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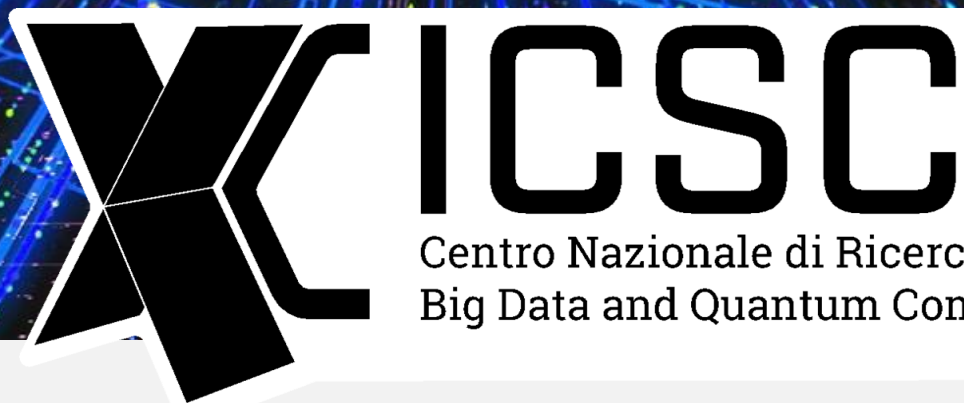


Italiadomani

PIANO NAZIONALE  
DI RIPRESA E RESILIENZA



Centro Nazionale di Ricerca in HPC,  
Big Data and Quantum Computing



Centro Nazionale di Ricerca in HPC,  
Big Data and Quantum Computing

# Super-Resolution Surrogate Model for Accelerated Geant4 Simulations

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(\*) Speaker

ICSC and Spoke2 – Where Are We Now?,  
Catania December 10-12, 2024



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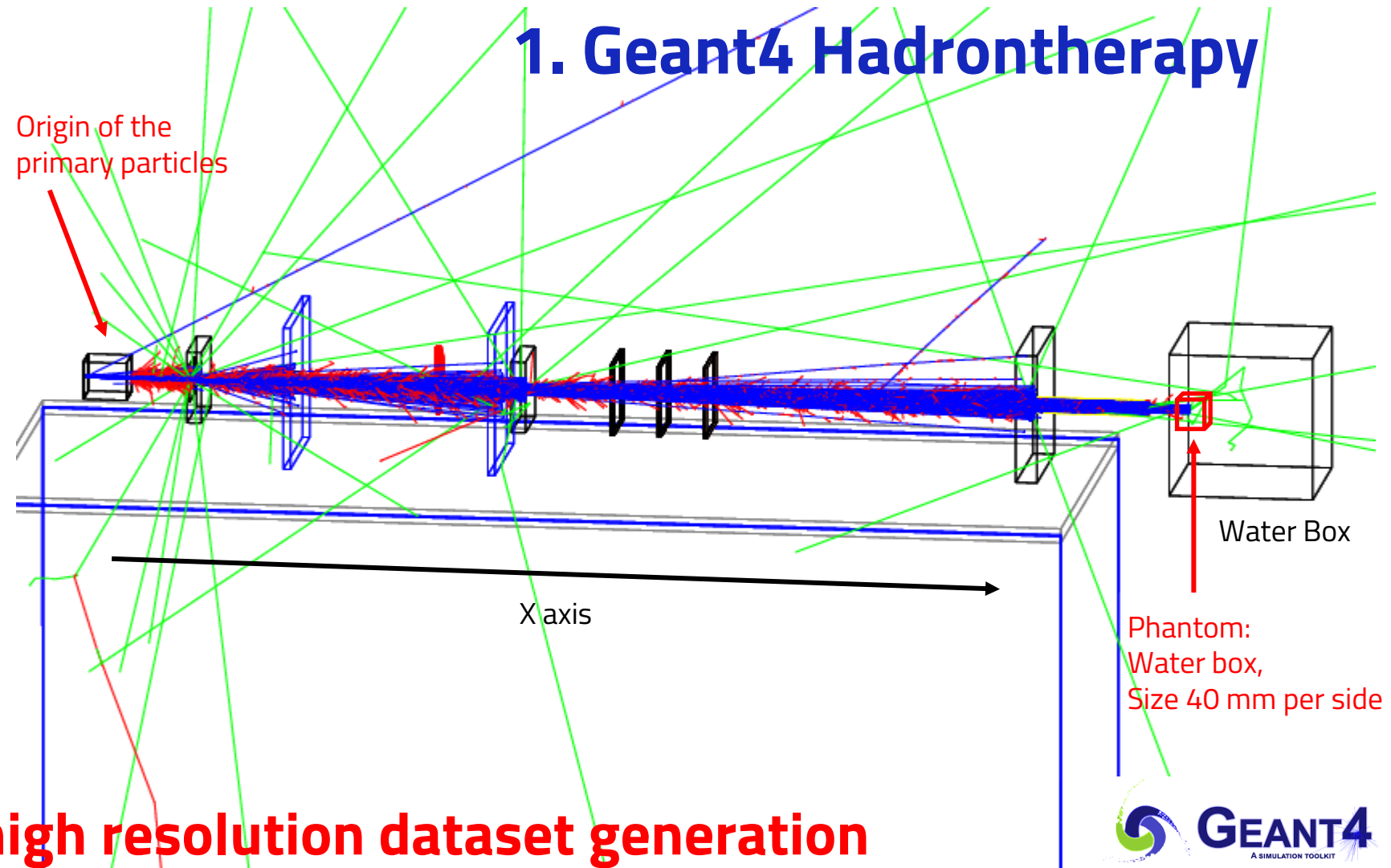
## SPOKE 2 - FUNDAMENTAL RESEARCH & SPACE ECONOMY

- WP 6
- UC 2.6.2 – ML\_GEANT4\_WP6

Enhancing Geant4 Monte Carlo Simulations  
through Machine Learning Integration

# 1. Geant4 Hadrontherapy

- Primary particles are protons of 63.5 MeV at the origin (62 MeV at phantom entrance)
- The phantom is subdivided in N slabs or "voxels" along the X axis
- The result of the simulation are:
  - Dose deposit in the phantom
  - Particle fluence
  - LET of primary particle and secondary ions



**>>> High quality, high resolution dataset generation**



[https://geant4.web.cern.ch/docs/advanced\\_examples\\_doc/example\\_hadrontherapy](https://geant4.web.cern.ch/docs/advanced_examples_doc/example_hadrontherapy)

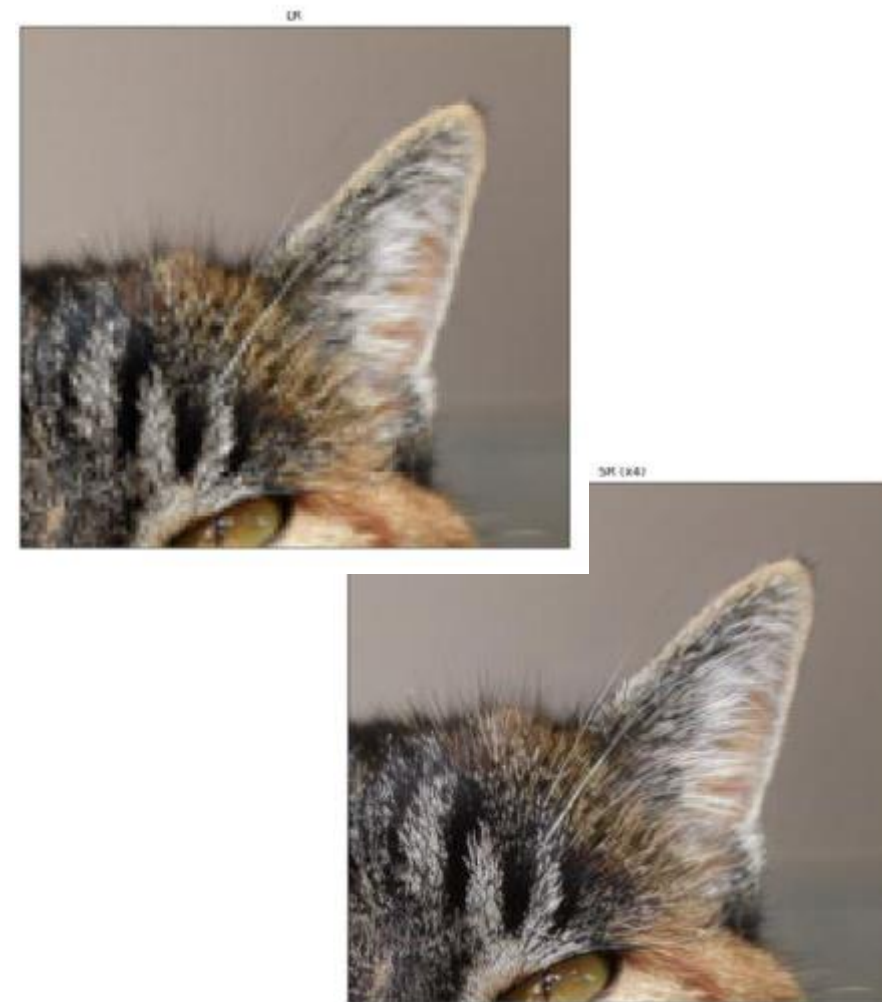
## 2. Super-Resolution in Machine Learning

### Goal:

- Predicting results that are **comparable** to high-resolution simulations
- **Challenge:** reduce computation cost by working with a lower voxel density

### Approach:

- **Input:** low-resolution data (lower density voxel)
- **Output:** improved simulations at higher resolution, predicted by the model.



### 3. Datasets production for ML training

Generating **high-density** and low-density datasets for studying and validating linear energy transfer (LET) calculation.

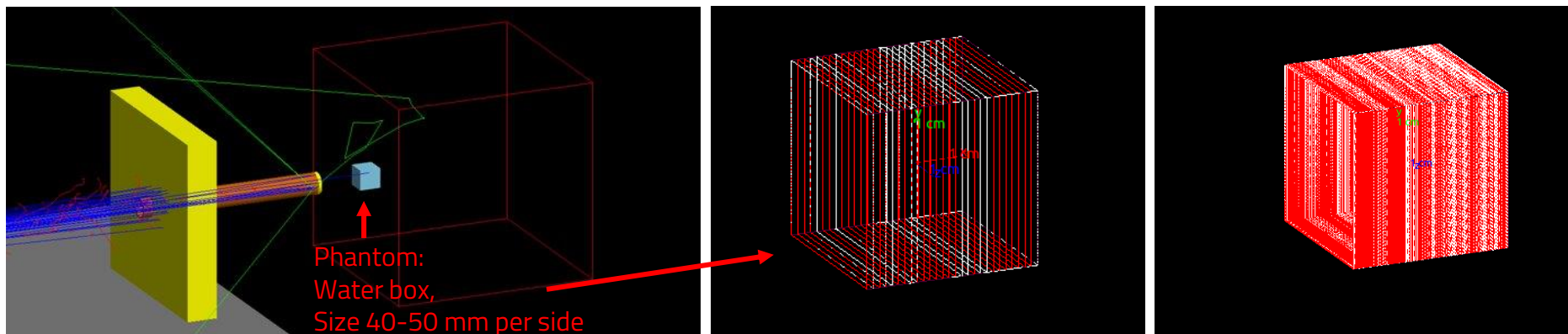
- How deep can we go with voxel sizes in Geant4?
- Up to which voxel size does the Geant4 code generate a physically correct simulation?
- How many primary particles do we need to run to get a reliable data set without blowing up the computational cost?

**Range Cut** (~ threshold on particle production)

- 1mm
- 100  $\mu\text{m}$
- 50  $\mu\text{m}$
- 10  $\mu\text{m}$
- 1  $\mu\text{m}$
- 0.5  $\mu\text{m}$

**Voxel Size:**

- 1 mm
- 100  $\mu\text{m}$
- 10  $\mu\text{m}$
- 1  $\mu\text{m}$



Cut (u)	Voxelsize (u)	Exec Time	CPU (%)	MEM (%)
1000	100	00h.00m.54s	78.96	0.11
100	100	00h.01m.08s	80.97	0.10
50	100	00h.01m.37s	84.47	0.12
10	100	00h.04m.25s	88.46	0.18
1	100	00h.33m.15s	92.03	0.20
0.5	100	00h.33m.20s	92.32	0.20
1000	10	00h.07m.27s	89.84	0.18
100	10	00h.08m.02s	89.81	0.19
50	10	00h.09m.08s	88.72	0.19
10	10	00h.18m.13s	90.50	0.20
1	10	00h.55m.52s	93.28	0.30
0.5	10	00h.56m.01s	92.78	0.30
1000	1	01h.17m.07s	90.07	0.20
100	1	01h.19m.27s	89.92	0.20
50	1	01h.24m.57s	91.63	0.22
10	1	01h.48m.07s	92.10	0.30
1	1	03h.14m.48s	93.31	0.50
0.5	1	03h.15m.00s	93.55	0.50

**N particles = 1 x 10<sup>6</sup>**

## 4. Execution time

- AMD EPYC 7552 96 Core
- 512 GB RAM

**N=96 Threads**



**Range Cut** (~ threshold on particle production)

- 1mm
- 100 μm
- 50 μm
- 10 μm
- 1 μm
- 0.5 μm

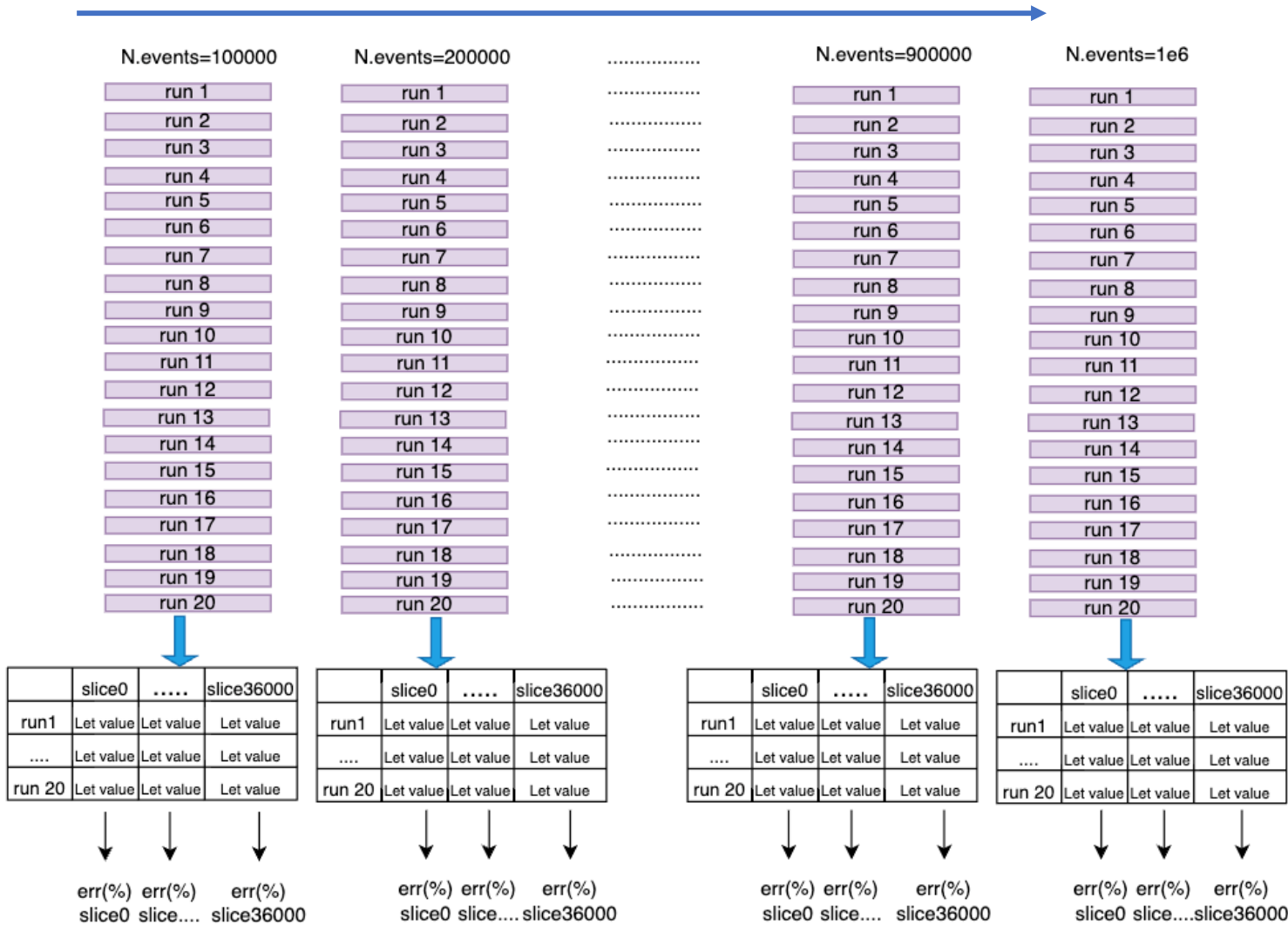
**Voxel Size:**

- 100 μm
- 10 μm
- 1 μm

# 5. Datasets validation

## How many particles for a reliable dataset?

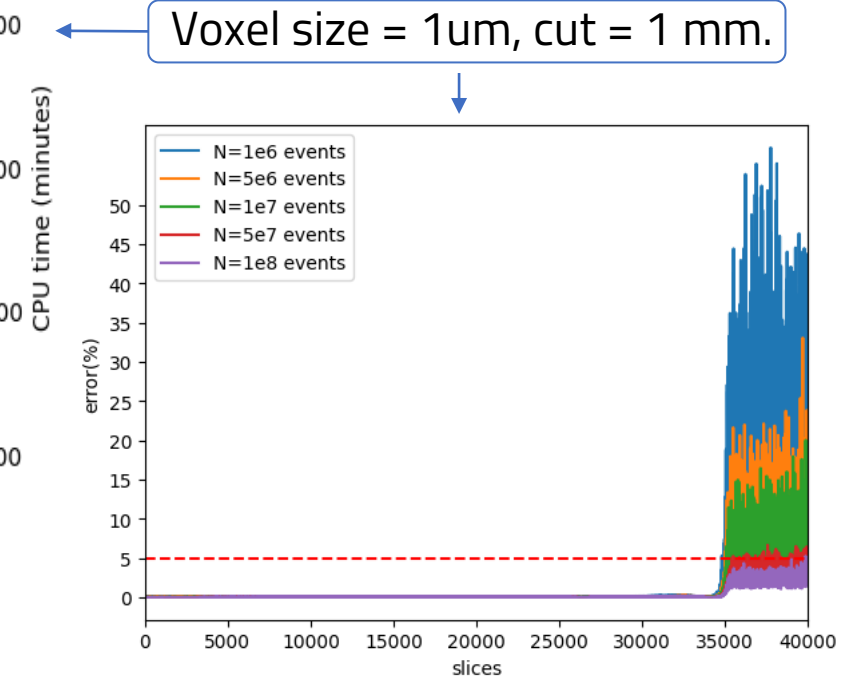
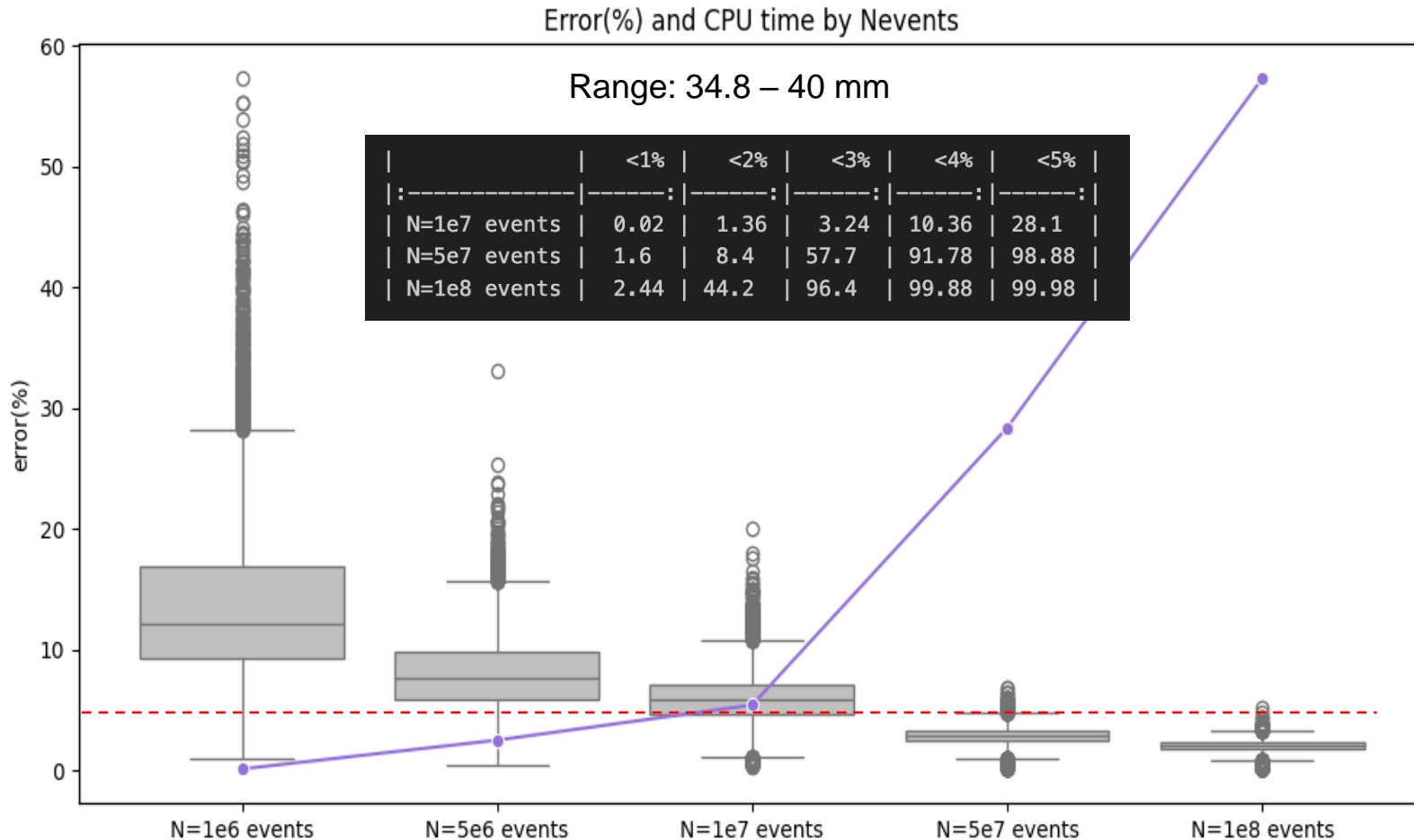
- Method definition: N events vs err(%) per slice



- AMD EPYC 7552 96 Core
- 512 GB RAM
- N=96 Threads

## 5. Datasets validation

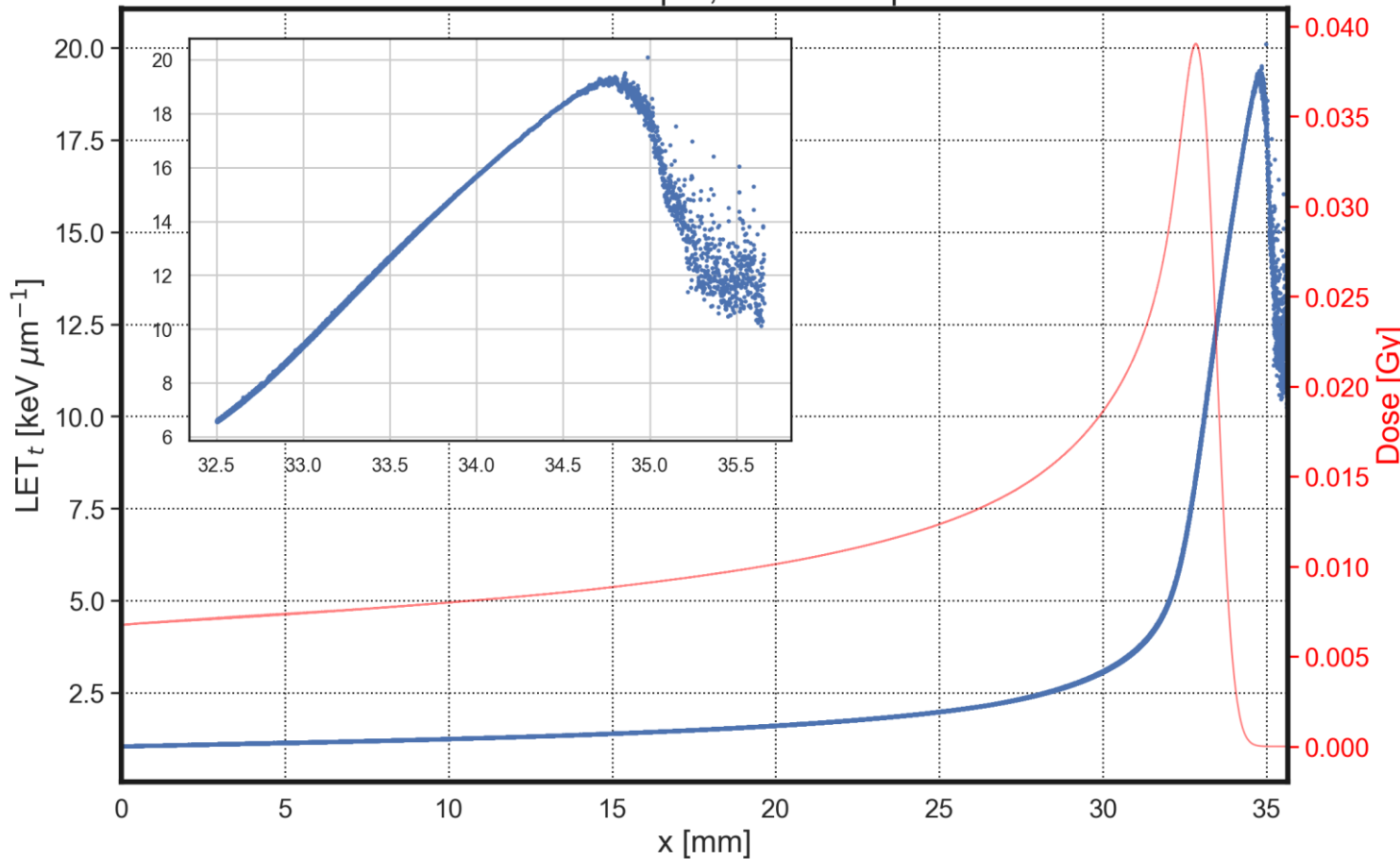
- The data considered for the box plots are err% (calculated on the 20 runs where the number of particles was fixed) for each voxel in the range indicated.





1e8 primary particles;  
Ep = 62 MeV at phantom entrance

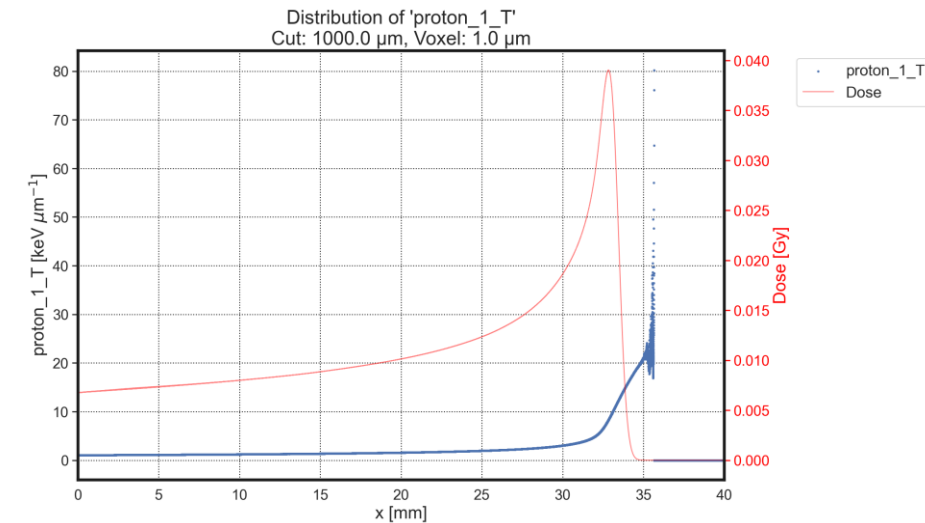
Scatter Plot for LET-track  
Cut: 1000.0  $\mu\text{m}$ , Voxel: 1.0  $\mu\text{m}$

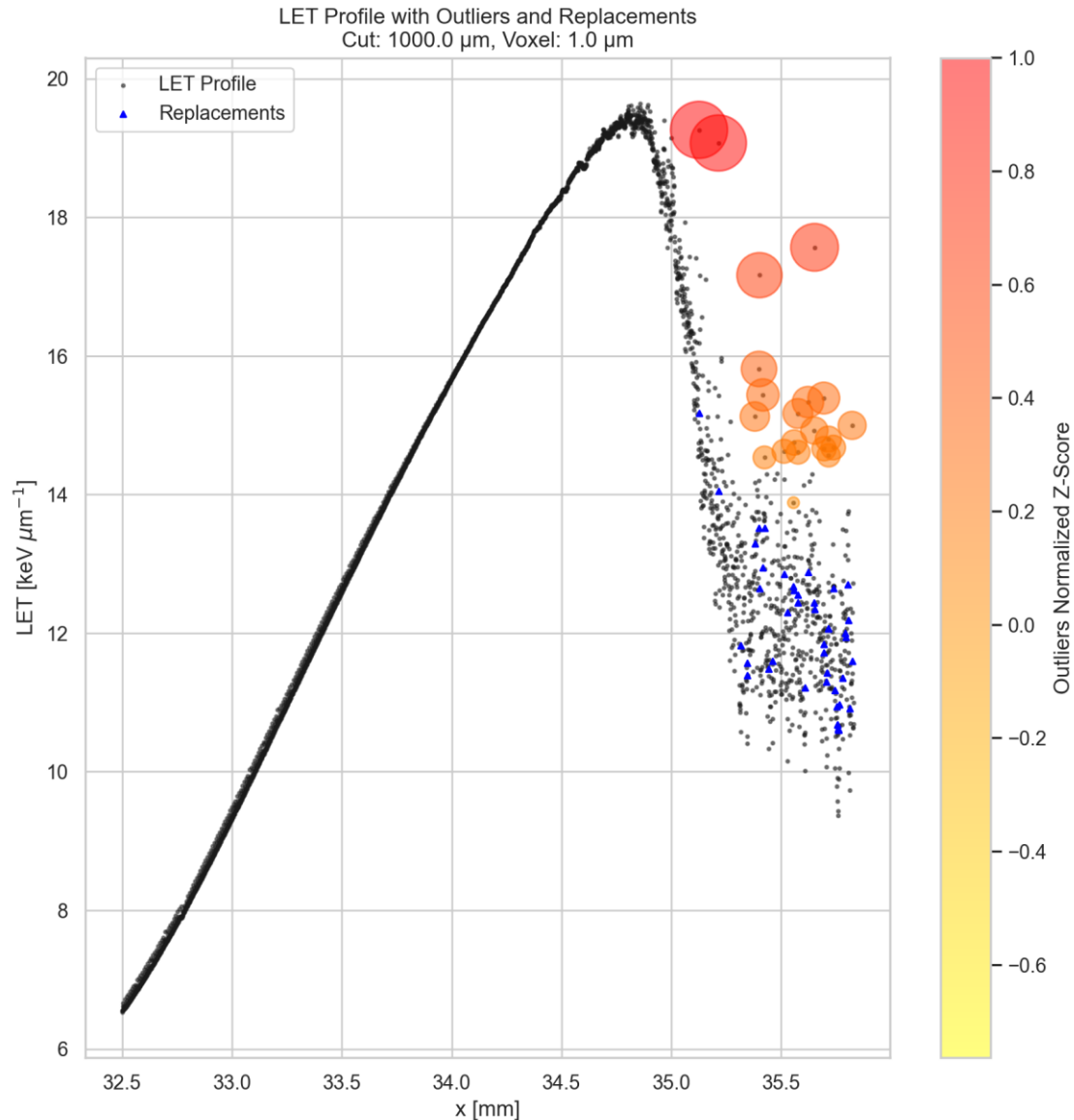


## 5. Dataset validation

### Dataset early stop:

- To limit the quality degradation of the LET profile, the data set is truncated corresponding to where the primary particle beam stops (~35.66 mm in water).





## 6. Data Exploration

### Dataset

- runbeam  $1 \times 10^8$ ,
- cut 1000  $\mu\text{m}$ ,
- voxel 1  $\mu\text{m}$

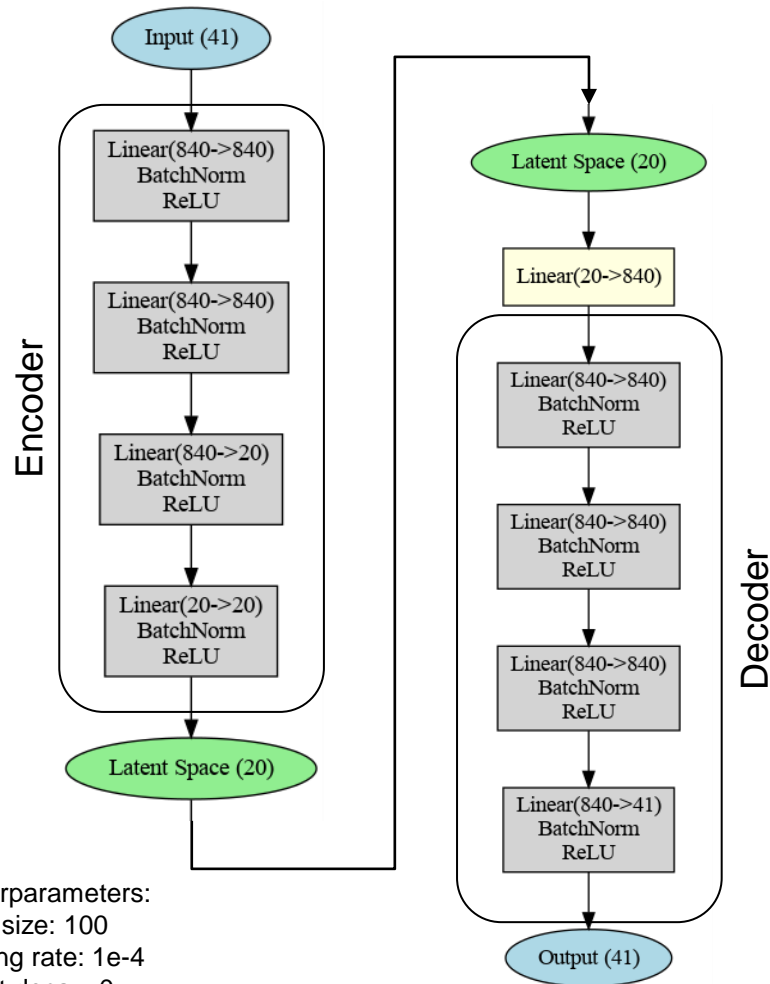
### Dataset cleanup:

Several combinations of first outlier detection and value replacement algorithms have been tested, including a denoising autoencoder.

The best results were obtained with:

- outliers\_method = 'DBSCAN',
- replace\_method = 'kneighbors\_regressor'

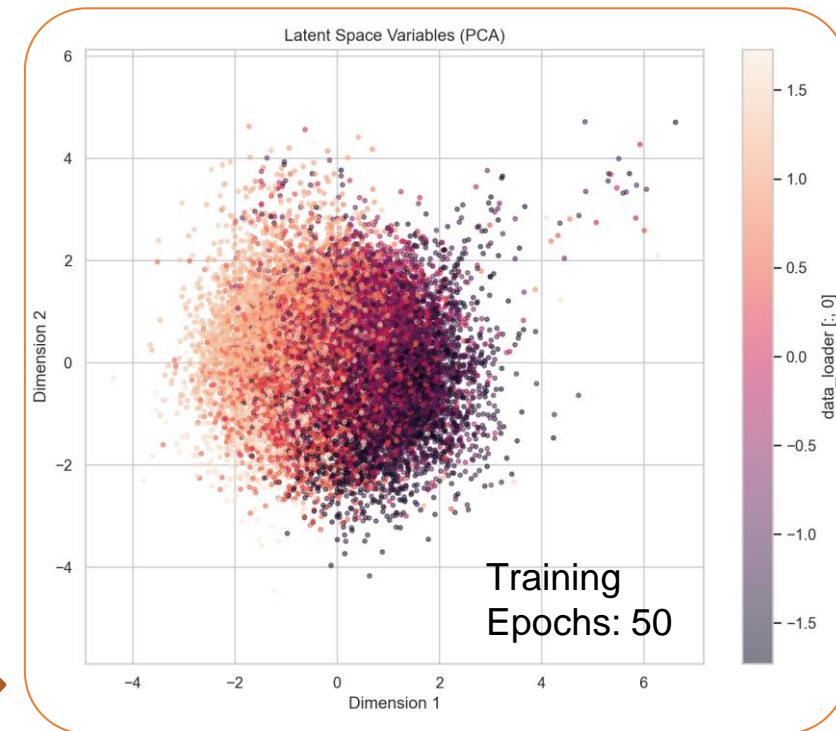
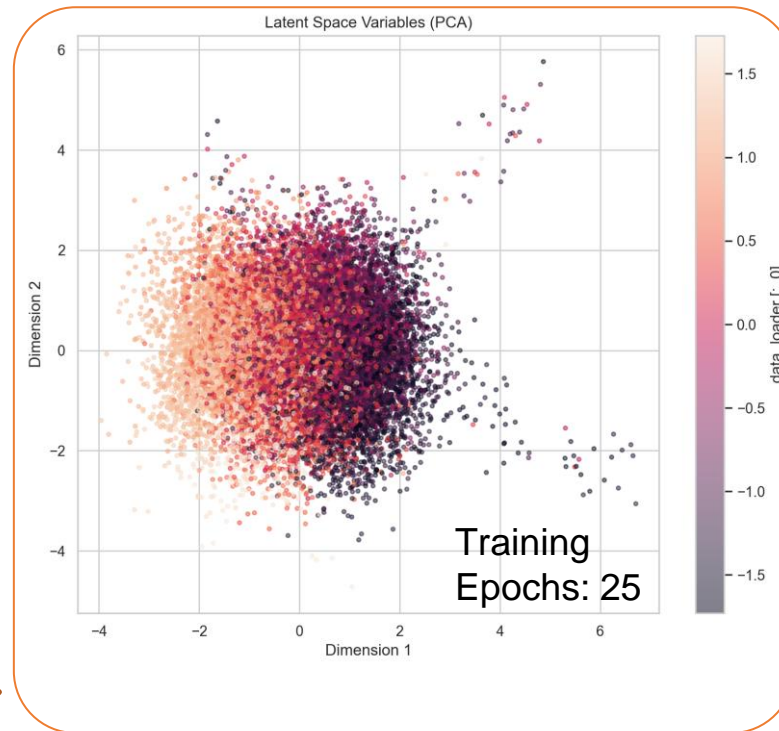
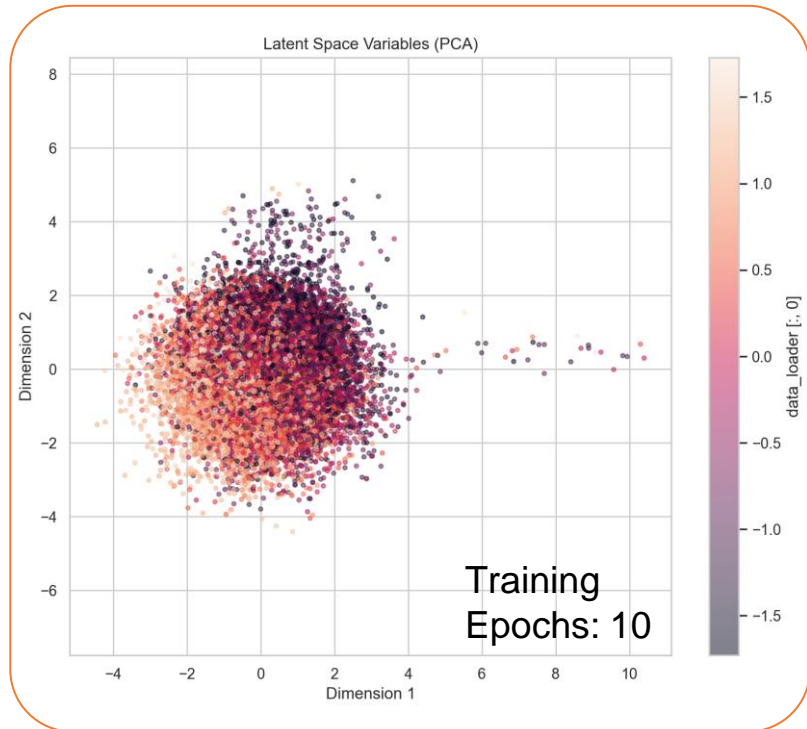
# 7. Super-Resolution model = Variational Autoencoder



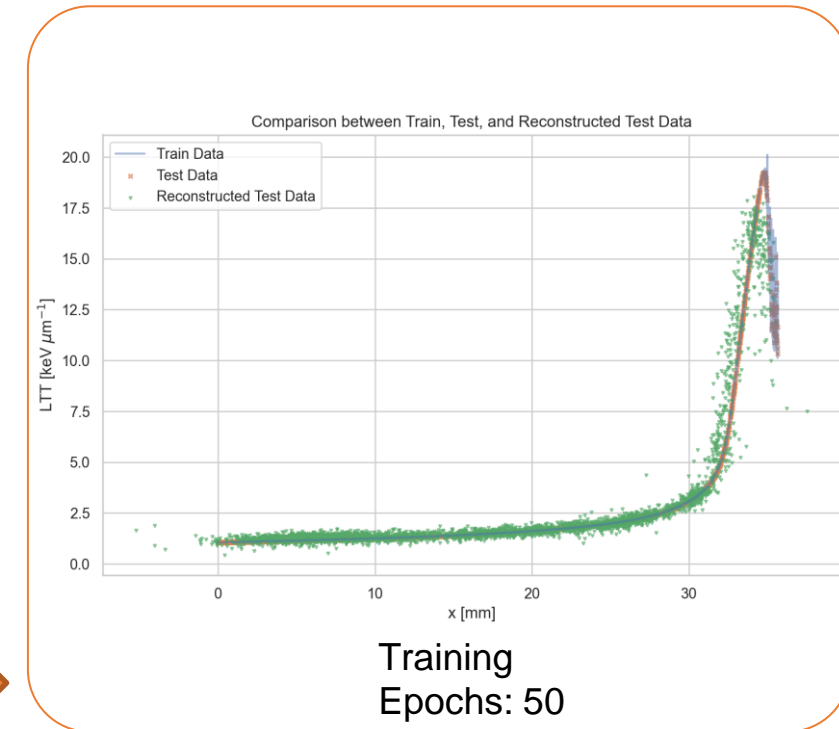
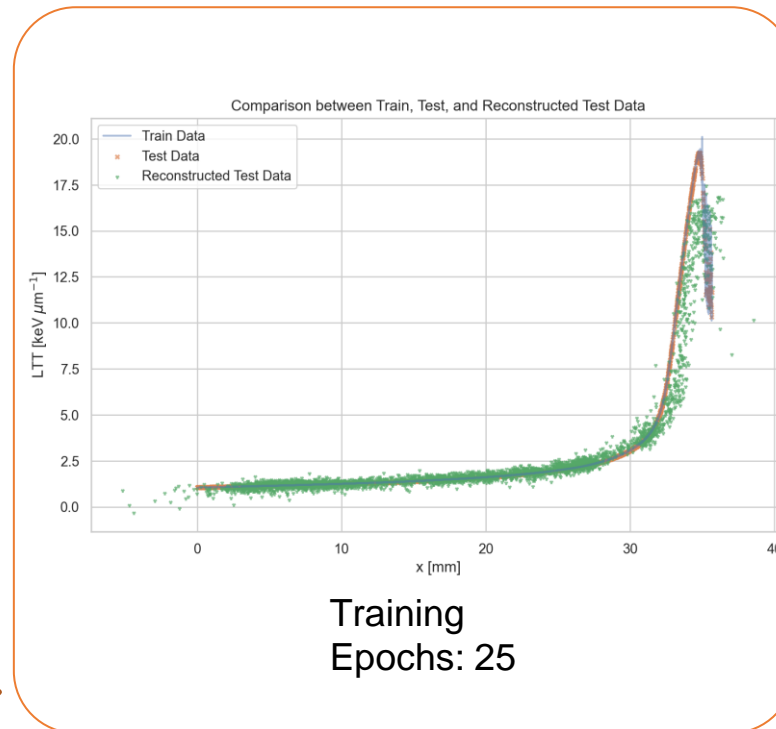
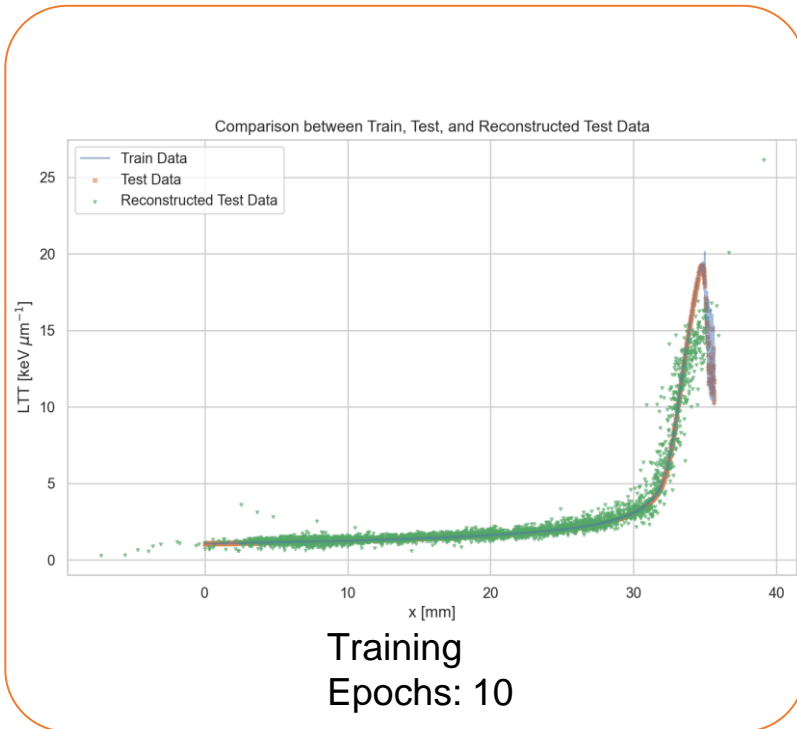
- Other hyperparameters:
- batch size: 100
  - learning rate: 1e-4
  - weight decay: 0



# 7. Super-Resolution model: Latent Space Evolution



# 7. Super-Resolution model: Test vs Reconstructed Data



## 8. Where are we now?

KPI ID	Description	Acceptance threshold
KPI2.6.1.1	Publications	1
KPI2.6.1.2	Presentation at conferences	1 <input checked="" type="checkbox"/>
KPI2.6.1.3	Publicly available Code repository	1 <input checked="" type="checkbox"/>
KPI2.6.1.4	Use case Test Datasets defined	1 <input checked="" type="checkbox"/>
KPI2.6.1.5	Geant4 Algorithms to be used as targets for a ML optimization	1 <input checked="" type="checkbox"/>
KPI2.6.1.6	Efficiency Gain on the same hardware: The improved simulation, when run on the same hardware as the standard simulation, should achieve at least a 20% reduction in the time taken to generate predictions.	20% in time reduction, with acceptable physics performance

### Achievements:

- Talk delivered at Congress of the Italian Physical Society (Bologna, September 9-13, 2024)
- 1<sup>st</sup> release of a public accessible code [repository](#)
- Testing and validation on chosen dataset
- LET calculation algorithm is the primary target for optimization by ML model for super-resolution task

## 8. Where are we now?

### Next Steps:

- Publish a paper in a peer-reviewed journal as soon as the ML model produces satisfactory results
- Create a pipeline to directly interface the ML model with the MC simulation and estimate the efficiency gain
- Test the ML model on the entire dataset, including the tail after the Bragg Peak
- Test of additional model strategies (stacked or chained AE, GAN...)

KPI ID	Description	Acceptance threshold
KPI2.6.1.1	Publications	1
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[www.supercomputing-icsc.it](http://www.supercomputing-icsc.it)

## ***Acknowledgements***

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**Università  
di Catania**



***Thank you for the  
attention!***



# Resources Required

LEONARDO BOOSTER-GPU	
Minimum Number of GPU hours	3000
Optimal Number of GPU hours	6000
Maximum number of usable GPU	2 (via tensorflow/ pytorch)
Total RAM	512 GB

CLOUD		
Data storage	5 TB	
vCPU	Number	24
	Time (Hours)	1600
	Optimal number of core	90
	Total RAM	512 GB

## 4. Execution time

- AMD EPYC 7552 96 Core
- 512 GB RAM

**N=32 Threads**



Cut(um)	Voxelsize(um)	Exec Time	CPU(%)	MEM(%)
1000	100	00h.00m.11s	16.72	0.08
100	100	00h.00m.12s	18.39	0.08
50	100	00h.00m.15s	20.48	0.09
10	100	00h.00m.26s	26.96	0.09
1	100	00h.02m.33s	31.86	0.1
0.5	100	00h.02m.36s	31.83	0.1
1000	10	00h.00m.43s	28.99	0.1
100	10	00h.00m.45s	29.27	0.1
50	10	00h.00m.51s	29.42	0.1
10	10	00h.01m.28s	30.98	0.1
1	10	00h.04m.12s	32.23	0.1
0.5	10	00h.04m.10s	32.26	0.1
1000	1	00h.06m.14s	31.72	0.1
100	1	00h.06m.25s	31.7	0.1
50	1	00h.07m.10s	31.62	0.1
10	1	00h.08m.47s	31.85	0.1
1	1	00h.15m.04s	32.3	0.2
0.5	1	00h.15m.00s	32.25	0.2

**N particles = 5 x 10<sup>5</sup>**

**Range Cut** (~ threshold on particle production)

- 1mm
- 100 μm
- 50 μm
- 10 μm
- 1 μm
- 0.5 μm

**Voxel Size:**

- 100 μm
- 10 μm
- 1 μm