

Fitting and Propagation in ACTS

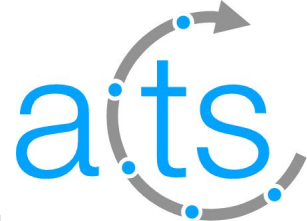
For ePIC Collaboration Meeting

Focus of this talk

1. How ACTS CKF fitting and propagation work
2. CKF fitting directions (e.g. inside-out, outside-in, combo of both)
3. How trajectory propagation handles magnetic field and material crossed
4. How the covariance matrix is determined

* Focusing on the current version of ACTS (v38.2.0), details might change with future versions

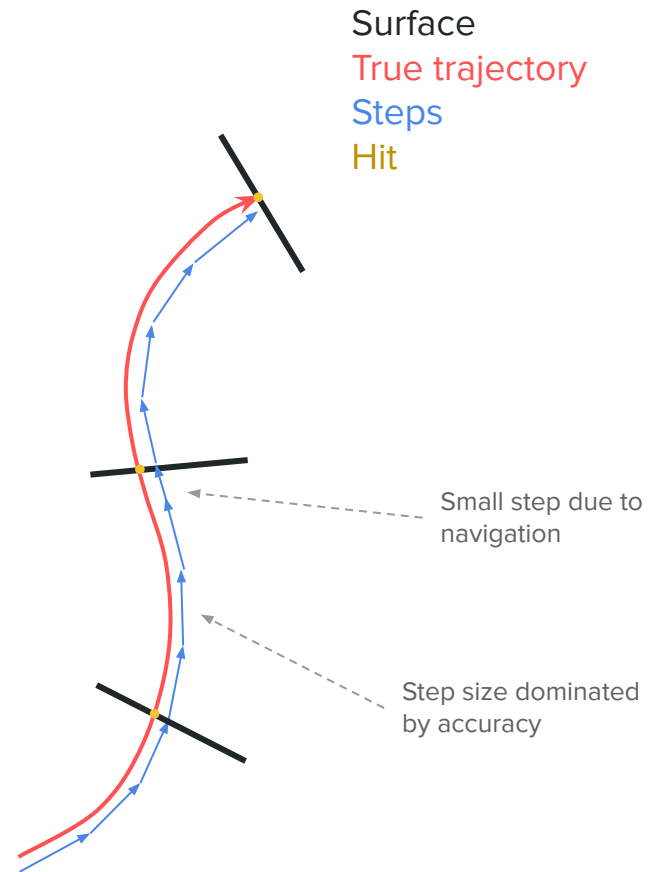
Quick reminder about ACTS



- Experiment independent toolkit for track reconstruction in modern C++
- Not a reconstruction framework but provides an Example one
- Example framework can be used for early studies but has limitations
- Is a community project and we invite everyone to contribute with code and discussions

Propagation

- Extrapolates given track parameters and optionally their covariance
- Is a composition of stepping and navigation
- Stepping extrapolates the parameters and optionally accumulates the transport Jacobians
- On request the stepper will use the full transport Jacobian to compute the current bound covariance
- Navigation determines the next surface to target and therefore effectively dictates the next step size
- Does **not** deal with material effects by itself



Propagation in a magnetic field

- Is handled by the stepping as it influences the numerical integration
- In case of the `EigenStepper` / `SympyStepper` we use RK4 integration
- RK4 requires 3 field queries per step
- ACTS does not deal with magnetic field uncertainties

Propagation Actors

- Actors can observe and steer the propagation
- Basically a function which is called after each step during propagation
- Can access navigation and stepping state and trigger the covariance transport
- This is used for our filters like KF, CKF
- Material effects are handled inside actors after reaching a surface
- For extrapolation you can use the [MaterialInteractor](#) actor
 - Example in [TrackFindingAlgorithm](#)

Covariance transport

- Is part of the propagation and automatically switched on if the input parameters carry an uncertainty
- Under the hood this is really just applying the accumulated transport Jacobian to a given starting covariance
- Material effects are **not** part of the covariance transport

Ad 3: How trajectory propagation handles magnetic field, materials crossed

- The magnetic field is directly consumed and used by the stepping
- Thereby it immediately affects the propagation

- ACTS represents material on surfaces
- If surfaces are encountered during propagation depends on the navigation
- The actor in charge of material interaction observes that we are on a material surface and acts on it

Ad 4: How is the covariance matrix determined

- The covariance matrix at any trajectory state is determined by
 - The initial covariance which is provided by the user
 - The transport Jacobian which is calculated by the stepping
 - Additional terms which are added by actors
- Intermediate covariances have to be requested by actors, otherwise you will only get a covariance at the propagation target
- Fitters have their own material interactor to avoid conflicts with other actors
- For extrapolation a material interactor has to be added to the propagation

Fitting algorithms

- Fitters are implemented as *Actors* in ACTS
- They observe and change the state of the propagation
- This aligns very well with iterative fitters like the Kalman Filter
- The KF really only relies on the current state of the propagation (predicted) and updates it given a measurement to derive a “better”, updated state (filtered)
- This only feeds information in the direction of the propagation and can be reversed afterwards to obtain optimal estimates for all track state (smoothed)

Ad 1: How ACTS CKF fitting and propagation work

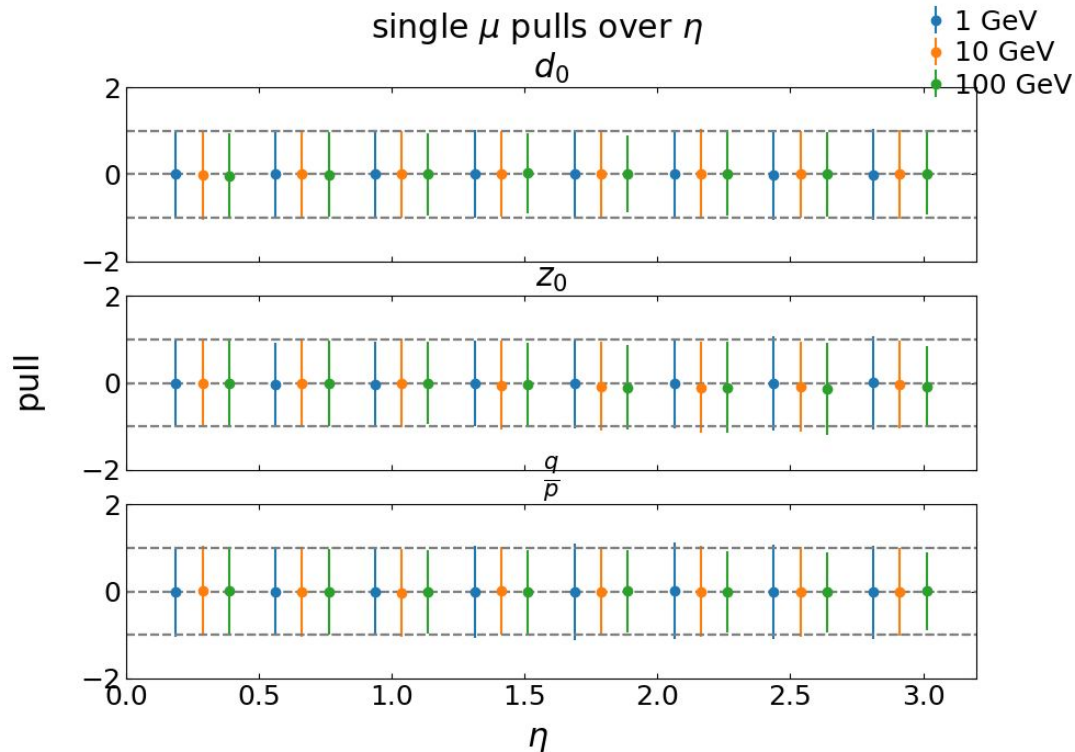
- CKF fitting is using the Kalman formalism to update predicted states using encountered measurements to derive filtered states
- This is done within the propagation using the actor mechanism
- Material effects are handled inside the fitting actor

- Propagation is composition of navigation and stepping
- The navigation selects the next surface we should encounter during the propagation
- The stepping advances the track parameters towards the next surface

Acts+ODD Performance



- Validates correct handling of uncertainties in reconstruction
- Good control of material effects and cluster uncertainties

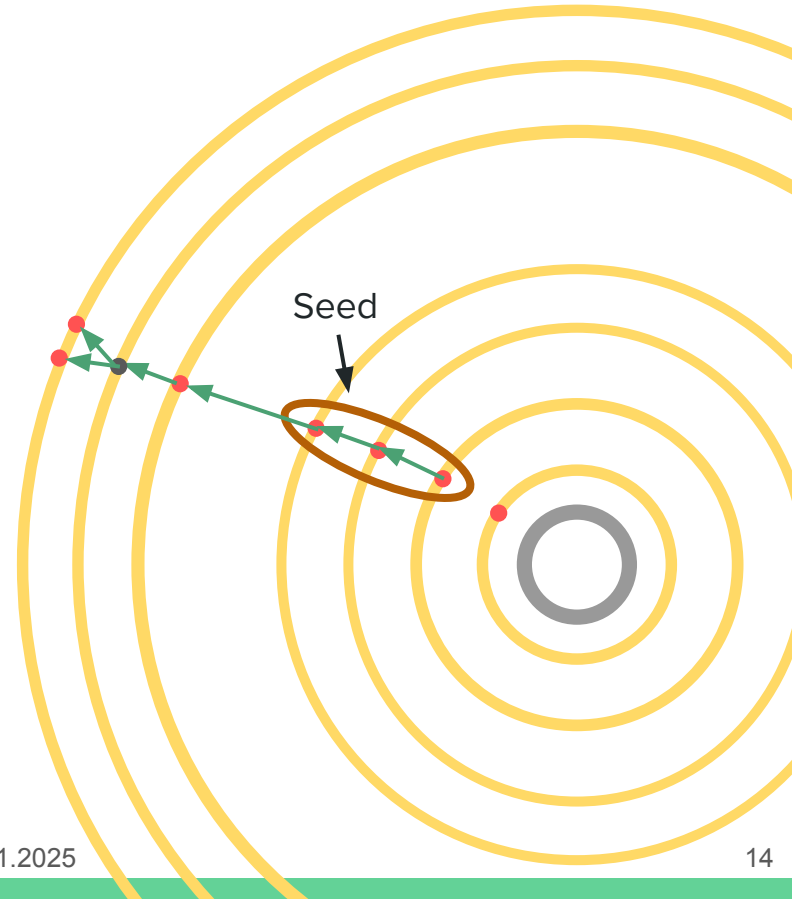
<https://indico.cern.ch/event/1252748/contributions/5521502>






Track finding direction

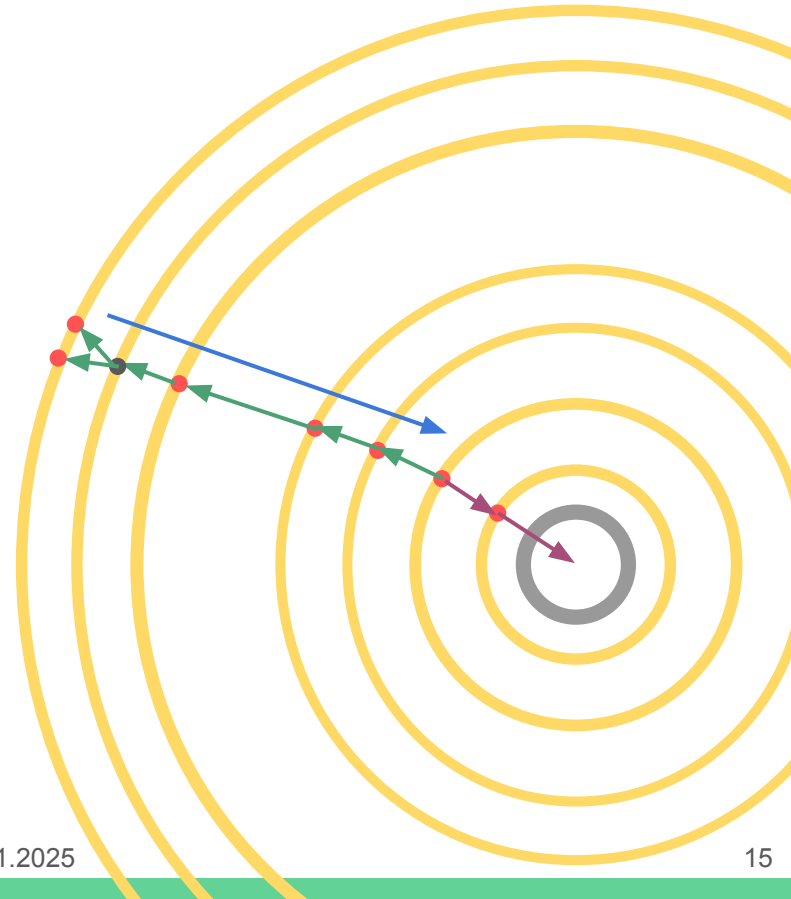
Track finding direction

1. Track finding starts with estimated track parameters at the innermost cluster (in case of pixel seed) 
2. Extrapolate, select measurements, branch, repeat 



Track finding direction

3. Get tracks from this outwards pass, smooth them 
4. Start inwards pass with smoothed params at innermost measurement state 
5. Terminate at perigee surface, extract parameters 
6. Reverse the inner tracklet, stitch them together
7. Output tracks



Track finding direction

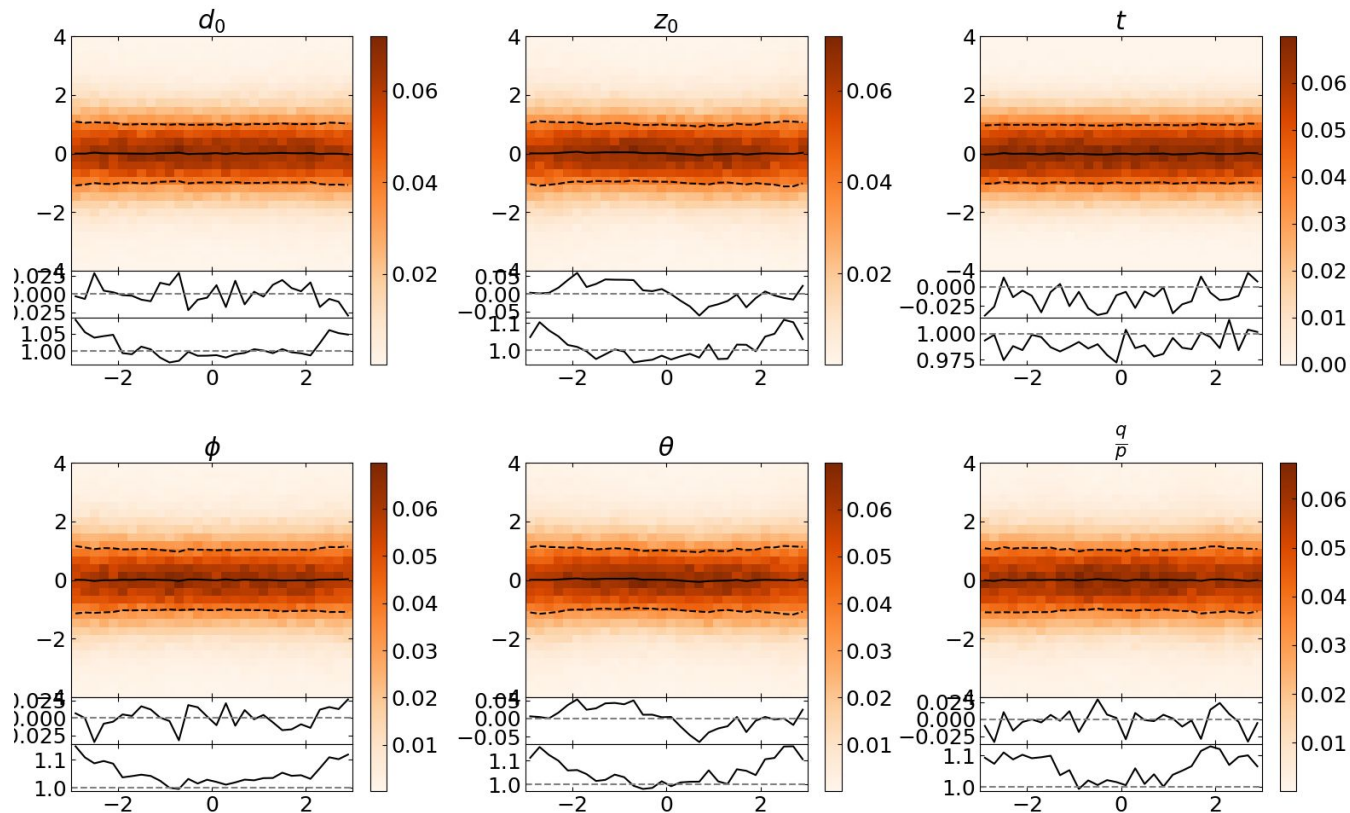
- To obtain all measurements on track we need to look outwards and inwards from the seed if we do not start from the first layer
- This can be achieved with the ACTS CKF by running first in one direction and then in the other direction
- Note that only the innermost track state and the extrapolated track state will have optimal resolution due to combining all measurements
- To obtain optimal resolution on all track states a refit or second smoothing pass is required

Ad 2: CKF fitting directions (e.g. inside-out, outside-in, combo of both)

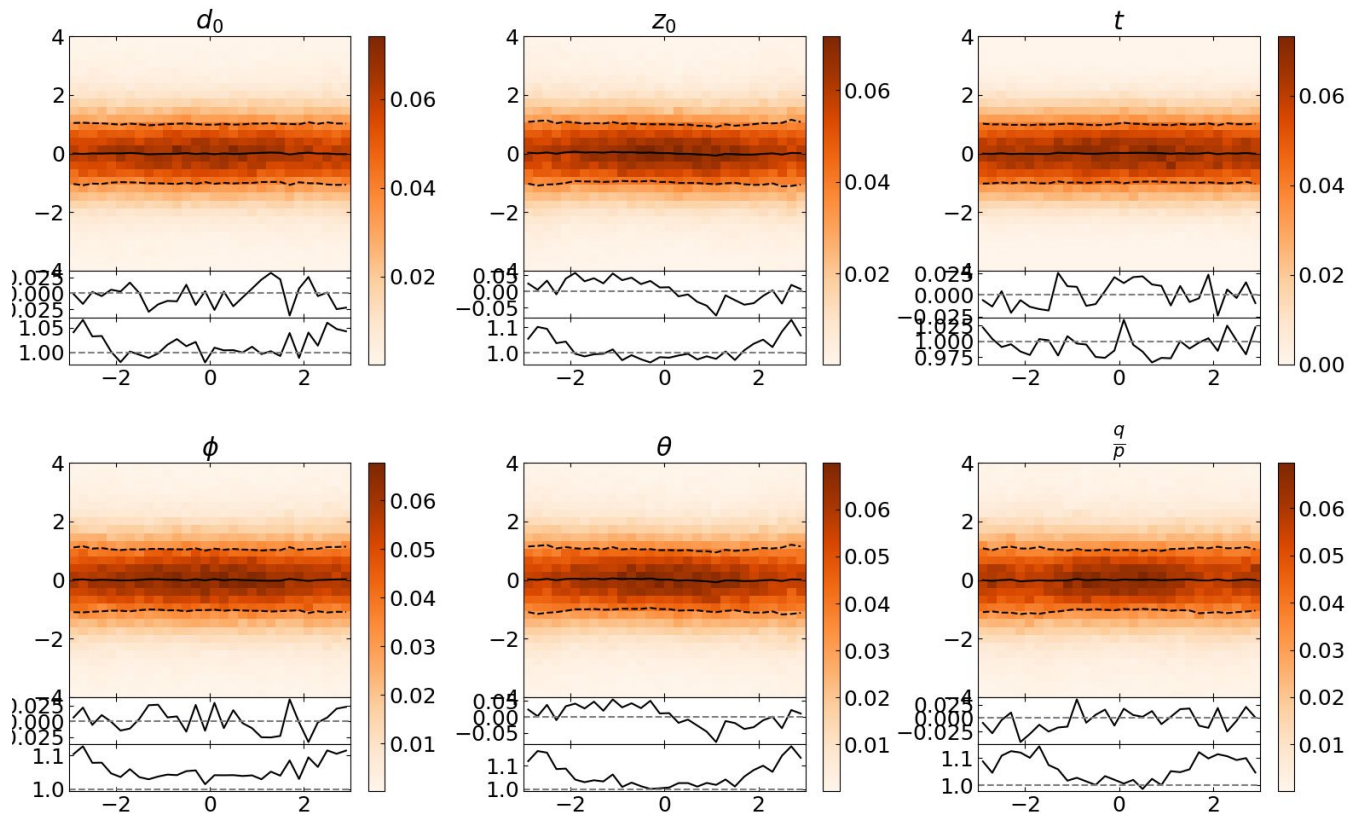
- This is important to find all measurements, primarily if we do not start the finding from the first layer
- To obtain optimal resolution on all track states a refit or second smoothing pass is necessary
- The CKF should always be guided towards the direction of more measurements first as the resolution will be better before reversing the direction
- The direction should only impact the finding performance and not the fitting performance as after smoothing all states should have optimal resolution

Backup

Single muon pulls 1 GeV pT



Single pion pulls 1 GeV pT



Single electron pulls 1 GeV pT

