# Gibbs and Helmholtz ensembles for flexible and semiflexible polymers with elastic bonds

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Numerical results

Conclusions and future work

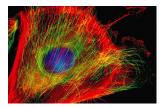
### Introduction to the problem

Stretching experiments on arbitrarily long single polymer molecules

Stretching experiments on single polymer molecules of arbitrary length opened the way for studying the statistical mechanics of **finite systems** with relevant applications to structured materials of **biological interest** 

Results of **stretching on DNA** have been found to be in **very good agreement** with **models** 





These results suggested that the mechanical properties of DNA, and in particular its **flexibility** have a **relevant role in many biological processes**  This importance has attracted many theoretical physicists who produced several **models and relationships** to explain the experimental results



### ⇒ understanding the force-extension relationship in polymers play an important role for the natural sciences

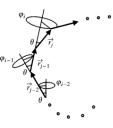
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#### Models of polymers Ideal chains: FJC, FRC, HRM

#### Freely-joined chain model (FJC)

- is the simplest model of a polymer
- fixed length polymer segments are linearly connected, and all bond and torsion angles are equiprobable
- the polymer can therefore be described by a simple random walk and ideal chain



Freely rotating chain model (FRC)

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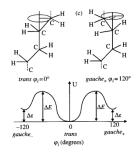
- takes into account that polymer segments make a fixed angle to neighbouring units because of specific chemical bonding
- under this fixed angle the segments are still free to rotate and all torsion angles are equally likely

#### Hindered rotation model (HRM)

the hindered rotation model assumes that

the torsion angle is hindered by a potential energy

• this makes the probability of each torsion angle proportional to a **Boltzmann factor** 



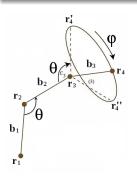
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## Models adopted in literature FJC and WLC

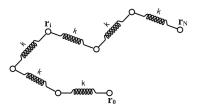
Models adopted in literature: polymer as an ideal chain

- freely jointed chain (FJC) and Worm-like chain (WLC) are tipically studied [2]
- these models describe a wide range of experimental results on molecules of biological interest including **DNA**



#### Two assumptions

- Main assumption 1: inextensibility of the bond
- Main assumption 2: infinite number of monomers



Our contribution deals with the thermoelastic response of a single chain **under stretching** with two specific features: the **extensibility of the bonds** between the monomers and the possibility to be **far from the thermodynamic limit** (arbitrary number of monomers) [1].

### Out of the thermodynamic limit different boundary conditions applied yield to different constitutive equations

- definition of flexible and semiflexible polymer models
- comparison between different boundary conditions  $\Rightarrow$  Helmholtz and Gibbs ensembles
- characterisation of the **convergence to the thermodynamic limit** with **power laws** and **scaling exponent**

Analytical approach: Statistical Mechanics foundation of polymers elasticity Definition of the problem

# Disordered polymers are too complex to be described using a deterministic method

#### $\Rightarrow$ Statistical approach is indeed mandatory

#### Main definitions and hypotheses

- A single monomer is characterized by **positions**  $\bar{r}_i (i = 1, ..., N)$  and **momenta**  $\bar{p}_i (i = 1, ..., N)$
- The hamiltonian of the system is:  $H = \sum_{i=1}^{N} \bar{p}_i \cdot \bar{p}_i / 2m_i + V(\bar{r}_1, ..., \bar{r}_N)$
- We consider the system in contact with a thermal bath at temperature T
- At thermal equilibrium, the **density probability** in the phase space is described by the Gibbs distribution:

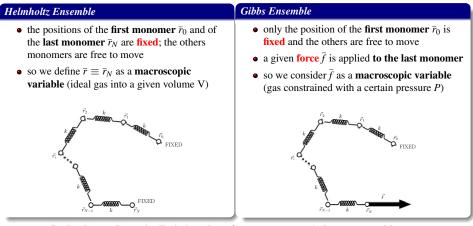
$$\rho(q,p) = \frac{1}{Z}e^{-\frac{H(q,p)}{k_BT}}$$

where  $Z = \iint_{\Gamma} e^{-\frac{H}{k_B T}} dq dp$  is the **partition function**.

## Original development: analytical approach

## **OUR GOAL**

Obtain the **thermodynamics** of the system starting from the above **Gibbs distribution**: two **dual approaches** are possible



In the thermodynamics limit (number of monomers  $\rightarrow \infty$ ) the two ensembles are equivalent

H

Theory results

Numerical results

Conclusions and future work

### Original development: analytical approach

Helmoltz and Gibbs ensemble

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1	<b>Hypotheses</b> : $\bar{r}_0$ fixed, $\bar{r}_N$ and $\bar{p}_N = 0$ fixed								
2	Hamiltonian:								
	(								

$$H = H(\bar{r}_1, ..., \bar{r}_N - 1, \bar{p}_1, ..., \bar{p}_N - 1; \bar{r}_N)$$

8 Partition function:

$$Z_r = Z(\bar{r}, T) = \iint_{\Gamma} e^{-\frac{H(q, p, \bar{r})}{k_B T}} dq dp$$

Equation of state:

$$\bar{f} = \langle \frac{\partial H}{\partial \bar{r}_N} \rangle = -k_B T \frac{\partial}{\partial \bar{r}} ln Z_r(\bar{r}, T)$$

#### Gibbs Ensemble

- **1** Hypotheses:  $\bar{r}_0$  fixed,  $\bar{f}$  applied to  $\bar{r}_N$
- **2** Augmented Hamiltonian:

$$H = H(\bar{r}_1, \dots, \bar{r}_N, \bar{p}_1, \dots, \bar{p}_N) - \bar{f} \cdot \bar{r}_N$$

#### **S** Partition function:

$$Z_f = Z(\bar{f}, T) = \iint_{\Gamma} e^{-\frac{H(q, p, \bar{f})}{k_B T}} dq dp$$

Equation of state:

$$\bar{r} = -\langle \frac{\partial H}{\partial \bar{f}} \rangle = k_B T \frac{\partial}{\partial \bar{f}} ln Z_f(\bar{f}, T)$$

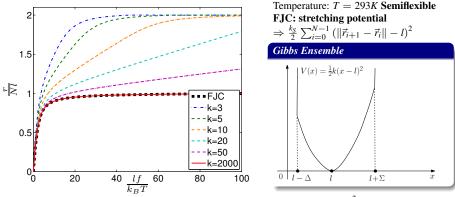
- we found an **analytic form of the partition function** Z for each ensemble  $(Z_r, Z_f)$
- we found the two Laplace transforms that allow us to switch between the two ensembles

Numerical results

### Original developement: analytical approach

Results for the FJC, Gibbs and Helmholtz ensemble (thermodinamic limit)

Elongation vs. traction curve for different values of the spring constant



The elongation *r* and the traction *f* varying in the range  $3 \le k_S \le 2000 k_B T/m^2$ . Three different regimes:

- very small applied force: entropic zone, linear relation:  $r = Nl^2 f / (3k_B T)$
- **2** elastic region characterized by a slope proportional to  $k_S$
- finally it is reached the saturation at the energy barrier  $l + \Sigma$ .

#### Original development: simulation approach Montecarlo Simulations

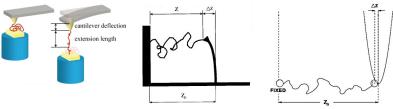
## **Original simulation results**

- Gibbs case: straightforwardly analytical/numerical results
- Helmholtz case: much more difficult to handle because of numerical instabilities

 $\Rightarrow$  a numerical approach can **bypass** such problems

## We developed a Metropolis Monte Carlo benchmark for the two ensembles

we imposed the **stretching** of the polymer under a force provided by a **cantilever** [3] with a proper adjustable **elastic stiffness**  $k_{trap}$ 



- mean force on the polymer:  $\langle f \rangle = k_{trap} \langle \Delta z \rangle$
- soft cantilever: Gibbs ensemble  $(k_{trap} = 0.01 \ k_B T/m^2)$
- stiff cantilever: Helmholtz ensemble  $(k_{trap} = 100 k_B T/m^2)^{<\Box} \rightarrow \langle \Box \rangle \langle \Xi \rangle \langle \Xi \rangle \langle \Xi \rangle \langle \Xi \rangle$

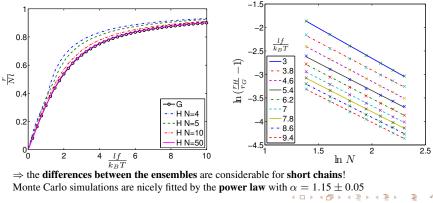
#### Freely Jointed Chain Original results

#### Elastic response curves

- FJC  $\Rightarrow k_S = 2000 k_B T/m^2$
- Gibbs ensemble: **single curve** (independence of N)
- Helmholtz ensemble: **different curves** for different numbers of monomers

#### Elongations comparison at a fixed force

- $\frac{r_H(N)}{r_G} = 1 + \frac{a}{N^{\alpha}}$
- each curve corresponds to a different value of the **normalized force**



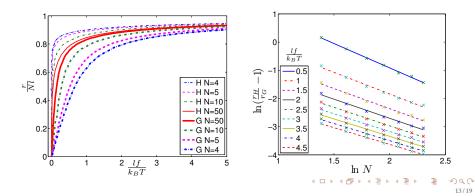
#### Worm Like Chain Original results

#### Elastic response curves

- WLC: bending potential  $\Rightarrow \frac{\kappa}{2} \sum_{i=1}^{N-1} (\vec{t}_{i+1} - \vec{t}_i)^2$
- $\Rightarrow k_S = 2000 \ k_B T / m^2$ ,  $\kappa = 1 \ k_B T$
- Gibbs ensemble: different curves for different numbers of monomers → dependence of N

#### Elongations comparison at a fixed force

- $\frac{r_H(N)}{r_G(N)} = 1 + \frac{a}{N^{\alpha}}$
- $\alpha = 1.30 \pm 0.05$



Numerical results

Conclusions and future work

#### Comparison with literature Simulations details

## Marko and Siggia - Rosa et al.

Marko and Siggia interpolation formula [6]

$$\frac{fl}{k_BT} = \frac{l}{L_p} \left[ \frac{1}{4(1-\zeta)^2} - \frac{1}{4} + \zeta \right]$$

 $\zeta = r/(Nl)$ : polymer extension normalized to the contour length  $L_p = l\kappa/(k_B T)$ :persistence length

asymptotically exact both in the large- and small-force limits of the continuous WLC model

#### Rosa et al. interpolation formula [7,8]

For the **discrete version** of the WLC model, where finite size of the equilibrium length *l* is accounted:

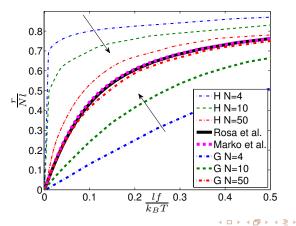
$$\frac{fl}{k_BT} = \frac{2L_p}{l} \left[ \sqrt{1 + \left(\frac{l}{2L_p}\right)^2 \frac{1}{(1-\zeta)^2}} - \sqrt{1 + \left(\frac{l}{2L_p}\right)^2} \right] + \left[ 3\frac{1-\mathcal{L}\left(\frac{L_p}{l}\right)}{1+\mathcal{L}\left(\frac{L_p}{l}\right)} - \frac{\frac{l}{2L_p}}{\sqrt{1 + \left(\frac{l}{2L_p}\right)^2}} \right] \zeta$$

 $\mathcal{L}(x) = \operatorname{coth} x - 1/x$  (Langevin function)

## Worm Like Chain: comparison with literature

#### MC vs analytical approximation

- the analytical approximation curves are **contained** between the Gibbs and Helmholtz Monte Carlo solutions for *N* **small**
- very good agreement with the behaviour of the WLC model at the **thermodynamic limit** (N > 50 in this case)



#### Semiflexible Freely Jointed Chain Original results

Main assumption in both the standard FJC and WLC models: inextensibility of the bonds but when considering large forces elasticity of chemical bonds becomes important

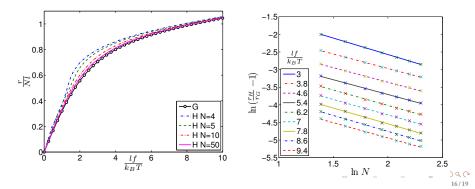
- $\rightarrow$  we set a small value for the elastic constant of the spring between the monomers
- $\rightarrow$  from the pure FJC model to a **Gaussian-FJC model** (extensible bonds)

#### Elastic response curves

• stretching constant:  $k_S = 10 k_B T/m^2$ 

#### Elongations comparison at a fixed force

• 
$$\frac{r_H(N)}{r_G} = 1 + \frac{a}{N^{\alpha}}$$



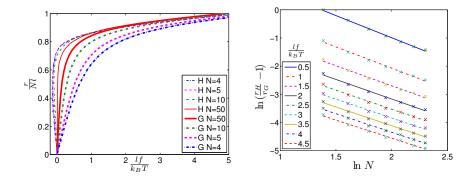
## Semiflexible Worm Like Chain Original results

#### Elastic response curves

- stretching constant:  $k_S = 10 k_B T/m^2$
- bending constant:  $\kappa = 1 k_B T$

#### Elongations comparison at a fixed force

- $\frac{r_H(N)}{r_G(N)} = 1 + \frac{a}{N^{\alpha}}$
- $\alpha = 1.40 \pm 0.05$



#### Conclusions and future work

#### Analytical development and results

- WE HAVE:
  - considered the differences in the force-extension curves between the Gibbs and Helmholtz ensembles
  - explicitly formulated flexible and semiflexible polymer models, with and without extensible bonds

#### **Computational development and results**

- WE HAVE:
  - **1** set a workbench for molecular simulations: Metroplolis Monte Carlo
  - 2 checked our previous theoric results by way of the simulation feedback
  - Oproved that different ensembles lead to the same results when stretching a polymer chain if the number of monomers is large enough
  - Showed how the convergence to the thermodynamic limit upon increasing N follows a suitable power law

#### Future works

- WE PLAN TO:
  - 1 extend the models to more complex, eventually with nonlinear springs
  - 2 consider models able to describe conformational transitions of a polymer chain
  - Study the statistical mechanics of flexible chains immersed in a solvent

Outline	Introduction and motivations	Models of polymers	Theory results	Numerical results	Conclusions and future work
Biblic	ography				

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