Search for Dark Neutrinos in SAND

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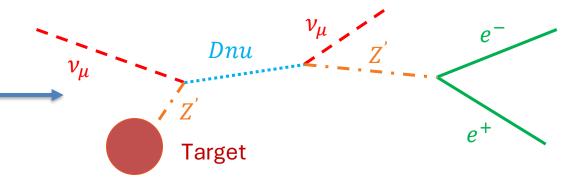


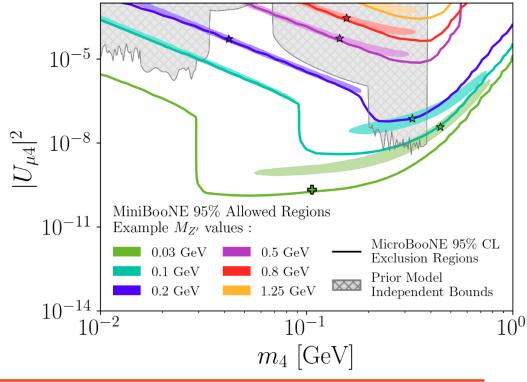
Dark Neutrino in a nutshell

Models with HNL states + Dark Photon Z':

- Dark neutrino (DNu) production in ν scattering
- Coherent scattering: low-Q² nuclear recoil
- Dnu decays to neutrino and Z'
- Z' finally decays to di-lepton pair at a distance from the primary interaction (model dependent)

- Current limits are from MicroBooNE (arXiv:2502.10900v1)
- Z' decays to e+e- have been explored so far
- The higher flux and low-density tracker at SAND may allow an improvement









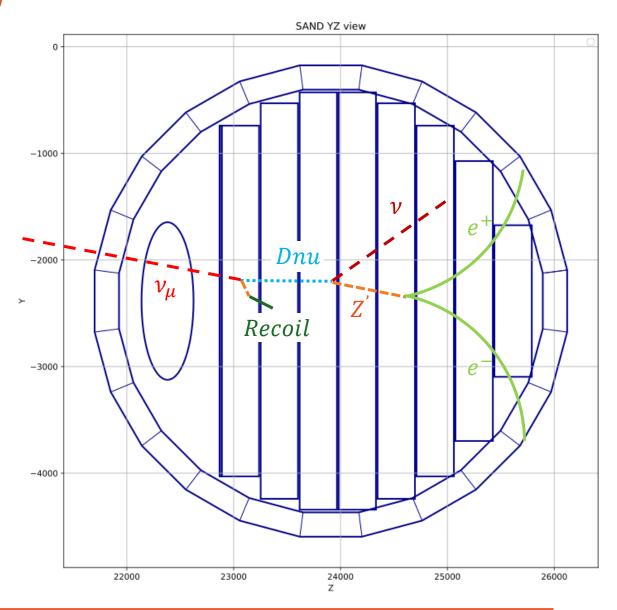
Dark neutrinos in SAND

What can be simulated in SAND with the available generators:

- Coherent scattering: no vertex trajectories
- Dnu decays to on-shell Z':
 - prompt decays, $\ell \leq 1 \ mm$
 - di-lepton pairs with a fixed invariant mass M_Z ,
- Z' decays to e+e- pairs

Signature in SAND

 e+/e- pair production in the tracker volume, in time with the beam and with the Z' invariant mass (model dependent)







Backgrounds

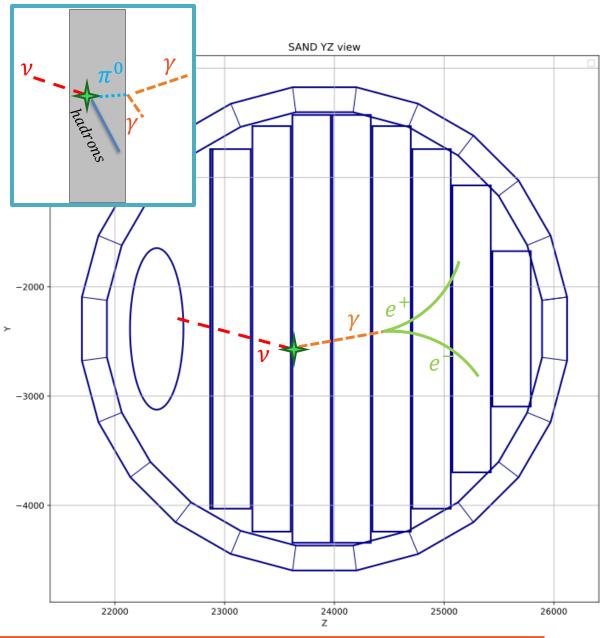
 e^+e^- pairs produced in the tracker without an associated vertex activity.

Potential sources:

- primary vertices outside the tracker volume (matching is not performed at the moment)
- Short or absent vertex tracks (e.g. NC interactions with $\pi^0 \to \gamma \gamma$)

Discrimination possible via pair kinematics:

- Pair invariant mass
- Pair energy and transverse momentum
- Pair-beam angle and aperture angle







Event simulation framework

SAND reco chain adapted to enable **Dnu** simulation.

A) Event generation with GENIE with Dnu production and decay

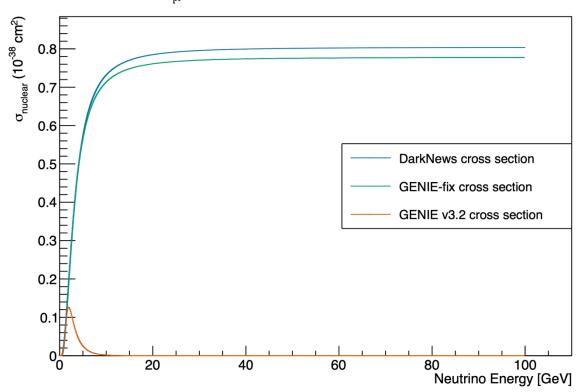


Fixed a bug in the cross-section evaluation (available in GENIE 3.6.2)



Particle propagation with edep-sim: fixed an issue with displaced vertex

 $v_{\mu}(HNL)$ cross section on C12



Limitations in GENIE (needs long-term development):

- scattering on free nucleons (H) not implemented
- only real (on shell) Z' are generated
- decay channels other e^+e^- are missing $(Z' \to \mu^+\mu^-)$





Data Production

Simulated processes:

- Signal: Dnu models spanning Dnu masses M_N between 35 MeV and 1 GeV. Fixed $M_{Z'}=30~MeV, \left|U_{\mu 4}\right|^2=2\times 10^{-10}$
- Background: simulated with the standard tune (AR23_20i_00_000)

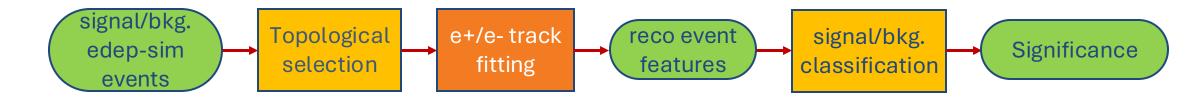
- Productions made with the Drift-chamber geometry (SAND_opt3_DRIFT1)
- ~500k events in GRAIN+TRACKER for each sample
- Beam: v_{μ} , \bar{v}_{μ} and v_{e} , \bar{v}_{e} in FHC mode (gsimple format)
- Fixed versions of genie and edep-sim discussed before (signal H1 interactions are neglected)





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Analysis pipeline



1. Topological cuts based on edep-sim info:

- Selecting candidate e^+e^- pairs produced in the tracker volume
- For bkg. events: no visible vertex activity (Dnu scattering is coherent, 50 keV recoil)

2. Fitting of the candidate pair trajectories:

- Fitting of the e^+e^- trajectory hits to reconstruct momenta and extract candidate event features
- Selection on fit-quality for the pair trajectories

3. Multivariate classification:

- Signal/background separation based on the the reconstructed features
- Compute the significance Z from the resulting number of signal and bkg. events (S and B)

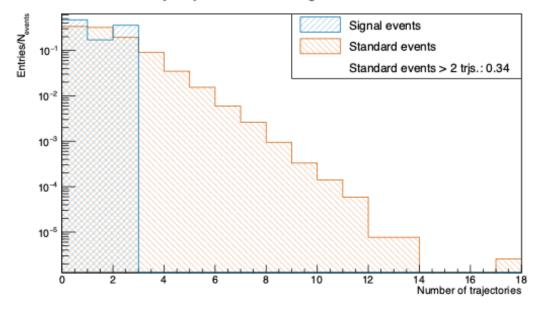


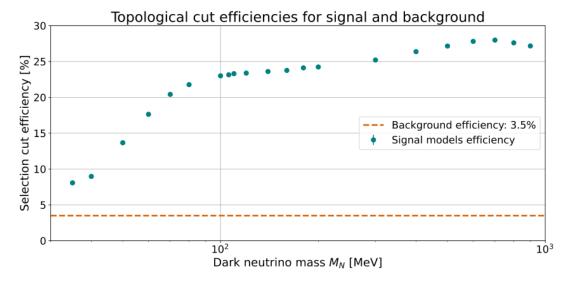


1. Topological cut

- Selection based on a standard quality cut for the tracker: ≥ 4 crossed tracker modules
- Candidate events have ≥ 1 pairs produced in the tracker and passing the cut.
- Cut on vertex activity based on primary trajectories above the threshold
- Two bkg. topologies:
 - No vertex trjs. above threshold, but ≥ 1
 candidate pairs → selecting the most upstream
 - Single primary pair above threshold
- Signal events: requiring signal pair to pass the candidate cut

Primary trajectories crossing ≥ 4 DRIFT modules







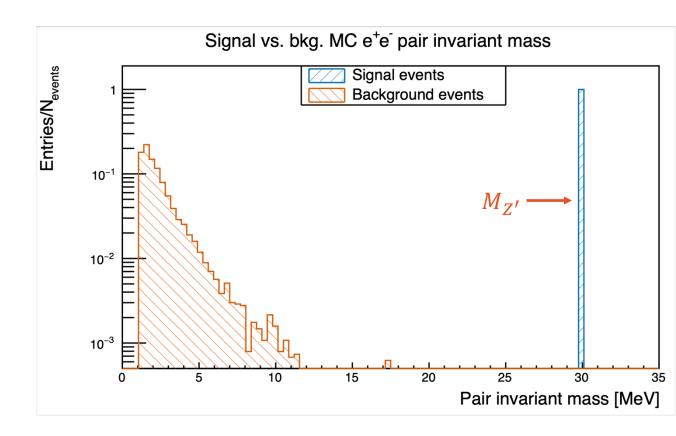


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MC pair kinematics features

- Characterised the candidate pairs by a set of kinematic features:
 - Invariant mass
 - Pair energy and transverse momentum
 - Pair opening angle and pair-beam angle
- Clear separation in the invariant mass (same $M_{Z'}$ in all signal models)
- The kinematic distributions vary across the model range.

 Implemented a track fitting algorithm to provide reconstructed features.





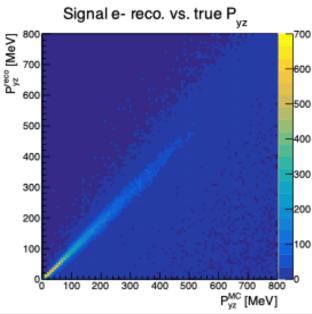


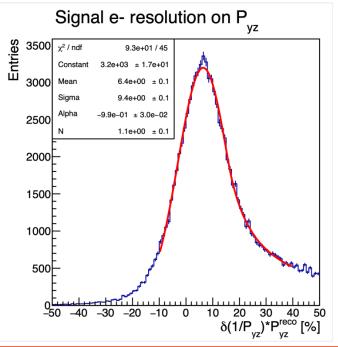
2. e+/e- track reconstruction

Preliminary track reconstruction using a helix-fit:

- Fitting the edep-sim hits of the e⁺e[−] trajectories
 → 0.2 mm smearing is applied
- Radiative losses in e+/e- tracks:
 - Fit limited to the first 25% of hits
 - Path-dependent weighting of χ^2 in the bending plane to account for reduced R
- Reconstructed momentum from fit parameters

- The helicoidal fit underestimates e+/e- momenta:
 - ~9.5% bending plane resolution, 6% bias







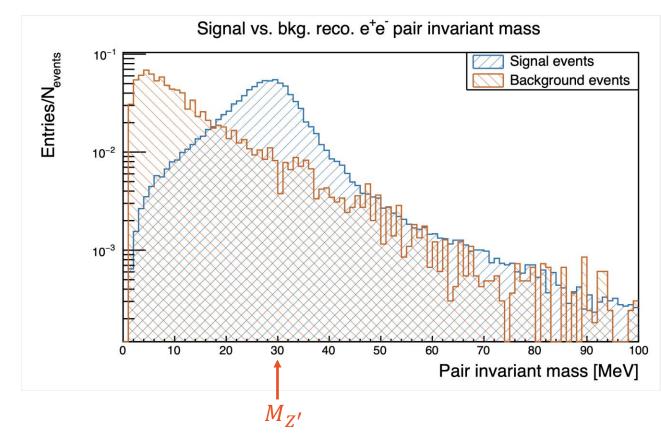


Reconstructed pair features

 Pair kinematics features extracted from the reconstructed tracks.

- Reconstructed invariant masses are not as well separated.
- Best resolutions are on the pair energy and pair-beam angle (7.9% and 8.2%)

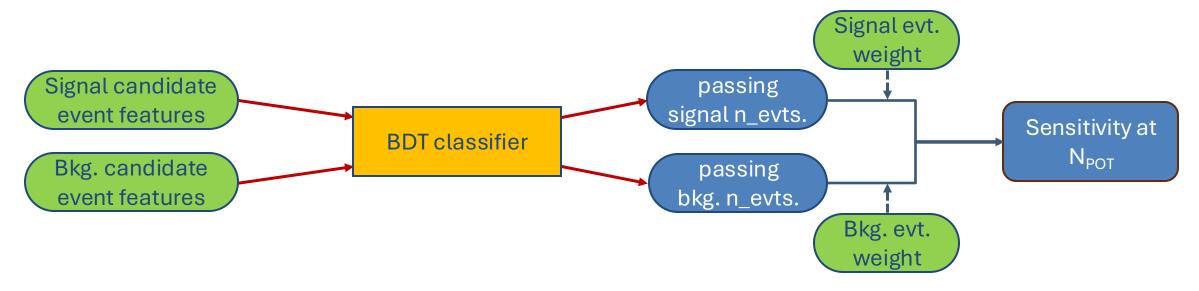
 Decided for a multivariate classifier trained on the kinematics to perform the final selection step.







3. Signal/bkg. discrimination with BDTs



- Boosted Decision Tree classification on reco-level e+/e- pair features
 (energy, aperture angle, pair-beam angle, invariant mass, P-transverse, etc...)
- Set up a data preparation/training/testing pipeline in TMVA (native TMVA models or XGBoost)
- Counting experiment approach to extract the sensitivity: obtain Z from the passing signal and background events from the classifier (S and B) + weights





Discovery potential computation

- Single BDT is trained on all signal model samples against the background events
- Working point score t^* found by optimising the significance on the BDT test set
- Applied the full chain on samples of ~500k event for all signal models + bkg and computed the significance at the t^* score cut:

$$Z_{tgt}(t^*) \equiv \sqrt{2\left[(S_{tgt}(t^*) + B_{tgt}(t^*)) \ln\left(1 + \frac{S_{tgt}(t^*)}{B_{tgt}(t^*)}\right) - S_{tgt}(t^*) \right]},$$

- General Z formula to account for potentially small B.
- Scaling S and B to the exposure and significance chosen for the curve (+ additional corrections for acceptance, cross-section, etc...)

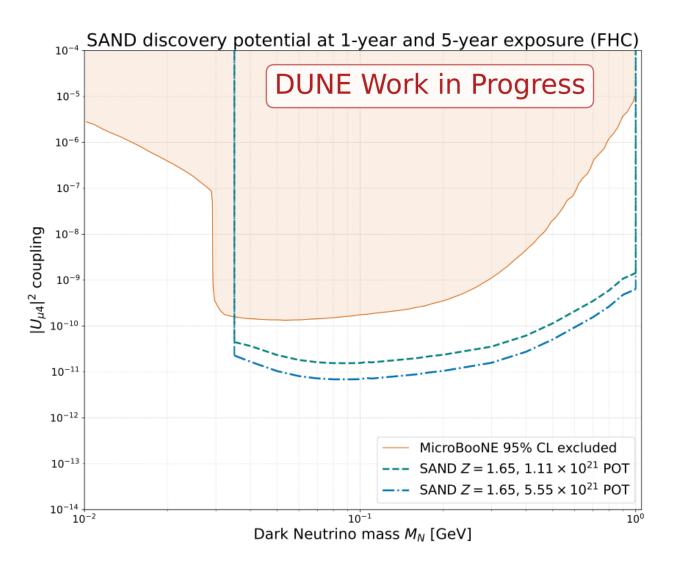




Discovery potential curve

- Reference exposures at 1e21 and 5e21 POT
- Discovery potential at Z=1.65 (95% C.L. one-sided)
- Reference MicroBooNE excluded region for the same M_{7} (~6.8e20 POTs)

- Off-shell decays $(M_{DNu} < M_{Z^{'}})$ are not included in GENIE but may be particularly interesting in SAND:
 - signal stat. depends on external mass
 - best case for low density detectors







Next steps

First performance assessment used a preliminary analysis pipeline.

Further developments are needed:

- On the SAND software side:
 - Integrate the sandreco track digitisation and reconstruction (Kalman filter or new algorithm)
 - Perform the topological selection through a vertexing algorithm
 - Investigate the use of sandreco ECAL reconstruction in the analysis (selection on cluster multiplicity, energy reconstruction, e+e- tagging via E/p)
- On the GENIE side as well:
 - Introduce a cross section for H
 - Implement off-shell Z' decays
 - Implement the decay channel to μ+μ-





Thank you for the attention!



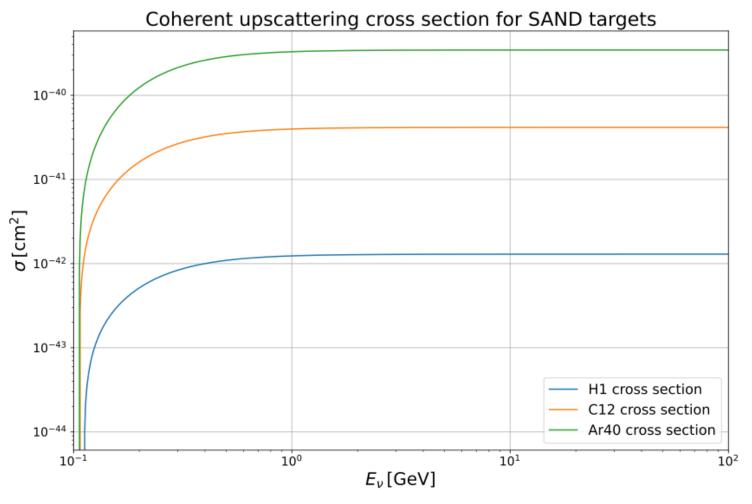


Backup and additional items





Dark neutrino cross section on H1



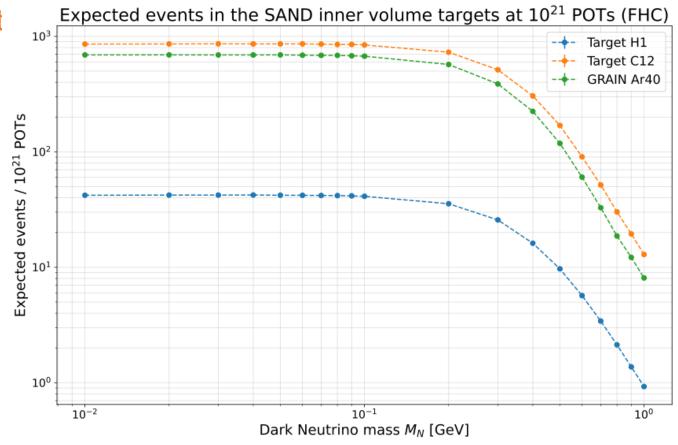
$$M_{DNu} = 106 \, MeV, M_{Z'} = 30 \, MeV, \left| U_{\mu 4} \right|^2 = 2 \times 10^{-12}$$





Missing statistics from H1

- Used DarkNews to estimate the event rate on several SAND targets:
 - Tracker target H1 (~488 kg)
 - Tracker target C12 (3.7 tons)
 - GRAIN Ar40 (1.2 tons)
- 5k weighted event generations at different M_{Dnu} for 10²¹ POT (FHC)
- Event rate lower by a factor of ~10
- Neglected for the moment





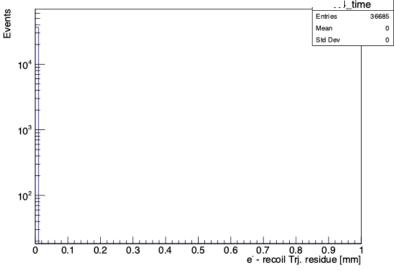


Event Simulation Framework (2)

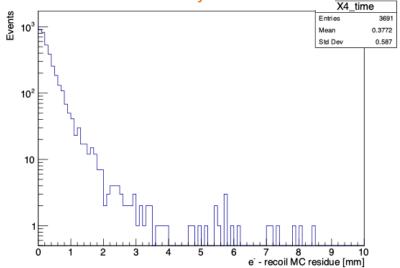
B) Particle Propagation:

- GENIE output files contain all particles: both from primary interaction and Z' decays, originating in different positions → edepsim primaries
- All primary tracks in edepsim are propagated them from the same point (the primary vertex)
- Displaced decays are a distinctive feature of Dark Neutrino models (in principle)
 - → We fixed edep-sim to group input particles by position and time and fill a vector of TG4PrimaryVertex with different positions (available at github.com/AlessandroRuggeri/edep-sim)





Fix: e⁻ – recoil trj. start residues

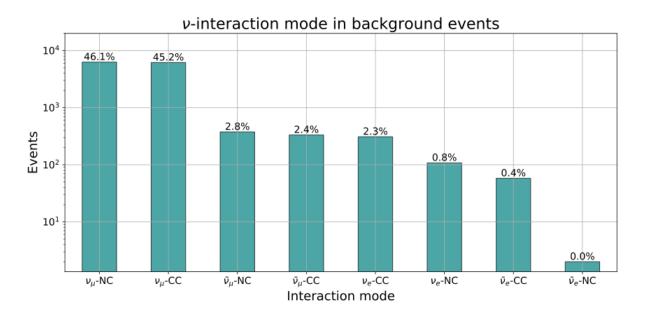




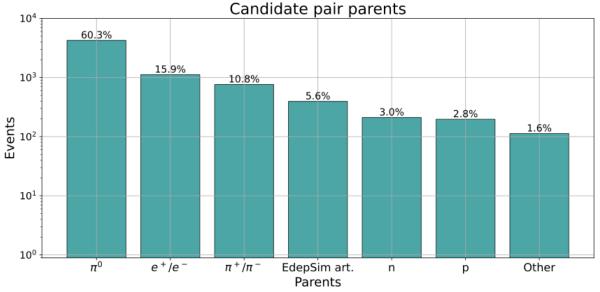


Background sources

Largest fraction of bkg. interactions are NC



Pi0 are the most common bkg. pair parents (via $\gamma\gamma$)



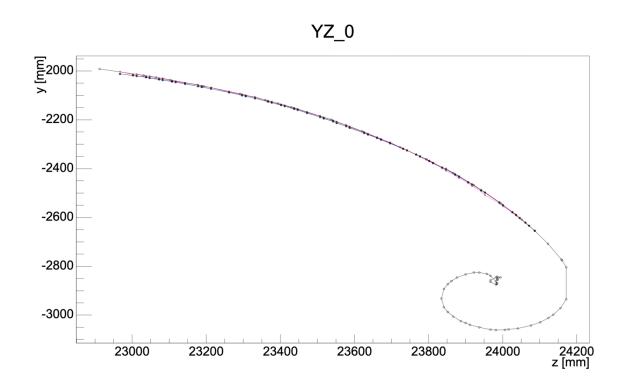
Pair parents taken from edep-sim: some parent γ trajectories are split

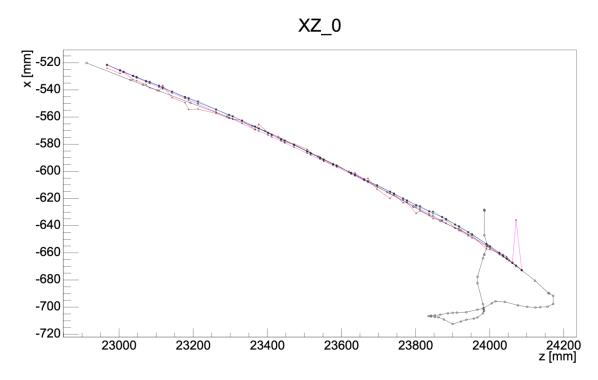




Signal e- trajectory examples

- Signal pair e- trajectories from a test with the Kalman filter ($M_N = 106$ MeV benchmark)
- The trajectories loop back within the tracker volume → underestimation of R







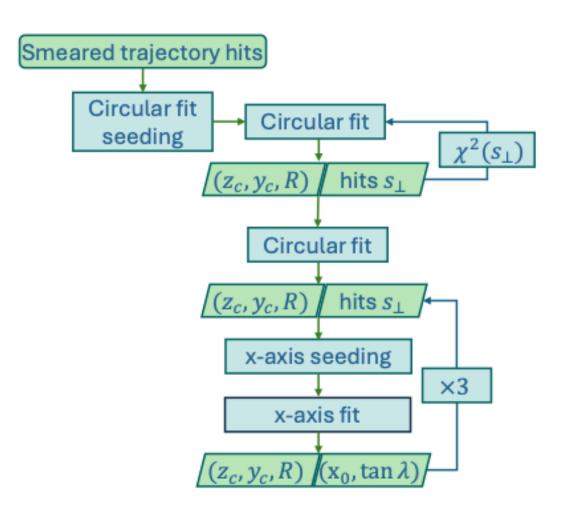


Track fitting algorithm

- Hit coordinates smearing (~0.2 mm)
- Circular + straight line fit:

$$\begin{cases} (z - z_c)^2 + (y - y_c)^2 = R^2 \\ x = x_0 + s_t \cdot \tan \lambda \end{cases}$$

- Accounting for reduction in R in the circular fit by:
 - 1. Limited fit to initial 1/4 of the track hits
 - 2. s_t -dependent χ^2 : $\sigma = \sigma_{res} + \alpha s_t + \beta s_t^2$
 - 3. χ^2 weights depending on R-residue: $w = c/\Delta R$

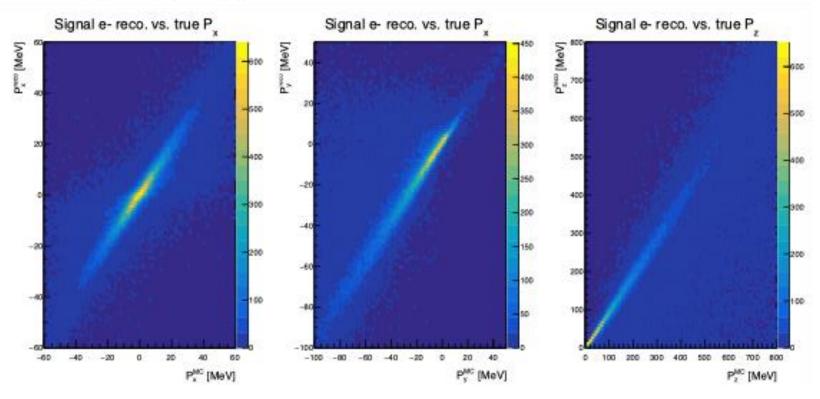






Reco. vs. true momenta

- Momentum extrapolated from fit parameters at the MC start of the trajectory
- In signal events: $p_z \gg p_v > p_x$



Momenta tend to be underestimated → energy loss in e+/e-



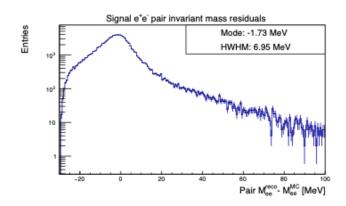


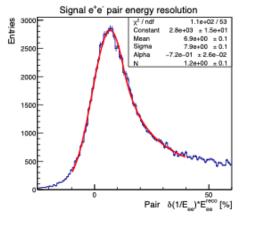
Reco. features resolutions

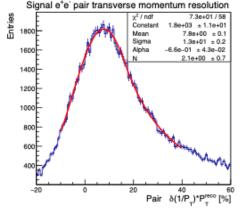
 Resolutions on the reconstructed pair kinematic variables (M_N=106 MeV benchmark)

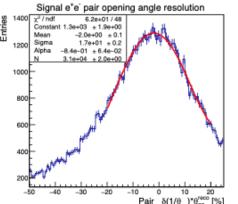
- Reconstructed invariant masses are not as well separated.
- Best resolutions are on the pair energy and pair-beam angle (7.9% and 8.2%)

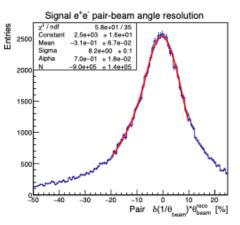
 Decided to go with a multivariate classifier for the final selection step











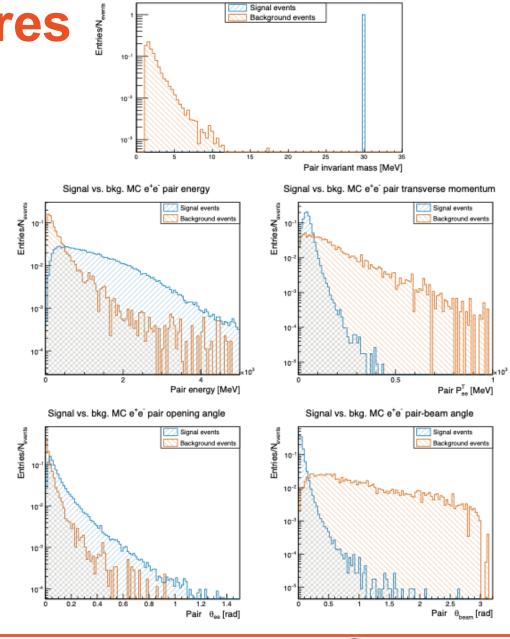




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Signal vs. bkg. MC e*e pair invariant mass



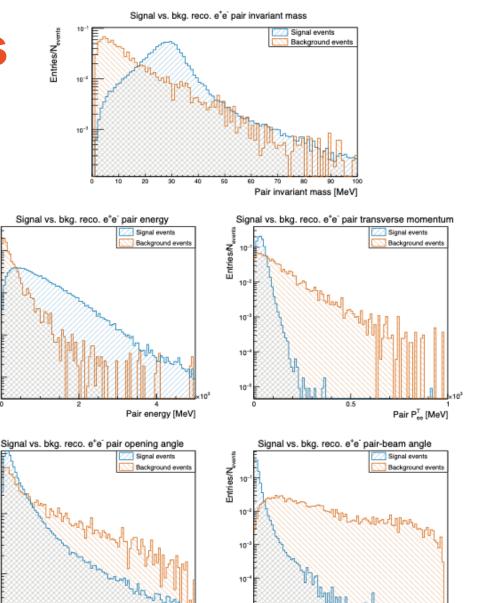


Reconstructed pair features

 Pair kinematics features extracted from the reconstructed tracks.

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Decided for a multivariate classifier trained on the kinematics to perform the final selection step.





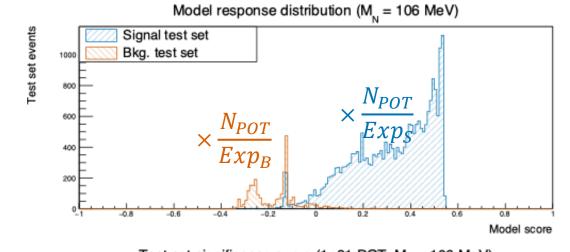


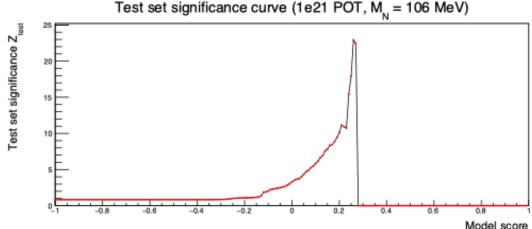
BDT and cut selection

- Single BDT is trained on all signal model samples against the background events
- For each signal model: computed the test-set significance as a function of the cut *t*:

$$Z_{test}(t) \equiv \sqrt{2\left[\left(S_{test}(t) + B_{test}(t)\right)\ln\left(1 + \frac{S_{test}(t)}{B_{test}(t)}\right) - S_{test}(t)\right]},$$

- S_{test} and B_{test} scaled from the production exposures
- Global BDT score t* found as the one maximising the worst test-set significance out of all signal models
- Tested several BDTs: chosen the one that maximises the significance on a benchmark model





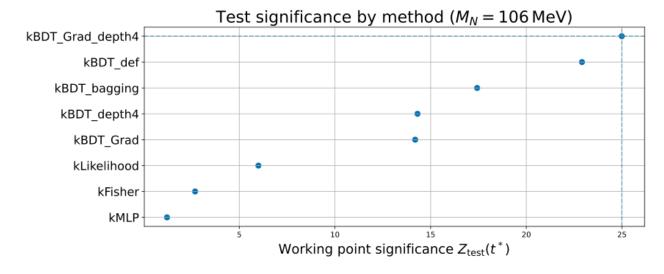


Choice of classifier

- Tested several classifier configurations, focusing on BDTs
- Reference classifiers of different types

Tested BDT models	MaxDepth	nCuts	${\tt BaggedBoost}$	BoostType
kBDT_def	3	20	no	AdaBoost
kBDT_Grad	3	50	no	GradBoost
kBDT_depth4	4	50	no	AdaBoost
kBDT_Grad_depth4	4	50	no	GradBoost
kBDT_bagging	3	50	yes	AdaBoost
Reference classifiers				
kLikelihood		Projective likelihood classifier		
kFisher		Fisher discriminant classifier		
kMLP		Multi-Layer Perceptron model		

• Selected the classifier with the best test-set significance $Z_{test}(t^*)$



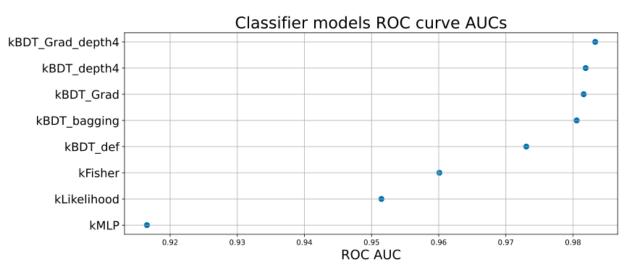
Best working-point significance found for kBDT Grad depth4



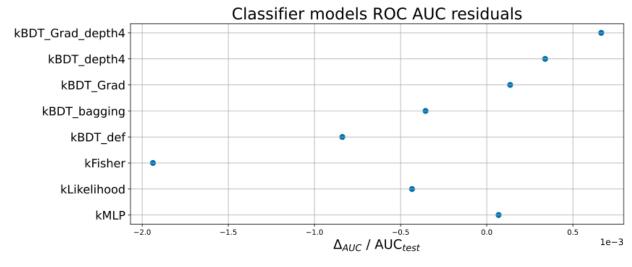


Initial classifier assessment

Basic performance assessment considering the ROC curve



Both BDT and reference classifiers are correctly trained



Relative train-test AUC residual: 0.05% residuals indicate negligible overtraining





Decay length correction

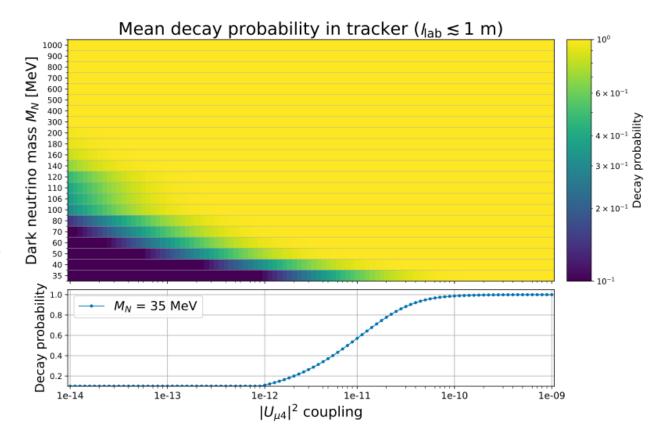
• It's not just the x-sec that scales with U^2 , the Dnu decay rate goes as:

$$\Gamma_{N\to Z'+\nu} \propto U^2 (1-U^2)$$

- At smaller couplings, the Dnu may decay outside the detector.
- Estimated the mean probability to decay within 1 m of the production point, relative to the production coupling:

$$A_{\lambda}(M, U^2) \equiv \frac{P_M(l_{det}, U^2)}{P_M(l_{det}, U_{prod}^2)}$$

• The resulting matrix is applied when scaling U^2 (~quite small effect)



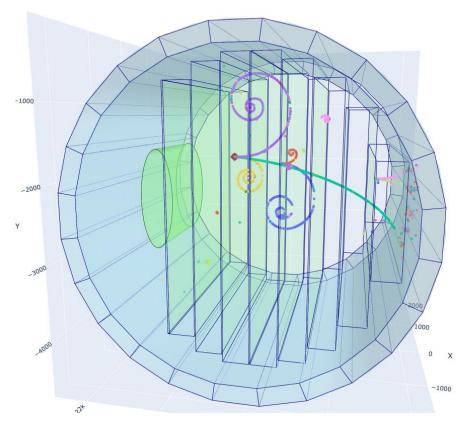




Event display

- Using the plotly Python library
- Generate outlines for:
 - GRAIN active volume
 - Drift supermodules
 - ECAL (hardcoded)
- 2D version in Matplotlib
- Data series added in custom functions
- Organised functions into a Python module (depends on code from analysis library)



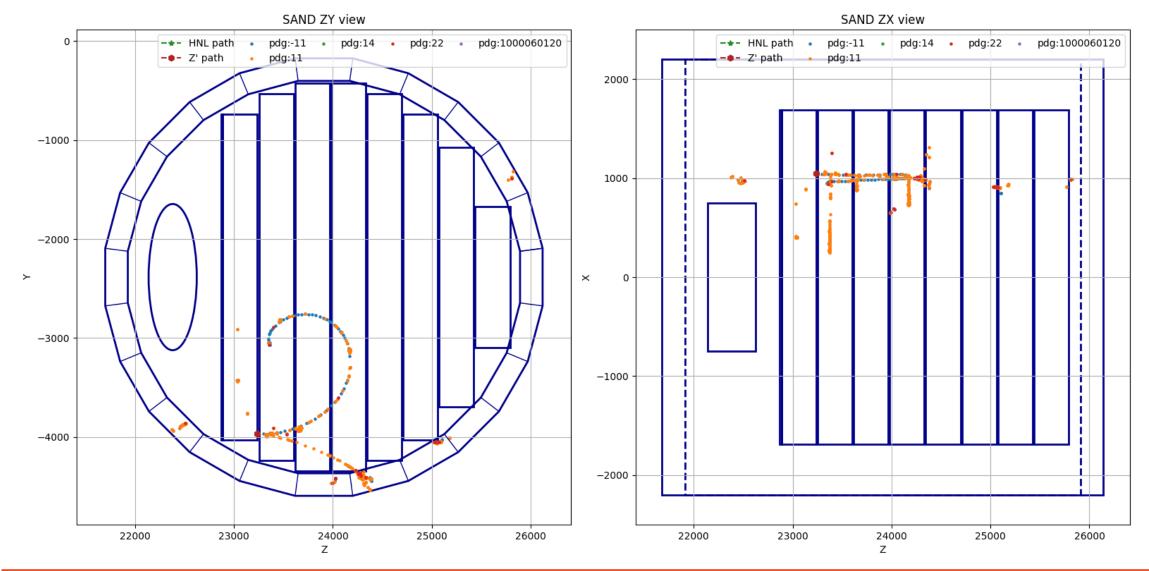


TrajectoryPoints by Trajectory ID





2D Display





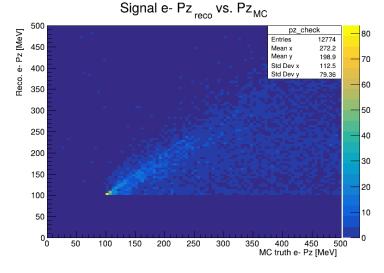


Preliminary tests of KF reconstruction

- KF does not yet include a Bremsstrahlung term
- Potentially keeping badly reconstructed tracks among the statistics
- Results do not seem significantly better than helicoidal fit
- Tried increasing the initial Covariance matrix terms (initial factor of 3x)

```
TMatrixD initial_cov_matrix(5, 5);
initial_cov_matrix[0][0] = 15*pow(200E-6, 2)
initial_cov_matrix[1][1] = 15*pow(200E-6, 2);
initial_cov_matrix[2][2] = 15*pow(0.1, 2);
initial_cov_matrix[3][3] = 15*pow(0.1, 2);
initial_cov_matrix[4][4] = 15*pow(0.1, 2);
```

Increased matrix terms by a factor of x3



Signal e- bending-plane momentum resolution

