



Quantum Back-Action Evasion for Future Gravitational Wave Detectors

IFD, Sestri Levante, 17 marzo 2025

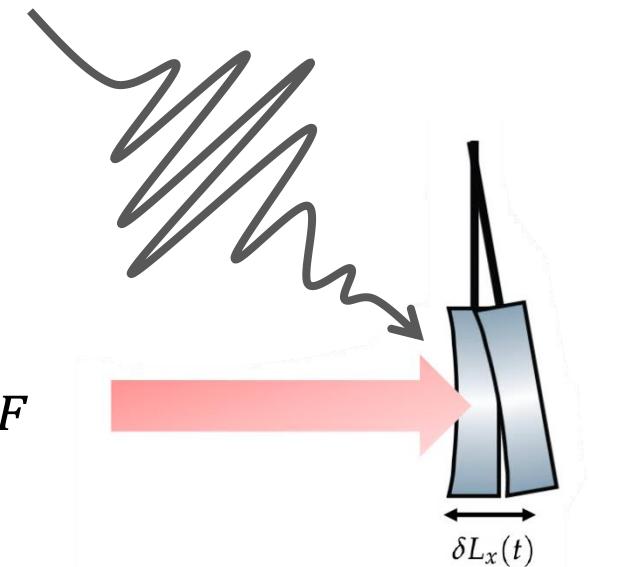
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Quantum Back-Action Evasion

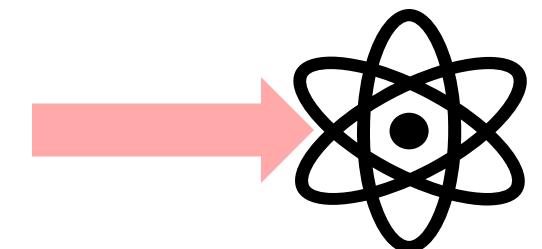
Quantum limited detector

$$q_{ITF} = \tilde{h}\sqrt{K_{ITF}} + p_1 + x_1 K_{ITF}$$



External quantum reference

$$q_{Ref} = p_2 + x_2 K_{Ref}$$



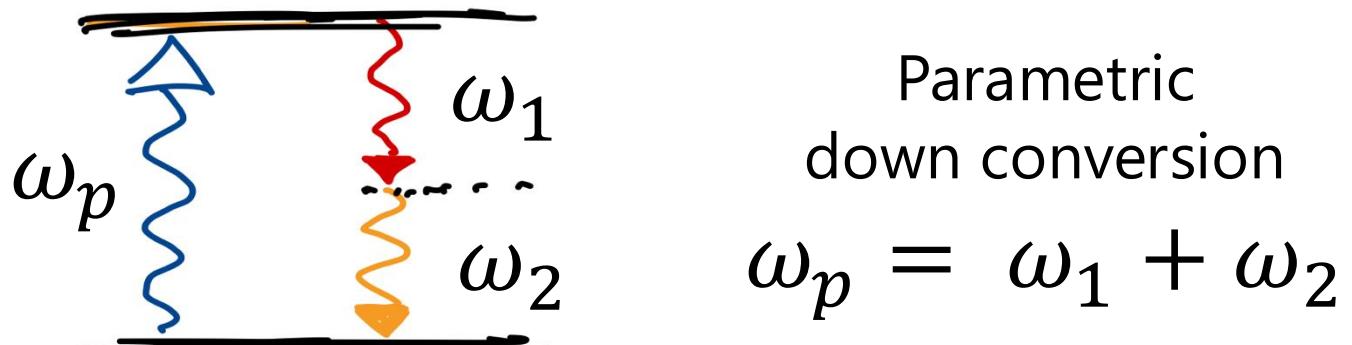


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Quantum Back-Action Evasion

Connection

Continuous variable entangled twin beams.



Amplitude and phase are correlated

$$\Delta(x_1 - x_2)^2 \rightarrow 0$$

$$\Delta(p_1 + p_2)^2 \rightarrow 0$$

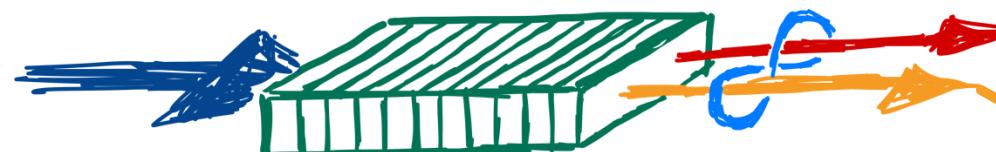


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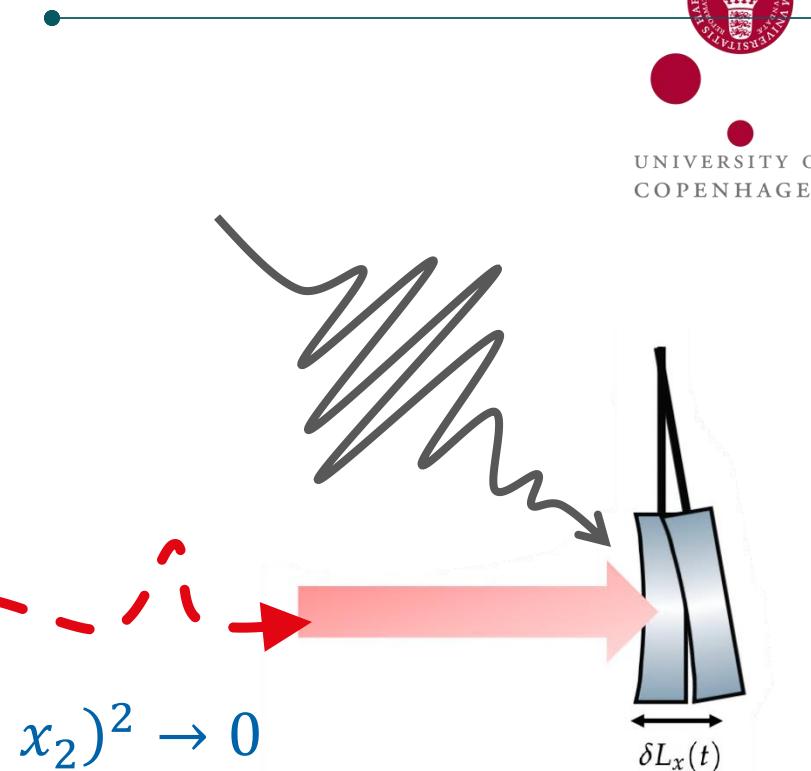
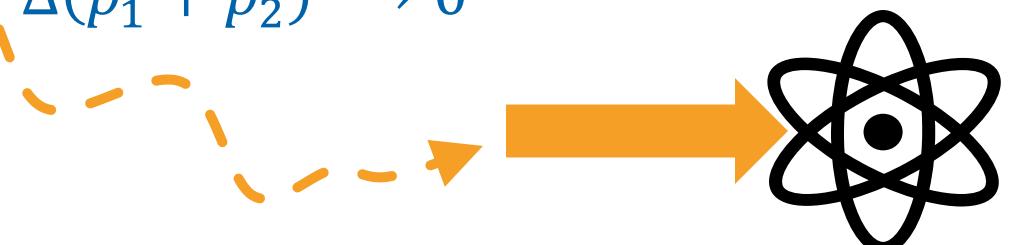
Connection

Continuous variable entangled twin beams.



Non-linear crystal.

$$\Delta(x_1 - x_2)^2 \rightarrow 0$$
$$\Delta(p_1 + p_2)^2 \rightarrow 0$$



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Quantum Back-Action Evasion

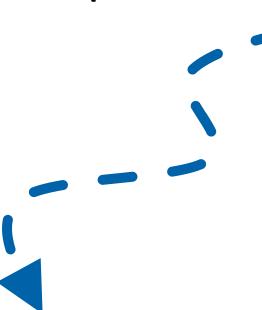
Quantum limited detector

$$\Delta(x_1 - x_2)^2 \rightarrow 0$$

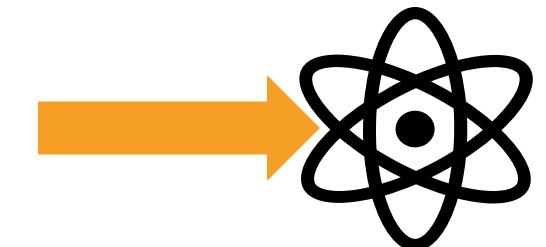
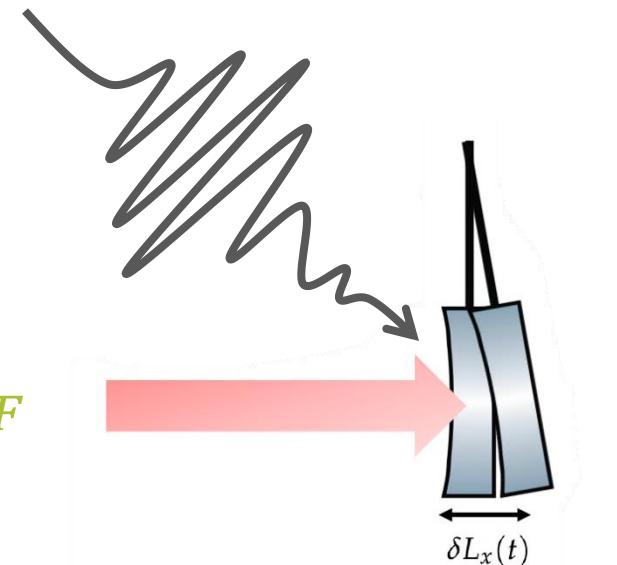
$$\Delta(p_1 + p_2)^2 \rightarrow 0$$

External quantum reference

$$q_{ITF} = \tilde{h}\sqrt{K_{ITF}} + p_1 + x_1 K_{ITF}$$



$$q_{Ref} = p_2 + x_2 K_{Ref}$$





Quantum Back-Action Evasion

Quantum limited detector

$$q_{ITF} = \tilde{h}\sqrt{K_{ITF}} + p_1 + x_1 K_{ITF}$$

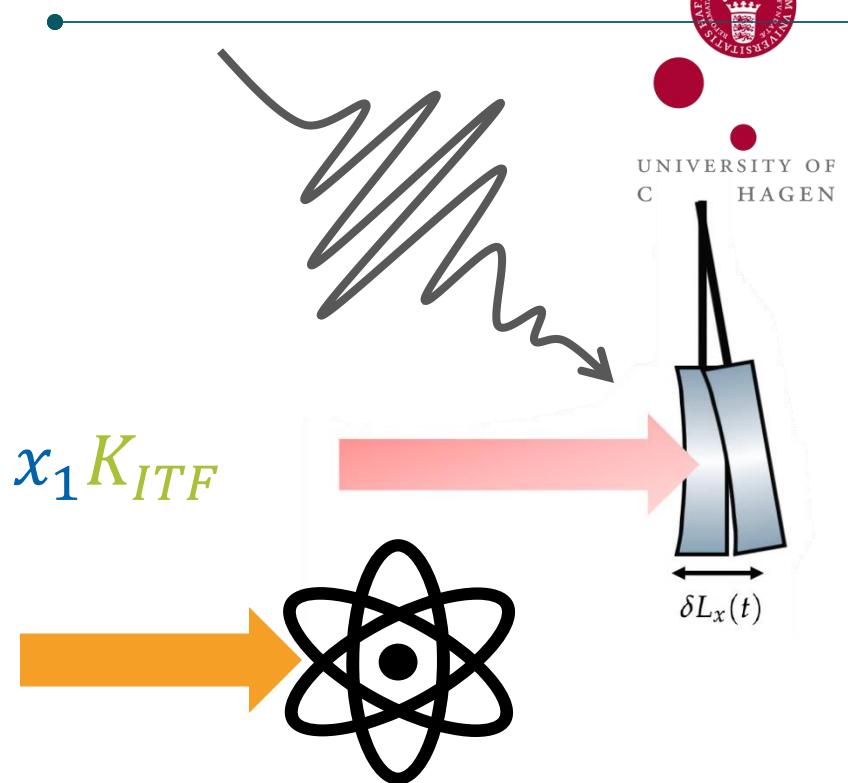
External quantum reference

$$q_{Ref} = p_2 + x_2 K_{Ref}$$

$$\Delta(x_1 - x_2)^2 \rightarrow 0$$

$$\Delta(p_1 + p_2)^2 \rightarrow 0$$

$$q_{ITF} + q_{Ref} = \tilde{h}\sqrt{K_{ITF}} + p_1 + x_1 K_{ITF}(\Omega) + p_2 + x_2 K_{Ref}(\Omega)$$

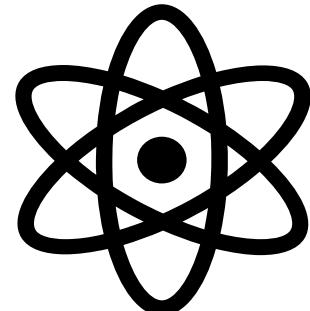


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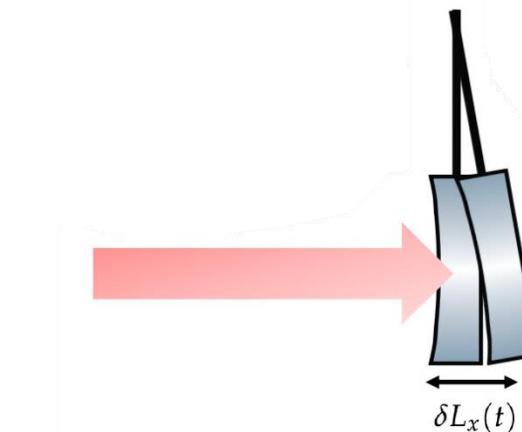
External (Quantum) Reference

$$K_{Ref}(\Omega)$$



$$\Delta(x_1 - x_2)^2 \rightarrow 0$$

$$K_{ITF}(\Omega)$$



Negative Mass Oscillator

Positive Mass Oscillator

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Quantum Back-Action Evasion

External (Quantum) Reference

$$K_{Ref}(\Omega)$$

$$\Delta(x_1 - x_2)^2 \rightarrow 0$$

$$K_{ITF}(\Omega)$$

$$K_{Ref}(\Omega) \propto \frac{-P_{in}}{\Omega^2(\Omega^2 + \gamma^2)}$$

$$K_{ITF}(\Omega) \propto \frac{P_{in}}{\Omega^2(\Omega^2 + \gamma^2)}$$

Effective
Negative Mass Oscillator

Positive Mass Oscillator



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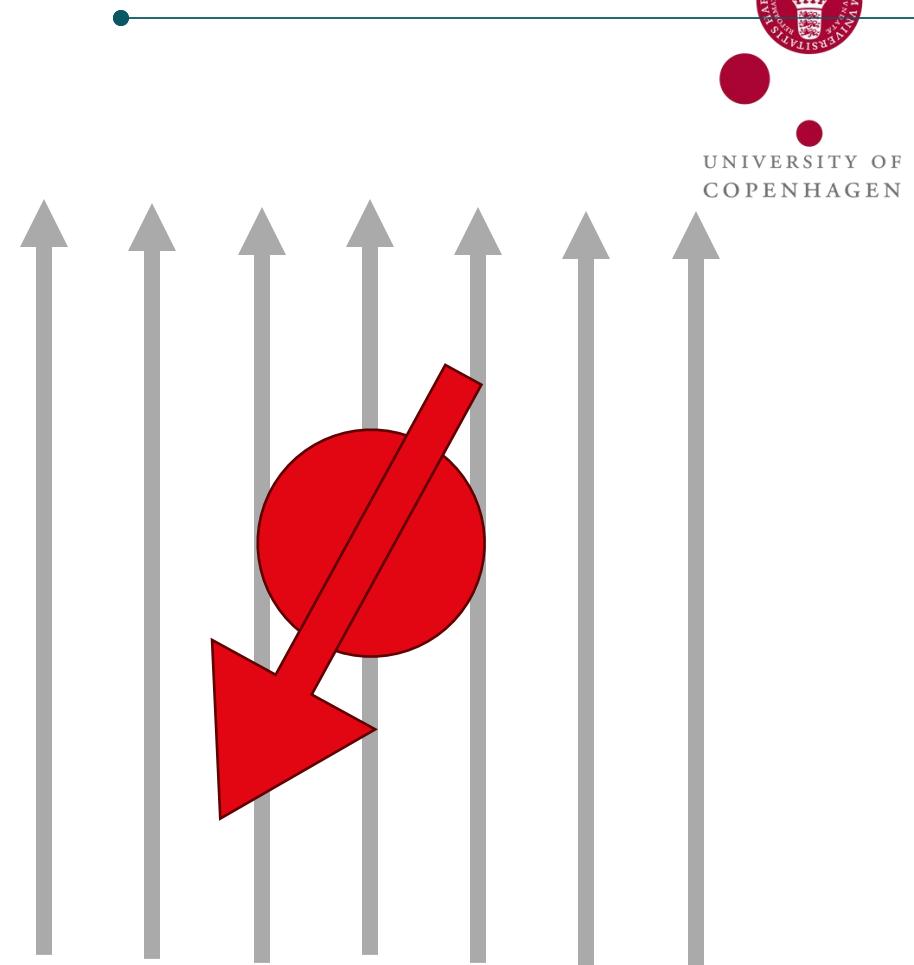
Quantum Back-Action Evasion

External (Quantum) Reference

$$K_{Ref}(\Omega)$$

$$K_{Ref}(\Omega) \propto \frac{-P_{in}}{\Omega^2(\Omega^2 + \gamma^2)}$$

Effective
Negative Mass Oscillator



Magnetic Field

$$H \propto -B \cdot J$$



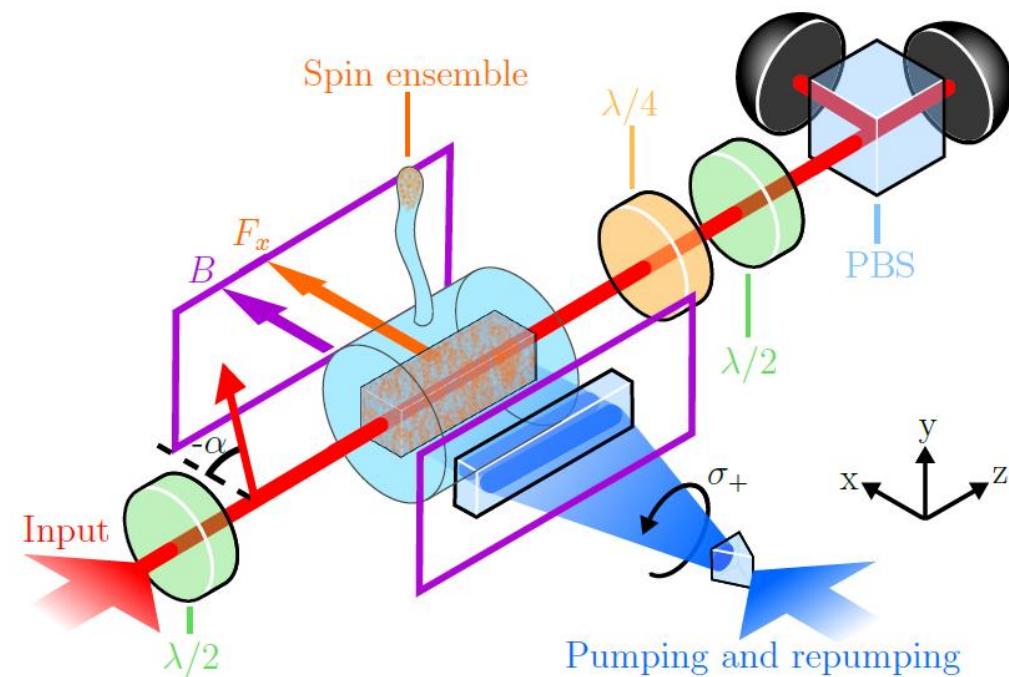
Quantum Back-Action Evasion

External (Quantum) Reference

$$K_{Ref}(\Omega)$$

$$K_{Ref}(\Omega) \propto \frac{-P_{in}}{\Omega^2(\Omega^2 + \gamma^2)}$$

Effective
Negative Mass Oscillator



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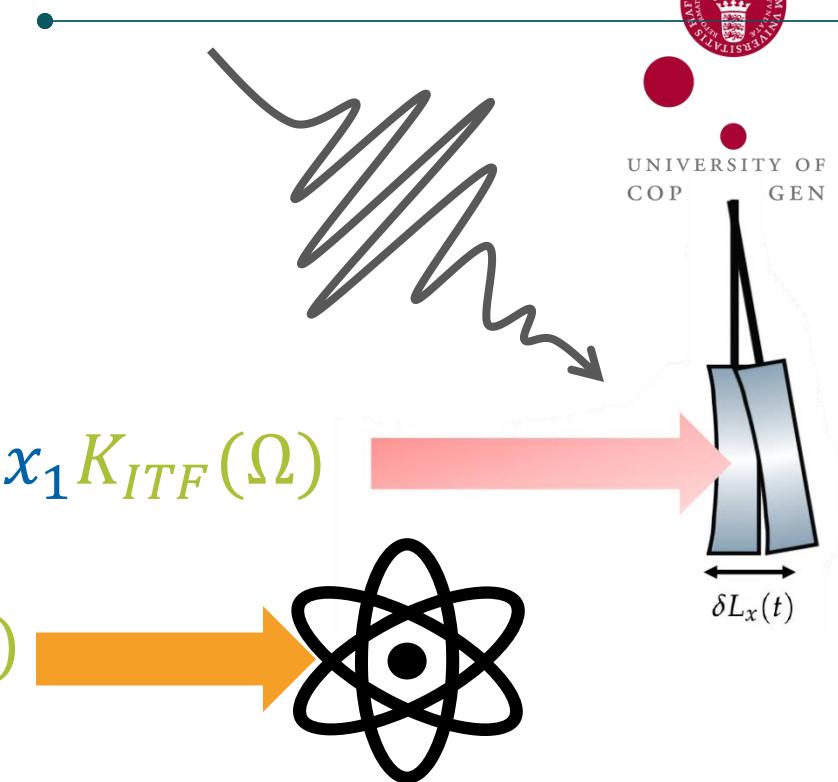
Quantum Back-Action Evasion

Quantum limited detector

$$q_{ITF} = \tilde{h}\sqrt{K_{ITF}} + p_1 + x_1 K_{ITF}(\Omega)$$

External quantum reference

$$q_{Ref} = p_2 + x_2 K_{Ref}(\Omega)$$



$$q_{ITF} + q_{Ref} = \tilde{h}\sqrt{K_{ITF}} + p_1 + x_1 K_{ITF}(\Omega) + p_2 + x_2 K_{Ref}(\Omega)$$

$$\Delta(p_1 + p_2)^2 \rightarrow 0$$

$$K_{Ref}(\Omega) \simeq -K_{ITF}(\Omega)$$

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Quantum Back-Action Evasion

Conditioning the $q_{ITF}(\Omega)$ based on the $q_{Ref}(\Omega)$, we can suppress the detector quantum noise

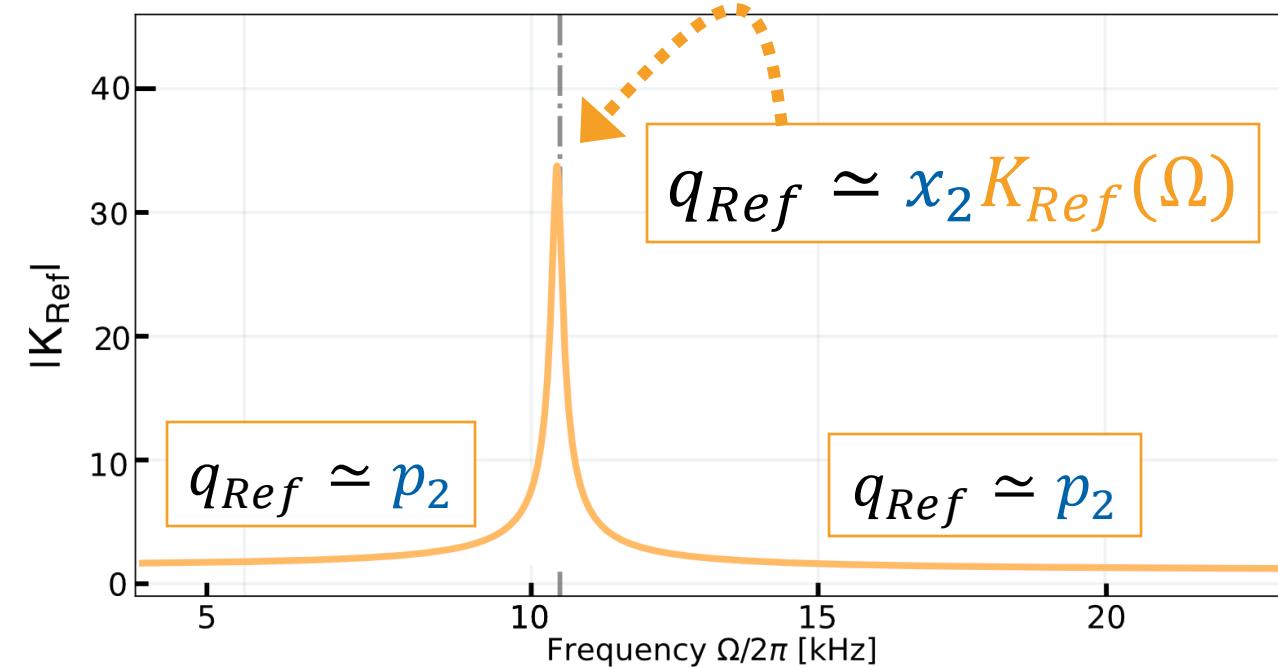
$$q_{ITF} + q_{ITF} = \tilde{h}\sqrt{K_{ITF}}$$

How did we demonstrate it?

How did we demonstrate it?

One-axis twisting on the idler arm

$$q_{Ref} = p_2 + x_2 K_{Ref}(\Omega)$$



How did we demonstrate it?

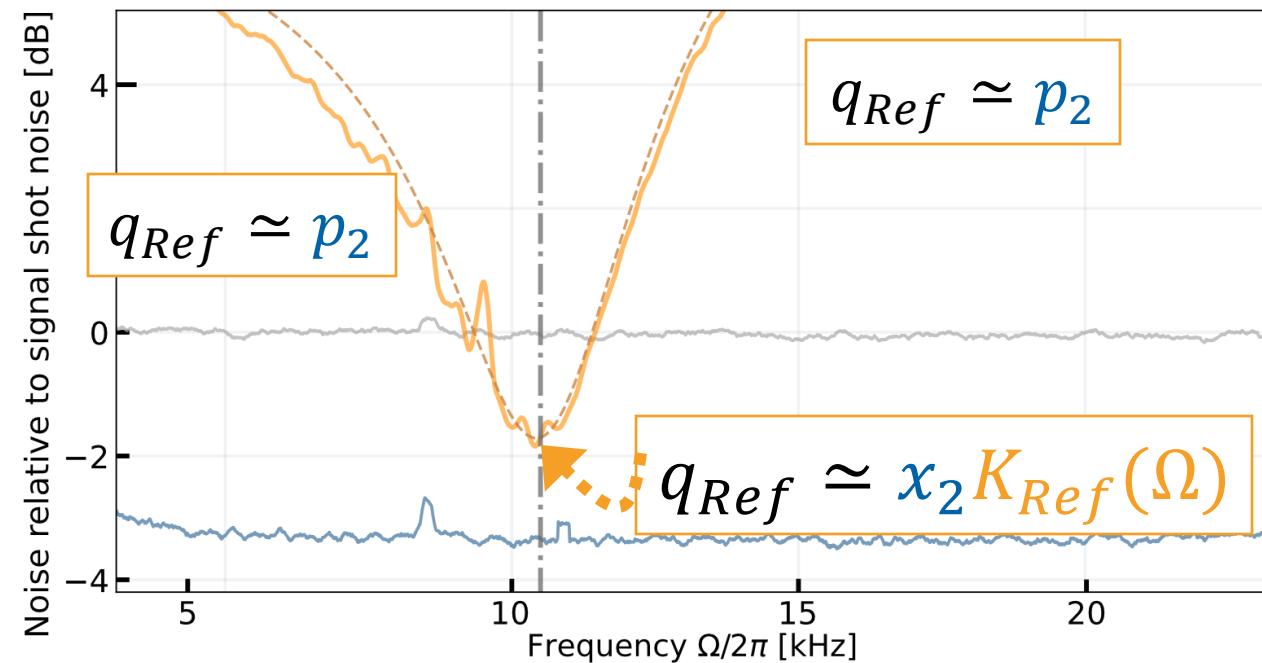
One-axis twisting on the idler arm

$$q_{Ref} = p_2 + x_2 K_{Ref}(\Omega)$$

$$q_1 = x_1$$

$$\Delta(x_1 - x_2)^2 \rightarrow 0$$

$$\Delta(p_1 + p_2)^2 \rightarrow 0$$



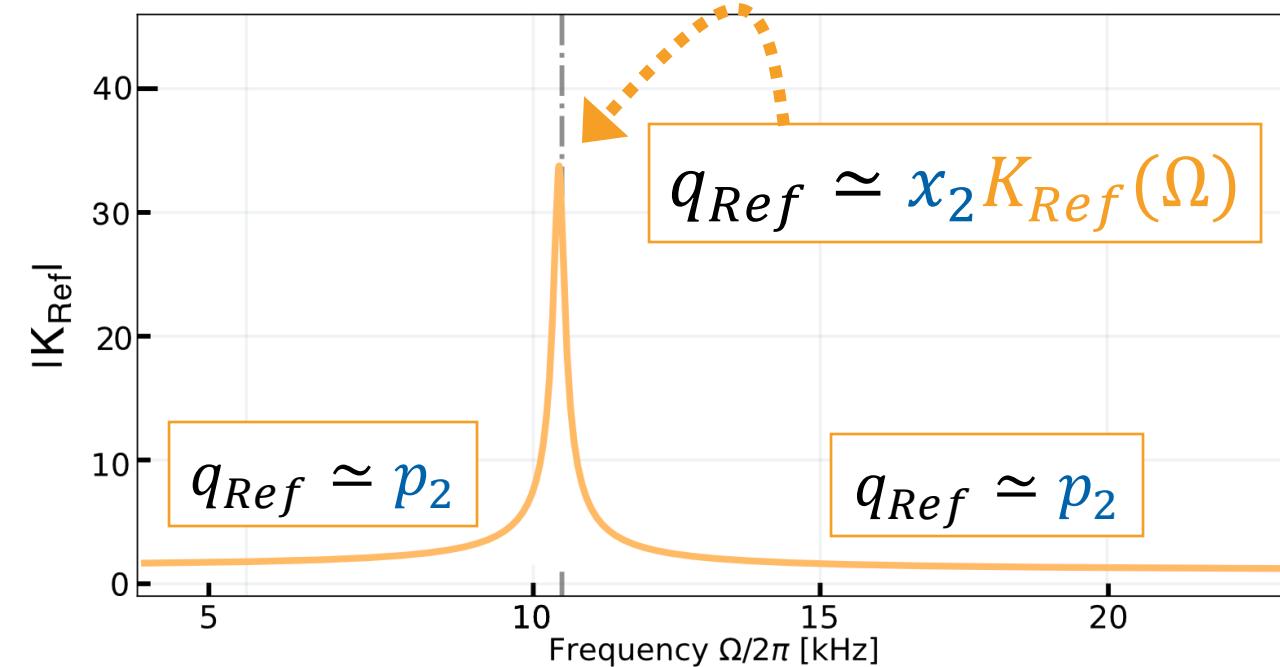
How did we demonstrate it?

One-axis twisting on the idler arm

$$q_{Ref} = p_2 + x_2 K_{Ref}(\Omega)$$

Phase Rotation

$$\Phi(\Omega) = \arctan[K_{Ref}(\Omega)]$$



$$q_{Ref}(\Omega) = N (p_2 \cos(\Phi(\Omega)) + x_2 \sin(\Phi(\Omega)))$$

How did we demonstrate it?

One-axis twisting on the idler arm

$$q_{Ref} = p_2 + x_2 K_{Ref}(\Omega)$$

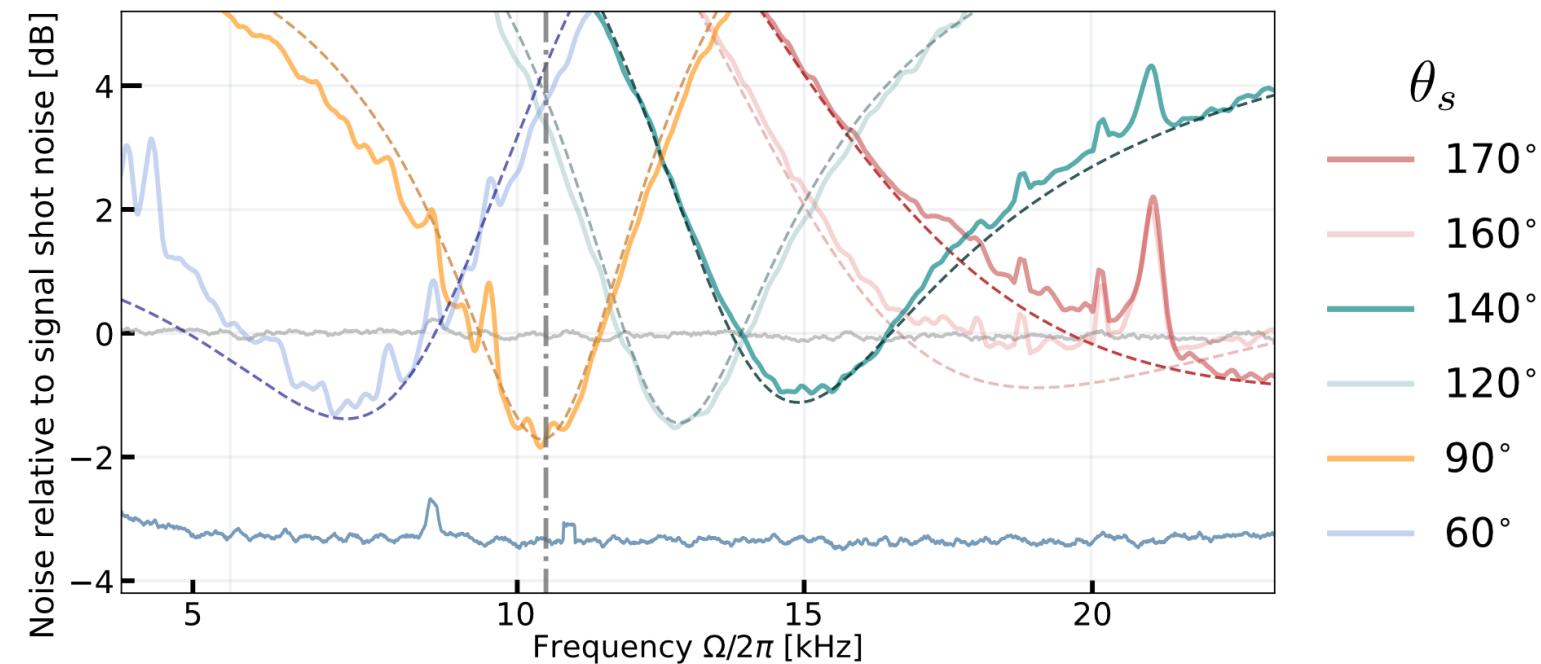
Phase Rotation

$$\Phi(\Omega) = \arctan[K_{Ref}(\Omega)]$$

$$q_1 = \sin(\theta_s)x_1 + \cos(\theta_s)p_1$$

$$q_{Ref}(\Omega) = N(p_2 \cos(\Phi(\Omega)) + x_2 \sin(\Phi(\Omega)))$$

$$\begin{aligned}\Delta(x_1 - x_2)^2 &\rightarrow 0 \\ \Delta(p_1 + p_2)^2 &\rightarrow 0\end{aligned}$$



How did we demonstrate it?

One-axis twisting on the idler arm

$$q_{Ref} = p_2 + x_2 K_{Ref}(\Omega)$$

Phase Rotation

$$\Phi(\Omega) = \arctan[K_{Ref}(\Omega)]$$

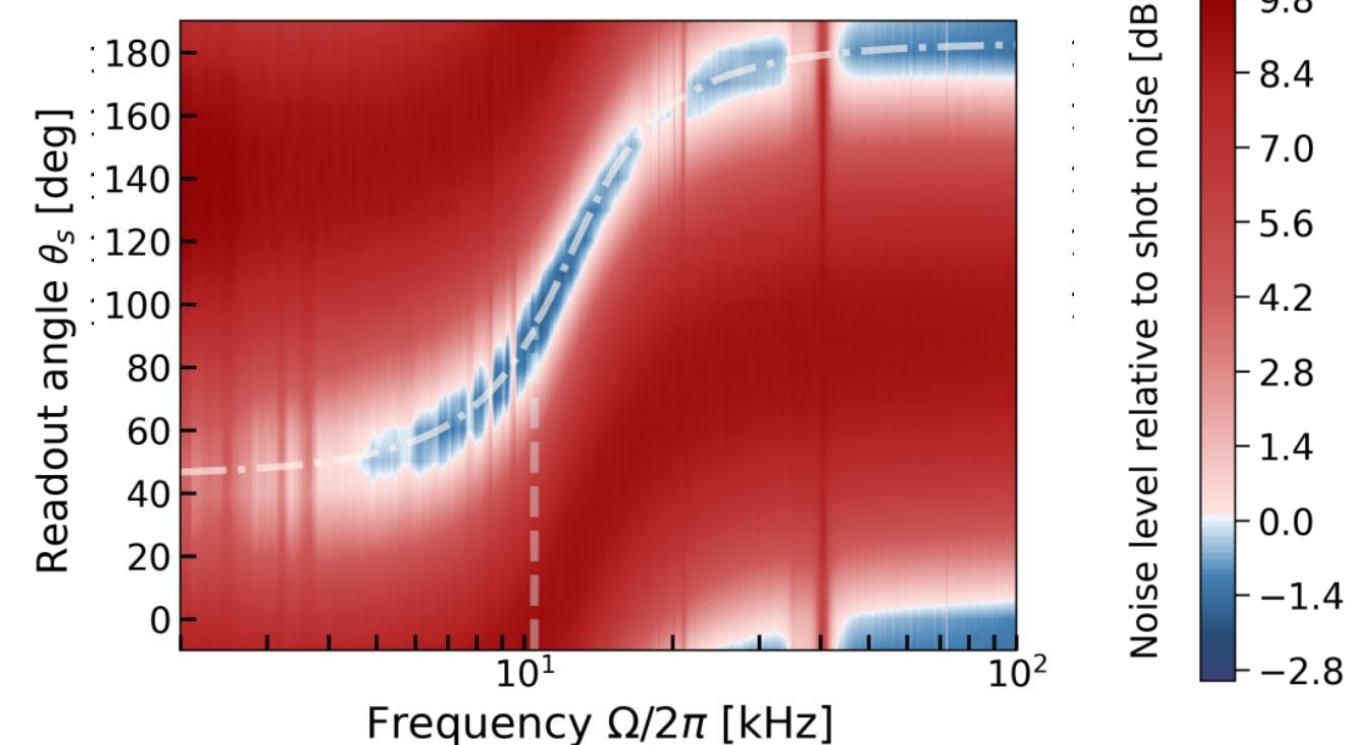
$$q_1 = \sin(\theta_s) x_1 + \cos(\theta_s) p_1$$

$$q_{Ref}(\Omega) = N(p_2 \cos(\Phi(\Omega)) + x_2 \sin(\Phi(\Omega)))$$

$$\Delta(x_1 - x_2)^2 \rightarrow 0$$

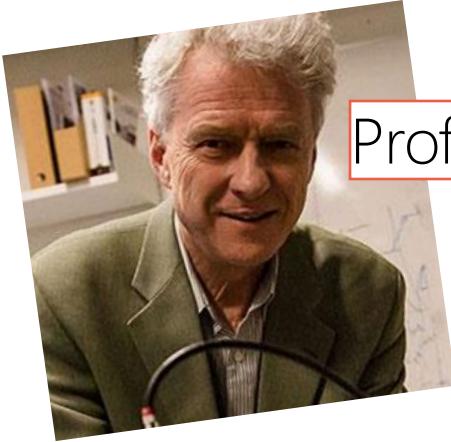
$$\Delta(p_1 + p_2)^2 \rightarrow 0$$

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The Team

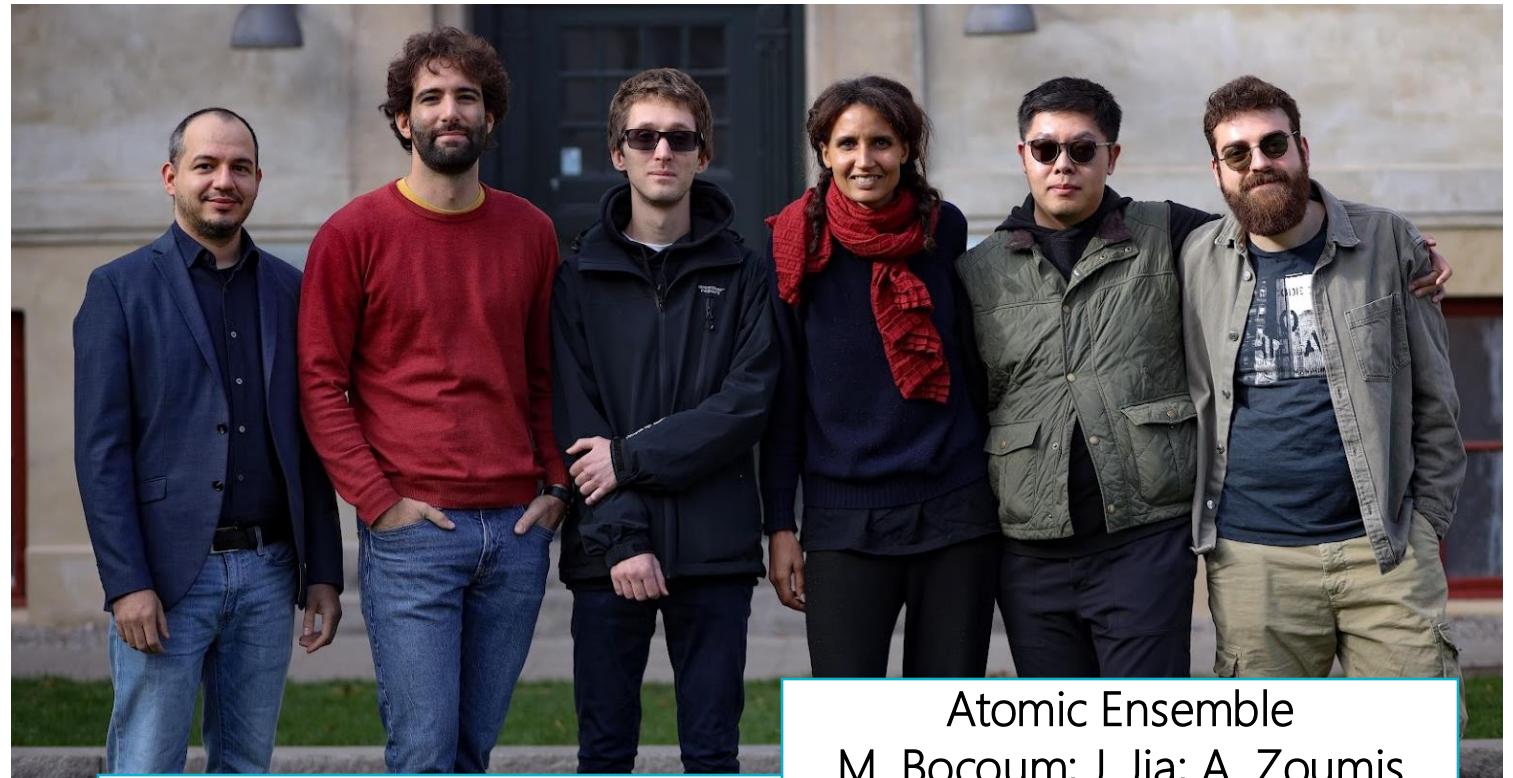
Niels Bohr Institute



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