

New Frontiers in Theoretical Physics - XXXVIII Convegno Nazionale di Fisica Teorica

# Work fluctuations for Active Particles: singularities, dynamical phase transitions and big jumps

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Cortona, 21st May 2025









# Outline

#### **Dynamical Phase Transitions**

### Harmonically confined AOUP

### Take-home messages



single components transform energy from internal reservoirs or **Active Matter:** from the surrounding environment to self propel



#### Ann Rev Cond Matt Phys 2010, Ramaswamy Physica A 2018, Fodor et al. Rev Mod Phys 2013, Marchetti et al.



• Active Matter: single components transform energy from internal reservoirs or from the surrounding environment to self propel



melanocytic cells

colonies of bacteria

Ann Rev Cond Matt Phys 2010, Ramaswamy Physica A 2018, Fodor et al.

Rev Mod Phys 2013, Marchetti et al.

vibrated nanorods

Janus particle



- Theoretical interest
- strong connection with biological systems
- new paradigm of out-of-equilibrium systems

• Experimental and technological interest

emergence of new features with no counterpart in passive systems



#### • Theoretical interest

- strong connection with biological systems
- new paradigm of out-of-equilibrium systems

Nature Rev Phys 2022, Shankar et al.



spontaneous flows



#### • Experimental and technological interest

# emergence of new features with no counterpart in passive systems

PRL 2020, Caporusso et al.

#### motility-induced phase separation





#### • Theoretical interest

- strong connection with biological systems
- new paradigm of out-of-equilibrium systems -

Nature Rev Phys 2022, Shankar et al.



spontaneous flows



active, liquid, hexatic and solid phases

#### • Experimental and technological interest

#### emergence of new features with no counterpart in passive systems inherently out of equilibrium character no imposed boundaries or external driving

PRL 2020, Caporusso et al.

Science 2013, Palacci et al.



motility-induced phase separation





#### • Theoretical interest

- strong connection with biological systems
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Nature Rev Phys 2022, Shankar et al.



spontaneous flows



active, liquid, hexatic and solid phases

#### • Experimental and technological interest

Nature Rev Mat 2017, Needleman et al.



new bio-inspired materials

J American Chem Soc 2013, Palacci et al.



targeted delivery

#### emergence of new features with no counterpart in passive systems inherently out of equilibrium character no imposed boundaries or external driving

PRL 2020, Caporusso et al.

Science 2013, Palacci et al.



motility-induced phase separation

#### Proc Nat Acad Sci Usa 2017, Di Leonardo et al.



active engines

Adv Funct Mat 2023, Pellicciotta et al.



nanorobots





• Langevin equations Physics A 2017, Fodor et al

$$\ddot{x}_{i}(t) = -\frac{dU(x(t))}{dx_{i}(t)} + f_{i}(t) - \gamma \dot{x}_{i}(t) + \sqrt{2D} \xi_{i}(t)$$

#### • Passive vs Active motion

Passive Brownian Particle









• Langevin equations Physics A 2017, Fodor et al

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external and interaction forces (conservative + non-conservative)

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external and interaction forces (conservative + non-conservative) thermal bath (friction + noise)

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# Large Deviations Theory

• Dynamical observables

$$\mathcal{W}_{\tau} = \frac{1}{\tau} \int_{0}^{\tau} G$$

 $p(\mathcal{W}_{\tau} = w) \asymp e^{-\tau I(w)}$ Large Deviations Theory I(w)**Rate Function (RF)** 

$$\phi(\lambda) = \lim_{\tau \to \infty} \frac{1}{\tau} \ln(\langle e^{\lambda \mathcal{W}_{\tau}} \rangle)$$

(SCGF)

 $\lambda \in O$ 



Dembo and Zeitouni 1988, Springer Phys Rep 2009, Touchette

 $f(x(s), \dot{x}(s), a(s)) \circ dx(s)$  $dx(s) \rightarrow \dot{x}(s) ds$ 

integrated observables measured along particle trajectories G generic function of positions velocity and active force  $1/\tau$  essential to make  $\mathscr{W}_{\tau}$  intensive in time

- asymptotic equivalence
- extension of thermodynamic potentials to out of equilibrium configurations
- **Scaled Cumulant Generating Function**
- function whose derivatives generate th distribution moments
- $I(w) = \sup\{\lambda w \phi(\lambda)\}$
- RF and SCGF often related through Legendre-Fenchel transform



# **Dynamical Phase Transitions**

Rate Functions can be singular Entropy 2019, Corberi et al

- Dy
  chain
  Training
- Many examples in the in Brownian and active motion
- Active Work in a system of interacting active particles

$$W_{\tau} = \frac{1}{\tau} \int_{0}^{\tau} a(t)v(t) dt$$

 In singular trajectories particles dragged against their active force



#### Dynamical Phase Transitions

change in the physical mechanism producing fluctuations **Trajectory Separation** 

trajectories in different regions of the RF behave dynamically different



articles PRL 2017, Cagnetta et al



### **Analytical study of fluctuations of Active Work**

#### Setting single particle with external potential



- Active Ornstein-Uhlenbeck Particle (AOUP) free or with external harmonic potential
- Approach analytical evaluation of the Rate Function through Large Deviations techniques
- Interest
- Theoretical PRX 2019, Pietzonka et al
  - energy cost to sustain self propulsion
- Practical EPL 2021, Fodor et al
  - thermodynamic efficiency of Active Engines

confining potentials mimic the trapping of other particles at finite density

experimental realisations

analytical results feasible

$$\begin{cases} \dot{x}(t) = F_a \gamma^{-1} a(t) - k x(t) + \sqrt{2T/\gamma} \xi(t) \\ \dot{a}(t) = -\gamma_R a(t) + \sqrt{2D_R} \eta(t) \end{cases}$$

Scope investigation of distribution singularities and Dynamical Phase Transitions

PRL 2002, Wang et al







**Free AOUP** 

J Stat Mech 2021, Semeraro, Suma, Petrelli, Cagnetta and Gonnella

Free AOUP in d dimensions

$$\begin{cases} \dot{x}(t) = F_a \gamma^{-1} a(t) + \sqrt{2T/\gamma} \xi(t) \\ \dot{a}(t) = -\gamma_R a(t) + \sqrt{2D_R} \eta(t) \\ < a(t)a(t') > \simeq \left(e^{-\gamma_R(t-t')} - e^{-\gamma_R(t+t)}\right) \end{cases}$$

• Probability distribution  $p(w) = \langle (\delta(\mathcal{W}_a - w) \rangle)$ evaluated through path integral techniques







• Harmonically-confined AOUP in 1 d

$$\begin{cases} \gamma \dot{x}(t) = a(t) - kx(t) \\ \dot{a}(t) = -\nu a(t) + F \end{cases}$$

- Direct evaluation of p(w)through path integral techniques becomes difficult
  - Trajectory path probability

$$\mathcal{P}_{\tau} \propto \left\{ -\frac{1}{2} (x(0) \ a(0)) \Sigma_0^{-1} \begin{pmatrix} x(0) \\ a(0) \end{pmatrix} \right\} exp \left\{ -\frac{1}{4} \int_0^{\tau} [\dot{x}(s) - a(s) + \kappa x(s)]^2 \ ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 ds \right\} exp \left\{ -\frac{1$$

initial conditions distribution

Onsager-Machlup weight for trajectories

• Laplace representation of the  $\delta$  function

$$p(w) = \frac{1}{2\pi i} \int_{-i\infty}^{+i\infty} e^{-\tau \lambda w} \left\langle e^{\lambda \mathcal{W}_a} \right\rangle$$

- Cumulant Generating Function
- Saddle-point estimation of the RF





• Harmonically-confined AOUP in 1 d

$$\begin{cases} \gamma \dot{x}(t) = a(t) - kx(t) \\ \dot{a}(t) = -\nu a(t) + F \end{cases}$$

Direct evaluation of p(w)through path integral techniques becomes difficult

Trajectory path probability

 $\mathcal{P}_{\tau} \propto \left\{ -\frac{1}{2} (x(0) \ a(0)) \Sigma_0^{-1} \begin{pmatrix} x(0) \\ a(0) \end{pmatrix} \right\} exp \left\{ -\frac{1}{4} \int_0^{\tau} [\dot{x}(s) - a(s) + \kappa x(s)]^2 \ ds \right\} exp \left\{ -\frac{1}{4Pe^2} \int_0^{\tau} [\dot{a}(s) + a(s)]^2 \ ds \right\}$ 

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 New Large Deviations results for quadratic functionals of **Gauss-Markov chains** 

J Math Phys 2023, Zamparo and Semeraro

- Time-discretization procedure
- Evaluation of the SCGF functional form
- Evaluation of the SCGF domain
- Continuum limit
- Evaluation of the RF through Legendre-Fenchel transform





#### **LDT for quadratic functionals of Gauss-Markov chains**

Time-discretization procedure

 $\mathcal{M}_{a} \cdot \tau \rightarrow \text{quadratic functional}$ 

Langevin Equations 
$$\rightarrow$$
 Markov chain  $X_{n+1} = SX_n + G_n$   
 $W_N = \frac{1}{2} < X_0, LX_0 > + \frac{1}{2} < X_N, RX_N > + \frac{1}{2} \sum_{n=1}^N < X_n, UX_n > + \frac{1}{2} \sum_{n=2}^N < X_n, VX_n$ 

Evaluation of the SCGF functional form

$$\varphi(\lambda) = \lim_{N \to \infty} \frac{1}{N} \log \langle e^{\lambda W_N} \rangle = -\frac{1}{4\pi} \int_0^{2\pi} \ln \det A$$

Evaluation of the SCGF domain two technical requests on positive definiteness

Continuum limit  

$$\phi(\lambda) = \lim_{\epsilon \to 0} \frac{\varphi(\lambda)}{\epsilon}$$

Dunuary lenns

DUIN CONTINUUTIONS

Symbol matrix  $F_{\lambda}(\theta) = (I - S^{T} e^{i\theta})(I - S^{T} e^{-i\theta}) - \lambda(U + V e^{-i\theta} + V^{T} e^{i\theta})$  $F_{\lambda}(\theta) d\theta$ 

> Primary domain  $P = (\tilde{\lambda}_{-}, \tilde{\lambda}_{+})$  $F_{\lambda}(\theta)$  is positive definite for all  $\theta \in (0, 2\pi)$

#### Effective domain $E = (\lambda_{-}, \lambda_{+}) \subseteq P$ the matrices $\mathscr{L}_{\lambda}$ and $\mathscr{R}_{\lambda}$ related to the initial conditions ( $\Sigma_0$ ) and boundary terms (L, R) are positive definite

Evaluation of the RF through Legendre-Fenchel transform

$$I(w) = \sup_{\lambda \in E} \{w\lambda - \phi(\lambda)\}$$









# **Singular Rate Function**

- SCGF  $\phi(\lambda) = \frac{1+\kappa}{2} \frac{1}{2}\sqrt{(1+\kappa)^2 4Pe^2\lambda(1+\lambda)}$
- Primary domain  $P = (\tilde{\lambda}_{-}, \tilde{\lambda}_{+})$

$$\tilde{\lambda}_{\pm} = -\frac{1}{2} \pm \sqrt{1 + \left(\frac{1+\kappa}{Pe}\right)^2} \qquad Pe = \frac{Fd}{k_B T} \qquad \kappa = \frac{kd^2}{k_B T}$$

- $E = (\lambda_{-}, \lambda_{+}) \neq (\tilde{\lambda}_{-}, \tilde{\lambda}_{+}) = P \longrightarrow Singularitie$
- Rate function

$$I(w) = \begin{cases} (w - w_{-})\lambda_{-} + i(w) & w \le w_{-} \\ i(w) & w_{-} < w < w_{+} \\ (w - w_{+})\lambda_{+} - i(w) & w \ge w_{+} \end{cases}$$
$$i(w) = \frac{1}{2} \left( \sqrt{1 + \left(\frac{w}{Pe}\right)^{2}} + \sqrt{(1 + \kappa)^{2} + Pe^{2} - 1 - \kappa - w} \right)$$

Fluctuation Relation not always satisfied









#### • Singularities phase diagram



# Linear Tails and Trajectory Separation

#### • Physical Mechanism:

singular trajectories are characterised and selected by



# Fluctuations of Injected power

 Underdamped Brownian particle with external harmonic potential



Carollo, Semeraro, Gonnella and Zamparo

$$\dot{x} = v(t)$$
$$\dot{v}(t) = -\gamma v(t) - kx(t) + \sqrt{2D} \xi(t)$$

 $100 \ll 100$ 

 $\land$   $W \gg W$ 

$$\bar{\xi}(t)\dot{x}(t)dt = \frac{1}{2\tau}[v^2(\tau) - v^2(0)] + \frac{k}{2\tau}[x^2(\tau) - x^2(0)] + \frac{\gamma}{\tau}\int_0^\tau v(t)\dot{x}$$

 $W \ll W_{-}$  $W \gg W_+$ 











# Take-home messages





Fluctuations of Active Work for a single harmonically confined AOUP

Analysis with new Large Deviation Results for quadratic functionals of Gauss-Markov chains

- **Singular Rate Functions** are analytically obtained
- Initial or final **big jumps** are responsible for the appearance of singularities

Big jumps behind singular rate functions and dynamical phase transitions in Brownian systems

# Acknowledgements



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Università degli Studi di Bari and INFN Bari



#### **Dr. Marco Zamparo**

Università del Piemonte Orientale







Istituto Nazionale di Fisica Nucleare







NECA



# Thank for your attention!



#### Scholar



#### Contact





# FieldTurb initiative - Bari Team



Prof. **Giuseppe Gonnella (PI)** 

#### Topics

- Non-equilibrium statistical physics
- Dynamics of complex fluids
- Active Matter



Prof. **Antonio Suma** 



Ph. D. student **Daniela Moretti** 



#### **PostDoc Massimiliano Semeraro**



**PostDoc Pasquale Digregorio** 



Ph. D. student Lucio Carenza



Prof. Marco Zamparo (past member)









- Driven Brownian particle  $\dot{x}(t) = \mu \cdot t + \sqrt{2D} \xi(t)$
- Empirical measure:
- fraction of time spent by the particle in the interval [a, b]

$$\rho = \frac{1}{\tau} \int_0^{\tau} \mathbf{1}_{[a,b]}(x(t)) \, dt$$

Singular trajectories: particles rapidly escaping from [a, b]give rise to the RF left linear branch

EPL 2017, Nyawo and Touchette

System of many interacting ABPs

• Active Work 
$$\mathcal{W}_a = \frac{1}{\tau} \int_0^\tau a(s)v(s) \, ds$$

Singular trajectories:

- particles dragged against their active force
- generate  $\mathcal{W}_{a}$  values in the linear tails

PRL 2017, Cagnetta, Corberi, Gonnella and Suma PRE 2021, Keta, Fodor, van Wijland and Cates



# **Dynamical Phase Transitions: examples**







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# **Dynamical Phase Transitions: examples**









Saddle-point estimation of  $p(w) = \frac{1}{2\pi i} \int_{-i\infty}^{+i\infty} d\mu \ F(\mu) e^{\tau \frac{d}{2}(\gamma_R - \alpha)}$ 

Steepest descent paths

$$Im[\mu w - \phi(\mu)] = 0$$

Saddle-points  $\mu w - \phi(\mu) = 0 \rightarrow \tilde{\mu}_{\pm}^{(s)} = \frac{\gamma_R^2}{4D_R\gamma} \left[ -\frac{1 \pm \sqrt{1 + 4A\left(\frac{4\tilde{w}^2 - 1}{4(A + \tilde{w})^2}\right)}}{2A} \right]$ 

Integration along steepest dissent paths deformed to pass by  $\tilde{\mu}_{+}^{(s)}$ and avoid non-analicities of the integrand

$$p(w) \asymp \frac{F(\tilde{\mu}^{(s)})}{2\pi} \left(-\frac{1}{2\pi}\right)^{-1}$$



 $e^{-\tau I(w)}$  –

 $\rightarrow$  Extraction of the Rate Function I(w)





#### LDT for quadratic functionals of Gauss-Markov chains

Continuous model (
$$\gamma$$
,  $T$ ,  $d = 1$ )  

$$\begin{aligned}
\tau = N \cdot dt, x_{p} \\
\dot{x}(t) = a(t) - \kappa x(t) + \sqrt{2} \xi(t) \\
\dot{a}(t) = -a(t) + Pe\sqrt{2} \eta(t)
\end{aligned}$$
initial conditions  
covariance matrix
$$\Sigma_{0} = \begin{pmatrix} \frac{1 + \kappa + Pe^{2}}{\kappa(1 + \kappa)} & \frac{Pe^{2}}{1 + \kappa} \\
\frac{Pe^{2}}{1 + \kappa} & Pe^{2} \end{pmatrix} \qquad \Sigma_{0} = \begin{pmatrix} \sigma_{x}^{2} & 0 \\
0 & \sigma_{a}^{2} \end{pmatrix}
\end{aligned}$$

• Entire trajectory is Gaussian distributed with  $\{(x_0, a_0), ..., (a_N, x_N)\}$  zero mean and covariance matrix

Discretisation of Active Work as a quadratic functional

$$\mathcal{W}_{a} \cdot \tau = \int_{0}^{\tau} a(t)\dot{r}(t) dt \qquad \longrightarrow \qquad \mathcal{W}_{N} = \frac{1}{2} \sum_{n=1}^{N} (a_{n} + a_{n-1})(r_{n} - r_{n-1}) = \frac{1}{2} (r_{0} \quad a_{0} \quad \dots \quad r_{N} \quad a_{N}) \mathsf{M}_{N} \begin{bmatrix} v_{0} & v_{0} \\ v_{N} & v_{N} \end{bmatrix} = \frac{1}{2} \sum_{n=1}^{T} (a_{n} + a_{n-1})(r_{n} - r_{n-1}) = \frac{1}{2} (r_{0} \quad a_{0} \quad \dots \quad r_{N} \quad a_{N}) \mathsf{M}_{N} \begin{bmatrix} v_{0} & v_{0} \\ v_{N} & v_{N} \end{bmatrix} = \frac{1}{2} \sum_{n=1}^{T} (a_{n} + a_{n-1})(r_{n} - r_{n-1}) = \frac{1}{2} (r_{0} \quad a_{0} \quad \dots \quad r_{N} \quad a_{N}) \mathsf{M}_{N} \begin{bmatrix} v_{0} & v_{0} \\ v_{N} & v_{N} \end{bmatrix} = \frac{1}{2} \sum_{n=1}^{T} (a_{n} + a_{n-1})(r_{n} - r_{n-1}) = \frac{1}{2} (r_{0} \quad a_{0} \quad \dots \quad r_{N} \quad a_{N}) \mathsf{M}_{N} \begin{bmatrix} v_{0} & v_{0} \\ v_{N} & v_{N} \end{bmatrix} = \frac{1}{2} \sum_{n=1}^{T} (a_{n} + a_{n-1})(r_{n} - r_{n-1}) = \frac{1}{2} (r_{0} \quad a_{0} \quad \dots \quad r_{N} \quad a_{N}) \mathsf{M}_{N} \begin{bmatrix} v_{0} & v_{0} \\ v_{N} & v_{N} \end{bmatrix} = \frac{1}{2} \sum_{n=1}^{T} (v_{0} \quad a_{0} \quad \dots \quad v_{N} \quad a_{N}) \mathsf{M}_{N} \begin{bmatrix} v_{0} & v_{0} \\ v_{N} & v_{N} \end{bmatrix} = \frac{1}{2} \sum_{n=1}^{T} (v_{0} \quad v_{N} \quad v_{N} \quad v_{N} \quad v_{N} \quad v_{N} \end{bmatrix}$$

quasi-Toeplitz block matrix -

Discrete model as a Gauss-Markov chain  $\tau = N \cdot dt, \ x_n, a_x \equiv x(n \cdot dt), a(n \cdot dt), \{\xi_n\}, \{\eta_n\}$  sequence of normal rv  $x_{n+1} = (1 - \kappa dt) \ r_n + a_n \ dt + \sqrt{2dt} \ \xi_n \longrightarrow X_{n+1} = SX_n + D\zeta_n \qquad X_n = (x_n, a_n)^T$  $x_{n+1} = (1 - dt) \ a_n + Pe\sqrt{2dt} \ \eta_n$ 

$$\mathsf{M}_{N} \equiv \begin{pmatrix} -E_{+} & E_{-}^{\top} & & \\ E_{-} & 0 & \ddots & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & 0 & E_{-}^{\top} \\ & & & E_{-} & E_{+} \end{pmatrix} \qquad \qquad E_{\pm} \equiv \frac{1}{2} \begin{pmatrix} 0 & 1 \\ \pm 1 & 0 \end{pmatrix}$$







#### **LDT for quadratic functionals of Gauss-Markov chains**

Evaluation of the SCGF (generalization of Szegö theorem)

$$\varphi(\lambda) = \lim_{N \to \infty} \frac{1}{N} \log \langle e^{\lambda W_N} \rangle = -\frac{1}{4\pi} \int_0^{2\pi} \ln \det F_{\lambda}($$

Positive definiteness  

$$\log < e^{\lambda W_N} > = -\frac{1}{2} \ln \det(\Sigma_N^{-1} - \lambda M_N) - N \ln(2 \ dt \ Pe) - \frac{1}{2} \ln \det \Sigma_0 \ \Sigma_N^{-1} - \lambda M_N = \begin{pmatrix} L & V^{\mathsf{T}} & \mathsf{T}_N \\ V & U & \ddots \\ \ddots & \ddots & \ddots \\ V & V & R \end{pmatrix} \stackrel{L = \Sigma_0^{-1} + S^{\mathsf{T}} D^{-2}}{R = D^{-2} - \lambda E_+} \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = -D^{-2} S - \lambda E_+ \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ U = D^{-2} + S^{\mathsf{T}} D^{-2} \\ V = D^{\mathsf{T}} S - X \\ U = D^{\mathsf{T}} S - X \\ U$$

Schur complement  $S_N \equiv \begin{pmatrix} P & V & V & V \\ -V(T_N^{-1})_{N1}V & R - V(T_N^{-1})_{NN}V^{\top} \end{pmatrix}$ Hermitian positive  $\mathscr{L}_{\lambda} \equiv \Sigma_{0}^{-1} + S^{\mathsf{T}} D^{-2} S + \lambda E_{+} - (D^{-2} S)^{-2} S + \lambda E_{+} - ($  $\mathcal{R}_{\lambda} \equiv D^{-2} - \lambda E_{+} - (D^{-2}S + \lambda E_{-})K_{\lambda}^{-1}\Phi_{\lambda}(0)(D^{-2}S + \lambda E_{-})^{\top}$   $\Phi_{\lambda}(n) \equiv \frac{1}{2\pi} \int_{0}^{2\pi} F_{\lambda}^{-1}(\theta)e^{-\mathrm{i}n\theta}d\theta \qquad H_{\lambda} \equiv I + (D^{-2}S + \lambda E_{-})\Phi_{\lambda}(1) \qquad K_{\lambda} \equiv I + \Phi_{\lambda}(1)(D^{-2}S + \lambda E_{-})$ 

Symbol matrix

 $(\theta) \ d\theta$ 

$$\begin{split} F_{\lambda}(\theta) &\equiv V e^{-\mathrm{i}\theta} + U + V^{\mathsf{T}} e^{\mathrm{i}\theta} \\ &- (D^{-2}S + \lambda E_{-})e^{-\mathrm{i}\theta} + D^{-2} + S^{\mathsf{T}} D^{-2}S - (D^{-2}S + \lambda E_{-})^{\mathsf{T}} e^{\mathrm{i}\theta} \end{split}$$

$$) \xrightarrow{N \to \infty} \begin{pmatrix} \mathcal{Z}_{\lambda} & 0 \\ 0 & \mathcal{R}_{\lambda} \end{pmatrix}$$
 positive definite

$$S + \lambda E_{-})^{\top} \Phi_{\lambda}(0) H_{\lambda}^{-1}(D^{-2}S + \lambda E_{-}) \longrightarrow \text{Effective domain } E = (\lambda E_{-})^{\top} \Phi_{\lambda}(0) (D^{-2}S + \lambda E_{-})^{\top}$$





### Harmonically confined AOUP: condensation

Trajectories corresponding to  $\mathcal{W}_a$  values in the linear tails are characterized by *big jumps* in the initial or final conditions

At stationarity



#### **Condensation mechanism**

Fixed initial conditions







# **Entropy Production at stationarity**

• Entropy Production  $\mathcal{S}$  is closely related to the Active Work  $\mathcal{W}_{a}$ 

$$\mathcal{S} \equiv \ln \frac{P_{\tau}(r(t), a(t))}{P_{\tau}(r(\tau - t), a(\tau - t))} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ v(\tau) \end{pmatrix} - \begin{pmatrix} r(0) & v(0) \end{pmatrix} \Omega \begin{pmatrix} r(0) \\ v(0) \end{pmatrix} \qquad \Omega = \Sigma_{0}^{-1} - \begin{pmatrix} \kappa & 0 \\ 0 & Pe^{-1} \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{W}_{a}$$

• SCGF with 
$$P = (\lambda_{-}, \lambda_{+}) = E$$
  $\phi(\lambda) = \frac{1+\kappa}{2} - \frac{1}{2}\sqrt{(1+\kappa)^2 - 4Pe^2\lambda(1+\lambda)}$   $\tilde{\lambda}_{\pm} = \lambda_{\pm} = -\frac{1}{2} \pm \sqrt{1 + \left(\frac{1+\kappa}{Pe^2\lambda(1+\lambda)} - \frac{1}{2}\right)^2 + \frac{1}{2}}$ 

I(w) = i(w) = -• Rate function. No linear tails.

- **No** singularities and Dynamical Phase Transitions !
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$$\frac{1}{2}\left(\sqrt{1+\left(\frac{w}{Pe}\right)^2}+\sqrt{(1+\kappa)^2+Pe^2-1-\kappa-w}\right)$$









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# **Entropy Production at stationarity**

• Entropy Production  $\mathcal{S}$  is closely related to the Active Work  $\mathcal{W}_{\alpha}$ 

$$\mathcal{S} \equiv \ln \frac{P_{\tau}(r(t), a(t))}{P_{\tau}(r(\tau - t), a(\tau - t))} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ v(\tau) \end{pmatrix} - \begin{pmatrix} r(0) & v(0) \end{pmatrix} \Omega \begin{pmatrix} r(0) \\ v(0) \end{pmatrix} \qquad \Omega = \Sigma_{0}^{-1} - \begin{pmatrix} \kappa & 0 \\ 0 & Pe^{-1} \end{pmatrix} = \mathcal{W}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & v(\tau) \end{pmatrix} \Omega \begin{pmatrix} r(\tau) \\ r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a} + \frac{1}{2} \begin{pmatrix} r(\tau) & r(\tau) \end{pmatrix} = \mathcal{U}_{a}$$

• SCGF with 
$$P = (\lambda_{-}, \lambda_{+}) = E$$
  $\phi(\lambda) = \frac{1+\kappa}{2} - \frac{1}{2}\sqrt{(1+\kappa)^2 - 4Pe^2\lambda(1+\lambda)}$   $\tilde{\lambda}_{\pm} = \lambda_{\pm} = -\frac{1}{2} \pm \sqrt{1 + \left(\frac{1+\kappa}{Pe^2\lambda(1+\lambda)} - \frac{1}{2}\right)^2 + \frac{1}{2}}$ 

I(w) = i(w) = -• Rate function. No linear tails.

- No singularities and Dynamical Phase Transitions !
- Fluctuation Relation satisfied !

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$$\frac{1}{2}\left(\sqrt{1+\left(\frac{w}{Pe}\right)^2}+\sqrt{(1+\kappa)^2+Pe^2-1-\kappa-w}\right)$$









# Fluctuations of Injected power

- Trajectories corresponding to  $\mathcal{W}_{\tau}$  values in the linear tails are characterized by *big jumps* in the initial conditions with similar patterns





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Positive- and negative-tail trajectories are discerned by looking the the white noise realisations

