

Dynamical attractors in Boltz flow

Now as put out by Helle, Spohn etc.
the set of evolution equations

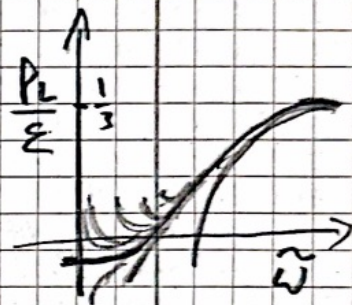
$$\partial_t \varepsilon = - \frac{\varepsilon + P_L}{\tau} \quad P_L = P + \pi^n$$

$$\partial_t \pi^n = - \frac{1}{\tau \eta} \left(\pi^n + \frac{4}{3} \frac{\eta}{\varepsilon} \right)$$

shows a remarkable feature, namely
its solutions.

By introducing a scaled new variable

$$\tilde{w} = \frac{\tau \varepsilon}{4 \pi \eta} \approx \frac{c}{\tau \omega^2}$$



the solutions exhibit stable fixed points
at both early and late times.

Hydro attractor ($\tilde{w} \gg 1$): $\frac{\pi^n}{\varepsilon} = - \frac{4}{3 \tilde{w}} + O(\tilde{w}^{-2})$

Early time attractor ($\tilde{w} \ll 1$): $\frac{\pi^n}{\varepsilon} = - \frac{2}{3} - \sqrt{\frac{4}{9} + \frac{16}{9} \frac{\eta}{\tau \omega}}$

While the late time behavior shall be explicit,
as eventually the system is expected to converge
to Navier-Stokes hydrodynamics and eventually,
therefore, the existence of an early time
attractor is suppressed, and a result of
the rapid longitudinal expansion.

Hydrodynamics, in the form of MHS equations shows us the phenomena that occur due to the interplay of anisotropic expansion and interactions in the system.

Notably, the emergence of unusual late time behavior and the possibility of partial anisotropic flow at early times, when the longitudinal expansion is dominant.

However, we don't expect hydrodynamics to accurately describe the early time dynamics, when system is highly anisotropic and subjected to strong gradients due to expansion, so we need to resort to a more microscopic description.

Kinetic theory

Description of weakly interacting QFT in terms of phase-space density of quasi-particles

$$f(x, p) \quad x = x^\mu \quad p = p^i$$

which satisfies a Boltzmann equation

$$p^\mu \partial_\mu f(x, p) - \Gamma_{\mu\nu}^i p^\mu p^\nu \frac{df}{dp^i} = C[f](x, p)$$

where the microphysics is encoded in the properties of the collision integral.

By solving the partial integro-differential equations we can then compute the evolution of the energy momentum tensor

$$T^{\mu\nu}(x) \equiv \int \frac{d^3p}{(2\pi)^3} \sqrt{-g} \frac{p^\mu p^\nu}{E_p} f(x,p)$$

||

Now in order to this we need to specify the microscopical interactions, and we will first consider the simplest possible model

Collisionless RTA:

$$C[f] = + \frac{p^\mu u_\mu}{c_R} (f - f_{eq})$$

where c_R is the Bosen

$$f_{eq} = \int_{\text{Bosen-Dirac}} \left(\frac{p^\mu u_\mu}{T} \right)$$

with u^μ and T determined self-consistently from Landau matching conditions

$$T^{\mu\nu}_v = -\epsilon u^\mu, \quad \epsilon = \frac{4\pi^2}{30} v T^4$$

which is necessary to satisfy energy-momentum conservation.

If we are interested in a conformal system, we set

$$c_R = 5 \frac{v/s}{T} \quad \text{with } v/s = \text{const}$$

Now let us adapt this description to Bjorken flow, and to do so, we first note that we are interested in

$$P_L(z) = T^{-n} \eta(z) = V \int \frac{d^2 p_\perp}{(2\pi)^2} \int \frac{d p_\parallel}{2\pi} a(z) \frac{p_\parallel^2 a(z) p_\parallel}{E_p} f(z, p_\perp, p_\parallel)$$

we see at this point, that it is more advantageous to use a different longitudinal momentum variable

$$p_\parallel = a(z) p_\parallel^z \quad p_\parallel^z = p_\parallel p_\parallel^z$$

which has dimension of momentum, and the energy-momentum tensor is given by

$$P_L(z) = T^{-n} \eta(z) = V \int \frac{d^2 p_\perp}{(2\pi)^2} \int \frac{d p_\parallel^z}{2\pi} \frac{p_\parallel^z}{E_p} f(z, p_\perp, p_\parallel^z)$$

Now lets look at the Boltzmann equation, when we need to evaluate

$$\Gamma_{\mu\nu}^i p_\mu p_\nu \frac{d f}{d p_i} = \underbrace{2}_{\text{only } i=j \text{ contributes}} (\Gamma_{z\parallel}^n + \Gamma_{\parallel z}^n) p_\parallel^z p_\parallel^z \frac{d f}{d p_\parallel^z} = 2 \frac{d}{d z} p_\parallel^z p_\parallel^z \frac{d f}{d p_\parallel^z}$$

now if we want to change coordinates from p_\parallel^z to $p_\parallel = a(z) p_\parallel^z$ we also need to consider that two derivatives at constant p_\parallel^z are different than two derivatives at constant p_\parallel

$$p_\mu p_\nu \frac{d f}{d p_i} = p_\parallel^z \frac{d f}{d z} \Big|_{p_\parallel^z} = p_\parallel^z \frac{d f}{d z} \Big|_{p_\parallel} + p_\parallel^z \frac{d p_\parallel}{d z} \Big|_{p_\parallel} \frac{d f}{d p_\parallel} \Big|_{p_\parallel} = p_\parallel^z \frac{d f}{d z} \Big|_{p_\parallel} + \frac{d p_\parallel}{d z} p_\parallel^z \frac{d f}{d p_\parallel} \Big|_{p_\parallel}$$

which partially cancels against the other terms

Collecting every thing, we have for generalized System flow

$$\partial_{\bar{z}} f = \underbrace{\frac{\dot{a}}{a} p_{||} \partial_{p_{||}} f}_{\text{lasti expression}} + \underbrace{C[\bar{z}]}_{\text{interactions}} \stackrel{RS4}{=} \frac{1}{\bar{c}} p_{||} \frac{\partial f}{\partial p_{||}} - \frac{1}{\bar{c}_R} (f - f_0)$$

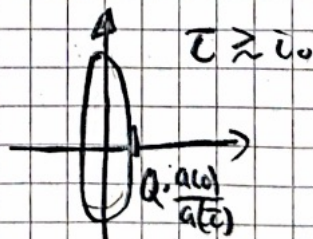
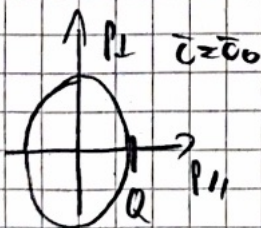
Now for System flow $\frac{\dot{a}}{a} = \frac{1}{\bar{c}}$ and the expression dominates at early times. ($\bar{z} \ll \bar{z}_{ii}$), if for the moment we neglect the interactions term, we can obtain an analytic solution to free-streams

Free-Streams: $\partial_{\bar{z}} f(\bar{z}, p_{\perp}, p_{||}) = \frac{\dot{a}}{a} p_{||} \frac{\partial}{\partial p_{||}} f(\bar{z}, p_{\perp}, p_{||})$

We can solve this by the method of characteristics to get

$$f(\bar{z}, p_{\perp}, p_{||}) = f_0\left(p_{\perp}, \frac{p_{||} \cdot a(\bar{z})}{a(\bar{z}_0)}\right)$$

which indicates, that the distribution remains unchanged w.r.t to p_{\perp} as there are no interactions, but gets squeezed in the longitudinal direction



Since the longitudinal pressure measures the width of the distribution in $p_{||}$, this leads to a rapid reduction of p_{\perp}

If we consider for Bohm flow $a(\tau) = \tau$

$$P_L(\omega) = T_{\eta}^{-1}(\tau) = v \int \frac{dp_{\perp}}{(2\pi)^2} \int \frac{dp_{\parallel}}{2\pi} \frac{p_{\parallel}^2}{\sqrt{p_{\perp}^2 + p_{\parallel}^2}} f_0(p_{\perp}, p_{\parallel} \frac{c}{\omega})$$

we can change variables to $p_{\parallel}^0 = p_{\parallel} \frac{c}{\omega}$

$$\approx \left(\frac{c}{\omega}\right)^3 v \int \frac{dp_{\perp}}{(2\pi)^2} \int \frac{dp_{\parallel}^0}{2\pi} \frac{p_{\parallel}^0{}^2}{\sqrt{p_{\perp}^2 + \frac{\omega^2}{c^2} p_{\parallel}^0{}^2}} f_0(p_{\perp}, p_{\parallel}^0)$$

$$\approx \left(\frac{c}{\omega}\right)^3 v \int \frac{dp_{\perp}}{(2\pi)^2} \int \frac{dp_{\parallel}^0}{2\pi} \frac{p_{\parallel}^0{}^2}{p_{\perp}} f_0(p_{\perp}, p_{\parallel}^0)$$

If already initially $p_{\parallel}^0 \ll p_{\perp}$ for typical excitations then

$$\approx \left(\frac{c}{\omega}\right)^3 P_L(\omega)$$

irrespective of this behavior, the logarithmic power decays rapidly and

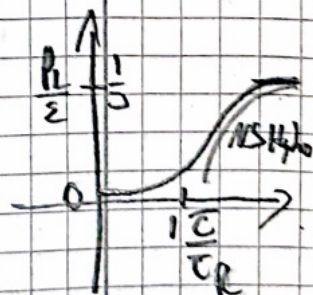
early time attractor: $P_L = 0 + O\left(\frac{c}{\omega}\right)$

Conversely for $\tau \gg \bar{\tau}_{\text{in}}$ instabilities start to play an important role, and for $\tau \gg \bar{\tau}_{\text{out}}$ dominate the dynamics of the system.

Since instabilities drive $f \rightarrow f_{\text{eq}}$, in this regime, we find

late time attractor $P_L = P_L^{\text{eq}} + O\left(\frac{\tau_{\text{eq}}}{\tau}\right)$

where the constants correspond to the usual hydrodynamic expansion



Dynamical attractors beyond system flow

Now to understand better the concept of attractors consider a situation, where instead of system expansion the system is periodically driven

$$a(t) = 1 + \alpha \sin(\Omega t) \theta(t)$$

Such that at $t=0$ space starts to periodically expand and compress, and we can independently control

α magnitude of perturbation
 \downarrow rate of expansion

Since the expansion will drive the system out of equilibrium, the near equilibrium regime, where hydrodynamics is applicable and accurate is given by

$$\text{Hydro regime: } \alpha \ll 1, \quad \int \dot{c}_{ii} \ll 1$$

i.e. response to small perturbations on long time scales compared to dynamics of the system.

Nevertheless, we can obtain analytic solutions for $\alpha \ll 1$ and any $\int \dot{c}_{ii}$.

Solution in MFS Hydro

We have for the longitudinal component $\pi = \bar{\pi}^n$, of the shear stress.

$$\partial_t \pi = -\frac{1}{\epsilon_\pi} (\pi - \pi_{ns})$$

$$\text{where } \pi_{ns} = -\frac{4}{3} \eta \frac{\dot{a}}{a}$$

Such that for weak perturbations

$$\frac{\dot{a}}{a} \stackrel{\text{dec}}{\approx} \dot{a} = \alpha \Omega \cos(\Omega t) \theta(t)$$

so we need to solve the ODE

$$(1 + \epsilon_\pi \partial_t) \pi = -\frac{4}{3} \eta \alpha \Omega \cos(\Omega t)$$

In principle this is straight-forward to solve, e.g. by Laplace transform; however to illustrate the structure of the solutions, it is more insightful to consider the perturbations as a collection of Fourier modes

$$a(t) = \int \frac{d\omega}{2\pi} a(\omega) e^{-i\omega t}$$

$$\text{where } a(\omega) = \frac{\alpha}{2} \left[\frac{1}{\omega + \Omega + i\epsilon} - \frac{1}{\omega - \Omega + i\epsilon} \right]$$

with the $i\epsilon$ prescription to obtain the $\theta(t)$ dependence.

In Fourier-space

$$-i\omega a(\omega) = -i\omega a(\omega)$$

and we obtain

$$(1 - i\omega\tau_{\pi}) \Pi(\omega) = + \frac{4}{3} \eta i\omega a(\omega)$$

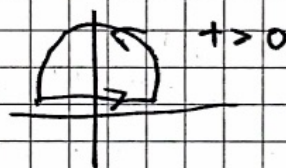
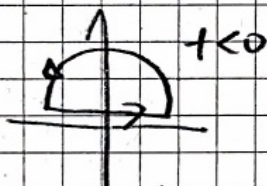
such that, we can obtain the Green's function

$$G(\omega) = \frac{\partial \Pi(\omega)}{\partial a(\omega)} = \frac{4}{3} \eta \frac{i\omega}{1 - i\omega\tau_{\pi}}$$

which we can use to determine the response to an arbitrary perturbation according to

$$\Pi(t) = \int \frac{d\omega}{2\pi} G(\omega) a(\omega) e^{-i\omega t}$$

When computing the frequency integral, we can use the residue theorem, and close the contour.



the singularities of G and a now determine the structure of the solution, i.e. for $t < 0$ no singularity is enclosed, whereas for $t > 0$, we

get two singularities at $\omega = \pm i\Omega - \Gamma/2$ from a and one singularity at $\omega = -i/\tau_{\pi}$ from G

such that the solution is a combination of oscillating and exponentially decaying behavior

One finds for sinusoidal perturbation

$$\Pi = \frac{-\frac{4}{3}\eta\beta\alpha \left[\cos(\Omega t) + \beta\bar{\sigma}_{11} \sin(\Omega t) - e^{-t/\tau_{\Pi}} \right]}{1 + \beta^2 \bar{\sigma}_{11}^2}$$

if we also consider an initial stress $\Pi(t=0) \neq 0$
we get an extra contribution

$$+ \Pi(t=0) e^{-t/\tau_{\Pi}}$$

which is the homogeneous solution of the linear ODE.

Now we can describe the characteristic behavior of the solution;

Early times: $t \lesssim \tau_{\Pi}$ transient decay of $e^{-t/\tau_{\Pi}}$ term
associated with initial shear stress
and non-hydrodynamic modes
corresponding to poles of $G(\omega)$

Late times: $t \gg \tau_{\Pi}$ Universal time dependence
of $\Pi(t)$ for different
initial conditions

Hydro attractor:
$$\Pi(t) = \frac{-\frac{4}{3}\eta\beta\alpha \left[\cos(\Omega t) + \beta\bar{\sigma}_{11} \sin(\Omega t) \right]}{1 + \beta^2 \bar{\sigma}_{11}^2}$$

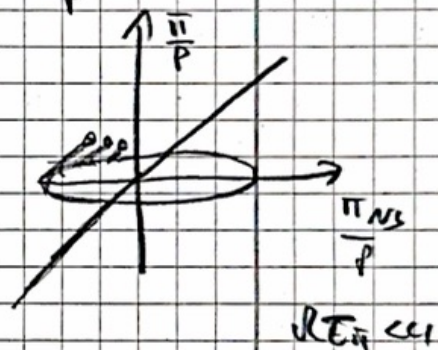
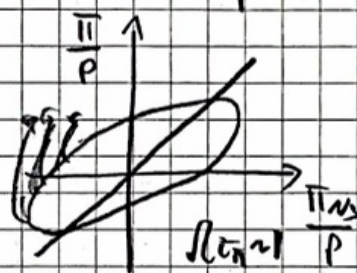
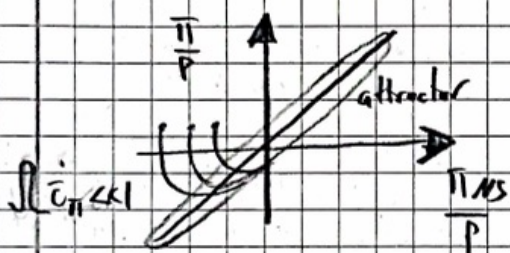
Now in the hydrodynamic limit $Re_{\Omega} \ll 1$

$$\Pi(t) \approx -\frac{4}{3} \eta R \alpha \cos(\Omega t) = \Pi_{NS}(t)$$

reduces to first order hydrodynamics, and the system is in steady state close to equilibrium.

Hence the dynamic attractor emerges also for $Re_{\Omega} \gg 1$, when it shows significant deviations from equilibrium / Navier-Stokes hydrodynamics

We can illustrate this by plotting $\frac{\Pi}{P}$ vs $\frac{\Pi_{NS}}{P}$



while for $Re_{\Omega} \ll 1$ the system remains close to equilibrium, for large $Re_{\Omega} \gg 1$ it is unable to follow the rapid expansion, the late time behavior is universal, but quite different from ordinary Navier-Stokes hydro

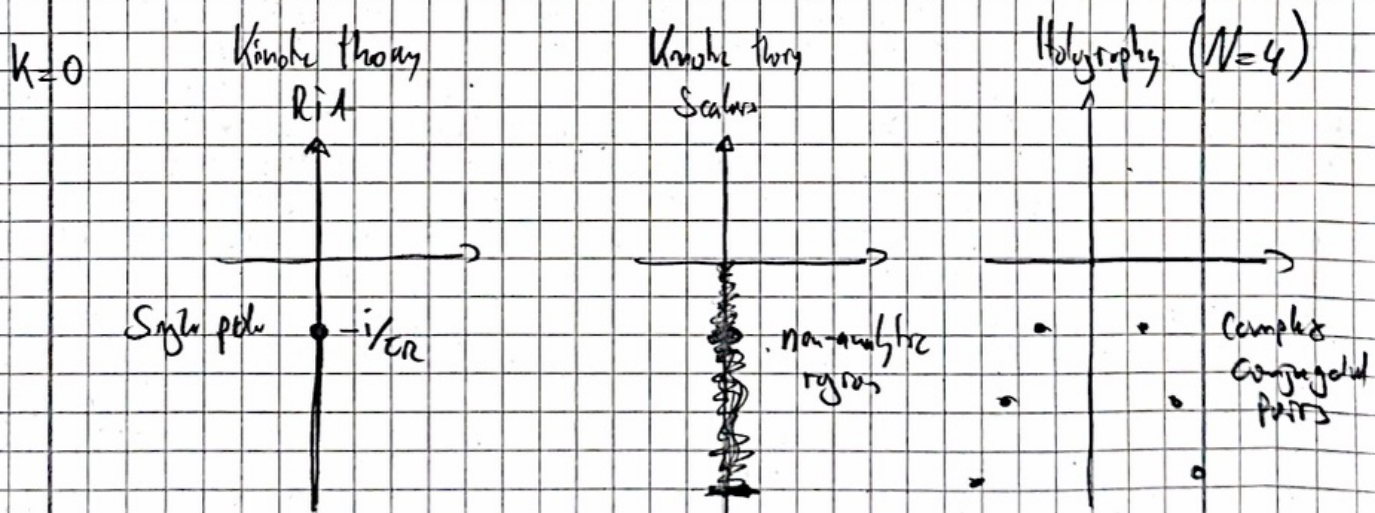
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We know from that hydrodynamic attractors

- describe long time evolution of non-equilibrium system
- emerge after decay of transients ($t \rightarrow \infty$) as described by poles of retarded Green's function $G(\omega)$ of the energy momentum tensor

While in MIS Hydrodynamics, the structure of $G(\omega)$ is rather simple, with a single pole on the imaginary axis, the investigation of their structure in microscopic theories is an area of active investigation

Generally stability limits singularities so in the lower complex half plane, however the structure can be different for different microscopic theories



Note that if spatial dependence (e^{ikx}) is also taken into account situation becomes significantly more complex