

End-to-End Optimization of Generative AI for Robust Background Estimation

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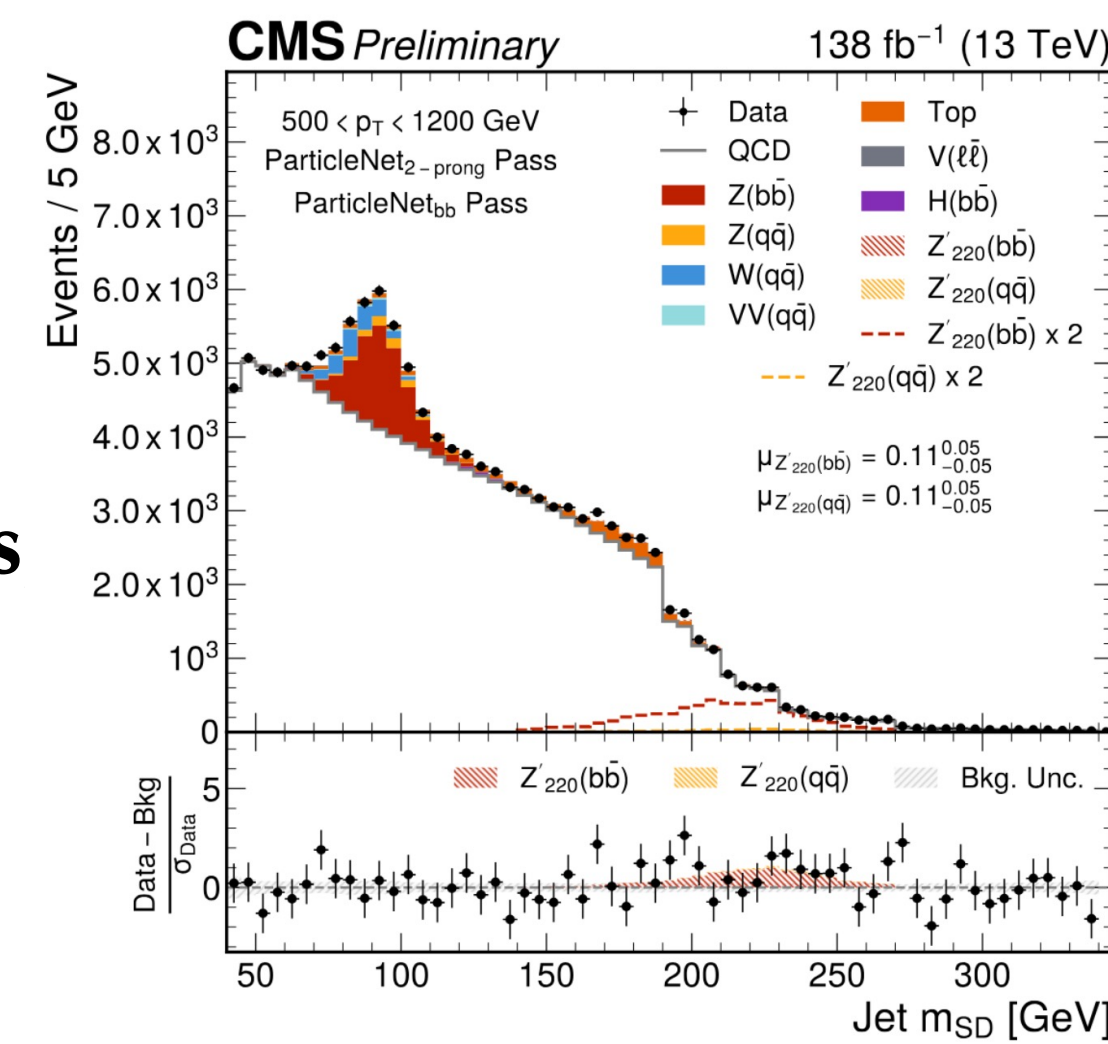
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MOTIVATION

Why do we need **better background models**?

LHC searches for BSM physics often target **rare-event, tails of distributions** where tight selection cuts **reduce background statistics** making **MC simulations too computational expensive** for reliable **background modeling, necessary for anomaly detection**.

→ **Generative data-driven models**



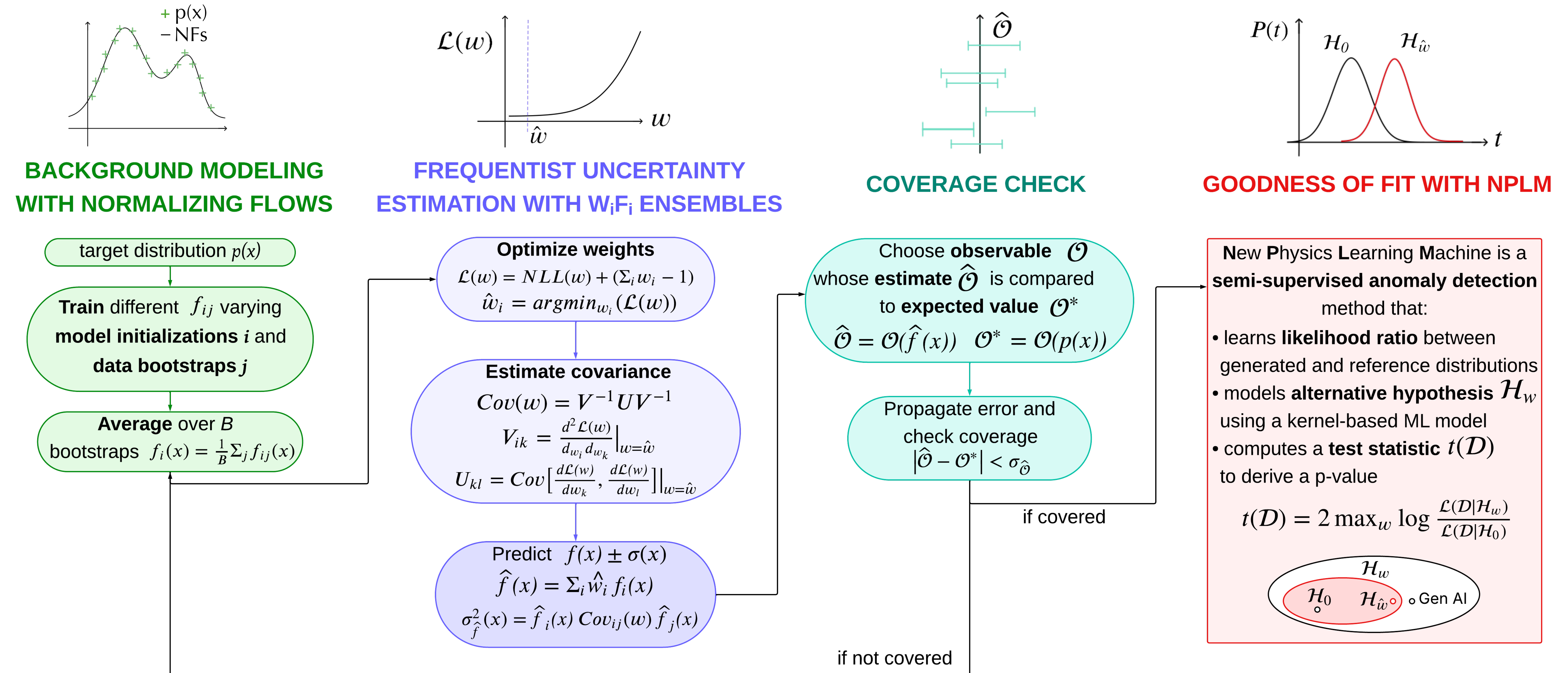
PROBLEM

To what extent can we trust **Generative AI**?

Generative models can interpolate complex distributions, **but in low-statistics regions** they may be **less precise**, so **estimating shape uncertainty is essential for robust use**.

→ **Model uncertainties** to ensure **robust anomaly detection** in **data-limited scenarios**

END-TO-END METHOD



NUMERICAL EXPERIMENT

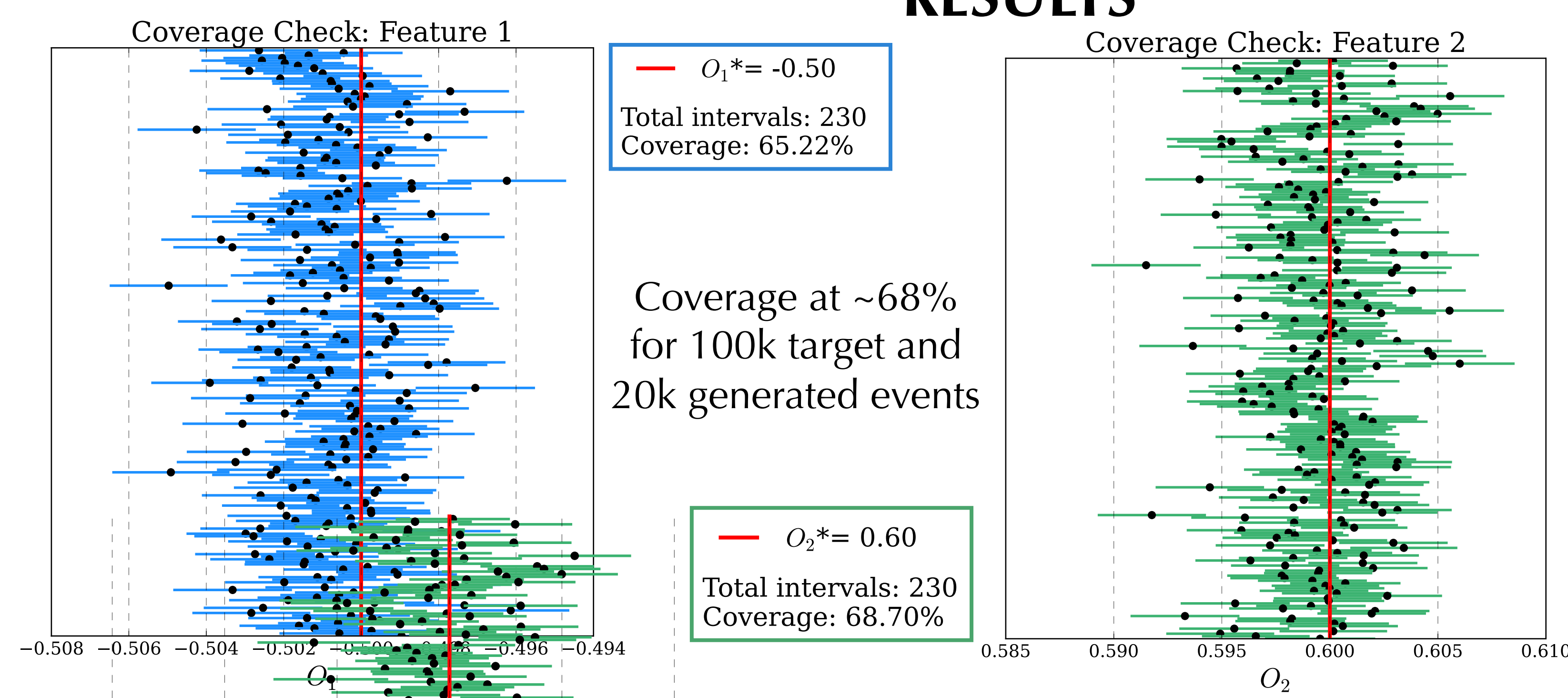
Training:

- target distribution $p(x) = \mathcal{N}(\vec{\mu}, \vec{\sigma})$ $\begin{cases} \vec{\mu} = (-0.5, 0.6) \\ \vec{\sigma} = (0.25, 0.4) \end{cases}$
- 100k target events
- each NF uses masked autoregressive splines and permutations
- 30 models on different bootstrapped datasets

For checking the coverage:
we choose observable $\hat{\mathcal{O}} = \int dx x \hat{f}(x)$
with expected value $\mathcal{O}^* = \int dx x p(x)$
best architecture found for coverage:
#bins = 15, #layers = 4, #blocks = 16, #features = 128

We use NPLM to test whether generated distribution $f(x)$ differs significantly from target distribution $p(x)$ corresponding to null hypothesis $\mathcal{H}_0$

RESULTS



FUTURE WORK

- Smoothness and flexibility impact on ensemble behavior
- Compare with other density estimators, e.g. Mixture of Gaussians
- Compare with alternative uncertainty modeling, e.g. Dropout, Bayesian Flows
- Integrate uncertainty into the GoF test

