# Mango DAQ update

**Twin Cameras** 

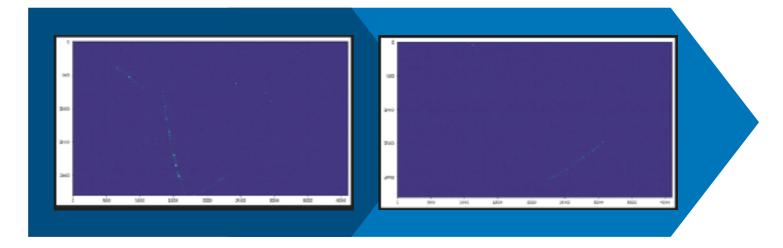
## **Previously on Mango:**



Set up continuous imaging CMOS mode

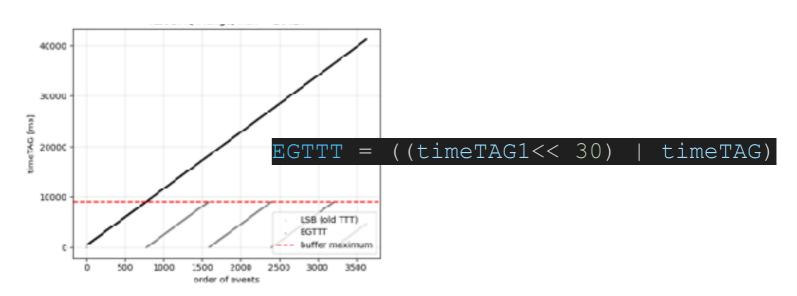


Cut Tracks seen





Trigger Time Tag extended to 60 bit





Proposed update to CygnoLib to support it All backward compatible

## More Cameras: software adjustment

#ifdef HAVE\_CAMERA
 #define NCAM\_MAX 6
#endif

New Macro for max number of cameras

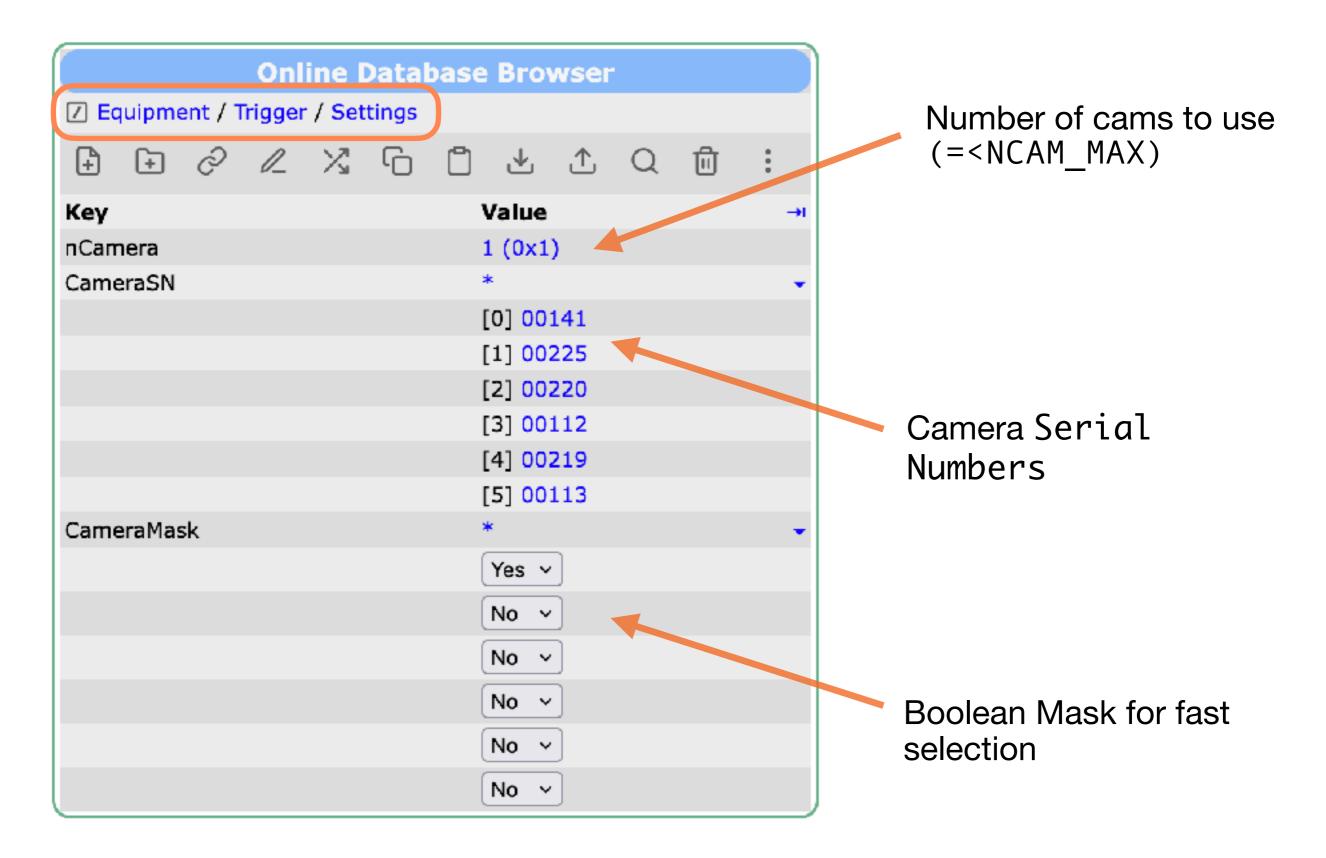
```
#ifdef HAVE_CAMERA
  int nCamera = 1;
  vector<HDCAM> gCam(NCAM_MAX, 0);
  vector<HDCAMWAIT> hwait(NCAM_MAX, 0);
  vector<bool> CamMask(NCAM_MAX, false);
  //HDCAMWAIT hwait = 0;
#endif
```

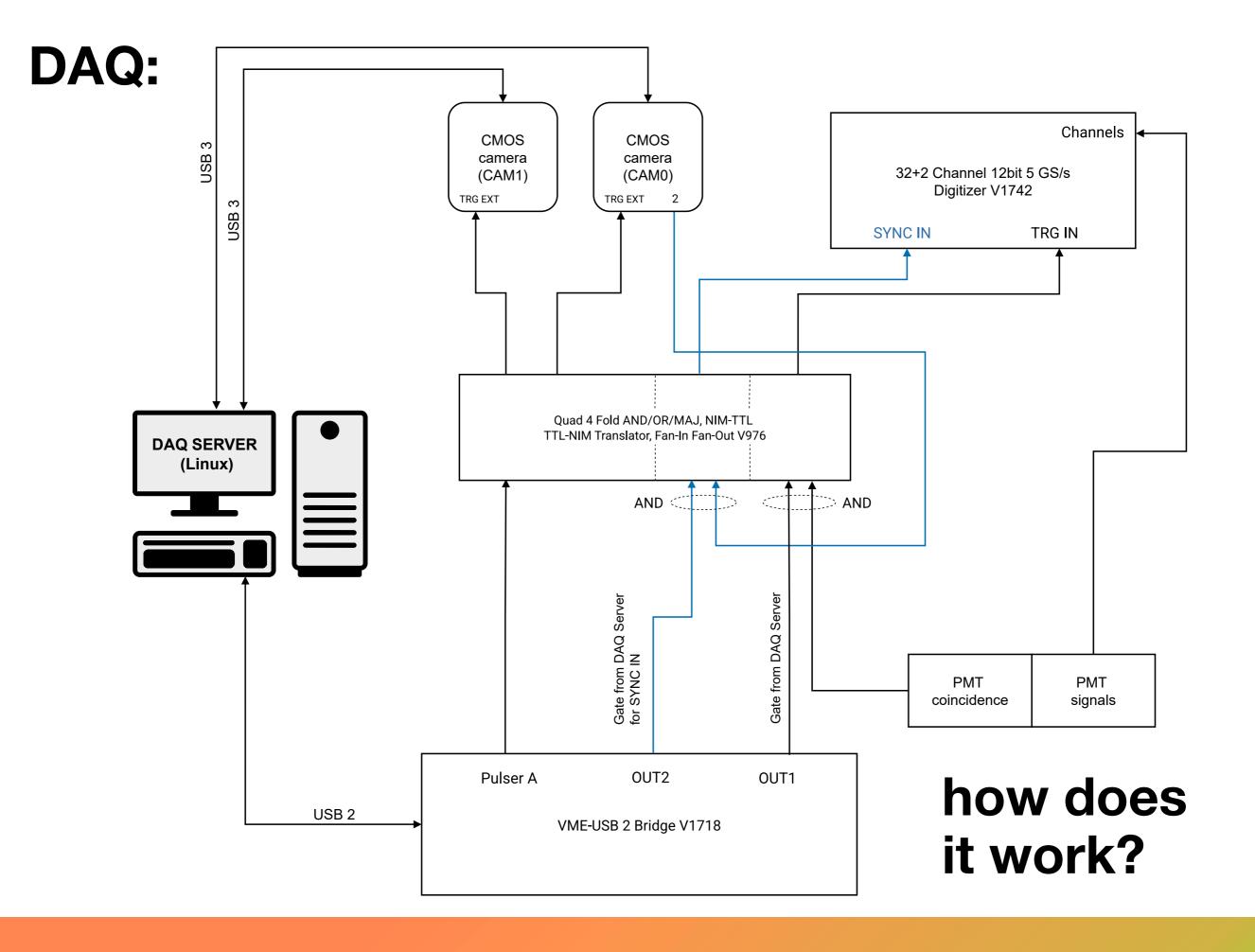
vectorisation of camera handles

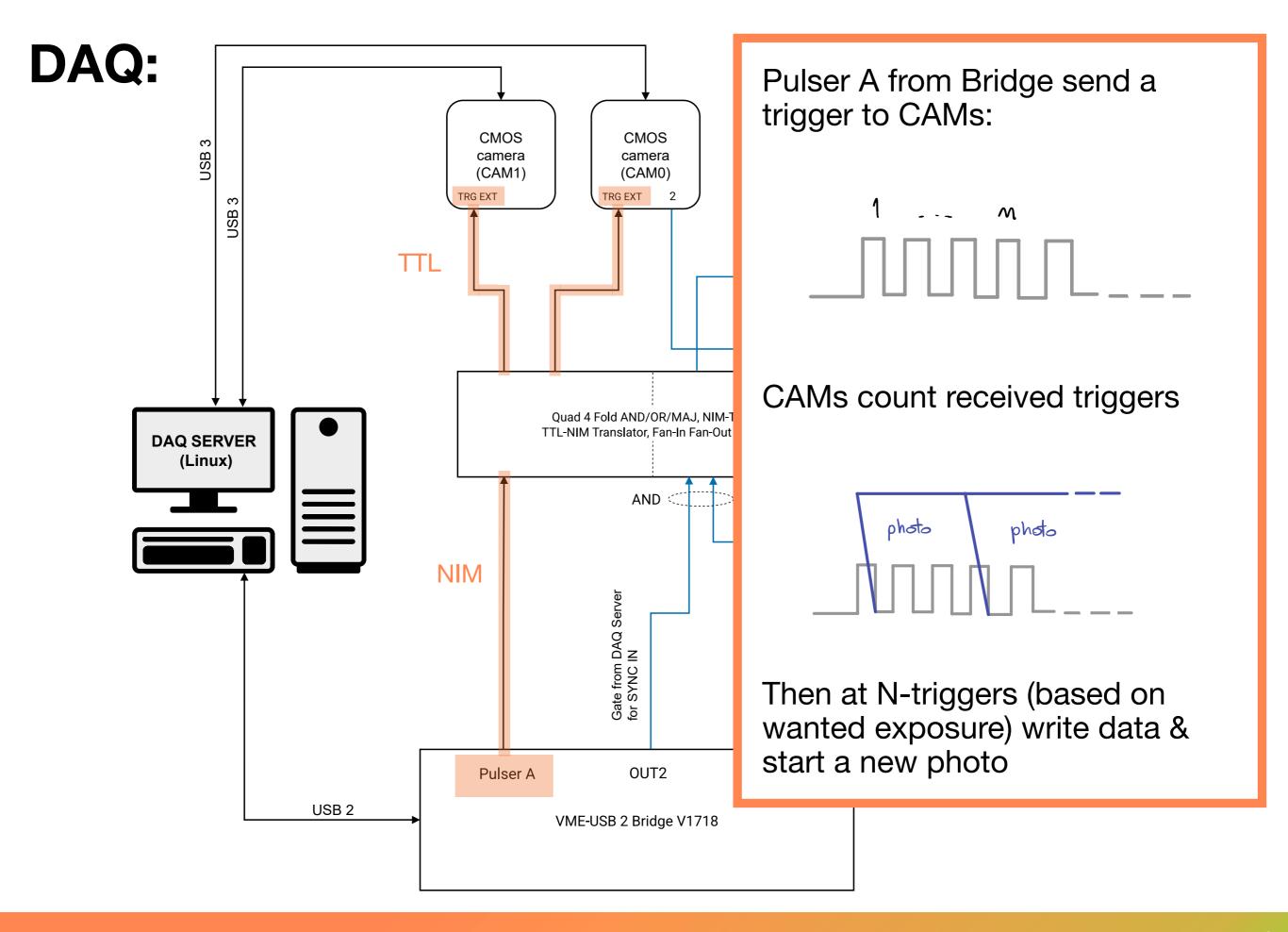


Updated frontend functions to loop over camera index icam

## easy cam management in ODB:

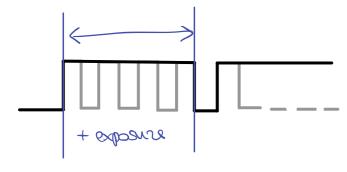




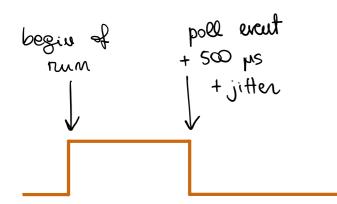


## DAQ:

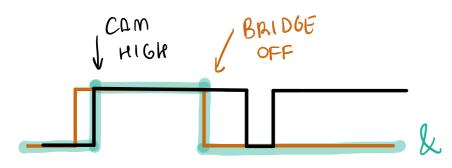
One of the cams (any of them, all are equivalent) sends a modified version of received trigger:

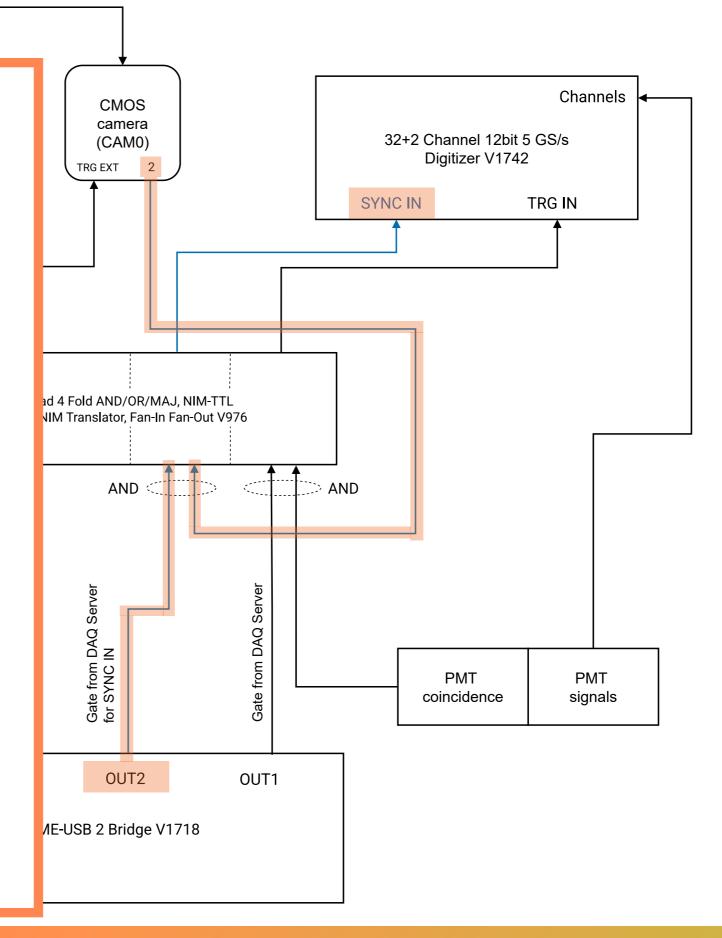


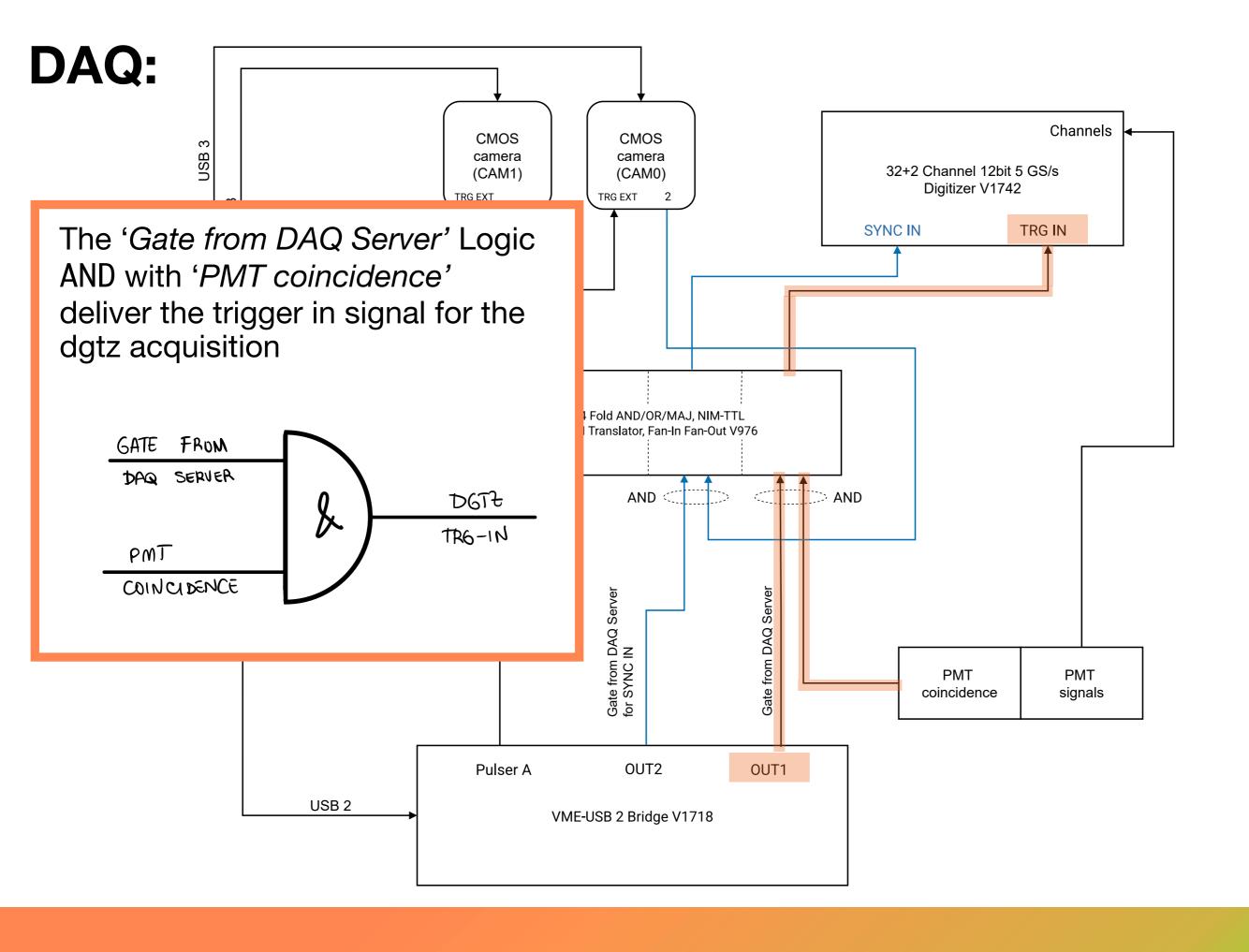
#### While the Bridge on OUT2:

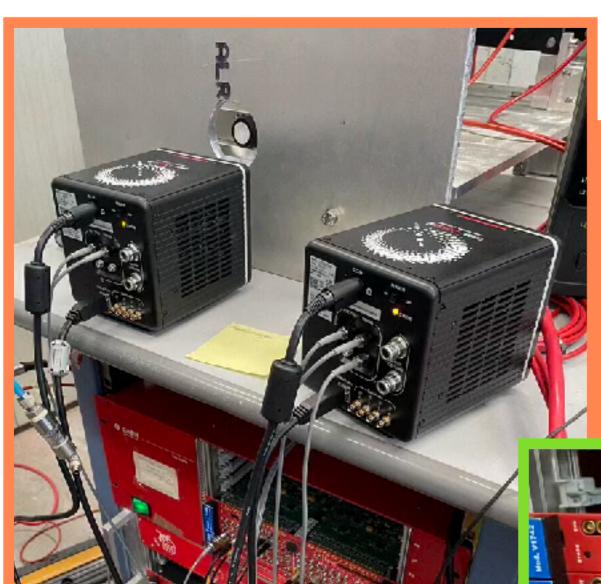


the AND-LOGIC guarantees the SYNC IN of the digitizer

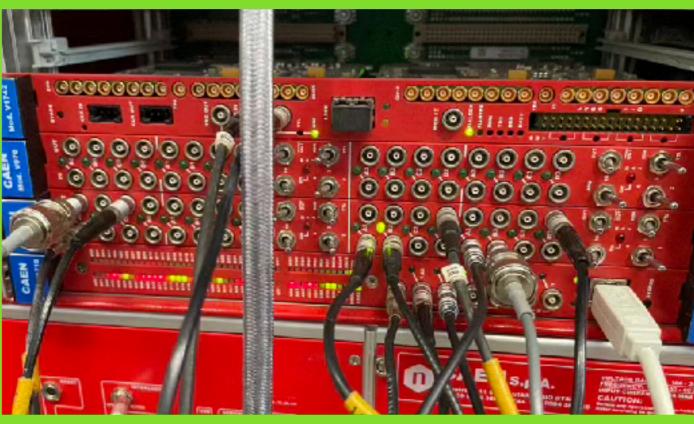


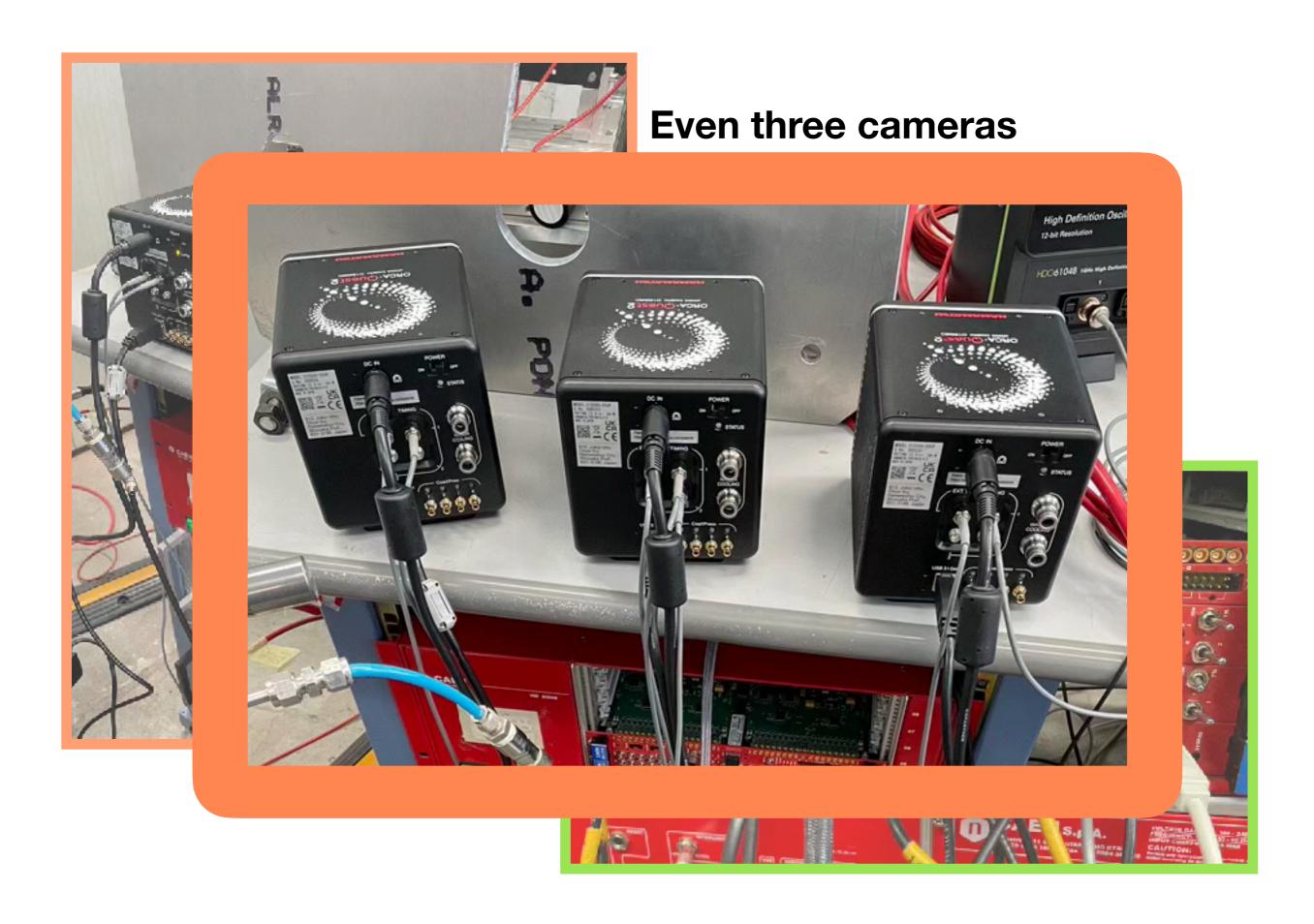




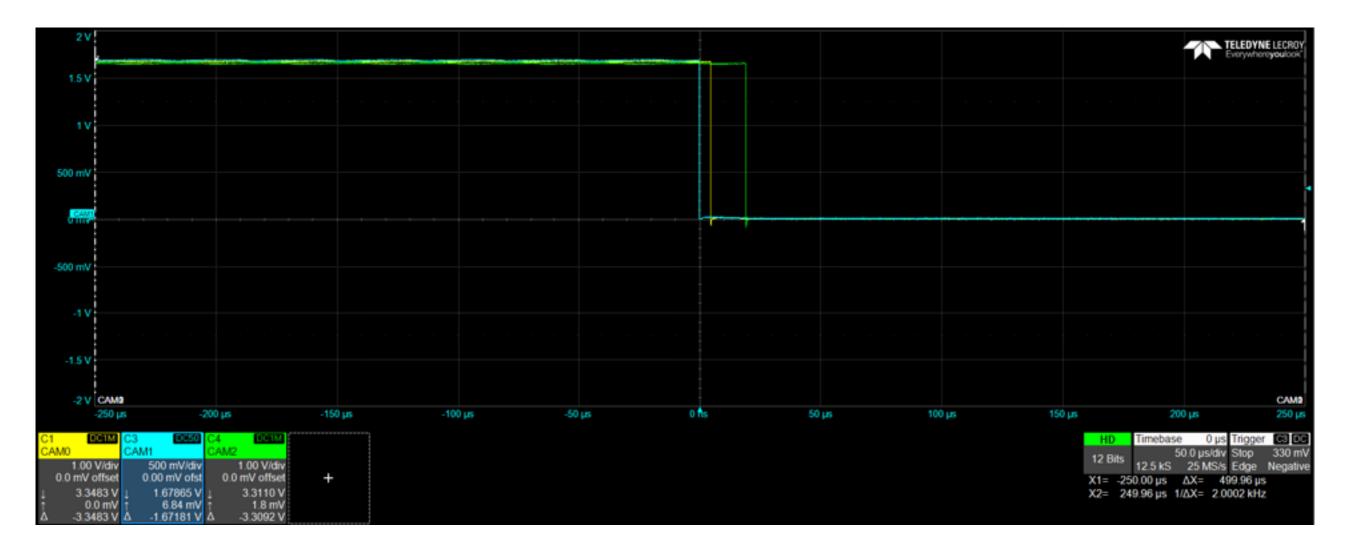


## Some photos





## Jitter evidence



Order of ~10us

### Jitter evidence

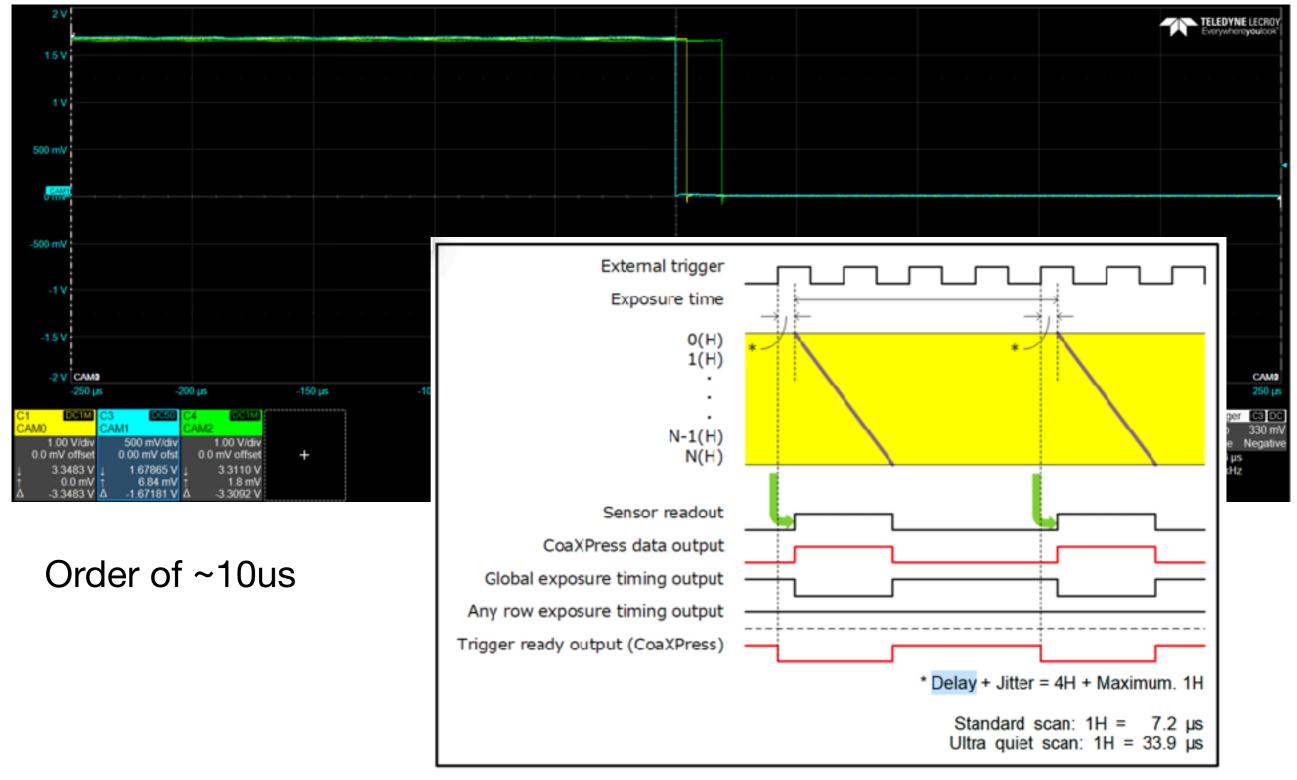
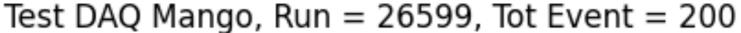


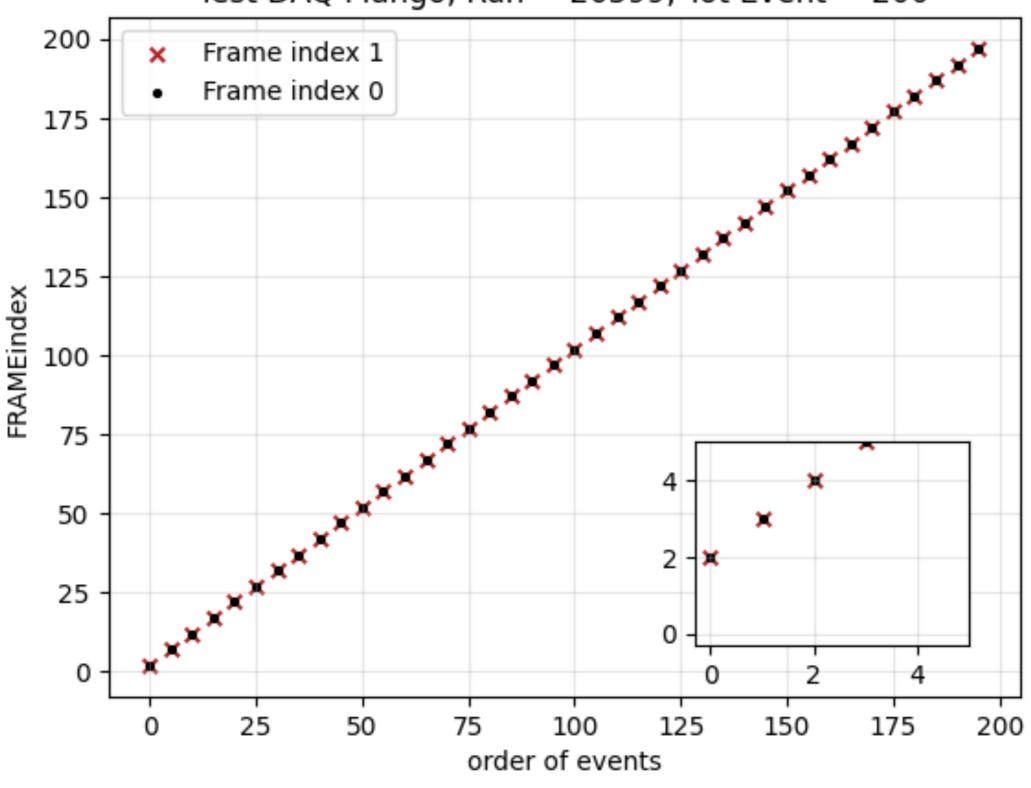
Figure 11-11 (Trigger Times)

## Frame index: OK

#### Same frame index

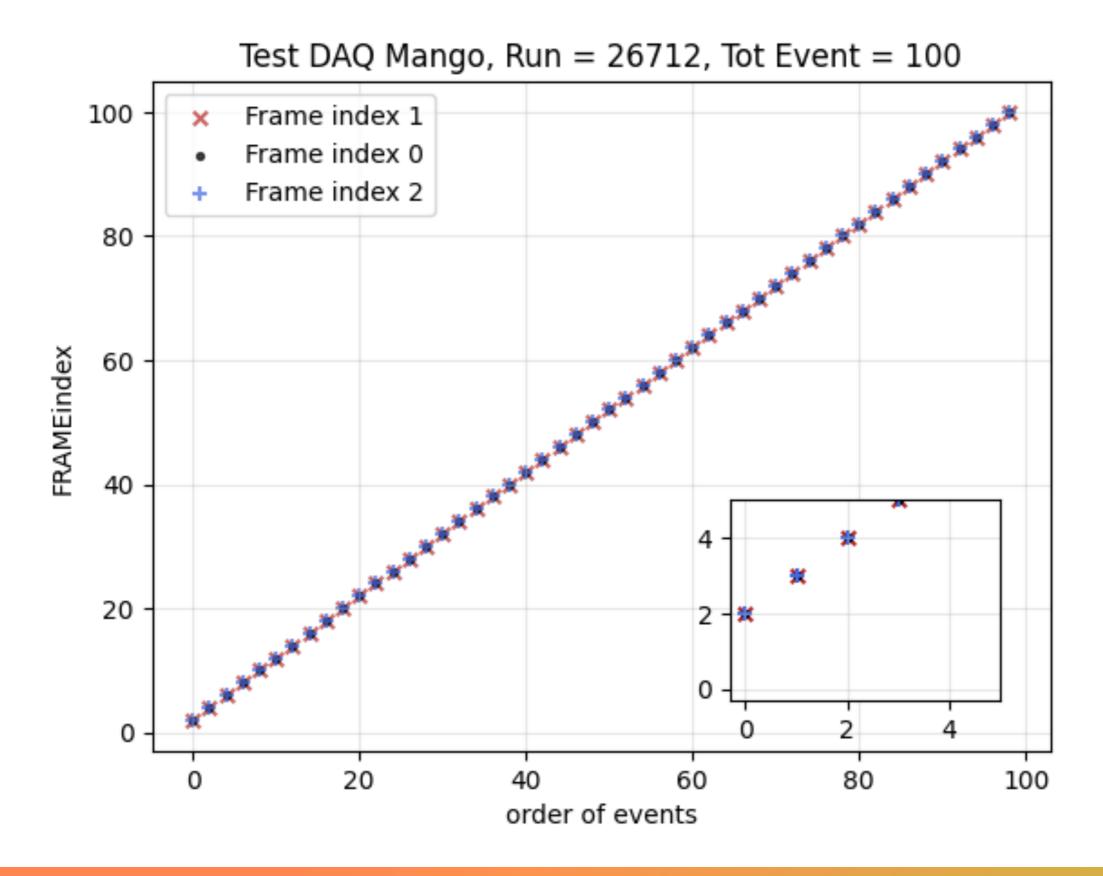
—> no frame skipped during readout



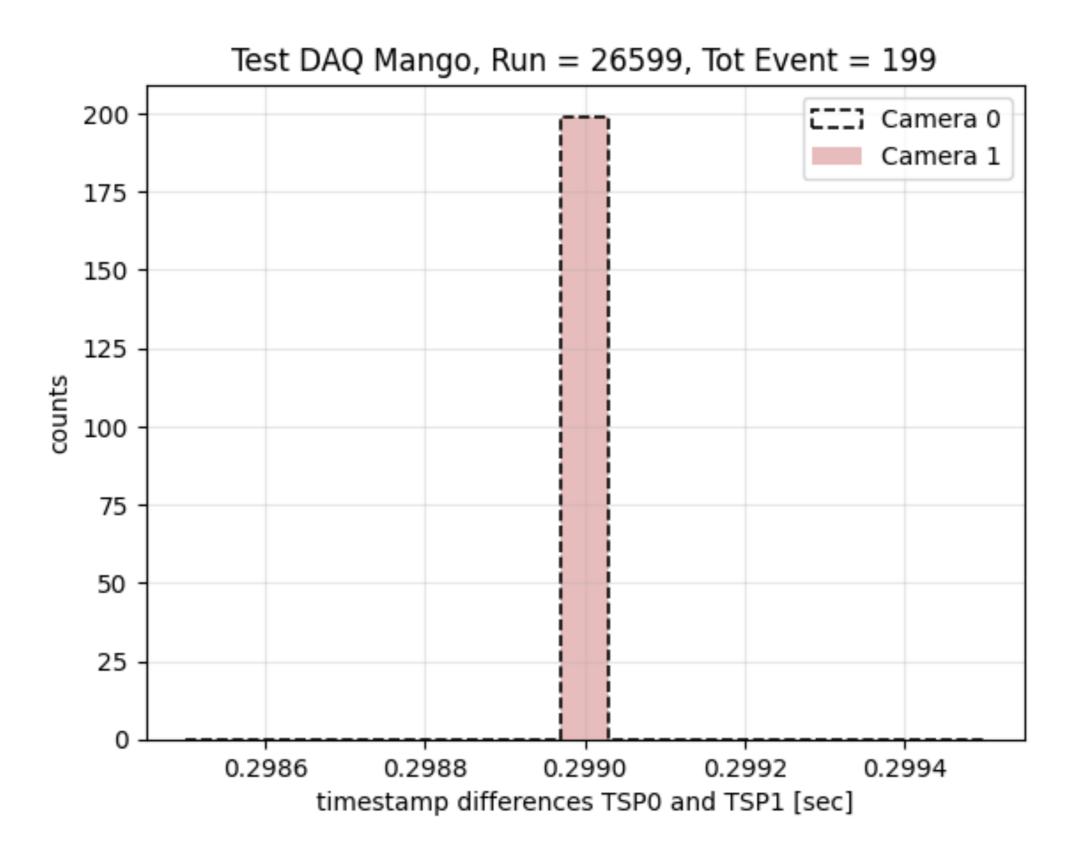


## Frame index: OK

#### **Even three cameras**



## **Exposure still consistent**



## Thanks for your attention