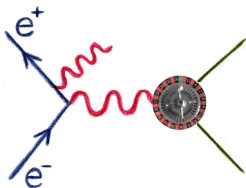


The Why's and How's of covariance matrices in the KLOE ISR analyses

S. E. Müller



*Radio MonteCarLOW Meeting
ECT* Trento, 11-12 April 2013*

The covariance matrix

A covariance matrix describes the correlation between the fluctuations (uncertainties) of n observables (data points)

$$V = \begin{pmatrix} \sigma_1^2 & \sigma_{12} & \sigma_{13} & \dots & \sigma_{1n} \\ \sigma_{21} & \sigma_2^2 & \sigma_{23} & \dots & \sigma_{2n} \\ \sigma_{31} & \sigma_{32} & \sigma_3^2 & \dots & \sigma_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sigma_{n1} & \sigma_{n2} & \sigma_{n3} & \dots & \sigma_{nn} \end{pmatrix}$$

The diagonal elements contain the squared uncertainties (variances).
The off-diagonal elements contain the correlation coefficient ρ :

$$\sigma_{ij} = \rho_{ij} \sigma_i \sigma_j$$

$$-1 \leq \rho \leq +1$$

If the observables are uncorrelated, the ρ 's are zero and the covariance matrix is diagonal.

The covariance matrix

The uncertainty of a function $f = f(x_1, x_2, \dots, x_n)$ which depends on the (correlated) observables is constructed via

$$\sigma_f^2 = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right) \begin{pmatrix} \sigma_1^2 & \sigma_{12} & \sigma_{13} & \dots & \sigma_{1n} \\ \sigma_{21} & \sigma_2^2 & \sigma_{23} & \dots & \sigma_{2n} \\ \sigma_{31} & \sigma_{32} & \sigma_3^2 & \dots & \sigma_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sigma_{n1} & \sigma_{n2} & \sigma_{n3} & \dots & \sigma_{nn} \end{pmatrix} \begin{pmatrix} \partial f / \partial x_1 \\ \partial f / \partial x_2 \\ \vdots \\ \partial f / \partial x_n \end{pmatrix}$$

If the covariance matrix is diagonal, one recovers the familiar formula

$$\sigma_f^2 = \left(\frac{\partial f}{\partial x_1} \right)^2 \sigma_1^2 + \left(\frac{\partial f}{\partial x_2} \right)^2 \sigma_2^2 + \dots + \left(\frac{\partial f}{\partial x_n} \right)^2 \sigma_n^2$$

If the observables are fully correlated ($\rho = +1$), we get

$$\sigma_f^2 = \left(\frac{\partial f}{\partial x_1} \sigma_1 + \frac{\partial f}{\partial x_2} \sigma_2 + \dots + \frac{\partial f}{\partial x_n} \sigma_n \right)^2$$

Dispersion integral for a_μ^{had}

Evaluating a_μ^{had} between s_{min} and s_{max} with a binned data set of n points with binwidth Δs :

$$a_\mu^{\text{had}}[s_{\text{min}}, s_{\text{max}}] = \frac{1}{4\pi^3} \int_{s_{\text{min}}}^{s_{\text{max}}} \sigma^{\text{had}}(s) K(s) ds \simeq \frac{1}{4\pi^3} \sum_{i=1}^n \sigma_i^{\text{had}} K_i \Delta s$$

With $c_i \equiv \partial a_\mu^{\text{had}} / \partial \sigma_i = (1/4\pi^3) K_i \Delta s$ we obtain for the uncertainty on a_μ^{had}

$$\begin{aligned} \left(\sigma_{a_\mu^{\text{had}}}\right)^2 &= \sum_{i=1}^n \sum_{j=1}^n c_i c_j V_{ij} \\ &= \underbrace{\sum_{i=1}^n c_i^2 \sigma_i^2}_{\substack{i=j, \\ \text{diagonal term}}} + \underbrace{\sum_{i=1}^n \sum_{\substack{j=1 \\ j \neq i}}^n c_i c_j \sigma_{ij}}_{\substack{i \neq j, \\ \text{off-diagonal term}}} \end{aligned}$$

The KLOE ISR analysis

From the observed spectrum to the ISR cross section:

$$\frac{d\sigma^{\pi\pi+\gamma}}{ds_\pi} = \frac{\Delta N_{Obs} - \Delta N_{Bkg}}{\Delta s_\pi} \cdot \frac{1}{\int \mathcal{L} dt} \cdot \frac{1}{\epsilon_{Sel}}$$

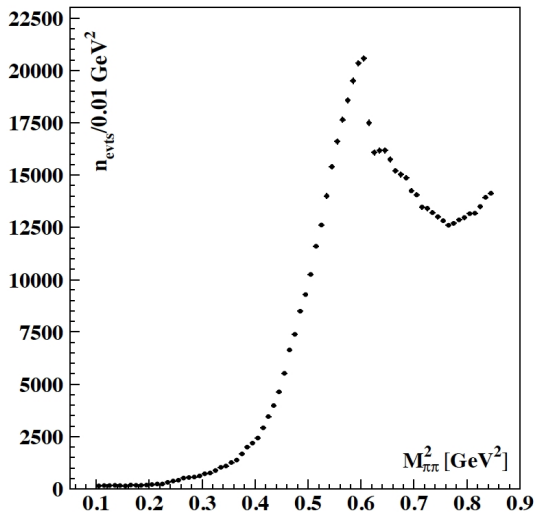
Applying the radiator function $H(s_\pi, s)$:

$$\sigma^{\pi\pi}(s_\pi) = \frac{d\sigma^{\pi\pi+\gamma}}{ds_\pi} \cdot s \cdot \frac{1}{H(s_\pi, s)}$$

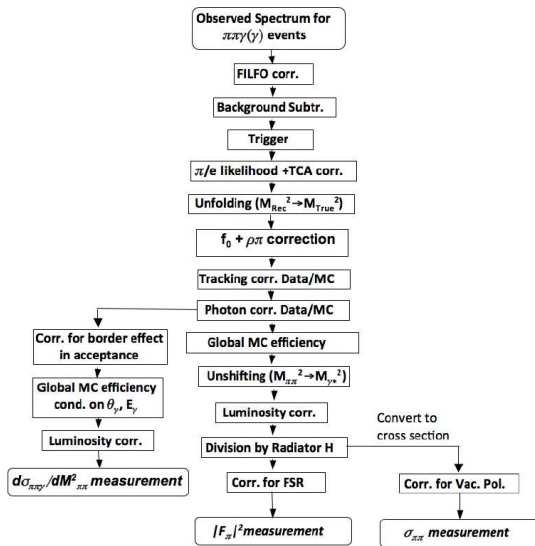
Dispersion integral:

$$a_\mu^{\pi\pi}[s_{\min}, s_{\max}] = \frac{1}{4\pi^3} \int_{s_{\min}}^{s_{\max}} \sigma^{\pi\pi}(s) K(s) ds$$

The observed spectrum (KLOE10)



Data analysis flow (KLOE10)



Uncorrelated uncertainties:

Uncertainties independent between different data points (bins) - enter only in diagonal elements of covariance matrix.

- ▶ e.g. stat. errors of observed spectrum

“Sum of squares” in the uncertainty estimation of $a_{\mu}^{\pi\pi}$:

$$\left(\sigma_{a_{\mu}^{\pi\pi}}\right)^2 = \sum_{i=1}^n \left(\frac{1}{4\pi^3} (\sigma_{\sigma_{\pi\pi}})_i K_i \Delta s \right)^2$$

$(\sigma_{\sigma_{\pi\pi}})_i$ can combine several uncorrelated uncertainties

$$(\sigma_{\sigma_{\pi\pi}})_i = \sqrt{\left(\sigma_i^{\text{spectrum}}\right)^2 + \left(\sigma_i^{\text{eff}}\right)^2 + \dots}$$

Fully correlated uncertainties:

Uncertainties affect all data points (bins) in a similar way. Covariance matrix elements are constructed as $V_{ij} = +1 \cdot \sigma_i \sigma_j$.

- ▶ e.g. error on int. luminosity measurement $\int \mathcal{L} dt$

“Square of sum” in the uncertainty estimation of $a_{\mu}^{\pi\pi}$:

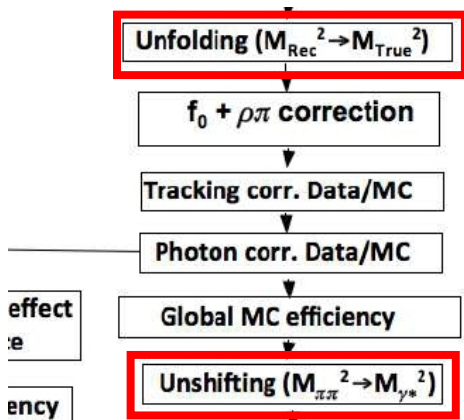
$$\left(\sigma_{a_{\mu}^{\pi\pi}}\right)^2 = \left(\sum_{i=1}^n \frac{1}{4\pi^3} (\sigma_{\sigma_{\pi\pi}})_i K_i \Delta s\right)^2$$

$(\sigma_{\sigma_{\pi\pi}})_i$ can not be a combined uncertainty (unless it's constant) - need to evaluate $(\sigma_{a_{\mu}^{\pi\pi}})^2$ for each individual uncertainty source (background, efficiencies, etc.) - then combine quadratically:

$$\left(\sigma_{a_{\mu}^{\pi\pi}}\right) = \sqrt{\left(\sigma_{a_{\mu}^{\text{background}}}\right)^2 + \left(\sigma_{a_{\mu}^{\text{eff}_1}}\right)^2 + \left(\sigma_{a_{\mu}^{\text{eff}_2}}\right)^2 + \dots}$$

Uncertainty

Partially correlated uncertainties:



Unfolding

Correction for detector resolution

- Passage from reconstructed quantity $s_{\pi}^{\text{rec}} \rightarrow s_{\pi}^{\text{true}}$ requires re-distribution of events:

$$N_i^{\text{true}} = \sum_{j=1}^n P(N_i^{\text{true}} | N_j^{\text{rec}}) \cdot N_j^{\text{rec}}$$

- $P(N_i^{\text{true}} | N_j^{\text{rec}})$ from unfolding method using Bayesian approach (G. D'Agostino, NIM A362 (1995) 487)

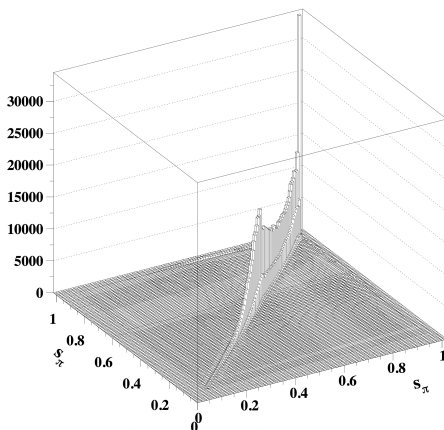
$$P(N_i^{\text{true}} | N_j^{\text{rec}}) = \frac{P(N_j^{\text{rec}} | N_i^{\text{true}}) \cdot P_0(N_i^{\text{true}})}{\underbrace{\sum_{k=1}^{n_{\text{true}}} P(N_j^{\text{rec}} | N_k^{\text{true}}) \cdot P_0(N_k^{\text{true}})}_{\text{from MC}}}$$

- Need to find contributions to covariance matrix of the N_i^{true} due to $P(N_i^{\text{true}} | N_j^{\text{rec}})$ and N_j^{rec} .

Unfolding

Contribution to covariance matrix

- D'Agostini's code provides the covariance matrix after the unfolding procedure:

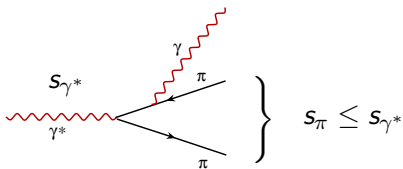


Covariance matrix of results - 1 -

Unshifting

Correction for shift in s_π due to FSR events

The presence of FSR shifts the observed value of s_π (evaluated from the 2 pion tracks' momenta) away from the invariant mass squared of the virtual photon s_{γ^*} :



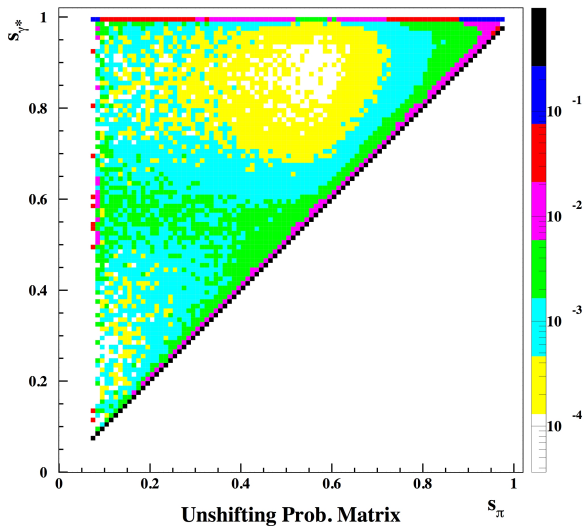
Redistribute events to obtain “unshifted” distribution:

$$N_i^{s_{\gamma^*}} = \sum_{j=1}^n P(N_i^{s_{\gamma^*}} | N_j^{s_\pi}) \cdot N_j^{s_\pi}$$

$P(N_i^{s_{\gamma^*}} | N_j^{s_\pi})$ obtained from MC (Phokhara_omega)

Unshifting

Probability matrix:



Unshifting

Contribution to covariance matrix:

Rewrite the unshifting procedure as

$$\vec{y}_{s_{\gamma^*}} = \mathbf{M} \cdot \vec{x}_{s_{\pi}} \Leftrightarrow y_k = \sum_{i=1}^n M_{ki} \cdot x_i$$

Then error propagation gives

$$V_{kl}^y = \sum_{i=1}^n \sum_{j=1}^n M_{ki} \underbrace{\text{cov}(x_i, x_j)}_{V_{ij}^x} M_{lj} + \sum_{i=1}^n \sum_{j=1}^n x_i \text{cov}(M_{ki}, M_{lj}) x_j$$

$\text{cov}(x_i, x_j)$ is the element V_{ij}^x of the covariance matrix of $\vec{x}_{s_{\pi}}$.

Need to evaluate $\text{cov}(M_{ki}, M_{lj})$

Unshifting

Evaluation of $\text{cov}(M_{ki}, M_{lj})$:

The transfer matrix \mathbf{M} is constructed from a 2 dim population histogram in s_{γ^*} and s_{π} which is normalized to the sum

$$N_i^{\text{tot}} = \sum_{k=1}^n N_{ik} \text{ for a given bin } i \text{ in the shifted variable } s_{\pi}.$$

- ▶ Each column M_{ki} for given i follows a multinomial distribution:

$$M_{ki} = N_{ki}/N_i^{\text{tot}} \quad , \quad \sum_{k=1}^n M_{ki} = 1$$

- ▶ $\text{cov}(M_{ki}, M_{lj}) = 0$ for $i \neq j$

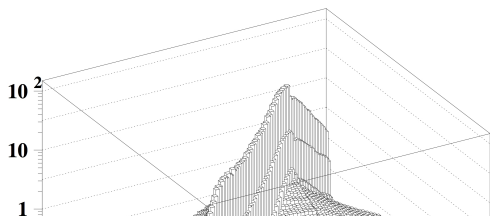
Therefore we get

$$\text{cov}(M_{ki}, M_{lj}) = \begin{cases} M_{ki}(1 - M_{ki})/N_i^{\text{tot}} & \text{if } i = j, k = l \\ -(M_{ki}M_{li})/N_i^{\text{tot}} & \text{if } i = j, k \neq l \\ 0 & \text{else} \end{cases}$$

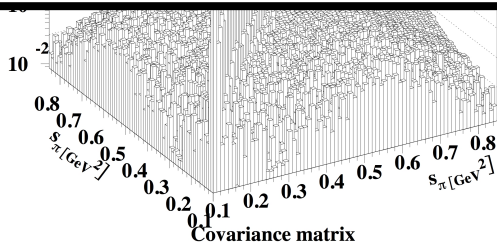
And finally...

The final covariance matrix:

Including also all uncorrelated uncertainties in the diagonal elements



$$\Delta a_{\mu}^{\pi\pi}[0.1 - 0.85\text{GeV}^2] = (478.5 \pm 2.0_{\text{stat}} \pm 5.0_{\text{exp}} \pm 4.5_{\text{theo}}) \times 10^{-10}$$



How to publish?

Long list of numbers

- ▶ KLOE08/12: 3600 entries
- ▶ KLOE10: 5625 entries
- ▶ BaBar: 113569 entries

- Don't publish

- ▶ Ask people to contact you via email

- Publish on institute's webpage

- ▶ <http://www.lnf.infn.it/kloe/ppg/> for KLOE data

- EPAPS depository

- ▶ BaBar result:

ftp://ftp.aip.org/epaps/phys_rev_lett/E-PRLTA0-103-045950/

- ...