

Master thesis internship

Flavour tagging

Primary Vertex identification

using advanced deep machine learning techniques

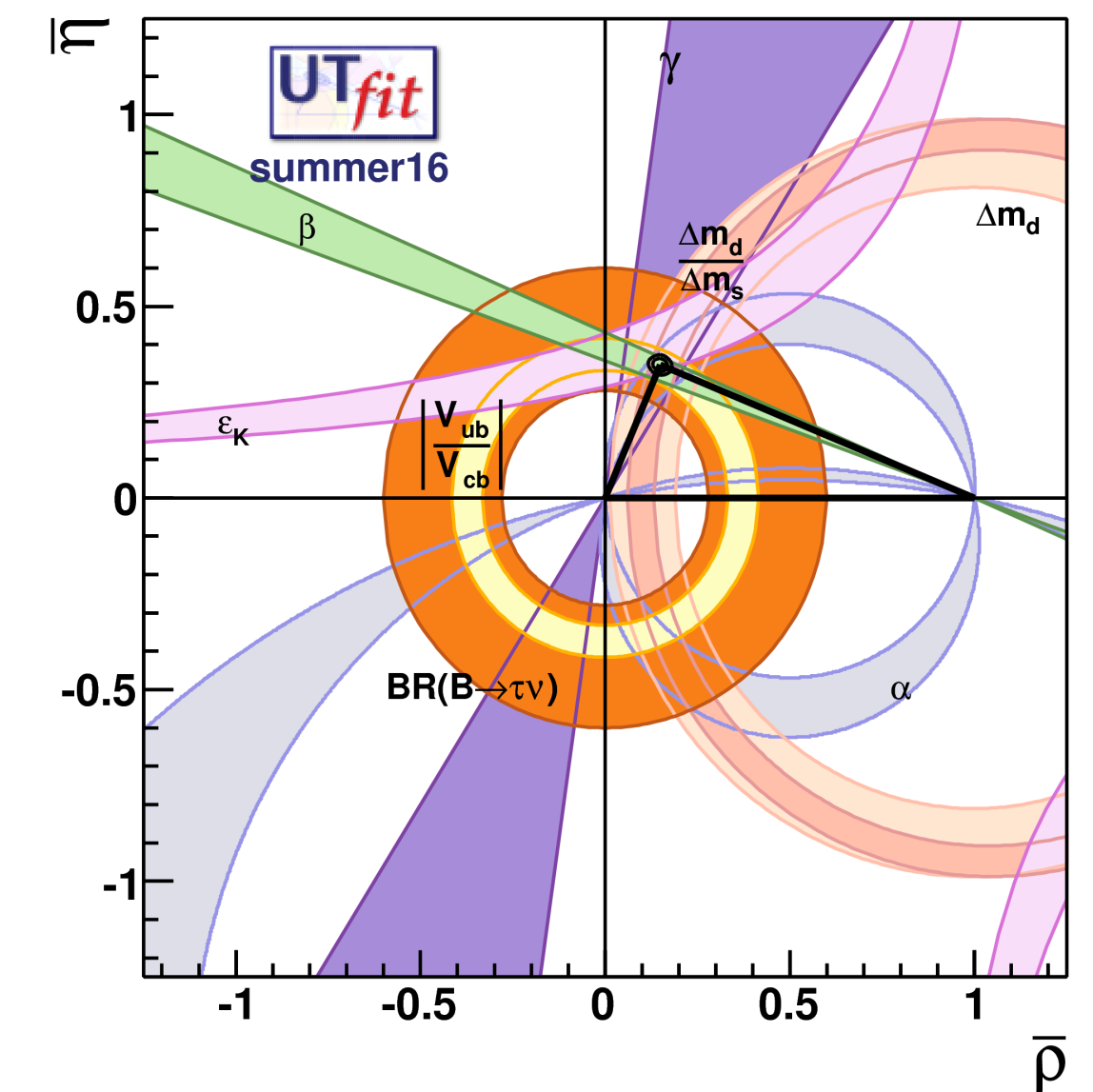
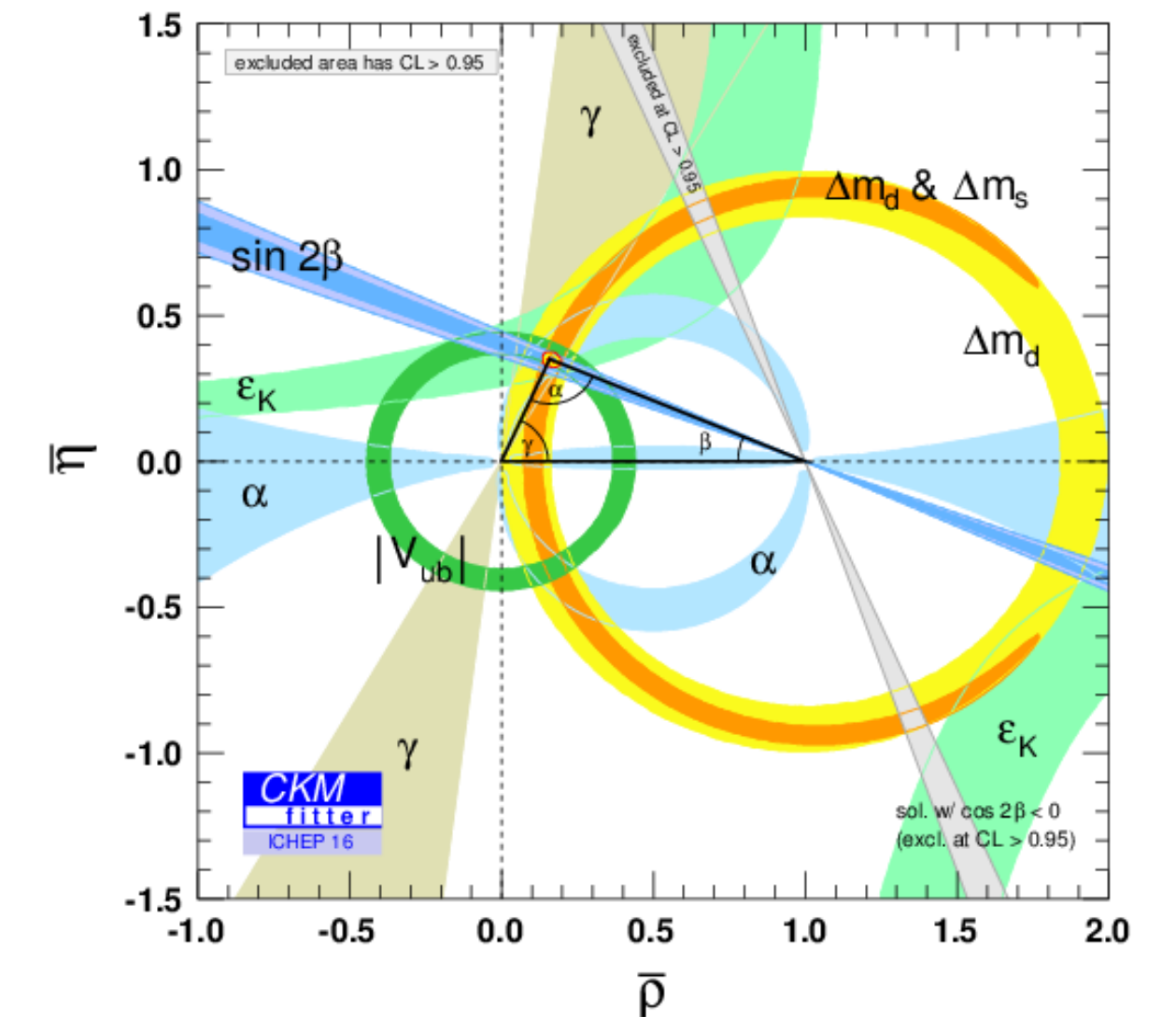
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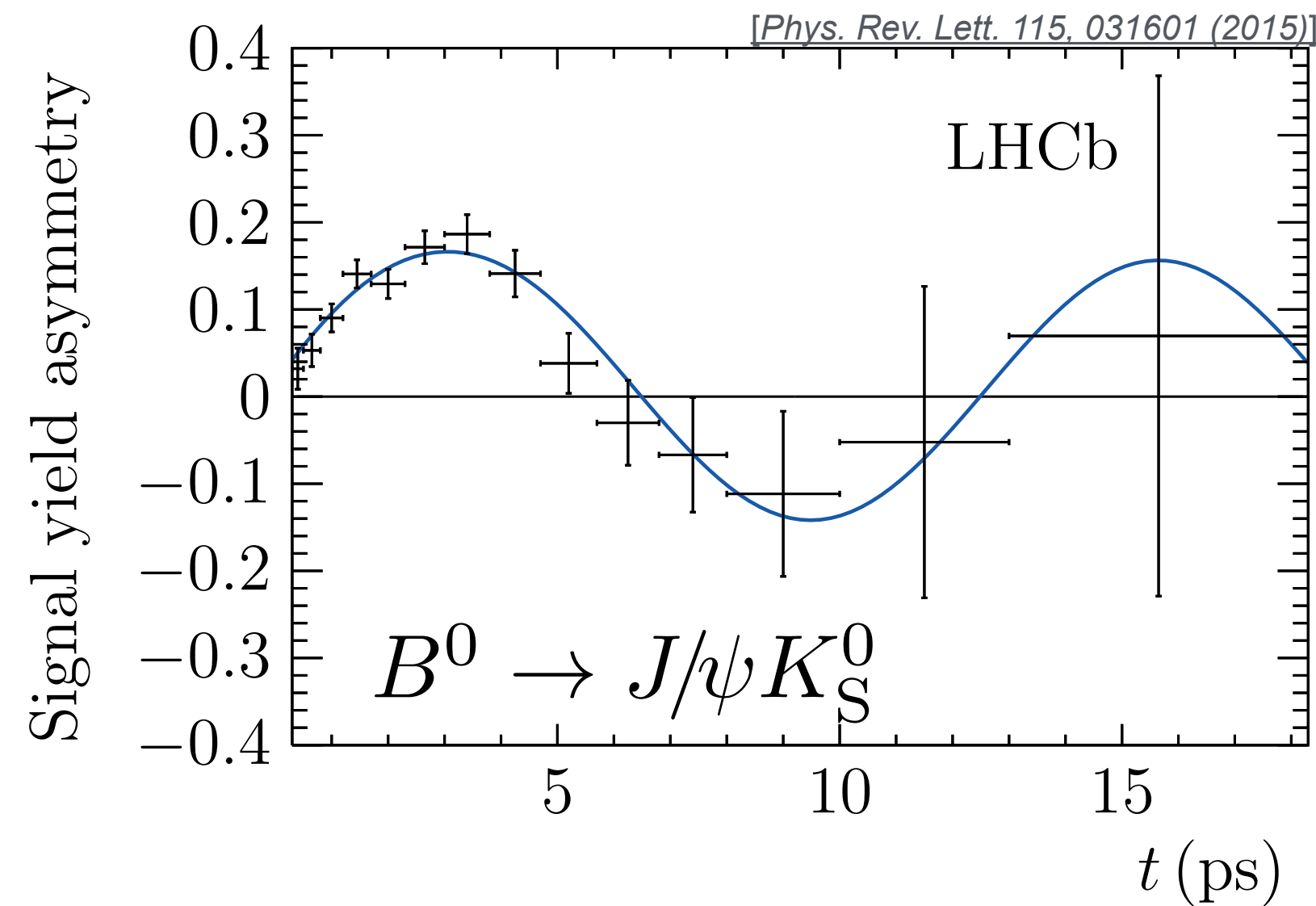


Time-dependent CP violation

- **CKM mechanism introduces CP violation and neutral meson mixing phenomena**
 - ▶ The presence of new heavy particles exchanged in virtual loops could introduce additional phases altering the corresponding measurements
 - ▶ Constraining these phases put stringent limits on a large range of NP models
- **CP violation is needed to explain baryon asymmetry in the Universe**
 - ▶ Discovered in 1964 in the kaons, 2004 in the B and each time awarded with Nobel Prizes
 - ▶ Still missing 10 orders of magnitudes!
- **Experimentally, CP violation observables accessed through ratios of measured quantities**
 - ▶ Cancellation of many experimental systematics
 - ▶ Flagship measurements for LHCb and Belle II



Time-dependent CP violation



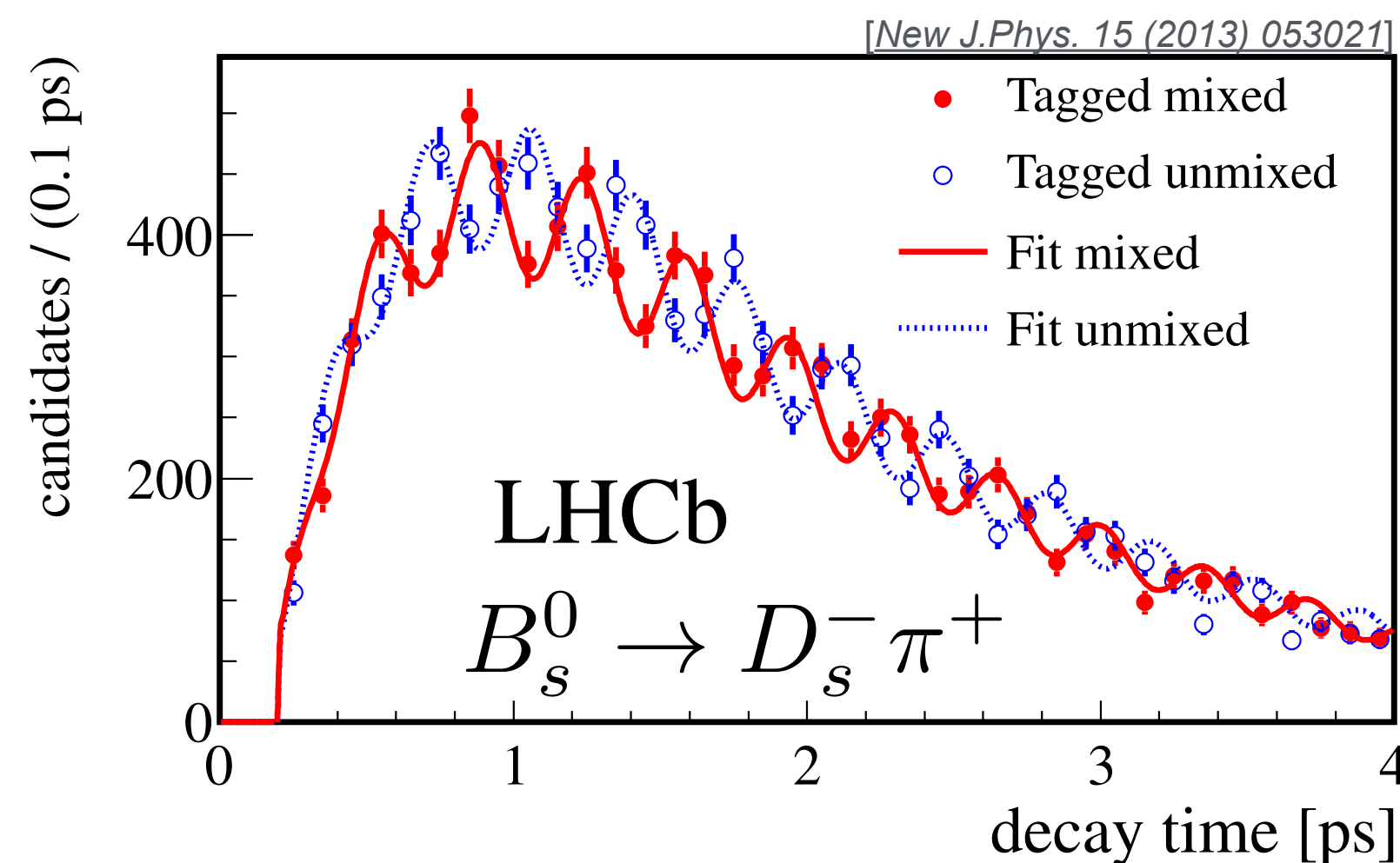
Time-dependent CP asymmetry:

$$\mathcal{A}_{CP}(t) = \frac{\Gamma(\bar{B}_q^0(t) \rightarrow f) - \Gamma(B_q^0(t) \rightarrow f)}{\Gamma(\bar{B}_q^0(t) \rightarrow f) + \Gamma(B_q^0(t) \rightarrow f)}$$

$$= \frac{\mathcal{S}_f \sin(\Delta m t) - \mathcal{C}_f \cos(\Delta m t)}{\cosh\left(\frac{\Delta\Gamma t}{2}\right) + \mathcal{A}_{\Delta\Gamma} \sinh\left(\frac{\Delta\Gamma t}{2}\right)}$$

Measurements of time-dependent asymmetries and decay rates require knowledge of **B flavour at the production time ($t = 0$)**

Flavour tagging algorithms tag the candidate as **B** or **\bar{B}** (tag decision) with some *efficiency* and *mistag probability*



Flavour tagging

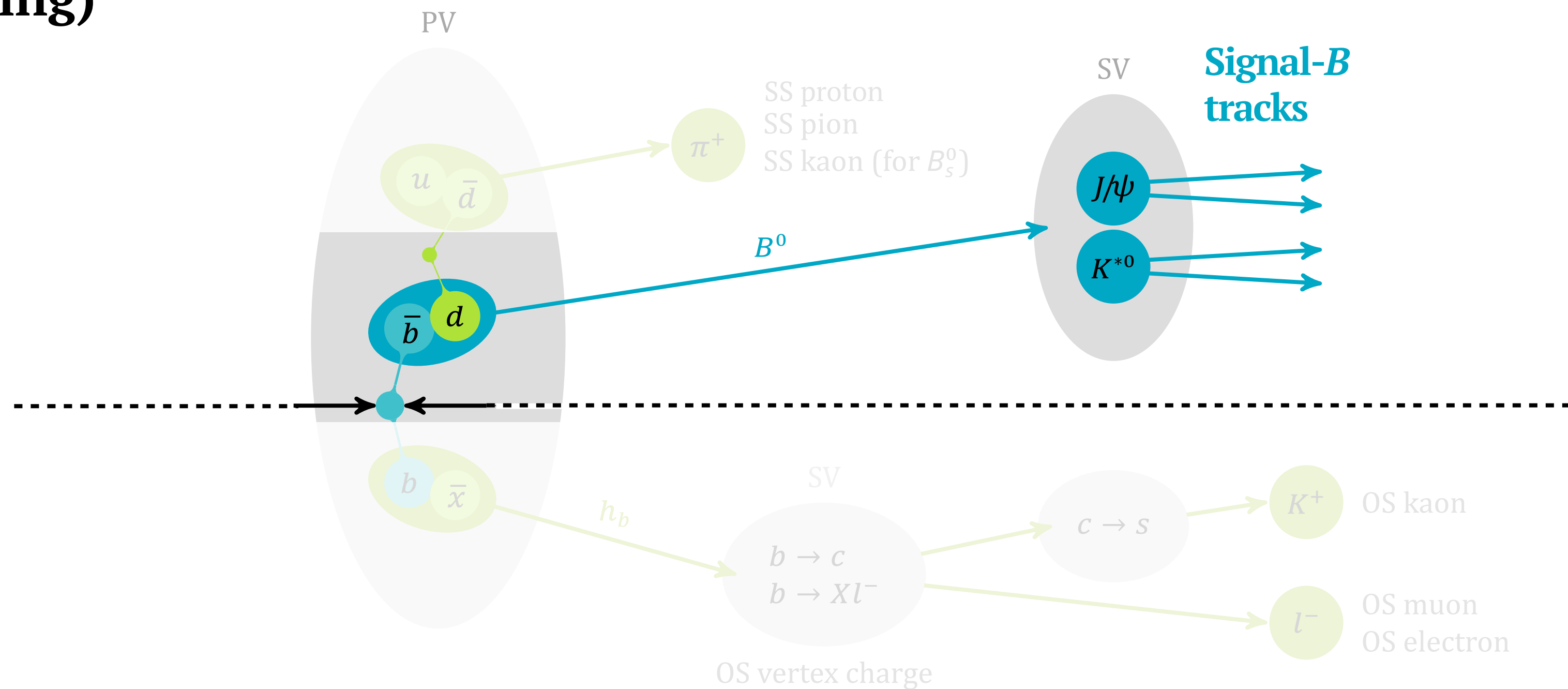
- **Motivation** : essential ingredient for ALL time dependants analyses

$$\sigma^{\text{stat}}(CP \text{ asym}) \propto \frac{1}{\sqrt{\varepsilon_{\text{eff}} N}}$$

Flavour tagging

- **Motivation** : **essential ingredient for ALL time dependants analyses**
- **Goal & challenges** :
Develop algorithms that exploit the charge correlations of particles produced together with B mesons in order to determine their production flavour (tagging)

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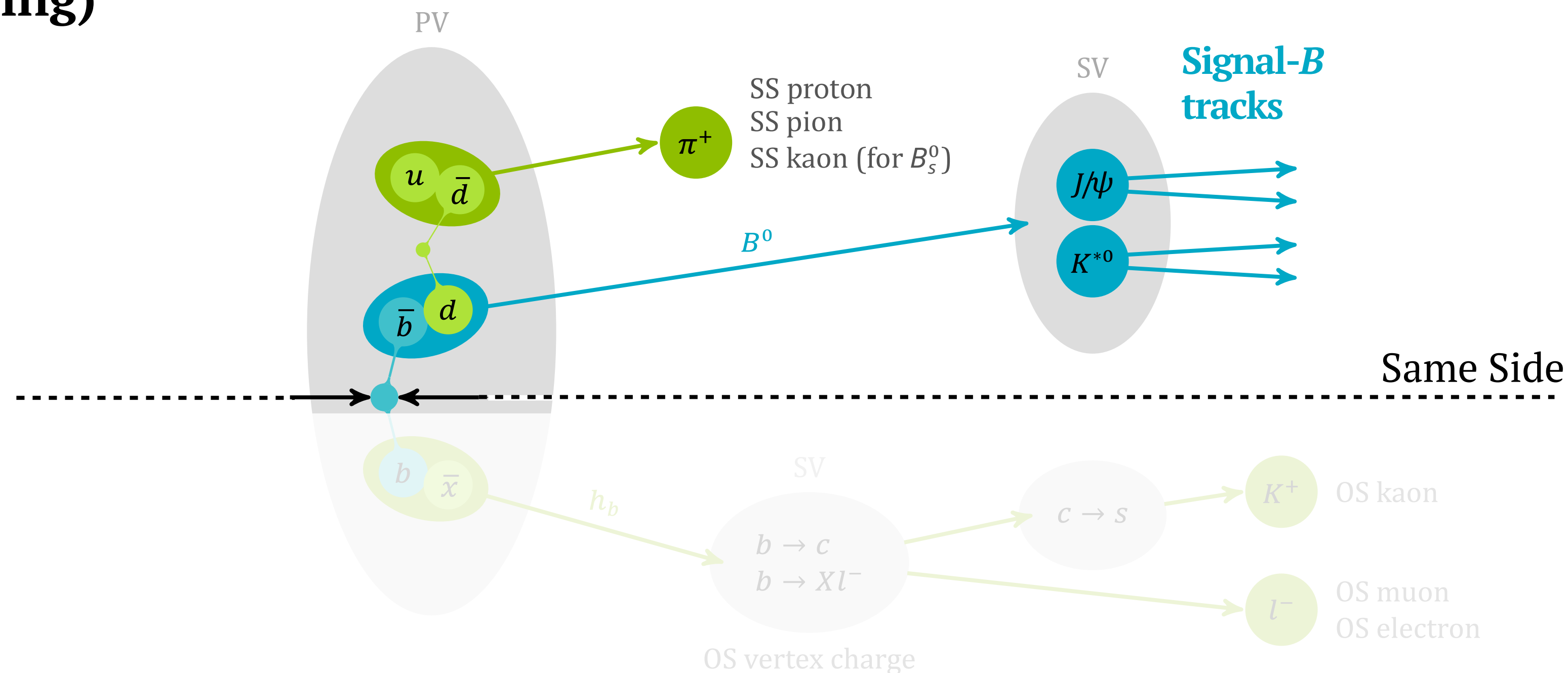
Flavour tagging

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Opposite Side (OS) : particles originating from the secondary vertex of the other b hadron **<5%> tracks**

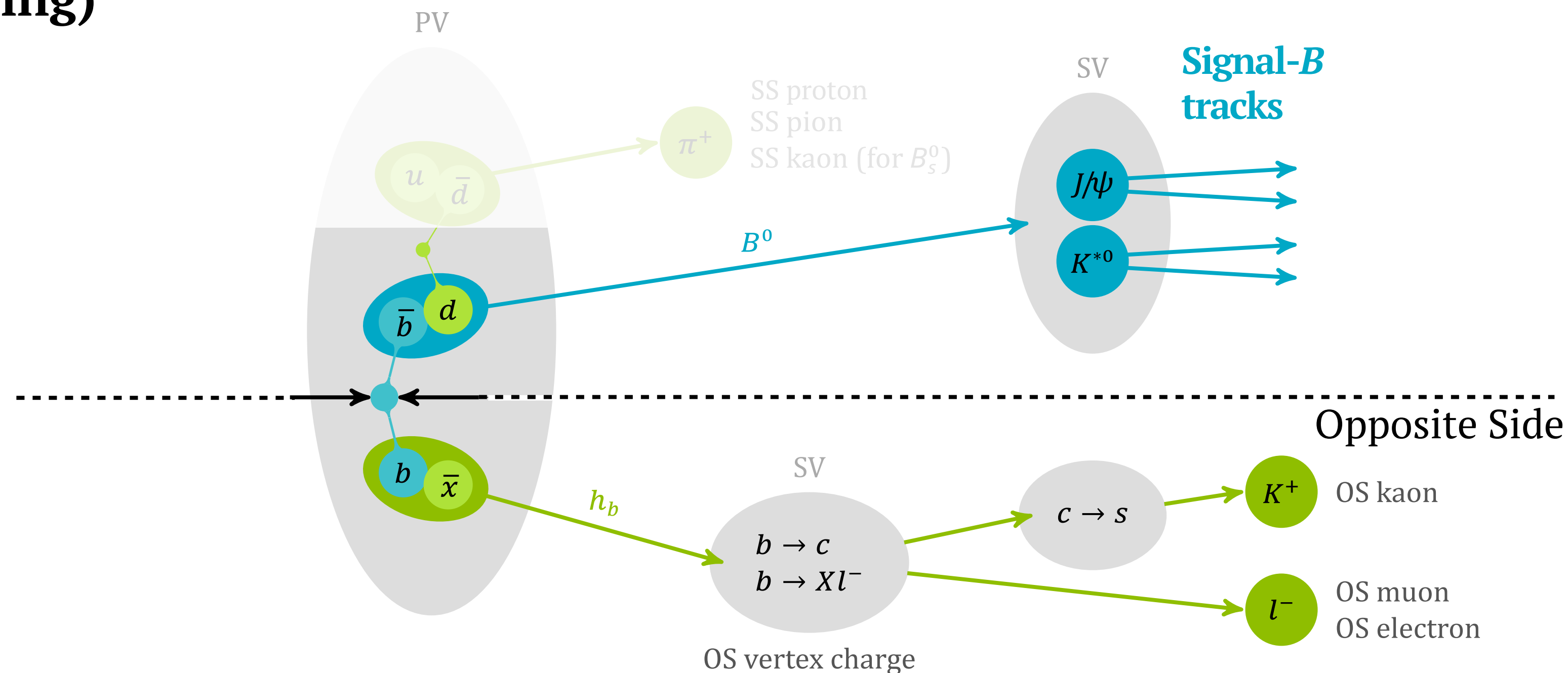
Flavour tagging

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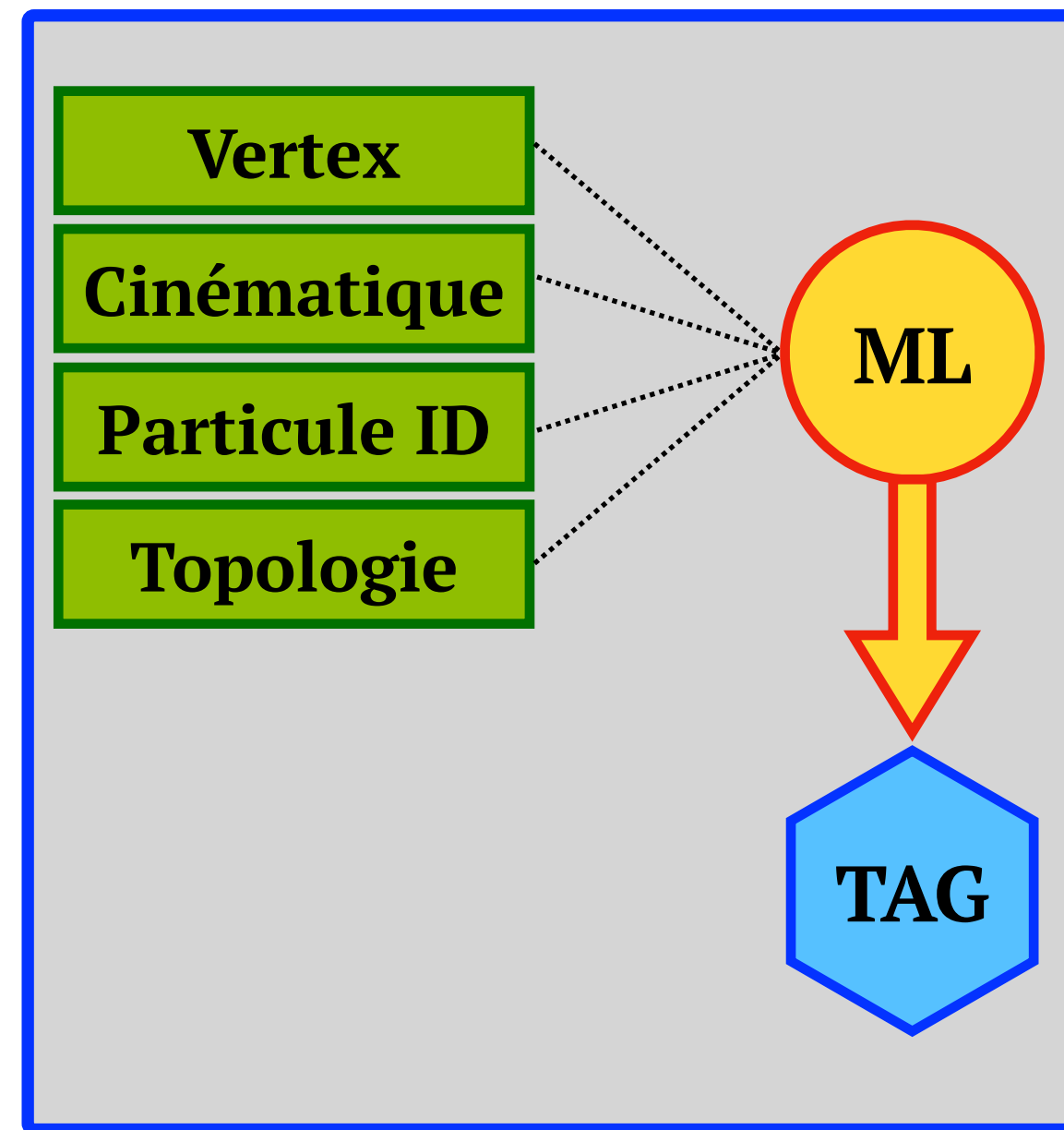
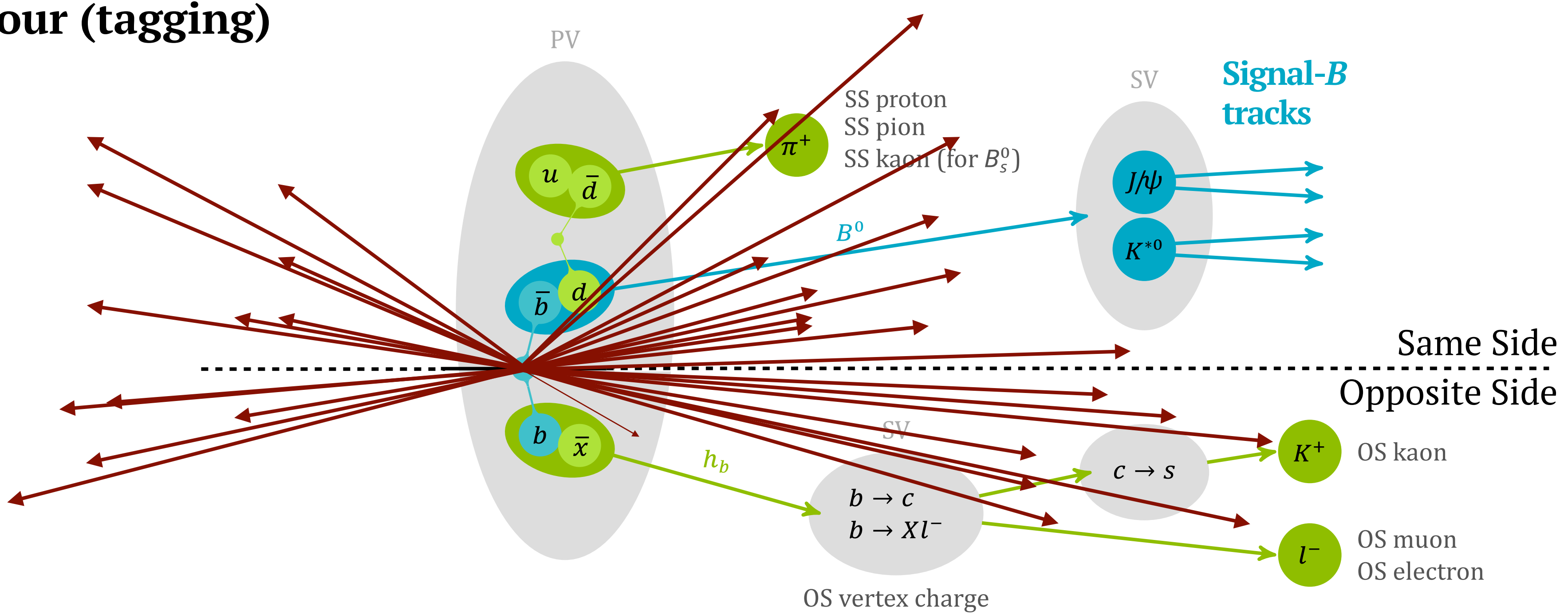
Opposite Side (OS) : particles originating from the secondary vertex of the other b hadron <5%> tracks
Same Side (SS) : particles produced in the hadronisation/fragmentation process <7%> tracks

Flavour tagging with advanced deep machine learning techniques

- **Motivation** : essential ingredient for ALL time dependants analyses

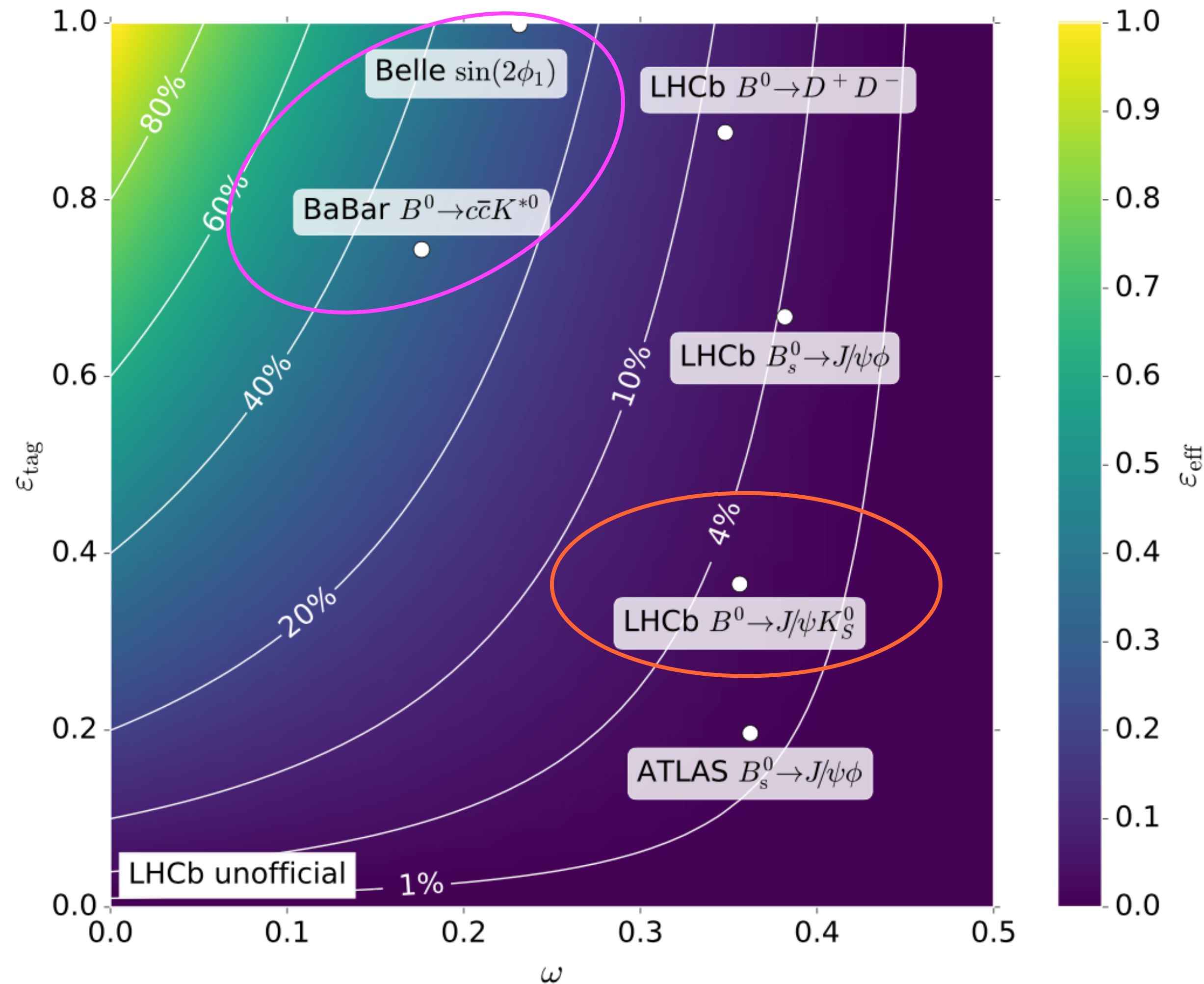
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- **Goal & challenges** :
Develop algorithms that exploit the charge correlations of particles produced together with B mesons in order to determine their production flavour (tagging)



Opposite Side (OS) :	particles originating from the secondary vertex of the other b hadron	<5%> tracks
Same Side (SS) :	particles produced in the hadronisation/fragmentation process	<7%> tracks
Background :	particles from soft-QCD pp interactions	<83%> tracks

Flavour tagging



[CERN-THESIS-2016-152]

$$\sigma^{\text{stat}}(CP \text{ asym}) \propto \frac{1}{\sqrt{\epsilon_{\text{eff}} N}}$$

An ambitious **two-fold improvement** in flavour-tagging performance is equivalent to having “**collected twice as much data**”

This would have a strong impact on the LHCb collaboration!

Primary vertex identification

- **Motivations :**

- Over the next years, the LHC detectors will face significantly increased luminosities
- One of main challenges in this high pile-up environment will be the ability to perform efficient vertexing

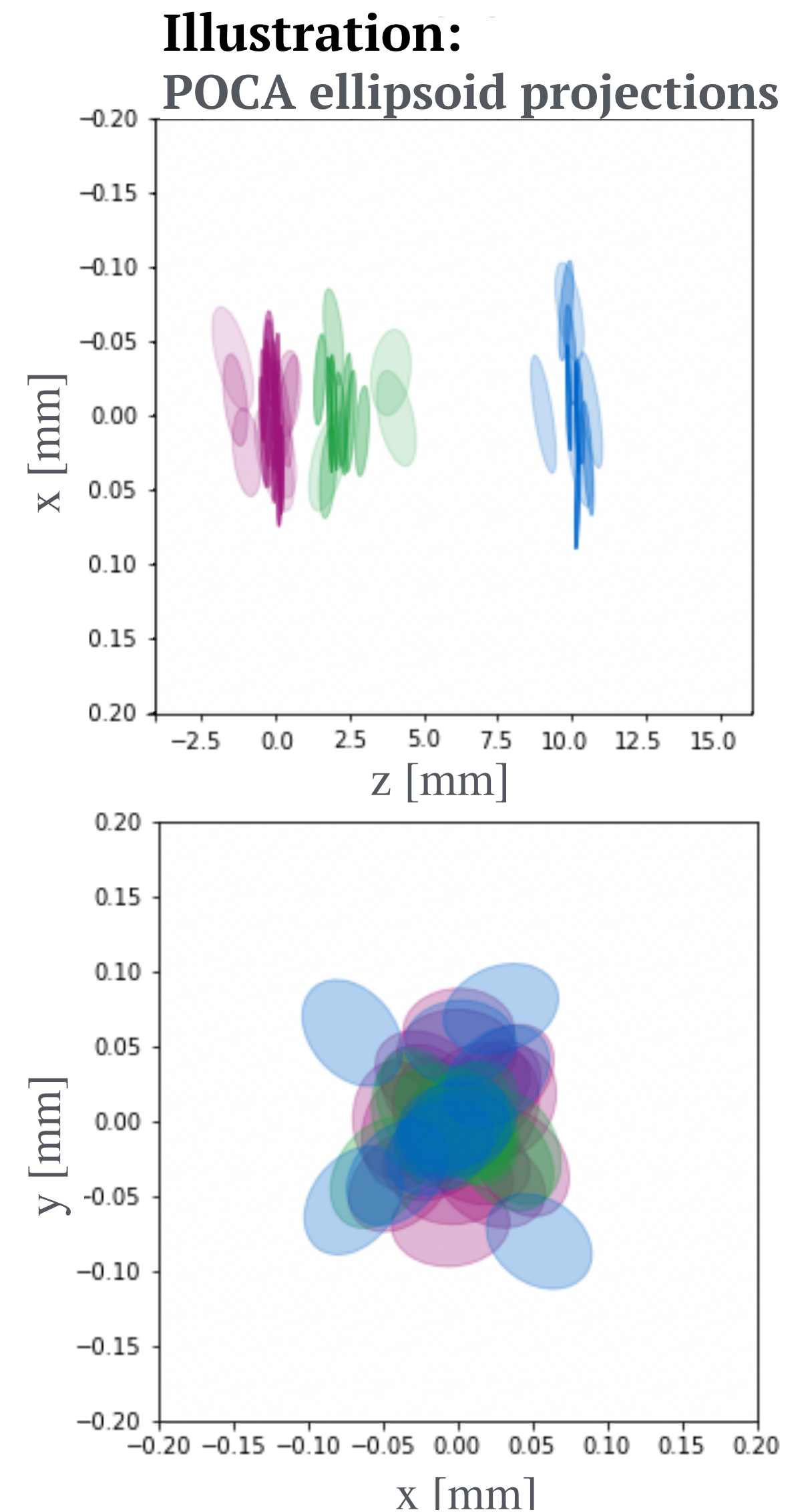
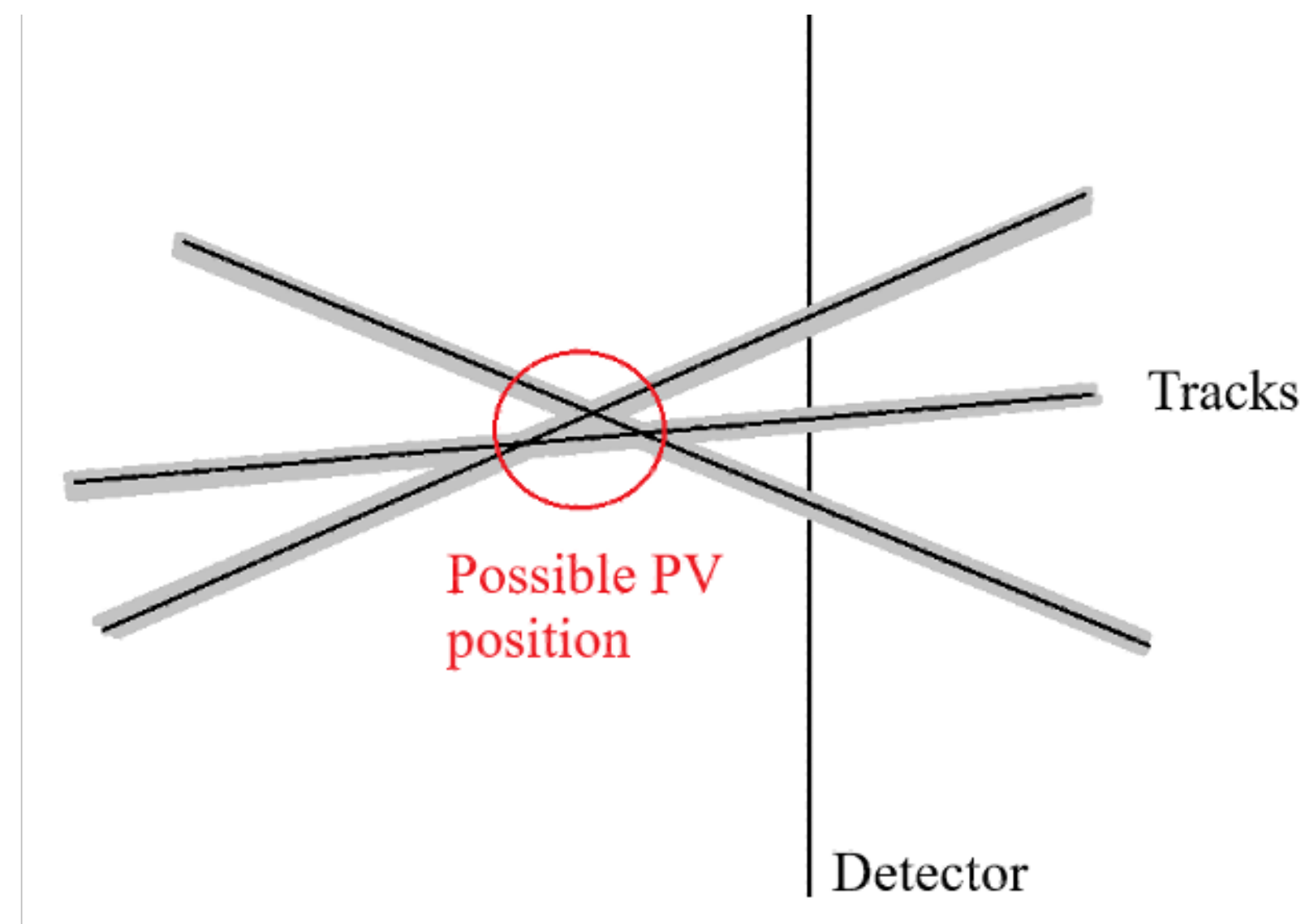
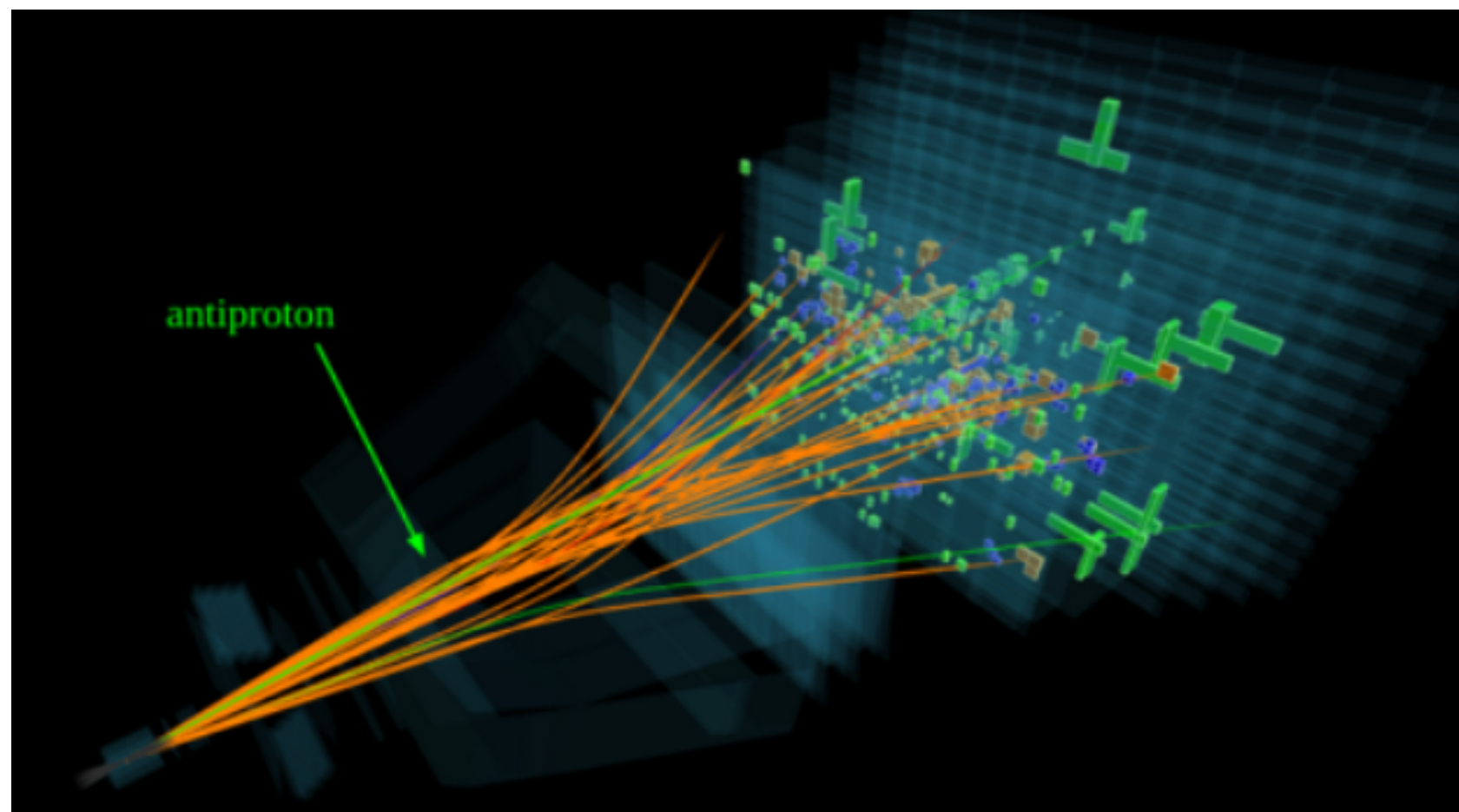
- **Goals :**

- **train realistic algorithms (in terms of fidelity and throughput) to find Primary Vertexes with high efficiency while producing false positives at low rates**
- **understand how the results depend on underlying model architectures and input features**

Primary vertex identification

What is Primary Vertex finding?

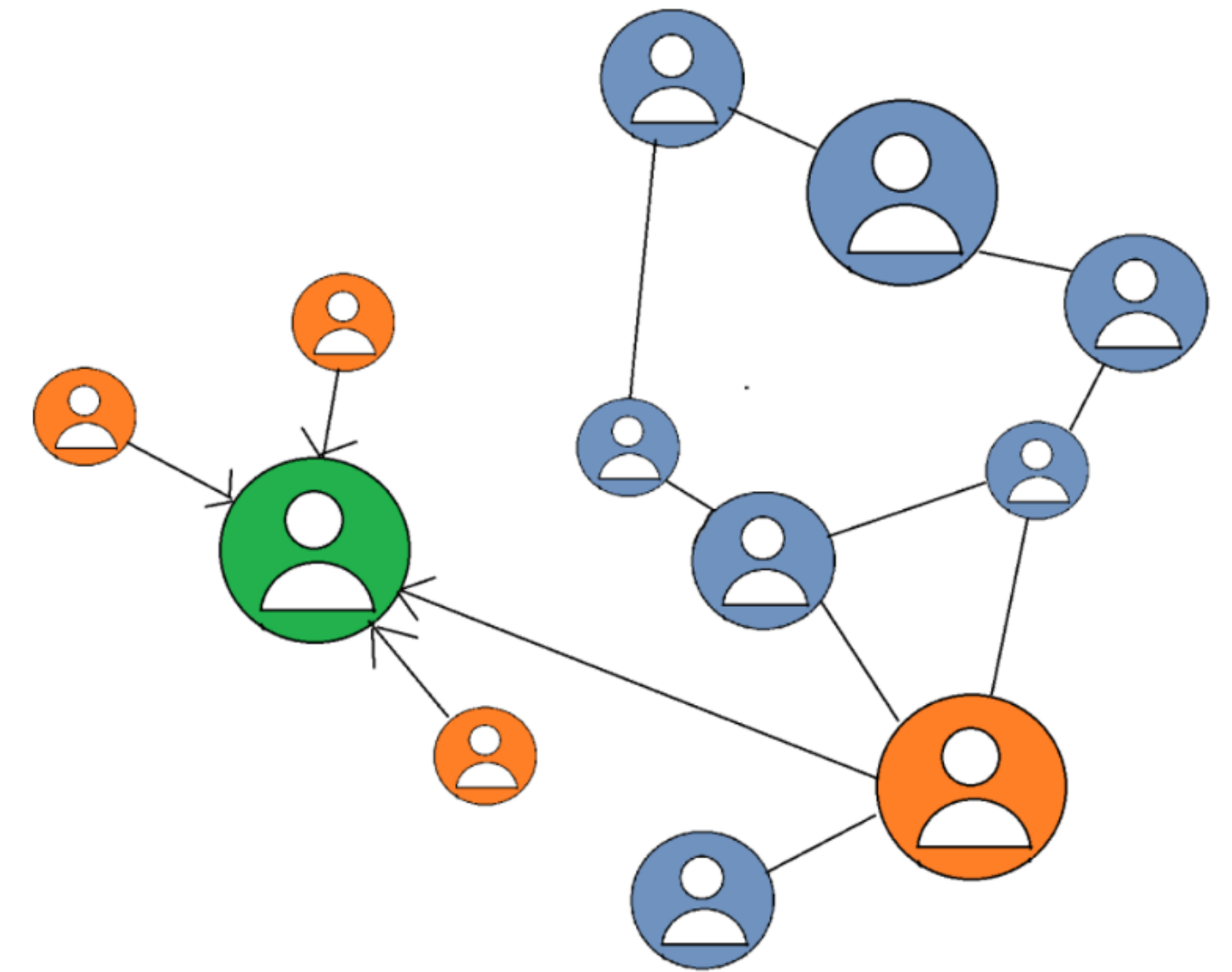
- ▶ When two beams collide inside a detector, we observe the collision through the particles it produces
- ▶ The trajectories (tracks) of particles produced by the collision are reconstructed by an existing algorithm and encoded through **POCA** (point of closest approach) values



Primary vertex identification

Graph Neural Networks (GNN):

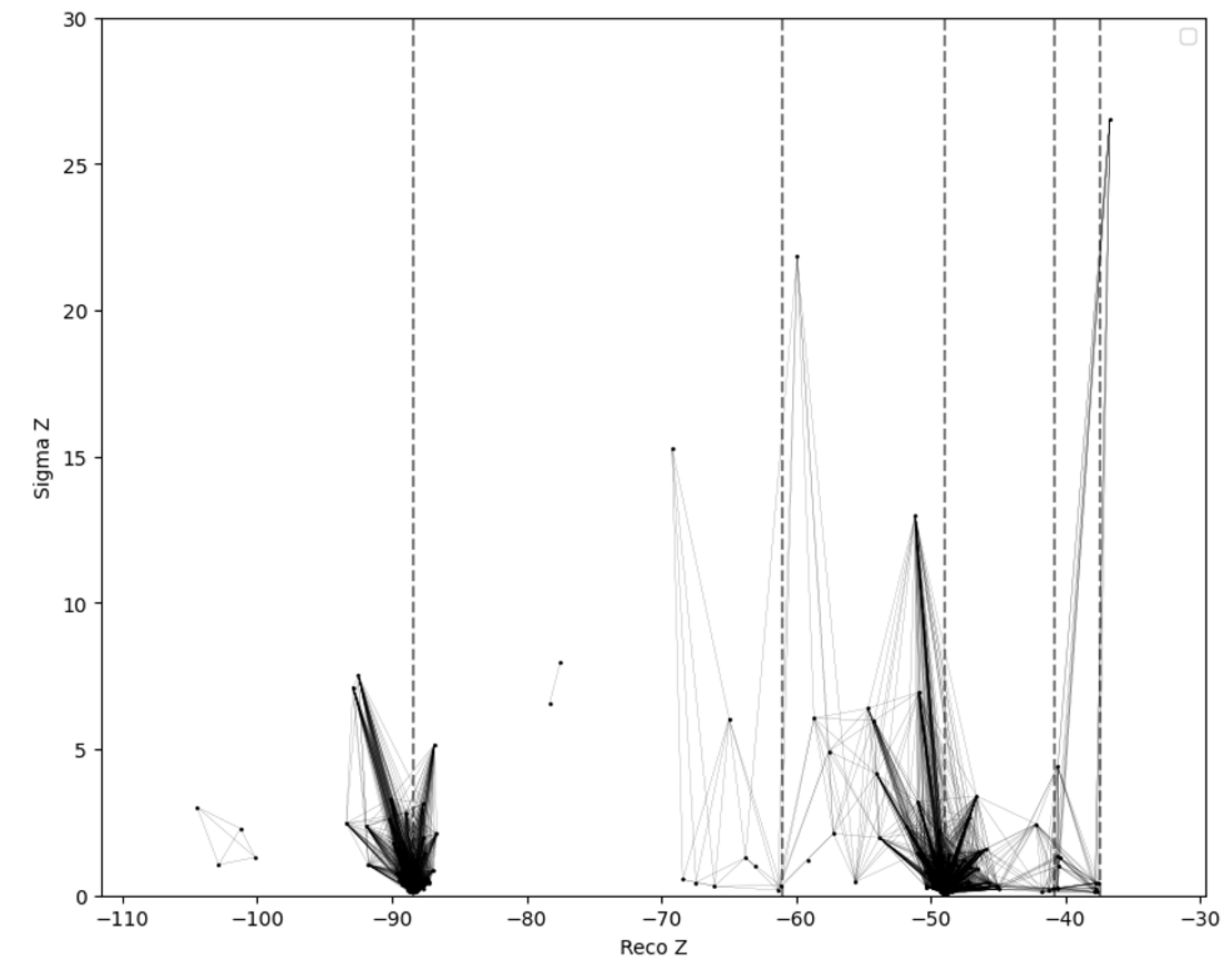
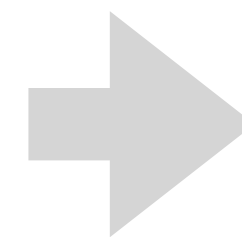
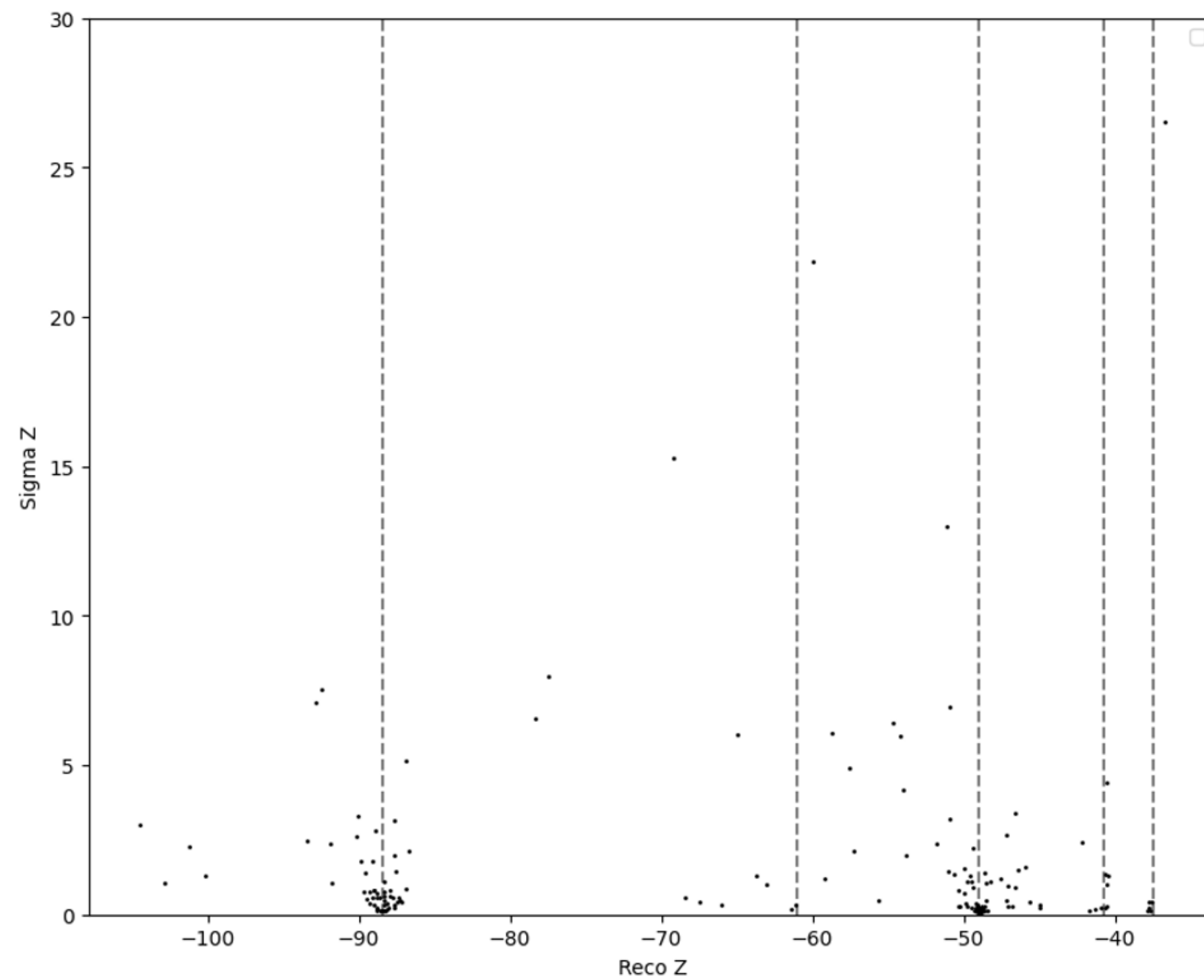
- ▶ Type of Artificial Intelligence Algorithm
- ▶ Data is represented by a graph with nodes and edges
- ▶ Data that can be represented by a graph examples:
 - Social Networks (nodes = people, edges = friendship)
 - Transportation Systems (nodes = cities, edges = roads)
 - Collision events (nodes = tracks, edges connect close tracks)
- ▶ The graphs are then used as the information the Neural Network is trained on, the GNN then makes prediction for a node based or edge based value
- ▶ Message passing step allows information from nearby nodes (connected by an edge) to influence node prediction



Primary vertex identification

GNN algorithm:

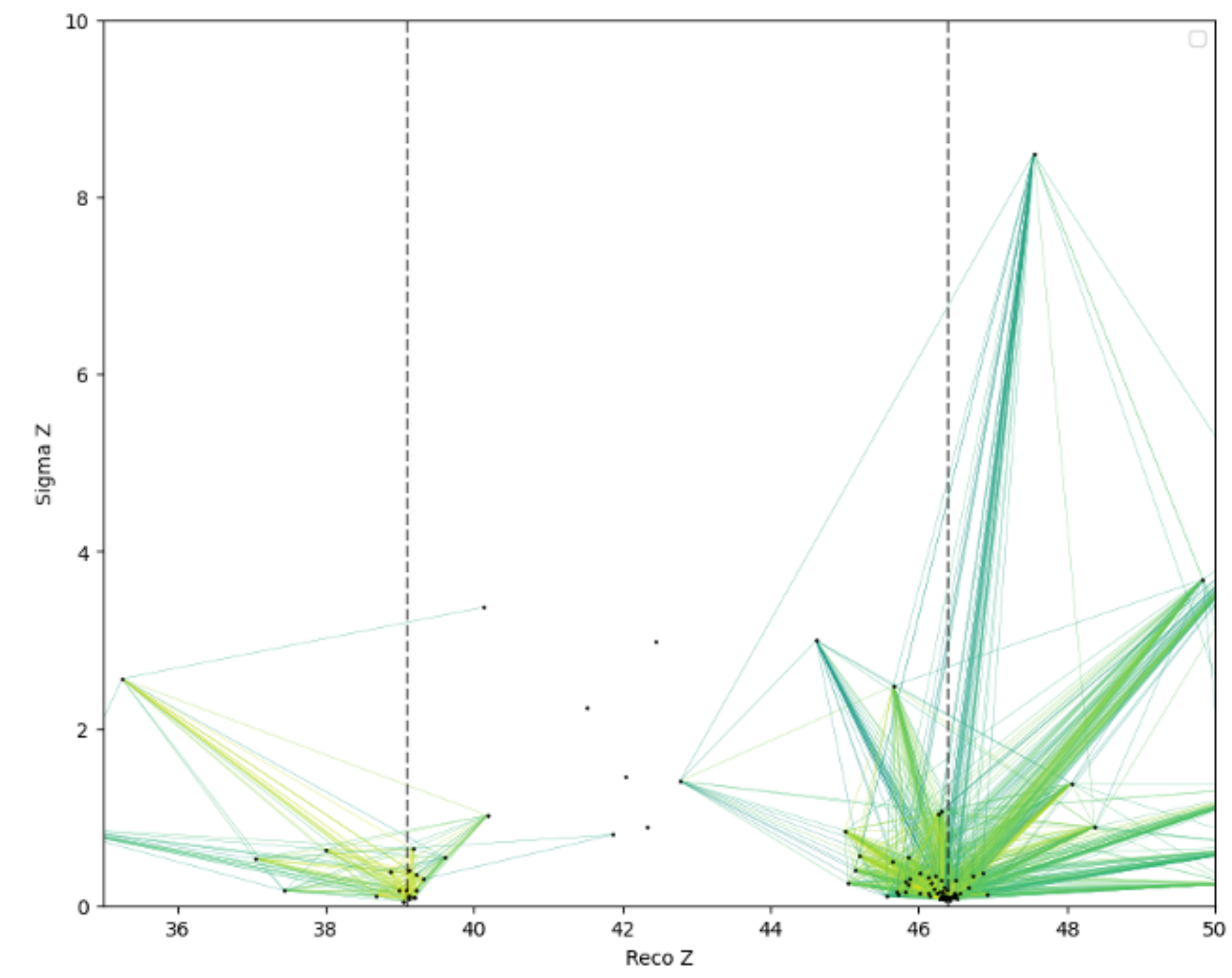
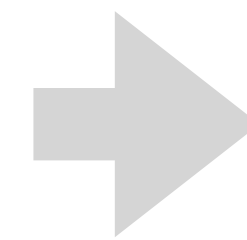
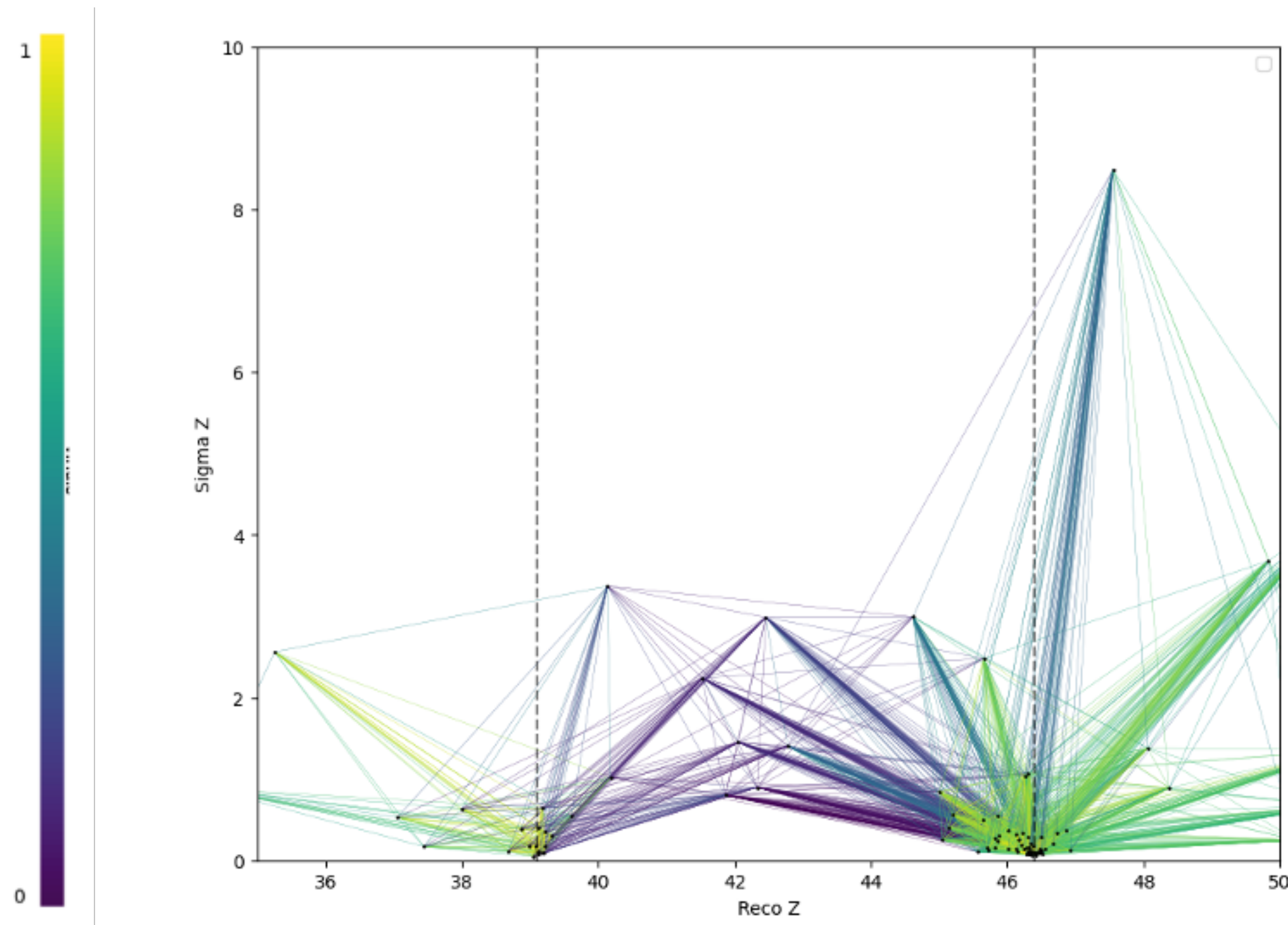
- ▶ Group tracks (build edges) from "distances"



Primary vertex identification

GNN algorithm:

- ▶ Group tracks (build edges) from "distances"
- ▶ Train GNN to best identify which tracks are likely to originate from same interaction point



Summary

▶ **Flavour tagging**

- Participate in the improvement of flavour tagging at LHCb

▶ **Primary vertex identification**

- Participate in the improvement of vertex identification at LHCb

- **In both cases develop expertise in advanced ML tools:
Graph Neural Network, Transformer...**