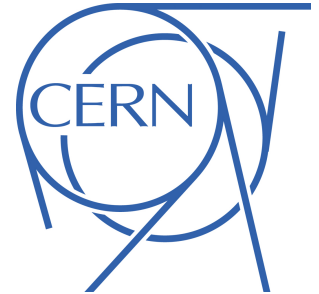


Overview of activities in the ALFA and AX-PET projects



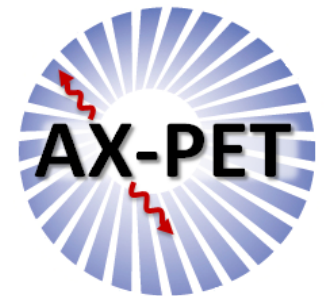
Matthieu Heller
CERN - PH/DT

Marie Curie network MC-PAD
P7 : Advanced photo detectors
Matthieu.heller@cern.ch



Supervisor : Christian Joram

On behalf of the AX-PET collaboration
<https://twiki.cern.ch/twiki/bin/view/AXIALPET>



On behalf of the ALFA community

MC-PAD closing network event
19-22st September 2012 in Frascati

Outline



- ALFA, Absolute Luminosity For ATLAS
 - Physics goal
 - Detector description
 - Physics analysis
 - Track based alignment
- AX-PET
 - Detector description
 - Test campaign on small animals
 - Using digital SiPM from Philips
- Conclusions
- Future and MC-PAD benefits

Outline

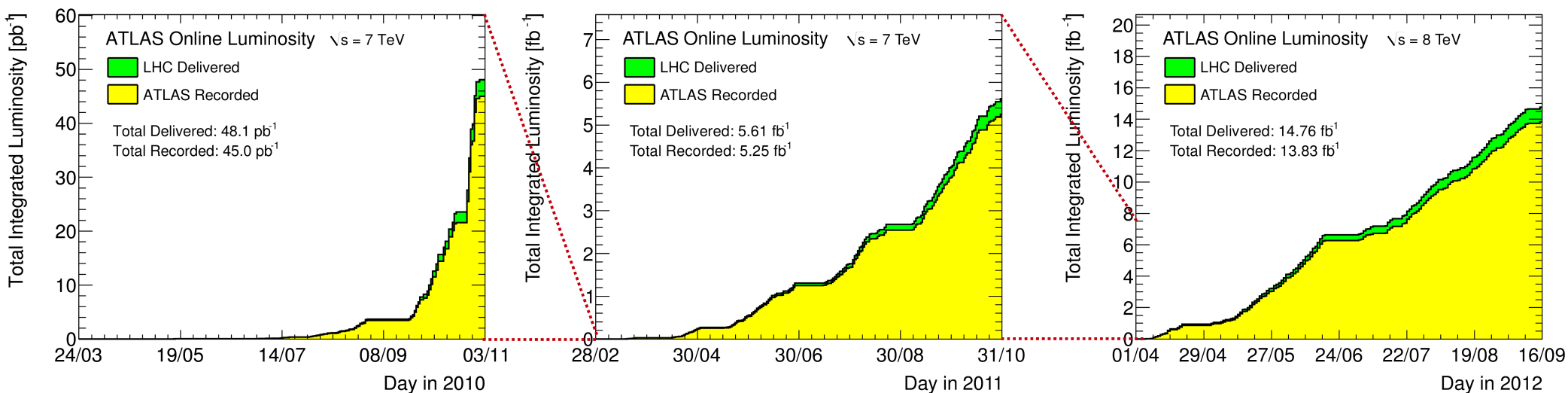


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Context of the ALFA detector



- The LHC has been delivering proton-proton collisions since 24th March 2010
- The energy went from 7 TeV in the center of mass to 8 TeV in 2012
- The efficiency of these collisions, called luminosity, has never stopped improving since then :



- In order to measure the cross sections of different physics process (e.g. Higgs boson production), one need to know the absolute luminosity :

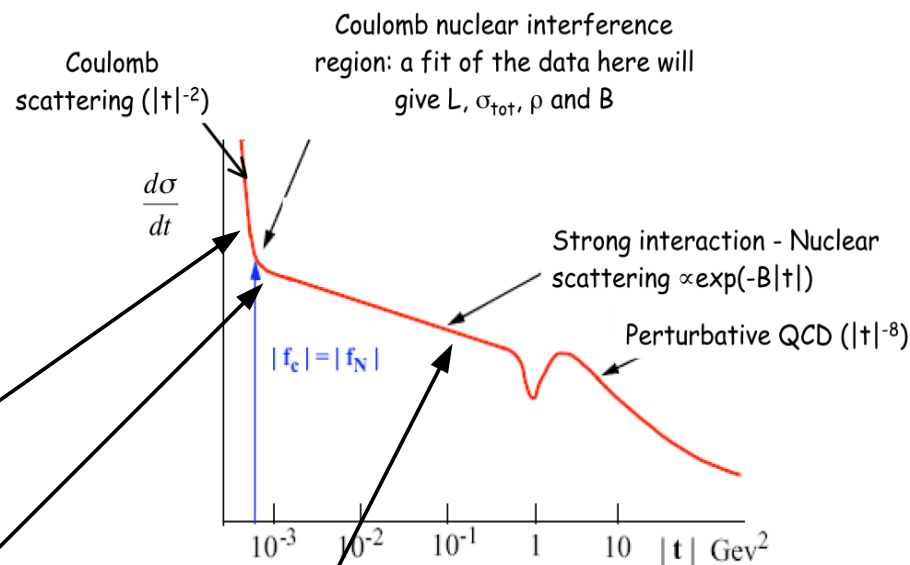
$$R = \mathcal{L} \cdot \sigma \cdot A \cdot \epsilon \quad \Longrightarrow \quad \sigma \propto \frac{R}{\mathcal{L}}$$

Physics goal

- The luminosity can be measured in an absolute way via different methods :
 - From the beam parameters : $\mathcal{L} = \frac{f \cdot N_{bunch} \cdot N_1 N_2}{4\pi \sigma_x \sigma_y}$
 - From a well known physics process
- ALFA uses the **optical theorem** to derive the luminosity, the total cross section and the nuclear slope from the measurement of the differential elastic cross section
- The process is very well described by the **Coulomb interaction** at very small angle (i.e few μrad) but suffers from uncertainties at larger scattering angles (nuclear interactions)



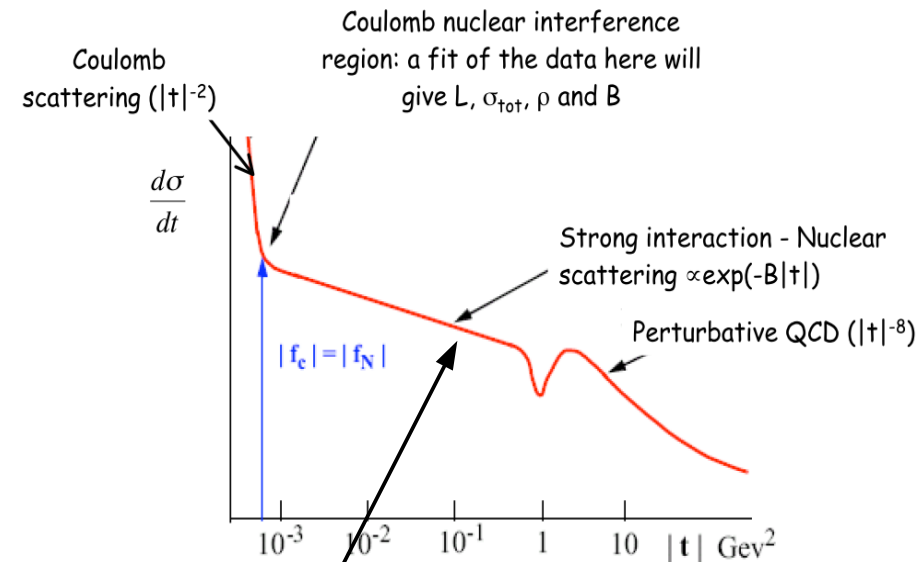
Measure elastic scattering in the Coulomb region to determine absolute luminosity (2-3 % precision) independently of the total cross section (1-1.5 % precision)



$$\frac{dN_{tot}}{dt} \sim L |A_{coulomb} + A_{nuclear}|^2 = L \left[\frac{4\pi\alpha^2}{t^2} - \frac{\alpha\rho\sigma_{tot}}{t} \exp\left(-\frac{B|t|}{2}\right) + \frac{\sigma_{tot}^2}{16\pi} (1 + \rho^2) \exp(-B|t|) \right] \text{ with } \begin{aligned} t &= (p_1 - p_3)^2 \\ t &\approx (p\theta)^2 \end{aligned}$$

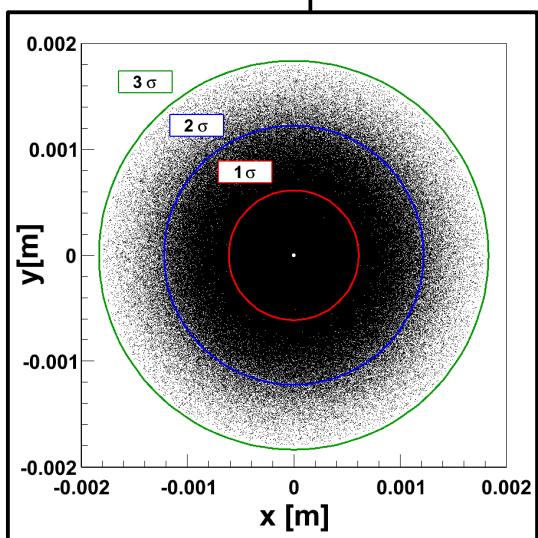
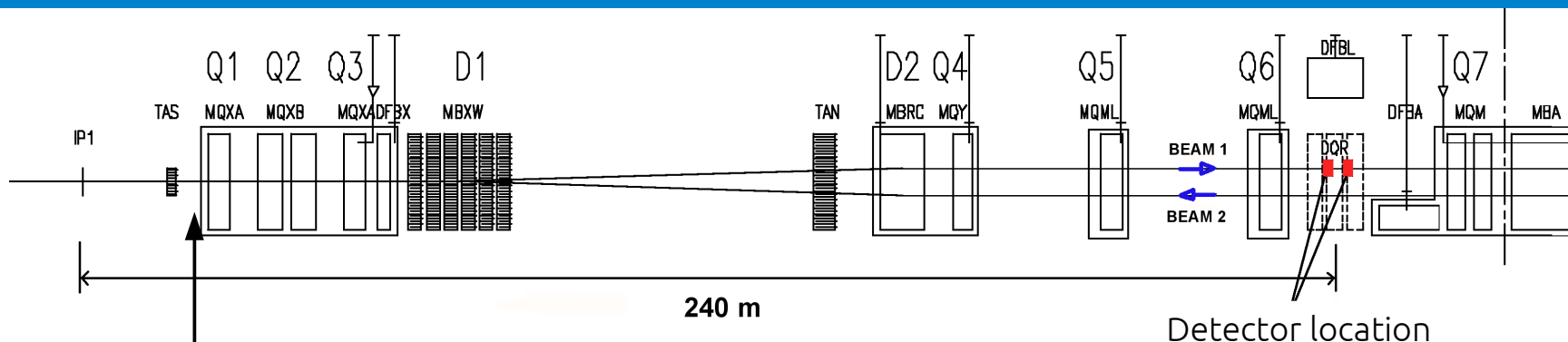
Physics goal

- The measurement of the Coulomb region requires the LHC to run in a special configuration (see next slide). This latter is hard to setup and will only be realised in 2014
- In the meantime, intermediate settings have been used but only allowing to reach the nuclear region
- Probing the nuclear part of the spectrum allows us to determine the total cross section and the nuclear slope
- For this we use the theoretical value of ρ and the luminosity measured using beam parameters (precision $\sim 2\%$)



$$\frac{dN_{\text{tot}}}{dt} \sim L |A_{\text{coulomb}} + A_{\text{nuclear}}|^2 = L \left[\frac{4\pi\alpha^2}{t^2} - \frac{\alpha\rho\sigma_{\text{tot}}}{t} \exp\left(-\frac{B|t|}{2}\right) + \frac{\sigma_{\text{tot}}^2}{16\pi} (1 + \rho^2) \exp(-B|t|) \right] \text{ with } \begin{aligned} t &= (p_1 - p_3)^2 \\ t &\approx (p\theta)^2 \end{aligned}$$

Optics settings



Scattering picture before the first magnetic element

- Elastically scattered protons are too close to the beam core to be intercepted before the first magnetic element
- Need to install the detectors after in the sequence to increase the separation of these protons

$$u(s) = f(u_{IP}) + \sqrt{\beta(s)\beta_{IP}} \sin(\Delta\mu) u'_{IP}$$

$$\sigma' = \sqrt{\frac{\epsilon}{\beta_{IP}}} \quad \text{Angular dispersion at the interaction point}$$

Parallel to point focusing and high β^* optics

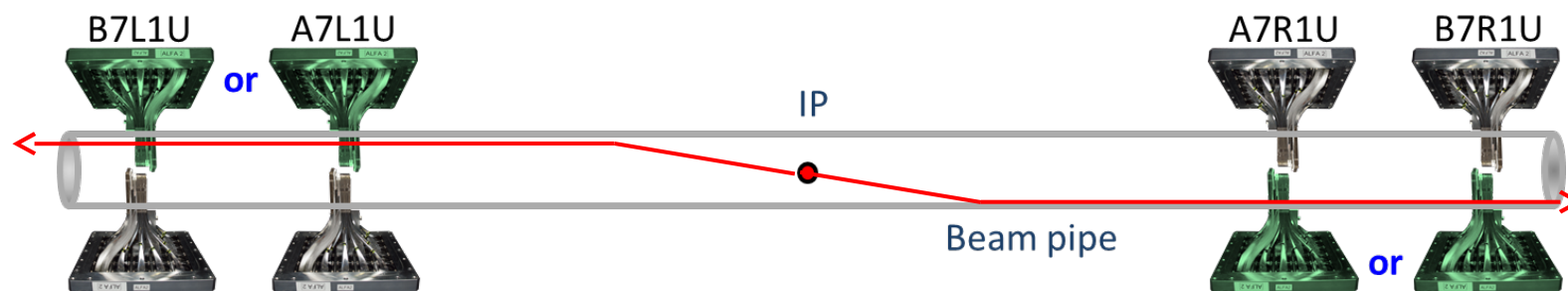
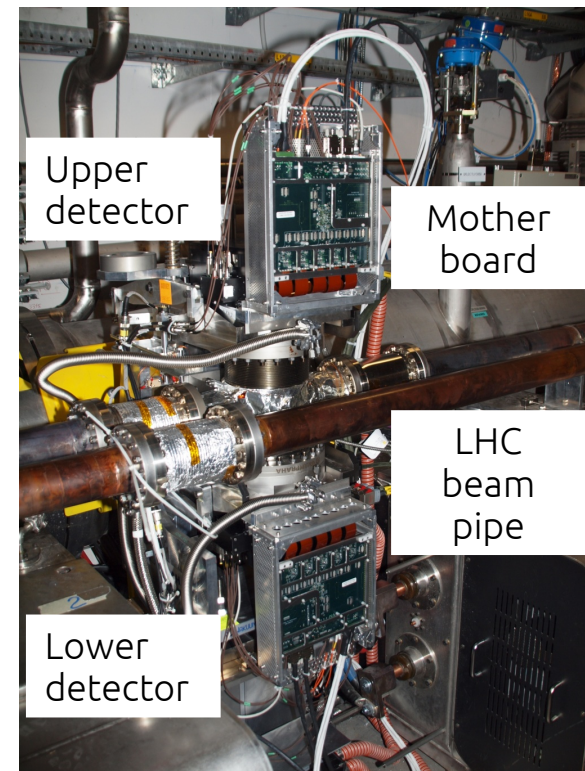
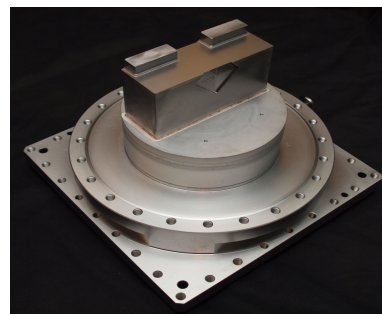
$$y_{det} \approx L_{eff,y} \theta_y^{IP} \quad \text{and} \quad x_{det} = L_{eff,x} \theta_x^{IP} + f(x_{IP})$$

with $L_{eff,y} \approx 270 \text{ m}$ and $L_{eff,x} \approx -10 \text{ m}$

Detector description

- The detectors still have to be approached very close the circulating beam at \sim mm distance The requirements are then :
 - No dead edge zones
 - Compatibility with operation in vacuum
 - Easy and quick to install and remove
 - Moderate radiation hardness
- A technical solution was already used in the past, the so called Roman Pot. A detector can be installed inside being separated from the primary vacuum of the accelerator

Roman pot

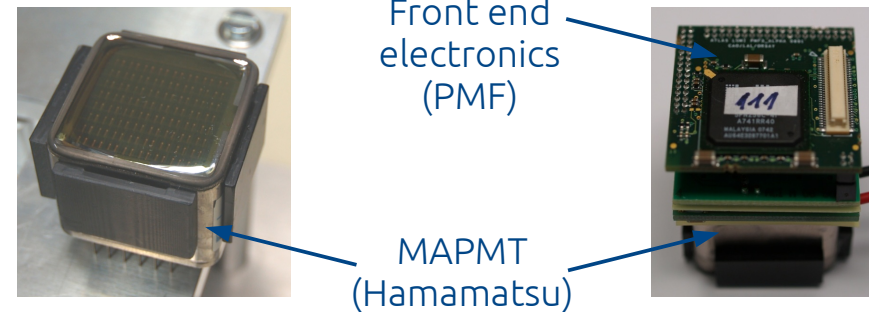
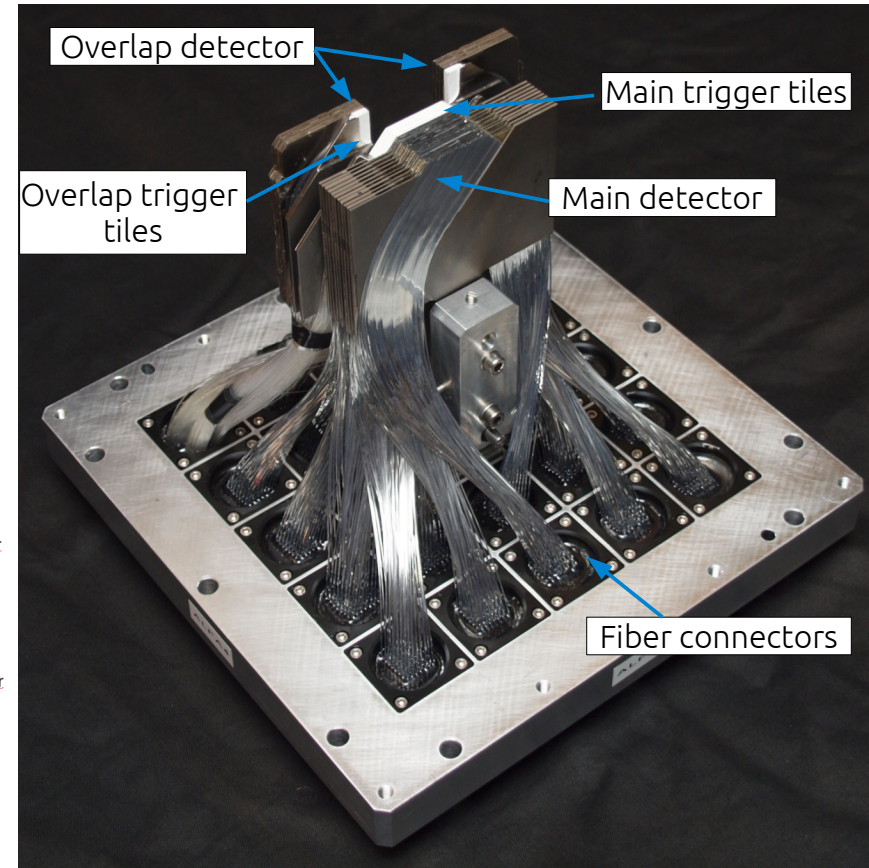
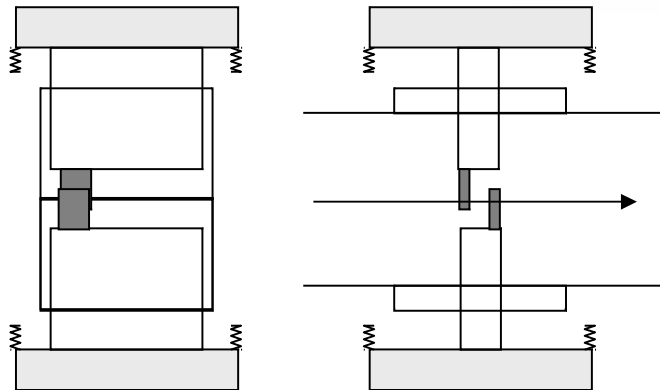
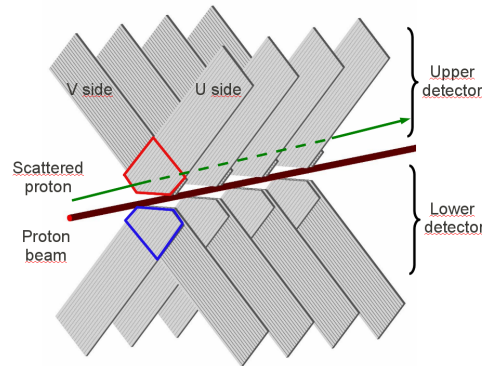
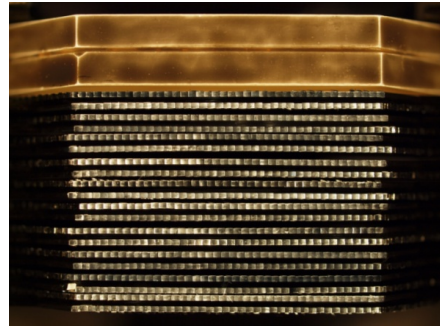


Detector description

Scintillating fiber tracker :

- 20 layers arrange in U-V geometry
- A staggering of a $1/10^{\text{th}}$ of a fiber \rightarrow ideal spatial resolution $\sigma_{x,y} = 14.4 \mu\text{m}$
- Each layer is made of 64 scintillating square fibers ($0.5 \times 0.5 \text{ mm}^2$)
- The 64 fibers are readout by an MAPMT from Hamamatsu connected to a compact front end electronics
- Overlap detectors to measure the distance between upper and lower detectors

Staggered fiber planes



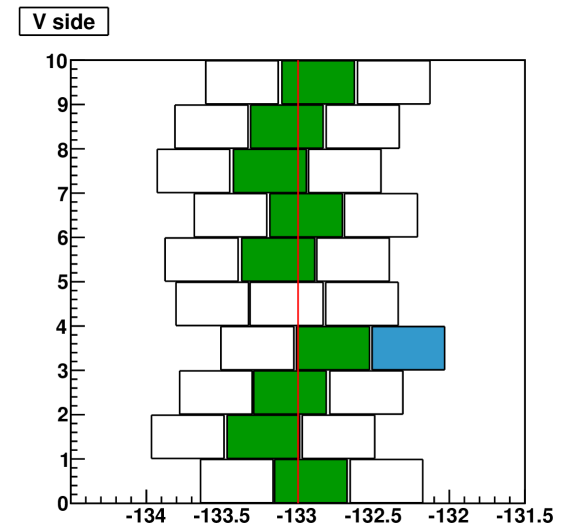
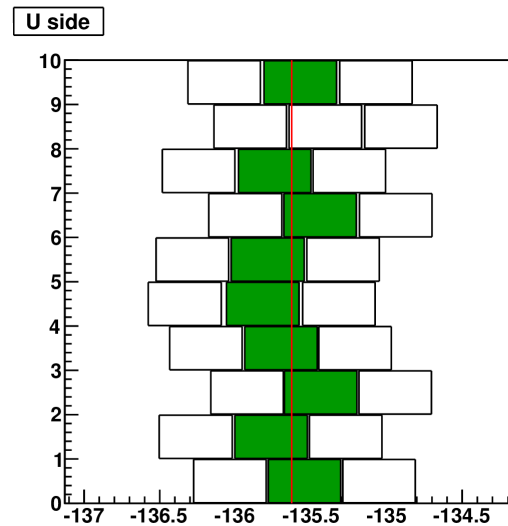
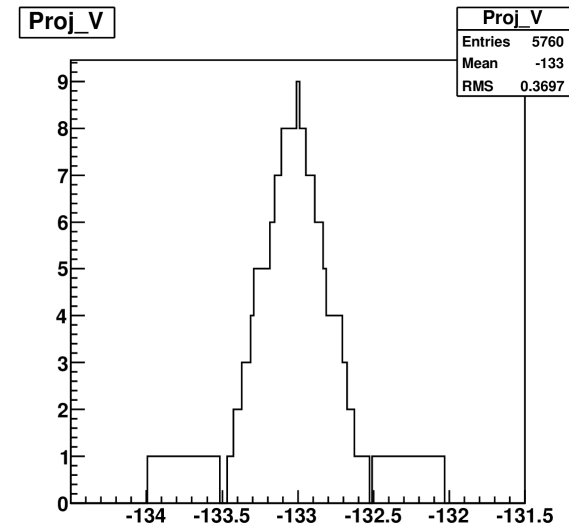
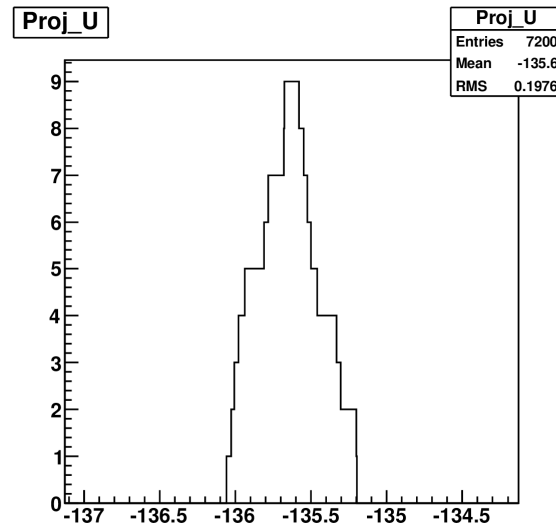
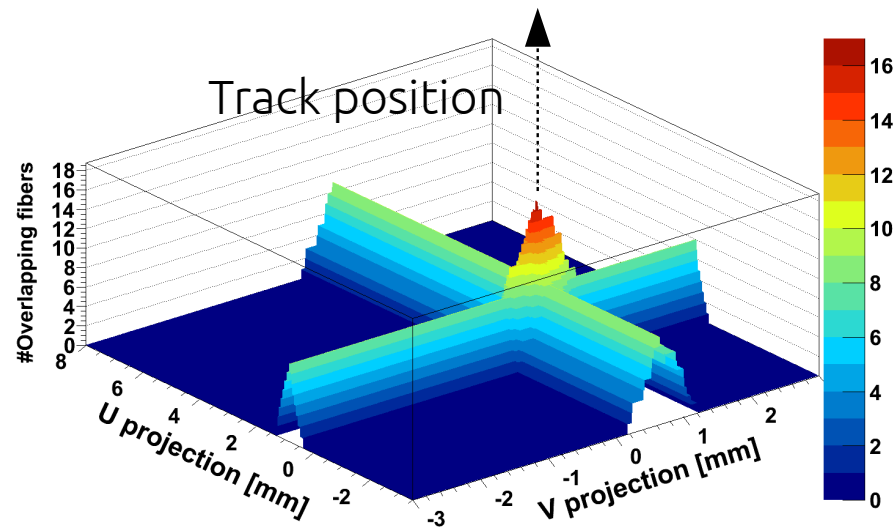
Track reconstruction



Tracks perpendicular to detector
→ Overlap reconstruction algorithm
→ $\sim 30 \mu\text{m}$ resolution achieved

Also available :

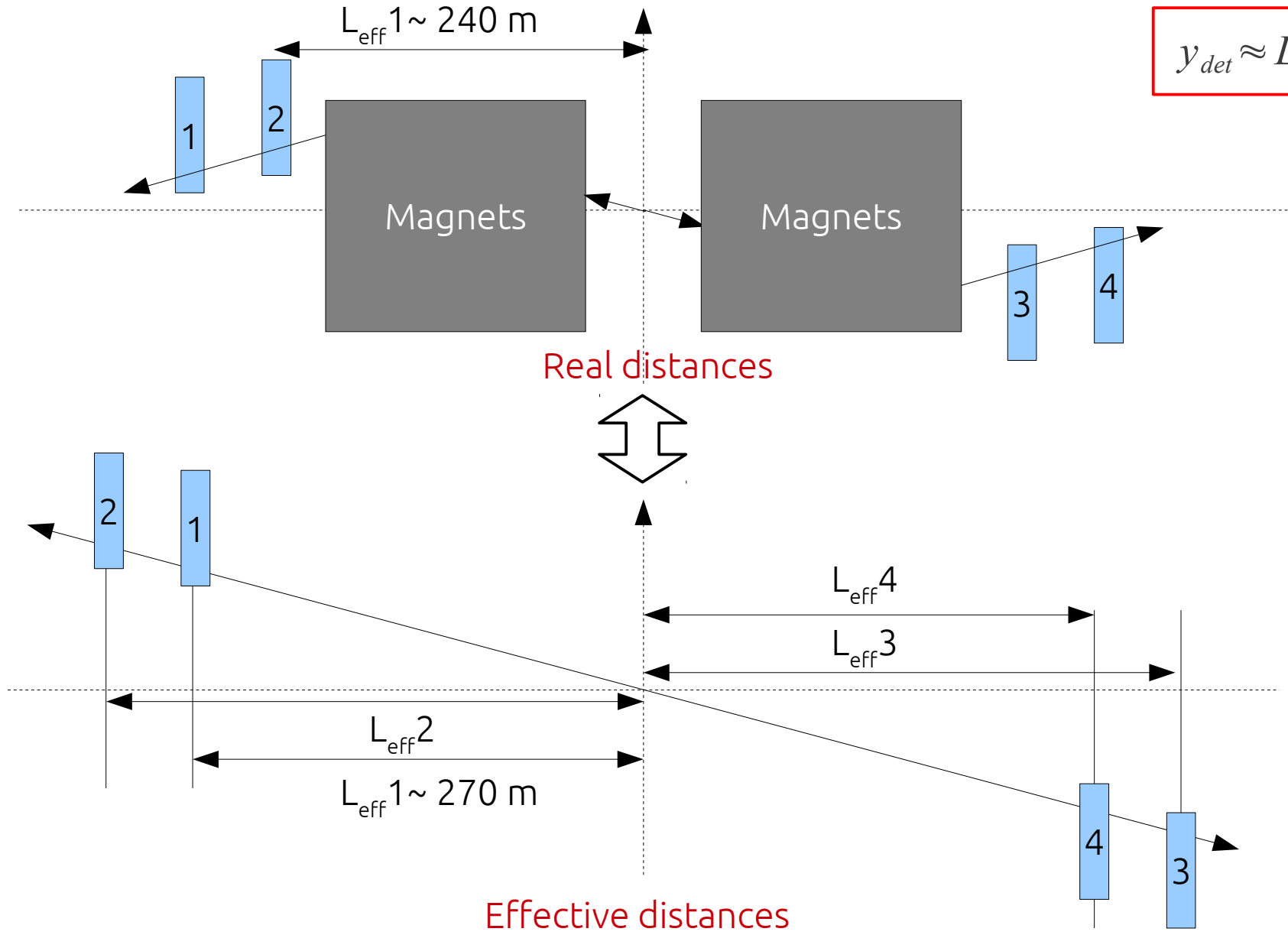
- Multiple track reconstruction
- Enhanced resolution using gaps
- 3D reconstruction if rotation in transverse plane known
- Very robust, almost insensitive to any noise hit (e.g. cross talk)



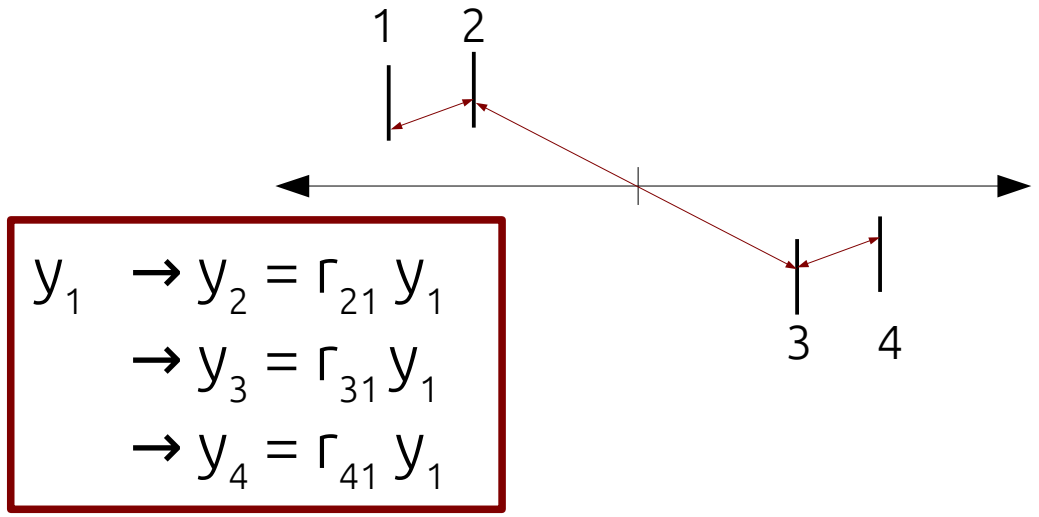
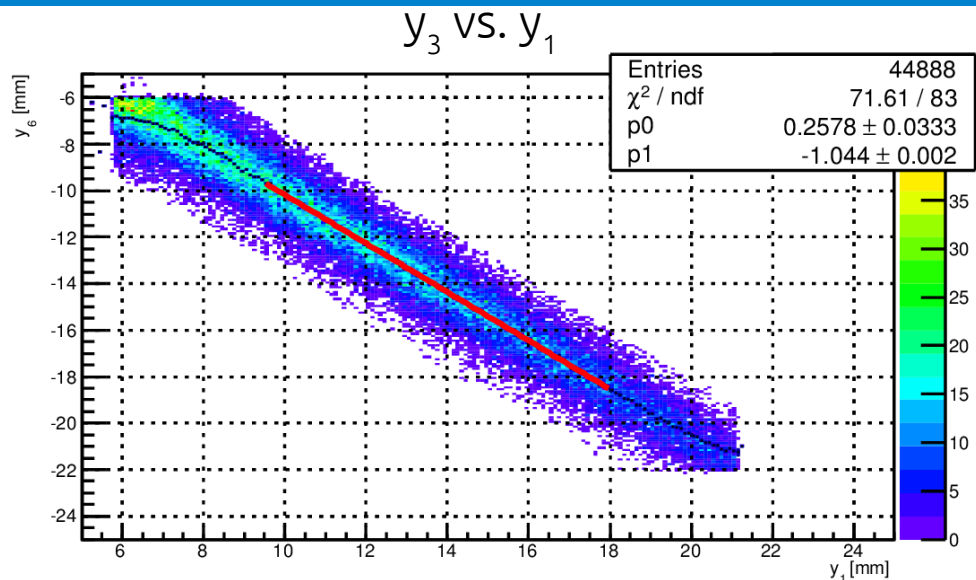
Track based alignment



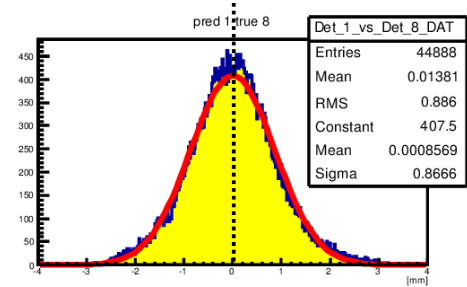
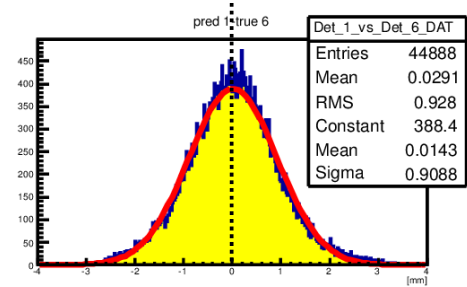
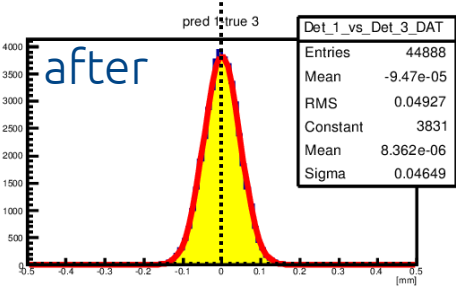
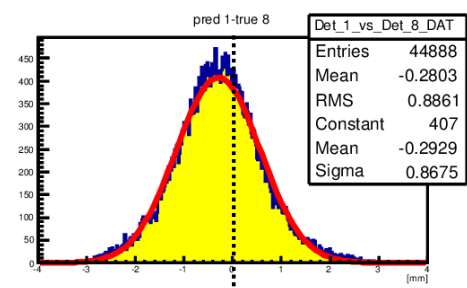
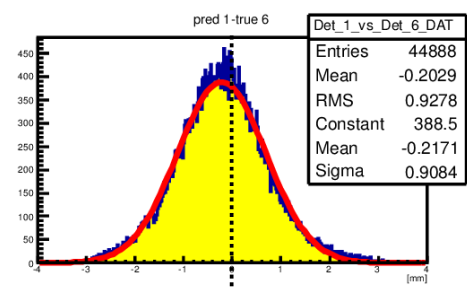
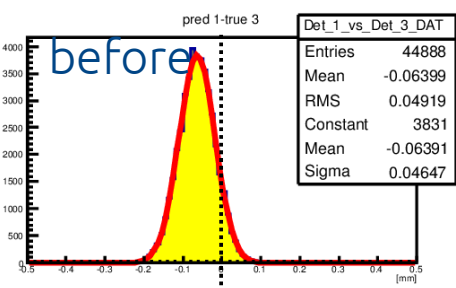
$$y_{det} \approx L_{eff,y} \theta_y^{IP}$$



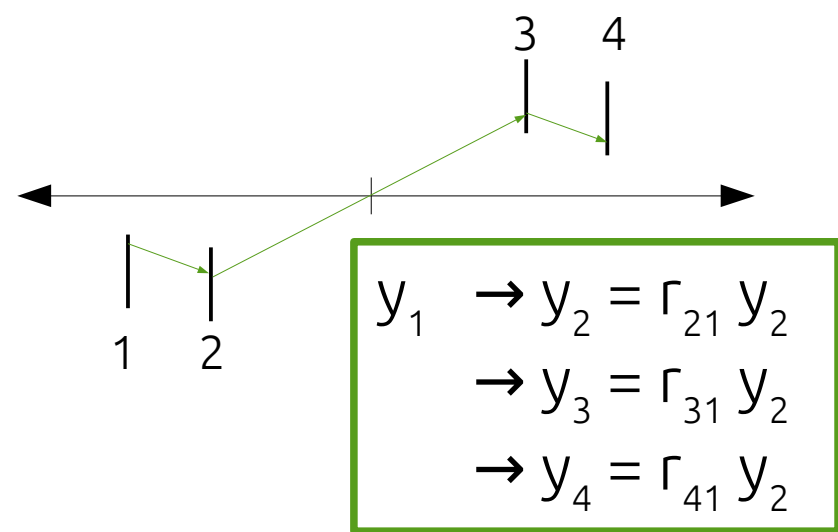
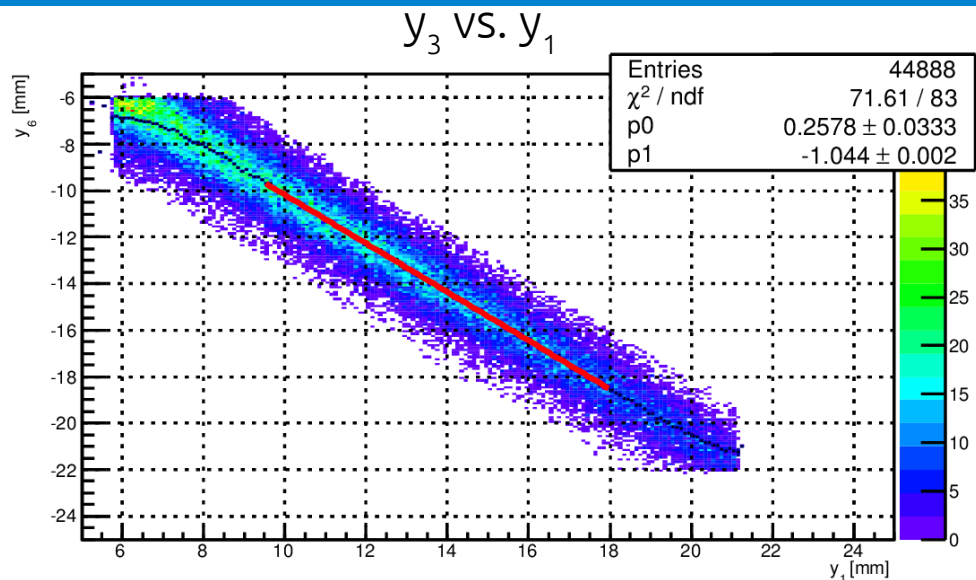
Track based alignment



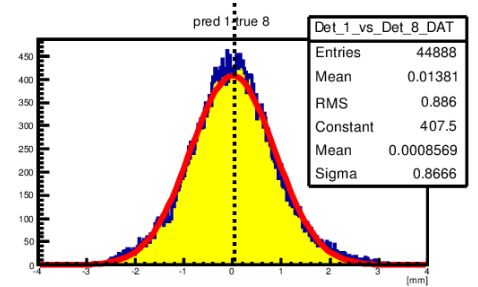
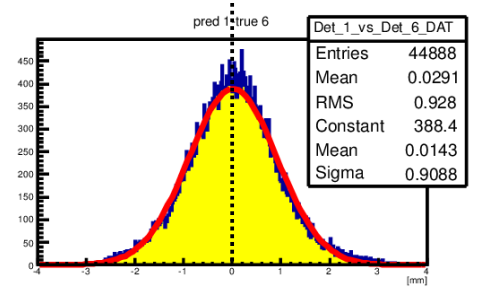
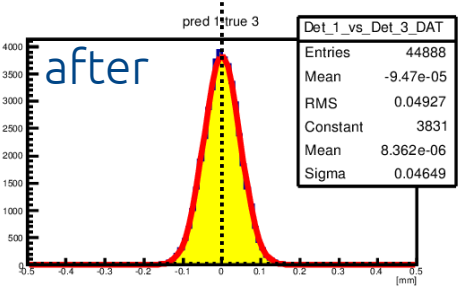
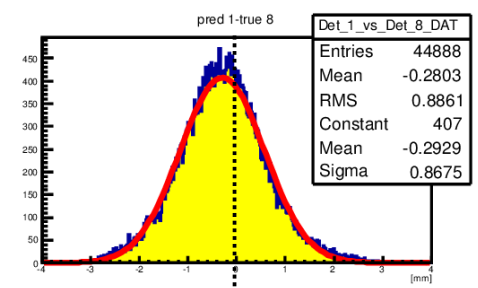
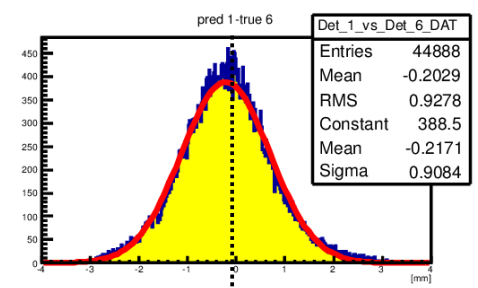
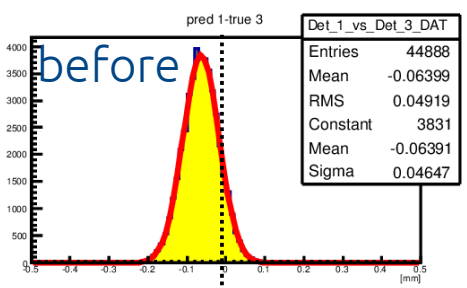
Example using station 1 as a reference



Track based alignment



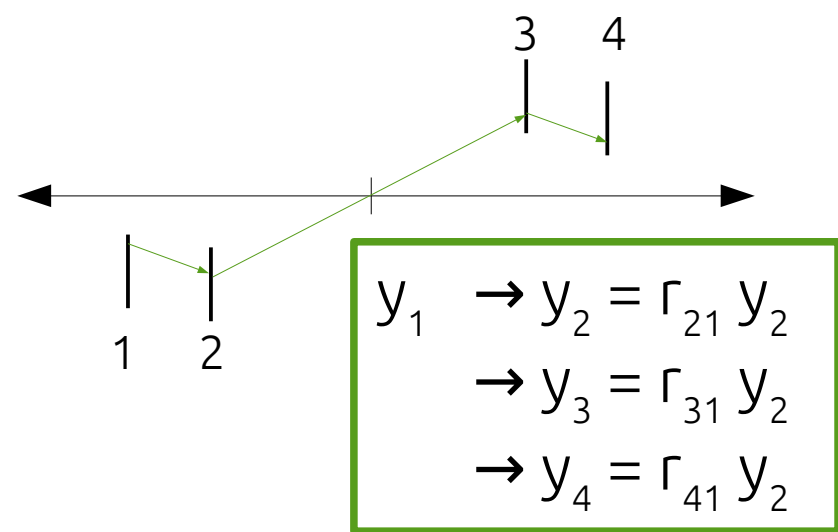
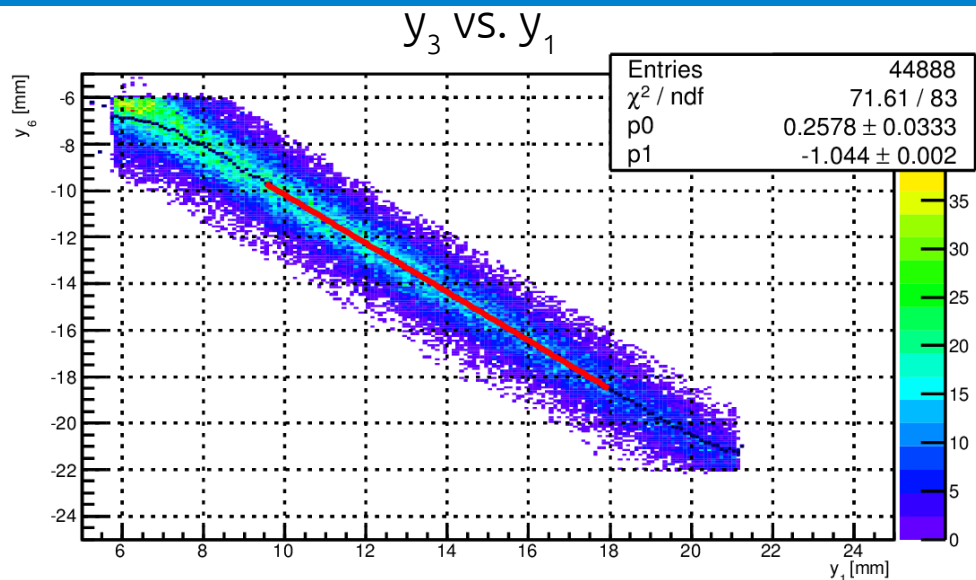
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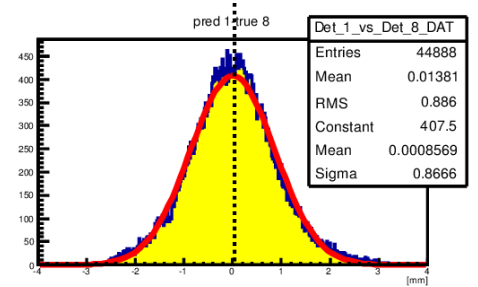
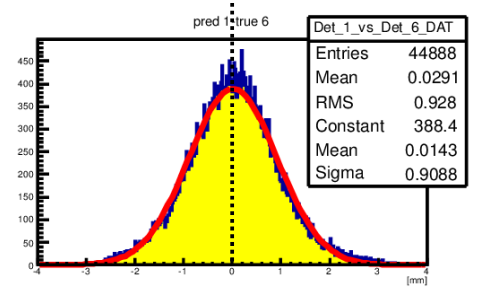
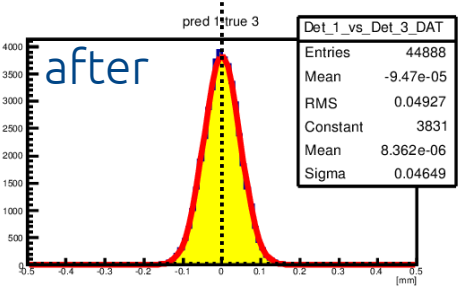
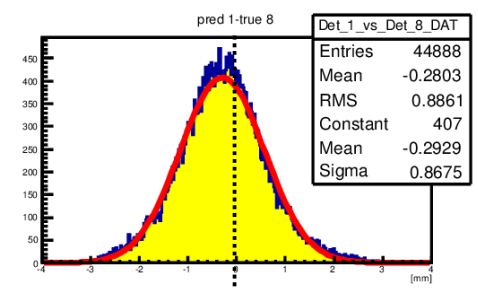
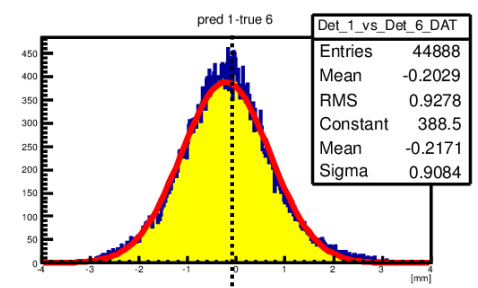
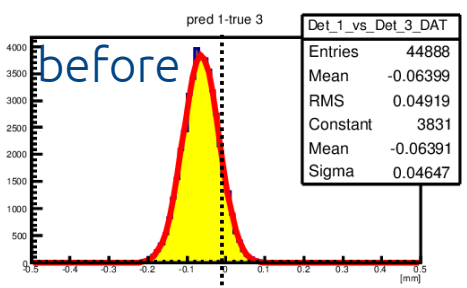
Relative alignment only, need a reference station !

Distance measurement is affected by very different systematical uncertainty depending on the station (calibration, data quality, statistics..)

Track based alignment



Example using station 1 as a reference



$$\Delta y_{UPPER} = \Delta d/2 - \Delta Off_y$$

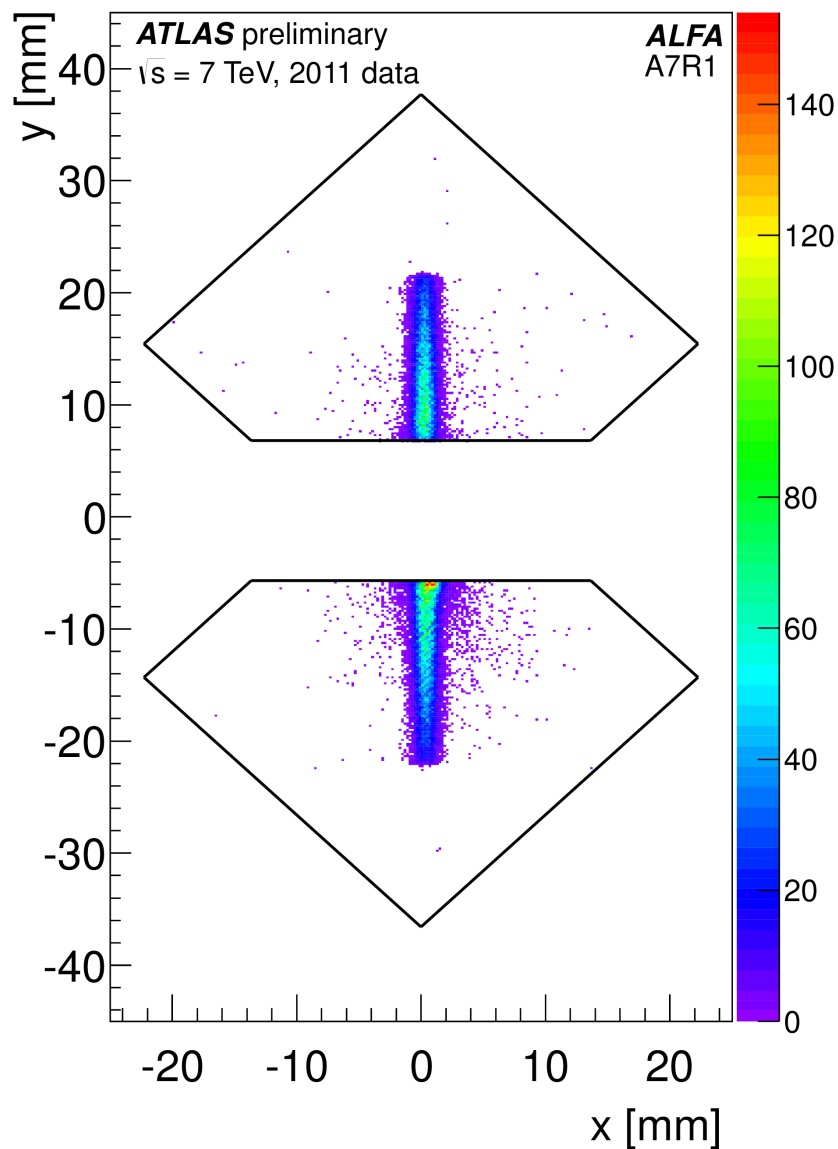
$$\Delta y_{LOWER} = -\Delta d/2 - \Delta Off_y$$



$$\Delta d = \Delta y_{UPPER} - \Delta y_{LOWER}$$

$$\Delta Off_y = \frac{-\Delta y_{UPPER} - \Delta y_{LOWER}}{2}$$

Physics analysis

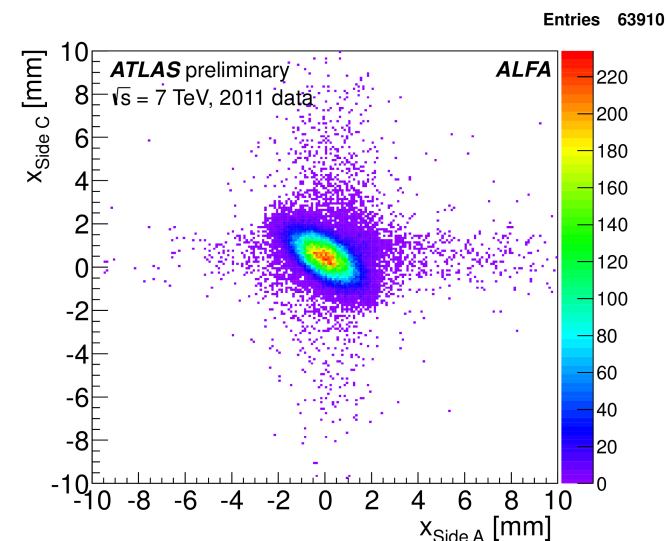
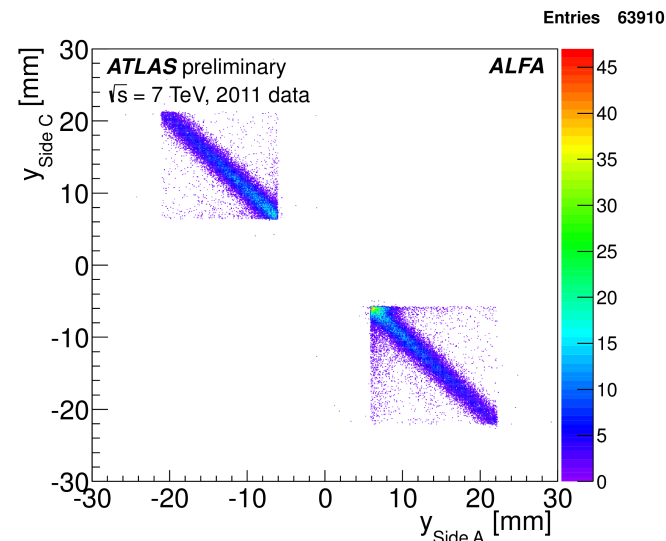


Alignment uncertainty driven by the distance measurement error ($\sim 30 \mu\text{m}$), relative precision better than $3 \mu\text{m}$

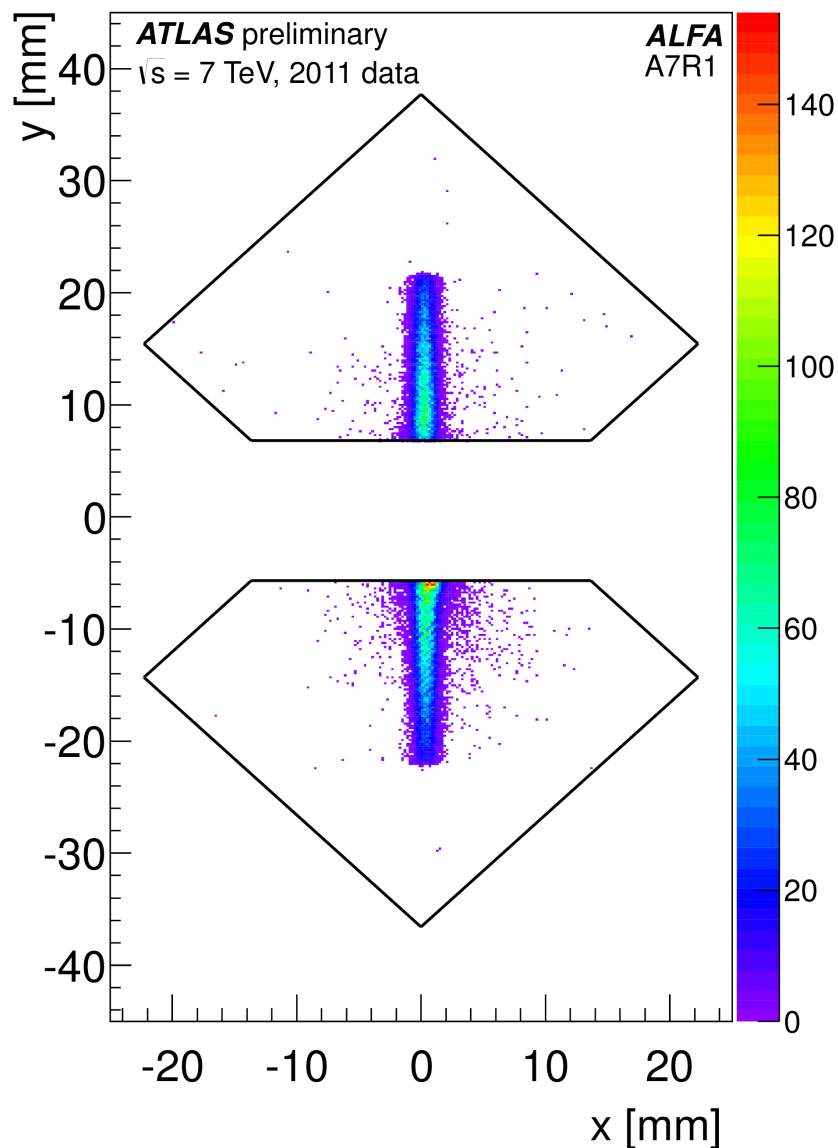
Horizontal alignment easier due to absence of acceptance cut

Once the tracks are expressed in the beam coordinate system, the physics analysis can start :

- First look at correlations between the two sides
- Define selection criteriae for elastic events
- Disentangle efficiency from acceptance corrections
- ...



Physics analysis

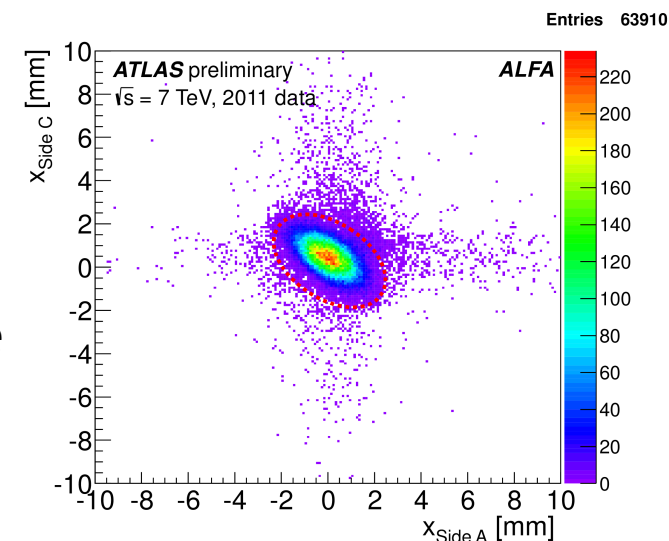
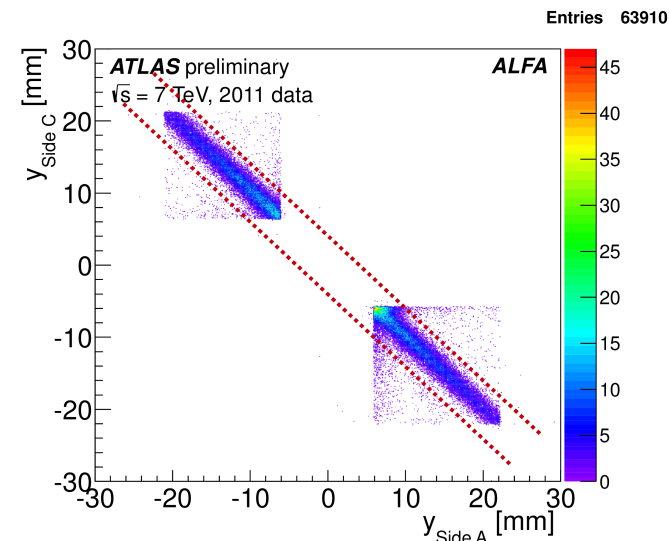


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- ...



Conclusion



- The ALFA detector has been fully installed and commissioned since 2011 and has taken so far three major run for physics
- The total cross section and nuclear slope measurement publication is still pending due to inconsistency between different t-reconstruction methods (optics related)
- A week ago, the optics was set such that we could reach the Coulomb-Nuclear interference region
- After the long LHC shutdown, the ultimate optics will be setup and the Coulomb region will be reached allowing the absolute luminosity measurement
- During this two years I have participated to the different commissioning activities, data taking (deputy run coordinator) and physics analysis (deputy convenor)

Outline

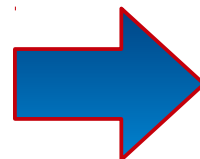
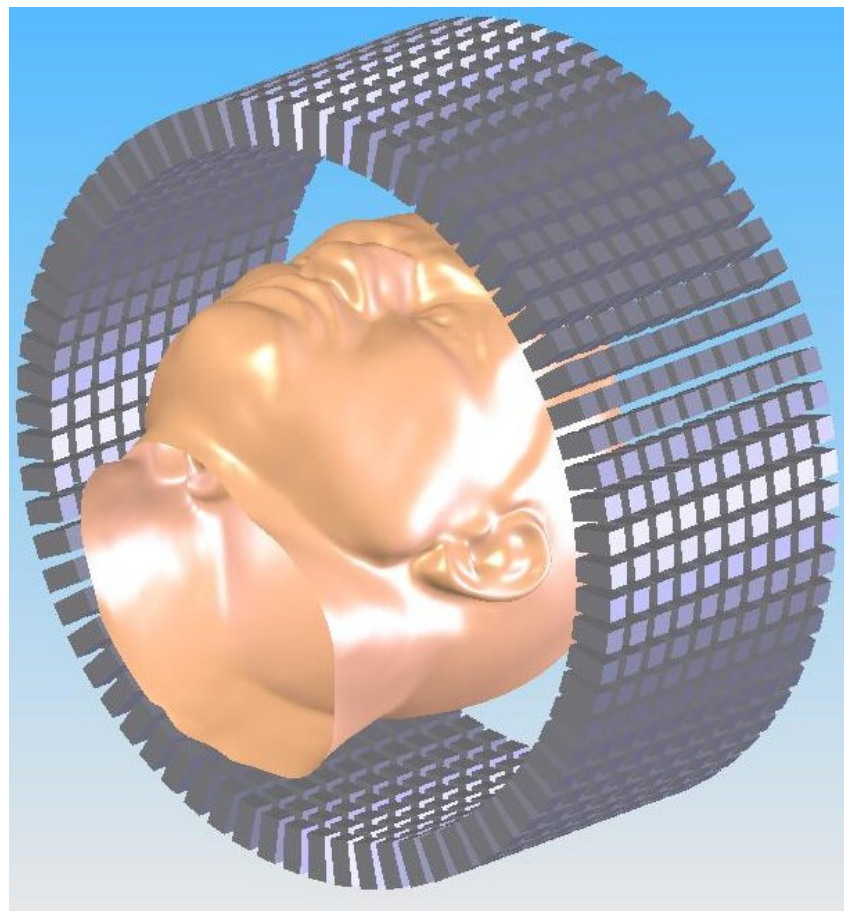


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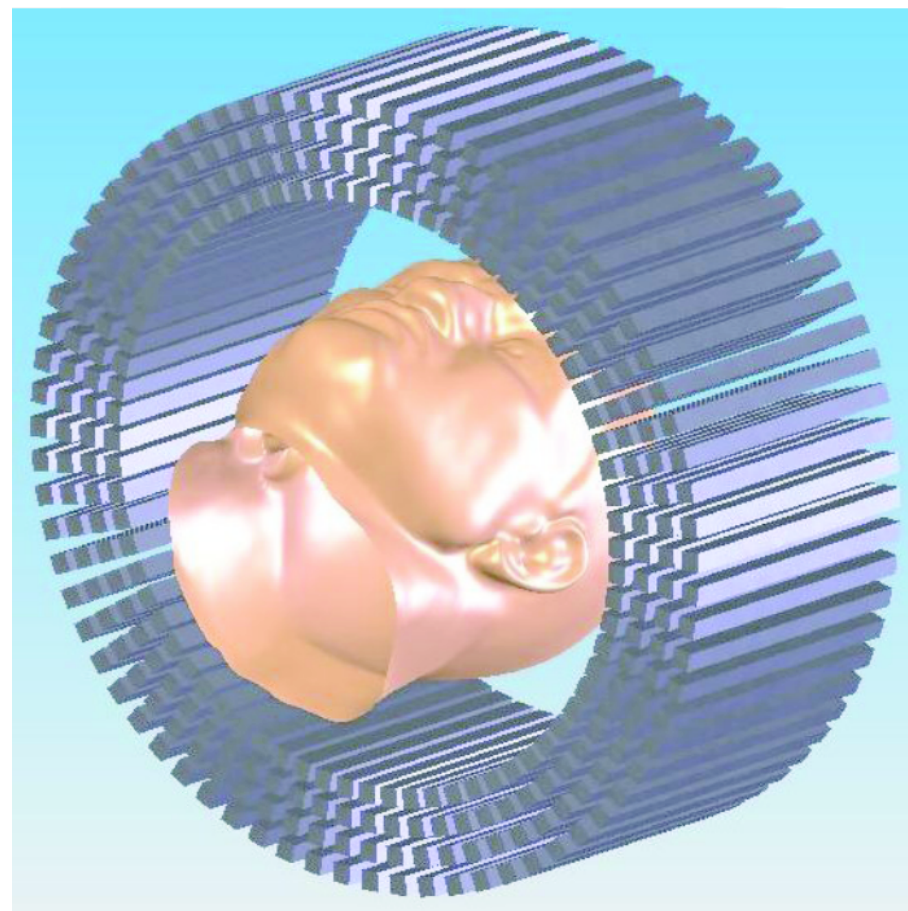
The AX-PET concept



Standard PET scanners



AX-PET geometry proposal



Short crystals radially oriented
Block readout

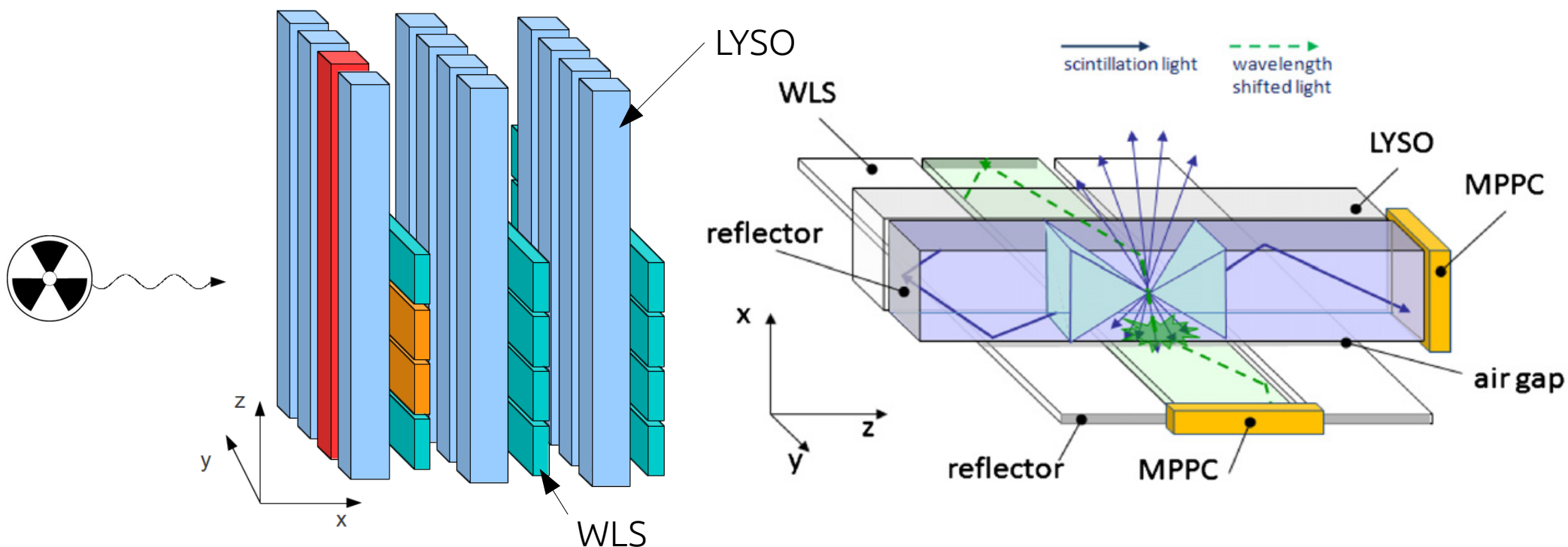
Long crystals axially oriented
Single crystal readout

The AX-PET concept

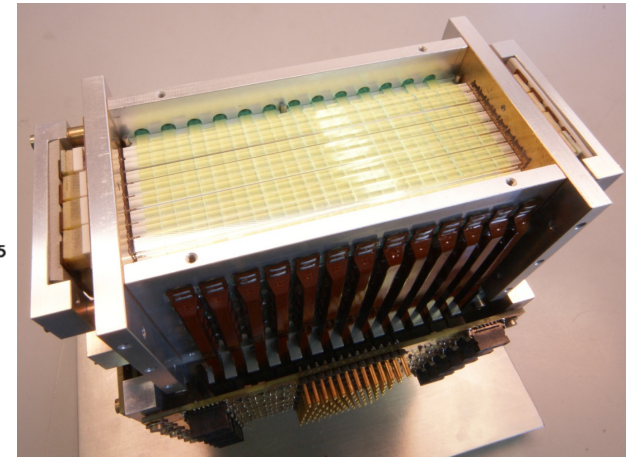
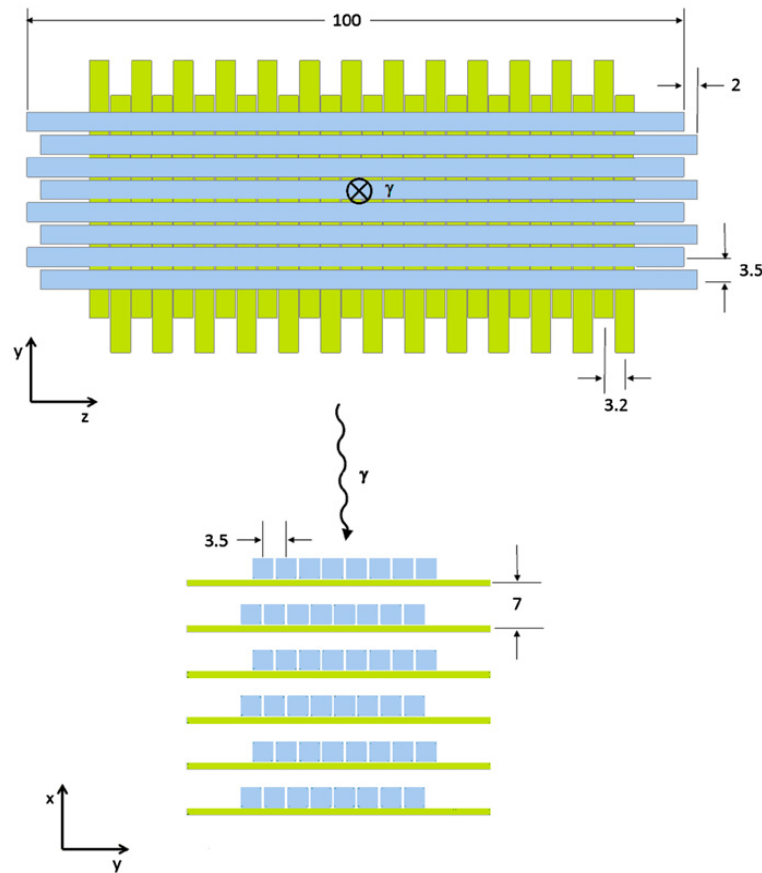
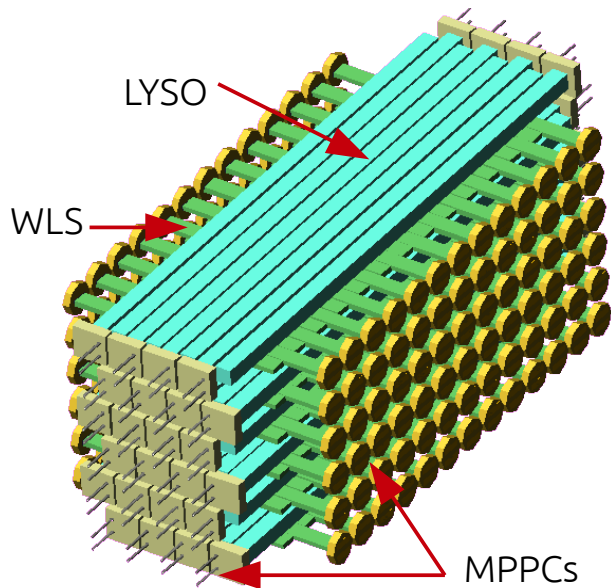


3D measurement of the photon interaction point

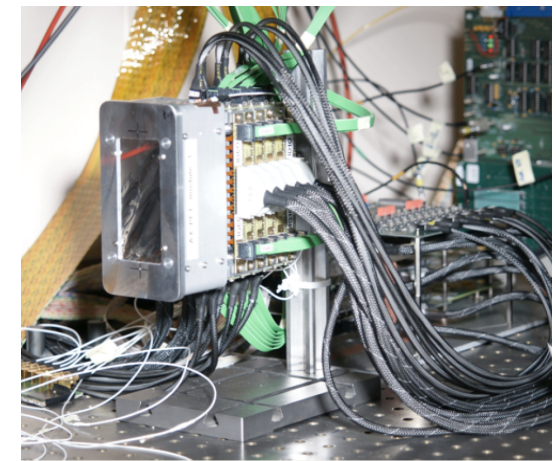
- Transaxial coordinate and energy measurement with thin elongated scintillator LYSO crystals
 - The hit crystals gives the transaxial coordinate (x, y)
- Axial coordinates measured with Wave Length Shifter (WLS) strips



Module assembly



Assembled module

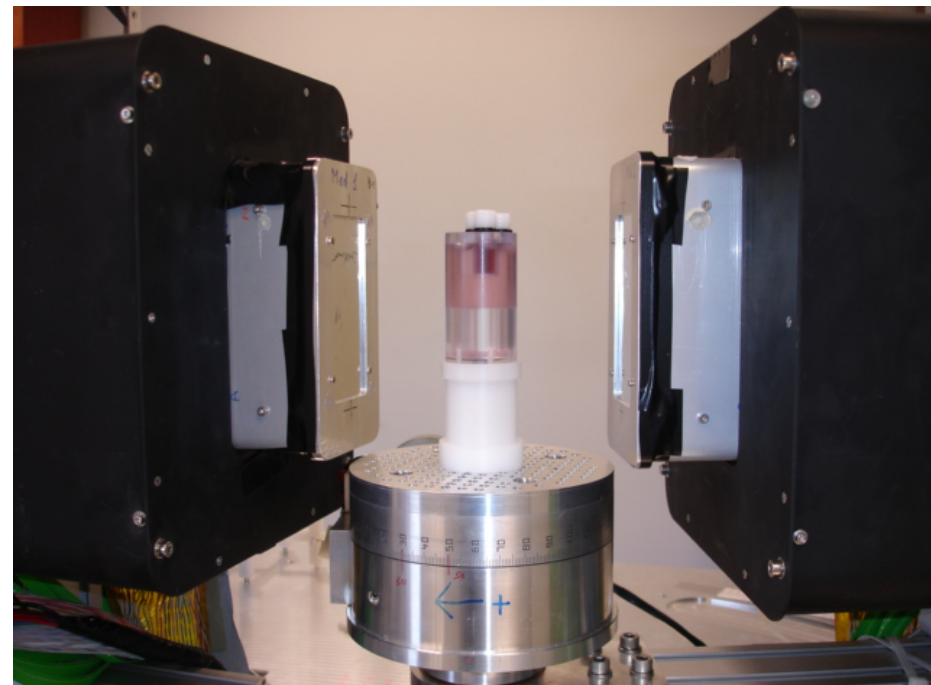
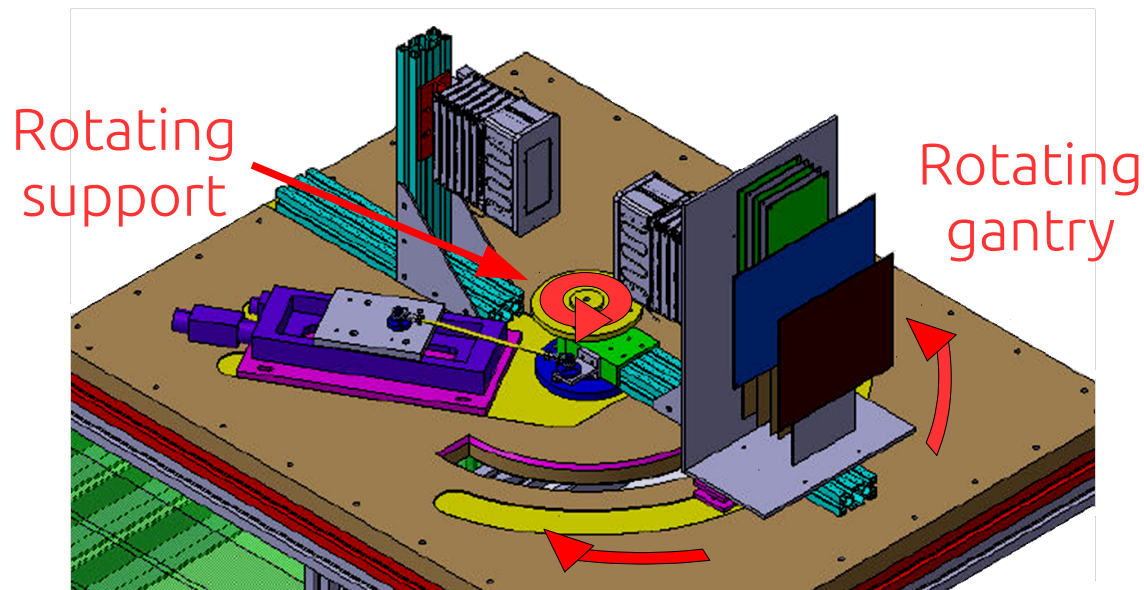


Module housing and services

- Each module is composed by six layers
- Each layer is made of 8 LYSOs and 26 WLS both staggered to enable the readout
 - 204 channels per module
- All layers are optically decoupled

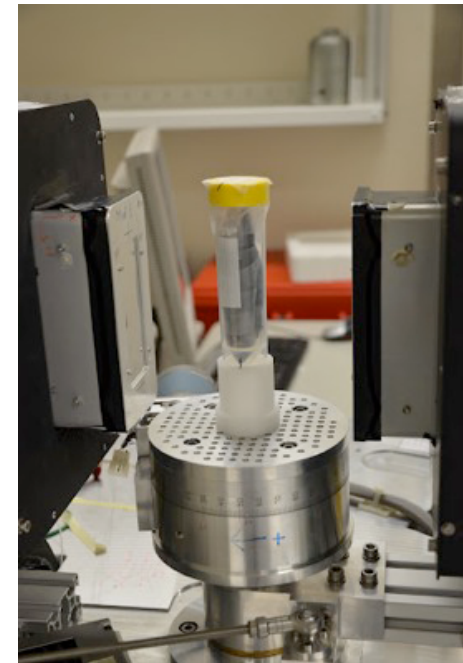
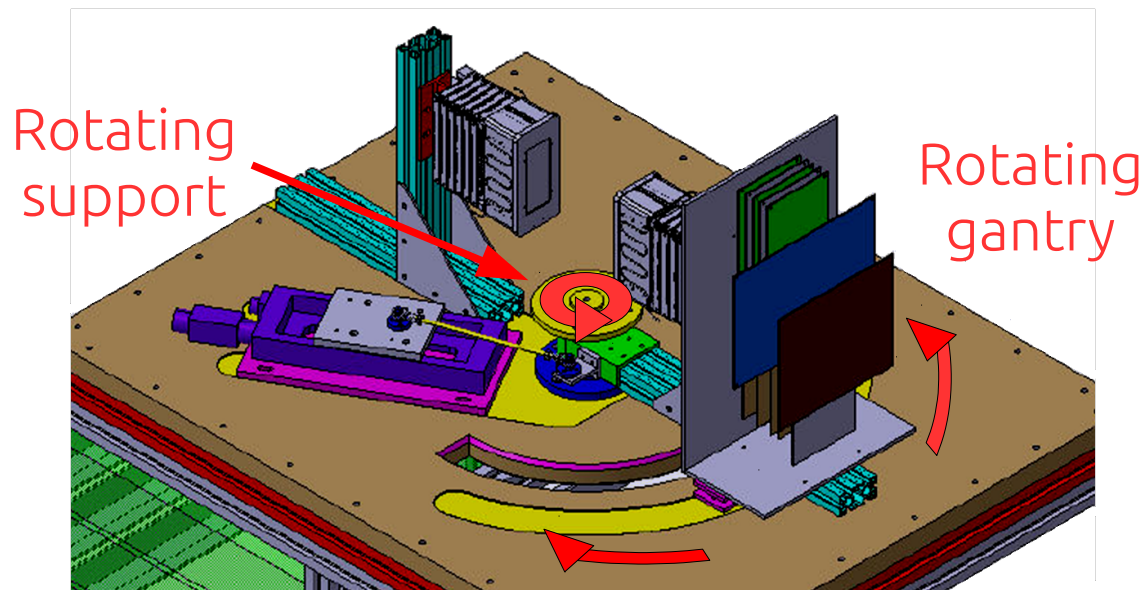
Test bench for tomographic reconstruction

- The two modules are mounted on top of a portable platform, which houses also the electronics, power supply, etc...
- A rotating motor can move the source or phantom positioned in the field of view
- One of the modules can rotate wrt 180° position by $\pm 60^\circ$



Test bench for tomographic reconstruction

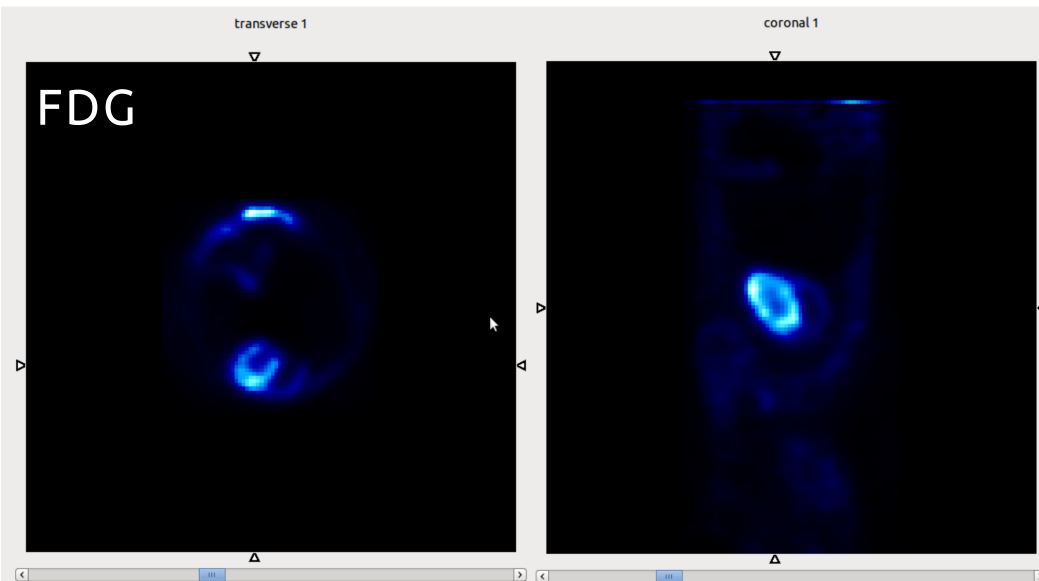
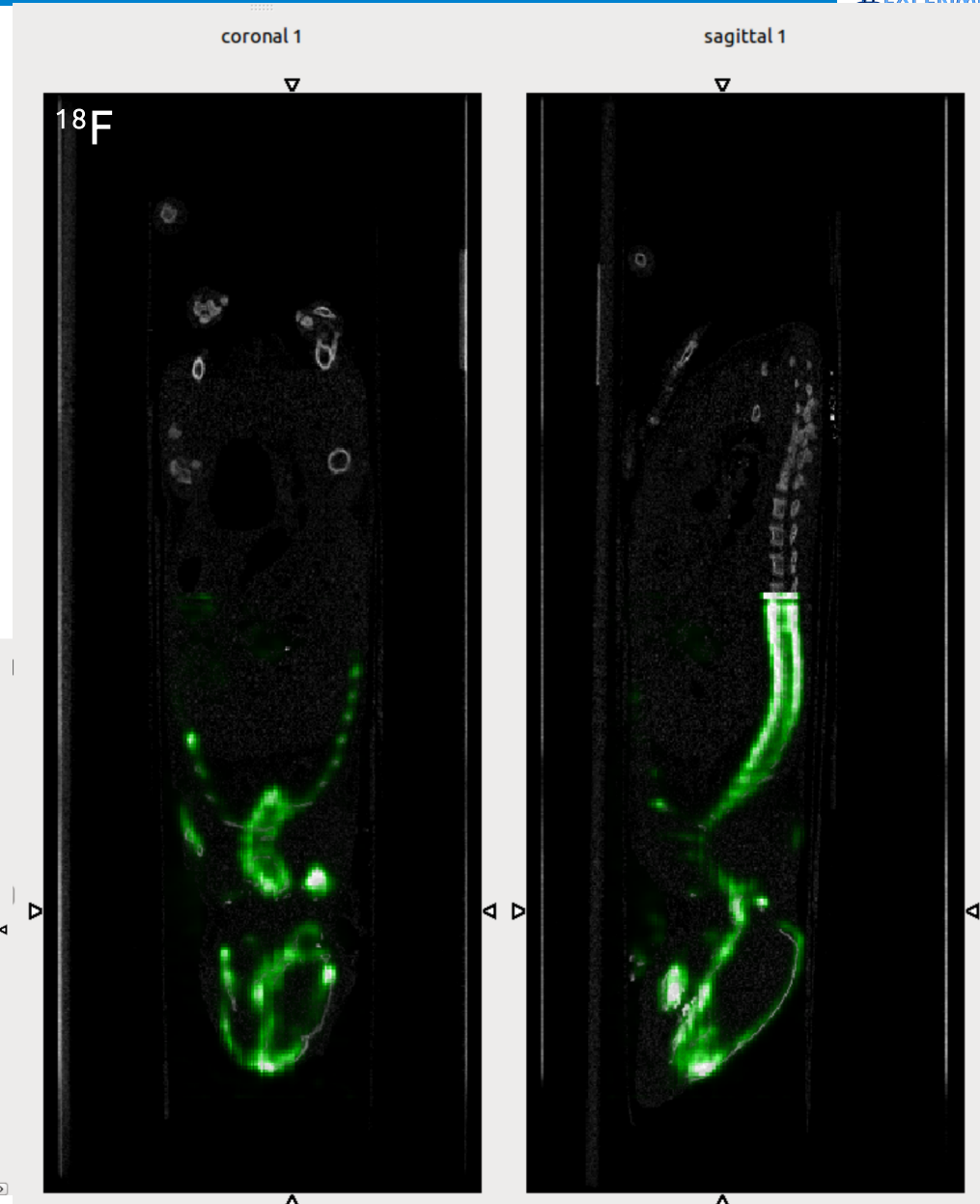
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Images from tomographic reconstruction



- Last measurement campaign done at ETH zurich on rat and mouse
- Goal : demonstrate that the AX-PET concept is capable of providing images at least as good as standard scanners (e.g ExploreVista)



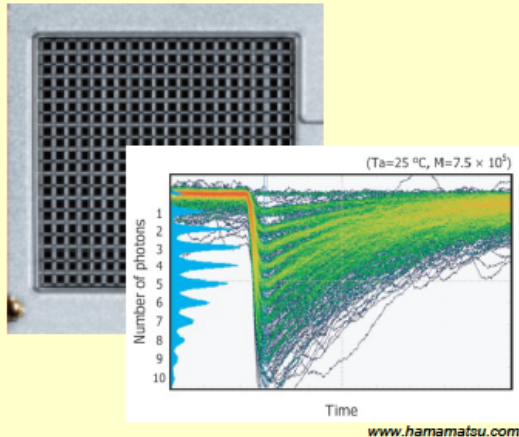
Using digital SiPM from Philips as alternative photodetectors

- extremely good timing performance
- GOAL : demonstrate the possibility a TOF-PET with the axial concept

PHILIPS

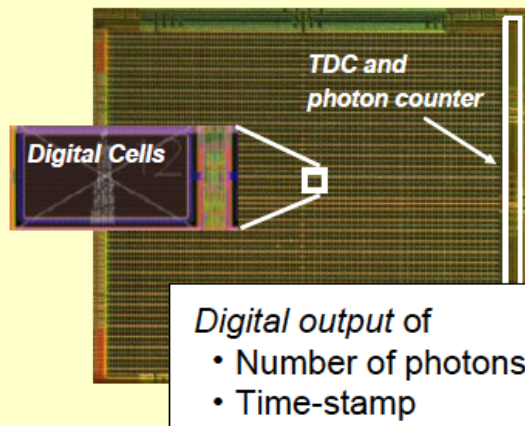
Digital SiPM – New Type of Silicon Photomultiplier

Analog SiPM



- Cells connected to common readout
- Analog sum of charge pulses
- Analog output signal

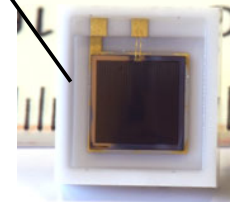
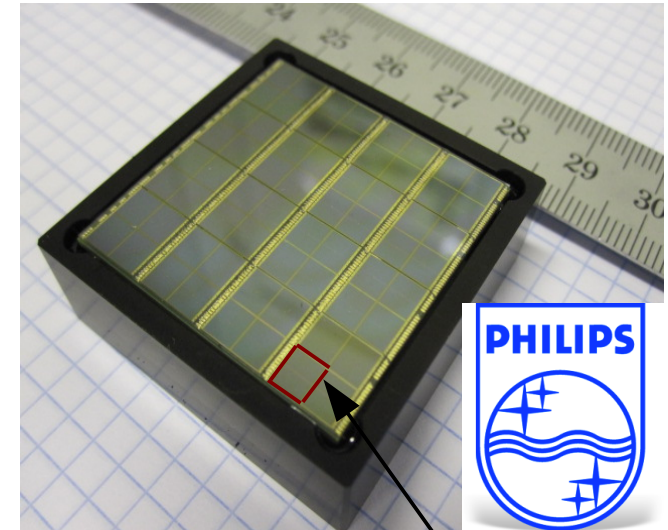
Digital SiPM



- Each diode is a digital switch
- Digital sum of detected photons
- Data packet

CERN Detector Seminar, October 21, 2011

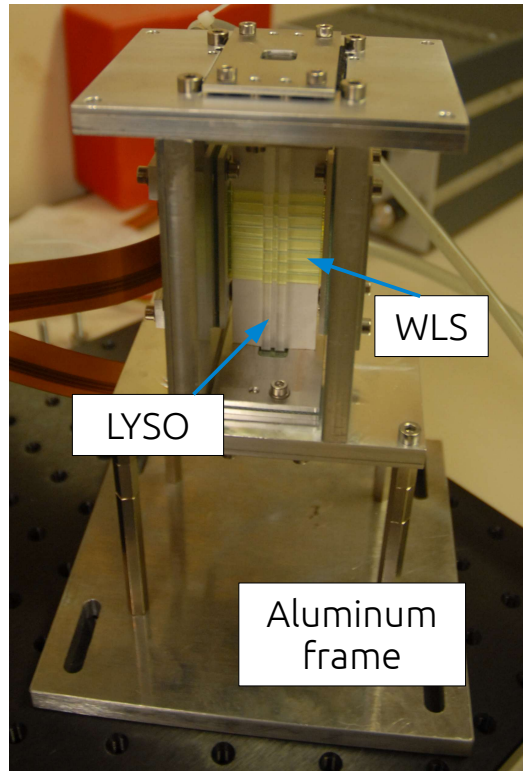
22



Still a prototype
Evaluation kit bought : **MPPC :**
3200 cells
3x3 mm²

Includes four sensors (2 with 3200 cells per detection unit, 2 with 6400 cells)

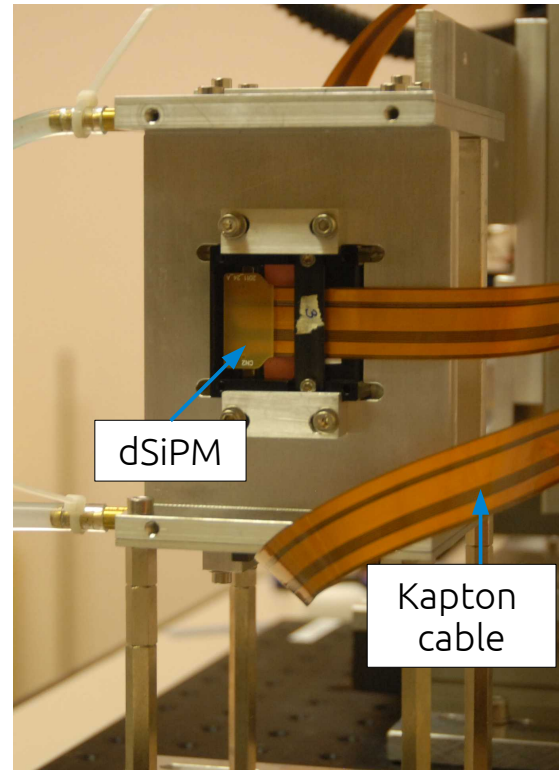
The different setup used



Test module composition :

2 layers made of :

- 2 LYSO $3 \times 3 \times 100 \text{ mm}^3$ (4.6 mm pitch)
- 8 WLS strips $3 \times 0.9 \times 40 \text{ mm}^3$ (4 mm pitch)



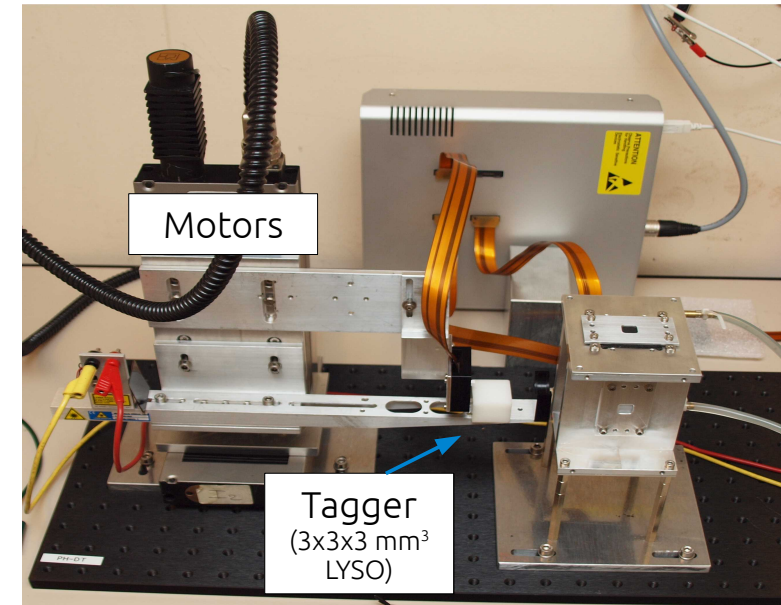
One module setup used for :

- Energy resolution
- Single module spatial resolution

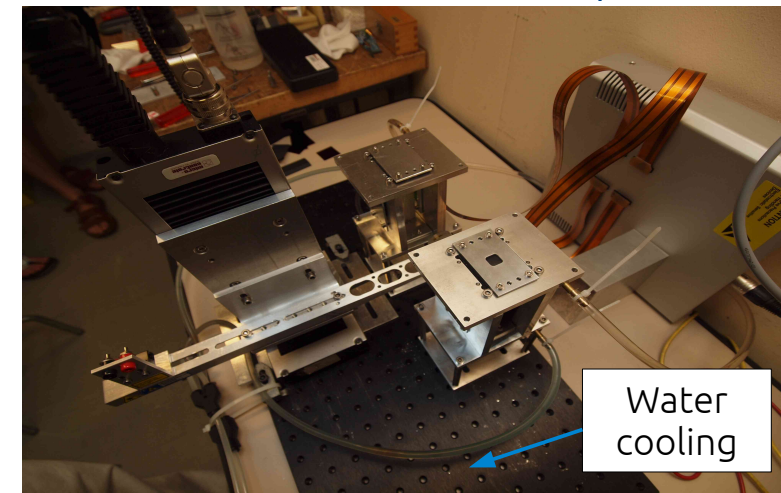
Two module setup used for :

- Spatial resolution for modules in coincidence
- Coincidence time resolution

One module setup



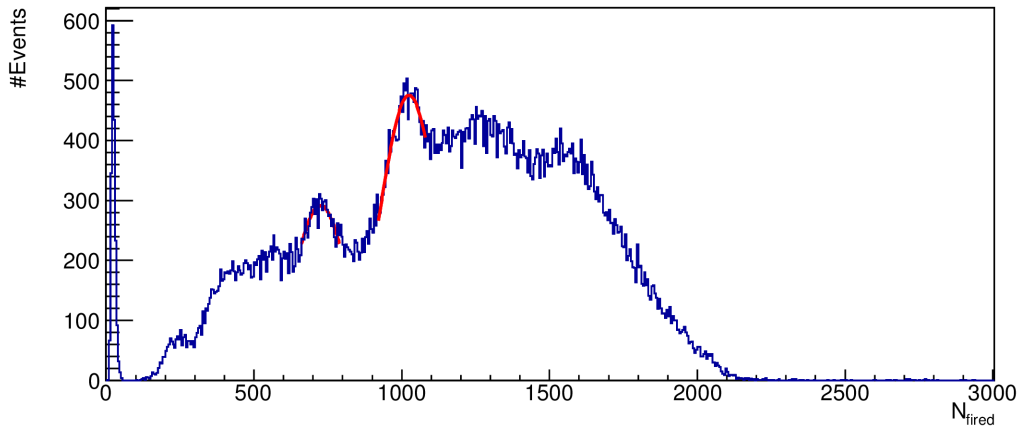
Two modules setup



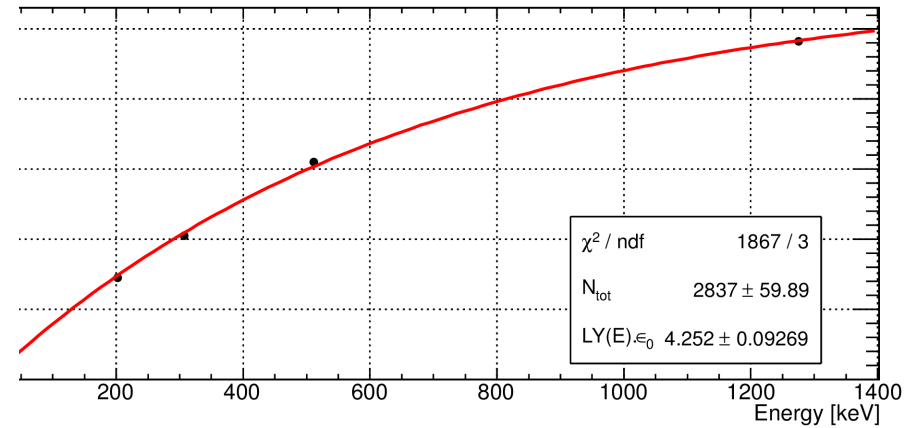
Energy resolution

$$E = N_{TOT} \left(1 - \exp \left(\frac{-N_y LY(E) \epsilon_0 (1 + XT)}{N_{TOT}} \right) \right) = N_{TOT} \left(1 - \exp \left(-\alpha \frac{N_{fired}}{N_{TOT}} \right) \right)$$

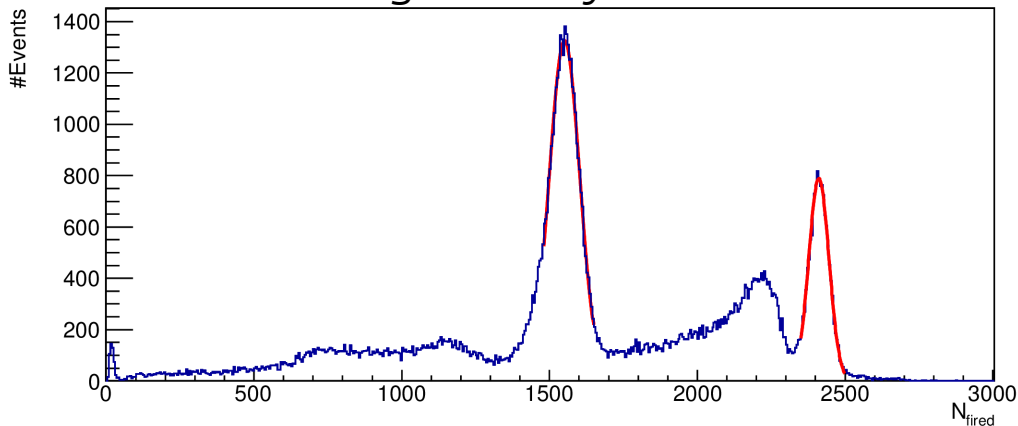
Intrinsic radioactivity



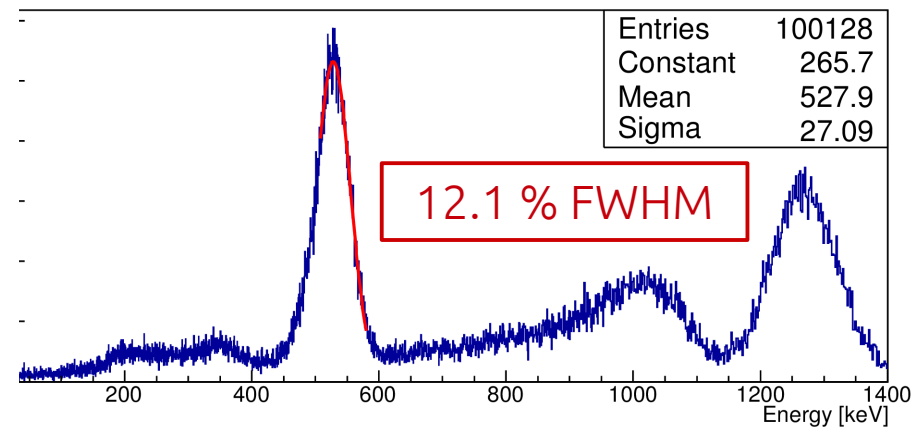
Energy Calibration [0]*(1-TMath::Exp(-x*[1]/[0]))



High activity ^{22}Na source

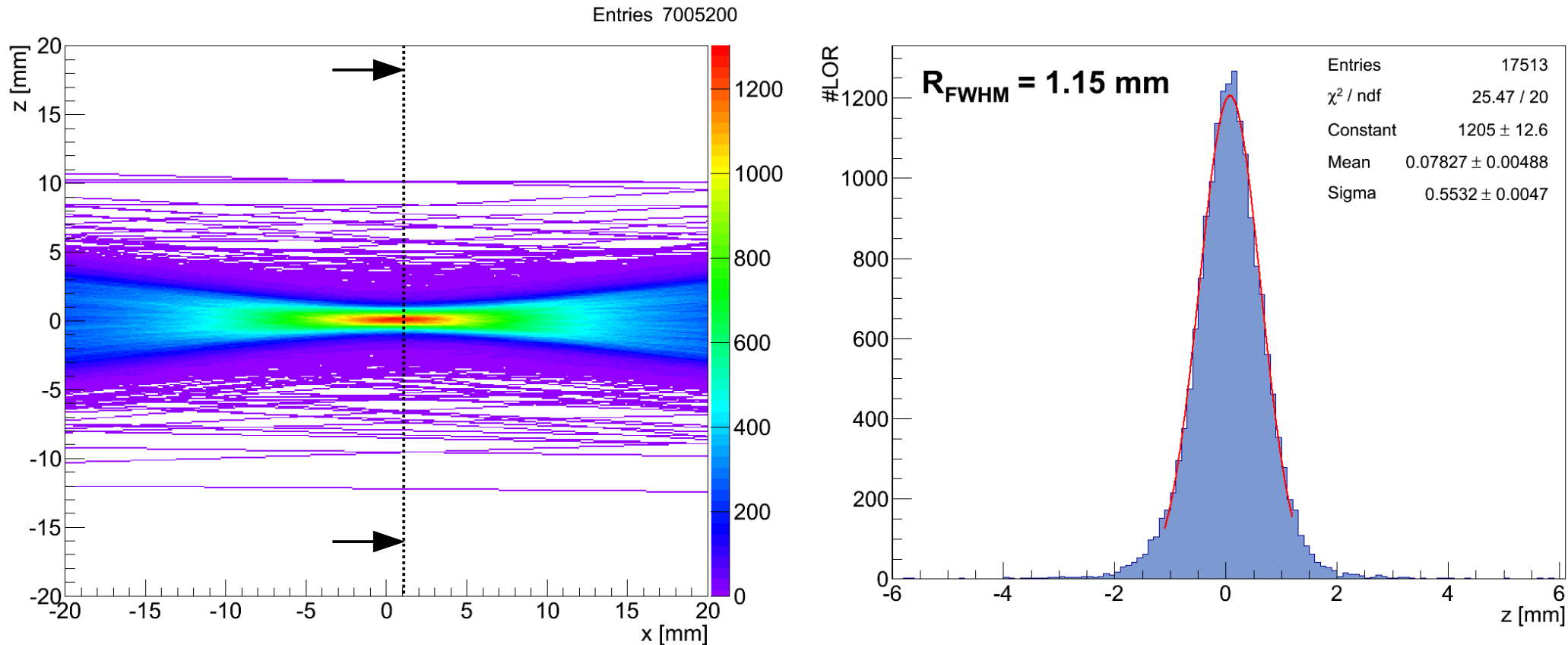


ENERGY CALIBRATED SPECTRUM



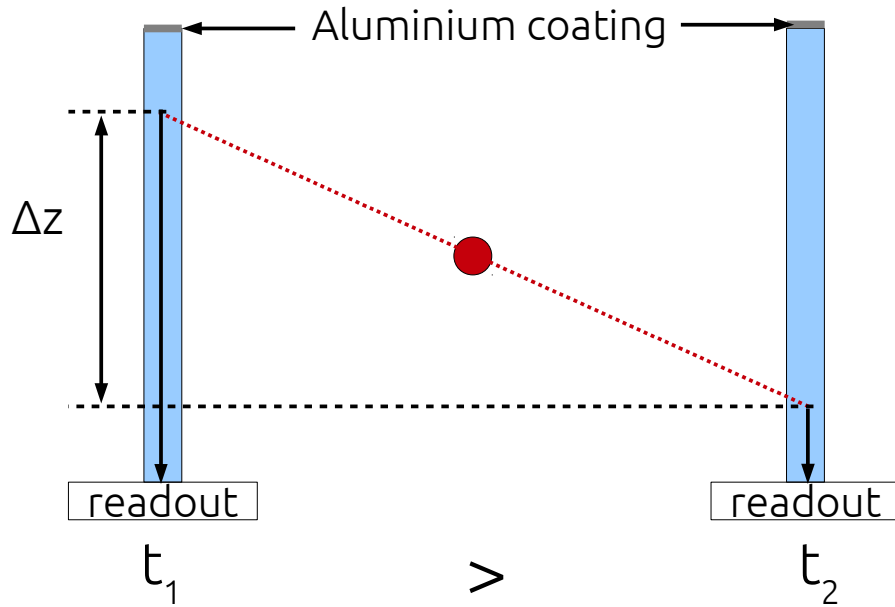
Spatial resolution

^{22}Na source of 250 microns diameter, 150 mm between the two modules

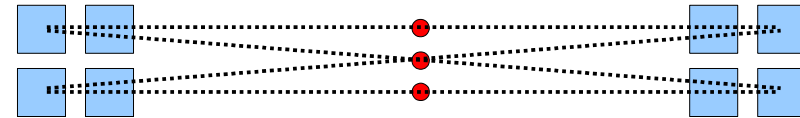


- Single module intrinsic resolution : ~ 1.6 mm FWHM
- Confocal axial resolution : 1.15 mm FWHM
- > Expected $\sqrt{2}$ factor observed between the two measurements

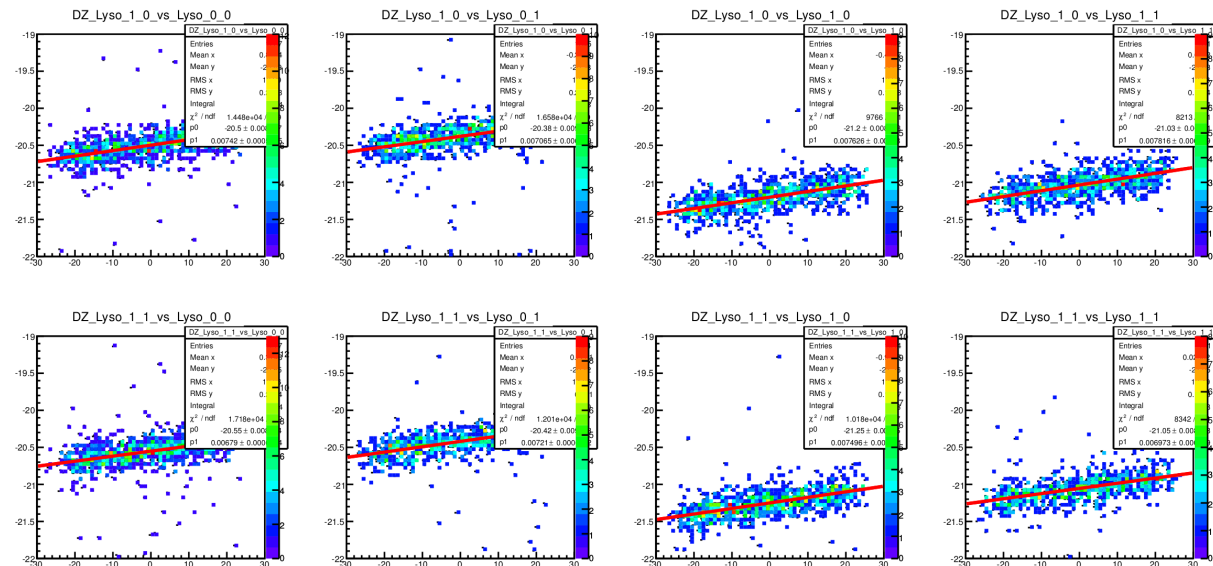
Coincidence Time Resolution Calibration for long crystals



- If the interaction happens at the same height in the crystal, the time difference between the two modules gives directly the position of the interaction (within time resolution)
- If the interaction is asymmetric, one has to correct for the light path in the two crystals.



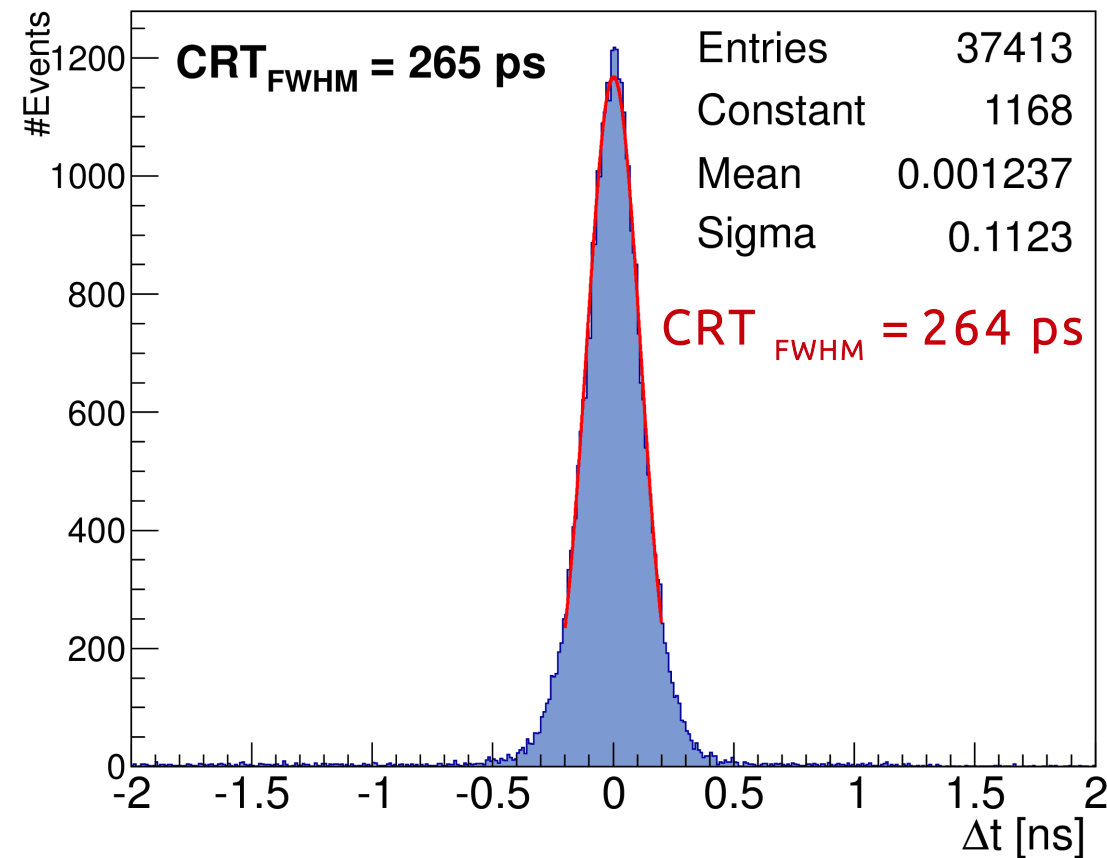
- The parametrization is done fitting the 2D distribution Δt vs. Δz
- This parametrization needs to be done for every crystal combination because all trigger networks have their own time offset



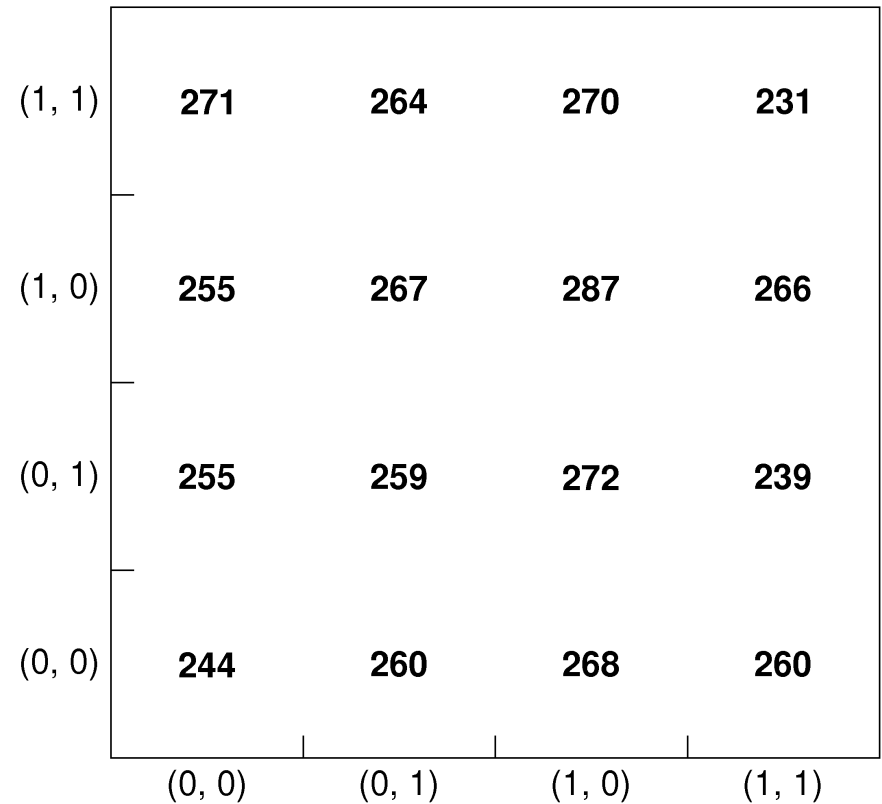
Coincidence Time Resolution



CRT FWHM [ps]

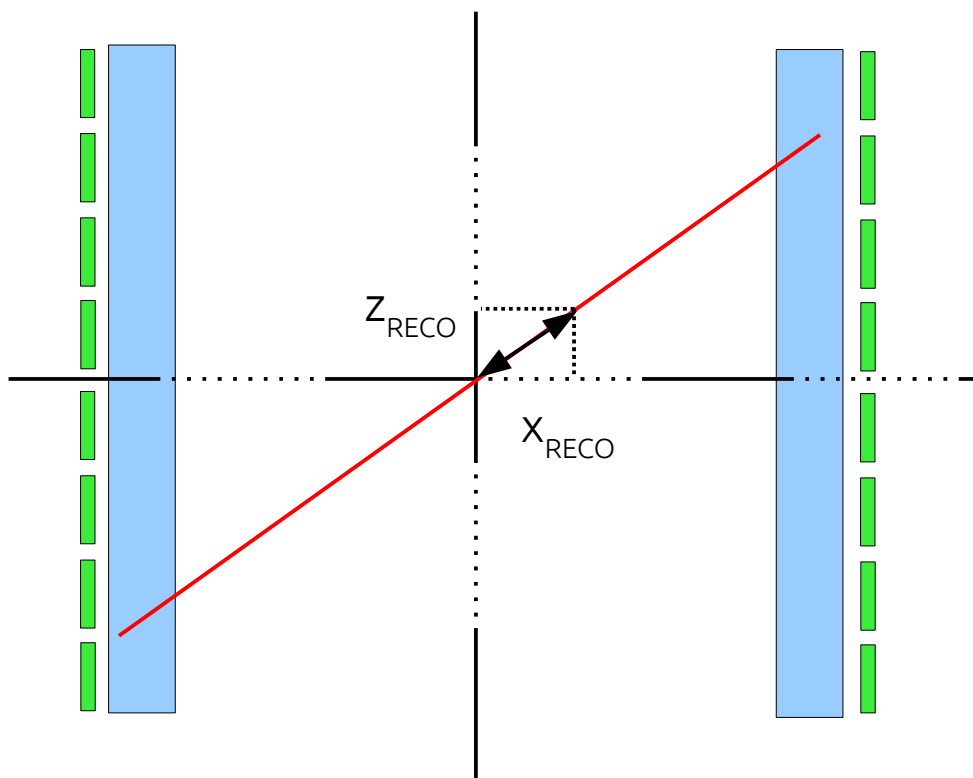


Module resolution

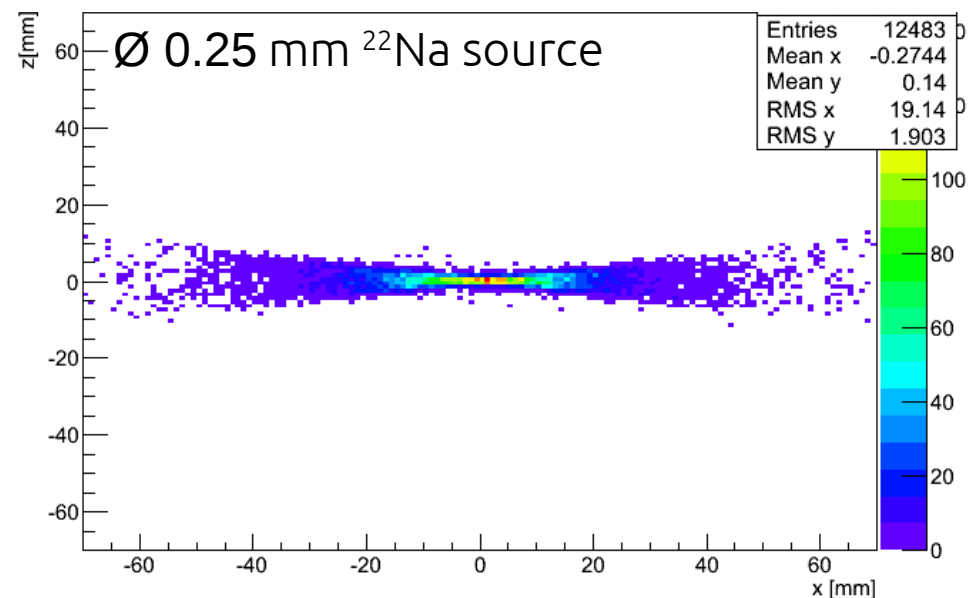
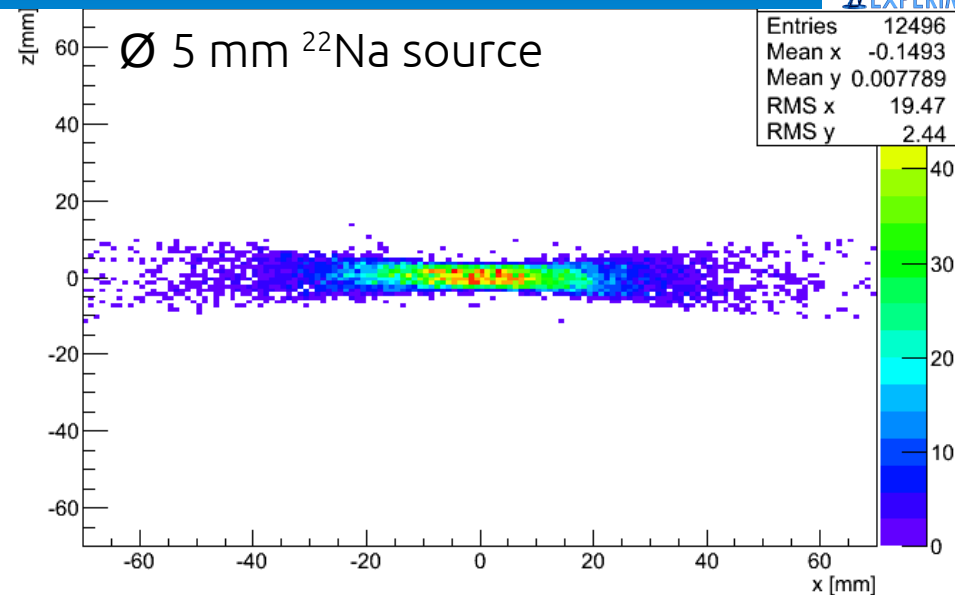


Resolution for all Lyso combinations

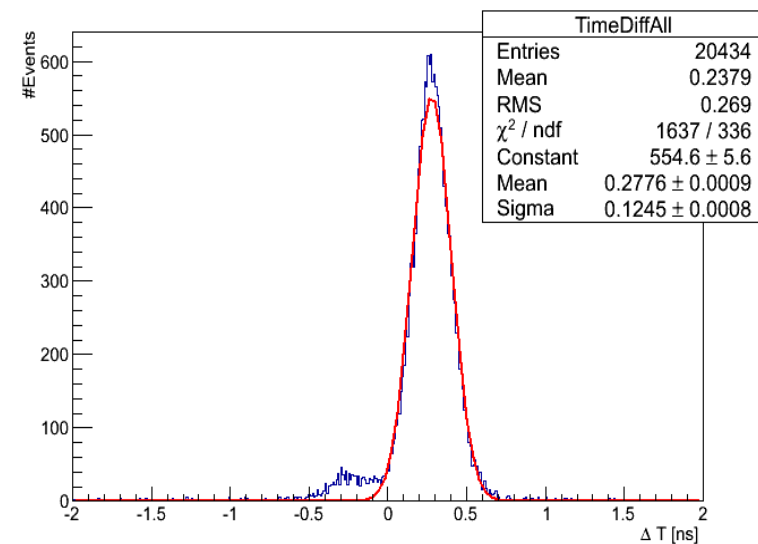
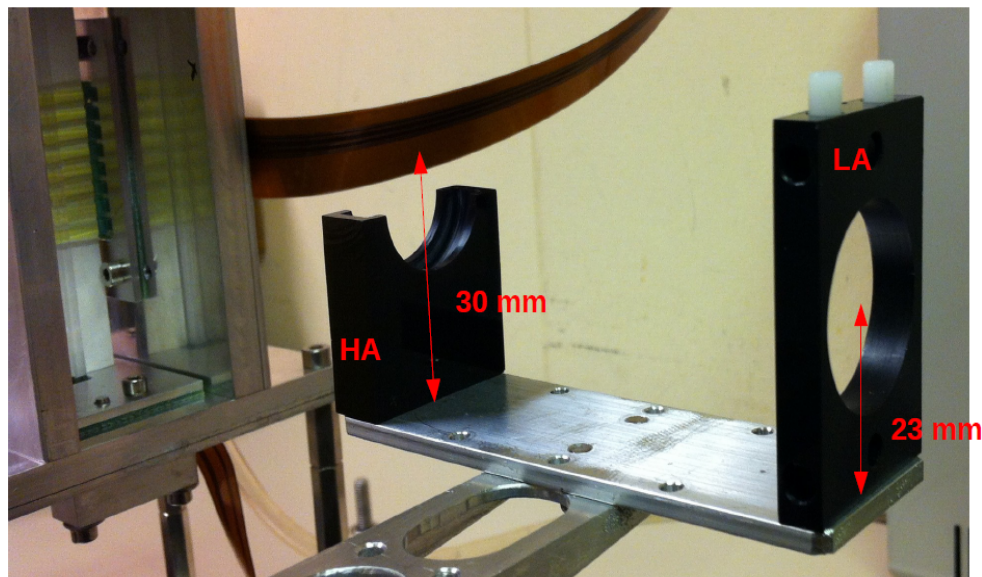
Time Of Flight reconstruction



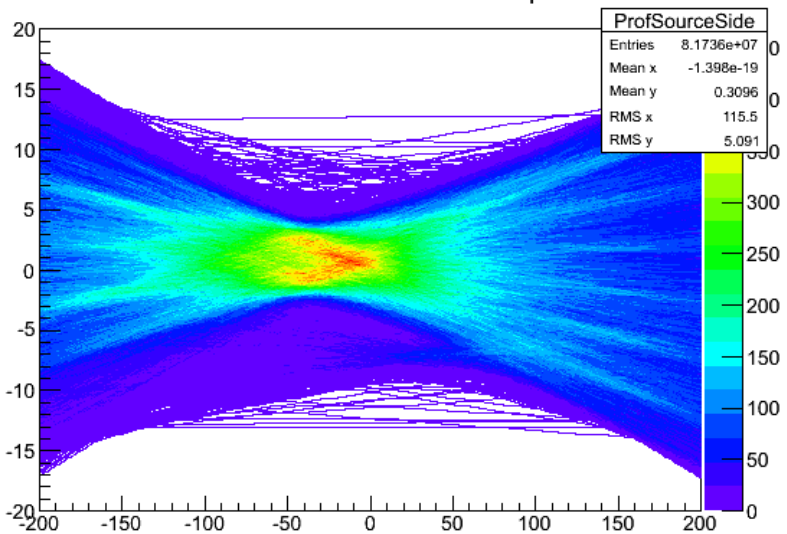
$$\Delta LOR = \frac{\Delta t * c}{2} \begin{cases} x_{reco} = \Delta LOR * \cos(\theta_{LOR}) \\ z_{reco} = \Delta LOR * \sin(\theta_{LOR}) \end{cases}$$



Time Of Flight reconstruction

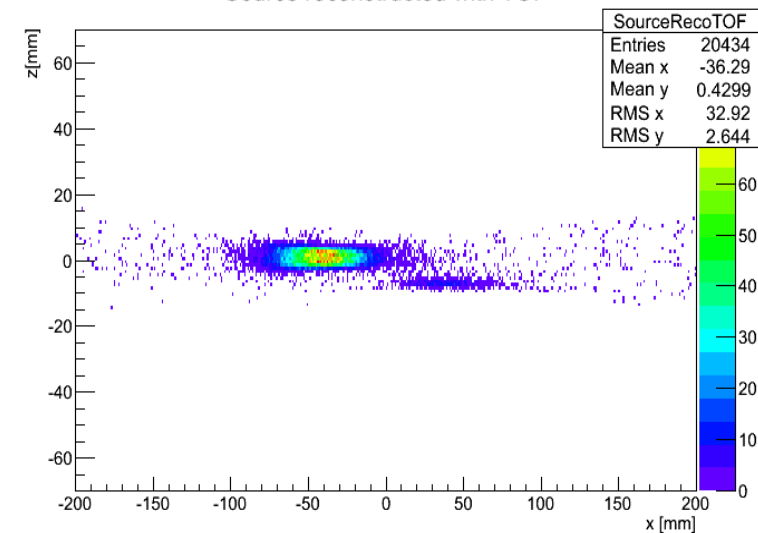


LOR distribution close to source position

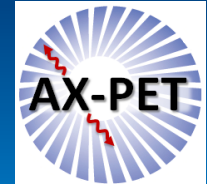


The excellent timing capabilities of the dSiPM allow to identify very clearly the low activity source, while in the simple LOR representation it is hard

Source reconstructed with TOF

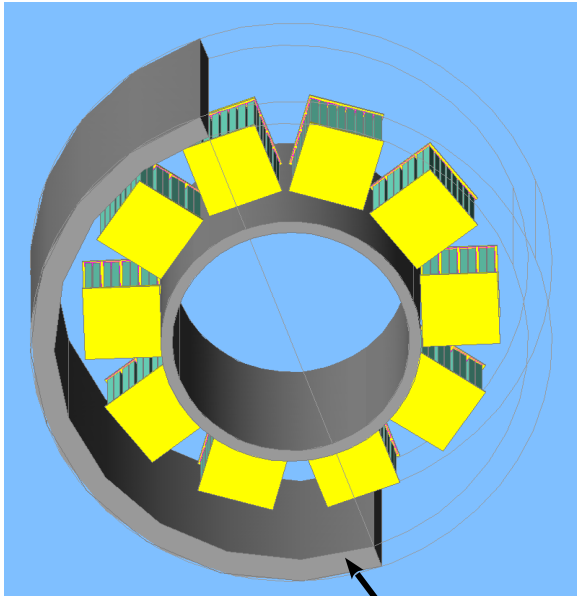


Conclusion



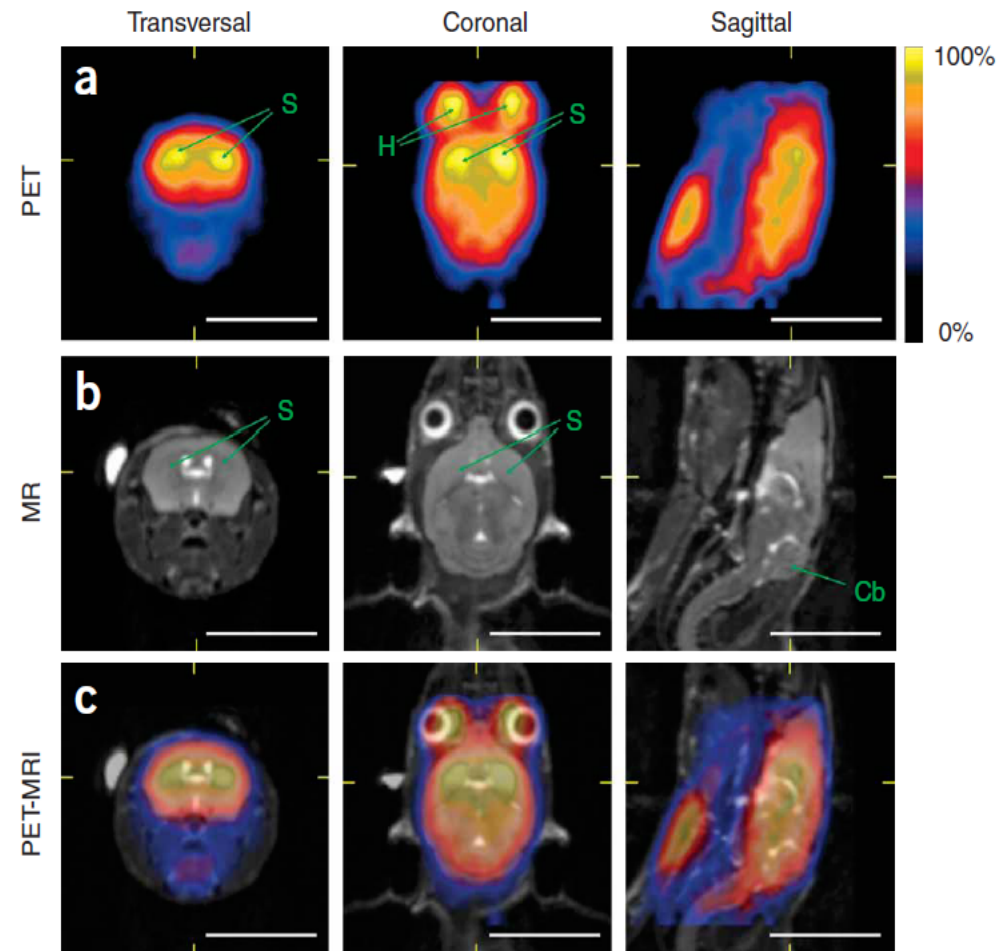
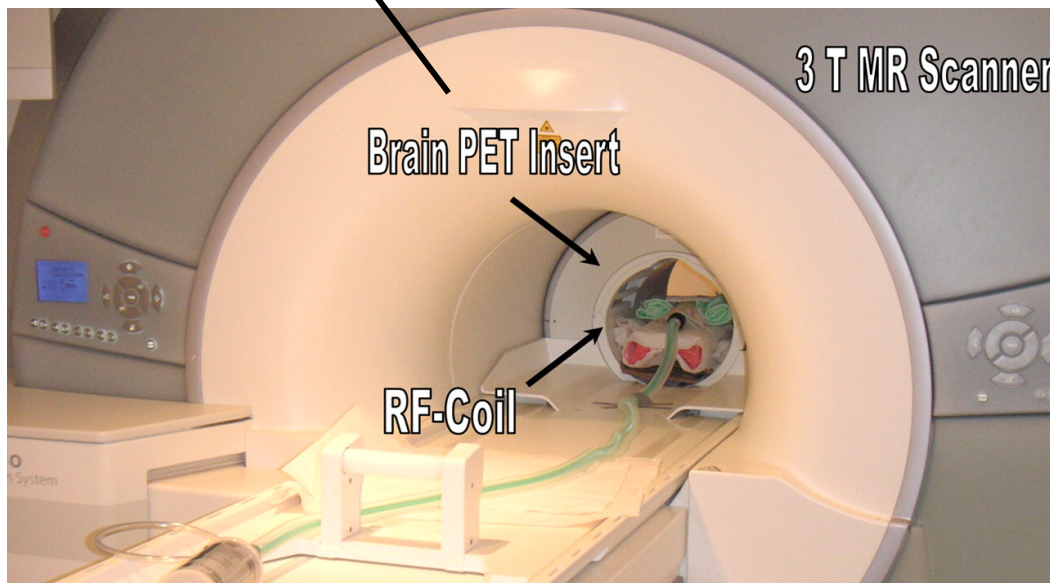
- The AX-PET demonstrator was extensively tested and so far has shown impressive capabilities for tomographic reconstruction despite its limitations
- The ultimate goal of AX-PET is not to build an entire ring. The goal was always to prove its principle and encourage people to use the concept
- Recent collaboration with Philips has opened new horizon, see next slide
- During these two years I have worked on data analysis, test campaign and more recently started at CERN the activities using the dSiPM from Philips (setup, data analysis...)

AX-PET future !!!



The axial concept provides compactness, good sensitivity and spatial resolution. Consequently it is a very good candidate for PET insert in an MRI scanner

Future collaboration with ETH zurich and Philips on the conception of an entire ring for small animal imaging



MC-PAD benefit and Future



- Wide spectrum covered during the different training events, pity that I was not in from the very beginning...
- Thanks to training events and collaborators, learnt a lot about detector physics both on a theoretical and experimental point of view
- Unfortunately no opportunity to exchange with the different members/partners except during the training events (marginal project)
- Hard to combine two very active projects ! However extremely interesting to combine fundamental and applied research, physics analysis and lab work
- Present and near future (Extended till end of February 2013) :
 - to participate to the realization of the new AX-PET project success and fortunately lead it to success
 - to publish the proton-proton total cross section and nuclear slope measurement

Thanks for you attention

Thanks to mobility funds I could attend :

- All MC-PAD training events since gaseous and photon detectors at CERN in march 2011
- EIROforum School of Instrumentation 2011 in Grenoble (Presentation of a poster on AX-PET)
- New Development In Photodetectors 2011 in Lyon (Talk on AX-PET)
- Workshop on Digital Counting Photosensors For Extreme Low Light Level in Lisboa (Talk on AX-PET)
- PhotoDET 2012 in Orsay (Talk on AX-PET)
- Chair experimental session in a school (JRJC) for the french PhD students

Measurement with phantoms

How to mimic a full ring scanner ?

➔ It depends on the Field Of View (FOV)

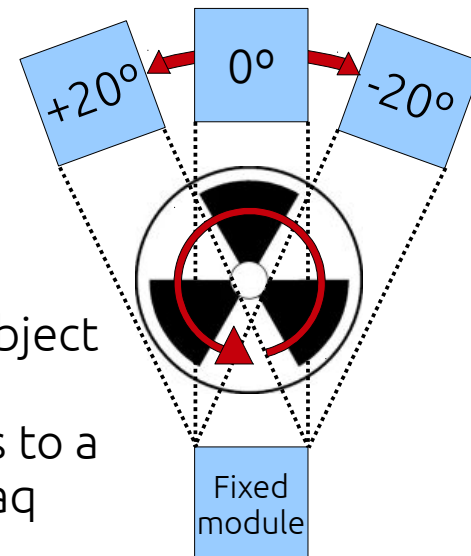
Standard FOV :

- Distance between modules 15 cm
- Modules both fixed : source rotates by 360°



Extended FOV :

- The source rotates by 360° (20° steps)
- One module fixed
- The other rotates by $+20^\circ$



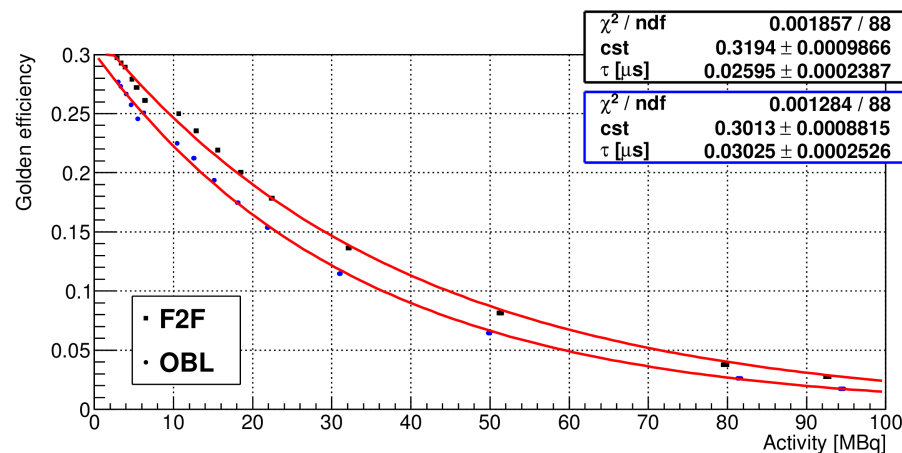
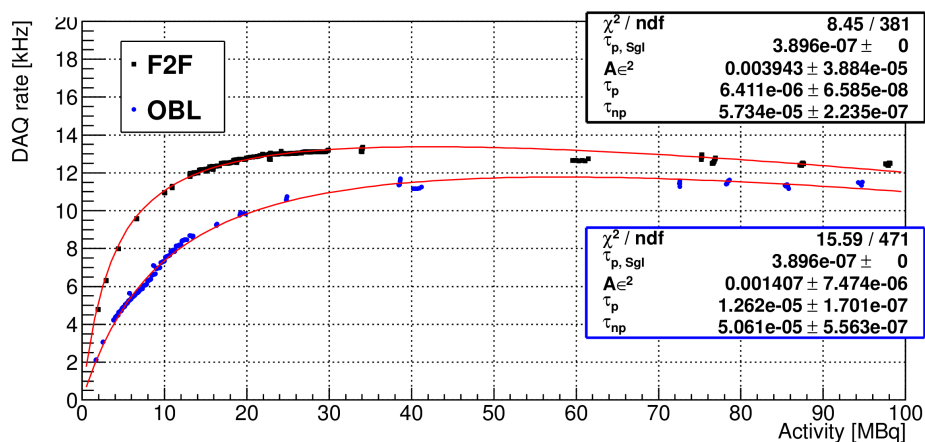
Limitations :

- The entire geometry of the scanned object is not embraced at the same time !
- The activity decay along the scan leads to a non uniform response of the system (daq rates, event selection...)

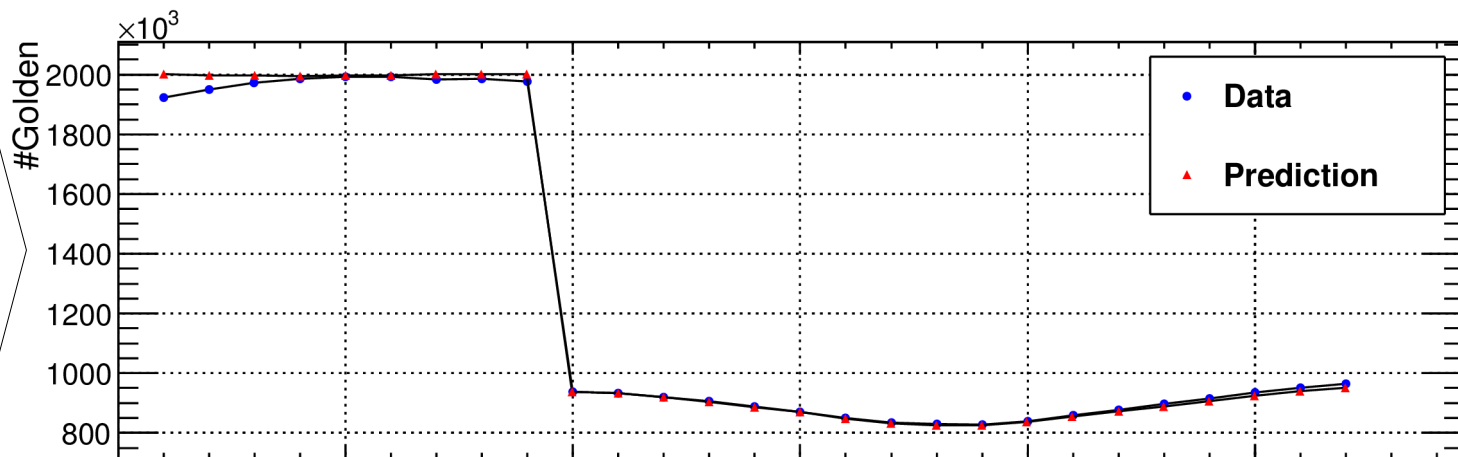
Rate prediction

How to overcome these limitations :

- Correct afterwards for source decay → can lead to lack of statistics
- In case of a performance demonstration campaign, one can anticipate all the different effects



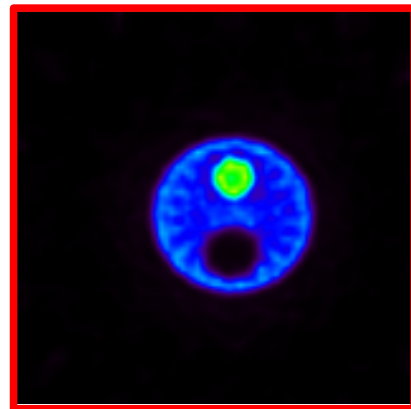
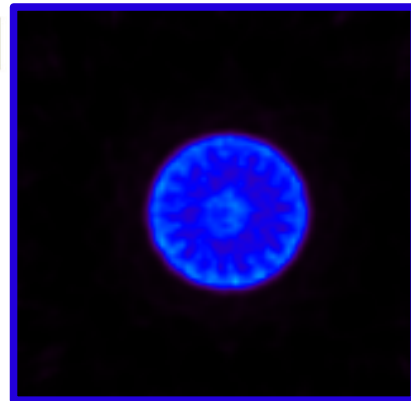
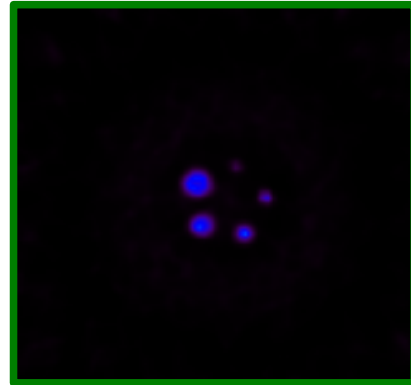
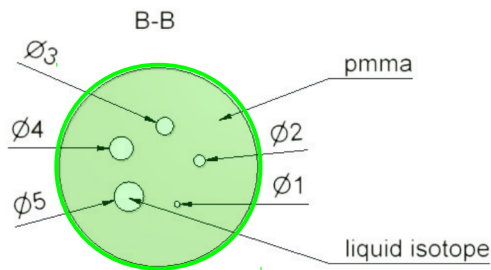
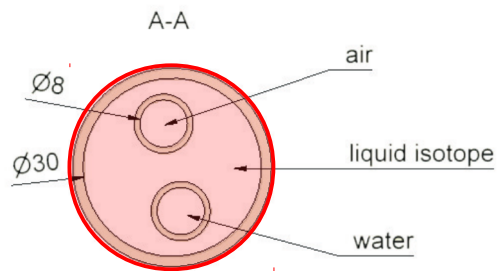
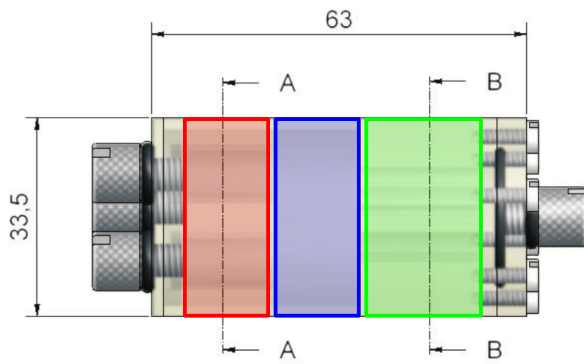
After extracting the geometry of the object in a so-called pre-scan, the number of golden events per position can be computed



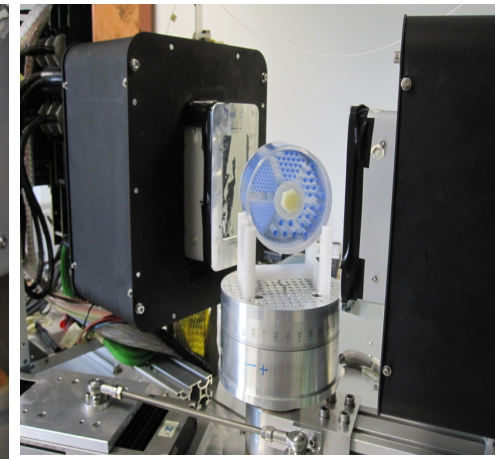
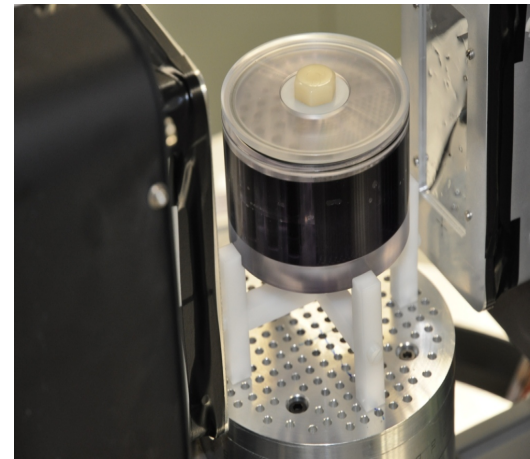
Images from tomographic reconstruction

NEMA NU4

Image Quality
Mouse Phantom

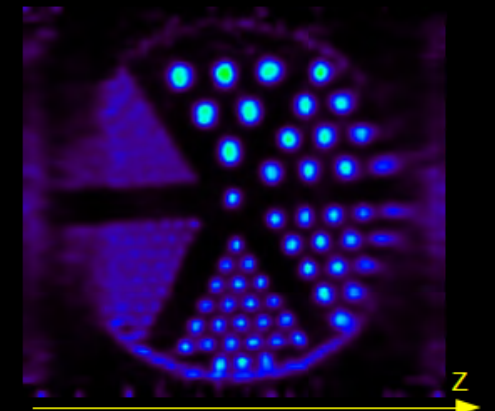
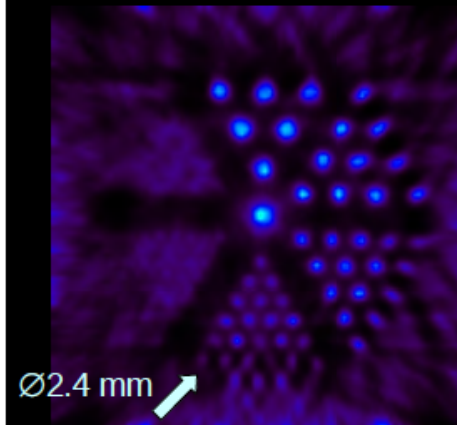


Mini deluxe



Parallel to Z axis

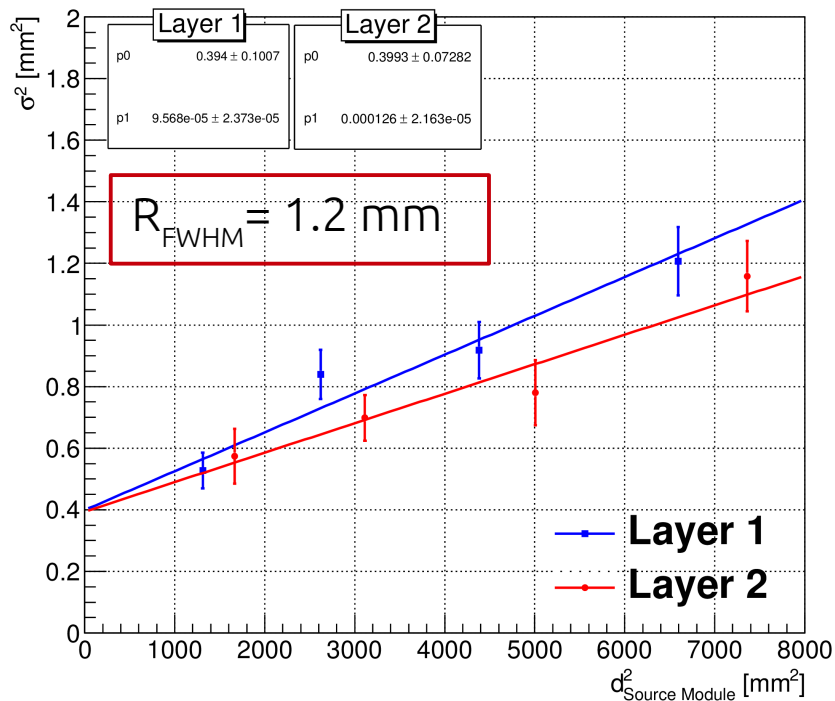
Perpendicular to Z axis



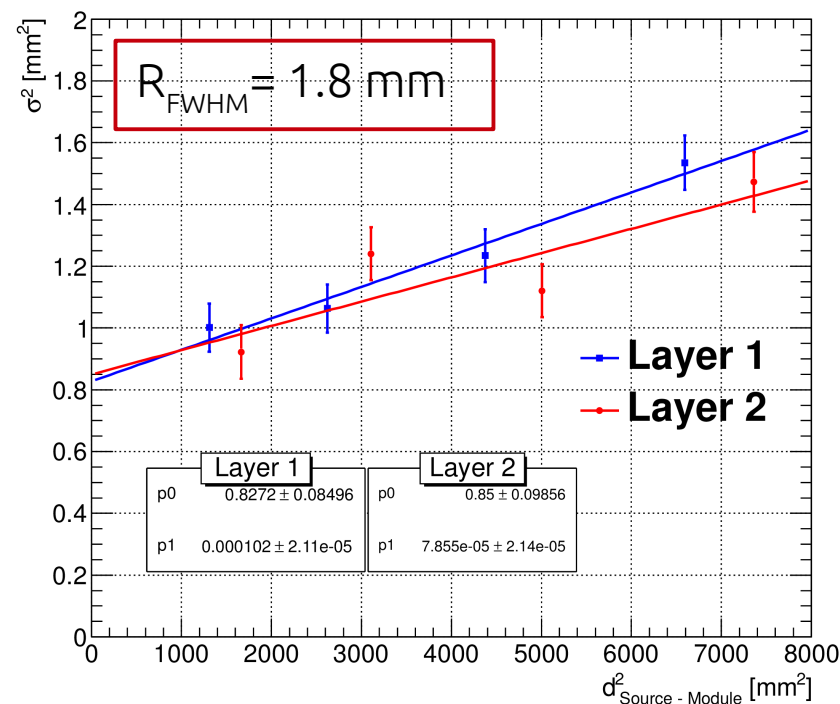
- Fixed time acquisition: 120 s /step
- 60 iterations + post-reconstruction smoothing
- No corrections
- Artefacts due to data truncation (FOV too small...)

Spatial resolution

Beam centered on one WLS strip



Beam centered between two WLS strips



• At each distances, the measured beam size is the convolution of several contribution :

- Distance dependant :
 - Beam width
 - Non-collinearity
 - Distance independant :
 - Intrinsic resolution
 - Source size
 - Finite positron range
- Cancelled by extrapolation to zero distance
- Quadratically subtracted to intercept value

