DCH performance vs endcap shape and position

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Goals

- Evaluate the DCH performance as a function of the shape and position of the endcaps
 - p resolution
 - K/π separation using dE/dx
 - B → D*K reco. efficiency, ΔE
- All studies shown in these slides have been produced using FastSim V0.3.2

Five DCH configurations

common features:

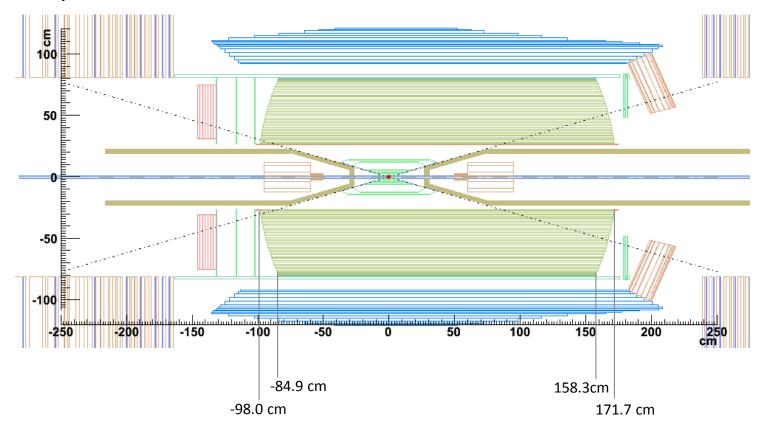
- 10 superlayers, 4 layers each: A A S₊ S₋ S₊ S₋ S₊ S₋ A A
 - |stereo angle| ≈ 0.06 rad
 - inner wall radius: 26.5 cm
 - outer wall radius: 80.3 cm
 - sense wires r_{min}: 28.6 cm
 - sense wires r_{max} : 78.0 cm
- hit spatial resolution: babar-like
- hit efficiency vs polar angle: babar-like (babar-like: tuned on babar data)
- $\sigma(dE/dx)$ modelization: babar-like
 - $-\sigma\left(\frac{dE}{dx}\right) = \alpha \left|\frac{dE}{dx}\right|^{\beta} dx^{\gamma} \quad \alpha, \beta, \gamma \text{ tuned on babar data}$

distinguishing features

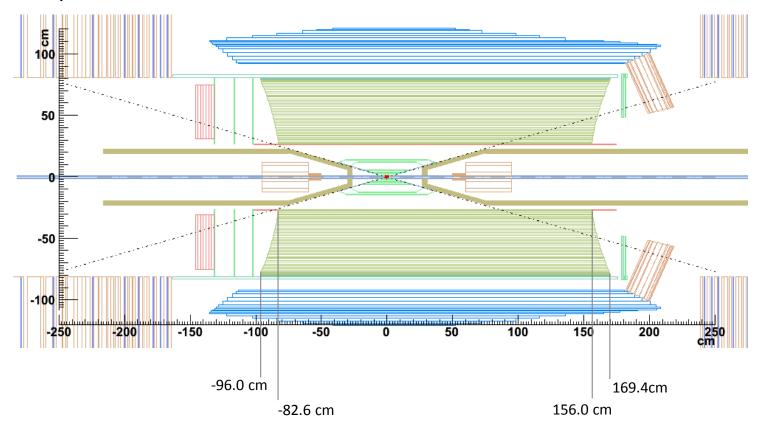
- shape and position of endcaps
 - concave/convex
 - varying position along z

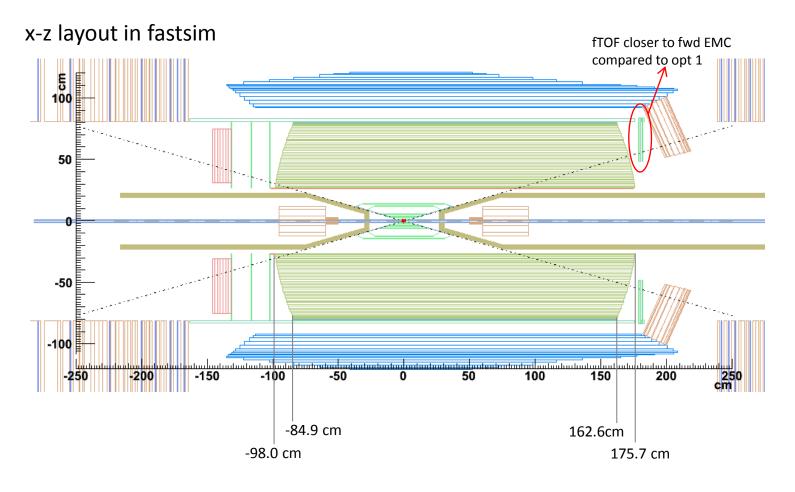
FastSim configurations based on drawings provided by S. Lauciani (see backup slides)

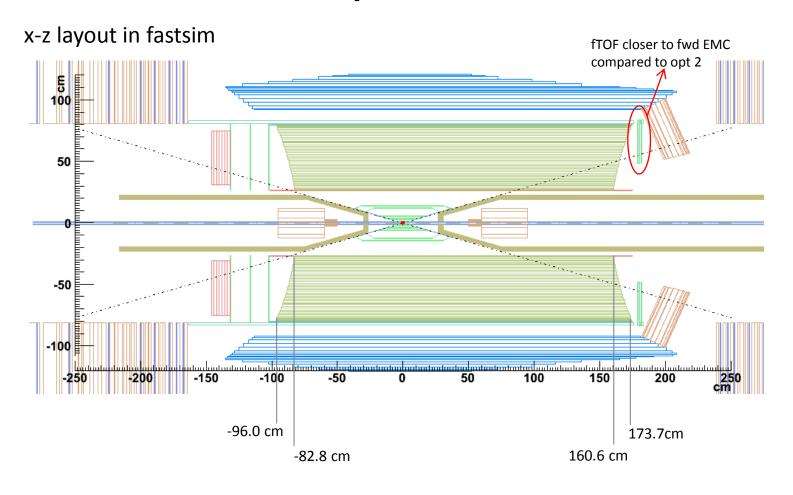
x-z layout in fastsim



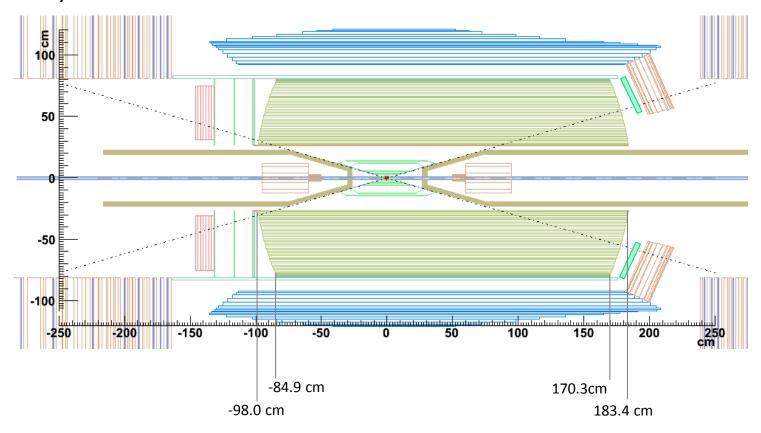
x-z layout in fastsim



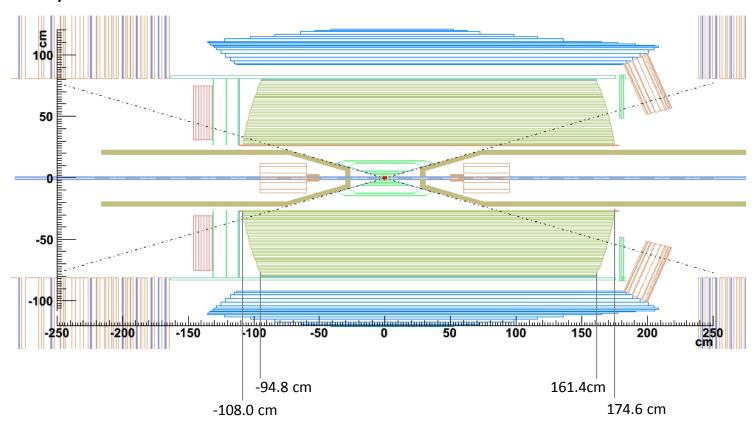




x-z layout in fastsim



x-z layout in fastsim



compared to Option 3:

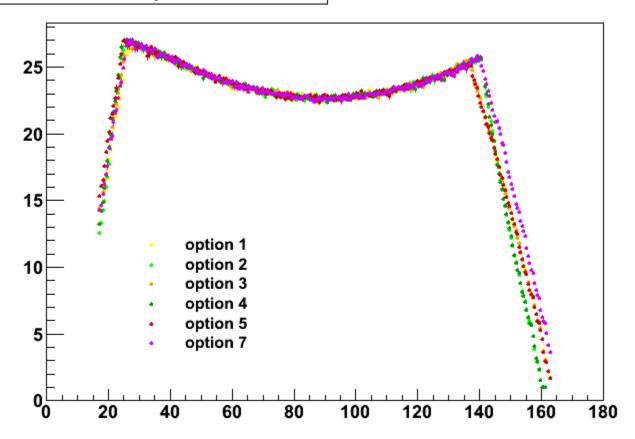
1.1 cm shorter in forward direction, 10 cm longer in backward direction

Part I validation with p = 4 GeV/c single particles

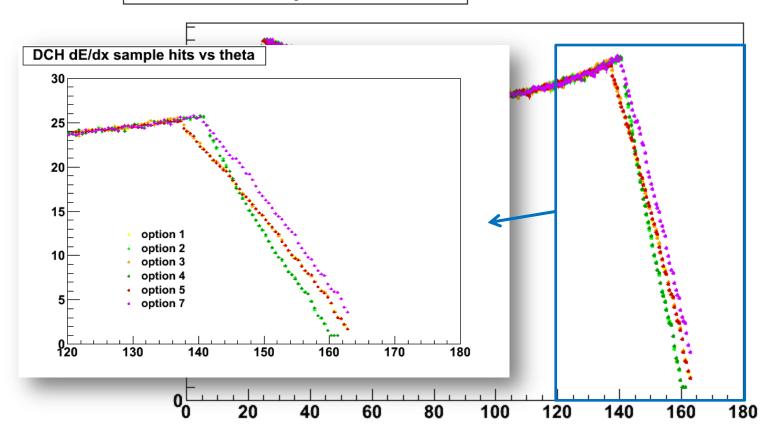
single particles generated with:

- p = 4 GeV/c
- dP/ dcos θ = const [θ = polar angle]
- $\cos\theta$ in [0.3, π -0.3] rad [SVT angular acceptance]
- 50k events for each configuration

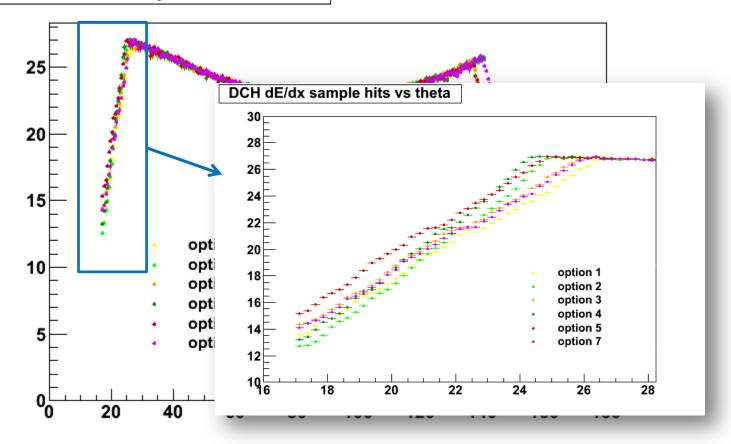
DCH dE/dx sample hits vs theta

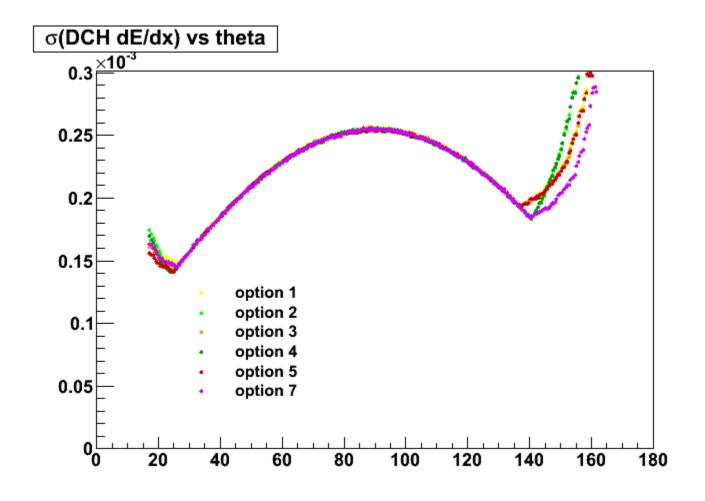


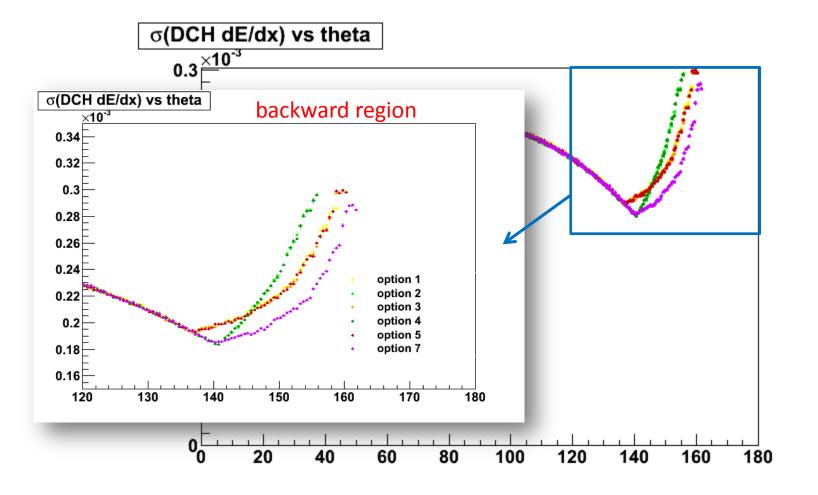
DCH dE/dx sample hits vs theta

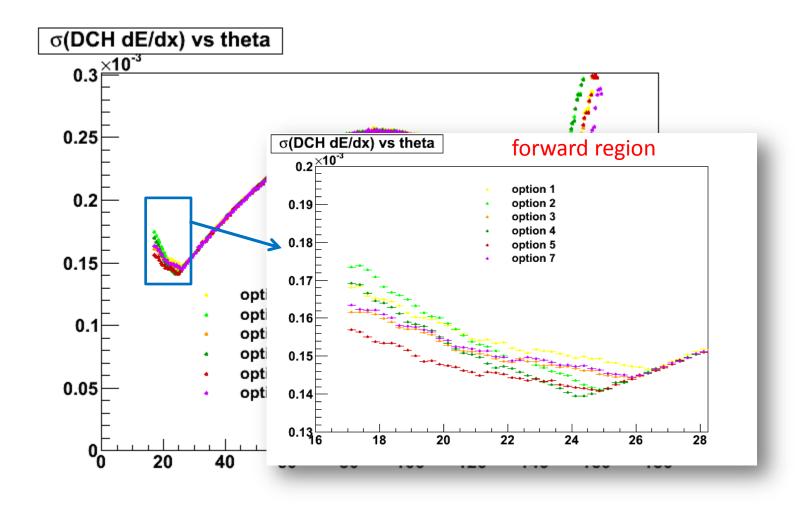


DCH dE/dx sample hits vs theta

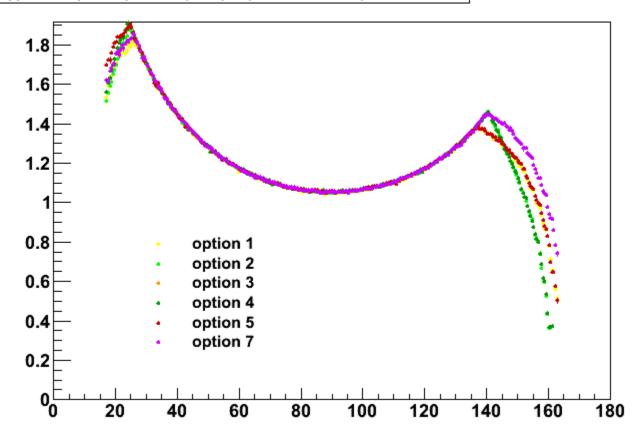




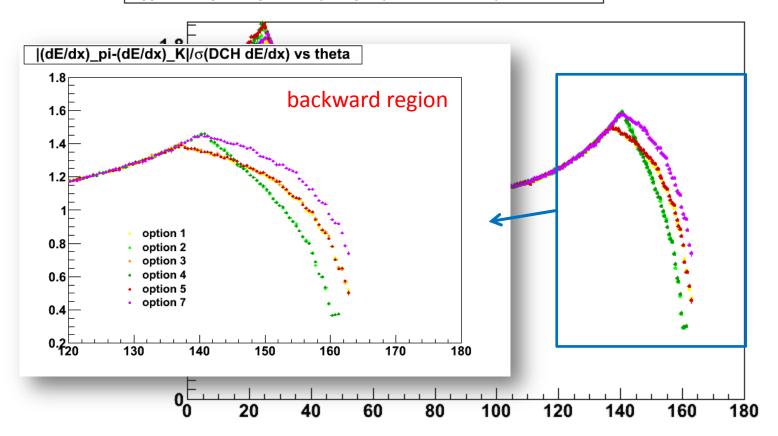


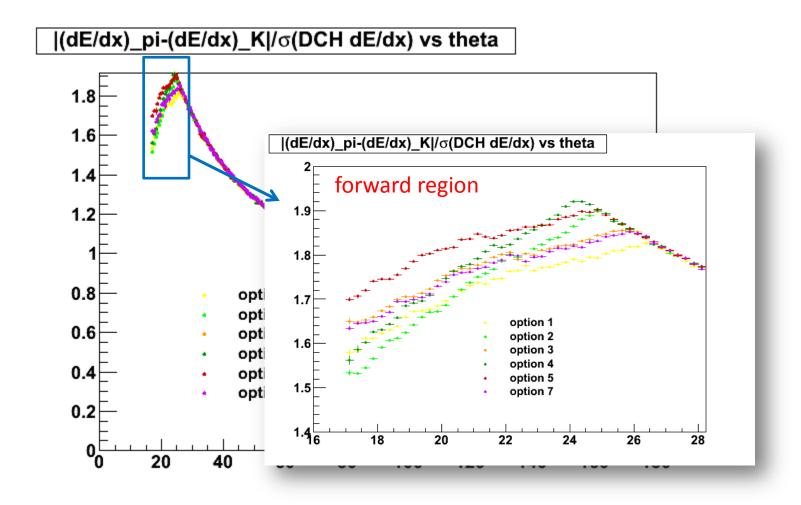


|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) vs theta



|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) vs theta





Part II

single particles (π^+) with flat p and $\cos\theta$ distributions

single particles generated with:

- p in [0.1, 4.0] GeV/c
- dP/ dcos θ = const [θ = polar angle]
- θ in [0.30,0.46] rad [DCH forward region] or θ in [2.40, π -0.30] rad [DCH backward region]
- 200k events for each configuration

Part II

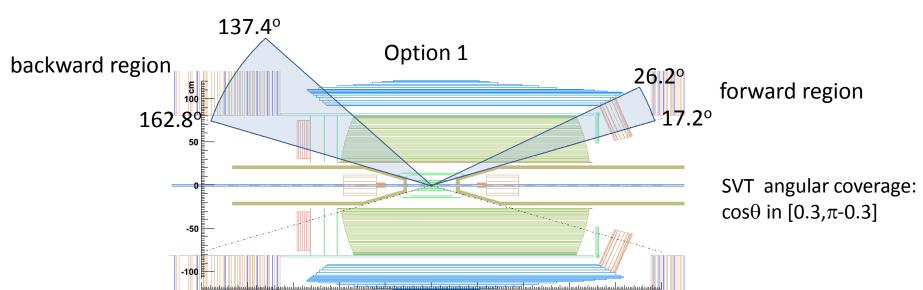
single particles (π^+) with flat p and $\cos\theta$ distributions

single particles generated with:

p in [0.1, 4.0] GeV/c

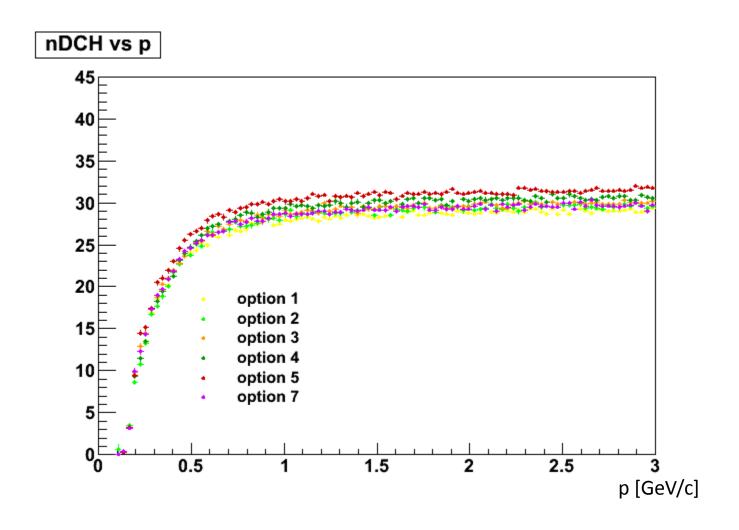
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- dP/ dcos θ = const [θ = polar angle]
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- 200k events for each configuration

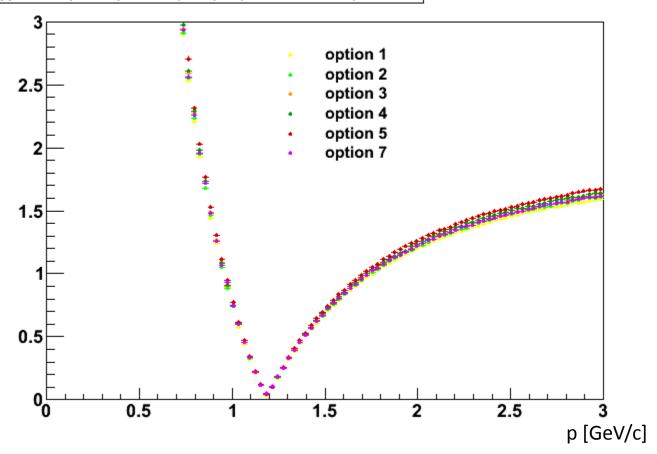


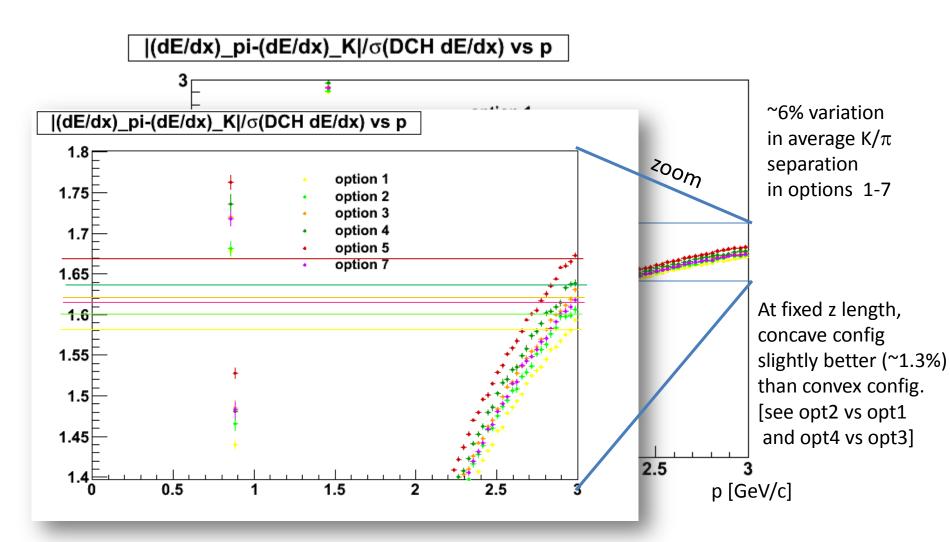
M. Rama

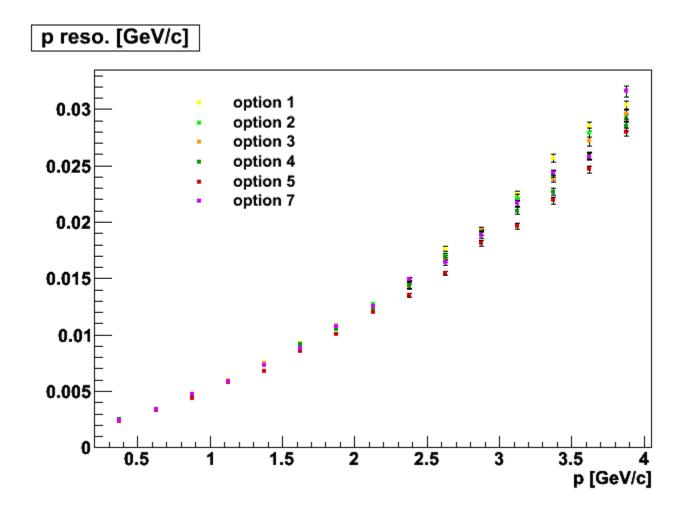
21

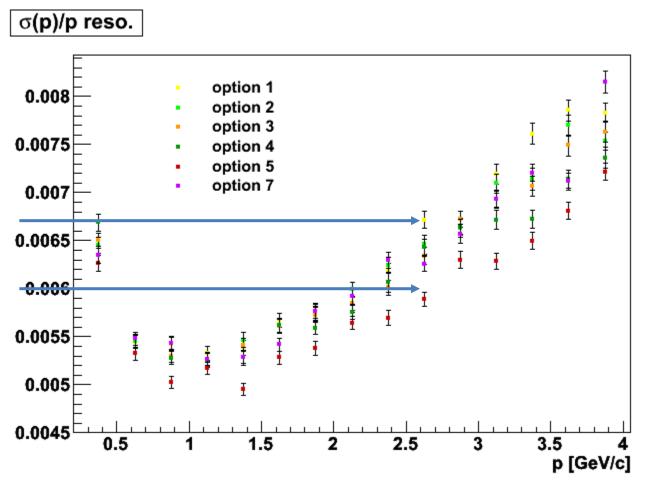


|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) vs p





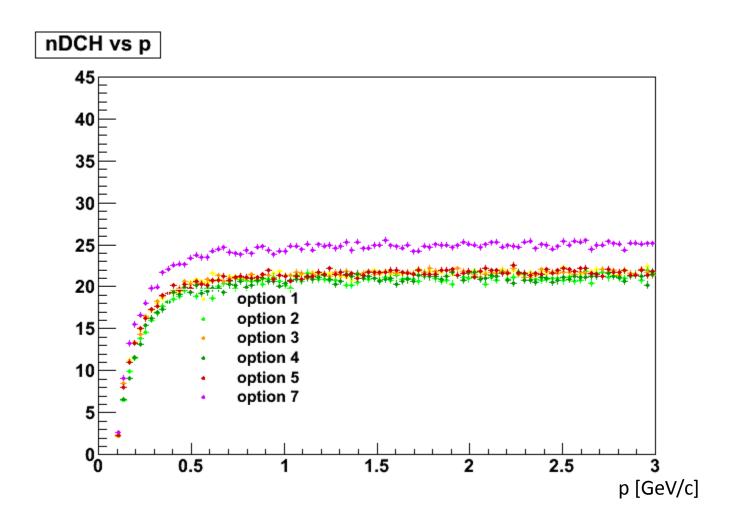




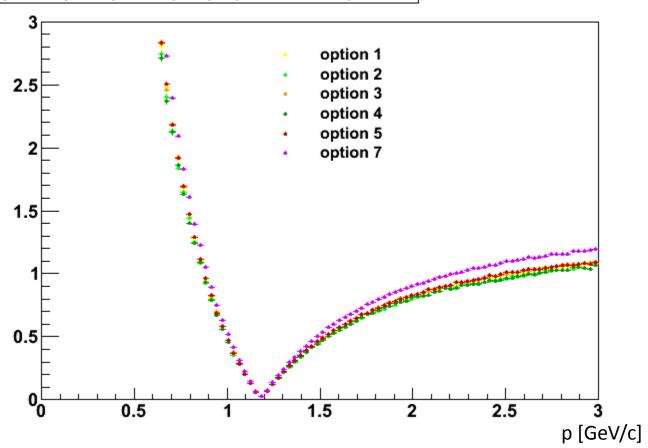
≈10% σ(p)/p relative variation over different configs.

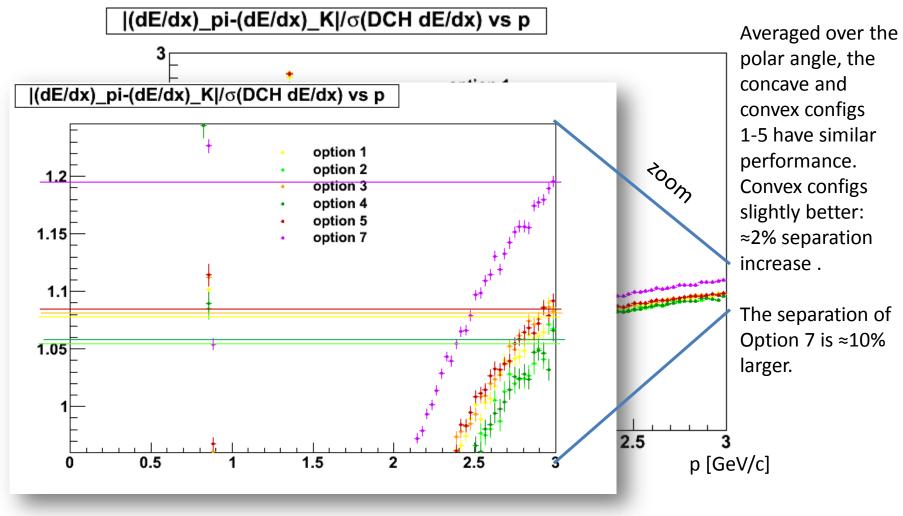
At fixed z length, concave and convex configs shows similar performance within the stat uncertainty.

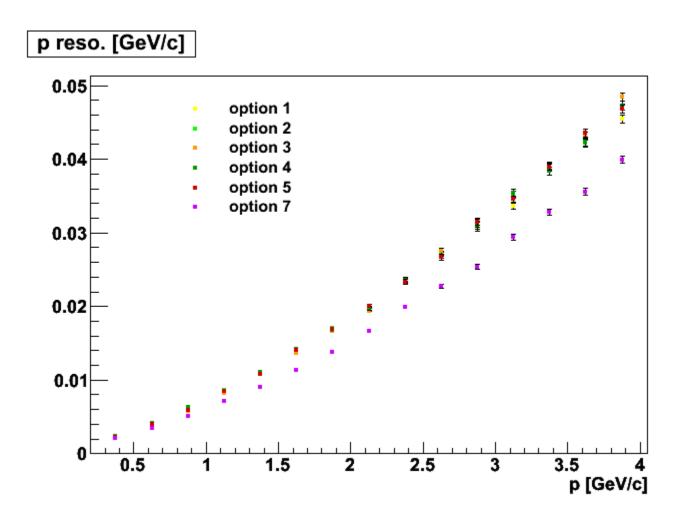
26

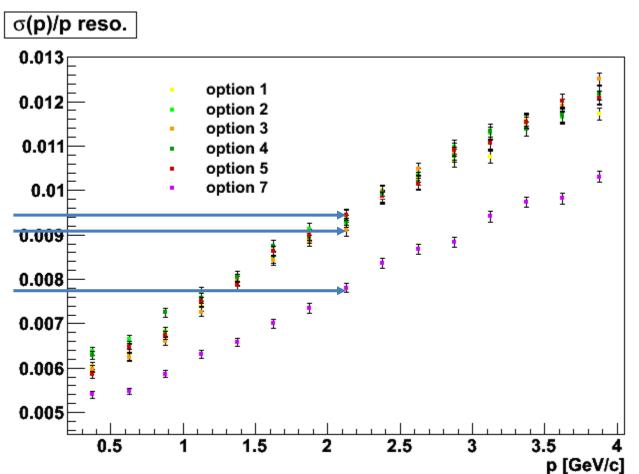


|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) vs p









Integrated over the whole bwd region, p resolutions of Options 1-5 are similar within a ≈4% relative variation.

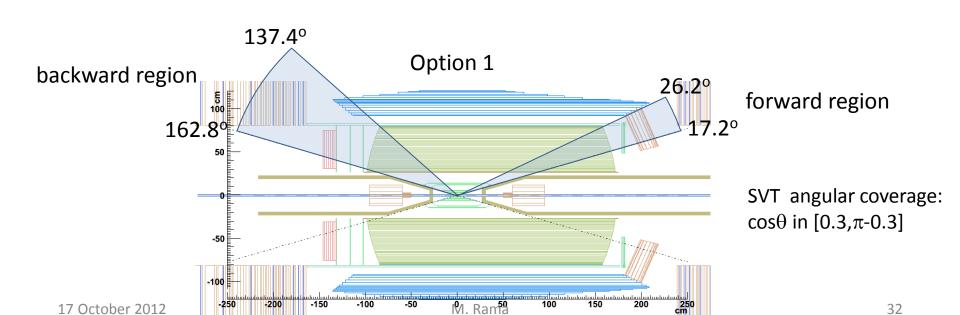
p resolution of Option 7 is ≈15-20% better.

Part III

$$B^0 o D^{*-}K^+, D^{*-} o \overline{D}{}^0K^-, \overline{D}{}^0 o K^+\pi^-$$

5x10⁴ B→D*K signal events for each configuration

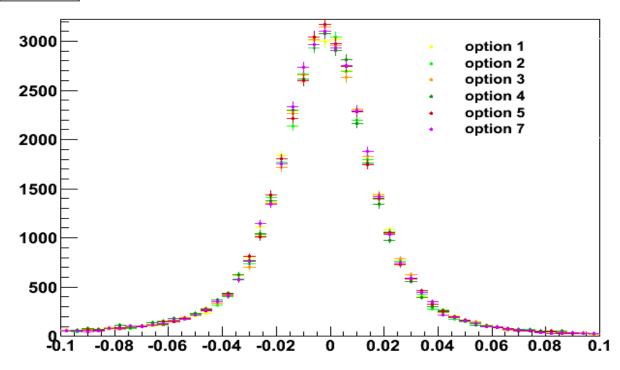
truth matching required



ΔE reconstruction

$$B^0 \to D^{*-}K^+, D^{*-} \to \overline{D}{}^0K^-, \overline{D}{}^0 \to K^+\pi^-$$

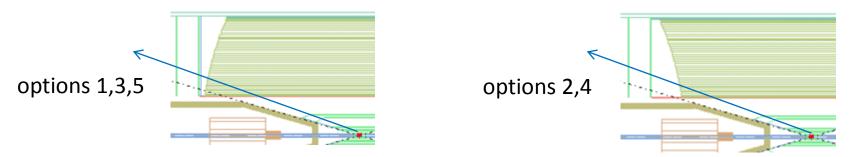




reconstruction efficiency of $B \rightarrow D^*K$

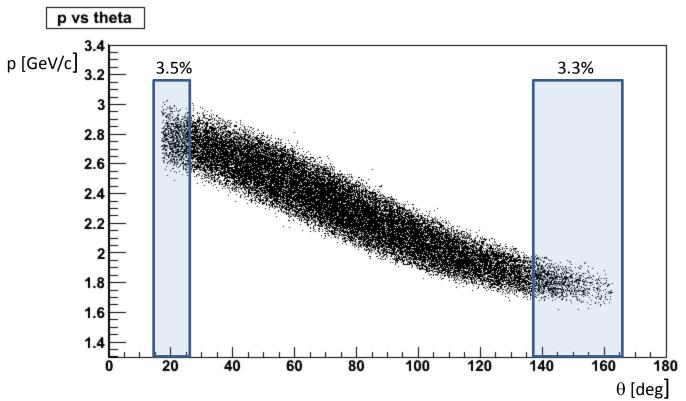
DCH configuration	B \rightarrow D*K reco efficiency [%] (Δ E <50 MeV ~2.5 σ)
option 1	65.4 ± 0.2
option 2	64.4 ± 0.2
option 3	65.1 ± 0.2
option 4	64.6 ± 0.2
option 5	65.3 ± 0.2
option 7	65.6 ± 0.2

The (tiny) differences are driven by the backward region: eff[opt1,3,5,7] > eff[opt 2,4]



Options 1, 2, 3 and 7 have the same efficiency within $\approx 0.2\%$

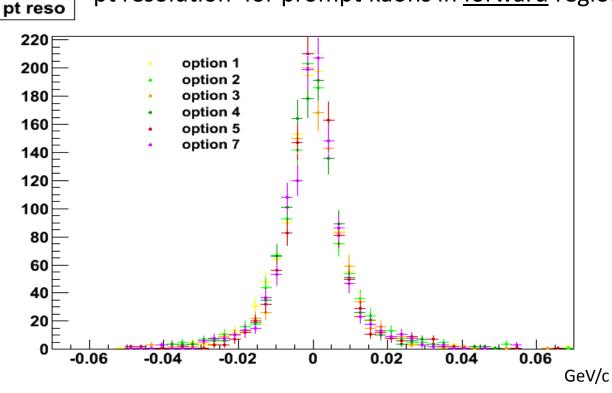
p vs θ distribution of prompt kaons (B \rightarrow D*K)



selected samples

forward region: 1213 (3.5%) barrel region: 32242 (93.2%) backward region: 1157 (3.3%)

pt resolution for prompt kaons in forward region



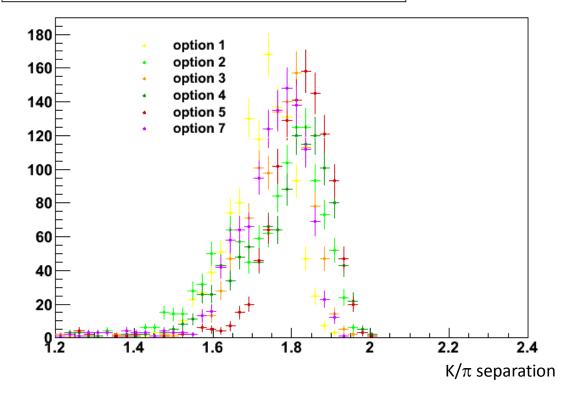
Option 5 is visibly better.
Differences in the

other options are not evident.

forward region

$$K/\pi \ separation \equiv \frac{\left| (dE/dx)_{\pi} - (dE/dx)_{K} \right|}{\sigma(dE/dx)}$$
 $\sigma(dE/dx)_{h} = \frac{\text{expected dE/dx}}{\text{in the } \textbf{\textit{h}} \text{ hypothesis}}$ $\sigma(dE/dx) = \frac{\text{dE/dx measurement}}{\text{error}}$

|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) forward



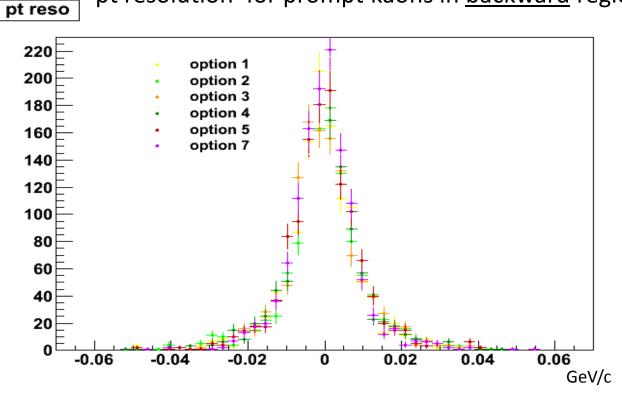
config	$\mu \pm RMS/\sqrt{N}$
1	1.723 ± 0.002
2	1.751 ± 0.003
3	1.767 ± 0.003
4	1.787 ± 0.003
5	1.822 ± 0.003
7	1.757 ± 0.003

The pattern sep1<sep2<sep3<sep4<sep5 is visible. Differences are tiny.

At fixed z length, concave config slightly better (≈1%) than convex config. [see opt2 vs opt1 and opt4 vs opt3]

backward region

pt resolution for prompt kaons in backward region



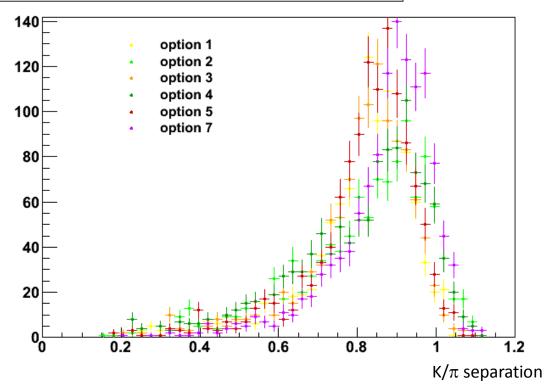
backward region

$$K/\pi \ separation \equiv \frac{\left| (dE/dx)_{\pi} - (dE/dx)_{K} \right|}{\sigma(dE/dx)}$$

$$\frac{(dE/dx)_{h}}{\sigma(dE/dx)} = \frac{e}{i\pi}$$

 $(dE/dx)_h$ = expected dE/dx in the **h** hypothesis $\sigma(dE/dx)$ = dE/dx measurement error

|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) backward



config	$\mu \pm RMS/\sqrt{N}$
1	0.801 ± 0.004
2	0.812 ± 0.005
3	0.802 ± 0.004
4	0.808 ± 0.005
5	0.816 ± 0.004
7	0.870 ± 0.004

Average K/ π separations of Opt 1-5 consistent within $\approx 0.5\%$.

 K/π separation of Opt 7 is \approx 7-8% larger.

Conclusions (Options 1-5)

- 5 options for the DCH endcaps have been compared. They differ in shape and z position.
- Differences in performance are generally small, as expected.

Forward region

- − K/π separation: At fixed z position, the concave shape shows slightly better performance (≈1% relative gain).
- <u>p resolution</u>: ≈10% σ (p)/p variation over different configs. Consistent with previous estimates of ~1% per cm of DCH length[1]. At fixed z length, concave and convex configs shows similar performance within the stat uncertainty (2-3%).
- $\underline{B \rightarrow D^*K}$: Possible differences in absolute (relative) reco efficiency due to track reconstruction and ΔE resolution are below 0.2% (0.3%) among different configs.

Backward region

- K/π separation: Using single particles generated with flat cosθ and p distributions, and averaging over the bwd region, the convex configuration shows slightly better performance (≈2%). Using prompt kaons from B->D*K, concave and convex configurations are consistent within 0.5%.
- <u>p resolution</u>: Integrated over the whole bwd region, p resolutions are equal within a ≈4% relative uncertainty.
- B->D*K: convex configuration shows slightly larger B→D*K reco efficiency: 0.8% (1.2%) absolute (relative) efficiency gain.

[1] http://agenda.infn.it/getFile.py/access?contribId=74&sessionId=11&resId=0&materialId=slides&confId=2902

[2] http://agenda.infn.it/getFile.py/access?contribId=133&sessionId=19&resId=0&materialId=slides&confId=1165

convex vs concave shape summary (Options 1-5)

Summary of results concerning the comparison between the concave and convex shapes with a given length (i.e., option1 vs option2 or option3 vs option4)

	forward region	backward region
K/π separation	concave +1% w.r.t. convex	With single particles (flat cosθ): convex +2% w.r.t. concave With prompt K from B→D*K: same separation within 0.5%. (*)
σ(p)/p	same resolution within 2-3% relative uncertainty (stat limited)	same resolution within ≈4% relative uncertainty (stat limited)
B->D*K reco. eff.	same reco. eff. within 0.3% relative uncertainty (stat limited)	convex +1.2% relative increase w.r.t. concave

^(*) The K/ π separation depends on both the polar angle (see for example slide 17) and p. Therefore, results for particle samples with different polar angle and p distributions can vary.

Conclusion (Option 7 vs 1-5)

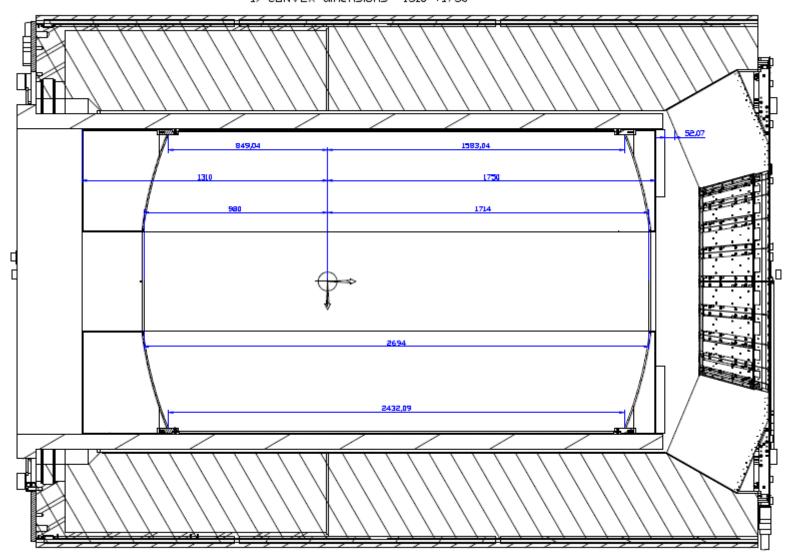
Backward region

- K/π separation in Option 7 is about 10% larger than that in Options 1-5.
- p resolution in Option 7 is about 15-20% better than in Options 1-5.
- B→D*K reco efficiency in Option 7 is consistent with that in Options 1,3,5 within 0.2%.

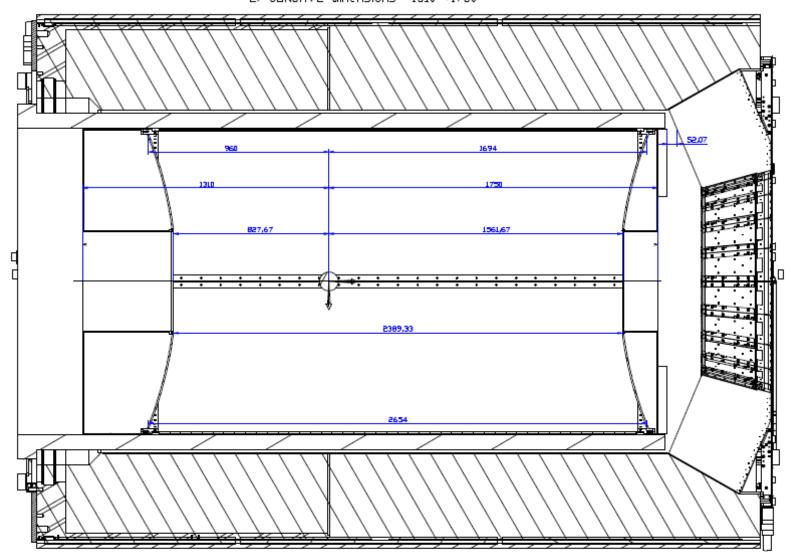
Forward region

Options 7 and 3 have the same performance

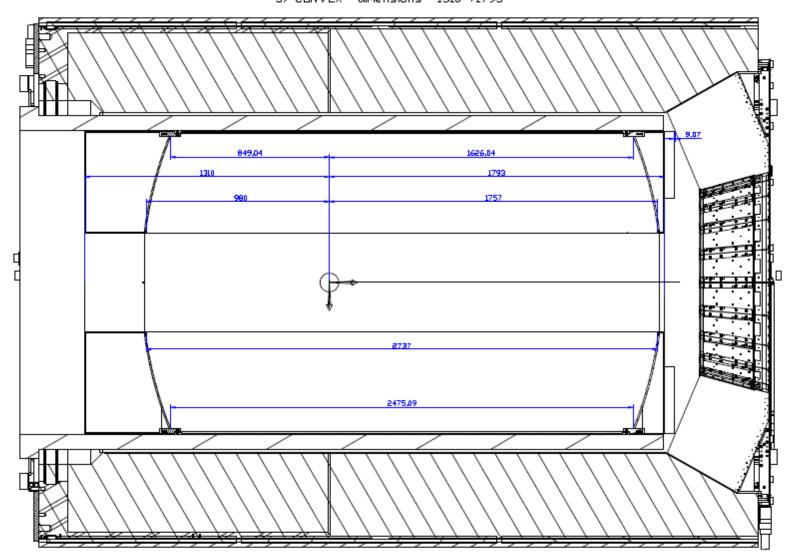
backup



Drawing from Stefano Lauciani, LNF

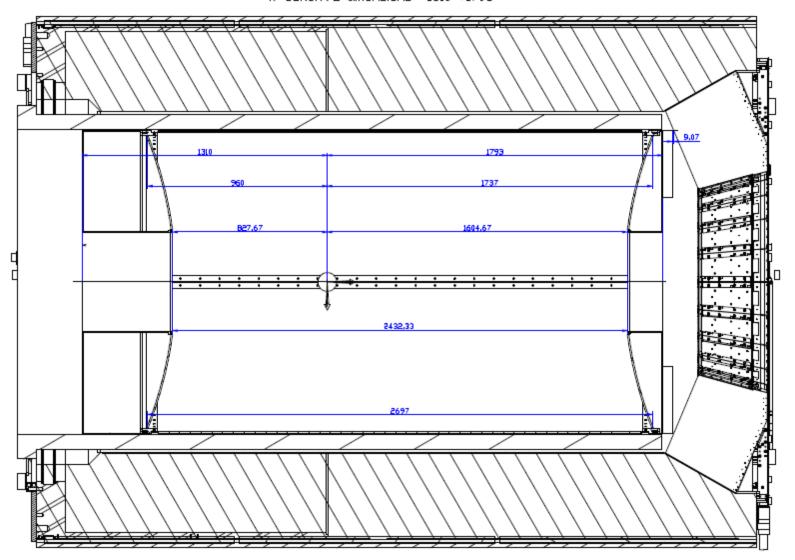


Drawing from Stefano Lauciani, LNF

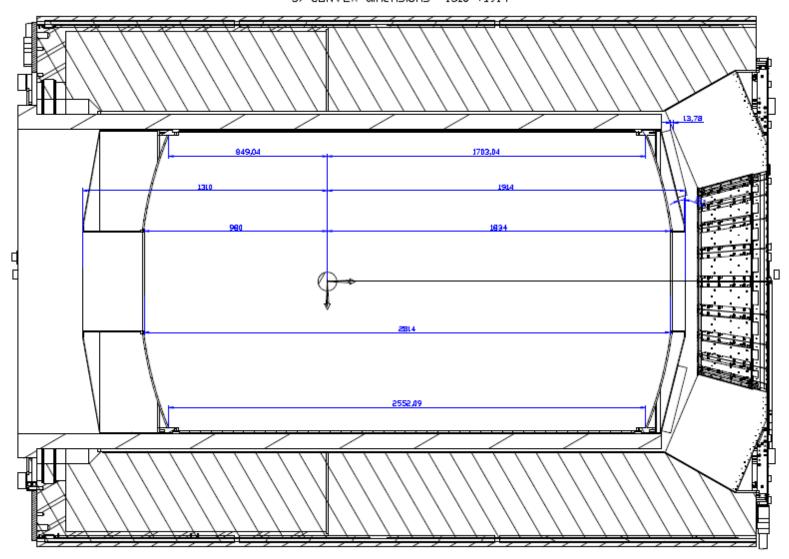


210 mm

Drawing from Stefano Lauciani, LNF

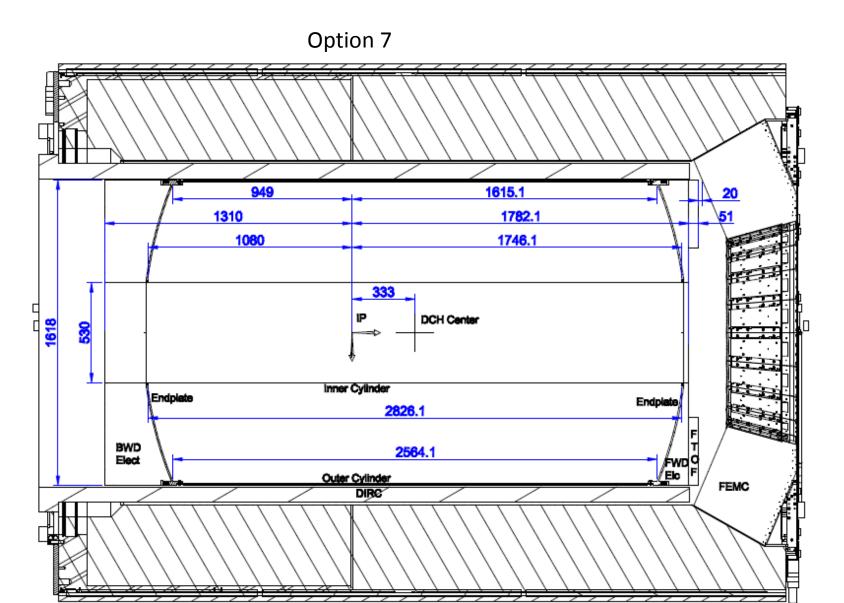


Drawing from Stefano Lauciani, LNF



210 mm

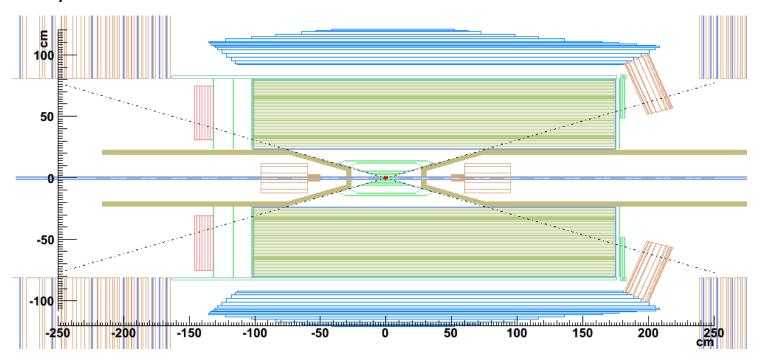
Drawing from Stefano Lauciani, LNF



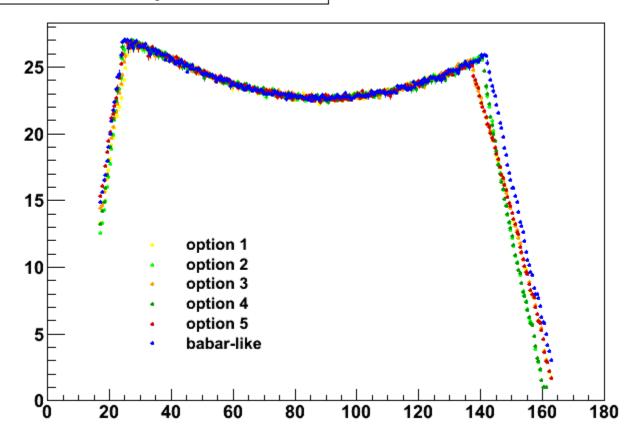
Drawing from Stefano Lauciani, LNF

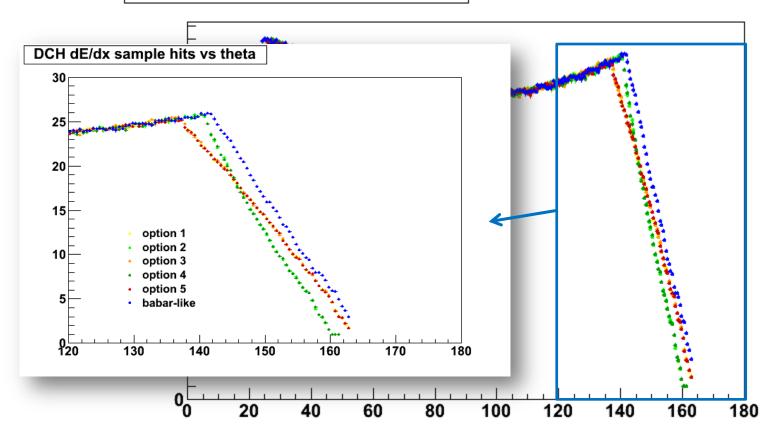
Option 6

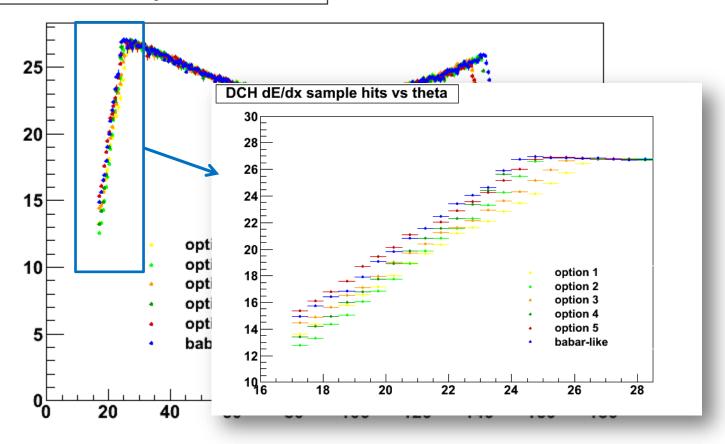
x-z layout in fastsim

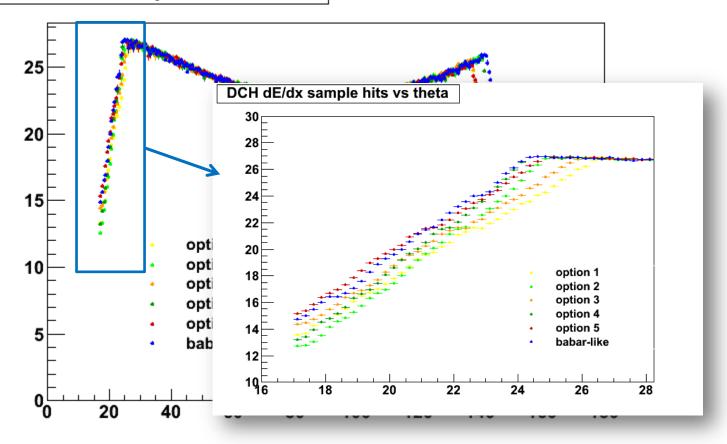


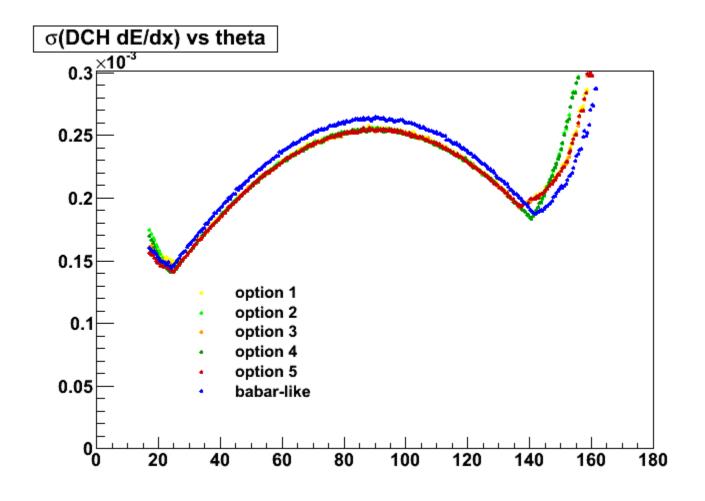
old SuperB (babar-like) configuration

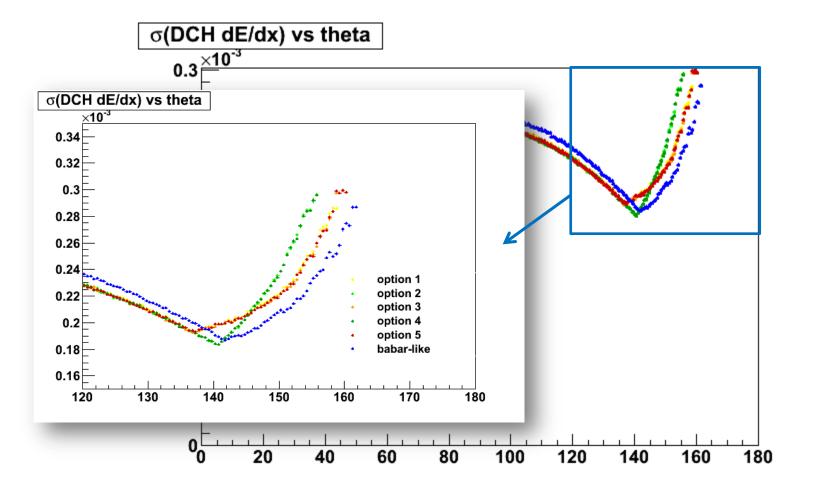


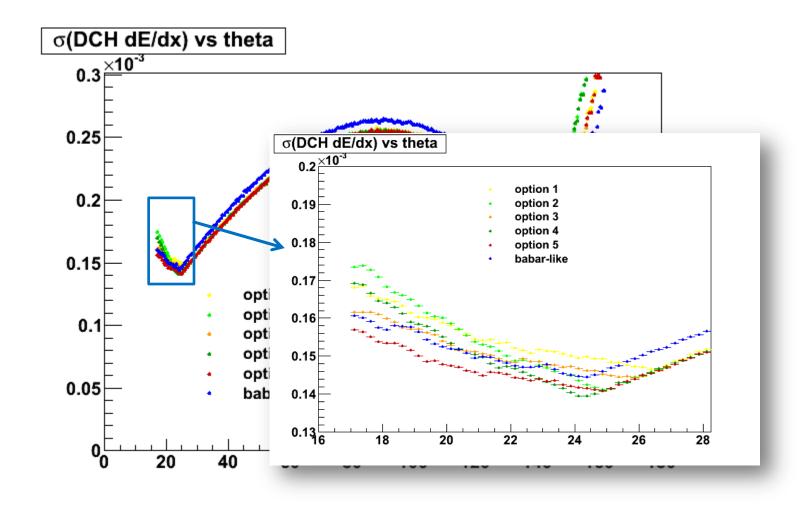




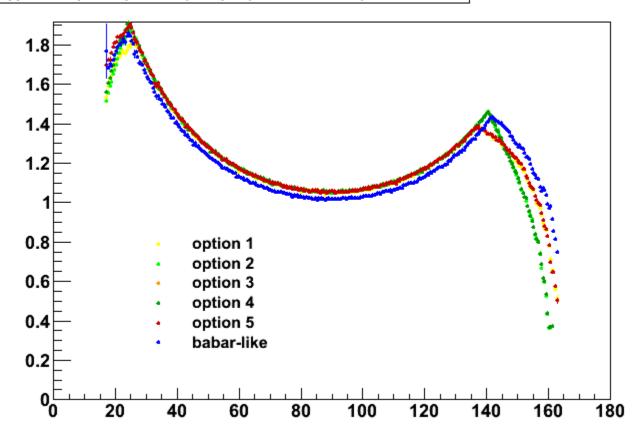








|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) vs theta



|(dE/dx)_pi-(dE/dx)_K|/σ(DCH dE/dx) vs theta

