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main discussion points

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Tracking sensors R&D

(a) UPO (Italy) (b) INFN Torino (Italy)



BIB environment

At the LHC we are used to backgrounds primarily from pile-up *pp* collisions ightarrow real tracks pointing at displaced vertices

Event at the CMS experiment with 78 reconstructed vertices

At the Muon Collider background tracks are not reconstructable

A cloud of looping tracks from soft electrons: <p⊤> = 3.5 MeV ►

Creates tremendous combinatorics for the classical outward track reconstruction

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Timing resolution

Raw hit density in the Vertex Detector is unsustainable → up to 5K hits/cm² in a 15 ns time-integration window

High time resolution of ~30 ps to reject BIB hits outside of a narrow time window

Substantial number of BIB hits arrive earlier created by particles exiting close to the sensor



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Background density varies across the tracker \rightarrow highest close to the tungsten nozzles (after time filtering)



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Hit density





Material budget

Majority of the hits (up to 90%) created by primary electrons coming from the MDI outer surface







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Secondary electrons



Technology I: RSD



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hn						
	Thickness	PGAIN dose	Trench process	Trench depth	O IMP	NHO
	55	1.02	P2	D2		
<i>c</i> .	55	1.02	P2	D2	Y	Y
tirs	55	1.06	P2	D2	Y	Y
	55	1.06	P2	D2	Y	Y
	55	1.02	P2	D2		
	55	1.06	P2	D2		
	55	1.06	P2	D2	Y	Y
	55	1.02	P2	D2	Y	Y
	55	1.02	P2	D2		
	55	1.06	P2	D2		
	55	1.02	P2	D2	Y	Y
	55	1.06	P2	D2	Y	Y
	55	1.06	P2	D2	Y	Y
	55	1.02	P2	D2	Y	Y
	5	1.06	P2	D2	Y	Y

sistance

ce Al-Si

Gain dose (implan

• EPI batch validatic

Ongoing R&D project: 4DSHARE

Things to study: pad layouts, readout electronics, power consumption, radiation tolerance

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ology I: DC-RSD

st tests of a 2x2 pixel prototype ongoing





DMAPS (Depleted Monolithic Active Pixel Sensor) - sensor + re



inner VTX layers



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Perfect technology for the high-occupancy regions of the tracker:

Tracking sensors R&D

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A more realistic digitizer in place: <u>MuonCVXDDigitiser</u> with implemented effects of noise, threshold and **charge sharing** → **realistic cluster shapes**



Things to implement: proper treatment of timing (pixel-level pile-up), shallow-angle particles Things to study: thicker sensors to improve signal/BIB separation, different readout schemes

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Digitization



