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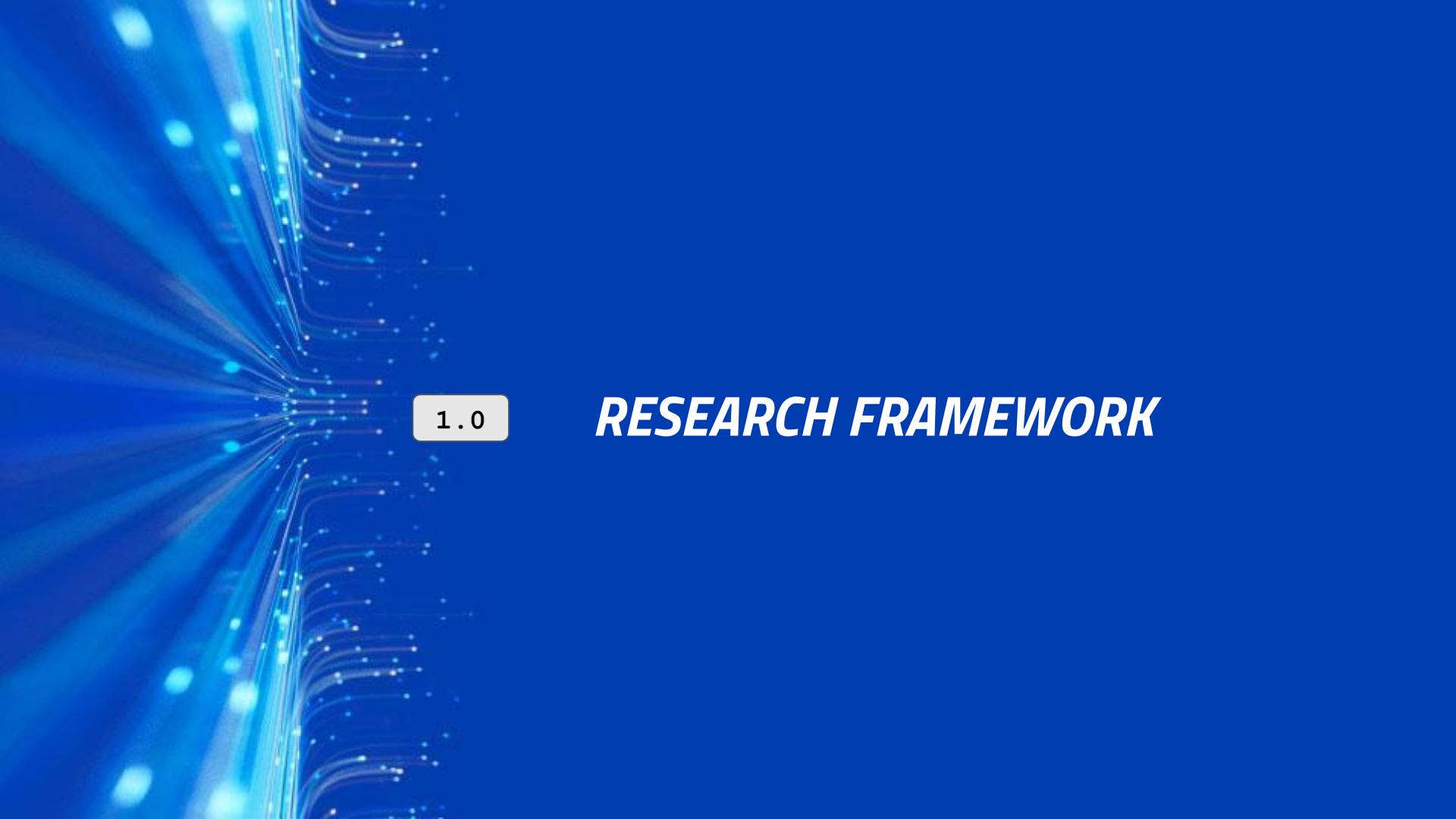


Centro Nazionale di Ricerca in HPC,
Big Data and Quantum Computing

Graph Anomaly Detection with GNNs: A Case Study on Predictive Maintenance for ENI's Industrial Machinery

R. Cornali, E. Ronchieri, Giovanni Zurlo

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The background of the slide features a dynamic, abstract design in shades of blue. It consists of numerous thin, glowing blue lines that curve and twist across the frame, creating a sense of motion and depth. Interspersed among these lines are numerous small, bright blue dots of varying sizes, resembling stars or distant galaxies. The overall effect is one of a futuristic, digital landscape.

1 . 0

RESEARCH FRAMEWORK

Research Framework

In mission-critical industries, continuous operation exposes equipment to wear that can escalate into costly failures and downtimes.

Raw data from IoT sensors enables real-time monitoring and predictive maintenance (PdM) of systems.



The goal is to perform maintenance when the maintenance activity is most **cost-effective** and **before the system loses performance**, going below an acceptable threshold.



Innovation Grant:

"Harnessing the Power of Artificial Intelligence for Predictive Maintenance of Industrial Plants"



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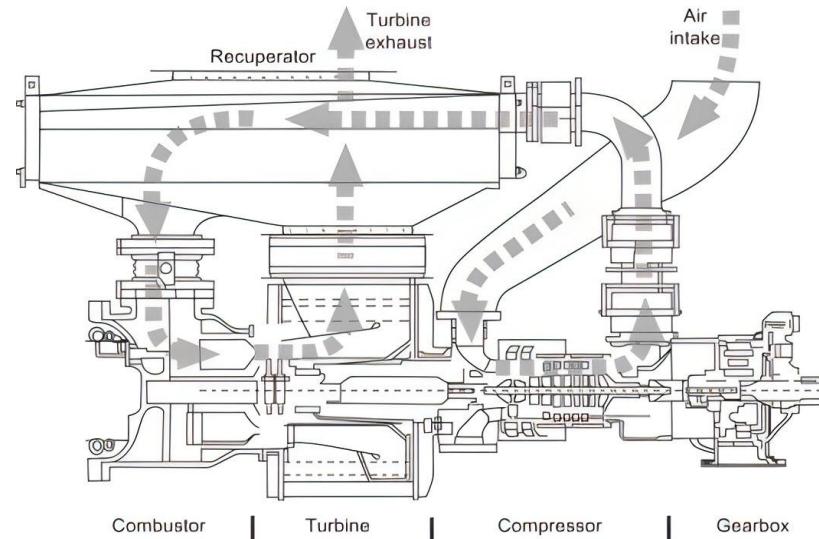
OUR APPROACH

Dataset

We tested our model on signals from industrial rotating machines operating at the ENI COVA plant [1]. For instance, we analyzed multivariate time-series data from a turbine generator, dedicated to supply the entire plant.

The series includes measurements from 55 sensors collected over a 390 days period.

| Measurement Type | Object of measurement |
|------------------------------|---|
| Turbine Operating Conditions | Turbine speed, Rotor speed |
| Temperatures | Fuel, Lube Oil, Bearings, Thermocouples, Drains, Enclosure |
| Pressures | Fuel, Lube Oil |
| Vibration Levels | Turbine Bearings, Gearbox, Generator |
| Electrical | Generator Amperage, Voltage, Frequency, Output and Reactive Power |

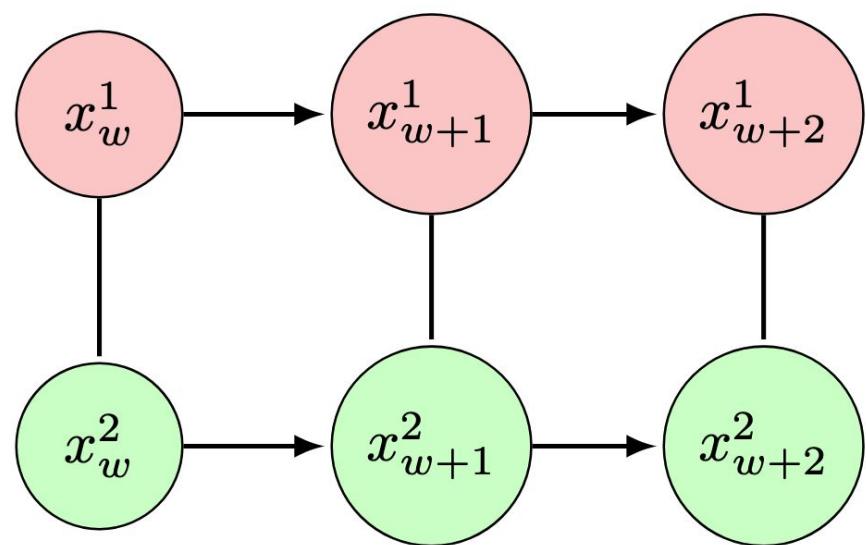


From Time-Series to Graphs

We followed a correlation network approach yielding to a single-layer of observations-based nodes [2].

Cross-Correlations

| Time | sensor1 | sensor2 |
|-----------|-------------|-------------|
| t_1 | x_1^1 | x_1^2 |
| t_2 | x_2^1 | x_2^2 |
| t_3 | x_3^1 | x_3^2 |
| \dots | \dots | \dots |
| t_w | x_w^1 | x_w^2 |
| t_{w+1} | x_{w+1}^1 | x_{w+1}^2 |
| t_{w+2} | x_{w+2}^1 | x_{w+2}^2 |



From Time-Series to Graphs

Two nodes are connected if the correlation between the signals in the last w timestamps is higher than **Alpha**. Similarly, two nodes associated with the same signal are connected if the autocorrelation between those timestamps is higher than **Beta**.

Alpha = 0.4, Beta = 0.3,
 $w = 100$

Frequency: 5 min

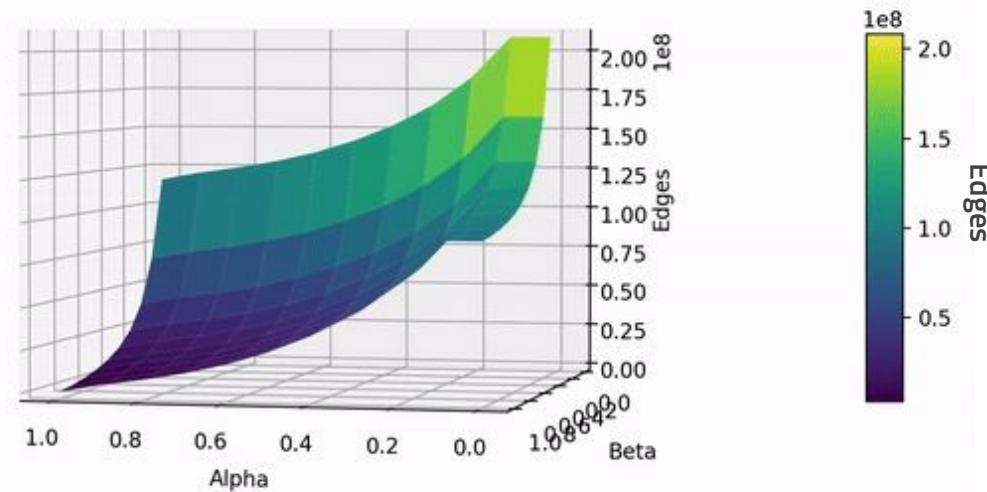
Variables: 55

Nodes: 6.186.620

Edges: 150.476.153

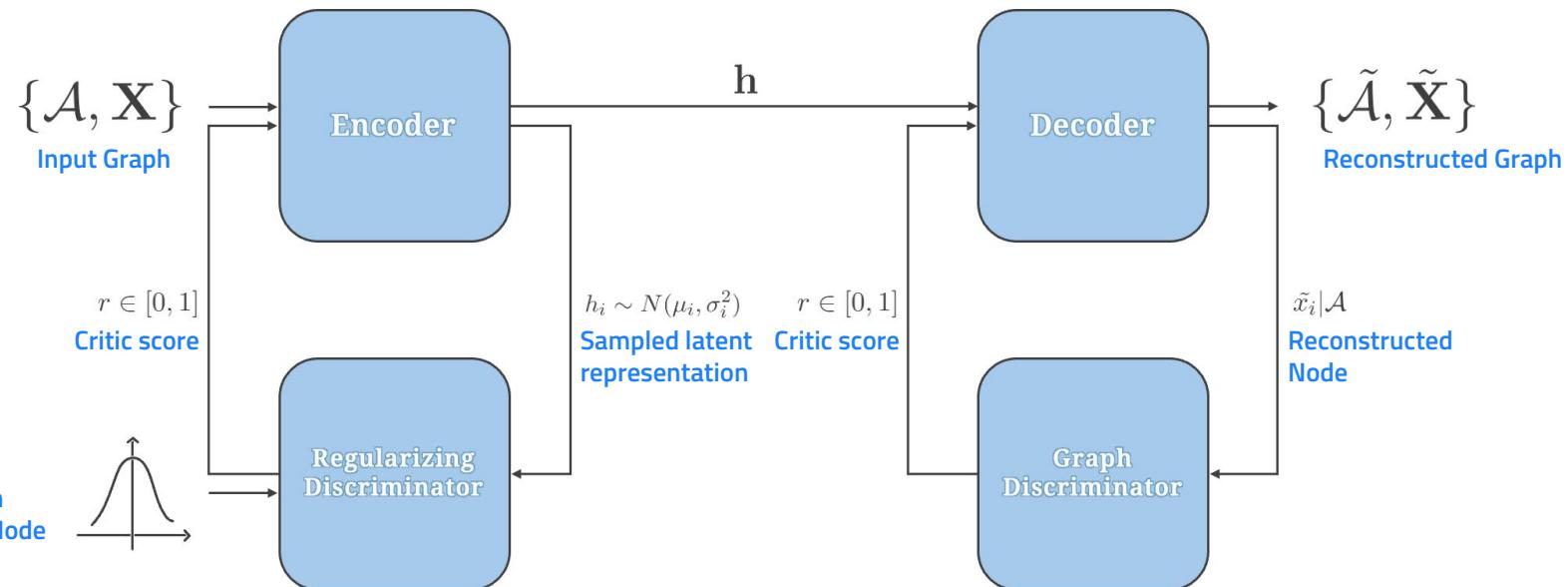


<1hr on LEONARDO DCGP [3]



Our Model

We can think of this model as two interconnected Generative Adversarial Networks (GANs), where the Autoencoder works as a double generator.



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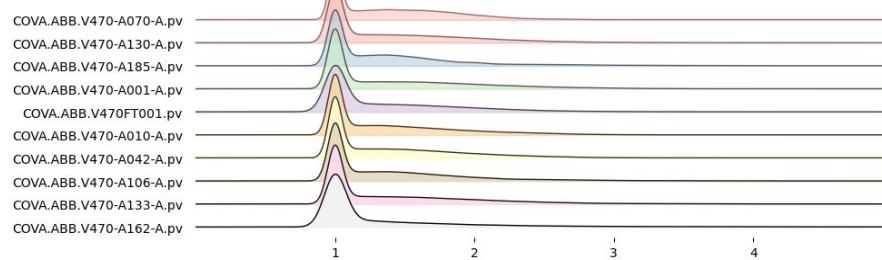
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RESULTS

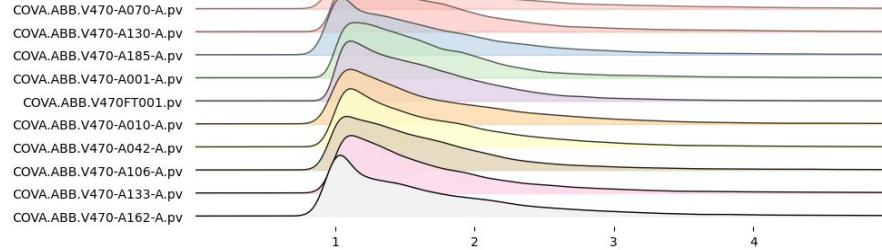
Anomaly Scores

Our model generates both a critic score and a reconstructed attribute for each node in the input graph, i.e. for each (time, signal) pair. This allows for a fine-grained examination of the model's predictions.

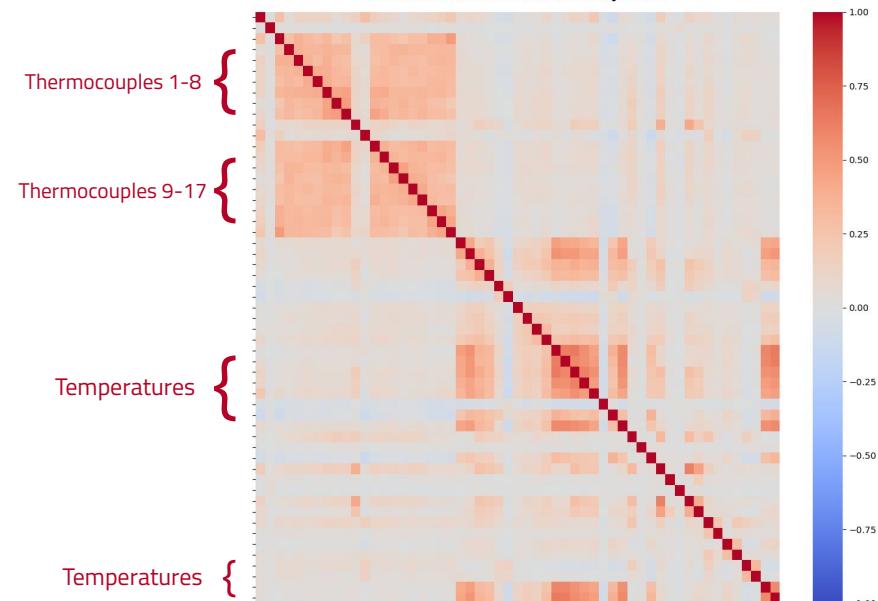
Reconstruction Errors



Graph Discriminator Loss



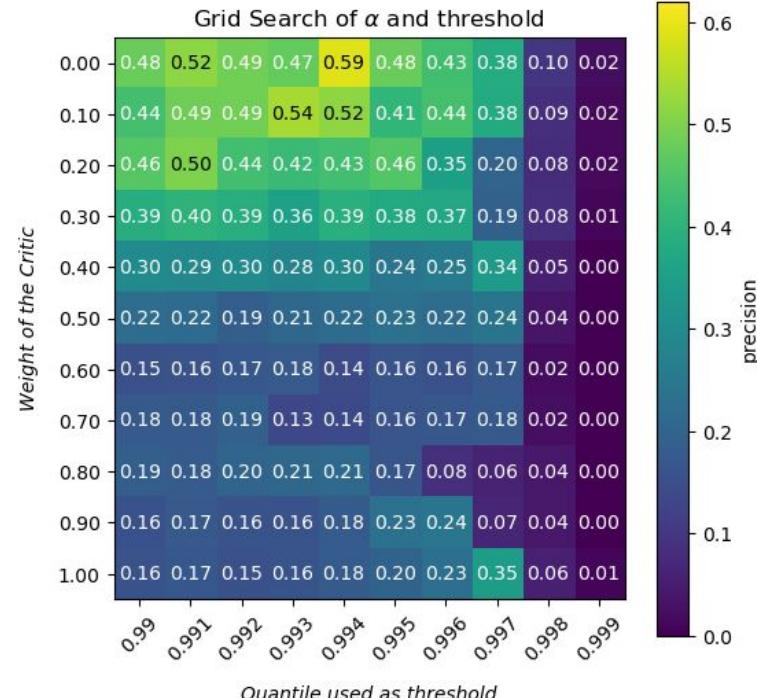
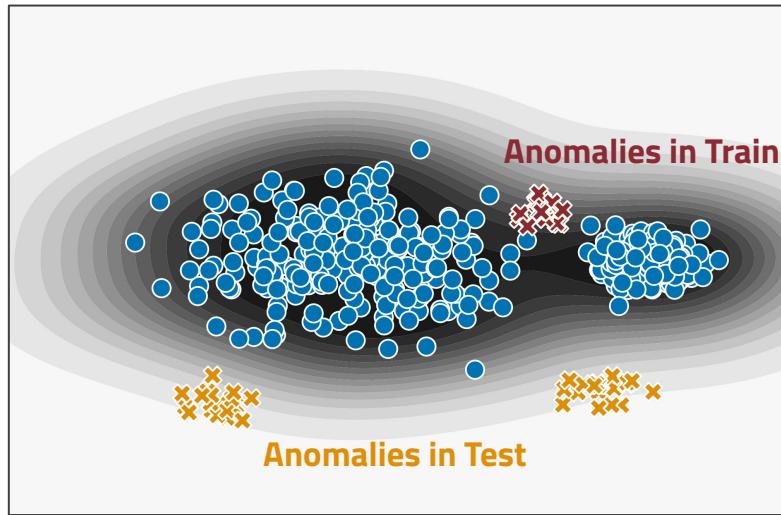
Correlation Matrix of the Anomaly Scores



2 Phase Semi-Supervised Method

By removing known anomalies in training, the model learns the normal data representation.

A decision threshold is tuned to correctly identify all anomalies possibility without misclassifying normal data.

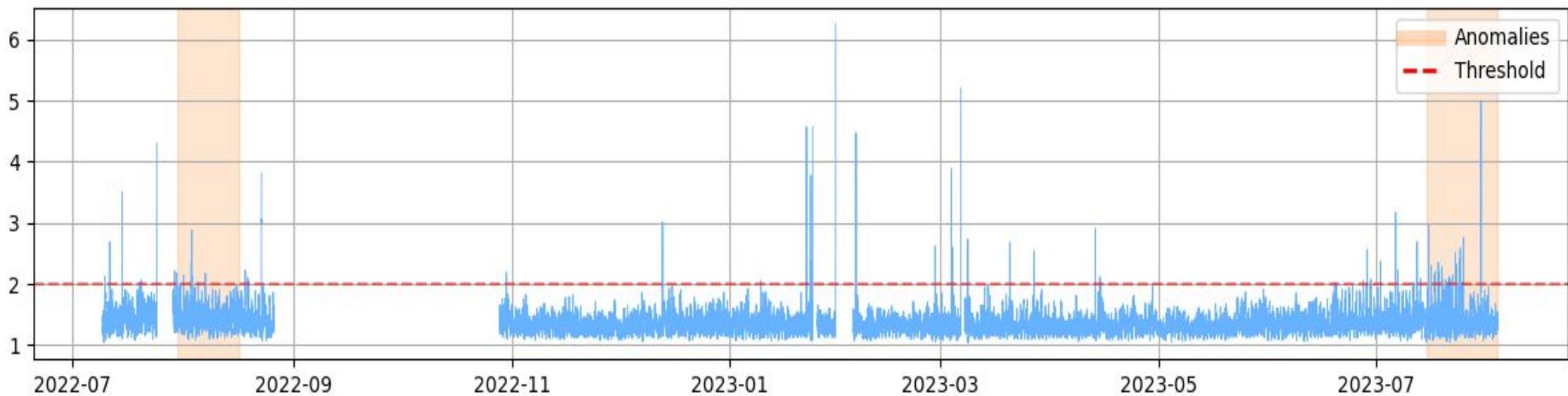




Anomaly Detection

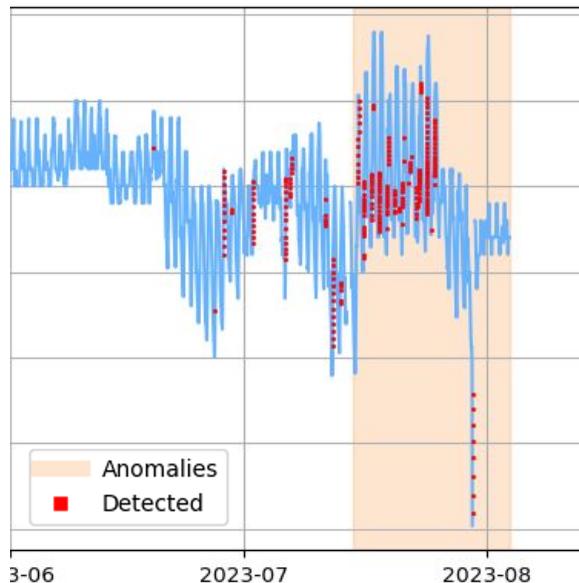
A threshold is required to do the decision: if the score for a point is greater than the threshold, an alert should be triggered. In this way, anomaly detection is similar to an imbalanced classification problem and well-known evaluation metrics can be used.

Time-Averaged Anomaly Scores

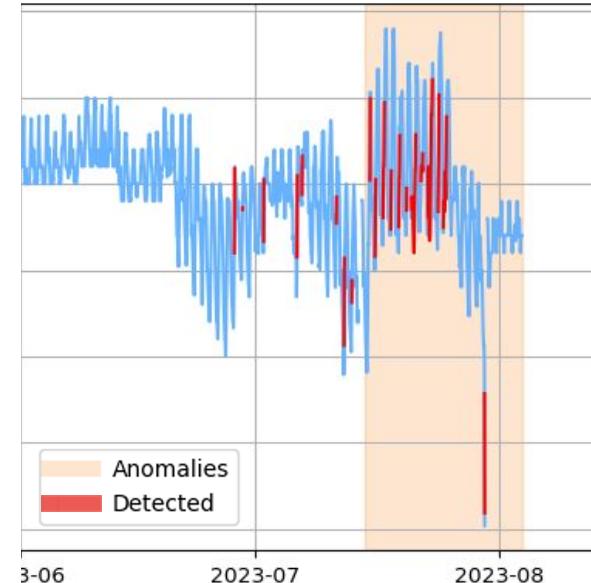


Anomaly Detection

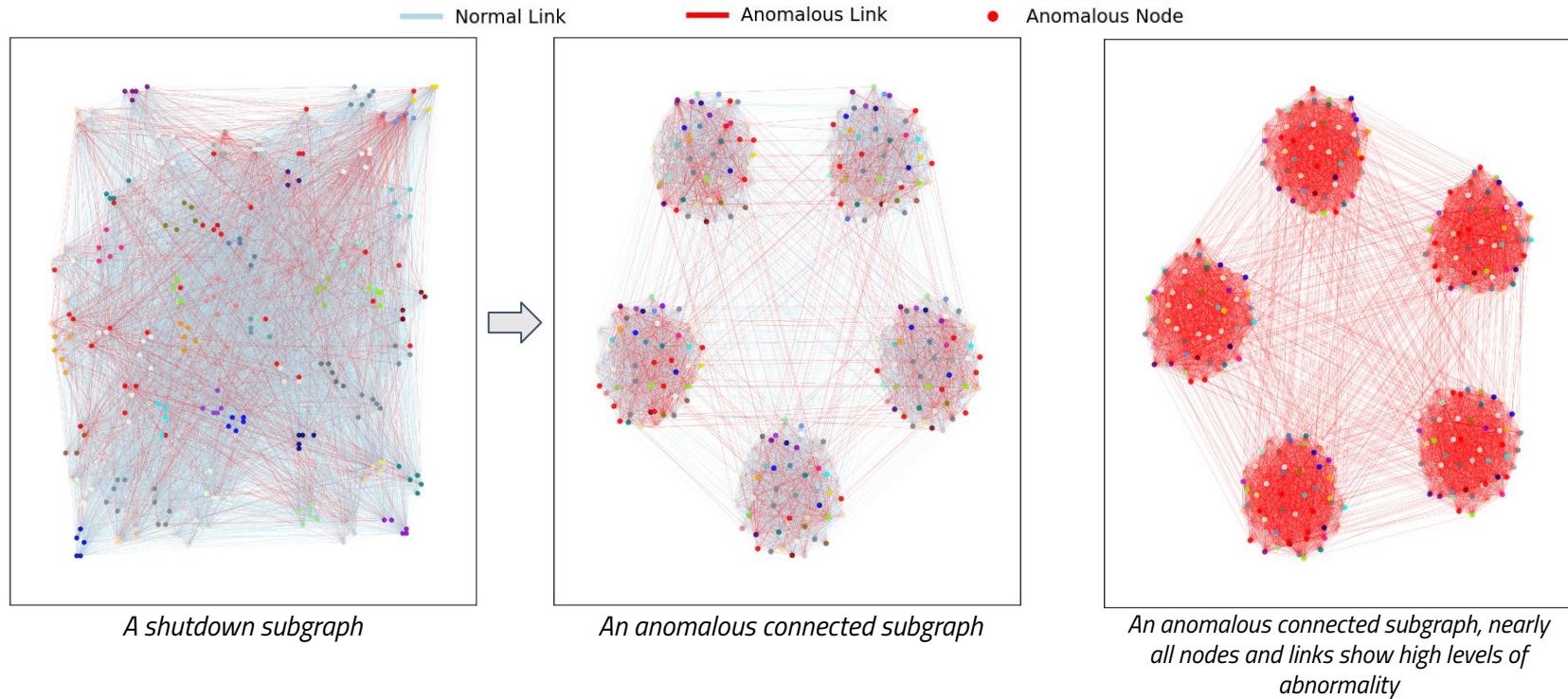
In real applications, the human operators generally do not care about these point-wise metrics. In practice, anomalous observations usually occur continuously to form contiguous anomaly segments. Thus, it is acceptable for an algorithm to trigger an alert for any point in a contiguous anomaly segment, if the delay is not too long [4].



Allow 12 hrs gap



Model Interpretation with Graphs

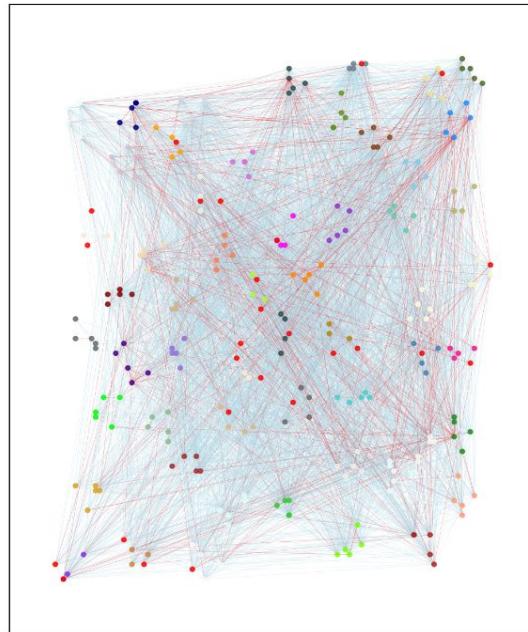


Model Interpretation with Graphs

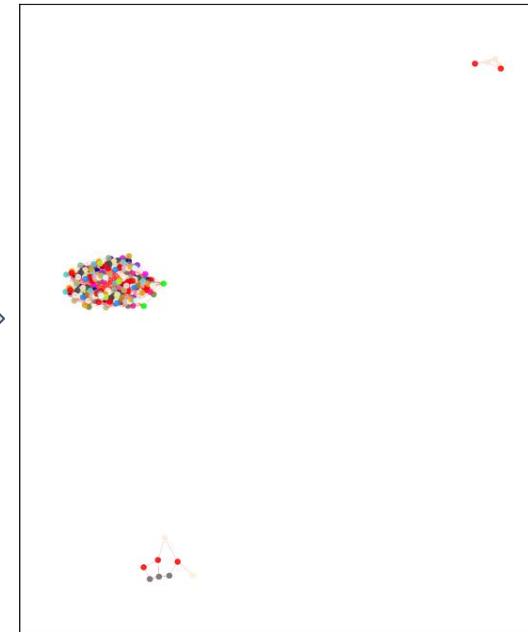
— Normal Link

— Anomalous Link

● Anomalous Node



A subgraph from anomalous interval



A unique anomalous connected subgraph



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Thanks!

Any questions or comments?

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References

1. Il Centro Olio Val d'Agri - <https://www.eni.com/eni-basilicata/it-IT/chi-siamo/centro-olio-val-d-agri.html>
2. Yang, Y. and Yang, H. (2008). Complex network-based time series analysis. *Physica A: Statistical Mechanics and its Applications*, 387(5–6):1381–1386.
3. [Leonardo HPC System | Leonardo Pre-exascale Supercomputer](#)
4. Su, Y., Zhao, Y., Niu, C., Liu, R., Sun, W., & Pei, D. (2019). Robust Anomaly Detection for Multivariate Time Series through Stochastic Recurrent Neural Network. *Proceedings of the 25th ACM SIGKDD International Conference on Knowledge Discovery & Data Mining*. <https://doi.org/10.1145/3292500.3330672>