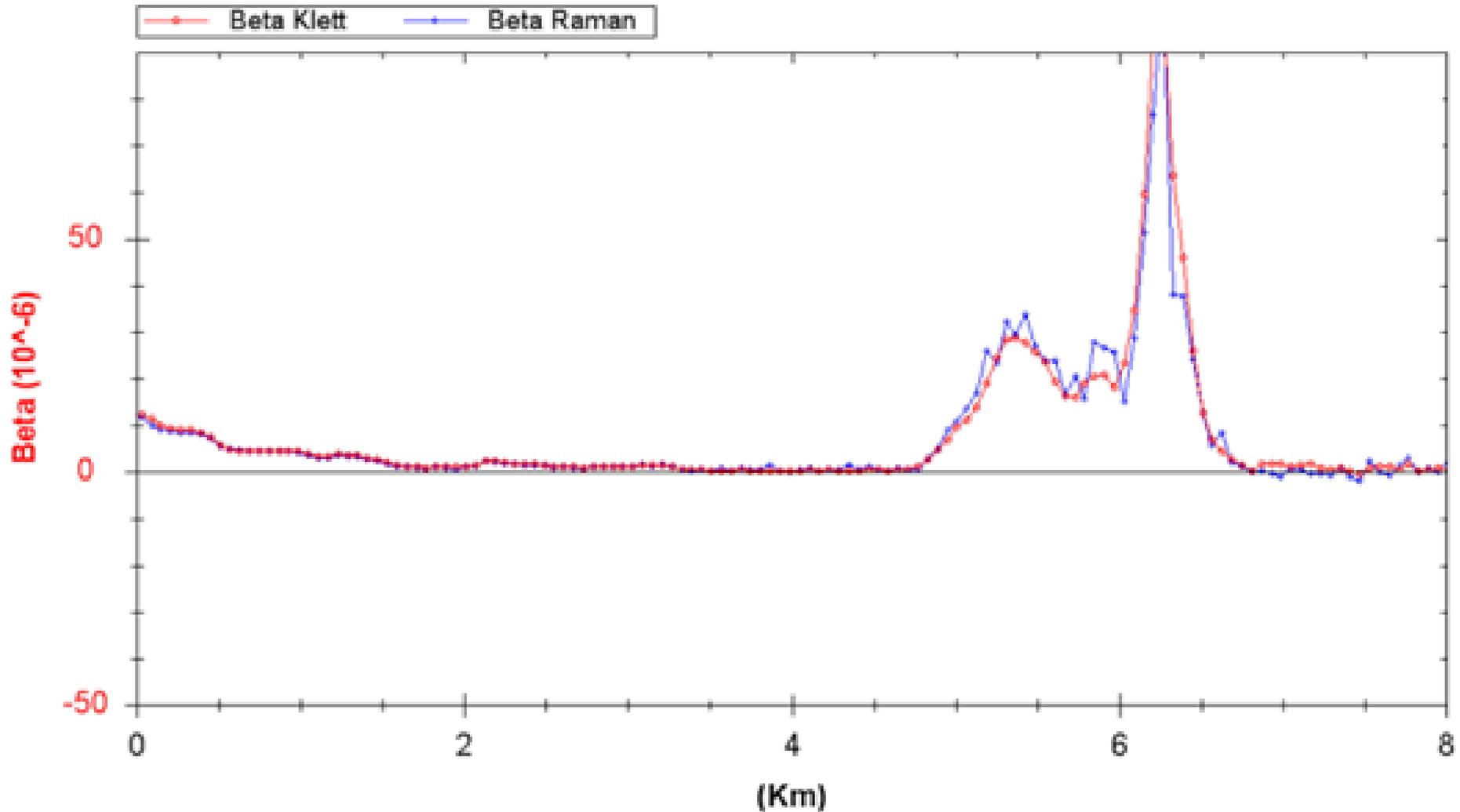
## 2. From Raman and Klett aerosol backscatter iterative For lidar system overlap function determination



## 2. From Raman and Klett aerosol backscatter iterative

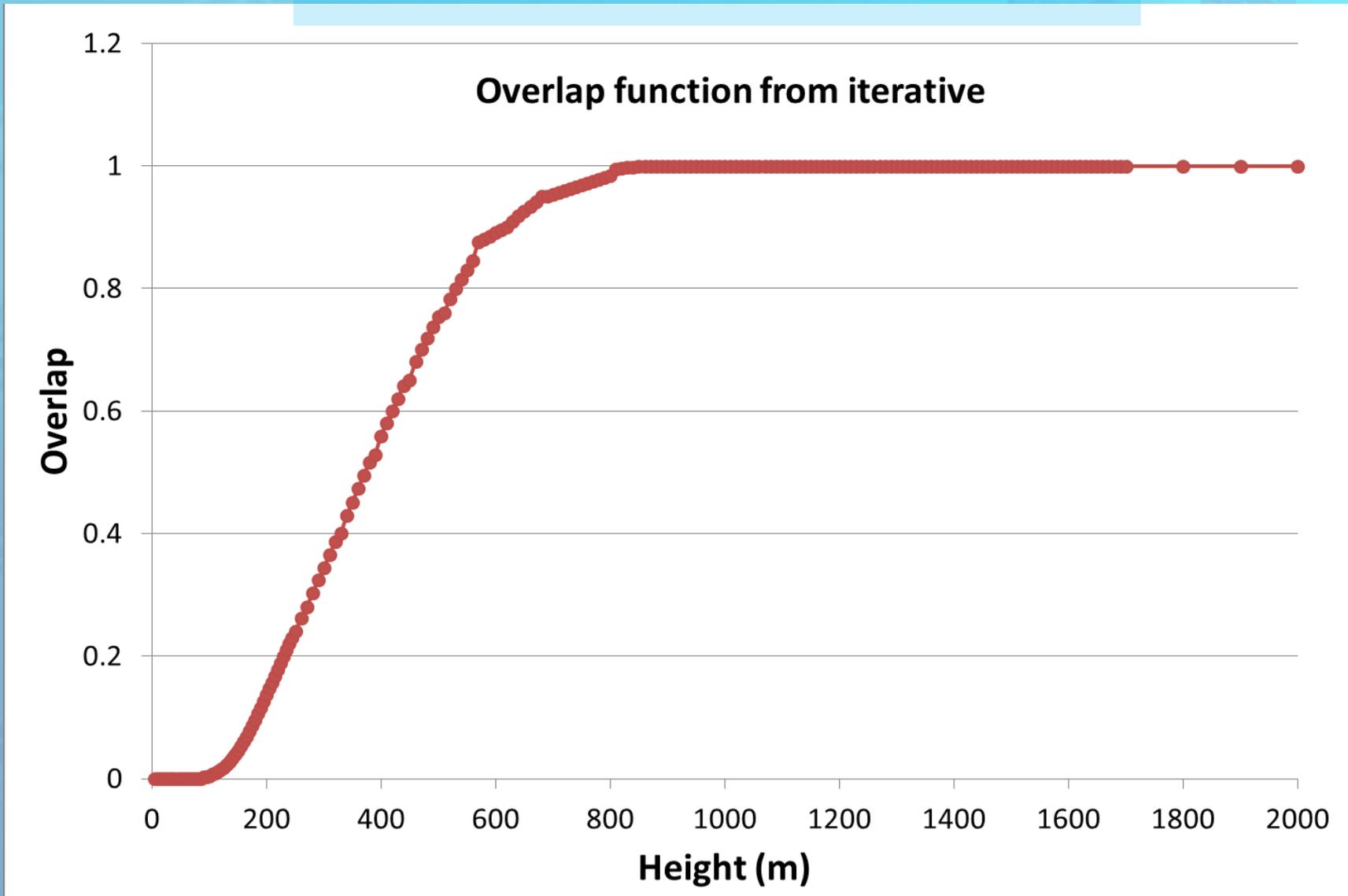


### For lidar system overlap function determination





## 2. From Raman and Klett aerosol backscatter iterative





Aerosol Backscattering Color Index – CI

$$CI = \frac{\log(\beta_{532} / \beta_{355})}{\log(355 / 532)}$$

Typical CI from -1 to 4

Cirrus cloud is ideal object for the calibration of different wavelength channel

$$\beta_{355} = \beta_{532} = \beta_{1064}$$

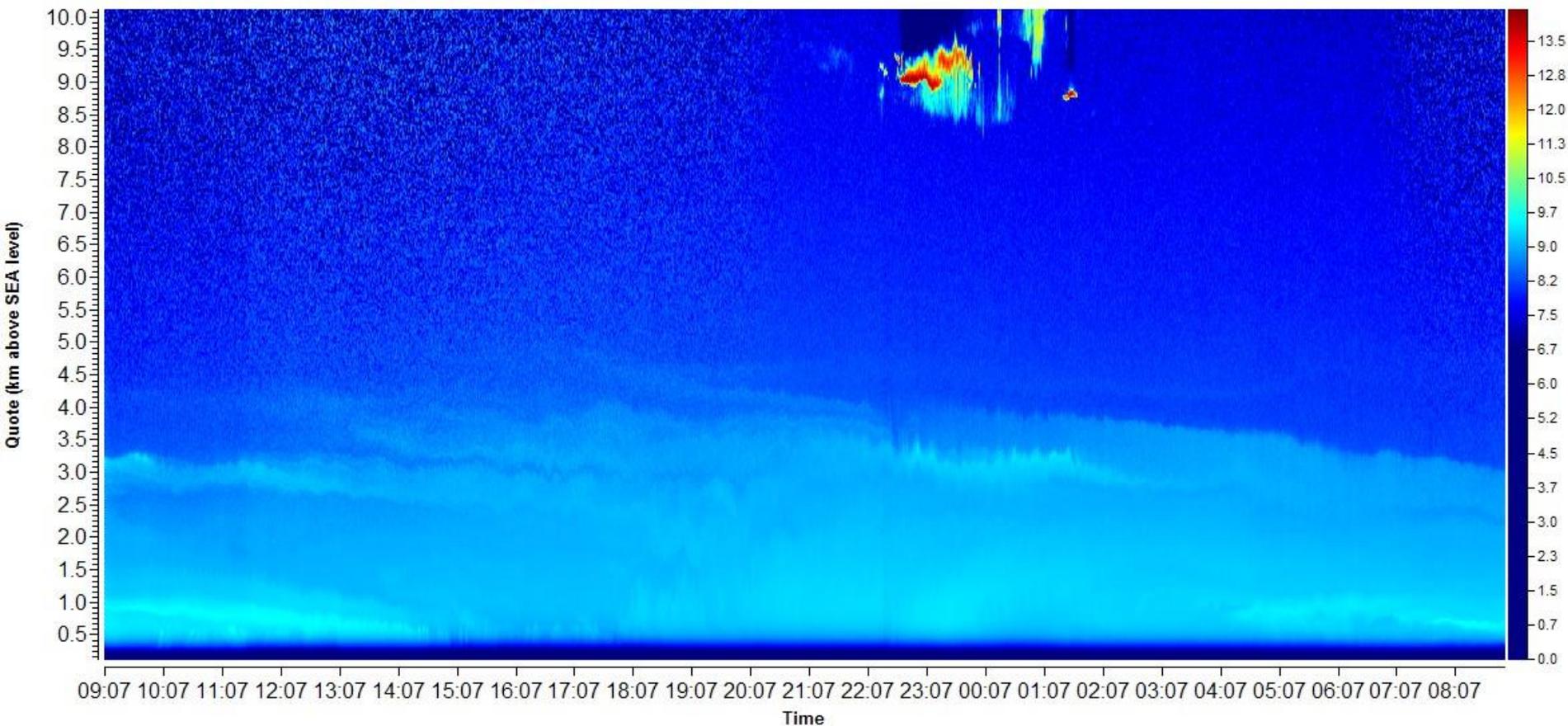
$$CI = 0$$



# Multiwavelength channel calibration



E532P LOG RCS from 19/08/13 09:07 to 20/08/13 08:57

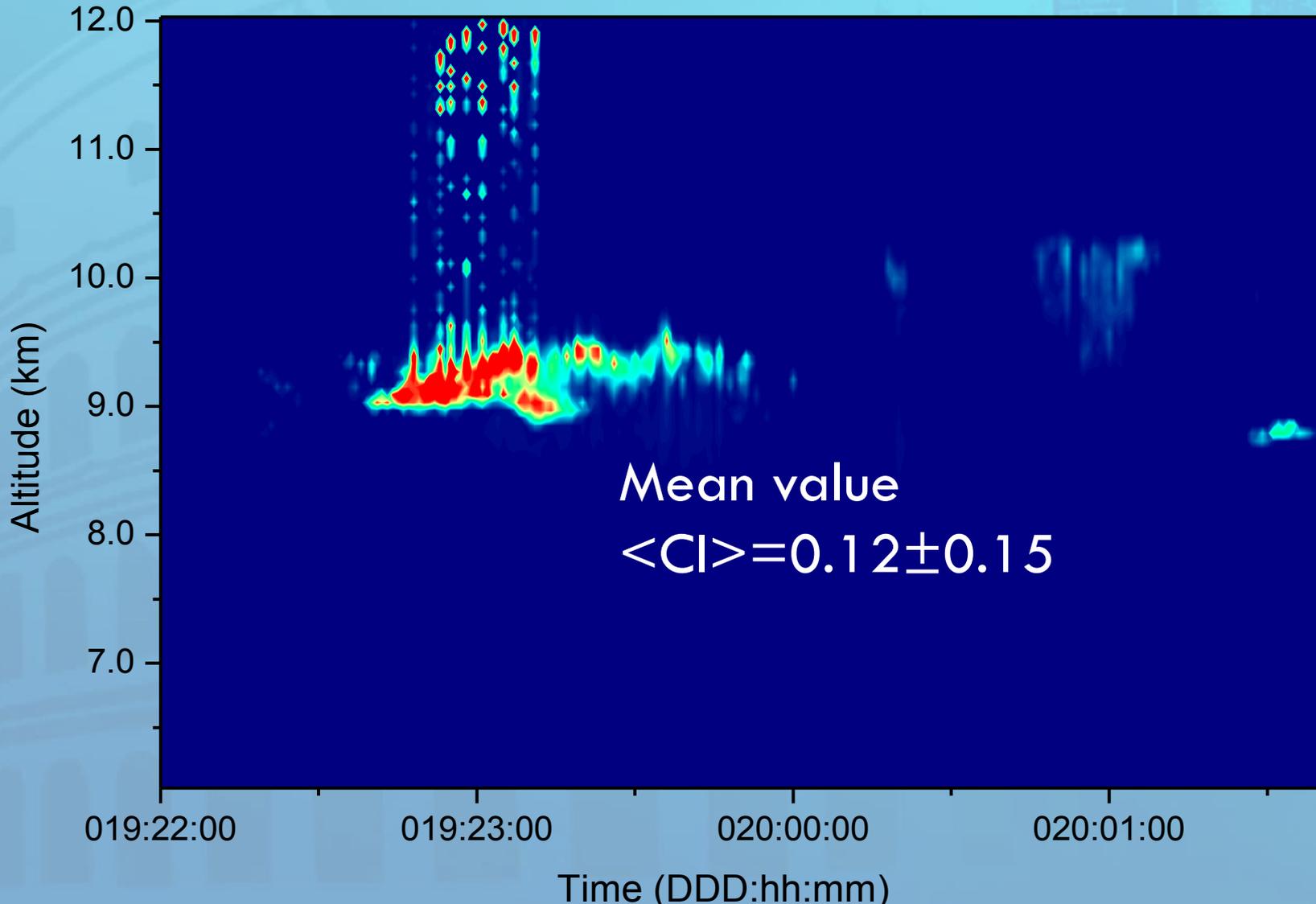




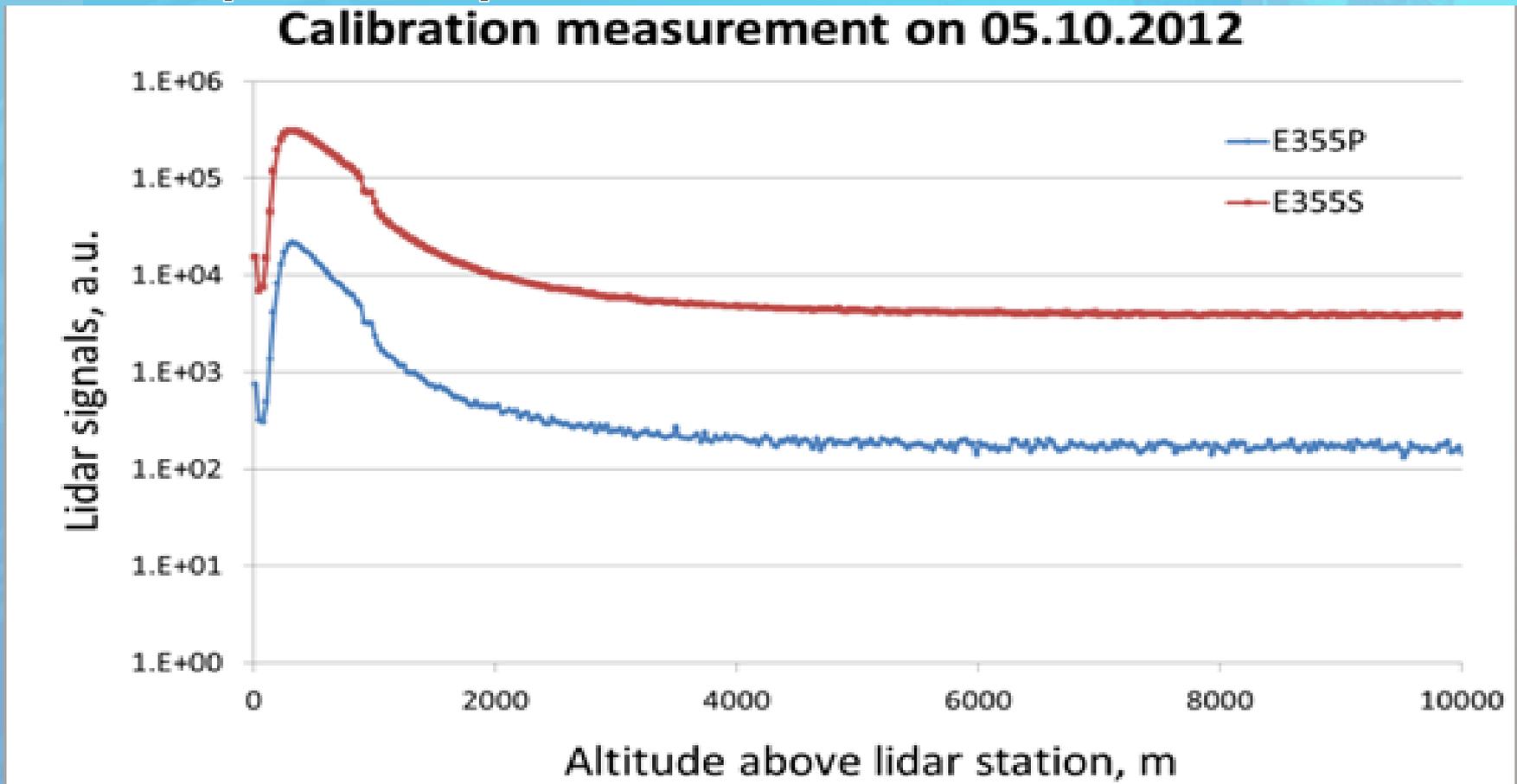
# Multiwavelength channel calibration



Aerosol Backscatter coefficient ( $\text{m}^{-1} \text{sr}^{-1}$ ) @532nm



## 1. Depolarizer plate measurement



Example of measurement for polarization calibration

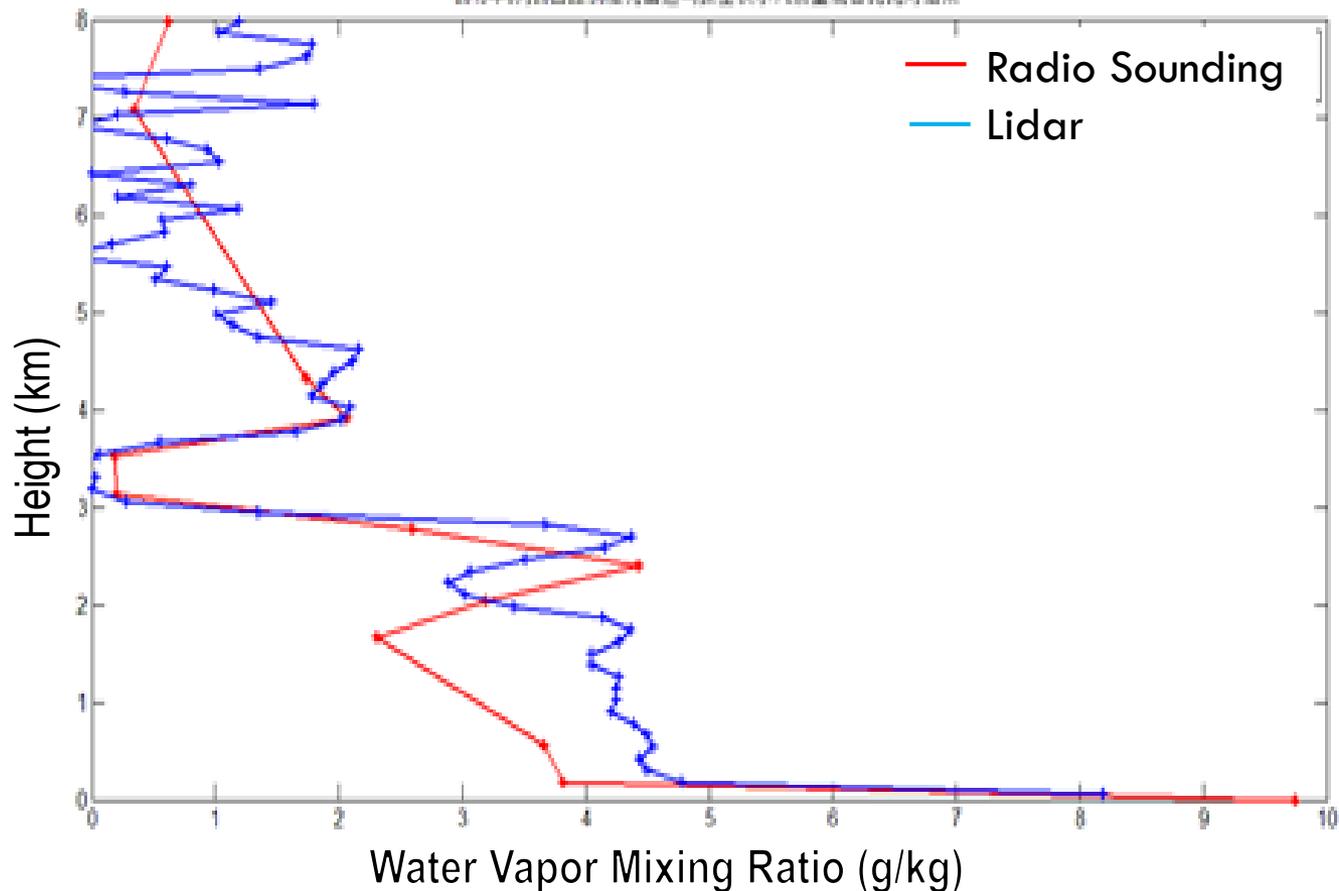
Difference in the signal amplitude can be due to the different gain of the photomultiplier used or to the different transmission optical efficiency

# Water Vapor Mixing Ratio Test



## Compare with radio sounding

2013年6月20日 欧洲空间局激光雷达与探空仪水汽质量数据对比结果

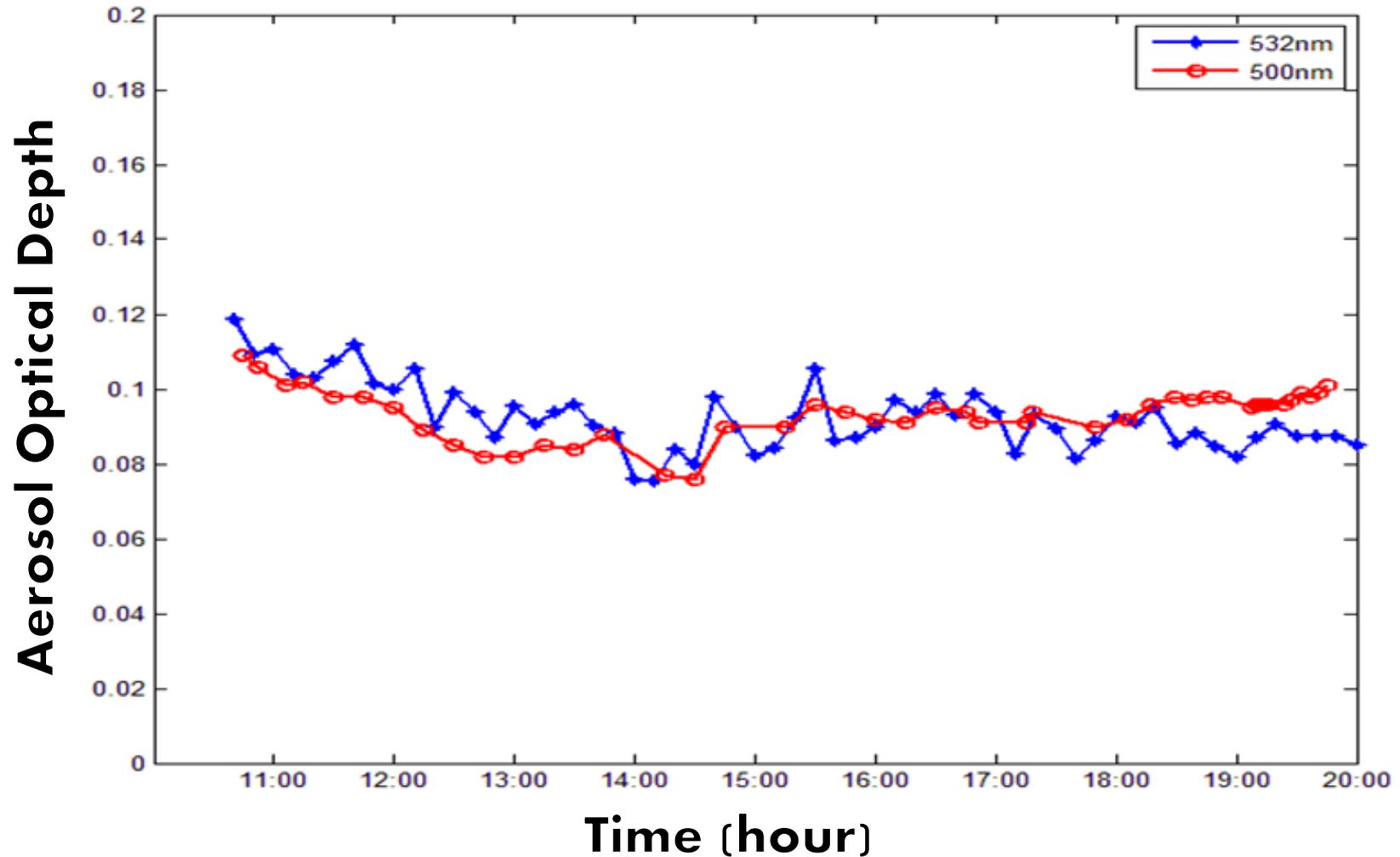




# Comparison with Sun-photometer



## Sun-photometer CE<sub>318</sub> 500nm, Aug. 20, 2013

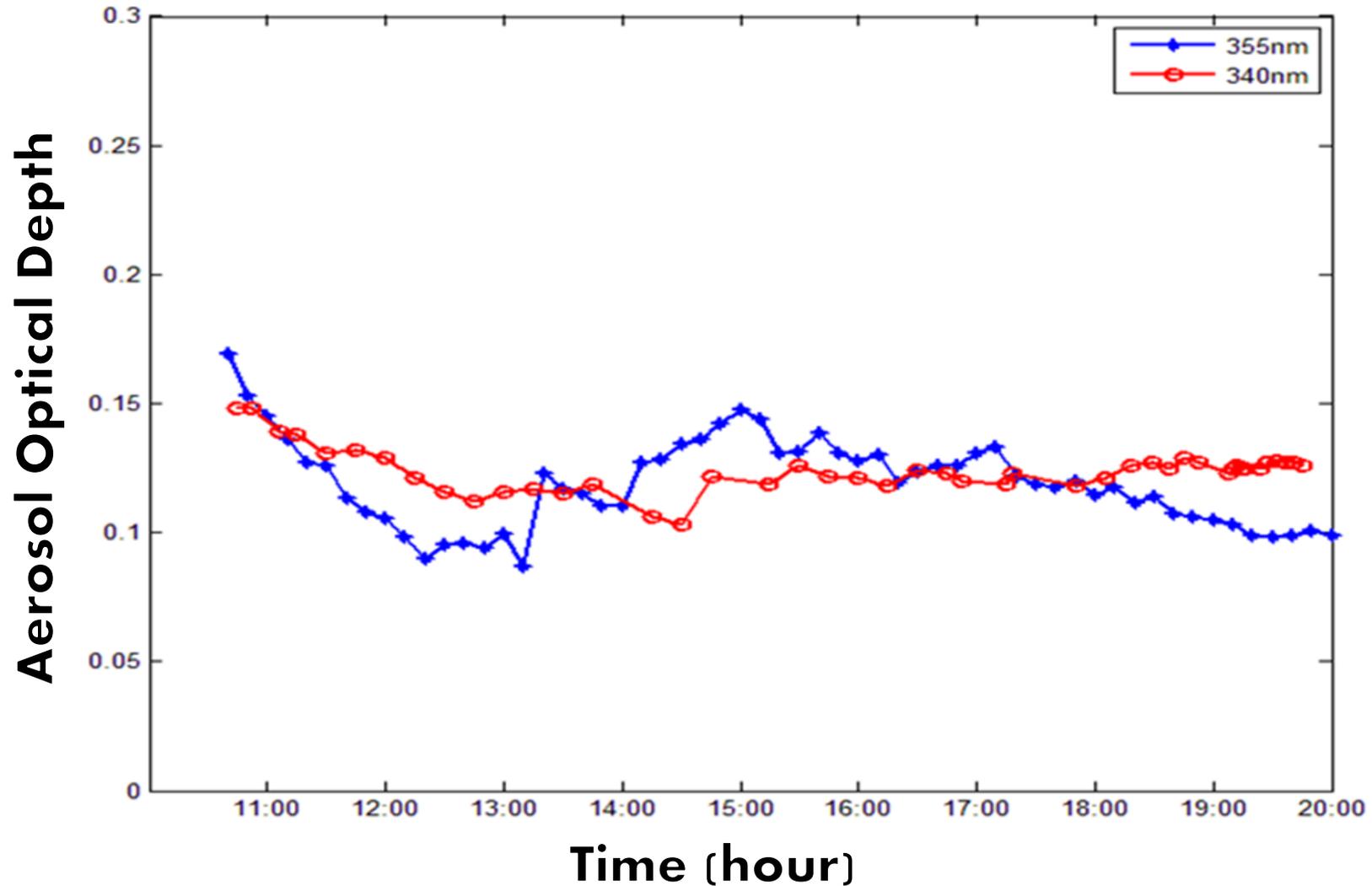




# Comparison with Sun-photometer

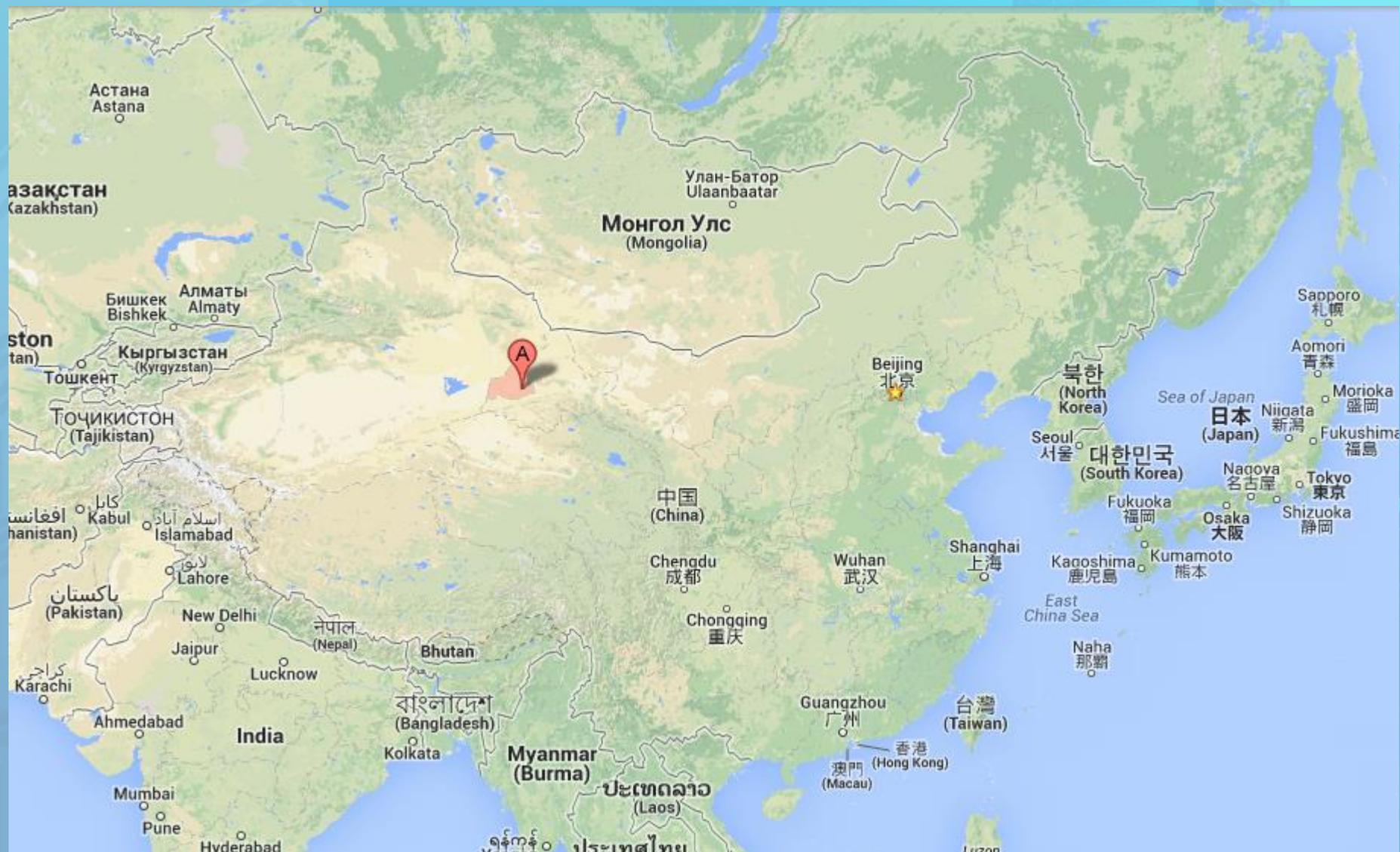


## Sun-photometer CE<sub>318</sub> 340 nm, Aug. 20, 2013





# Results from the field measurements

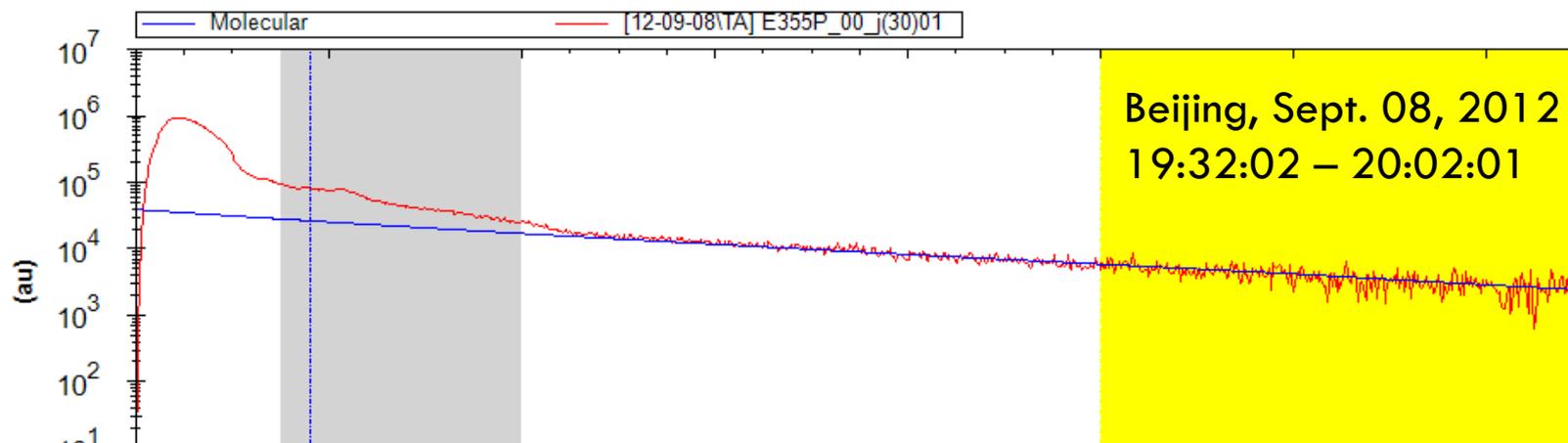




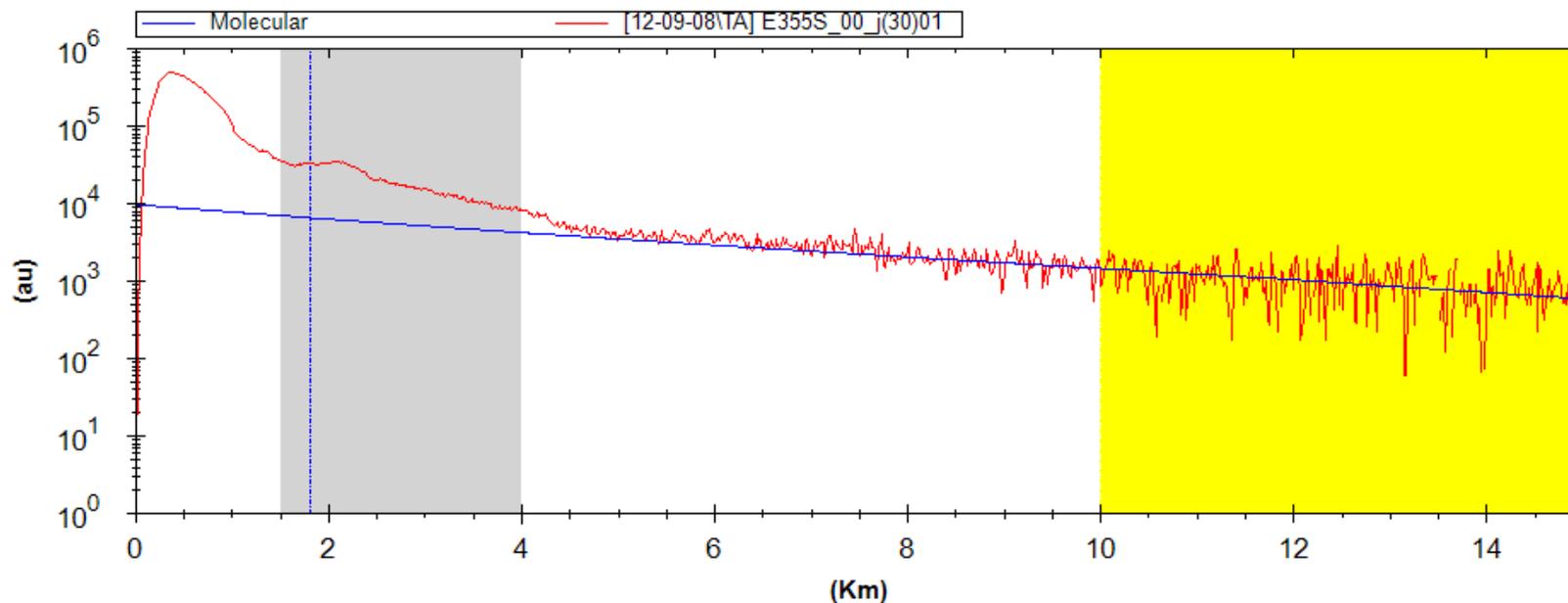
# Results in Beijing



E355P - 08/09/12 12:32 (100 ns) RCS[355]

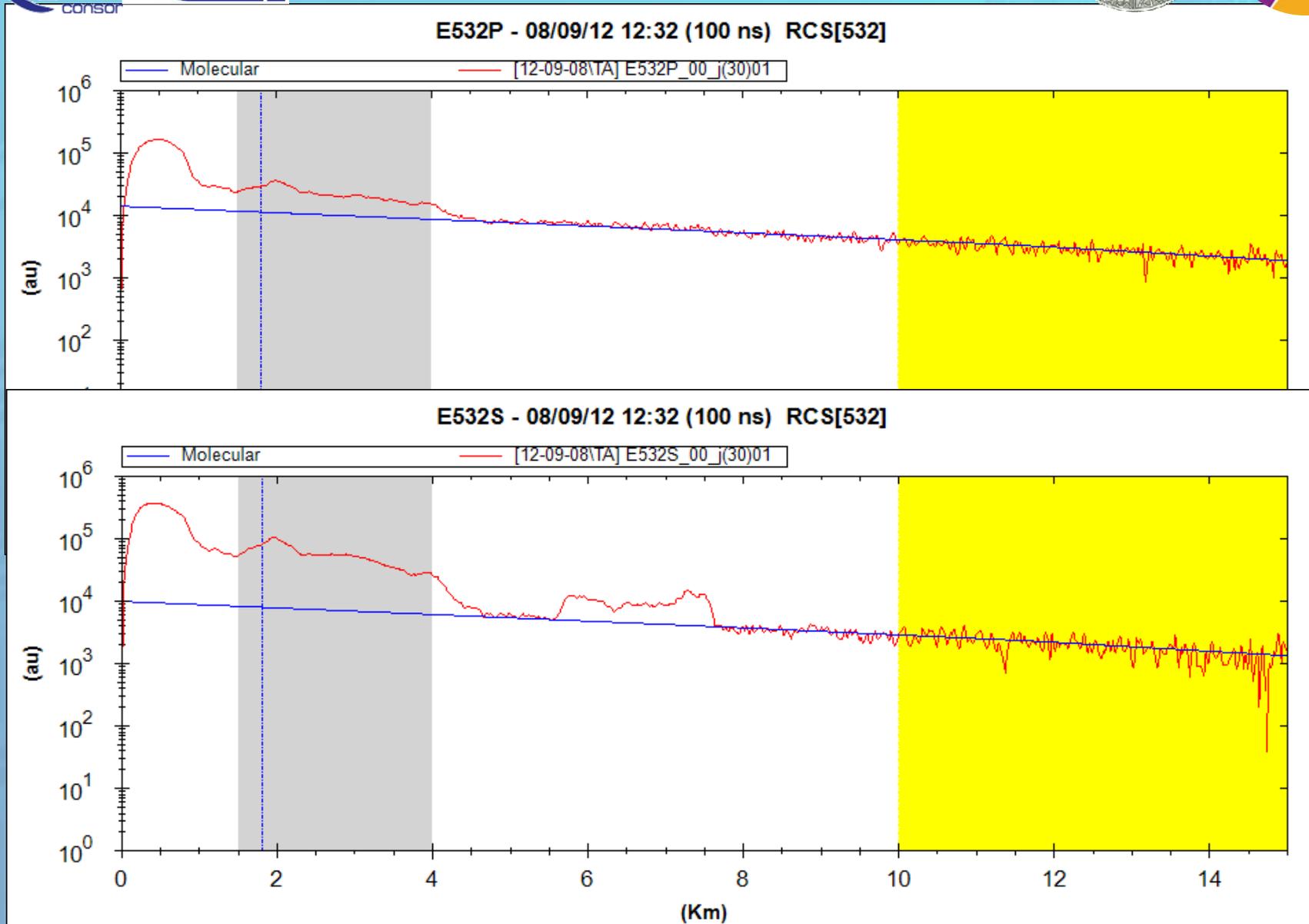


E355S - 08/09/12 12:32 (100 ns) RCS[355]

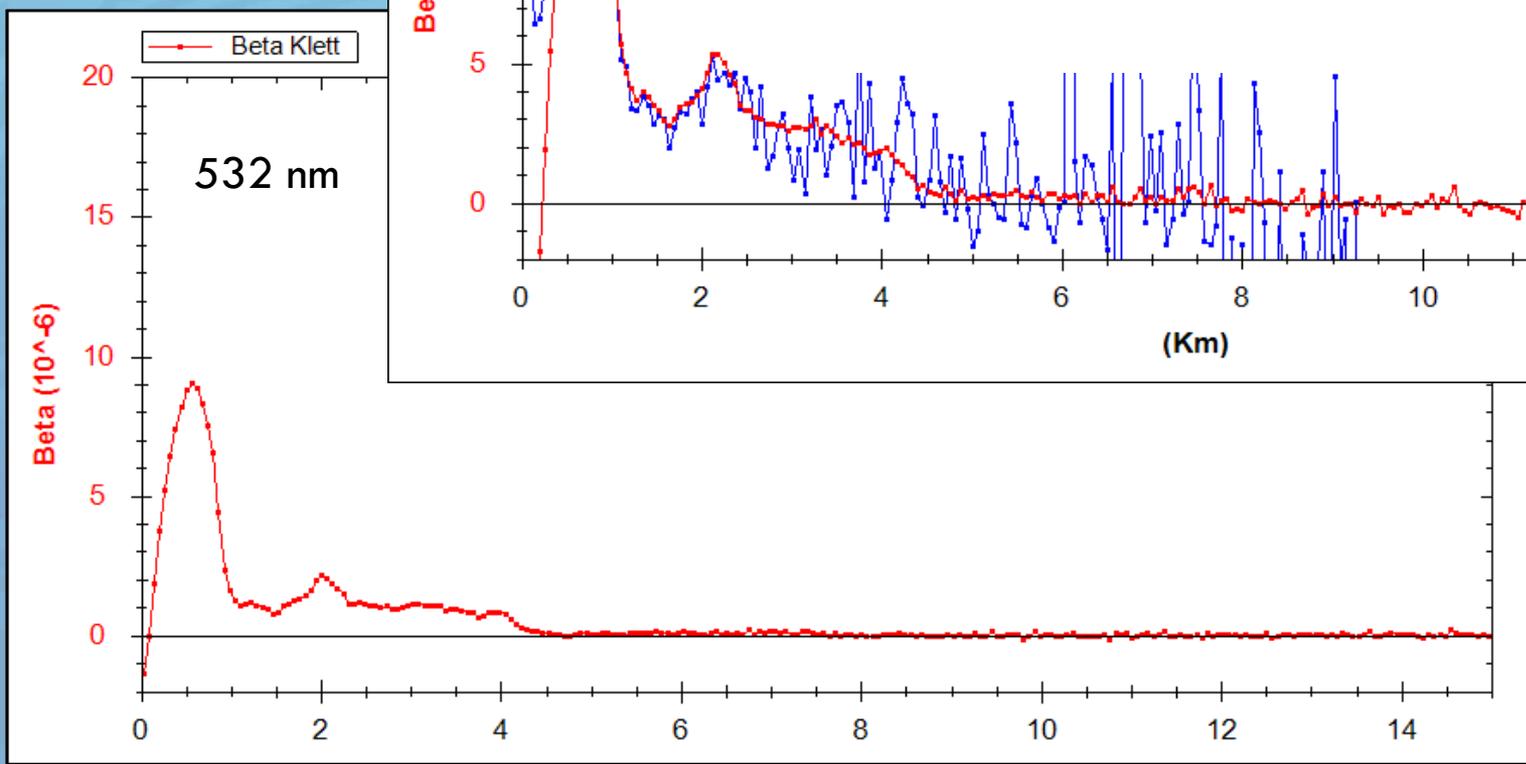
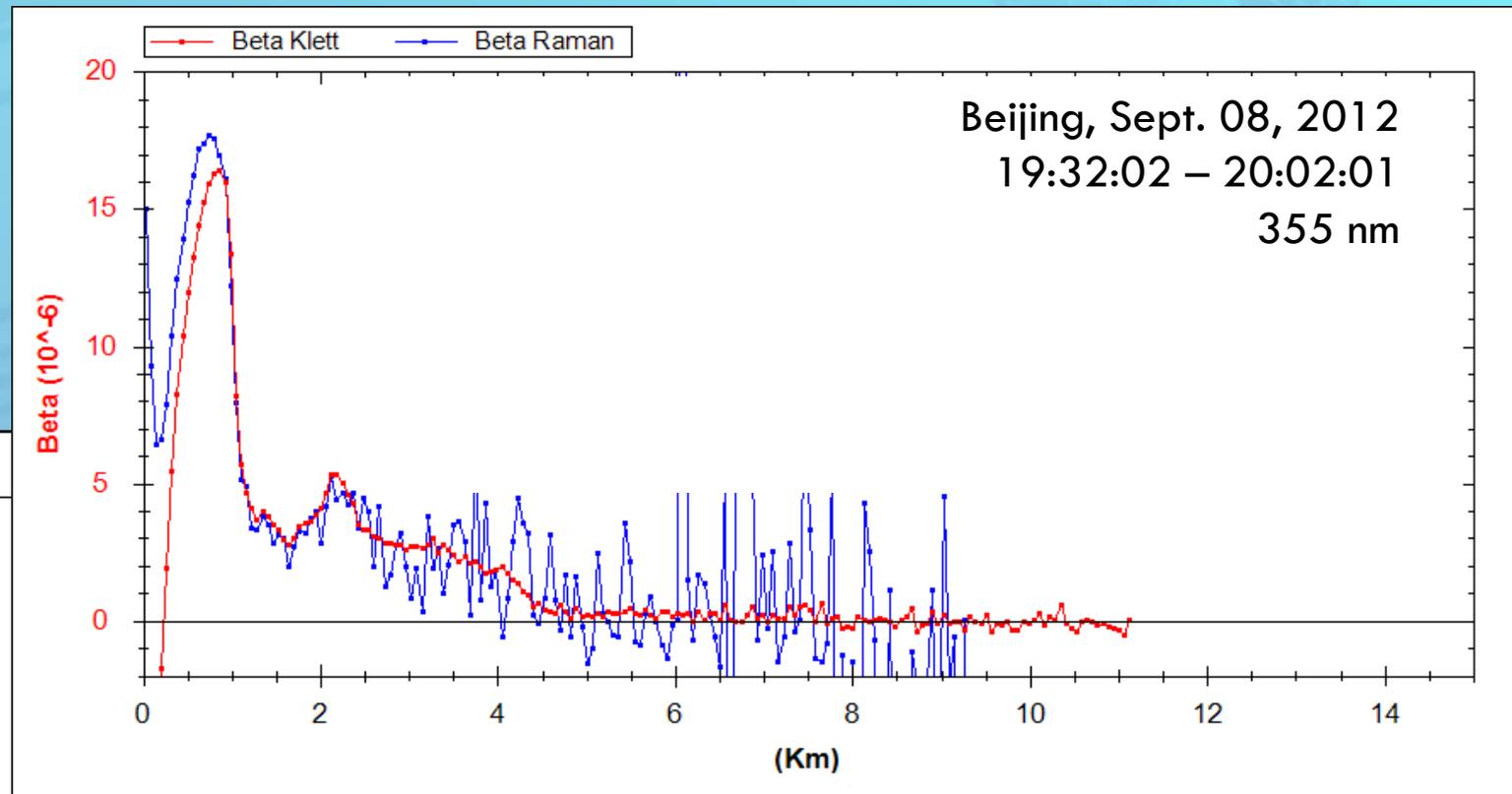




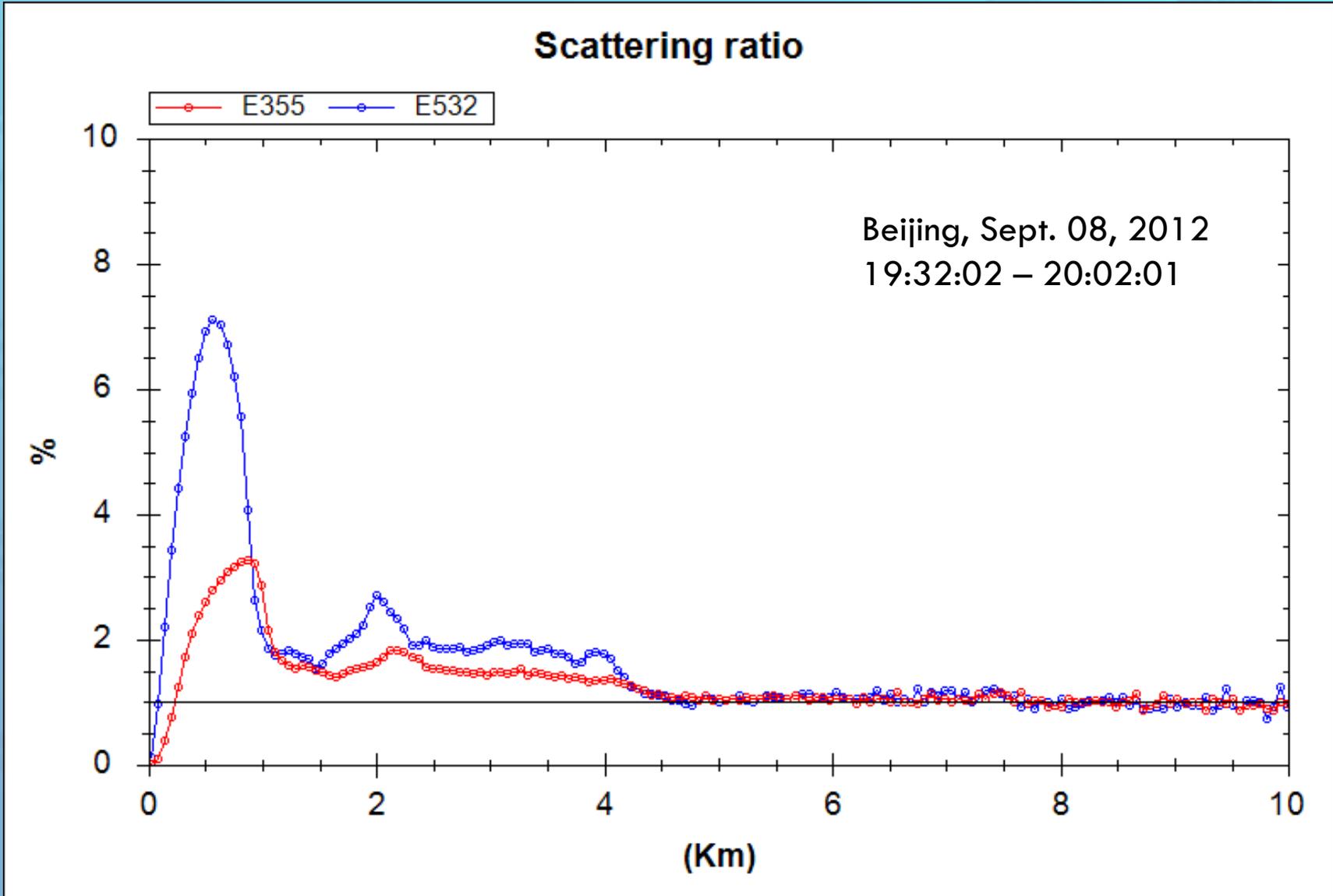
# Results in Beijing



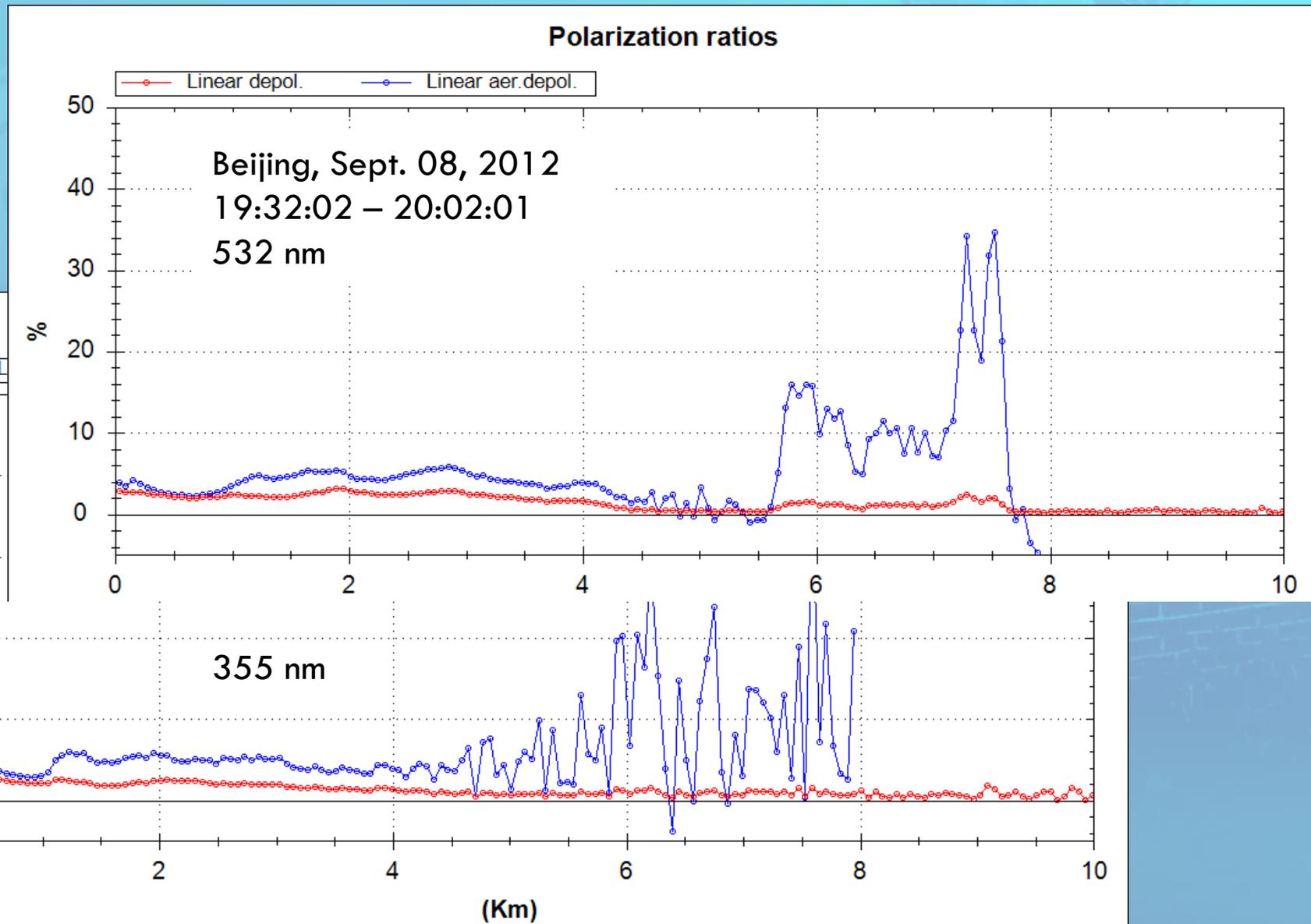
# Results in Beijing



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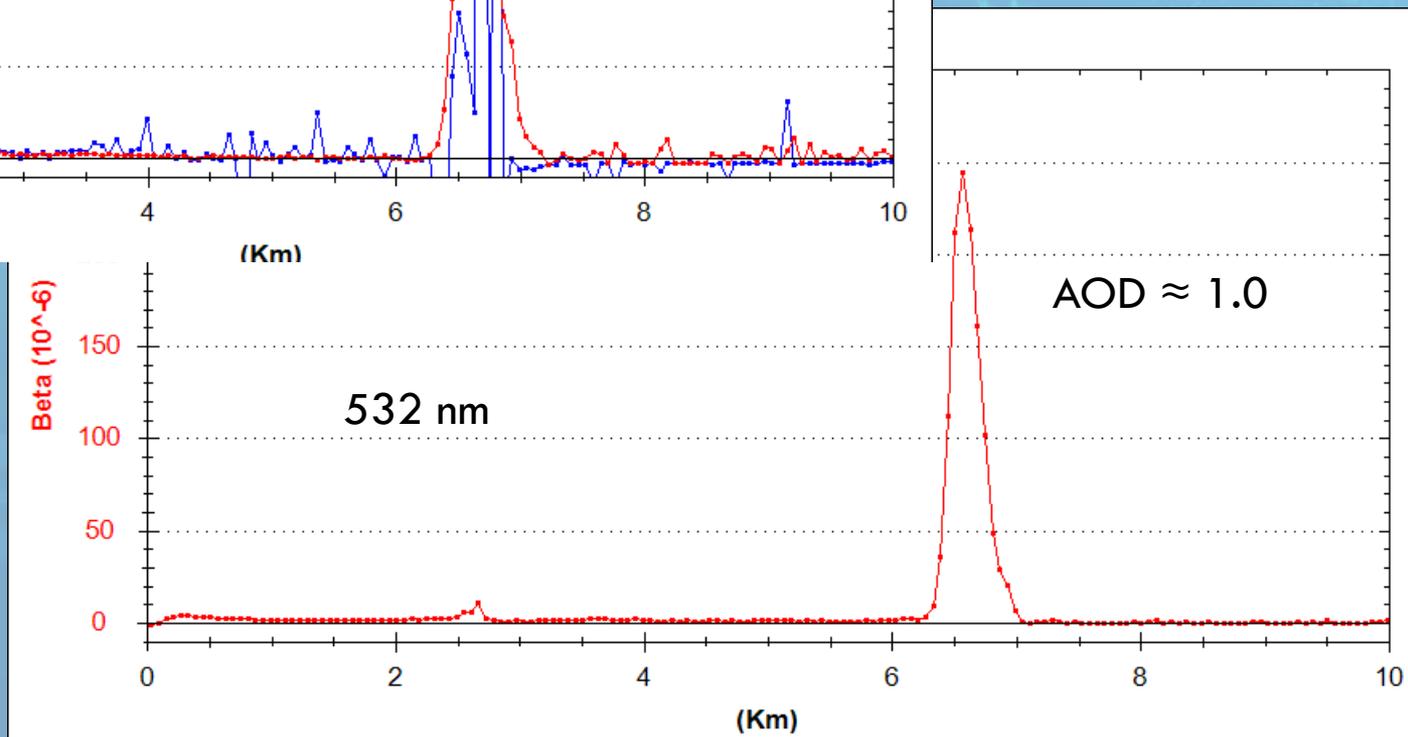
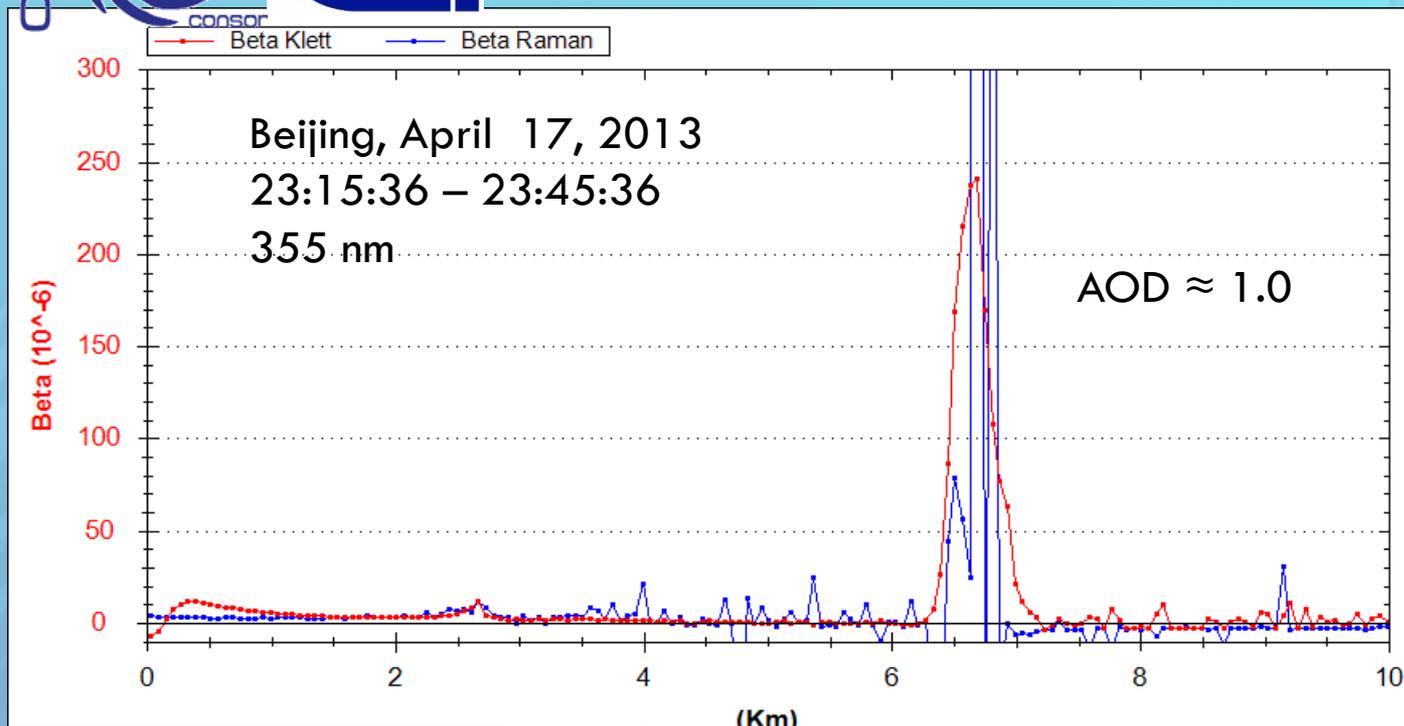


# Results in Beijing





# Results in Beijing





# Results in Dunhuang

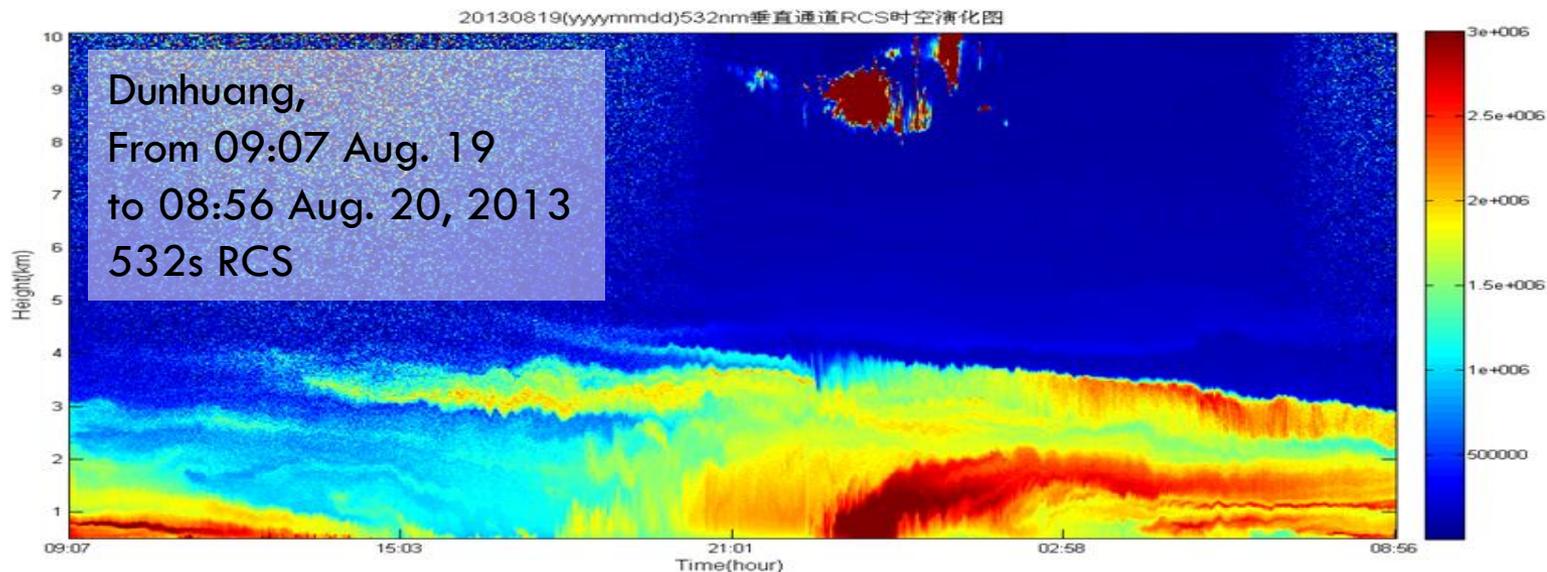
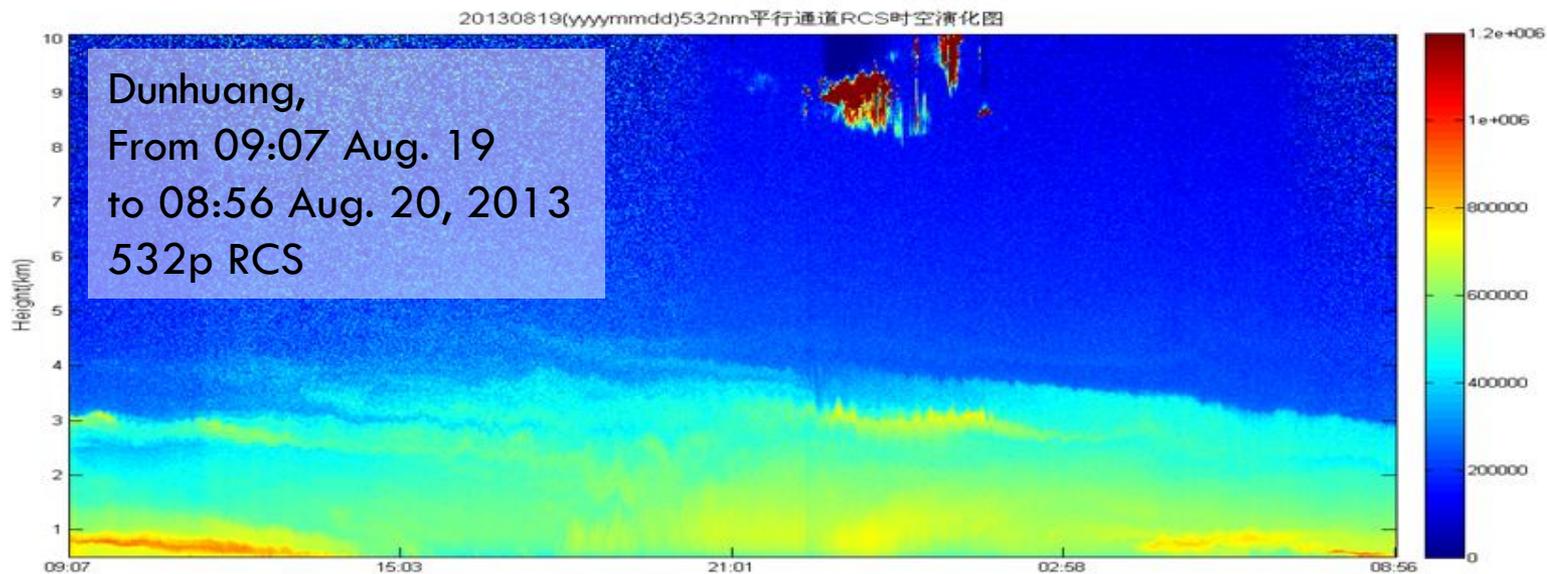


Dunhuang, @ 40.8N , 94.41E

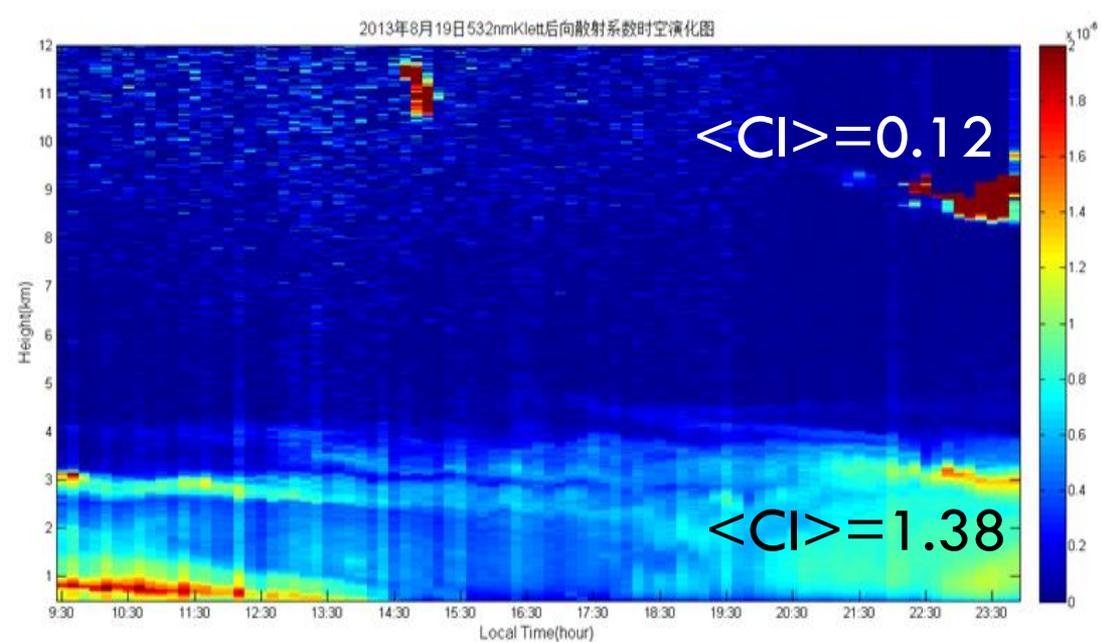
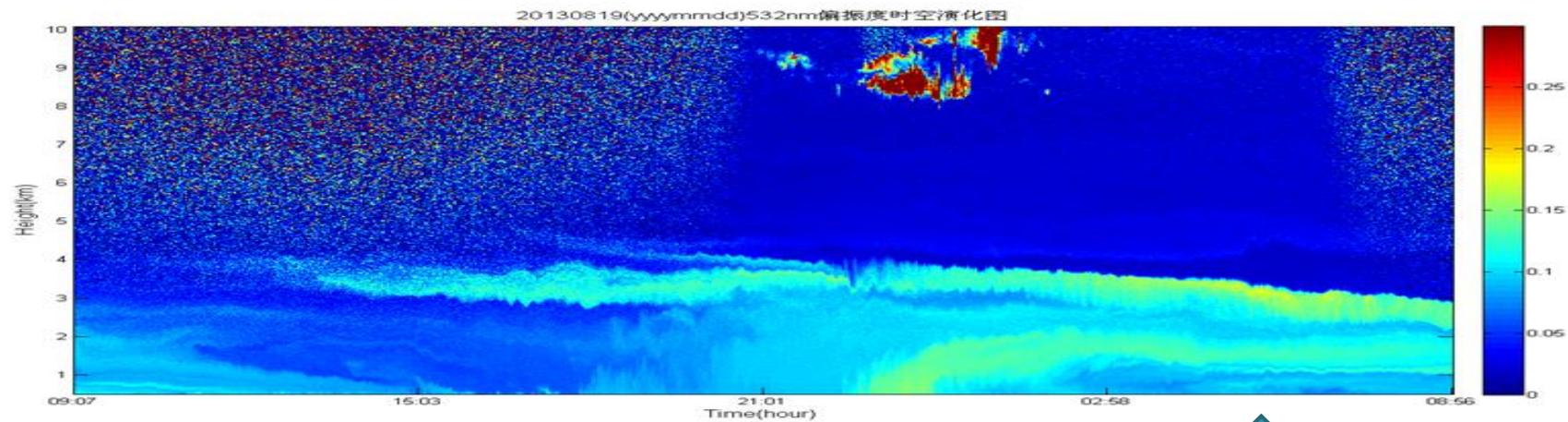




# Results in Dunhuang



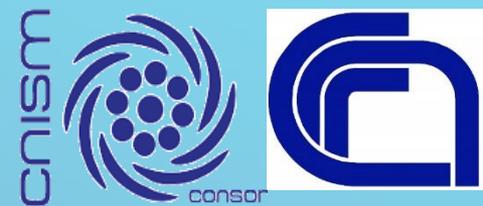
# Results in Dunhuang



↑  
532 Depolarization

← 532 Backscattering

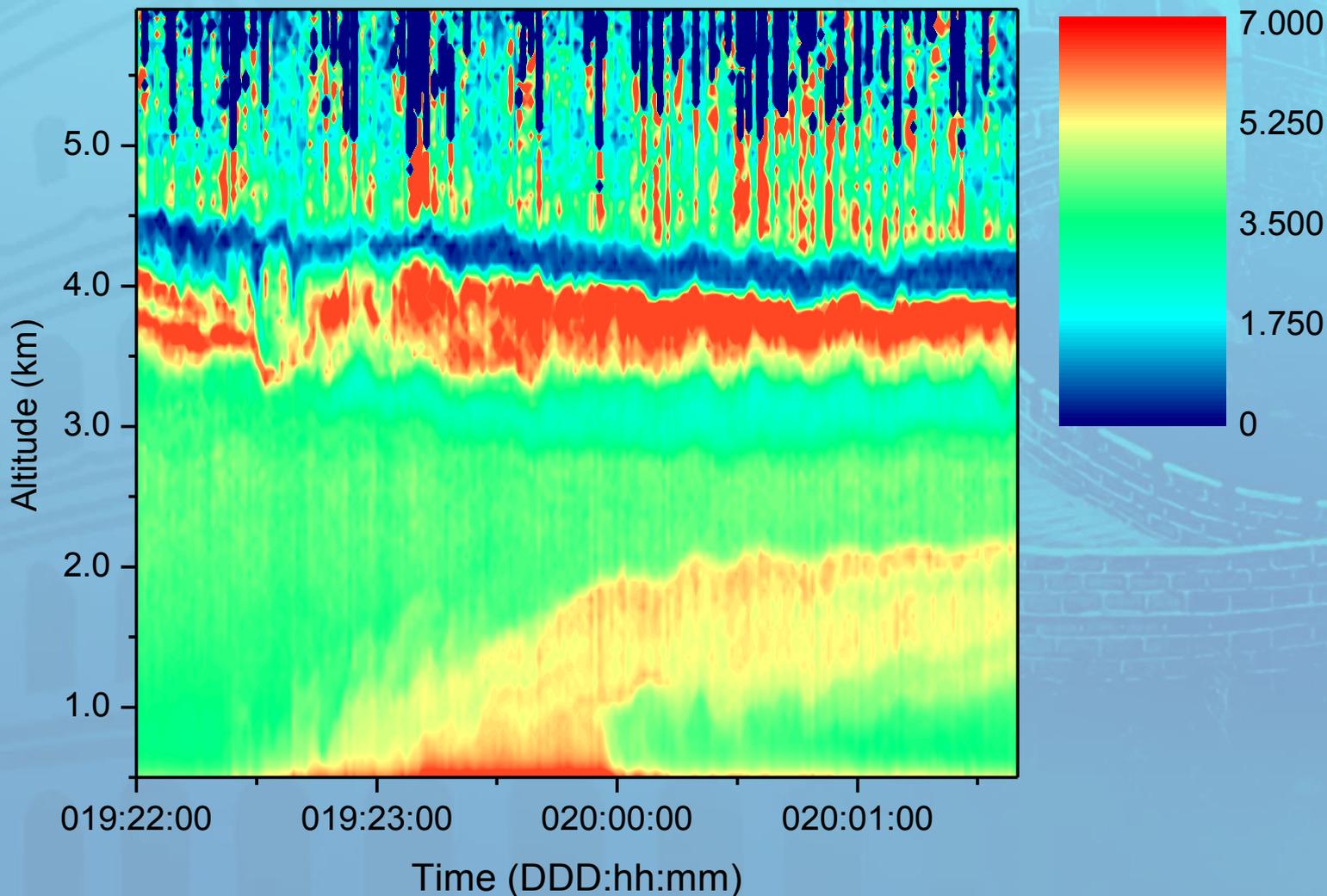
Dunhuang,  
From 09:07 Aug. 19  
to 08:56 Aug. 20, 2013



# Results in Dunhuang



Aerosol Depolarization (%) @532nm

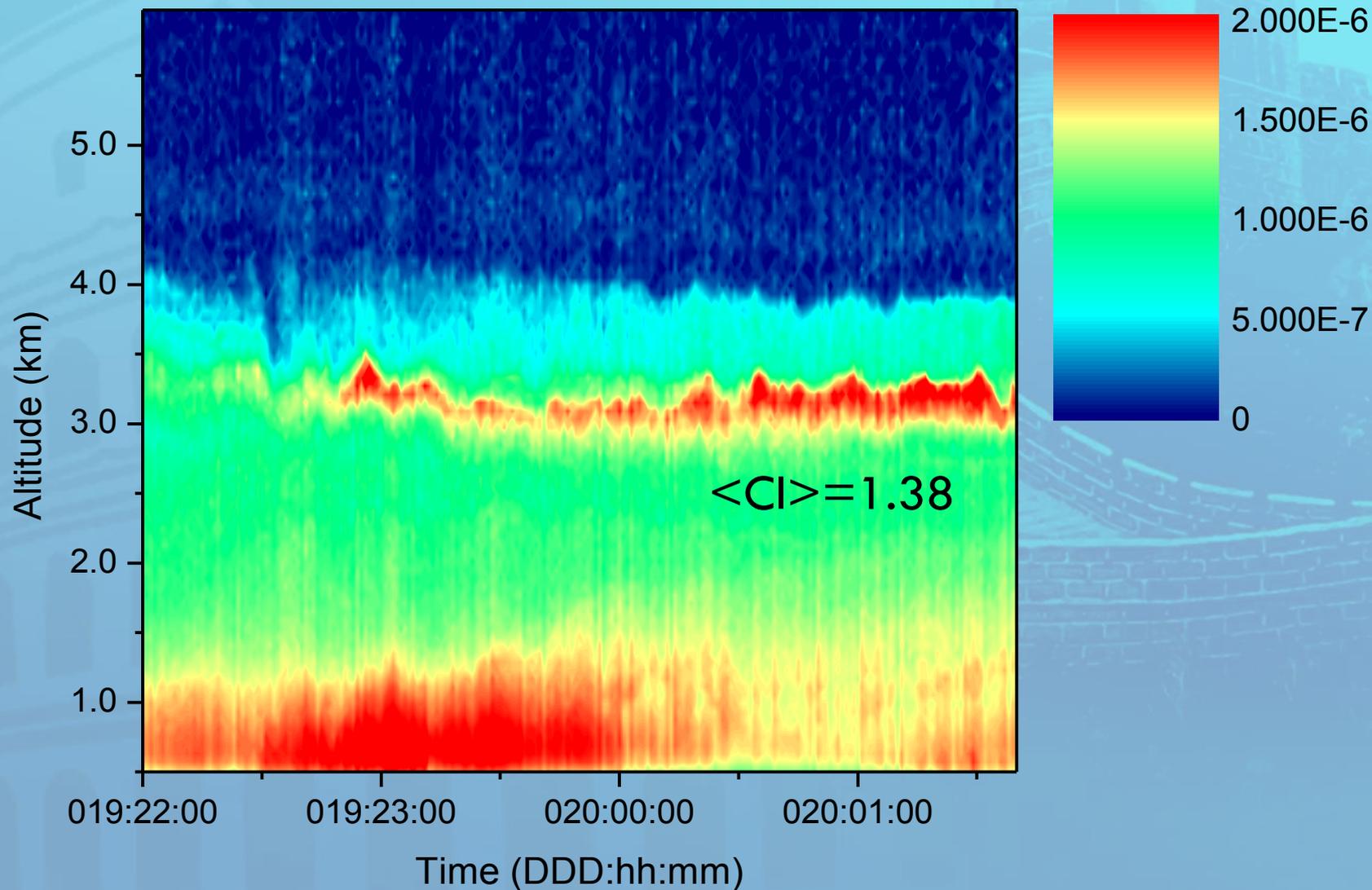




# Results in Dunhuang



Aerosol Backscatter coefficient ( $\text{m}^{-1}\text{sr}^{-1}$ ) @532nm

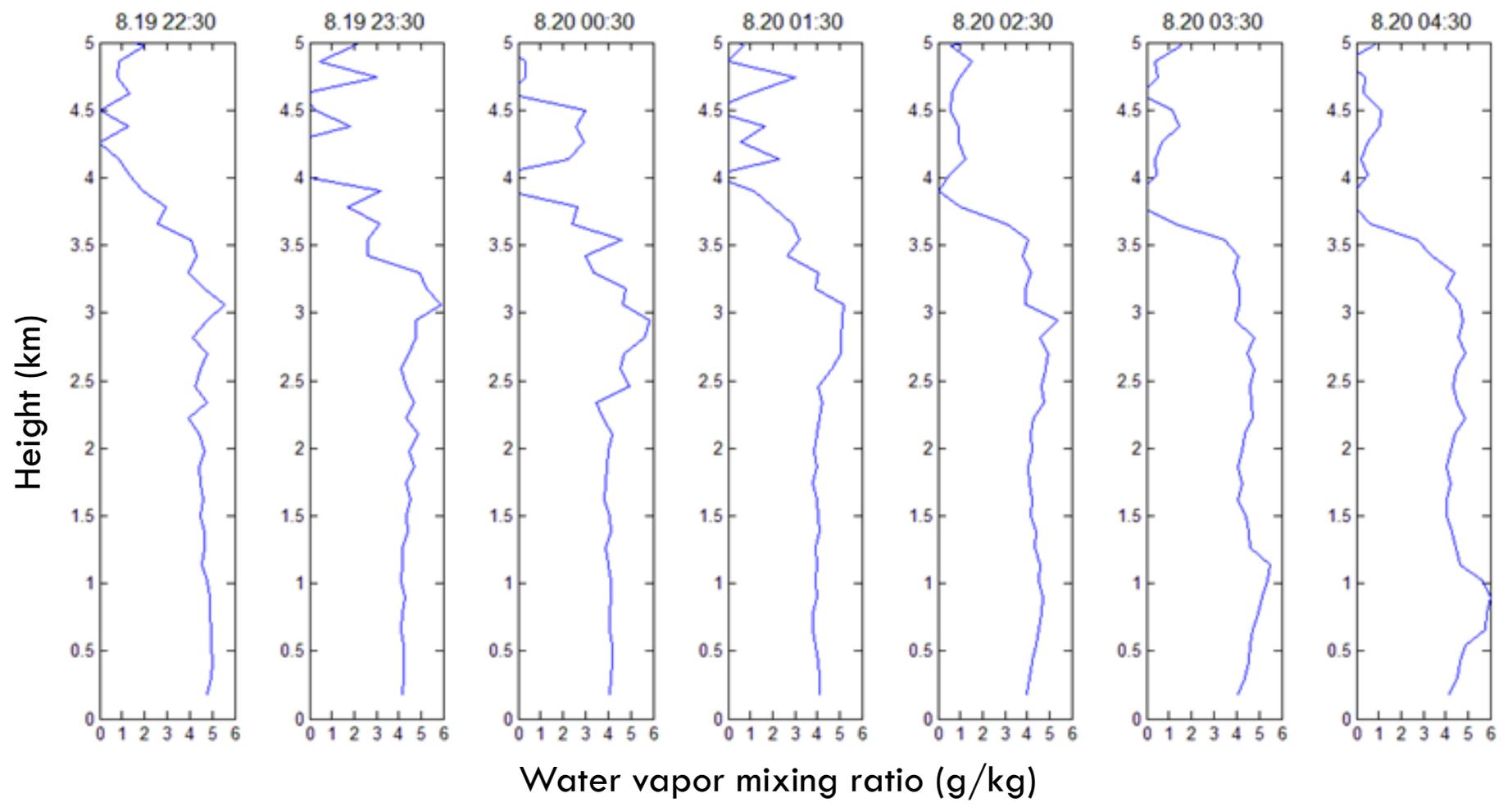


# Results in Dunhuang

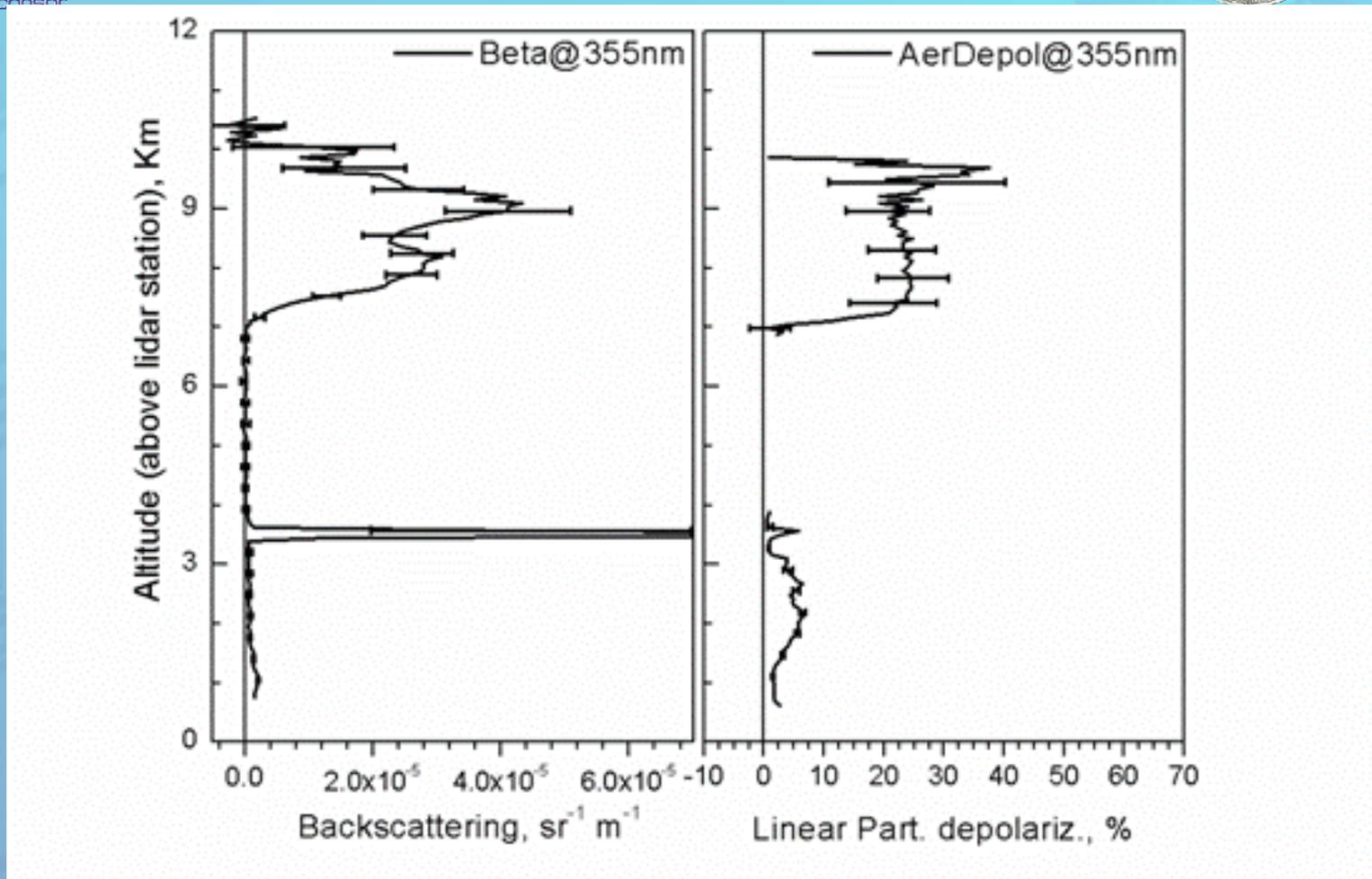


Water vapor mixing ratio

Dunhuang, Aug. 20, 2013



# Results in Catania



Backscatter (left) and particle depolarization (right) profiles measure at Serra la Nave (Catania, Italy, 1760 m a.s.l.) (15min)

# Conclusion



1. **A new, versatile prototype of polarization, Raman scanning lidar system (named AMPLE - Aerosol Multi-wavelength Polarization LIDAR Experiment) has been designed and implemented.**
2. **Special, unusual design allow it to perform Raman measurements for high dense aerosol load thanks its high dynamic signal range.**
3. **Field measurement results show that AMPLE lidar system is suitable for quantity monitoring and 3D mapping of dense mineral aerosol, high polluted urban aerosol and volcanic ash plume.**