# Training with Real Rata : Signal Extraction via Density Ratios

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Based on: [DIG, RT,](https://arxiv.org/abs/2409.08183)  [arXiv:2409.08183 \(2024\)](https://arxiv.org/abs/2409.08183)

# Density Ratios

● Often we require the ratio of 2 different distributions : **Density Ratio**

●In 1D we may just use 2 histograms and create a 3<sup>rd</sup> which is their ratio



**100x less events**



- But in many dimensions this become infeasible
- Similar to having very low statistics
- Alternatively we can use Machine Learning classification tasks which are suited to such problems

## Previous Work with Density Ratios

#### $\overline{\mathbf{B}}\mathbf{T}\times\mathbf{1}\mathbf{V}$  > physics > arXiv:2207.11254

**Physics > Data Analysis, Statistics and Probability** 

[Submitted on 22 Jul 2022]

#### **Machine Learned Particle Detector Simulations**

D. Darulis, R. Tyson, D. G. Ireland, D. I. Glazier, B. McKinnon, P. Pauli

#### https://arxiv.org/abs/2207.11254



Excellent tool for mapping acceptance probabilities in multi-dimensions i.e. probability a particle is detected at particular point



Figure 11: Results of applying a neural network with a Gaussian transform for acceptance modelling with a BDT correction. The BDT used 100 weak learners with a maximum depth of 10 and a learning rate of 0.1. The network used is the higher capacity model with 4 hidden layers of 512, 256, 128, and 16 neurons respectively. The improvement in the 3-vector component distributions is smaller than in the case of the low capacity network.

●Optimised algorithm using combination of Neural Networks and BDT for multi-dimensional correlations and accuracy

# Full Reaction Simulations

#### Momentum resolutions / correlations Toy Simulation



Figure 3: Some of the multidimensional correlations in the toy detector reconstruction. It is important that the machine learned simulation can reproduce these features.

#### Momentum resolutions / correlations ML Simulation



#### • Resolutions mapped with Decision Tree inference

#### Kinematic distributions : invariant masses decay angles



Figure 26: Accepted and reconstructed physics variables for the Fast (blue) and Toy (red) simulations of the 2 pion photoproduction reaction. The distributions show: the invariant mass of the three final state particles, W; the invariant mass of the two pions,  $M(2\pi)$ ; the production angles in the centre-of-mass system  $(\cos(\theta_{CM}))$ ,  $\phi_{CM}$ ); and the decay angles of the two pions.

# Machine Learning With Experimental Data

- Often train ML with simulated data requires excellent agreement between simulation and experimental data.
- Instead we can train ML with experimental data – this relies on being able to separate contributions from different event sources in the data.
- In the example plot, we would need to separate the background and neutron signal to use the neutron data in training.



#### sPlot and sWeights

- The sPlot formalism aims to unfold the contributions of different event sources to the experimental data.
- sPlot generalises side-band subtraction weights to where there is no clear isolated background to subtract from the total event sample.
- The data is assumed to have:
	- discriminating variables where distribution of event sources are known
	- control variables where distributions of event sources are unknown.
- Fit expected pdf to discriminating variables to obtain sWeights that allow to reconstruct distribution of control variables.
- Requires that the discriminatory variable and control variables are independent of each other.





# Negative sWeights

 Essential characteristic of sWeights is that they can be negative.

 Necessary to preserves the statistical properties of the dataset eg correct uncertainties and normalisation.

 Creates issues for ML training : -ve weights in general allow loss to become arbitrarily negative

 Circumvent this issue starting with sample weighted binary cross entropy loss

$$
L(f(x_i)) = -\sum_i w_i(y_i \log f(x_i) - (1 - y_i) \log (1 - f(x_i)))
$$

 And convert sWeights to positive definite probabilities through density ratio classification task.



## Density Ratio Weights (drWeights)

- For this we can use density ratio estimation:
	- Summing the sWeights for a given species recovers the yield of that species.
	- $\blacktriangleright$  Define weights for a given species equivalent to the ratio of its probability density over the sum of probability densities of all species in the data ie

$$
W_{dr}(x_i) = \frac{D_S(x_i)}{D_S(x_i) + D_B(x_i)} = \frac{D_S(x_i)}{D_{all}(x_i)}
$$

- To convert the signal weights we create a training sample with "all events weighted by signal sWeights" as class 1 and "all events weighted by 1" as class 0.
- Avoids the issues due to negative weights as all events in class 0 are contained in class 1 Requires :  $\sum w_i < N$  (number of events). True by definition of signal sWeights
- ML classifier with this training sample will have output for signal *f(xi)* : Then transform to probability  $W_{dr}$

$$
f(x_i) = \frac{D_S(x_i)}{D_S(x_i) + D_{all}(x_i)}
$$

$$
\Rightarrow W_{dr}(x_i) = \frac{f(x_i)}{1 - f(x_i)}.
$$

See also Nachman/ThalerNeural : resampler for monte carlo reweighting with preserved uncertainties. Phys. Rev. D, 102:076004, Oct 2020

# Density Ratio Weights (drWeights)



 sPlot requires that the discriminatory variable and control variables are independent of each other.

⇒ conversion should only be made with the control variables

- sPlot unfolds the control variable distributions
- ⇒ conversion works only at the distribution level and not on an event by event basis.
- sWeighted uncertainty is calculated by taking the sum of the squared sWeights.
- $\Rightarrow$  This doesn't work with converted weights W<sub>dr</sub>. But we can just propagate sWeight sum of squared weights
- We can apply the method twice, ie correct the drWeights for better results.



#### Toy Example

- Create toy event generator to produce three dimensional events:
	- mass such as an invariant mass as discriminatory variable
	- azimuthal (ϕ) angular distribution
	- $z = cos \theta$ .
- Signal events were generated with a Gaussian distribution in mass and a cos 2ϕ distribution of amplitude 0.8.
- Background events were generated with a Chebyshev polynomial distribution in mass and a cos 2ϕ distribution of amplitude -0.2.
- The aim is to measure the signal asymmetry in  $\phi$  by unfolding the signal distribution in the control variable ϕ .



 $cos(2<sub>\Phi</sub>)$ 





Apply two consecutive Gradient Boosted Decision Trees to convert sWeights.

- $\rightarrow$  Second acts as reweighter fine-tuning results
- $\rightarrow$  Measurably improves results
- Several other learning models tested, generally good performance.

#### Training rate ~2 kHz, prediction rate ~500 kHz on 5 cores of a AMD EPYC 9554 64-Core Processor at 3.1GHz.



# Quantifying how well it works

Want to reproduce signal ϕ asymmetry amplitude of 0.8.

- Repeat training the density ratio model and fitting  $\phi$ asymmetry for 50 independent toy datasets of 100k events
- Use Signal to Background ratio of (1:2) or (1:9).
- Obtain mean amplitude and uncertainty along with the standard deviation of the amplitude over the 50 datasets
- Fit performed via binned χ2
- The expectations are:
	- mean should be consistent with the nominal value of 0.8
	- mean uncertainty and standard deviation should be numerically similar i.e. the fluctuation of results is consistent with the calculated uncertainty
	- i.e. **σ / Uncertainty** ~ 1.0



#### Number of Events

 $\blacktriangleright$  Same test as before, vary number of events.

Use signal to background ratio of (1:9).

- At 1000 events we have only 100 signal events.
- drWeights are robust and function well with large backgrounds and limited statistics.
- $\blacktriangleright$  Issues with sWeights at low event number due to -ve bin contents in binned χ2
- Expected behaviour when use event based maximum likelihood instead



# Testing with real data

 $ep \rightarrow e^{\prime} \pi^{+}(n)$ 

- Apply this technique to CLAS12 neutron detection.
- Fit neutron missing mass using simulated template.
- Produce drWeights over the reconstructed neutron spherical momentum components.
- Show results for neutron momentum using sWeights and drWeights



# Example Application

We can estimate the neutron detection efficiency by comparing the reconstructed to detected neutron.

 We can also use density ratios to obtain a multidimensional model of the neutron detection efficiency (see Slide 3,14 & [arxiv:2207.11254\)](https://arxiv.org/abs/2207.11254).

 Neutron detection is hard to simulate as it relies on detecting the various reaction products produced in scattering between the neutron and calorimeter material.

 To obtain an accurate multidimensional model of neutron detection efficiency we should use experimental data, this relies on being able to convert sWeights to probabilities.



- Use exclusive reactions to train acceptance algorithm e.g.  $y + p \to \pi^+ + \pi^- + p'$
- Filter all events with  $\pi+\pi$  and calculate missing proton momentum  $\mathbf{p'}_\text{calc}$
- If proton also detected flag (acceptance=1), if not (acceptance=0)
- Train classifier with  $\mathbf{p}_{\text{calc}}$  components on acceptance=0 and 1 events
	- Equivalent to Slide 16 analysis
	- => proton acceptance as function of **calculated** variables.
	- Equivalent to fast sim parameterisation Slide 3
- Issues : We want as a function of **truth** variables There will be background under the mass peak so need drWeights

 It can be preferable to use experimental data instead of simulated data to train ML algorithms.

- This relies on being able to separate different event species in the data.
- sWeights are a convenient tool to do so, however they can be negative.
- Density ratios can accurately convert sWeights to positive definite probabilities.
- drWeights are robust and function well with large backgrounds and limited statistics.
- drWeights can then allow to create good training datasets from experimental data.
- Note: sWeights still provide a more reliable method, the goal not to replace them but only convert them in cases such as machine learning training where positive definite probabilities are required.



# Background



