

# Atom Interferometry for Detection of Gravitational Waves

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# Atom-based Gravitational Wave Detection

Why consider atoms?

- 1) Neutral atoms are excellent proof masses
  - atom interferometry
- 2) Atoms are excellent clocks
  - optical frequency standards

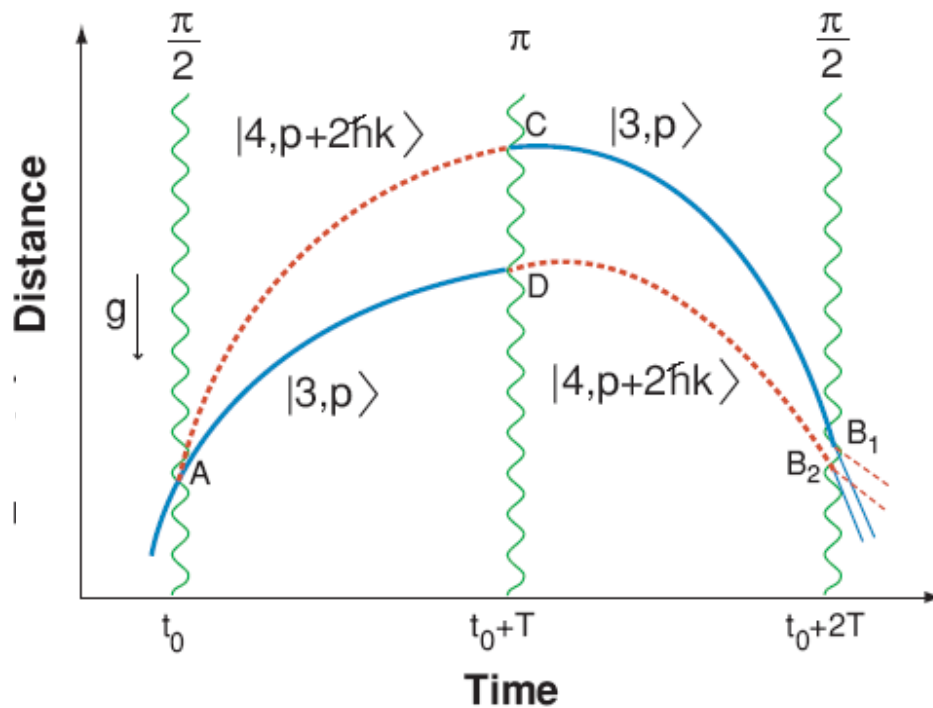


Literature: B. Lamine, et al., Eur. Phys. J. D **20**, (2002); R. Chiao, et al., J. Mod. Opt. **51**, (2004); S. Foffa, et al., Phys. Rev. D **73**, (2006); A. Roura, et al., Phys. Rev. D **73**, (2006); P. Delva, Phys. Lett. A **357** (2006); G. Tino, et al., Class. Quant. Grav. **24** (2007), Dimopoulos, et al., PRD (2008), Graham, et al., PRL (2013).



# Light-pulse atom interferometry

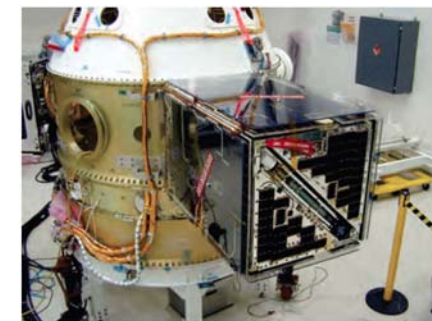
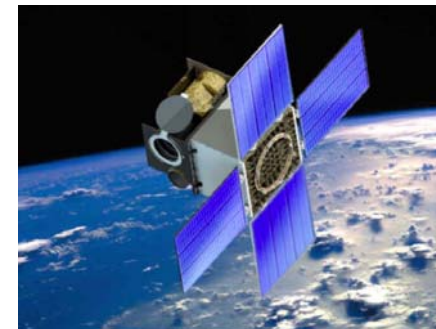
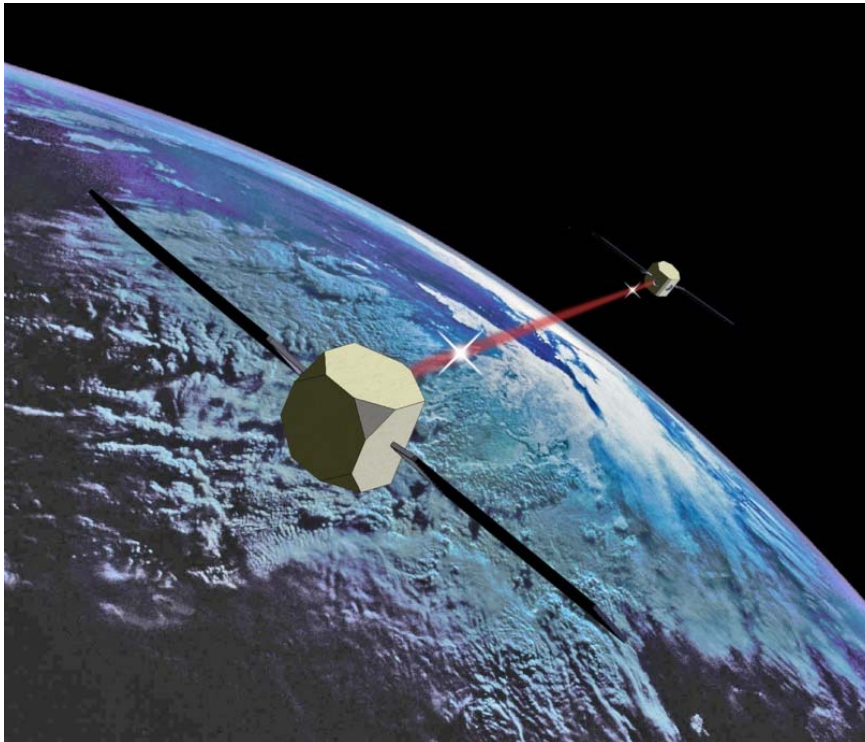
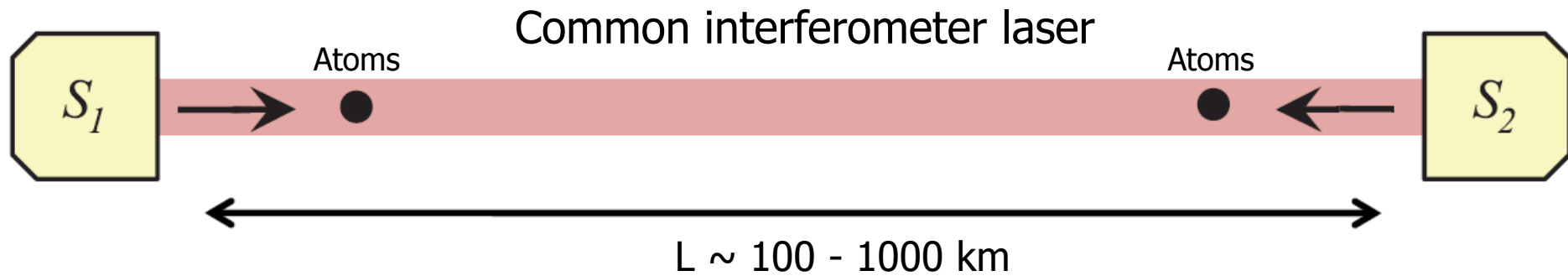
Pulses of light are used to coherently manipulate atom de Broglie waves:



Phase shift read-out by counting atoms at each output port.

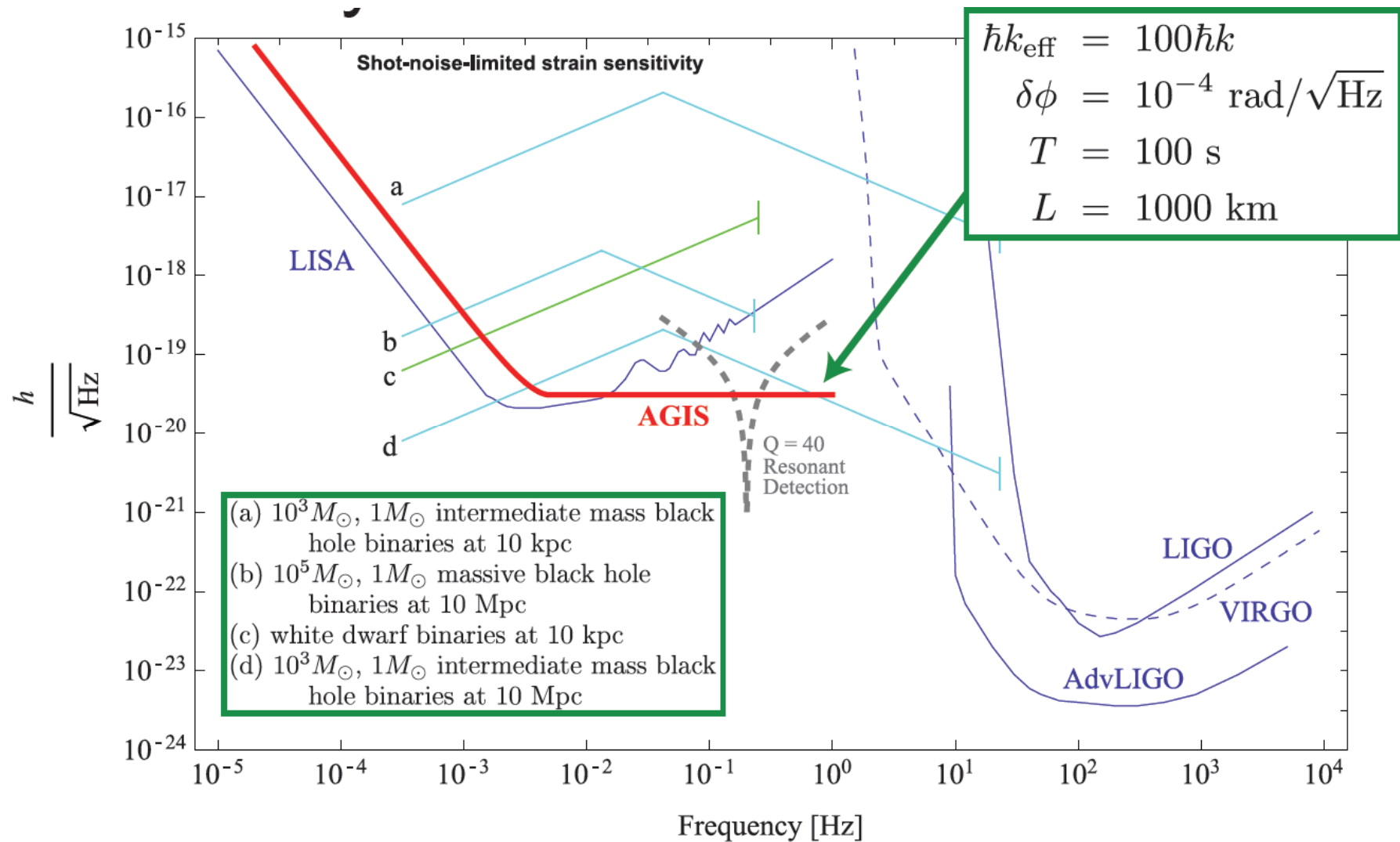


# Satellite GW Antenna

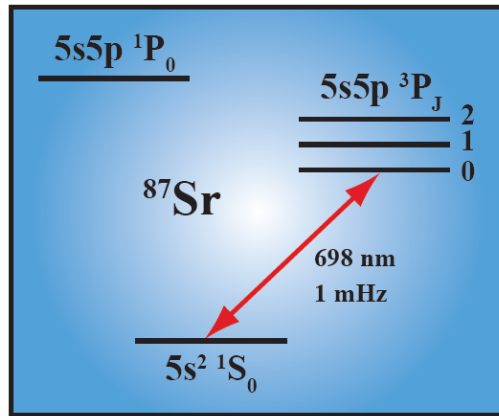


*JMAPS bus/ESPA  
deployed*

# Potential Strain Sensitivity

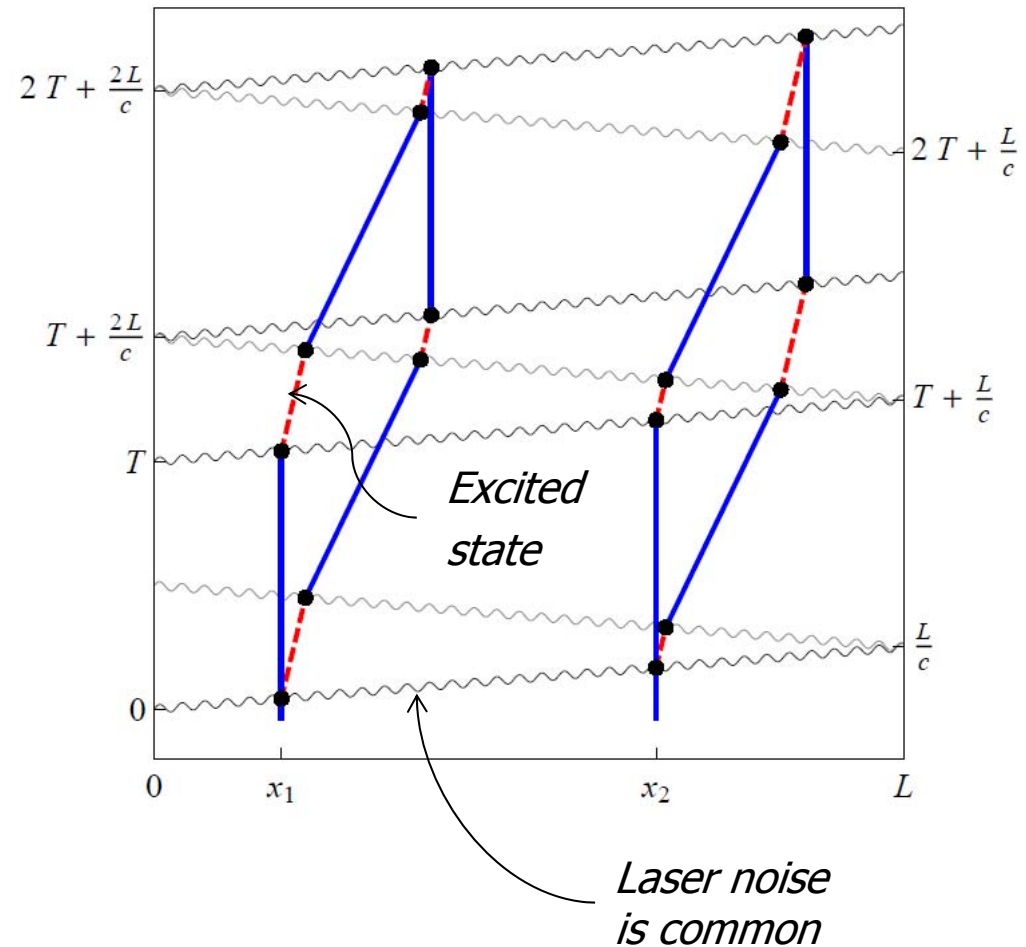


# Laser frequency noise insensitive detector



Clock transition in candidate atom  $^{87}\text{Sr}$

- Long-lived single photon transitions (e.g. clock transition in Sr, Ca, Yb, Hg, etc.).
- Atoms act as clocks, measuring the light travel time across the baseline.
- GWs modulate the laser ranging distance.

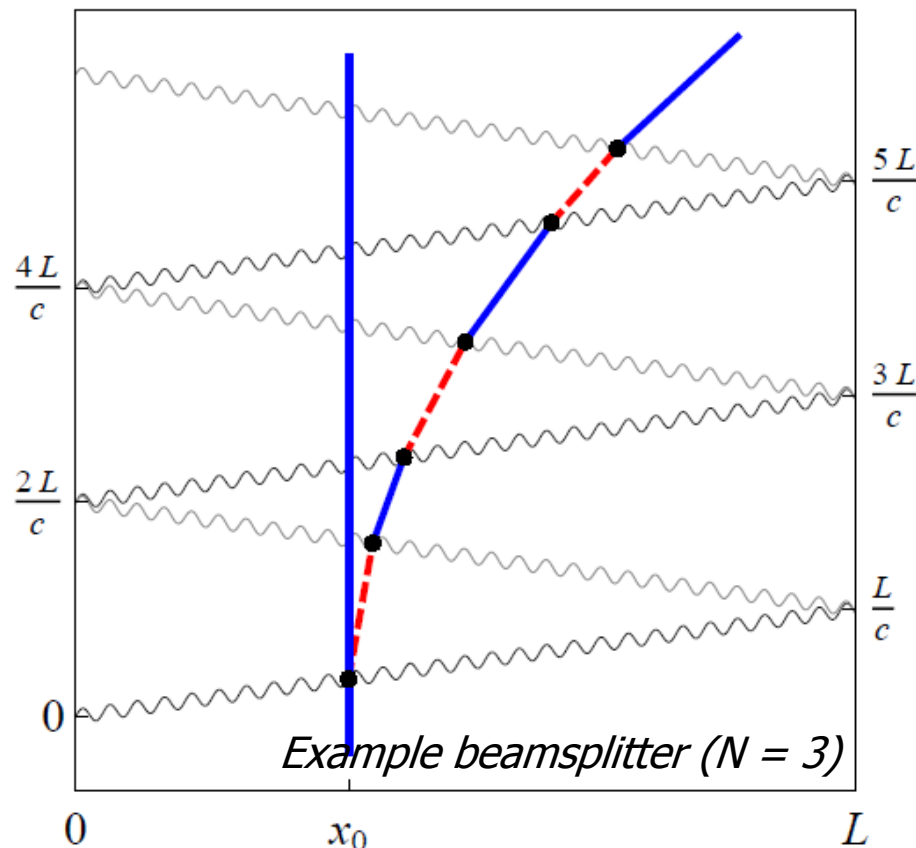


# Atom optics with single photon transitions

$$\Delta\phi = \frac{4N\omega_a h}{c} (x_1 - x_2) \sin^2\left(\frac{\omega T}{2}\right) \sin(\phi_0 + \omega T)$$

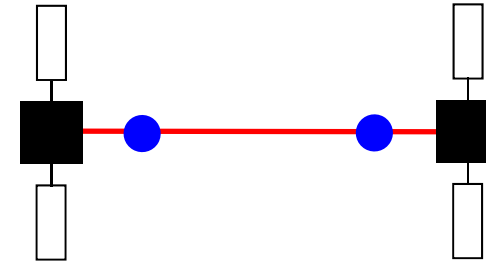
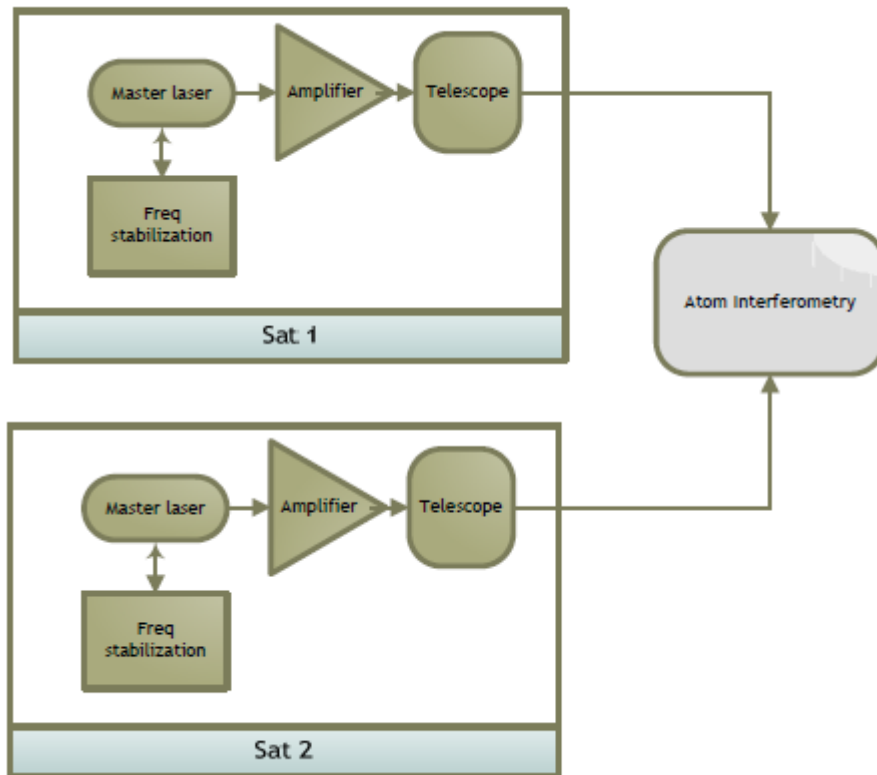
Atomic transition freq.
GW phase

*GW phase shift for interferometer sequence*



- Large N realized by sequential pulses from alternating directions.
- Selectively accelerate one arm with a series of pulses

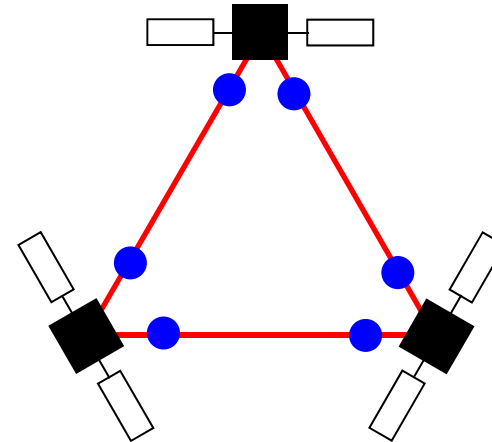
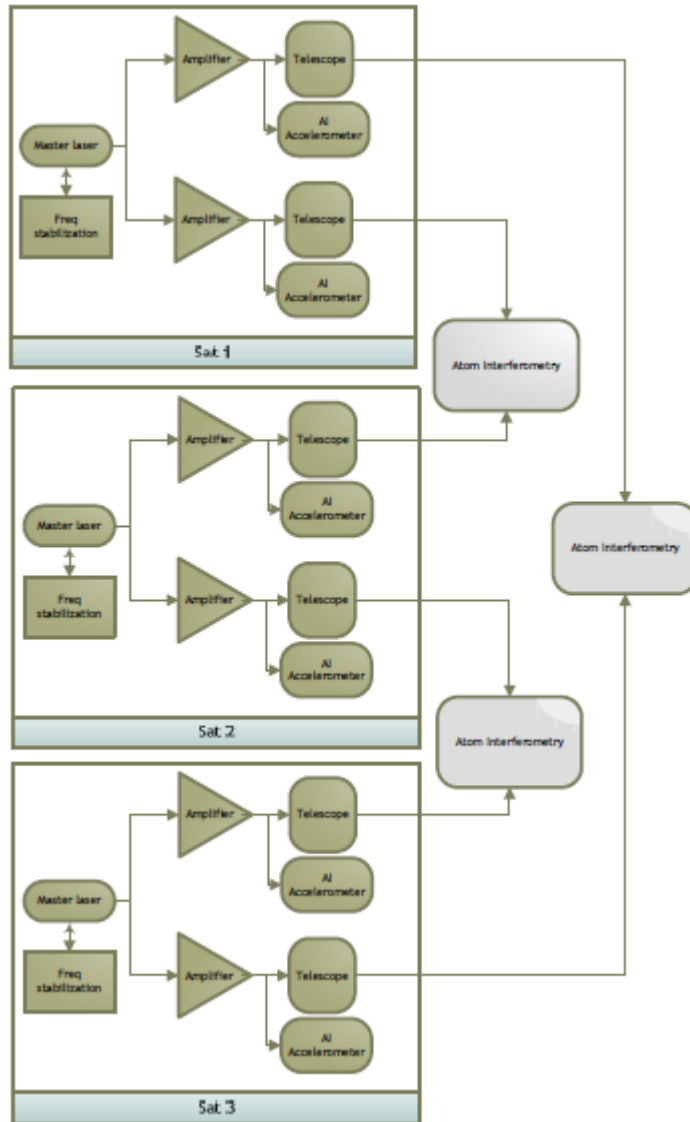
## 2 Satellite Sr Single Photon



- Single baseline (two satellites)
- Single photon atom optics (e.g., Sr) for laser and satellite acceleration noise immunity
- Atoms act as clocks, measuring the light travel time across the baseline



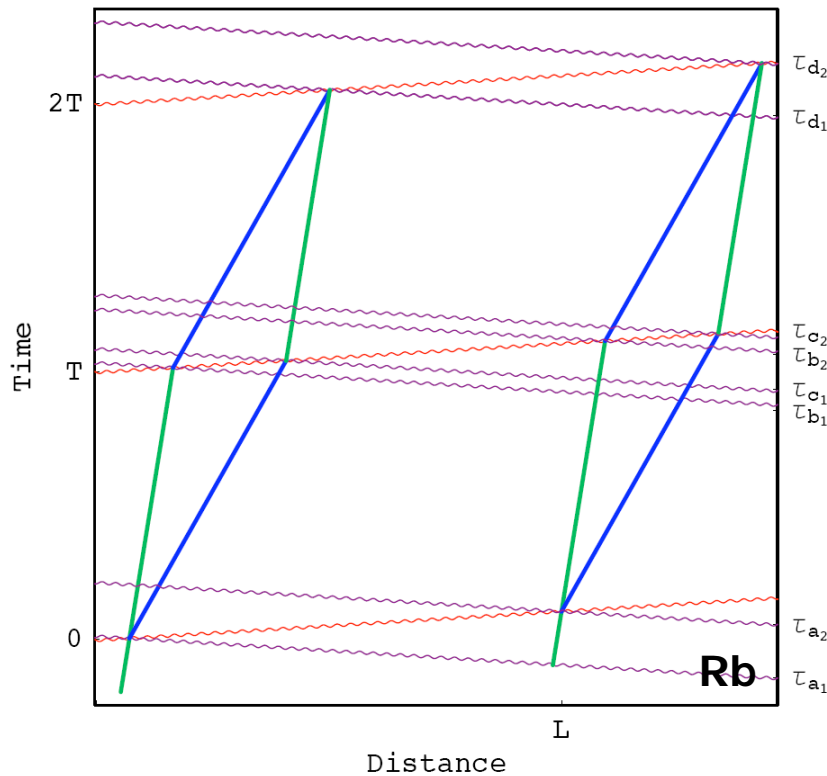
# 3 Satellite Rb



- Conventional, proven atom optics (Rb atom)
- Three satellites allow TDI for compensation of laser frequency noise.
- AI accelerometers to measure satellite vibration noise, which leads to laser frequency noise due to the Doppler effect.

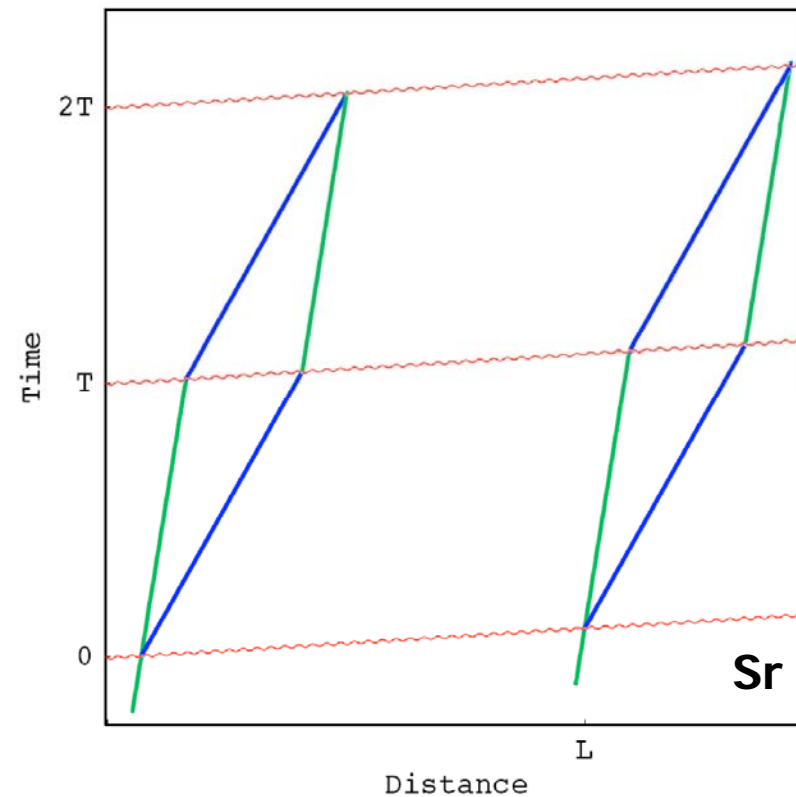
# Two-photon vs. Single photon configurations

## 2-photon transitions



GW signal from relative positions of atom ensembles with respect to optical phase fronts.

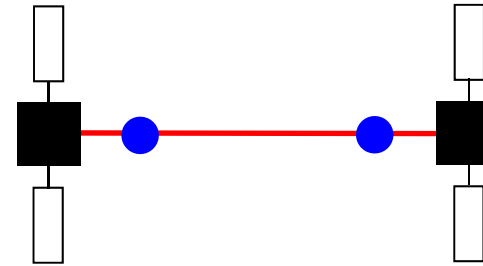
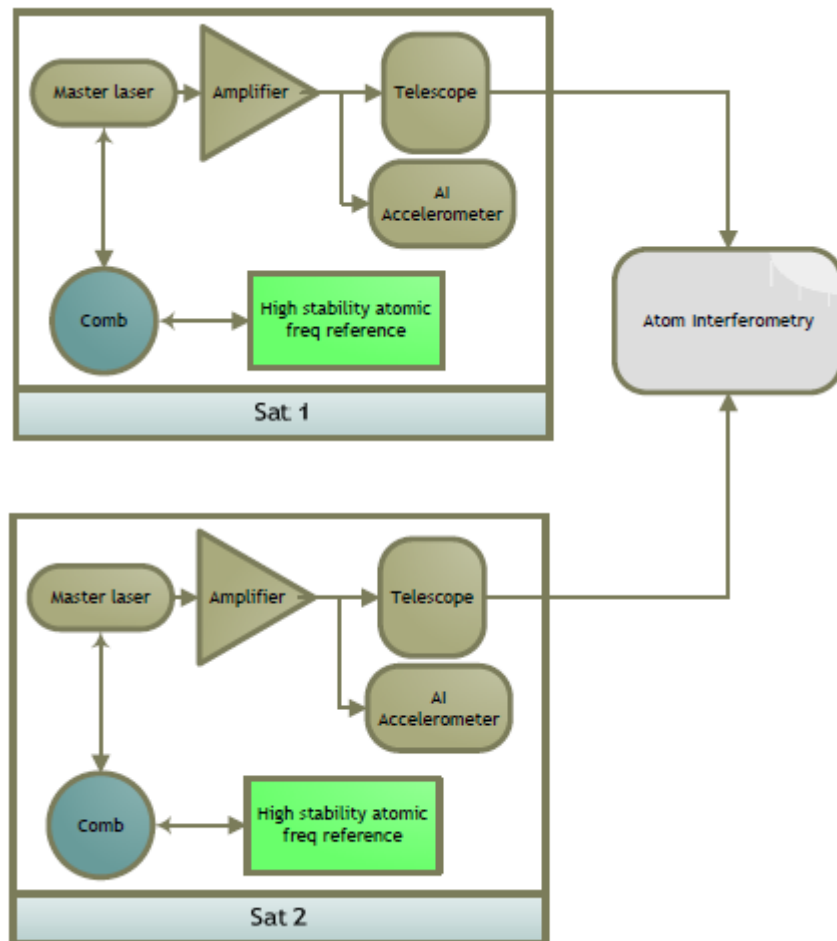
## 1 photon transitions



GW signal from light propagation time between atom ensembles.



## 2 Satellite Rb + Atomic Reference



- Conventional, proven atom optics (Rb atom)
- Single baseline (two satellites)
- Atomic frequency reference (e.g., Sr) for laser noise tracking
- AI accelerometers to measure satellite vibration noise

# Requirements for $h = 1\text{e-}20/\text{Hz}^{1/2}$

Attribute	Req.
Sat. acceleration noise (longitudinal)	$10^{-8} \text{ g/Hz}^{1/2}$
Transverse position jitter	$10 \text{ nm/Hz}^{1/2}$
Spatial wavefront	$\lambda/100$
Atom cloud temperature	$1 \text{ pK}$
Pointing stability	$0.1 \text{ } \mu\text{rad}$
Magnetic fields	$4 \text{ nT/Hz}^{1/2}$
Laser phase noise	$10 \text{ Hz linewidth; } 100 \text{ kHz/Hz}^{1/2}$
Atom optics	$100 \text{ } \hbar k$
Formation flying	$2 \text{ satellites}$
Atom source	$10^8/\text{s} \text{ Sr}$



# Risk

Noise source	Risk
Magnetic Fields	Low
AC Stark	Low
Laser intensity jitter	Low
Atom source velocity jitter	Mid
Laser pointing jitter	Mid
Solar radiation	Low
Blackbody	Low
Atom flux	Low
Laser wavefront noise	High?
Atom detection noise	High?
Gravity gradient	Mid

See analysis in Graham, *et al.*, arXiv:1206.0818, PRL (2013)  
(and references therein).



# Error Model

Analysis to determine requirements on satellite jitter, laser pointing stability, atomic source stability, and orbit gravity gradients.

	Differential phase shift	Size (rad)	Constraint
1	$\frac{1485k_{\text{eff}}^3 \hbar^2}{4Lm^2} T^6 T_{xx} \Omega_{\text{or}} \delta\Omega$	$(180 \text{ s}) \delta\Omega$	$\delta\Omega < 0.57 \mu\text{rad/s}$
2	$\frac{1485k_{\text{eff}}^3 \hbar^2}{2Lm^2} T^6 \Omega_{\text{or}}^3 \varepsilon_{zz} \delta\Omega$	$(350 \text{ s}) \varepsilon_{zz} \delta\Omega$	$\varepsilon_{zz} < 0.50$
3	$\frac{15}{2} k_{\text{eff}} T^4 R \Omega_{\text{or}}^2 (15T (T_{zz} + 3\Omega_{\text{or}}^2) + 8\Phi \Omega_{\text{or}}) \varepsilon_g \delta\Omega$	$(3 \times 10^9 \text{ s}) \varepsilon_g \delta\Omega$	$\varepsilon_g < 5.8 \times 10^{-8}$
4	$30k_{\text{eff}} T^4 \Omega_{\text{or}}^4 \varepsilon_{xx} (\delta x_n - \delta x_f)$	$(22 \text{ m}^{-1}) \varepsilon_{xx} (\delta x_n - \delta x_f)$	$(\delta x_n - \delta x_f) \varepsilon_{xx} < 4.5 \mu\text{m}$
5	$15k_{\text{eff}} T^4 T_{xx} \Omega_{\text{or}} \left( \frac{k_{\text{eff}} \hbar}{Lm} + 9T \Omega_{\text{or}}^2 \right) (\delta z_f - \delta z_n)$	$(0.84 \text{ m}^{-1}) (\delta z_f - \delta z_n)$	$(\delta z_f - \delta z_n) < 120 \mu\text{m}$
6	$30k_{\text{eff}} T^4 \Omega_{\text{or}}^3 \left( \frac{k_{\text{eff}} \hbar}{Lm} + 9T \Omega_{\text{or}}^2 \right) \varepsilon_{zz} (\delta z_f - \delta z_n)$	$(1.7 \text{ m}^{-1}) \varepsilon_{zz} (\delta z_f - \delta z_n)$	$\varepsilon_{zz} < 0.49$
7	$\frac{45}{2} k_{\text{eff}} T^5 (T_{xx}^2 + 6T_{xx} \Omega_{\text{or}}^2 + 4T_{zz} \Omega_{\text{or}}^2 + 5\Omega_{\text{or}}^4) \Delta v_x$	$(270 \text{ s/m}) \Delta v_x$	$\Delta v_x < 370 \text{ nm/s}$
8	$3k_{\text{eff}} T^4 \Omega_{\text{or}} \left( \frac{9k_{\text{eff}}^2 \hbar^2}{L^2 m^2} - 5T_{xx} \right) \Delta v_z$	$(9.6 \times 10^3 \text{ s/m}) \Delta v_z$	$\Delta v_z < 10 \text{ nm/s}$
9	$30k_{\text{eff}} T^4 \varepsilon_{zz} \Omega_{\text{or}}^3 \Delta v_z$	$(1.9 \times 10^4 \text{ s/m}) \varepsilon_{zz} \Delta v_z$	$\varepsilon_{zz} < 0.52$
10	$60 \frac{\hbar k_{\text{eff}}^2}{L^2 m} T^4 T_{yy} \delta v_{yn} \delta y_n$	$(4.3 \times 10^{-2} \text{ s/m}^2) \delta v_{yn} \delta y_n$	$\delta v_{yn} \delta y_n < 23 \text{ cm}^2/\text{s}$
11	$36k_{\text{eff}}^3 \frac{\hbar^2}{Lm^2} \Omega_{\text{or}} T^3 (7 + 8 \cos(\omega T)) \sin^4\left(\frac{\omega T}{2}\right) \overline{\delta\theta}$	$(3.9 \times 10^5) \overline{\delta\theta}$	$\overline{\delta\theta} < 0.26 \text{ nrad}$
12	$4k_{\text{eff}} \delta z_n (7 + 8 \cos(\omega T)) \sin^4\left(\frac{\omega T}{2}\right) \overline{\delta\theta}$	$(1.3 \times 10^{10} \text{ m}^{-1}) \delta z_n \overline{\delta\theta}$	$\overline{\delta\theta} < 0.77 \text{ nrad}$
13	$\frac{27\sqrt{2}}{4} k_{\text{eff}} x_n \frac{L}{R} \Omega_{\text{or}}^2 T^2 \chi(\omega T) \overline{\delta\theta}$	$(1.1 \times 10^4) x_n \overline{\delta\theta}$	$\overline{\delta\theta} < 0.91 \text{ nrad}$

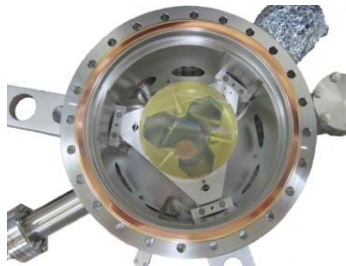
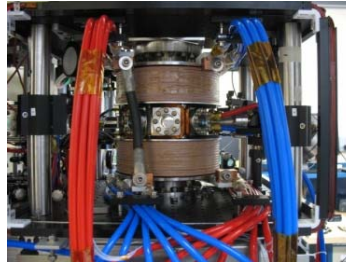
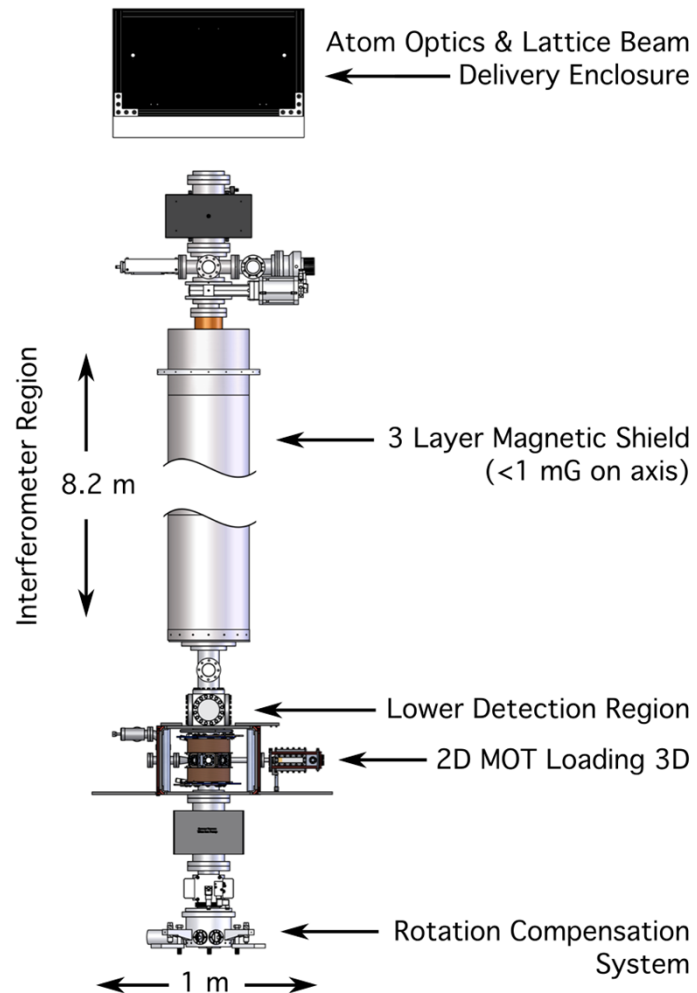


# Atom technology roadmap

- 1) Large wavepacket separation
- 2) Ultracold atom temperatures
- 3) Optical wavefront noise characterization and mitigation
- 4) Phase readout
- 5) Satellite rotation jitter mitigation
- 6) Strontium atom interferometry development



# Demonstration apparatus



Ultracold atom source  
 $>10^6$  at 50 nK

Optical Lattice Launch  
13.1 m/s with 2372 photon recoils to 9 m

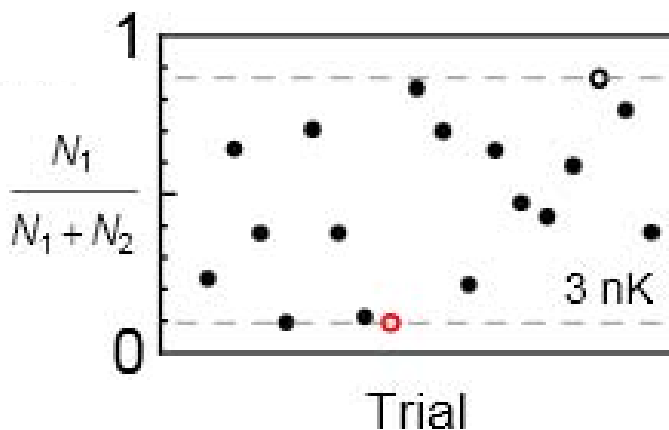
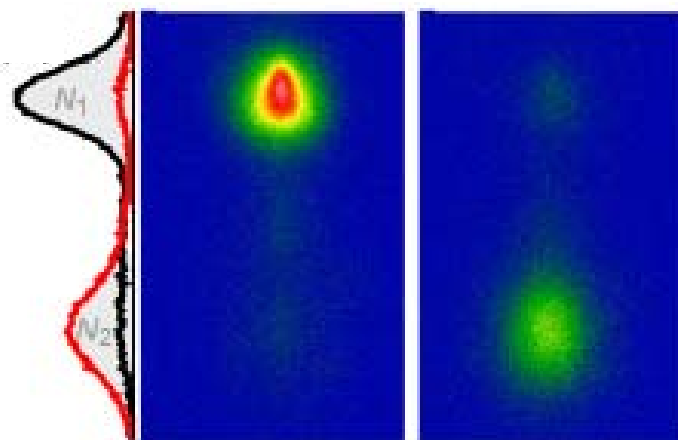
Atom Interferometry  
2 cm  $1/e^2$  radial waist  
500 mW total power  
Dynamic nrad control of laser angle with precision piezo-actuated stage

Detection  
Spatially-resolved fluorescence imaging  
Two CCD cameras on perpendicular lines of sight

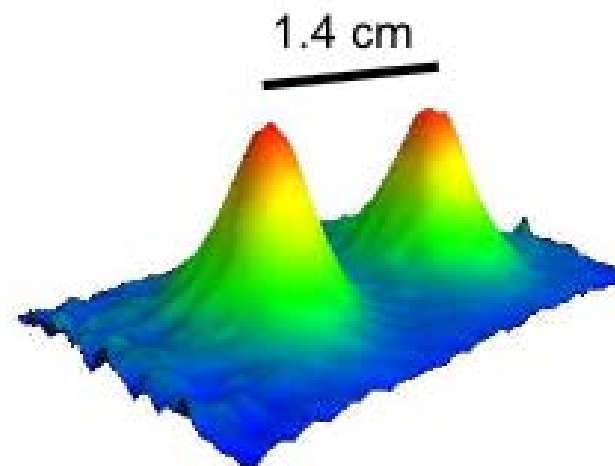
Might achieve  $h \sim 3e-19/\text{Hz}^{1/2}$  resolution on ground near 1 Hz



# Interference at long interrogation time



*Interference*



*Wavepacket separation at apex*

$2T = 2.3$  sec

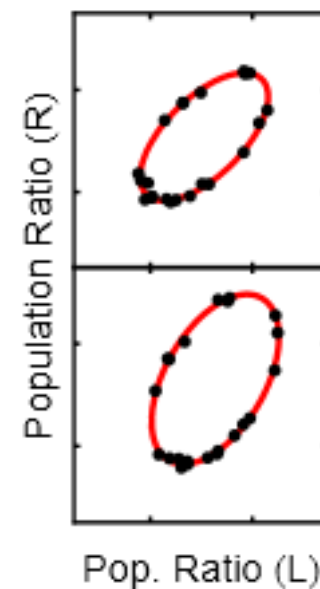
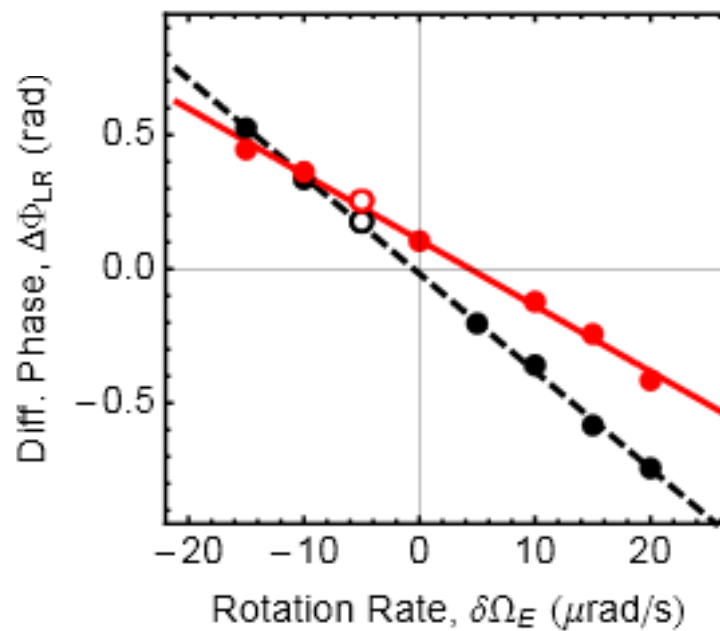
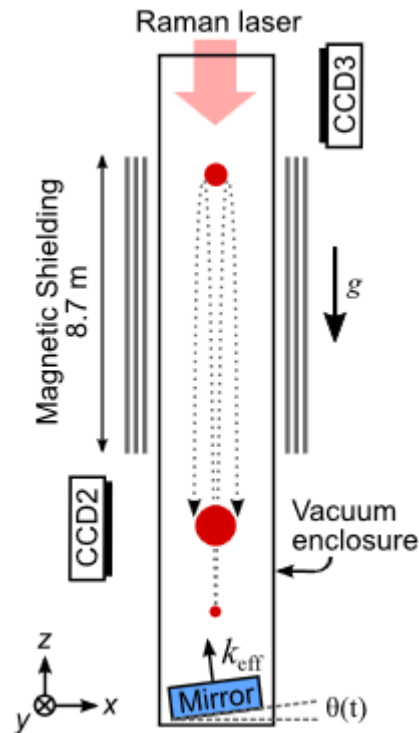
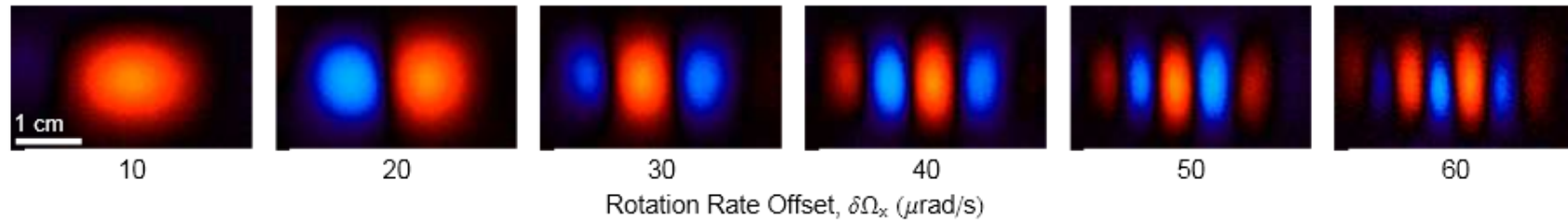
Near full contrast

3 nK

$6.7 \times 10^{-12}$  g/shot

# 2-axis rotation measurement

*Interference patterns for rotating platform:*

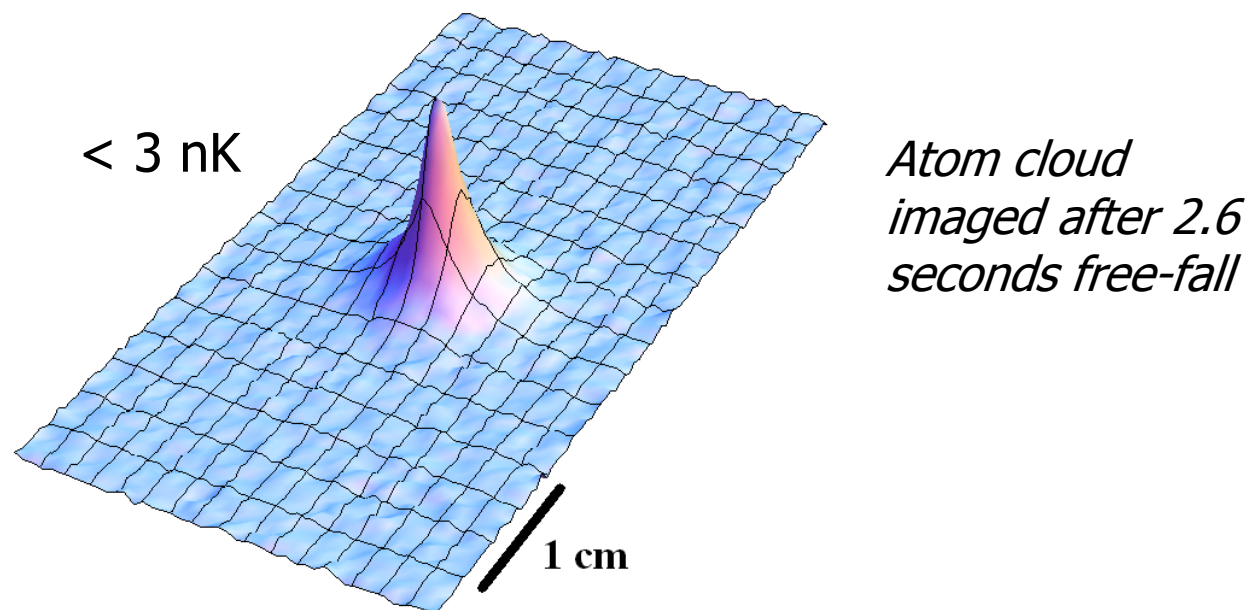


*Measurement of rotation rate near null rotation operating point. Other form factors possible!*

Dickerson, et al., arXiv:1305.1700 (2013)

# Magnetic lens cooling

Cold atom temperatures are required for efficient excitation sequences.

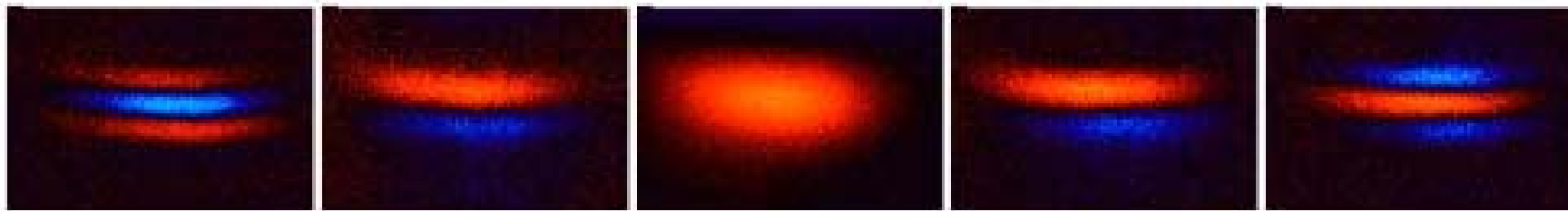


Cooling performance limited by Earth gravity.  
Extrapolated microgravity performance:  $1\text{e-}12$  K.

# Phase shear readout



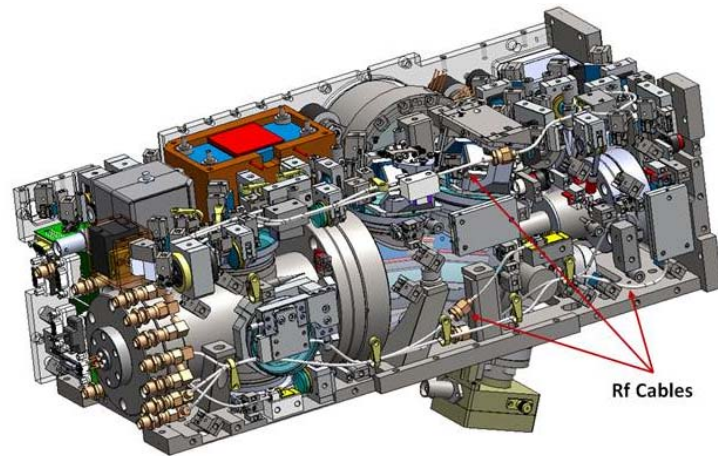
*Shear via laser beam tilt*



*Shear via interferometer timing asymmetry*

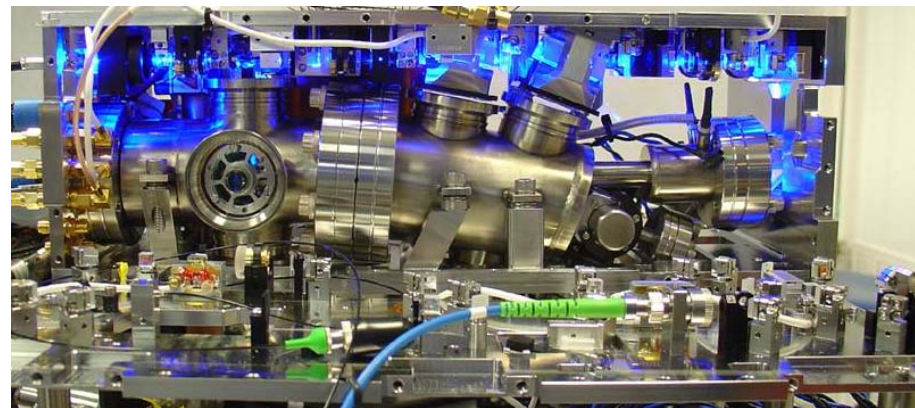
Enables simultaneous read-out of contrast and phase

# DARPA QuASAR SBOC-1/Optical clock

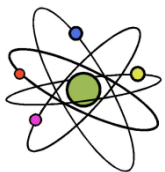


6 liter physics package.

Contains all lasers, Sr source, 2D MOT, Zeeman slower, spectrometer, pumps, and 3 W Sr oven;  $4 \times 10^{10}$  cold a/sec.



As built view with front panel removed in order to view interior.



**AO Sense**

408-735-9500  
AO Sense.com  
Sunnyvale, CA

# Collaborators

## Stanford University

*PI:*

Mark Kasevich

*EP:*

Susannah Dickerson  
Alex Sugarbaker

*LMT:*

Sheng-wei Chiow  
Tim Kovachy

*Theory:*

Peter Graham  
Savas Dimopoulos  
Surjeet Rajendran

*Former members:*

David Johnson (Draper)  
Jan Rudolf (Rasel Group)

**Also**

Philippe Bouyer (CNRS)



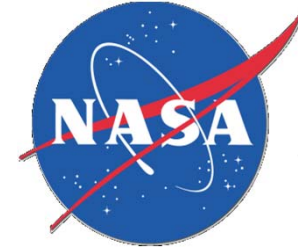
## NASA Goddard Space Flight Center

Babak Saif

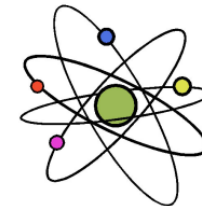
Bernard D. Seery

Lee Feinberg

Ritva Keski-Kuha



**AOSense**



# Kinematic Noise Sensitivity

Laser noise cancels. What are the remaining sources of noise?

Relative velocity  $\Delta v$  between the interferometers changes the time spent in the excited state, leading to a differential phase shift.

Leading order kinematic noise sources:

	Phase Shift	Control Required
1.	$N \frac{\Delta v}{c} \frac{\omega_a}{c} T^2 \delta a$	$\delta a \lesssim 10^{-8} g / \sqrt{\text{Hz}}$
2.	$N \frac{\Delta v}{c} \omega_a \delta T$	$\delta T \lesssim 10^{-12} \text{ s}$
3.	$N \Delta v \delta k \Delta \tau$	$c \delta k / 2\pi \lesssim 10^2 \text{ kHz} / \sqrt{\text{Hz}}$
4.	$N^2 \frac{\Delta v}{c} \frac{\hbar}{m} \frac{\omega_a}{c} T \delta k$	$c \delta k / 2\pi \lesssim \text{GHz} / \sqrt{\text{Hz}}$

1. Platform acceleration noise  $\delta a$
2. Pulse timing jitter  $\delta T$
3. Finite duration  $\Delta \tau$  of laser pulses
4. Laser frequency jitter  $\delta k$

Most severe constraint on laser frequency noise is that laser needs to be resonant with the transition (linewidth < transition Rabi freq.)





# System architectures under study

Currently evaluating several architectures:

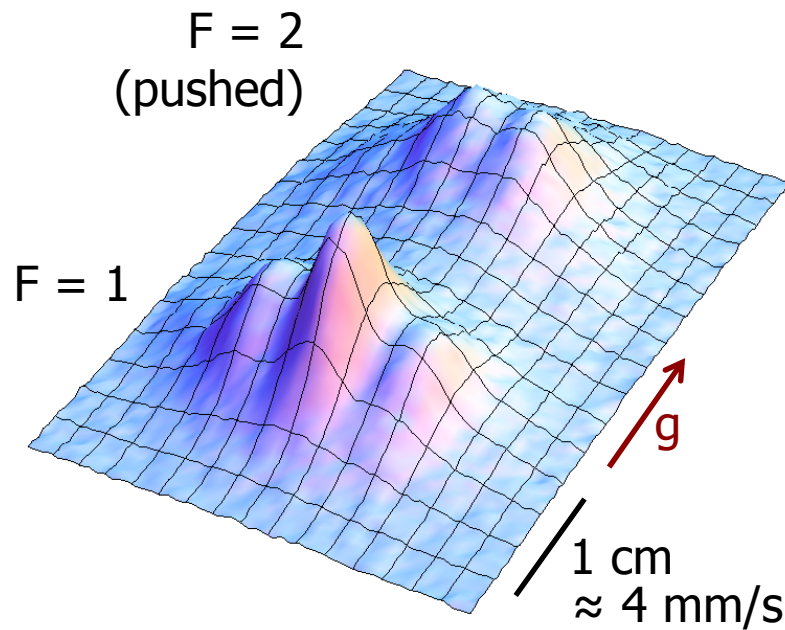
- 1) Three satellite, Rb
- 2) Two satellite, Rb + atomic phase reference
- 3) Two satellite, Sr, single photon transition

Top level trade space is driven by strategy employed to mitigate laser frequency noise, which, if uncontrolled, will mask GW signatures.



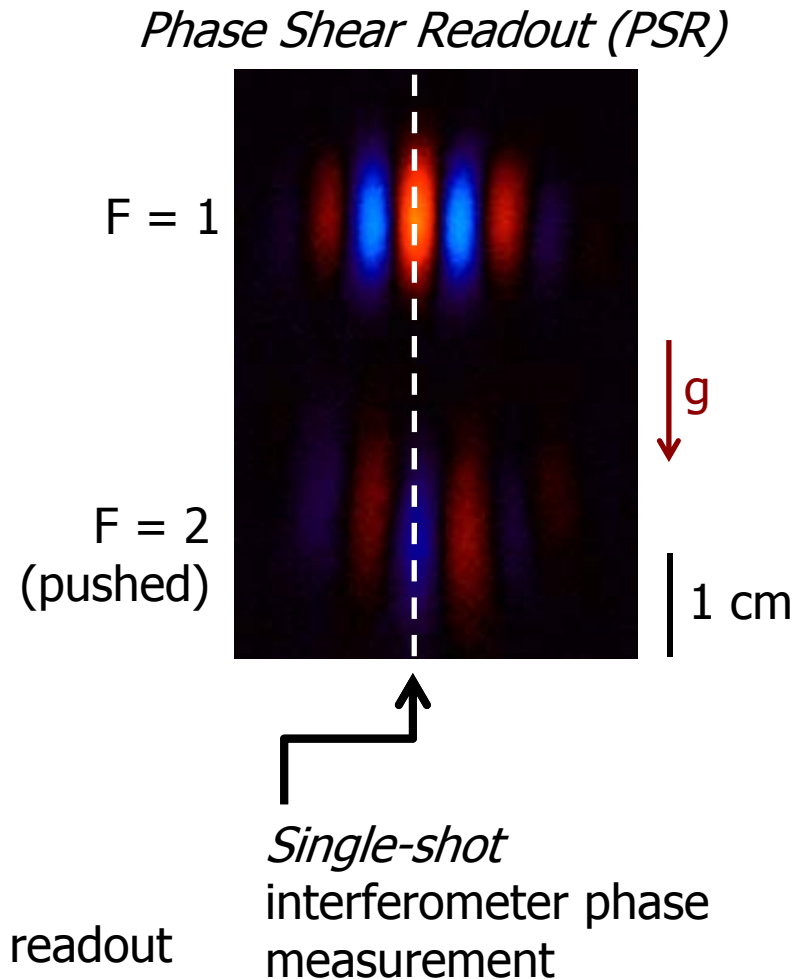


# Phase shear readout

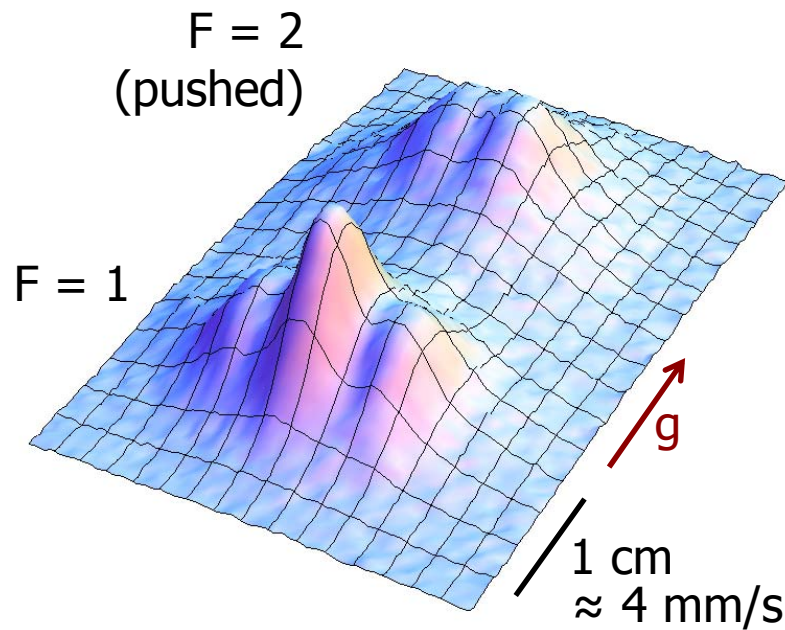


Mitigates noise sources:

- ✓ Satellite pointing jitter and residual rotation readout
- ✓ Laser wavefront aberration in situ characterization

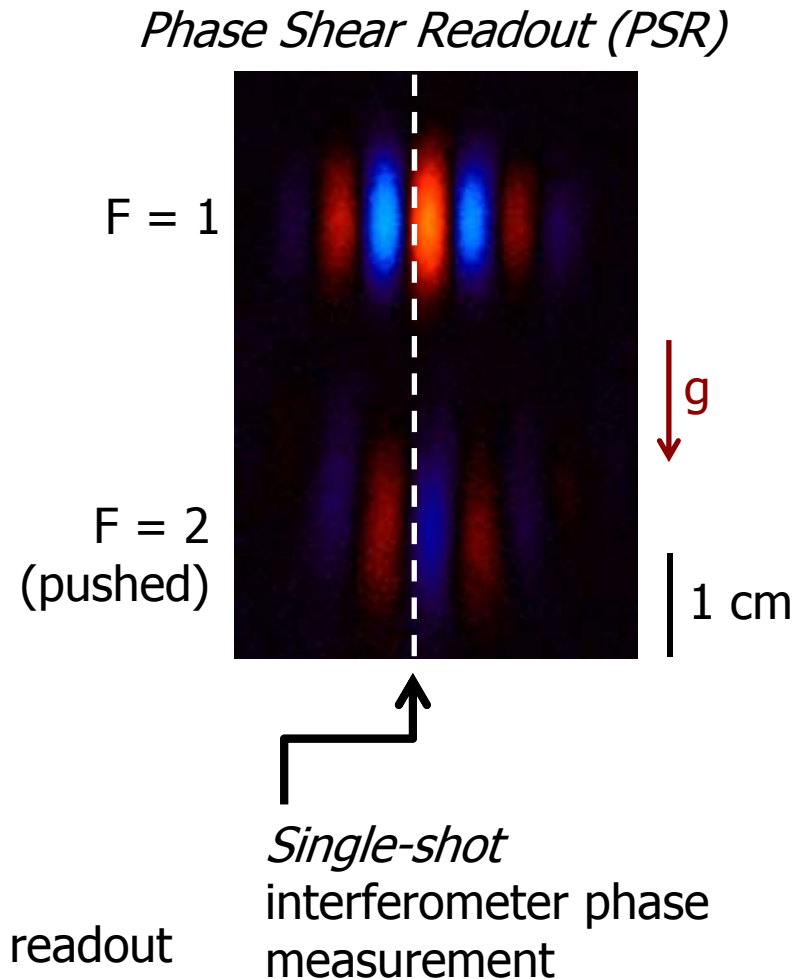


# Phase Shear Readout

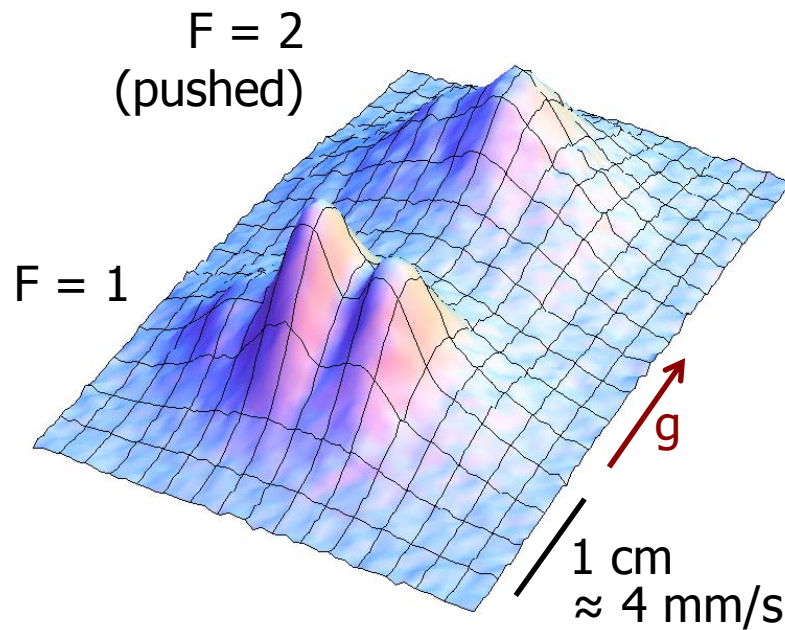


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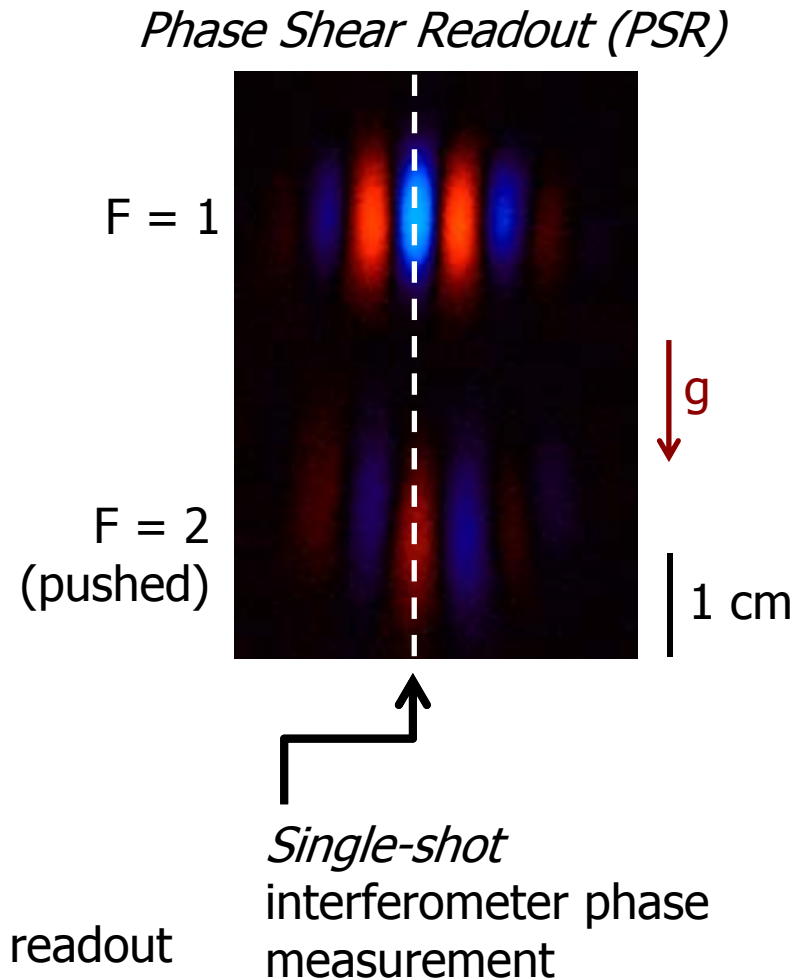


# Phase Shear Readout

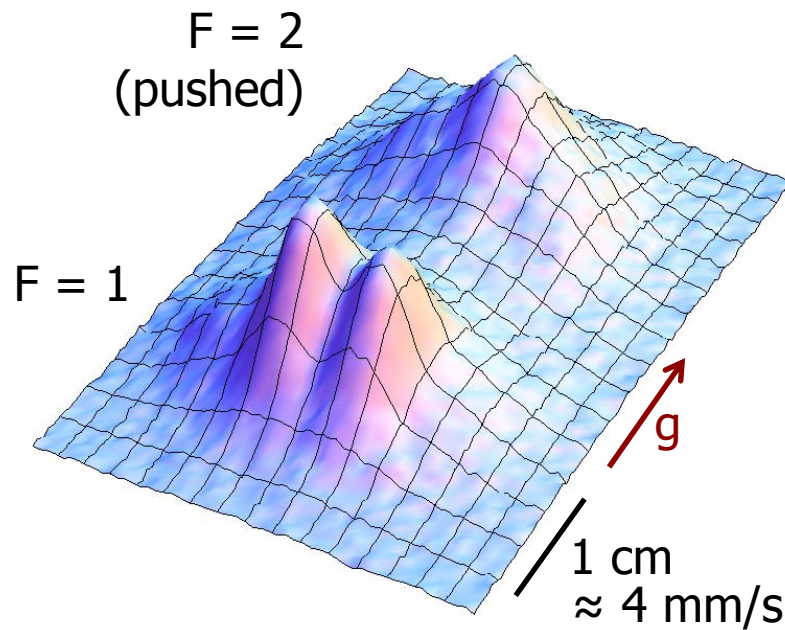


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Mitigates noise sources:

- ✓ Satellite pointing jitter and residual rotation readout
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