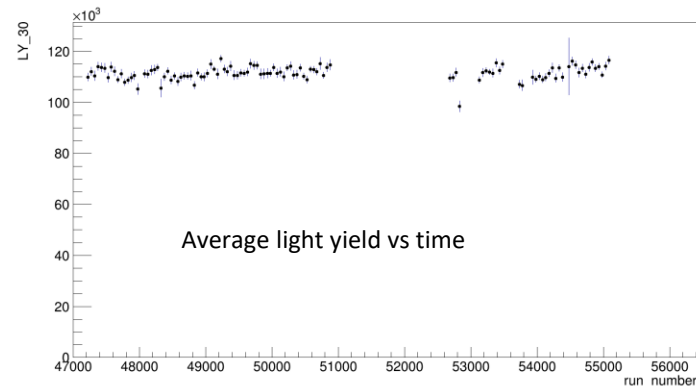


WP2

Giorgio Dho

Istituto Nazionale di Fisica Nucleare (INFN-LNF), Frascati (RM), Italy

WHERE WERE WE



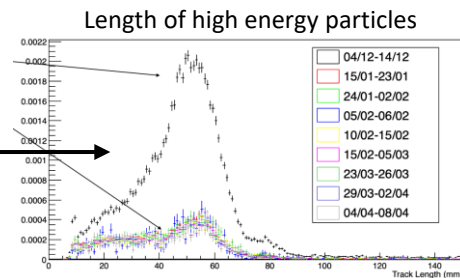
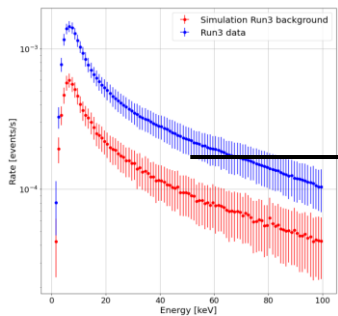
- Data Analysis on Run4 data (copper and water shielding) was begun.

Highlighted stability of data taking
(>90% duty cycle)

- Data-MC comparison hinted internal contamination (Radon?)

Run3

Data and MC
energy spectra



- This half year we focused a lot on development of software and tools to more efficiently and better analyse data

Reconstruction

3D association

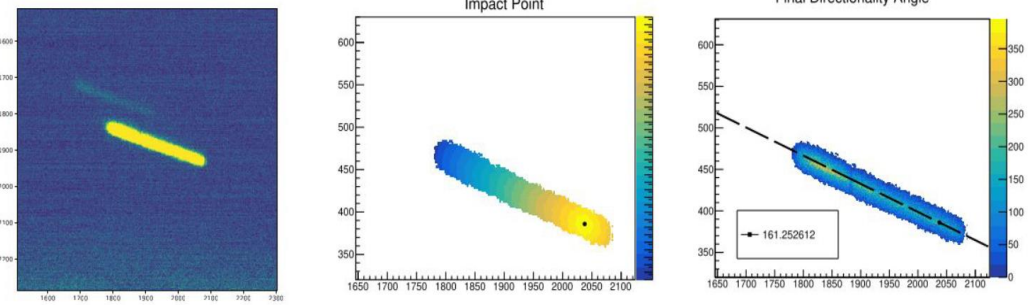
Digitisation (simulation)

Directionality

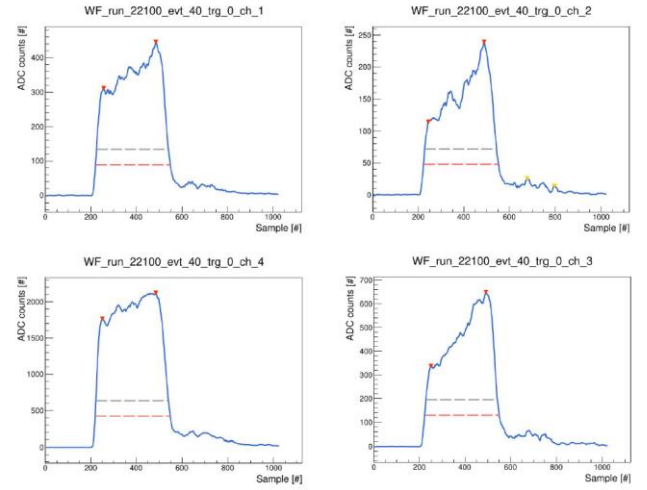
Physics fit

- To develop the 3D reconstruction algorithm we started simple → long, straight, not-so-rare tracks: **alphas**
- 2 detector type:

Camera



PMT



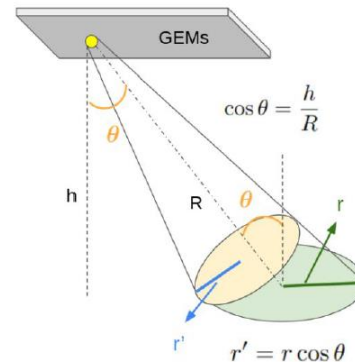
From X-Y pixel distribution and intensity we can obtain:

- bidimensional angle of direction (Φ)
- sense of direction in 2D
- Projected length in 2D

From relative intensity of PMT signals, Time over threshold and waveform shape we can obtain:

- sense of direction in Z
- Projected length in Z

3D RECO II



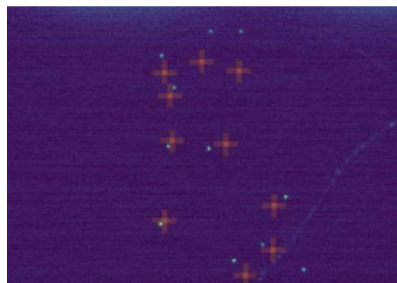
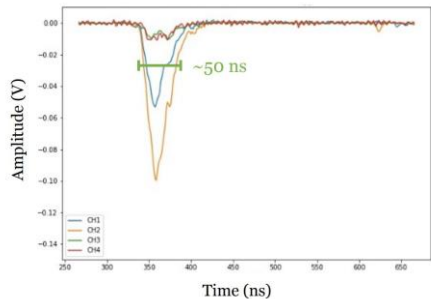
- $L'_{ji} = c_i \frac{L_j}{R_{ij}^\alpha}$
- $R_{ji} = \sqrt{x_{ji}^2 + y_{ji}^2 + z^2}$

One can retrieve from PMT signals x,y coordinate and L (light yield at GEM)

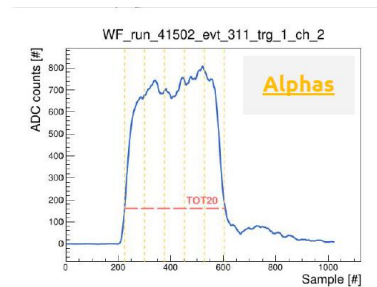
- Merging the two detector allows 3D reconstruction
- LIME has 4 PMTs whose distance from the event changes their intensity
- Important to match the signals of the detectors: multivariate Bayesian fit

$$p(\{x_{ij}\} | \theta) = \prod_{j=1}^{N_{points}} \prod_{i=1}^4 \mathcal{N}(\{x_{ij}\} | L'_{ij}(\theta))$$

1. Calibrated with iron signal with known x,y position from camera

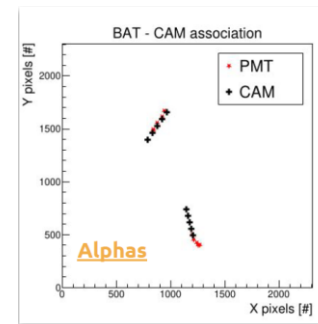


2. Applied to alpha signal



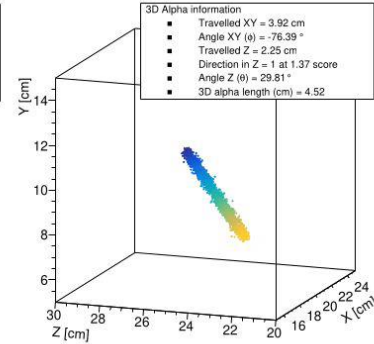
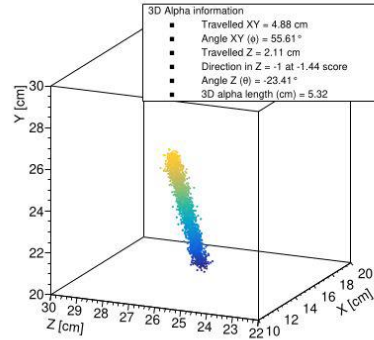
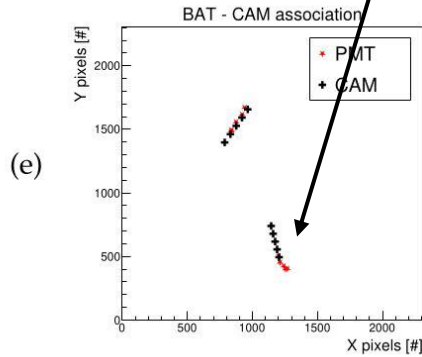
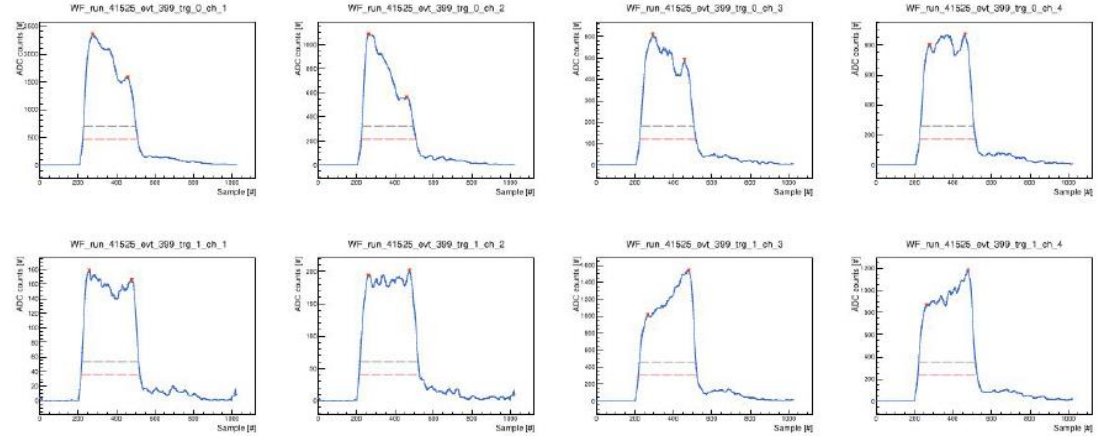
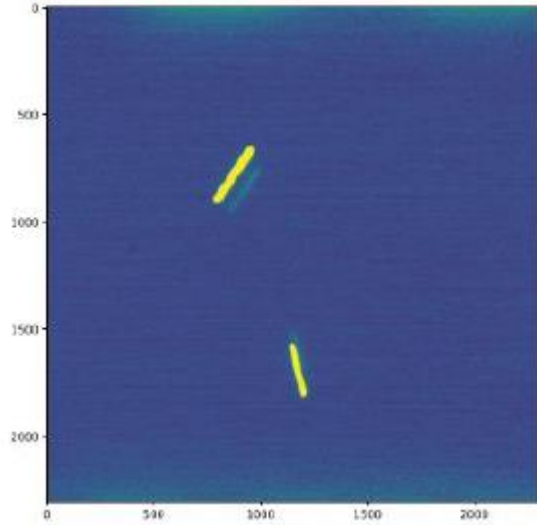
Signal sliced into 5 blocks

Accuracy within 2 cm



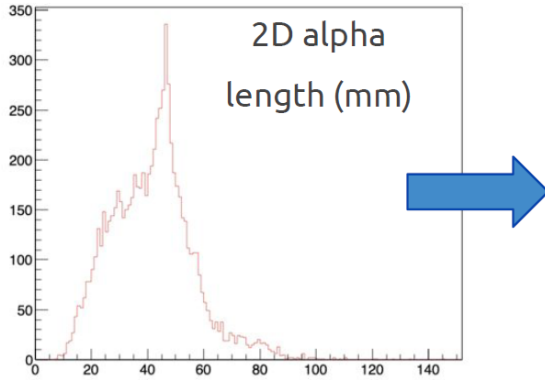
Enough for association purposes

3D RECO IIBIS



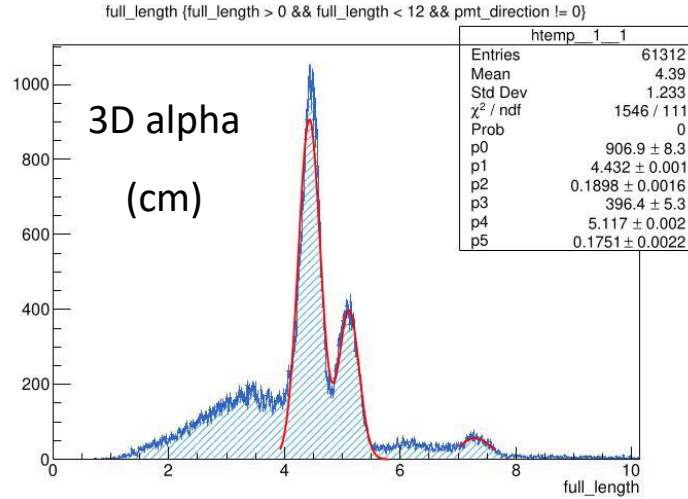
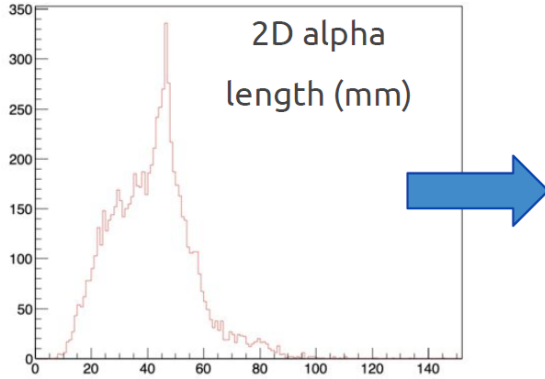
3D RECO III

- With 3D recoed tracks we can look at lengths

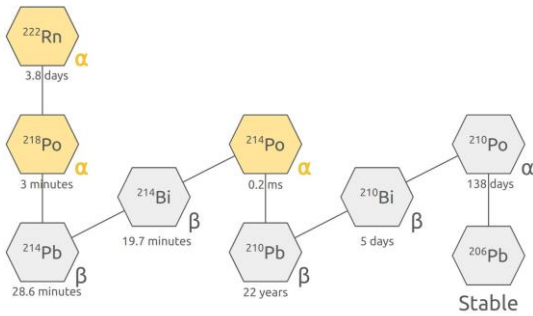


3D RECO III

- With 3D recoed tracks we can look at lengths



- Expecting Radon contamination:



Theory + *detector effect* (7% error)

- $^{222}\text{Rn} \rightarrow 5.50 \text{ MeV} \rightarrow 45.7 \text{ mm}$
- $^{218}\text{Po} \rightarrow 6.00 \text{ MeV} \rightarrow 51 \text{ mm}$
- $^{214}\text{Po} \rightarrow 7.69 \text{ MeV} \rightarrow 71 \text{ mm}$

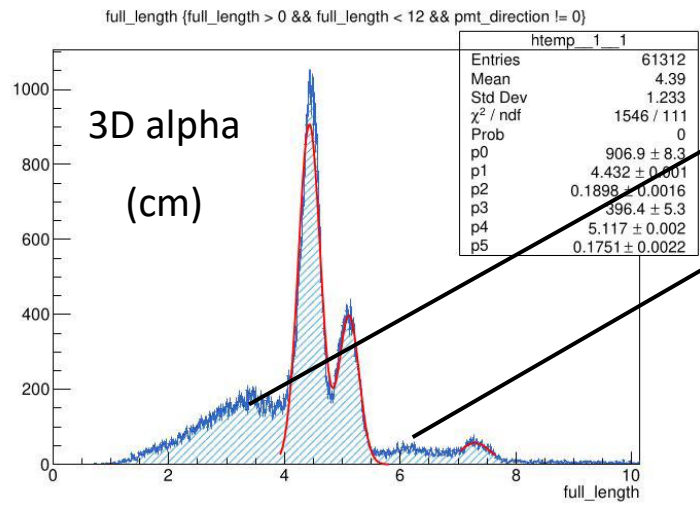
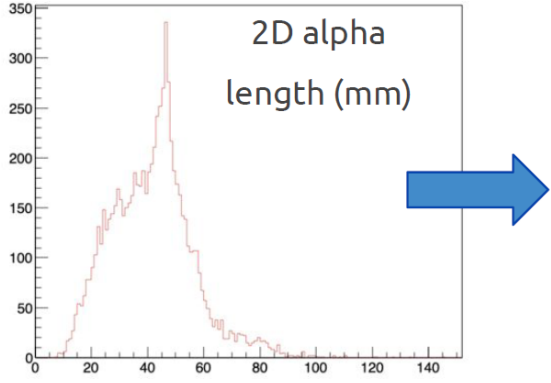
Measured (1% error)

- 44.3 mm
- 51.2 mm
- 72.9 mm

Radon contamination confirmed

3D RECO III

- With 3D recoed tracks we can look at lengths



33.7 mm

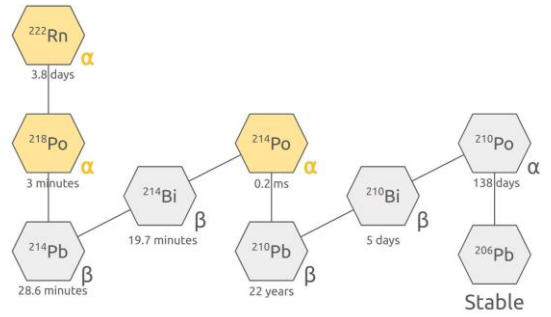
61 mm

Compatible with:

^{238}U

^{220}Rn or ^{216}Po

- Expecting Radon contamination:



Theory + *detector effect* (7% error)

Measured (1% error)

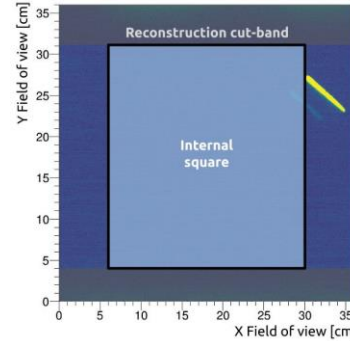
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- $^{214}\text{Po} \rightarrow 7.69 \text{ MeV} \rightarrow 71 \text{ mm}$

- 44.3 mm
- 51,2 mm
- 72.9 mm

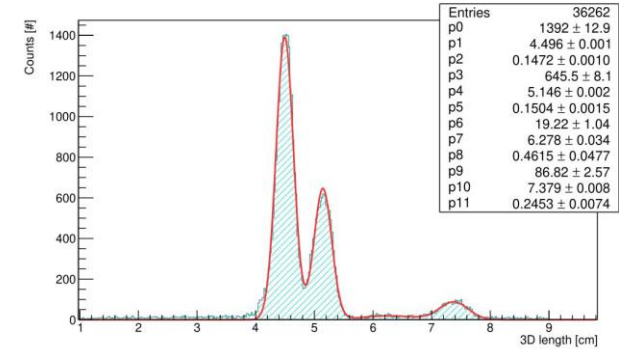
Radon contamination confirmed

3D RECO IV

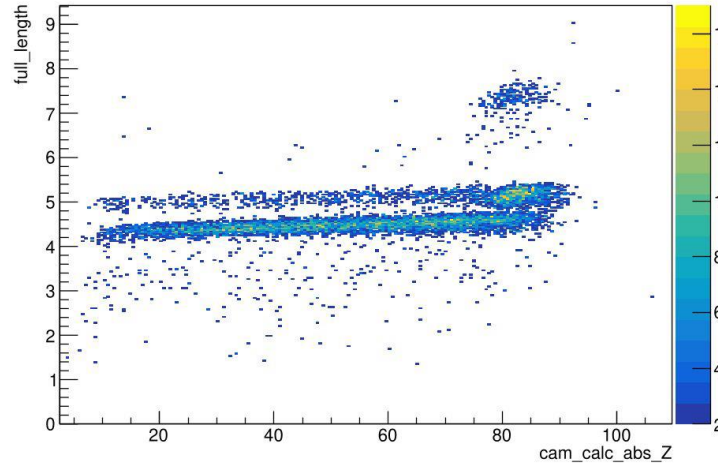
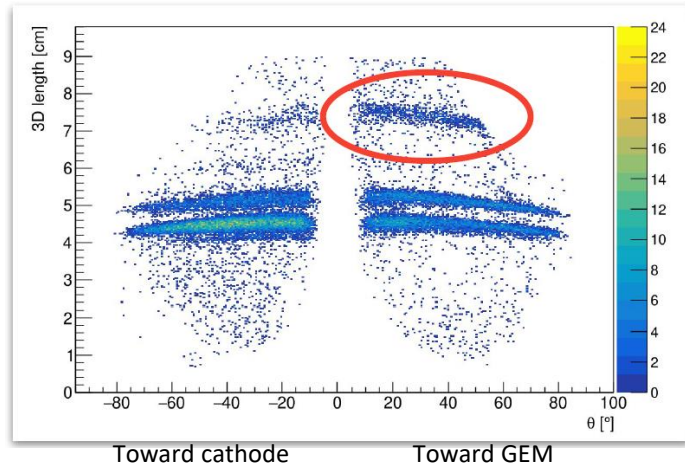
- What about orientation of these Rn daughter alphas?
- Selection in the centre to include cathode, GEM and detector gas (no borders with resistors and field rings)
- Inclination angle and rough estimation of absolute z coordinate support Radon daughter behaviour



(a) Geometrical cut - central square



(b) 3D length of alphas



Daughters, generated positively charged, will move to the cathode:

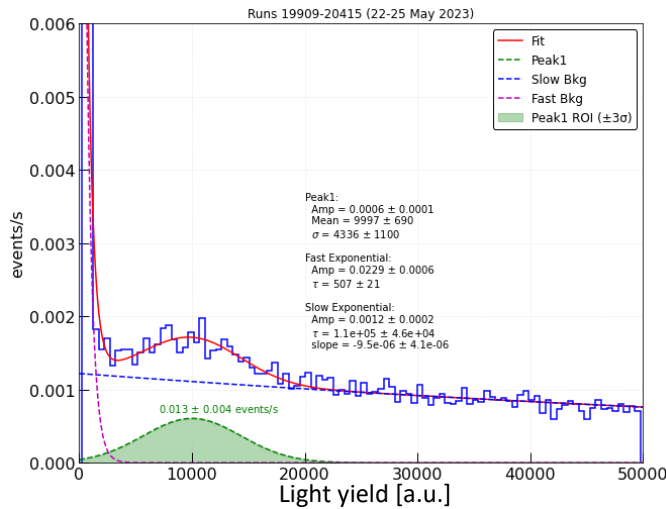
- Higher Z (closer to cathode)
- Emission mostly toward GEM

Potential of 3D just starts unveiling!

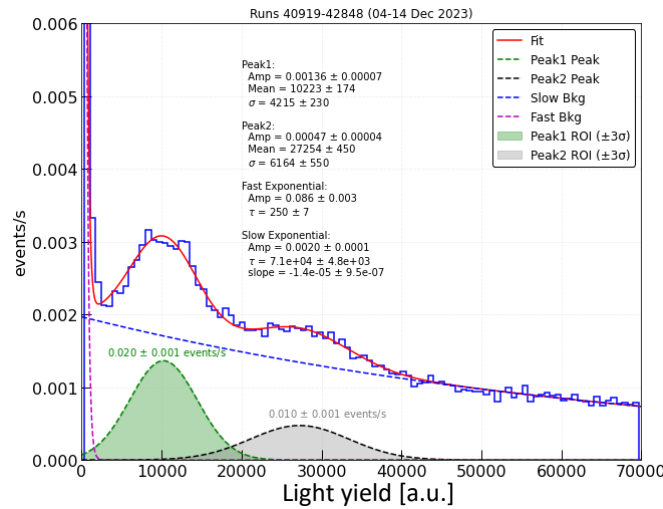
Paper in preparation

- Normalisation of spectra based on time duration of runs
- Different periods of data of Run4 taken into consideration
- Data normalised in light intensity: 10000 about 5.9 keV (non-linear response in z not considered yet)

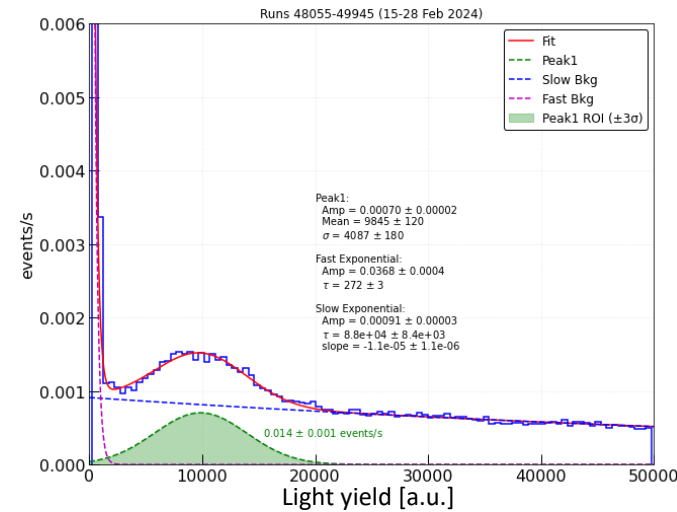
Run3 no ricirculation
low Rn



Run4 unfiltered
high Rn



Run4 filtered
low Rn

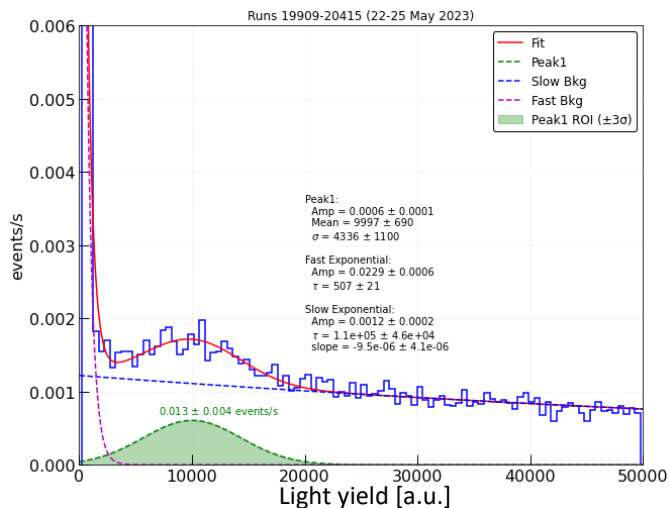


RUN4: LOW ENERGY

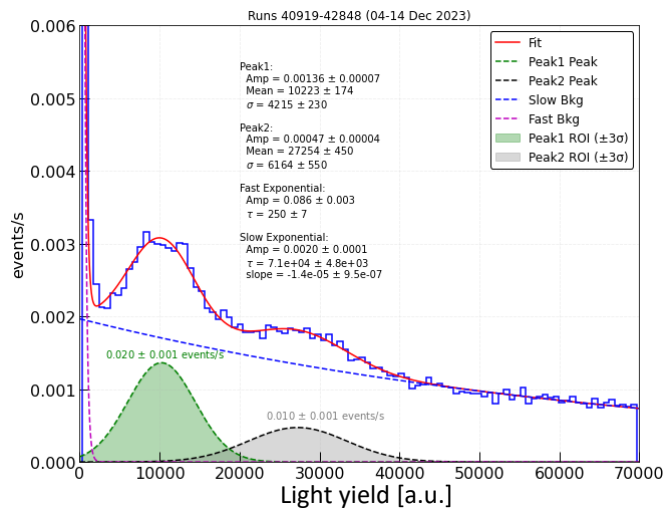
PRELIMINARY

- Normalisation of spectra based on time duration of runs
- Different periods of data of Run4 taken into consideration
- Data normalised in light intensity: 10000 about 5.9 keV (non-linear response in z not considered yet)

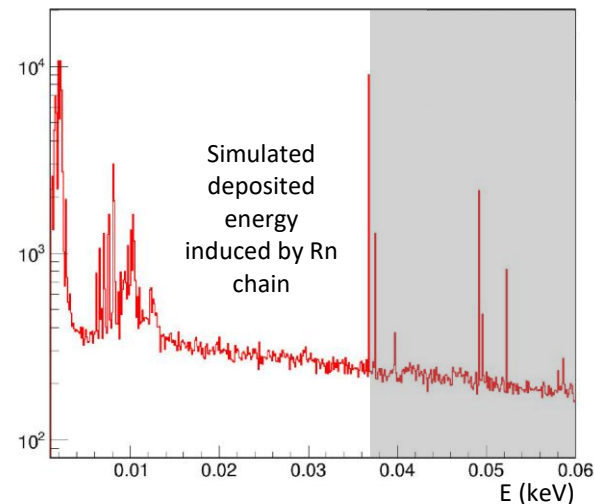
Run3 no ricirculation
low Rn



Run4 unfiltered
high Rn



Run4 filtered
low Rn



- MC comparison will give further insight

We are studying the impact of Rn chain on low energy region

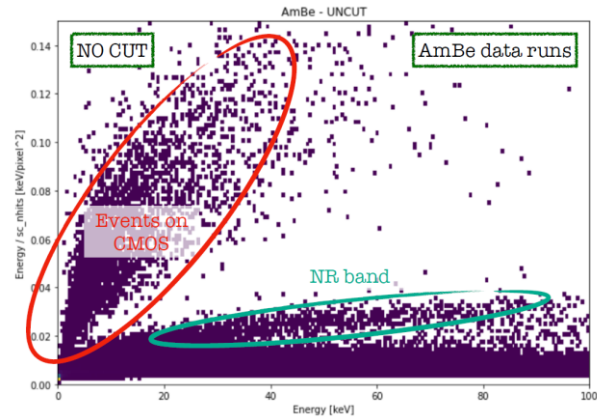
Simulation code improved to speed up MC comparison: Now 10 times faster and more efficient

RUN4: NEW VARIABLES

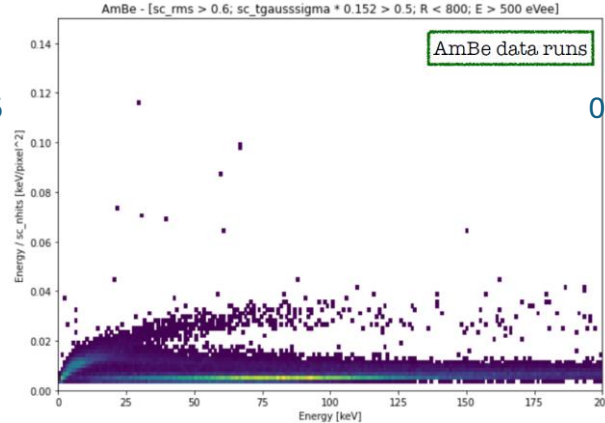
$$\rho \equiv \frac{sc_rms}{sc_nhits}$$

RMS of distribution of pixel intensity
Number of pixel above threshold

- New reconstructed variables exploiting pixel distribution and intensity

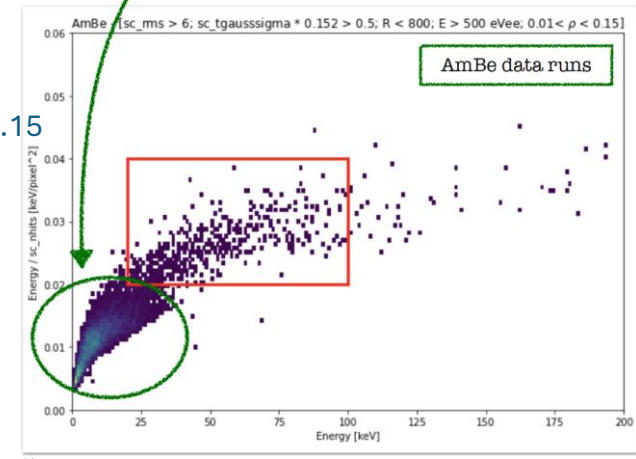


$\rho < 0.15$



$0.01 < \rho < 0.15$

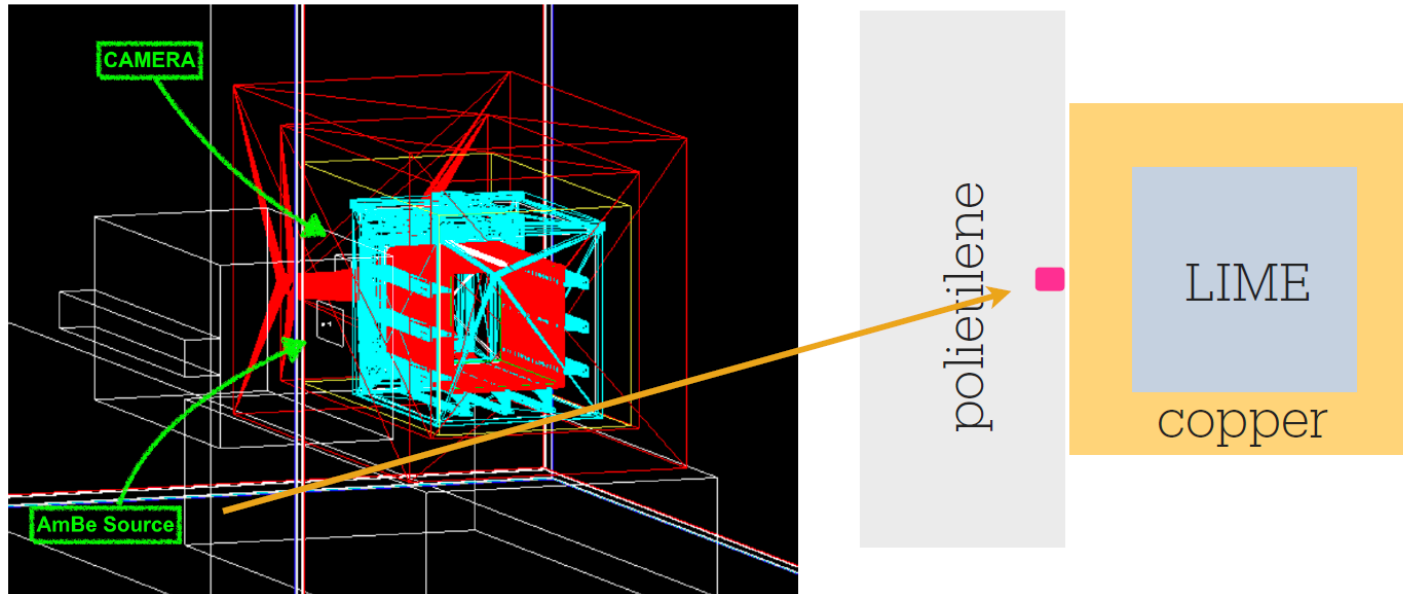
Still ER contamination



- This variable appears to be a good method to remove ER
- It will be included in ER/NR rejection studies

NUCLEAR RECOIL ANGULAR RESOLUTION

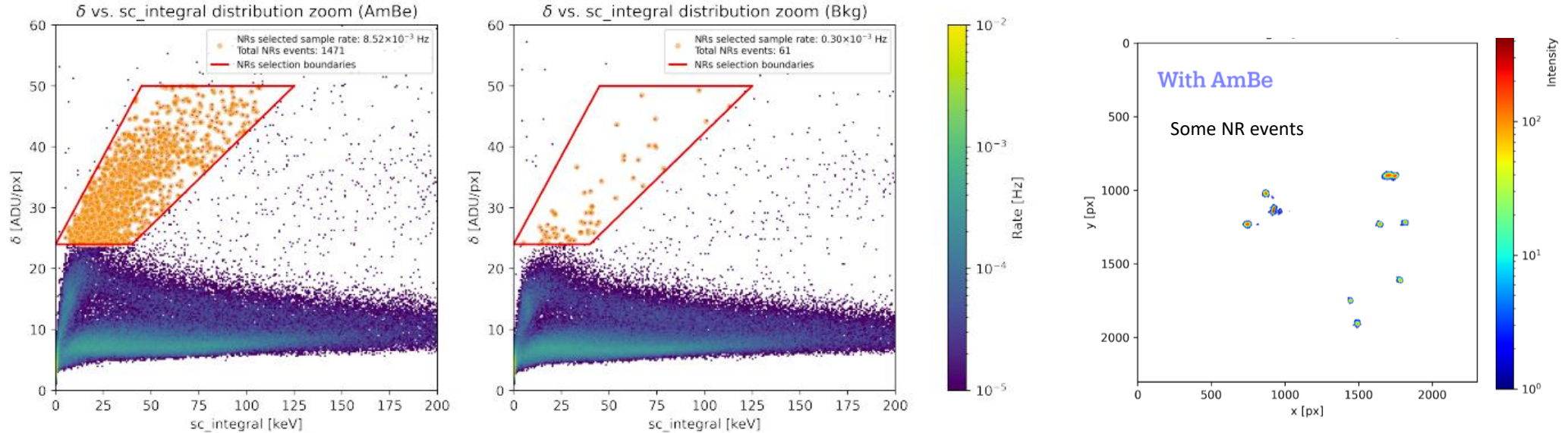
- AmBe neutron source was exploited to induce large amount of NR in LIME detector
- This data set is a key test bench for NR angular resolution measurements, ER/NR discrimination



- From the camera point of view, the neutrons emitted horizontally are aligned so that their angle is 0°

NUCLEAR RECOIL ANGULAR RESOLUTION II

- Arbitrary coarse selection on NR events

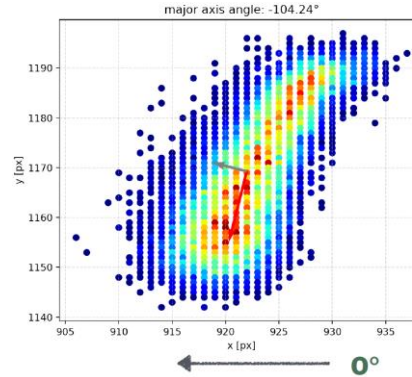


**Machine learning work on
ER/NR discrimination will
help improve selection and
select in lower energy range**

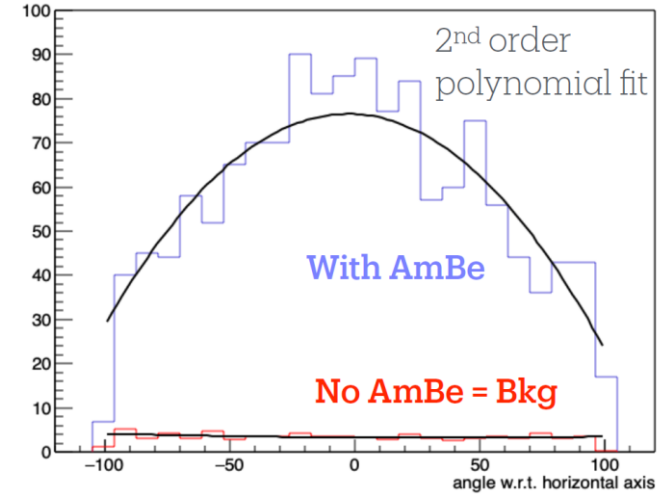
NUCLEAR RECOIL ANGULAR RESOLUTION III

PRELIMINARY

- Direction estimated by simple principal component decomposition
- Kinematic simulation of the recoil distribution is convoluted with gaussian angular resolution and tested with data



Data suggests 45° angular resolution above 100 keV_{ee}



Background is flat

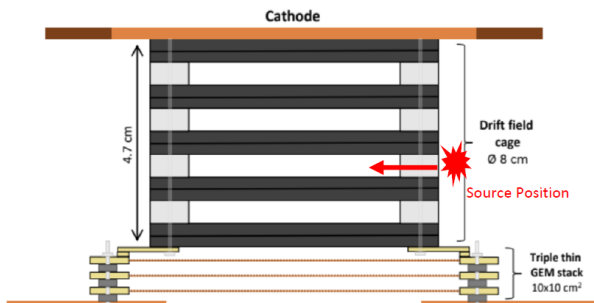
Source peaked at 0 deg

Convolution with source distribution to be removed

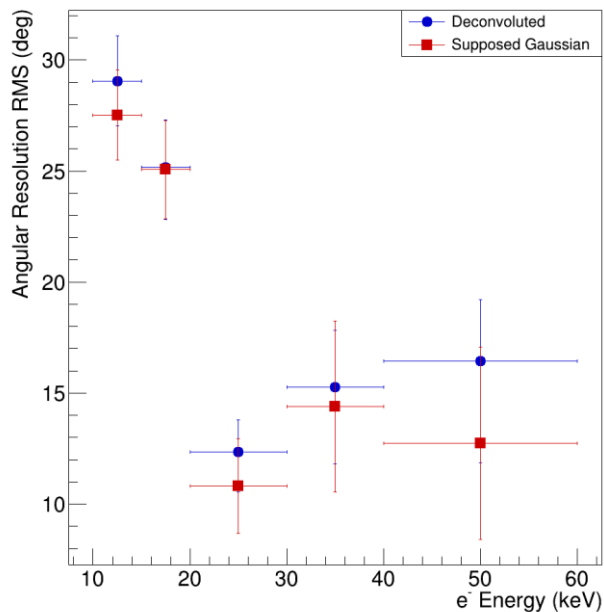
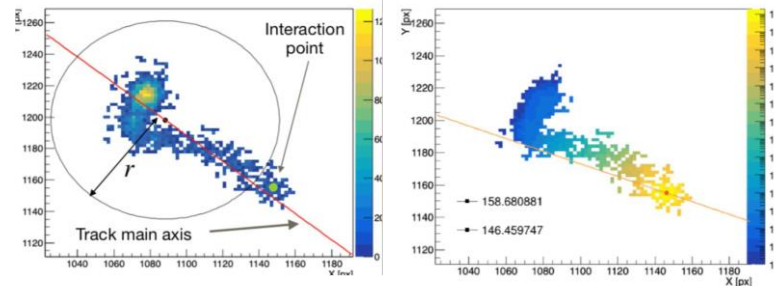
- 3D reconstruction can help improving the direction and the determination of the energy (by length)
- New simulation will improve the MC comparison

DIRECTIONAL RECONSTRUCTION

- Code for directional reconstruction was developed in the past
- Recently the code was improved and applied to real data taken with a prototype
- Beta⁻ emitter ⁹⁰Sr source



Confronting MC and data, the angular resolution was measured



- Excellent result on data for ER angular resolution
- HT 100% at all energies
- Can be adapted to NR and applied to AmBe data

Paper published in the context of the PRIN project

SENSITIVITY LIME

- The limit estimation and fit procedure of the data is a key element for dark matter physics
- Strong effort to put into a single code the calculation of the spectra of expected DM signal and the Bayesian fit procedure to estimate limit (BAT toolkit used)
- Limit evaluation based on Credible Interval calculated by exploiting Bayesian technique.

$$p(\vec{\mu}, \vec{\theta} | \vec{x}, H) = \frac{p(\vec{x} | \vec{\mu}, \vec{\theta}, H) \pi(\vec{\mu}, \vec{\theta} | H)}{\int_{\Omega} \int_D p(\vec{x} | \vec{\mu}, \vec{\theta}, H) \pi(\vec{\mu}, \vec{\theta} | H) d\vec{\mu} d\vec{\theta}} \quad \mu_1(90\%CI) : \int_0^{\mu_1(90\%CI)} p(\mu_1 | \vec{x}, H) d\mu_1 = 0.9$$

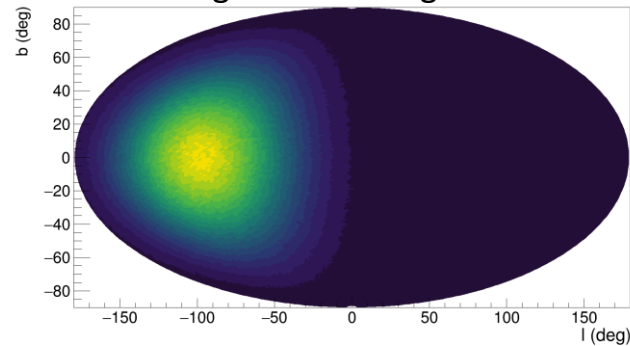
- In general based on a Likelihood profiled on measurable variables as direction and energy

$$\mathcal{L}(\vec{x} | \mu_s, \mu_b, H_1) = (\mu_b + \mu_s)^{N_{evt}} e^{-(\mu_b + \mu_s)} \prod_{i=1}^{N_{bins}} \left[\left(\frac{\mu_b}{\mu_b + \mu_s} P_{i,b} + \frac{\mu_s}{\mu_b + \mu_s} P_{i,s} \right)^{n_i} \frac{1}{n_i!} \right]$$

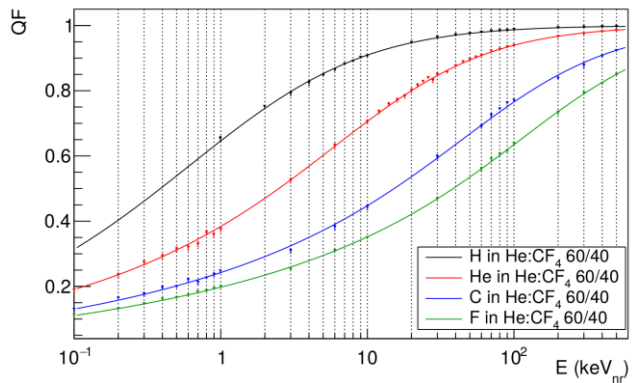
SENSITIVITY LIME II

- Detector effects which can be included are

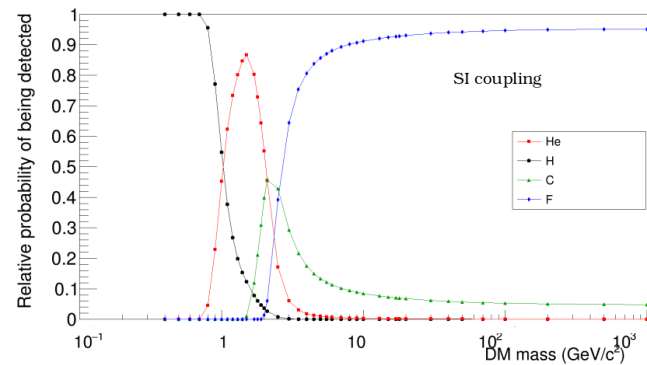
Angular and energy distribution of signal and background



Quenching factor of elements in gas



Mixture composition



- LIME **cannot** be used to estimate limits: unknown contamination -> no background model (LIME was not meant for this!!)
- However, we can use it to estimate where the exposure of the detector can lead us
- As a first test no measurable variables were included in the study:

As if LIME was a simple counting experiment



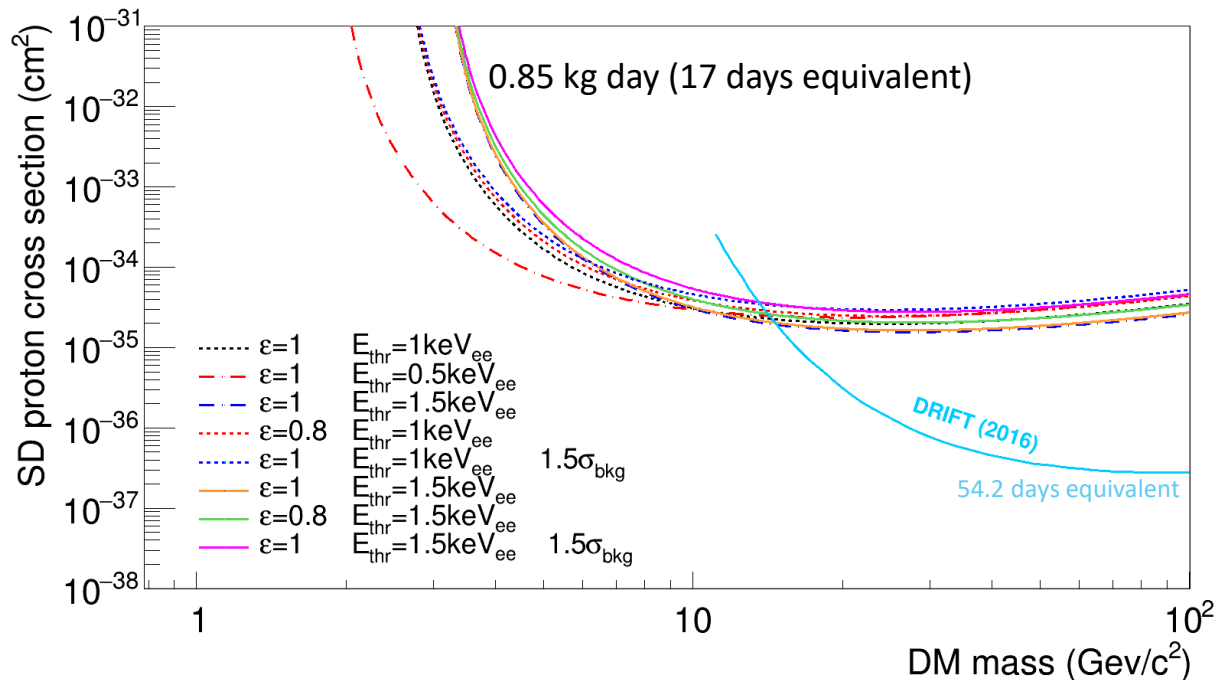
Large background
Counting experiment:
Worst possible scenario

SENSITIVITY LIME III

- Simple cuts on geometry to exclude borders (33 L active volume)
- Loose cut on rho variable to remove many ER (Machine learning technique will strongly improve this)
- Different thresholds and NR efficiency analysed
- 20% of Run4 data used as background model and the rest as data

We are quite close to DRIFT
(with a detector not thought for DM search)

Great improvement in energy threshold (with respect to other directional detectors)

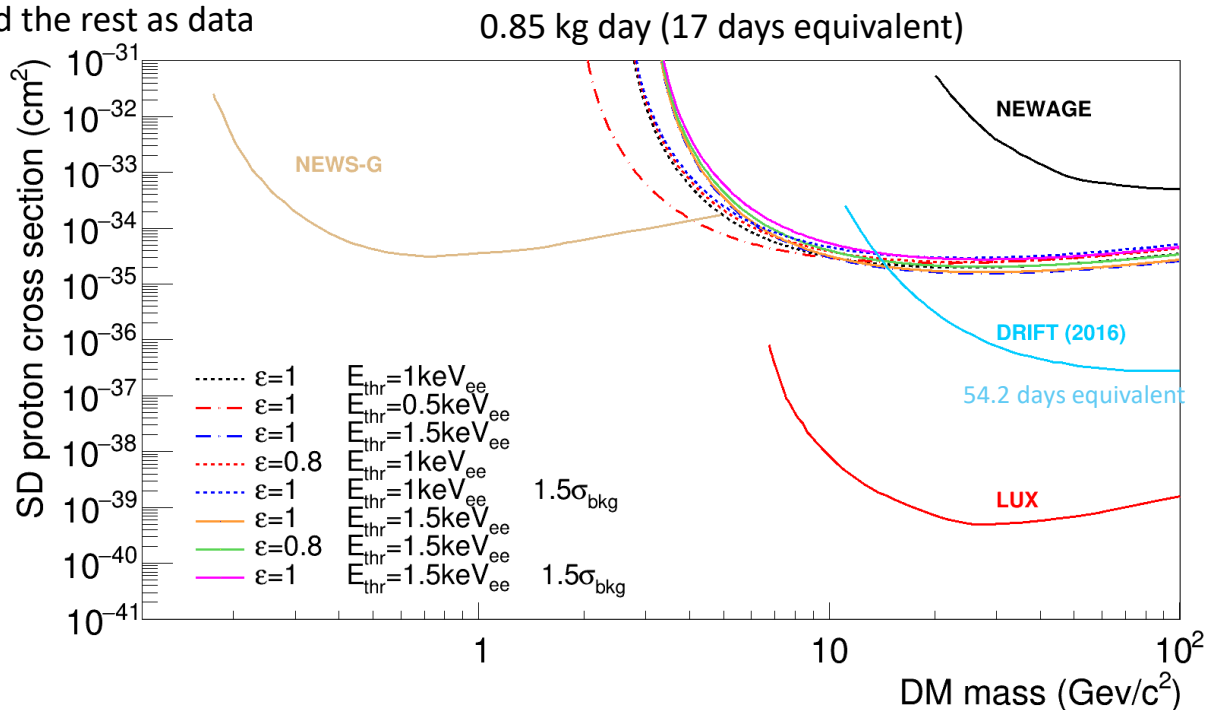


SENSITIVITY LIME III

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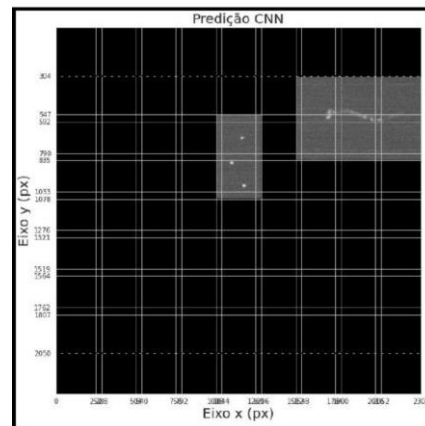
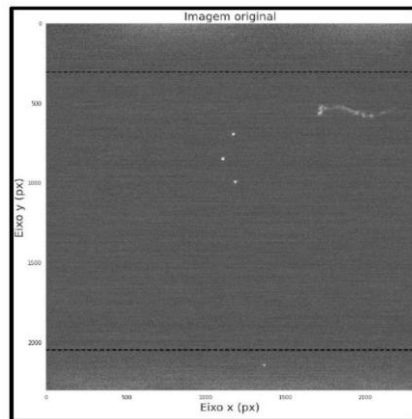


ANALYSIS CODE AND DATA REDUCTION

- CYGNO-04 will use ORCA QUEST camera as sCMOS detector (different shape, noise, performance) and new lens
- Analysis and simulation code integrated the new camera and lens interface
- Example of data clusterised with same reconstruction parameters



- Machine learning technique (and not) study to be applied at frontend level to reduce the raw data output for CYGNO-04 (we will use 6 cameras!)



Data reduction expected to be of a factor
150

Efficiency at low energy under study
(already outperforming current
reconstruction algorithm)

CONCLUSIONS

- During these months a lot of effort was spent in improvement of software in order to carry out more complex analysis
- 3D reconstruction algorithm is currently working for long NR tracks with extremely interesting results
- AmBe campaigns are paramount to determine operative parameters of the CYGNO detector and will soon exploit the software improvements
- A conservative angular resolution of 45 deg on NR above 100 keV_{ee} was found
- An angular resolution on electrons was measured of 30 deg at 10 keV and below 20 deg above 20 keV
- Extremely conservative estimation of exposure of LIME puts it within range of DRIFT results
- Work on analysis tools and data reduction for CYGNO-04 has already started

BACKUP I: DIRECTIONALITY

- Track reconstructed by analysis code
- Noise and below threshold pixel pruned
- Principal axis component and barycenter calculated
- Radius r opened around the barycenter and new barycenter calculated on the pixels outside the radius in the region with low skewness
- After finding the Impact Point (IP), the track is weighted in intensity as a function of the distance from IP
- Linear fit of the weighted points

