SAND Software and Analysis

Matteo Tenti, INFN - Bologna SAND Review CSN1 12/07/2024 Frascati



Introduction



Meetings

- The Physics/Software WG (16 people) has regular weekly meetings: Wednesday at 15:00 CEST (08:00 CT)
- A shared google docs is used to take notes
- Meetings are recorded
- A list of action items is produced and checked during the meeting
- Two mailing lists:
 - <u>DUNE-ND-SAND-PHYSICS@FNAL.GOV</u>
 - DUNE-ND-SAND-SOFTWARE@FNAL.GOV



Repositories

- <u>github.com/DUNE/dunendggd</u>: geometry repository
- github.com/DUNE/sandreco

detector simulation, reconstruction and analysis tools

- <u>github.com/DUNE/ND_Production</u>
 ND «official production» for simulation
- <u>github.com/DUNE/ND_CAFMaker</u> CAF maker: event summary data

Coding and Development Workflow

- Language: C++11
- Code Format:
 - Based on <u>Google C++ Style Guide</u>
 - **Proposal:** *clang-format -style="{BasedOnStyle: Google, BreakBeforeBraces: Linux, DerivePointerAlignment: false}"*

Agile

Deploy

Design

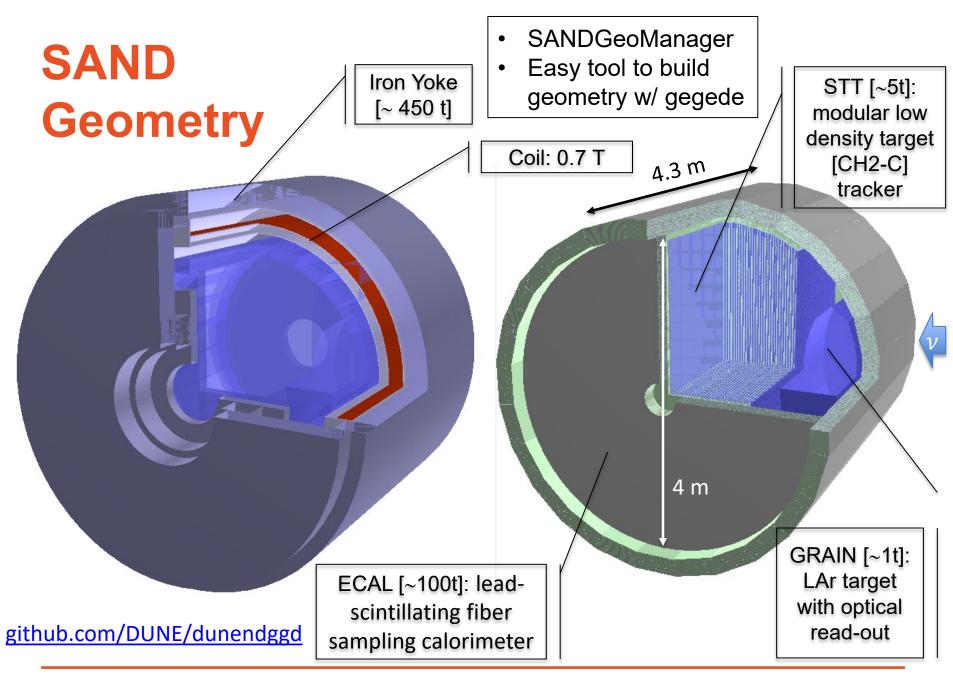
- Project layout: <u>pitchfork</u>
- Development Workflow:
 - 1. Create Issue
 - 2. Open Branch
 - 3. Develop
 - 4. Test / Review
 - 5. Merge Request
 - 6. Release

Exploits: Agile/DevOps, Merging by Pull Request Peer Code Review, Automated Tests,



SAND Geometry



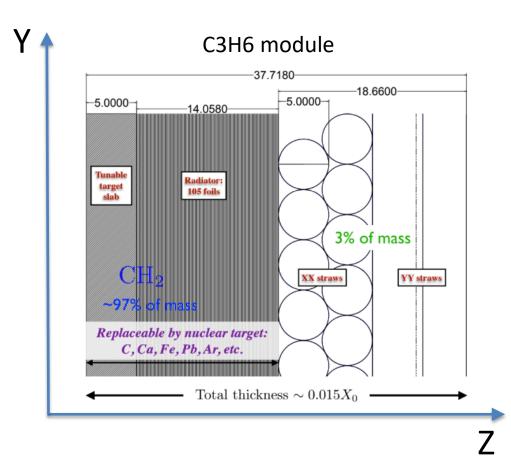


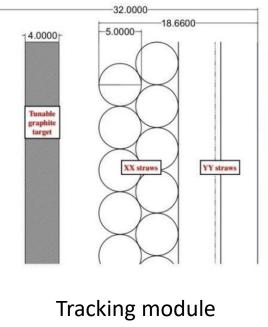


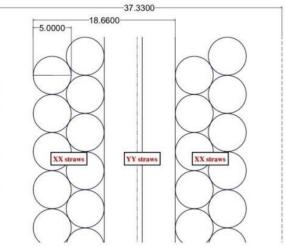


C (graphite) module

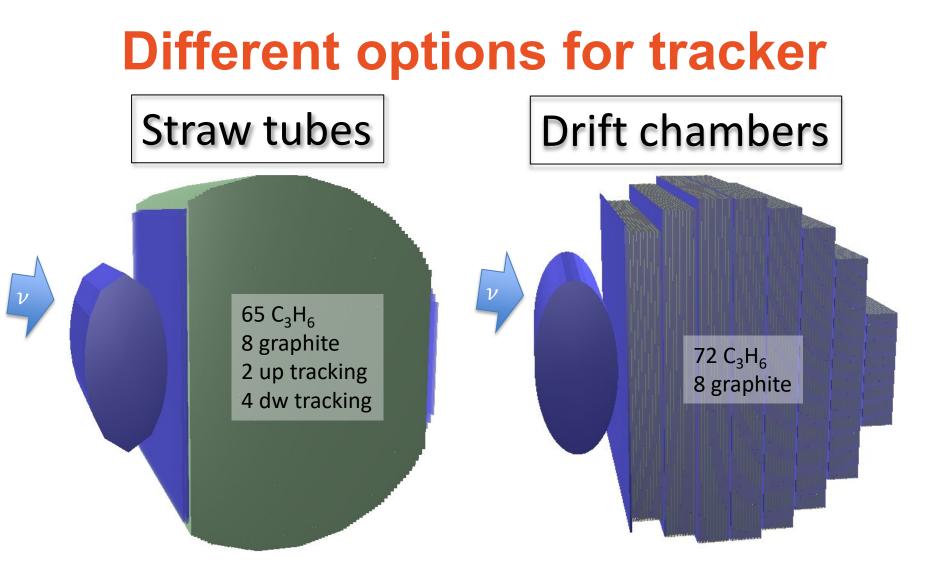
Tracker Modules







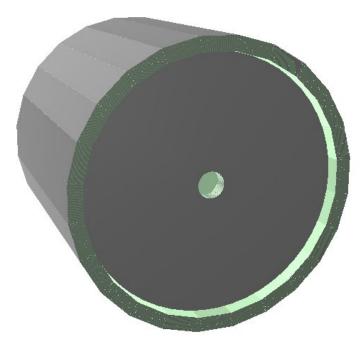




Geometries with several tracker configuration: clearance, straw radius, GRAIN size, TR removal

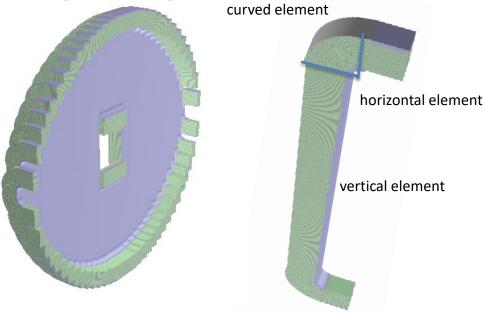


ECAL Geometry



Improved endcap geometry

[P. Gauzzi]



Barrel: 24 modules

2 x Endcaps: 32 modules

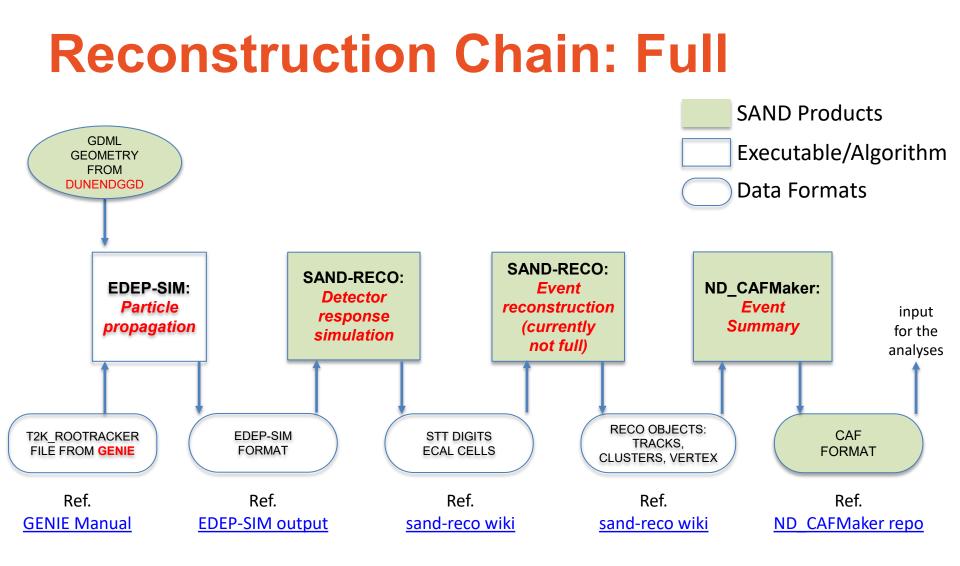
Module:

209 0.4-mm lead slabs + 209 0.7-mm scint. slabs A team (P. Gauzzi, A. Ruggeri, D. Casazza, M. Tenti) is working to finalize the digitization for the new endcap geometry



SAND Simulation & Reconstruction







Detector Simulation

- ECAL [sand-reco]:
 - Light yield, scintillation decay time, attenuation, photon propagation, segmentation, PMT response and front-end [ADC & TDC].
- STRAW/DRIFT[sand-reco]:
 - drift towards wire, electric signal propagation and front-end [ADC & TDC]

Charged Particle **STRAW TUBE** GRAIN -Illimm

ECAL MODULE

- GRAIN:
 - LAr : Rayleigh scattering, absorption
 SiPM : PDE, cross-talk, after-pulse
 front-end : waveform with electronic noise

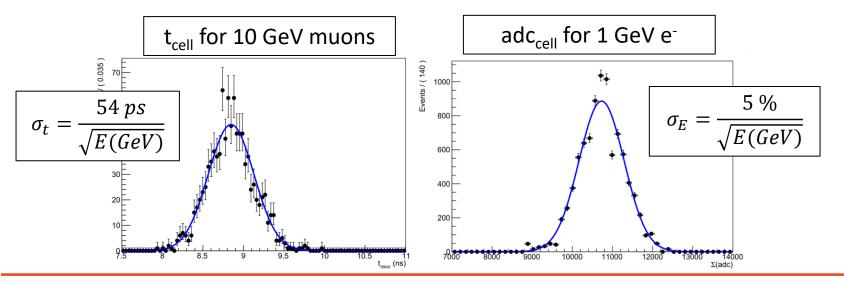


Reconstruction

• ECAL:

[D. Casazza, R. D'Amico, P. Gauzzi]

- CELL: Energy, position and time of energy deposits in ECAL are reconstructed using signals of PMTs on both ends.
- PATTERN RECOGNITION: CELLS are grouped in CLUSTERS using MC truth.
- FIT: Energy, position, time and direction of the track/shower are then reconstructed using energy deposit topologie

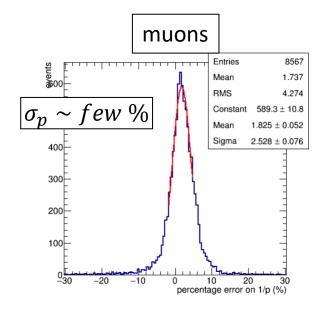


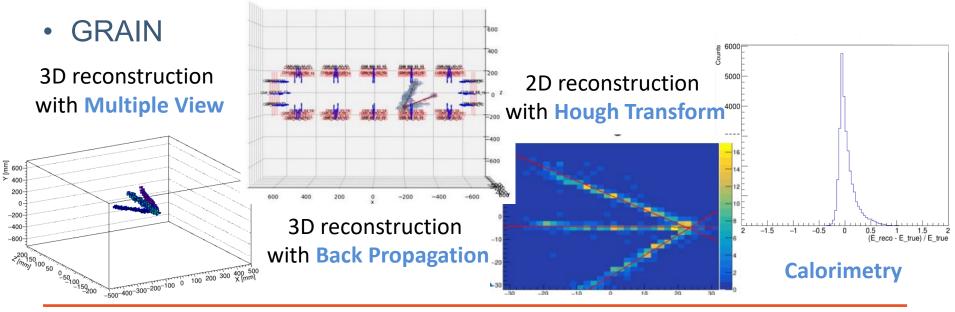


Reconstruction

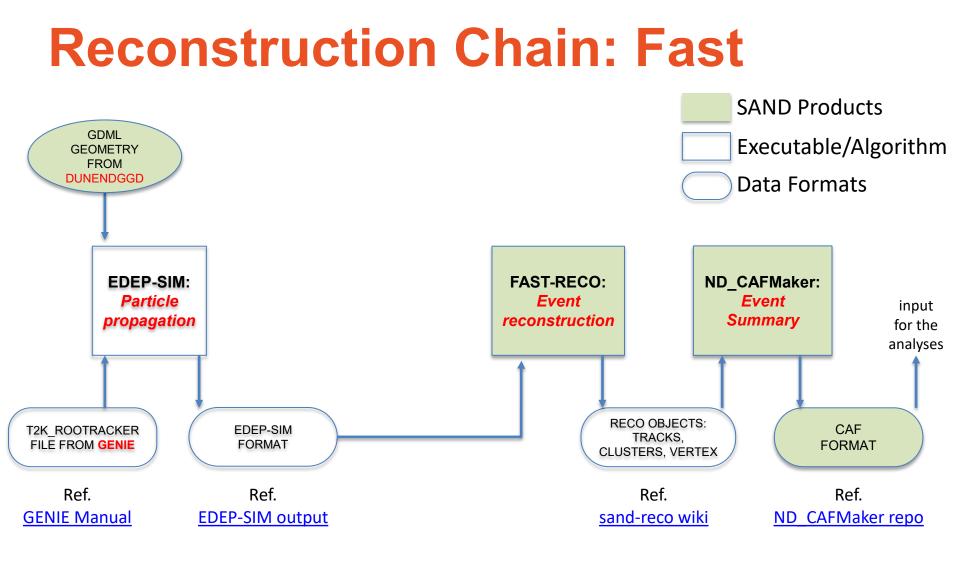
• STT

- PATTERN RECOGNITION: TUBES are grouped in TRACKS using MC truth.
- FIT: hits from vertical and horizontal tubes are fitted separately to obtain position direction and momentum of the TRACK







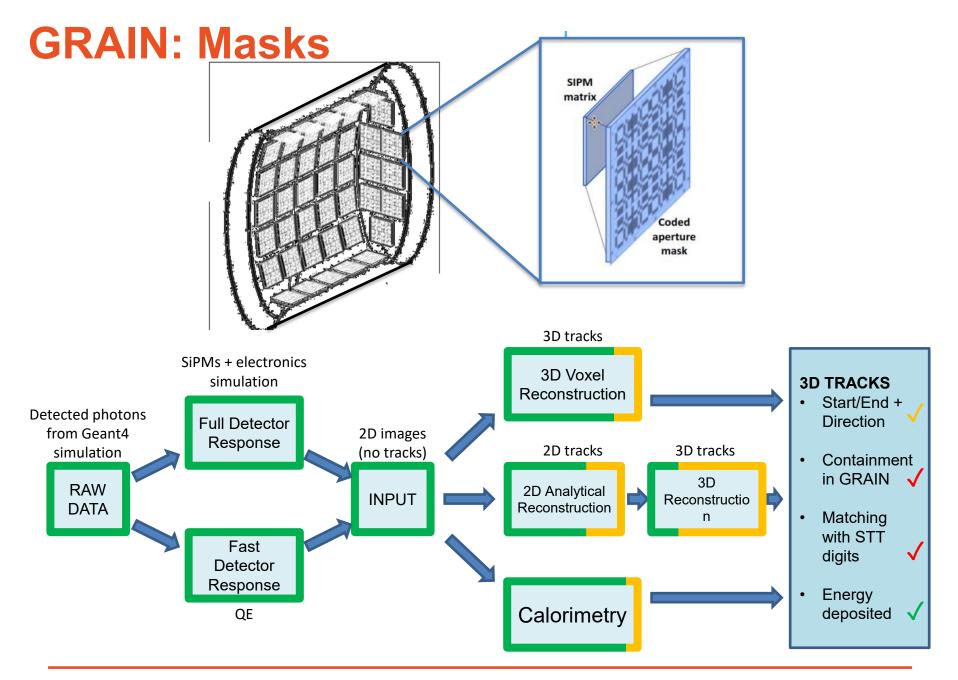




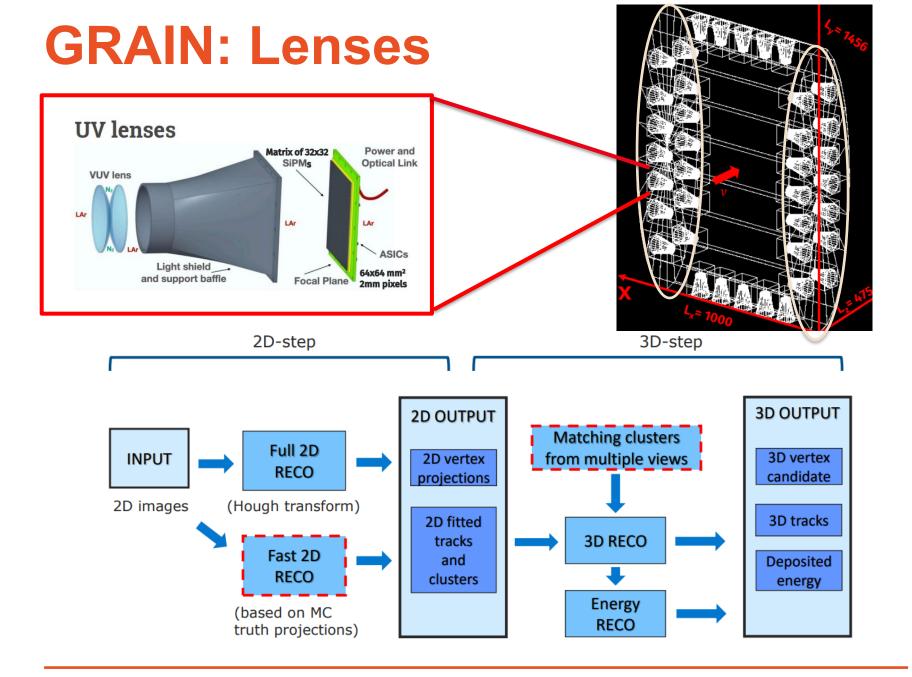
Fast Reconstruction

- A (simplified) fast reconstruction has been developped to quickly obtain reliable results
- Basic ingredients:
 - Detection thresholds:
 - 250 eV for straw
 - 100 keV of deposited energy in fibers (equivalent to ~ 1 MeV in cell)
 - Tracks:
 - Reconstruction threshold N(digitis) > 4
 - Pattern recognition and PID from MC truth
 - Reconstructed momentum using Gluckstern formula
 - Gammas' energy: $(5.6\%)/\sqrt{(E/GeV)}$ on visible energy in ECAL
 - Neutrons' energy: TOF

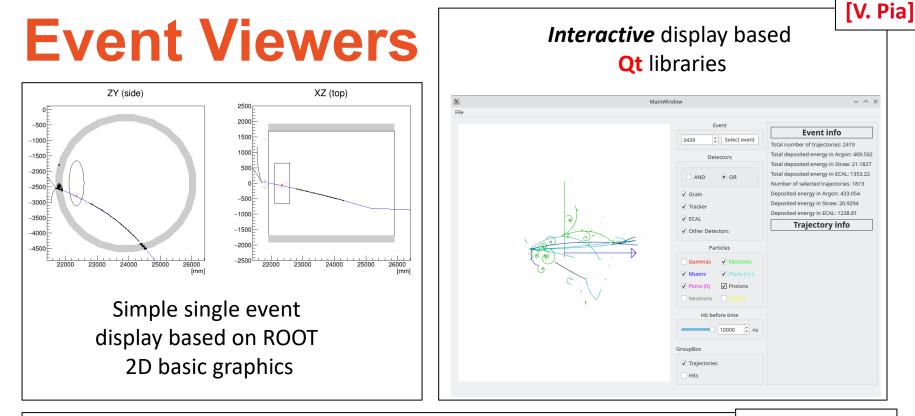


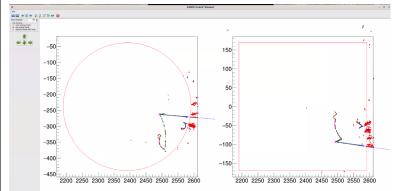












Interactive display based on ROOT Graphical User Interface

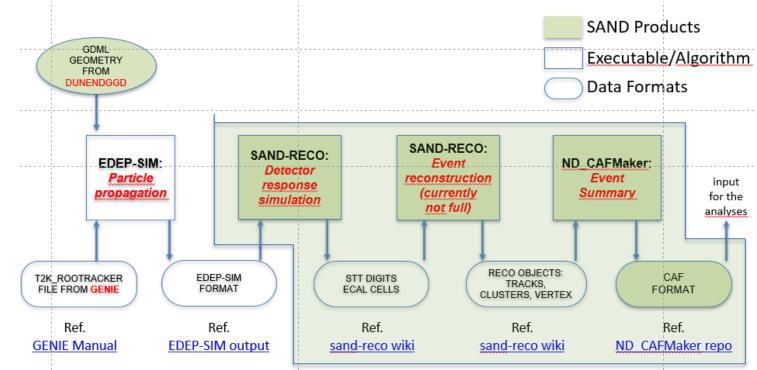


[A. Chukanov]

Integration in DUNE



Interfaces with DUNE



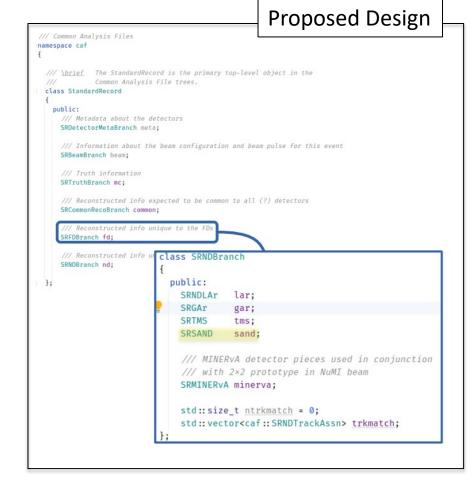
The green area is responsability of the SAND Physics/Software WG

- sandreco: continuous integration, testing, versioning and release
- Integration into ND simulation and reconstruction chain
- Development of an event summary data: CAF



CAF Updates Highlights

- Common Analysis Files are the input for high-level analysis (used for TDR LBL analysis and by CAFAna, Mach3, etc...)
- Event Summary format is
 StandardRecord object
- It contains SAND-related objects and info



Currently, we have a skeleton with minimal event info



We are involved in developing a complete CAF for SAND



Integration in DUNE

- ND Sim/Reco group requests for an **integration** of the SAND simulation and reconstruction tools into the production chain
- A first integration of the SAND has been **completed**
- This includes *Fast-Reco* and *sand-reco* but not GRAIN reconstruction
- However, FNAL computing service has recently upgraded machines from SL7 to AL9
- In parallel, they decide to change the package manager from UPS (custom product) to Spack
- We are working to integrate *sandreco* in the new framework

24

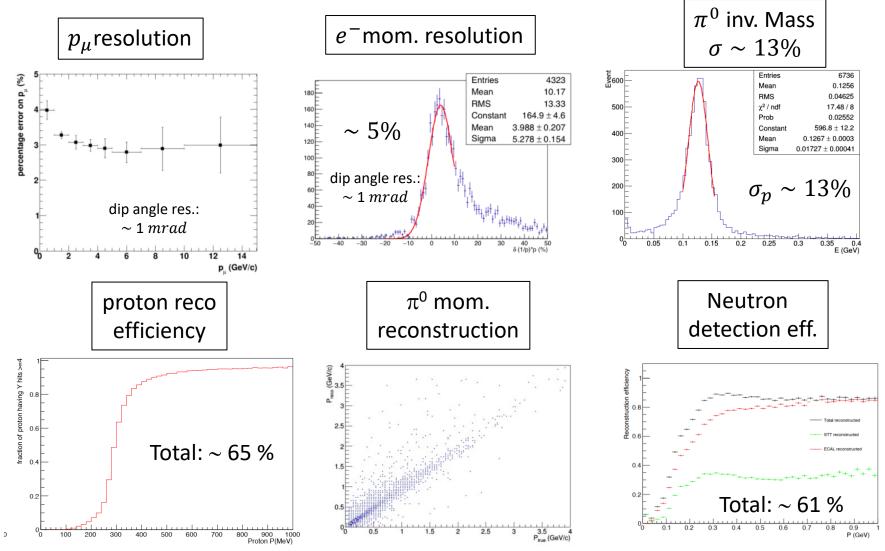


[M. Tenti]

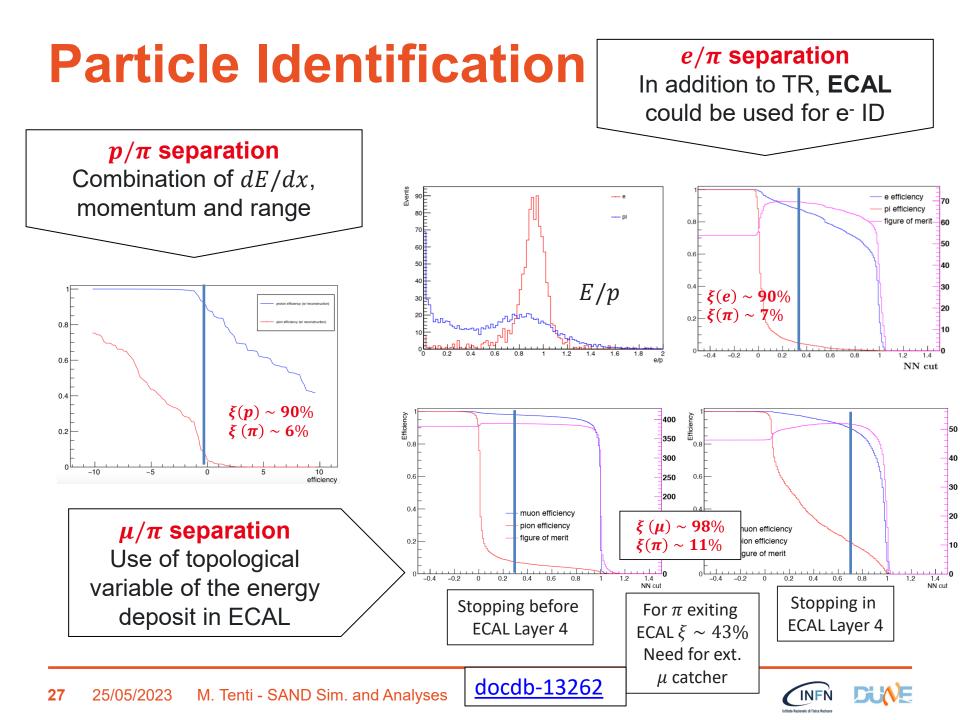


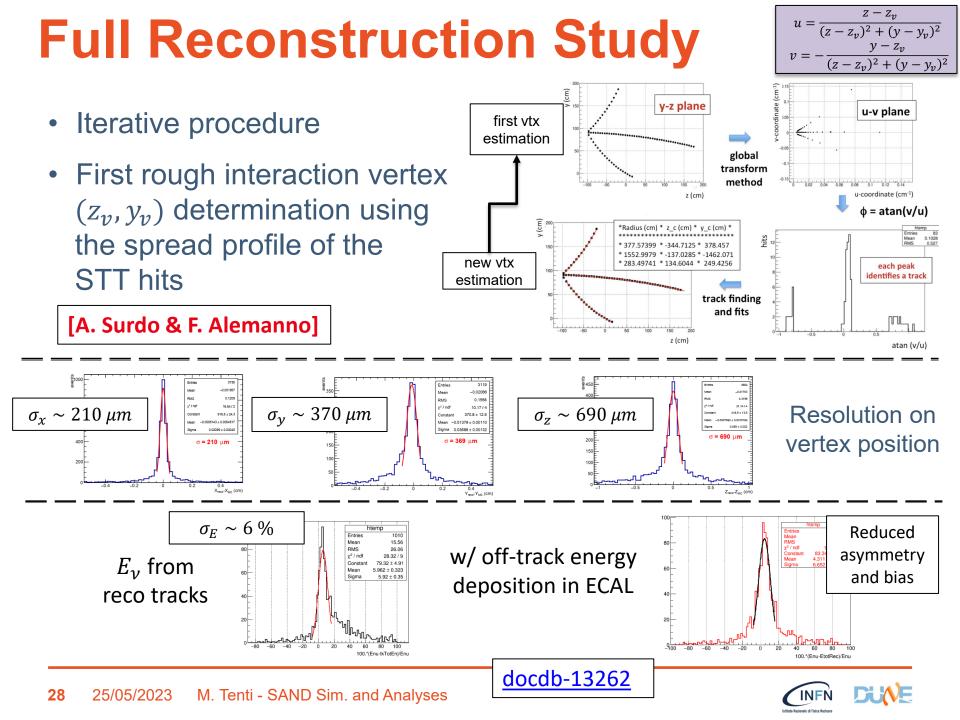


Particle Reconstruction

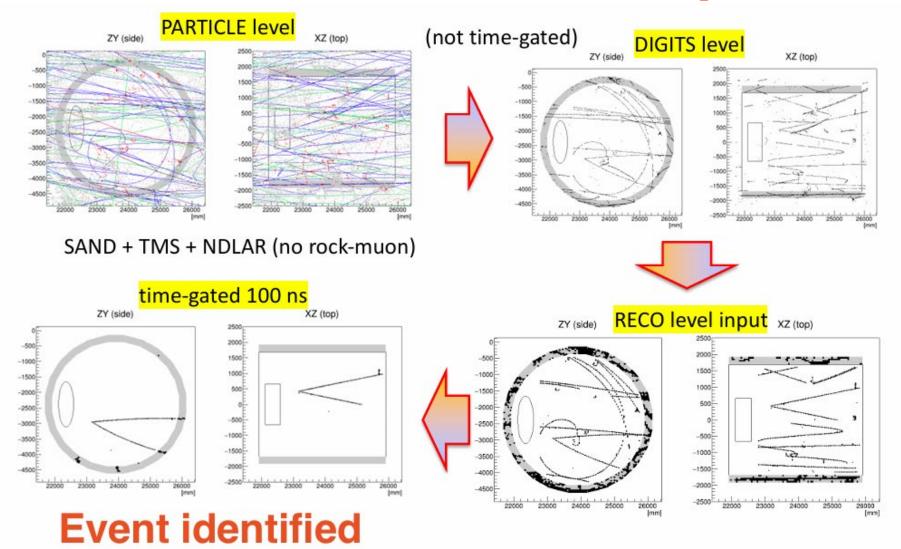








Events in an entire spill





Event Classification

 Primary lepton identification using ANN with kinematical variables

$\begin{array}{c} FHC \ \nu_{\mu} \ CC \\ RHC \ \bar{\nu}_{\mu} \ CC \end{array}$	$99.1 \ \% \\ 99.3 \ \%$
FHC ν_e CC	98.0~%
RHC $\bar{\nu}_e$ CC	98.6~%

- Additional $v_{\mu}(\bar{v}_{\mu})$ selections based on:
 - μ catcher and μ/π separation w/ ECAL
 - Likelihood ratio based on kinematics (NC rejection)
- Additional $v_e(\bar{v}_e)$ selections based on:
 - Invariant mass and e/π separation
 - Transition Radiation

		Purity		Wrong sign	
Cuts	Efficiency	$(\nu_{\mu} + \bar{\nu}_{\mu} + \nu_e +$	$\bar{\nu}_e$) CC + NC	contamination	
FHC ν_{μ} CC selection:					
Kinematic tagging of μ^-	99.1~%	93.2	%	1.4~%	
ECAL on tagged μ^-	98.4~%	97.5	%	0.5~%	
RHC $\bar{\nu}_{\mu}$ CC selection:					
Kinematic tagging of μ^+	99.3~%	76.2	%	11.1 %	
ECAL on tagged μ^+	98.8~%	90.0	%	$6.1 \ \%$	
Wrong sign veto on tagged μ^-	97.9~%	97.8	%	0.3~%	
RHC ν_{μ} CC selection:					
Kinematic tagging of μ^-	98.7~%	66.4	%	22.7~%	
ECAL on tagged μ^-	97.9~%	85.8	%	9.4~%	
Wrong sign veto on tagged μ^+	95.4~%	97.3	%	0.3~%	
FHC $\bar{\nu}_{\mu}$ CC selection:					
Kinematic tagging of μ^+	99.3~%	9.9	%	78.0~%	
ECAL on tagged μ^+	98.2~%	34.2	%	$55.1 \ \%$	
Wrong sign veto on tagged μ^-	97.1~%	83.2	%	2.3~%	
Kinematics	95.4~%	94.2	%	2.6~%	

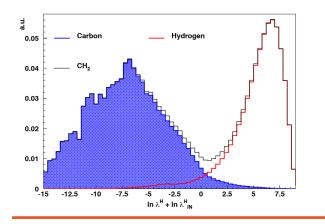
		Purity			
Cuts	Efficiency	$(\nu_{\mu} + \bar{\nu}_{\mu} + \nu_e + \bar{\nu}_e) \text{ CC} + \text{NC}$			
FHC ν_e CC selection:					
Kinematic tagging of e^-	98.0~%	1.3 %			
Muon veto on tagged e^- and e^+	96.6~%	10.6 %			
m_{+-} and ECAL on tagged e^-	91.8~%	27.3~%			
$TR + dE/dx$ on tagged e^-	82.6~%	99.4 %			
RHC $\bar{\nu}_e$ CC selection:					
Kinematic tagging of e^+	98.6~%	1.1 %			
Muon veto on tagged e^- and e^+	97.2~%	15.2 %			
m_{+-} and ECAL on tagged e^+	93.2~%	30.9~%			
$TR + dE/dx$ on tagged e^+	83.8 %	99.2 %			
RHC ν_e CC selection:					
Kinematic tagging of e^-	97.7 %	2.3 %			
Muon veto on tagged e^+ and e^+	95.6~%	11.9 %			
m_{+-} and ECAL on tagged e^-	91.1~%	29.7~%			
$TR + dE/dx$ on tagged e^-	82.0 %	99.3 %			
FHC $\bar{\nu}_e$ CC selection:					
Kinematic tagging of e^+	98.4 %	0.3 %			
Muon veto on tagged e^- and e^+	97.4~%	2.4~%			
m_{+-} and ECAL on tagged e^+	93.7~%	6.0 %			
$TR + dE/dx$ on tagged e^+	84.3~%	93.6 %			

<u>docdb-13262</u>



ν-H interaction sample

- *v*-H scattering is free from **nuclear**
- STT allows the precise determination of the interaction target material (CH₂ vs C)
- Separation of v-H from v-C in (CH₂ target) with simple kinem. and topological selections



	5y (FHC) + 5y (RHC)	Eff.	Purity	Size
	$ u_{\mu}$ CC inclusive	93%	93%	2.9M
	$ u_{\mu}p ightarrow \mu^{-}p\pi^{+}$	96%	95%	2M
r	$\nu_{\mu}p \rightarrow \mu^{-}p\pi^{+}X$	89%	93%	760k
	$\nu_{\mu}p \rightarrow \mu^{-}\pi^{+}\pi^{+}X$	75%	70%	93k
	$\bar{\nu}_{\mu}$ CC inclusive	80%	84%	1.6M
	$\bar{\nu}_{\mu}p ightarrow \mu^{+}n$	75%	80%	860k
	$\bar{\nu}_{\mu}p ightarrow \mu^{+}p\pi^{-}$	94%	95%	300k
	$\bar{\nu}_{\mu}p \rightarrow \mu^{+}n\pi^{0}$	84%	84%	210k
	$\bar{\nu}_{\mu}p \rightarrow \mu^{+}p\pi^{-}X$	85%	94%	135K
	$\bar{\nu}_{\mu}p \rightarrow \mu^{+}n\pi\pi X$	82%	84%	156k

 Improvements exploiting the correlation of kinematical variables through the ratio of multidimensional likelihoods

 Possibility to study exclusive channels
 [G. Ingratta]

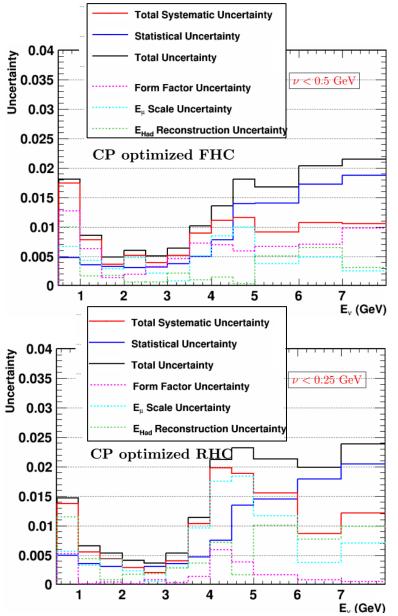


docdb-13262

docdb-13262

Flux Measurements

- SAND is well suitable to fully characterize $v(\bar{v})$ flux.
- ν_{μ} spectrum from low- ν sample [560k ev.] of $\nu_{\mu} + p \rightarrow \mu^{-} + p + \pi^{+}$
- $\bar{\nu}_{\mu}$ spectrum from low- ν sample [610k ev.] of $\bar{\nu}_{\mu} + p \rightarrow \mu^{+} + n$
- v_{μ}/v_e and \bar{v}_{μ}/\bar{v}_e from reco v_{μ}/v_e CC scattering on H
- Absolute v_{μ} flux from ve scattering [~1k ev./y]
- Additionally, $\bar{\nu}_{\mu}$ flux from $\bar{\nu}_{\mu} + p \rightarrow \mu^{+} + n$ with $Q^{2} < 0.05 \ GeV^{2}$ [27k ev./y]





Beam Monitoring

		ECAL			
Beam parameter	Variation	$\Delta \chi^2(E_{\nu})$		$\Delta \chi^2(E_\mu)$	
		true	rec	true	rec
Horn current	+3 kA	107.6	76.1	26.0	25.4
Water layer thickness	+0.5 mm	21.2	16.2	8.7	8.5
Decay pipe radius	$+0.1 {\rm m}$	42.0	34.3	12.0	11.9
Proton target density	+2%	18.0	14.3	8.9	8.7
Proton beam radius	+0.1 mm	34.9	27.6	18.2	17.8
Proton beam offset X	+0.45 mm	24.6	16.9	9.0	8.7
Proton beam θ, ϕ	0.07 mrad $\theta,1.57~\phi$	0.5	0.1	0.1	0.1
Proton beam θ	0.070 mrad	0.7	0.2	0.1	0.1
Horn 1 X shift	+0.5 mm	16.2	10.7	4.3	4.1
Horn 1 Y shift	+0.5 mm	20.6	13.6	5.7	5.5
Horn 2 X shift	+0.5 mm	0.4	0.2	0.1	0.1
Horn 2 Y shift	+0.5 mm	0.4	0.1	0.0	0.0

Continuous beam monitoring on a weekly basis $(3.78 \times 10^{19} pot)$ is crucial

A sample of ~**780k** v_{μ} CC events in the upstream barrel ECAL

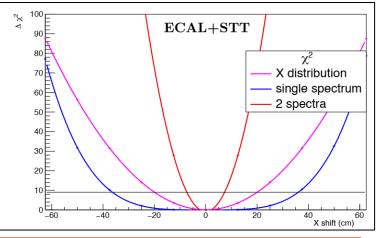
Sensitivity on a list of possible variations obtained comparing expected spectra with:

$$\Delta \chi^2 = \sum_{i=1}^{N} \frac{(N_i^{\text{nom}} - N_i^{\text{var}})^2}{N_i^{\text{nom}}}$$

Beam direction monitoring: SAND can detect shifts down to 8.4 cm with a significance $\Delta \chi^2 \ge 9$

docdb-13262

[F. Barillari]





External Background

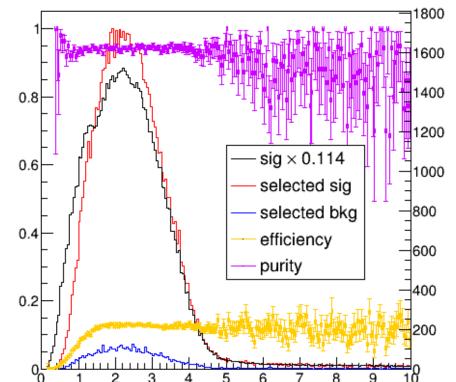
- Backgrounds sources: CR, natural radioactivity and products of external beam-neutrino interactions.
 [first two bkg. suppressed to negligible level requiring beam spill coincidence].
- Several case studies for the 3rd source:
 - **Neutron Background in** $\bar{\nu}_{\mu} + p \rightarrow \mu^{+} + n$: ANN with kinematical variables assigns rank to each isolated energy deposit (neutron candidate). The highest rank neutron candidate is the primary neutron in 85% and a secondary neutron in 6.5%
 - **Neutron Background in Inclusive** $\nu(\bar{\nu})$ **CC**: signal efficiency of 85.6% with a background rejection factor of 6 × 10–3
 - Rock Muons and Magnet Events in Upstream ECAL: Rejection factor is about 7×10-5.
 Overall efficiency of about 70% in the fiducial volume of the upstream barrel ECAL
 - Rejection of External Neutrino Interactions in STT : Overall we achieve a combined rejection factor of 3 × 10−5 against CC+NC external background, retaining a signal efficiency of 92.7% and a purity of 99.65%.
 - Pile-up Background in Upstream barrel ECAL: The fraction of CC events within the fiducial volume of the upstream barrel ECAL is 2.6% with the 30ns window.. The fraction of ECAL cells with pileup and the fraction of the pileup energy is 0.1% and 0.04% respectively with the 30ns window



35 25/05/2023 M. Tenti - SAND Sim. and Analyses

ν_{μ} CCQE in GRAIN

- Assess the contributions SAND (with GRAIN) could provide in understanding the physics of $v_{\mu} - Ar$ interactions
- The performances of SAND in terms of selecting exclusive $\mu^- + p$ are studied
- GRAIN exploited as homogeneous calorimeter
- CCQE-like selection has been defined:
 - Efficiency > 10% and Purity > 90%



h neutrino energy true [CCQElike]

[V. Cicero]



E, (GeV)



- We have obtained the previous results (<u>docdb-13262</u>) mainly using the fast reconstruction
- The main goal, now is to develop a full reconstruction
- In order to **reproduce the analyses** w/ full reconstruction



Ongoing activities

- Implement and optimize a full event reconstruction
- Comparison of straw- VS drift-based tracker using same reconstruction tools
- ECAL:
 - Integrate new endcap geometry in sandreco
 - Assess PID performances
- Assess beam monitoring potential with more realistic reconstruction
- Analysis:
 - Study vH in a exclusive channel: $\bar{\nu}_{\mu} + p \rightarrow \mu^+ + n$
 - Study v CCQE in GRAIN with exclusive topology: $\mu + p$



A. Surdo]

[F. Alemanno,

[M. Sorbara, A. Gioiosa]

[P. Gauzzi, A. Ruggeri]

[D. Casazza, R. D'Amico]

[F. Barilari]

[G. Ingratta]

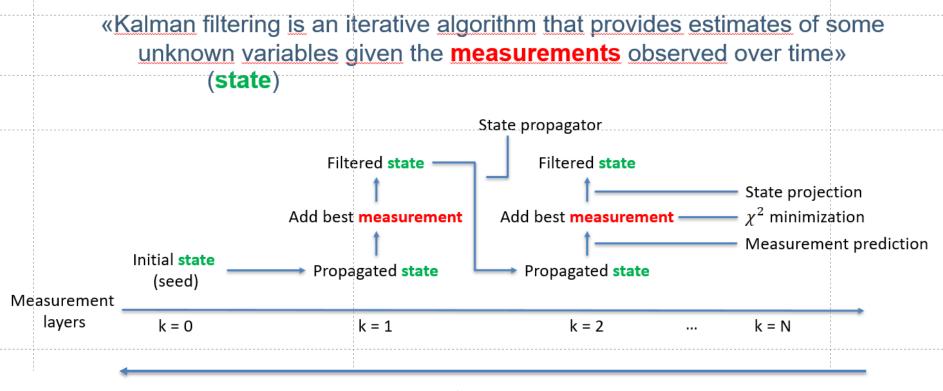
[V. Cicero]

Kalman Filter





Kalman Filter

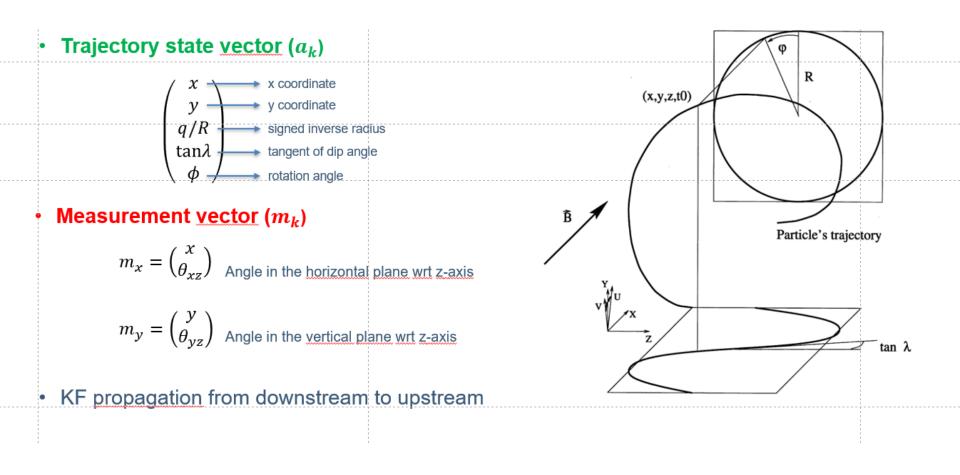


Smoothing state

<u>dune / STTTrackReco · GitLab (infn.it)</u>

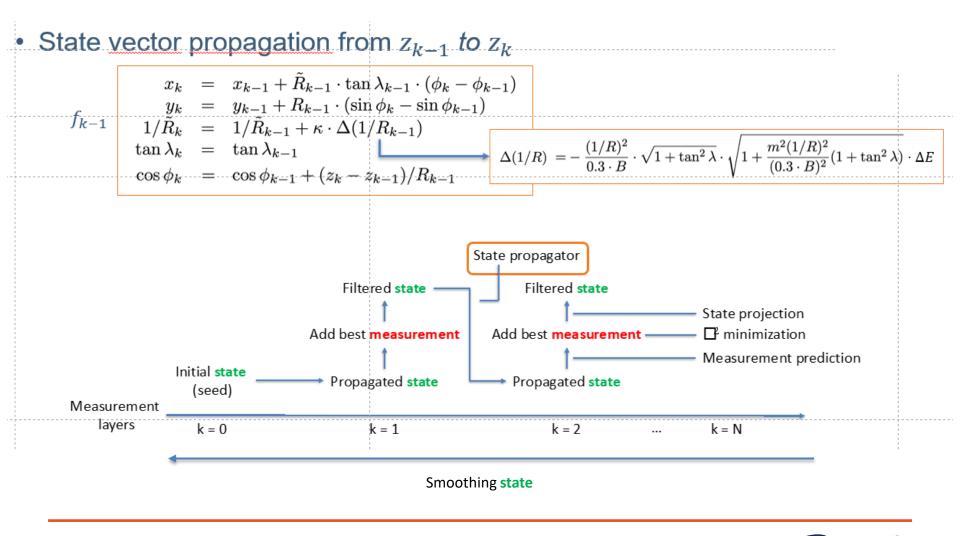


Trajectory Parametrization





Propagation

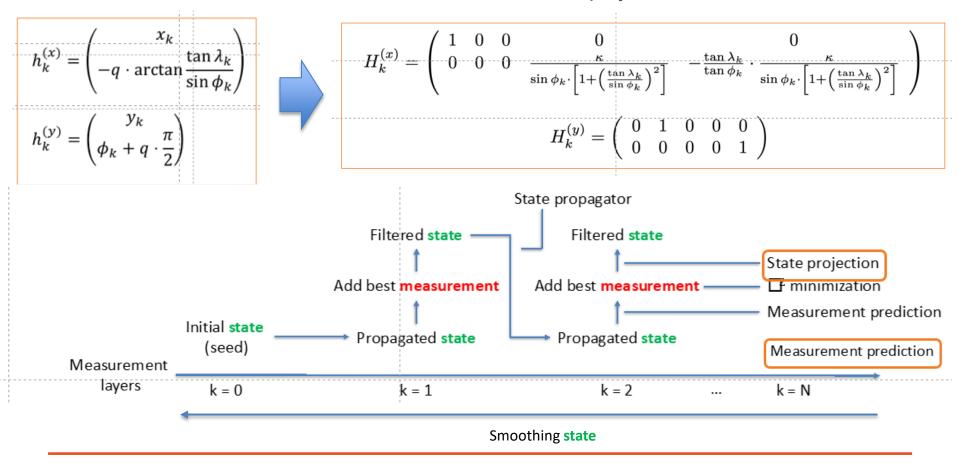




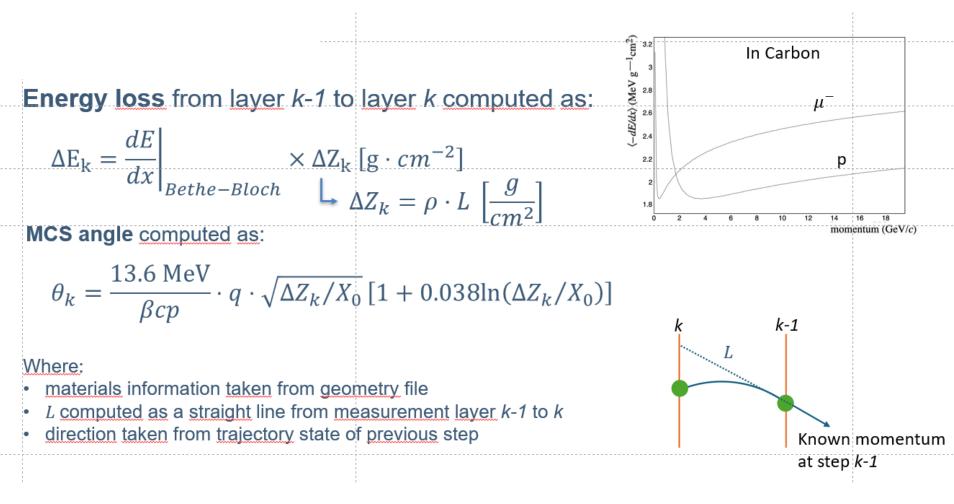
Projection

Prediction of measurement vector m_k from propagated state vector

Measurement projection to state vector

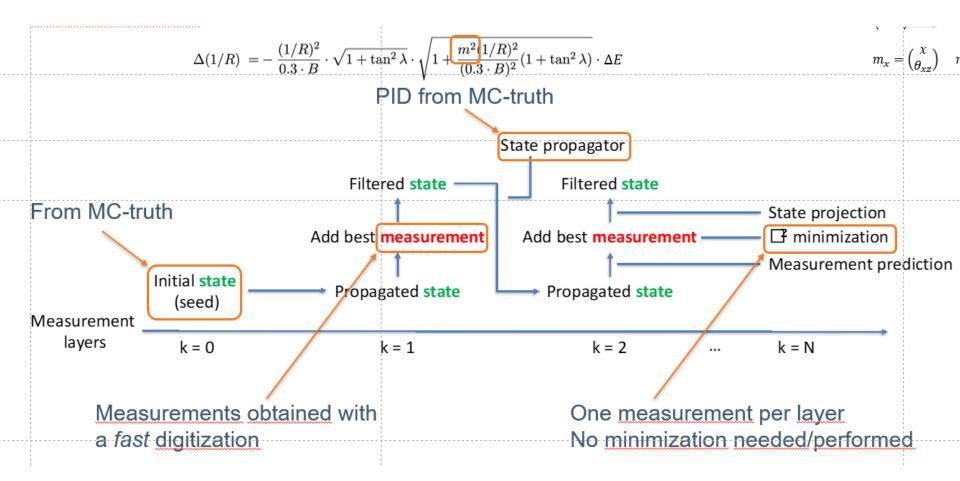


ΔE and MCS

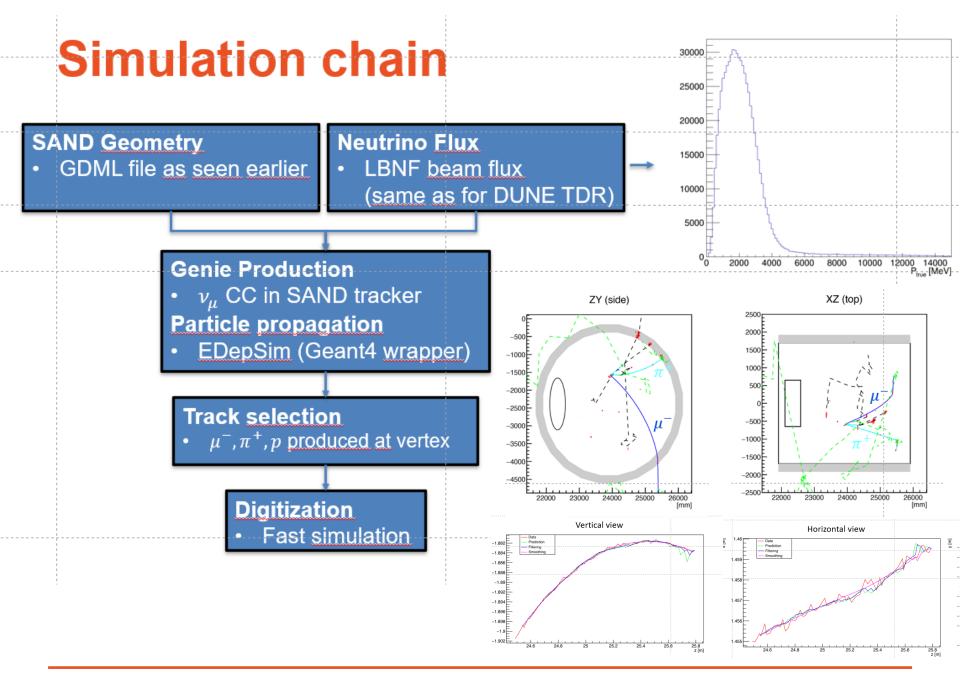




Caveats for KF validation









KF Validation [WIP]

truo

$$r_k = m_k^{r_k m} - m_k^{r_k m}$$

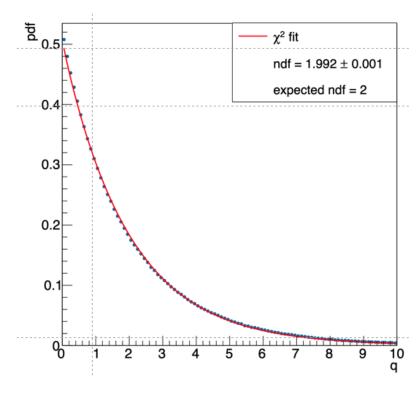
 $C_k = \text{covariance matrix}$

pred

• Two consistency checks:

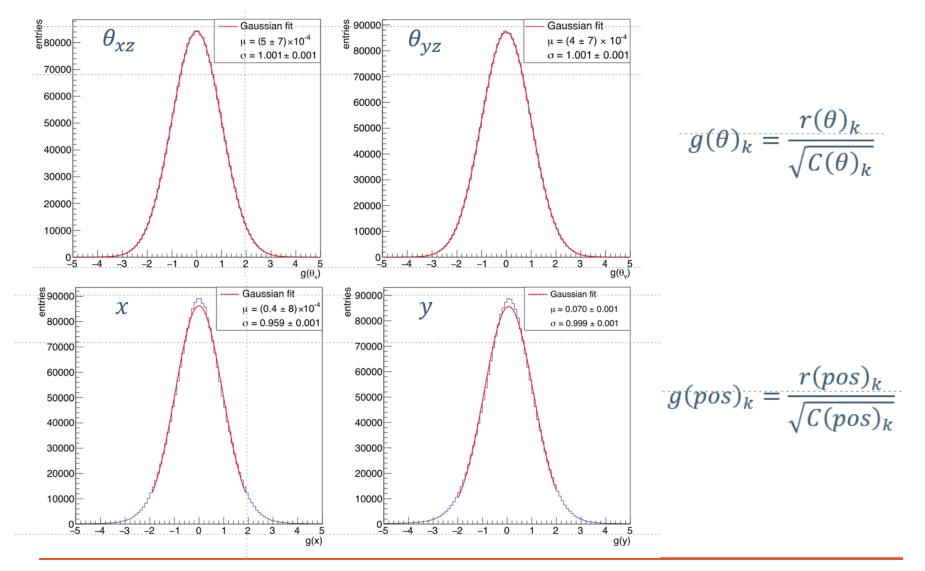
1.
$$q_k = r_k^T C_k^{-1} r_k \sim \chi^2 (ndf = 2)$$

2.
$$g(i)_k = \frac{r(i)_k}{\sqrt{C(i)_k}} \sim Gaus(\mu = 0, \sigma = 1)$$





KF Validation [WIP]





ECAL clustering



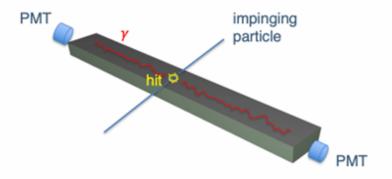
Reconstruction of energy deposit position, time and energy

The coordinate along the fiber z is derived by time difference between two ends while x and y are given by the center of the fired cell. $t^{A,B}$ time in ns measured at the

$$t^{e} = \frac{t^{A} + t^{B}}{2} - \frac{t_{0}^{A} + t_{0}^{B}}{2} - \frac{L}{2\nu} \qquad z^{e} = \frac{\nu}{2} \left(t^{A} - t^{B} - t_{0}^{A} + t_{0}^{B} \right)$$

 $t^{A,B}$ time in ns measured at the ends, $t_0^{A,B}$ overall time offset, Llength of the cell, v light velocity in the fiber.

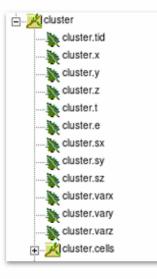
Each cell is read by two photosensors, one per side (A,B) which collects the scintillation light guided by the optical fibers.





Clustering

C++ algorithm inspired by KLOE experiment to create ECAL cluster output as ROOT TTree



Cells are divided in **complete** (signal on both photo sensors) and **incomplete** (with signal only in one sensor).

Neighbor complete cells are grouped in pre-clusters.

Pre-clustering

Takes one complete cell as a seed and checks the neighbors, if are found complete cells they are added to the pre-cluster.

The process goes on until no adjacent complete cells are found.

Pre-cluster variables are calculated, time and position as energy weighted averages over contributing cells, energy as the sum of the cell energies. $\Gamma^A = \Gamma^B$

$$E_i = \frac{E_i^A + E_i^B}{2}$$

- **Splitting** compute time variance of the precluster and in case of time discrepancy > 5ns divides into quadrants forming new pre-clusters.
- Merging compares two close pre-clusters and merges them if their spatial distance is < 40 cm and time difference < 2.5 ns.
- Adding incomplete cells to the pre-clusters, comparing cell position and closest pre-cluster centroid.

Under testing, validation and optimization









ND sim/reco «official ND production»

- Infrastructure for production chain:
 - Event generator, detector responce simulation, digitization, reconstruction

		으 Notifications 양 Fork 4 ☆ Star 0
<> Code 🕑 Issues 1 រ៉ា Pull requests 2	🖸 Actions 🖽 Projects 🔍 Security 🗠 Insights	
^৫ main - ND_Production / scripts /		Go to file
Jeffrey Kleykamp Fixed typo in overlay code. Previous overlay using this script was 1		56810a2 on 8 Jul 🕚 History
CMakeLists.txt	make a UPS product with mrb	17 months ago
ProcessND.py	Fixed typo in overlay code. Previous overlay using this scrip	t was 1 4 months ago
🗋 template.sh	fix line 60, add comma	13 months ago



DUNE / ND_CAFMaker Public

△ Notifications

⊙ Issues 2 រ Pull requests 1 Actions Projects ③ Security ✓ Insights <> Code

ピ master ◄ ND CAFMaker / src / reco /

chenel whoops, don't be lazy. put implementation in .cxx 6

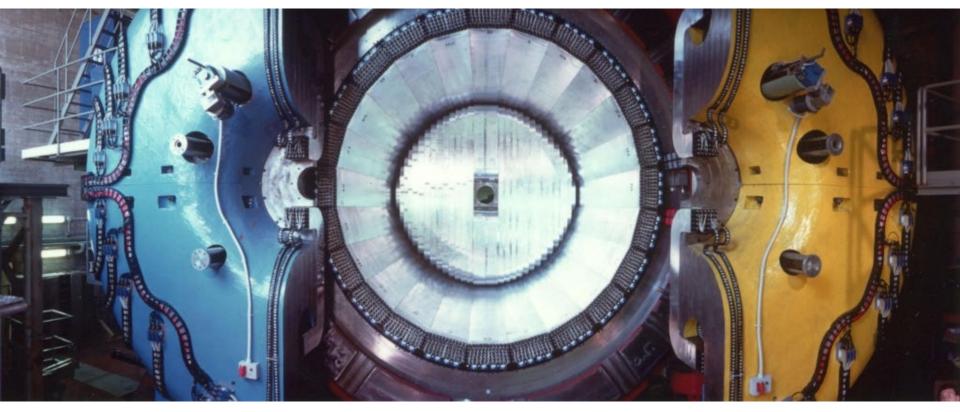
	• Event Su	
IRecoBranchFiller.h	Merge branch 'master' into feature/TMSconverer to pick up cr Input fo	
MLNDLArRecoBranchFiller.cxx	Merge branch 'master' into feature/TMSconverer to pick up cl • SAND CA	
MLNDLArRecoBranchFiller.h	getting rid of dt + parametrized reco • Content	
DULArProductFiller.cxx	whoops, don't be lazy. put implementation in .cxx	
DULArProductFiller.h	whoops, don't be lazy. put implementation in .cxx	
NDLArSummaryH5DatasetReader.cxx	quiet print statements in NDLAr fillers	
DULArSummaryH5DatasetReader.h	once again, don't set a size_t to -1 (eyeroll)	
NDLArTMSMatchRecoFiller.cxx	Update matcher to use TMS distances in cm units, and not to convert L	
DULArTMSMatchRecoFiller.h	Update matcher to slightly different method (propagate the LAr track	
SANDRecoBranchFiller.cxx	Automatically enable or disable compilation of sand reco based on exi	
SANDRecoBranchFiller.h	Automatically enable or disable compilation of sand reco based on exi	
TMSRecoBranchFiller.cxx	Move TMS reco branches to have lengths in cm, not mm, as to match LAr	
TMSRecoBranchFiller.h	Merge branch 'master' into feature/TMSconverer to pick up changes due	

CAF Maker

- Common Analysis File ٠
- ummary
- or Analyses
- AF implemented
- t to be defined

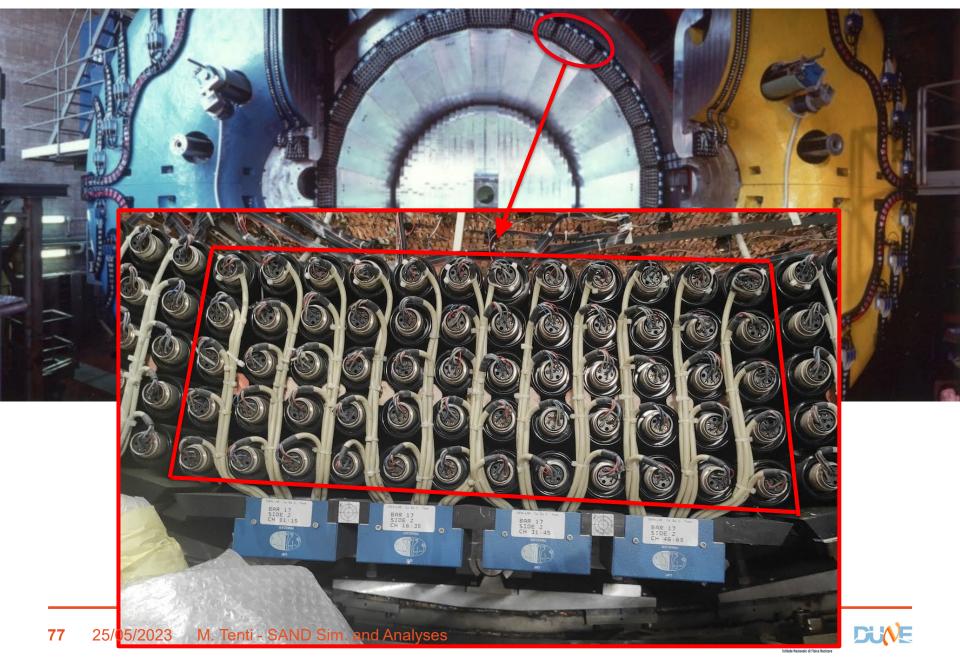


ECAL

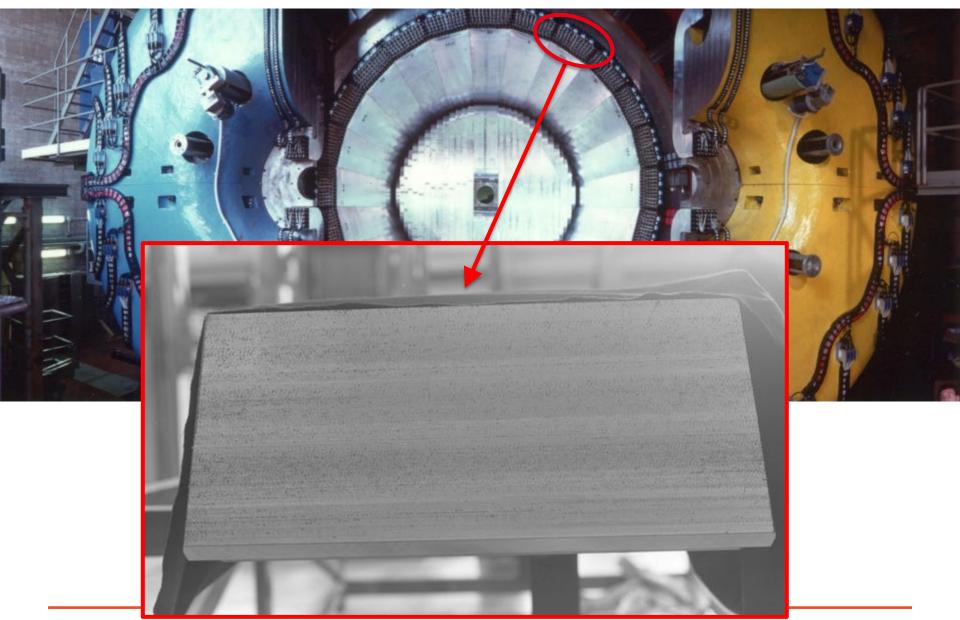




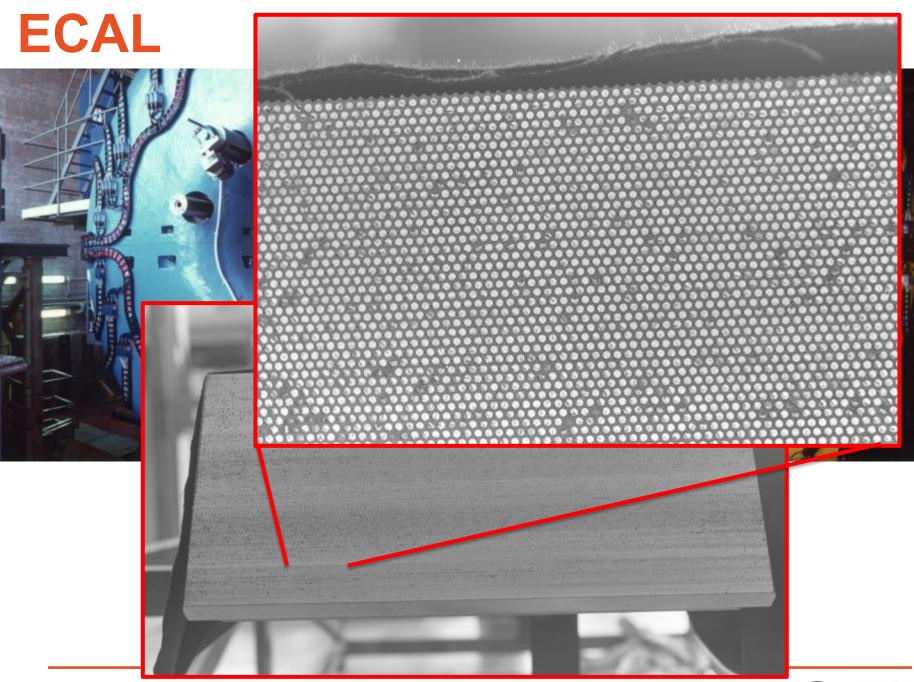
ECAL



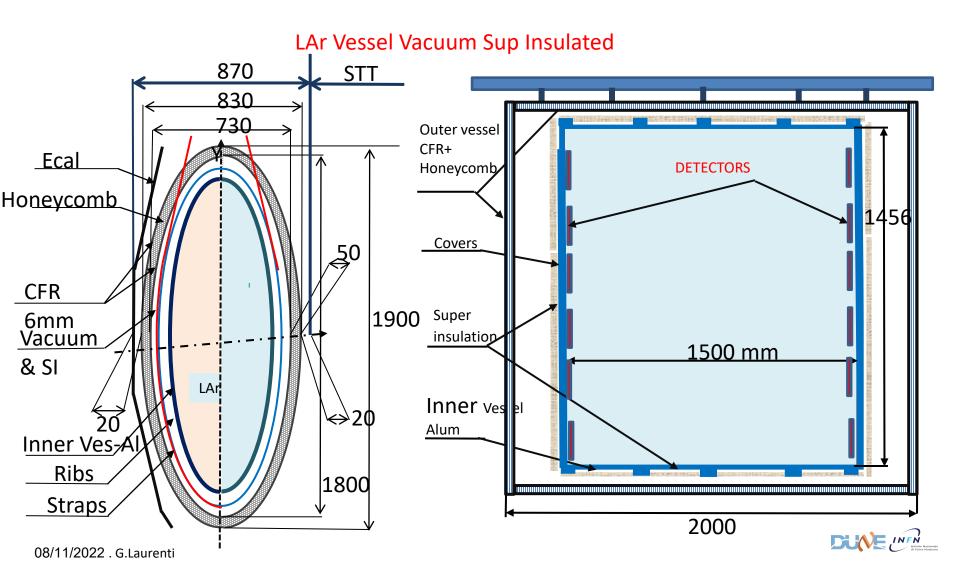
ECAL





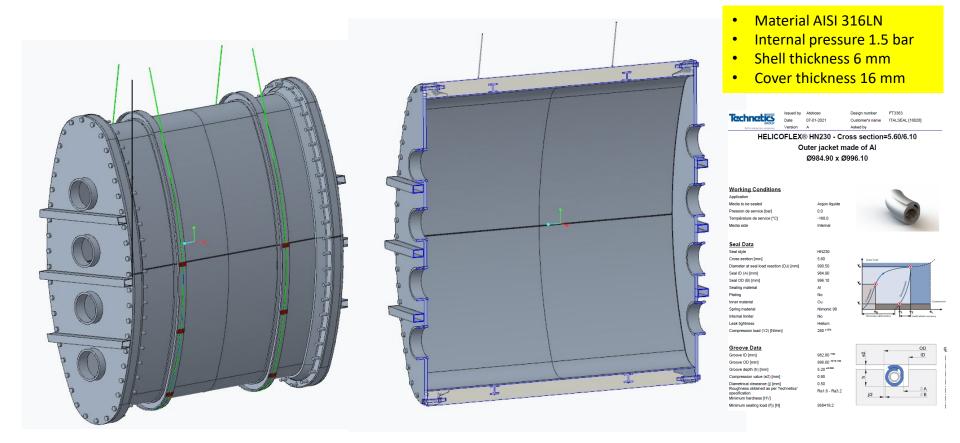






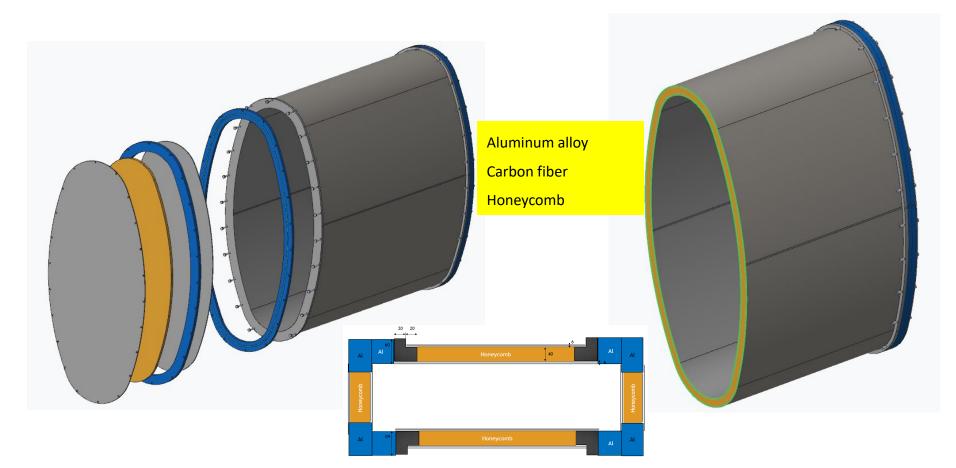


Internal vessel design



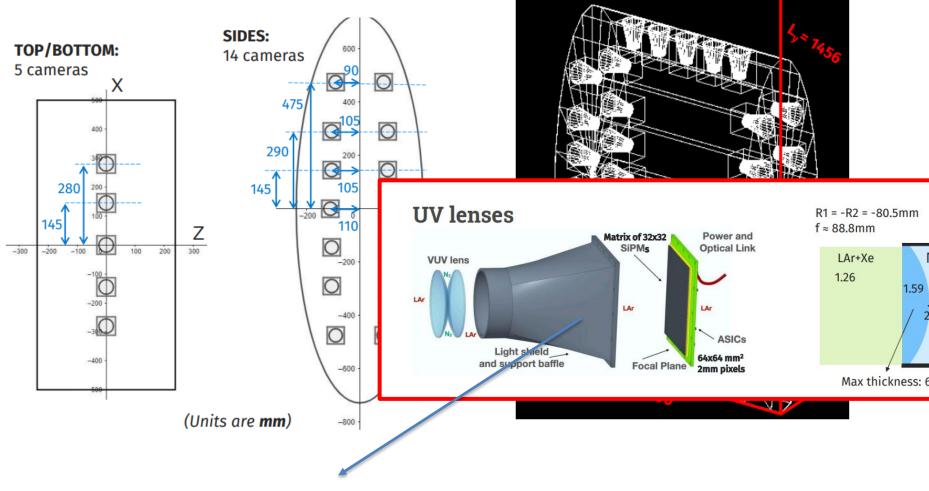


External vessel design



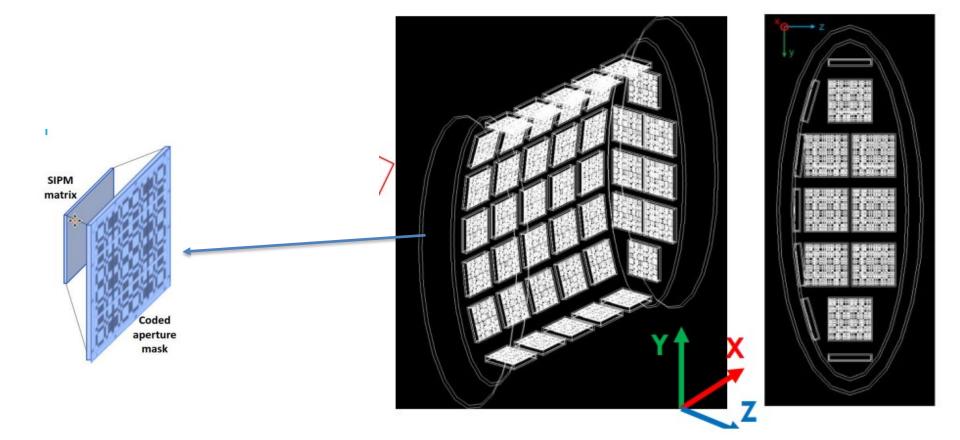


Optical System: Lens





Optical System: Coded Aperture Mask





GRAIN: Analytic Approach

3D reconstruction:

front-to-front lenses and using theoretical P, P' and F

$$X_{s} = -\frac{2cx'(x^{2} + y^{2})}{f(x^{2} + y^{2} + xx' + yy')}$$
$$Y_{s} = -\frac{2cy'(x^{2} + y^{2})}{f(x^{2} + y^{2} + xx' + yy')}$$
$$\mathbf{x} = (x, y), \qquad \mathbf{x}' = (x', y')$$

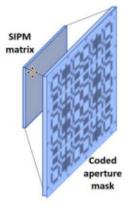
c distance of the center of the lens from the center of GRAIN

f lens-sensor distance

WARNING: the labels X_s and Y_s are meant as the transversal 3D coordinates to the projection direction



3D RECONSTRUCTION WITH CODED APERTURE MASKS



Coded aperture mask techniques were developed as the evolution of a single pinhole camera Matrix of multiple pinholes to improve light collection and reduce exposure time Image formed on sensor is the superimposition of multiple pinhole images.

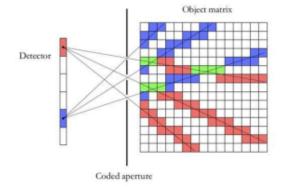
Advantages: Good light transmission (50%) Good depth of field Small required volume

Detailed description of Hadamard masks and deconvolution methods: Eur. Phys. J. C 81 (11) 1011 (2021)

Readout system with SiPM matrixes coupled with coded aperture masks.

The custom reconstruction algorithm produces a 3D map of the deposited energy:

- measured incident photons are propagated back into the LAr volume with an appropriate weight assigned to voxels.
- This weight represents the Bayesian probability of the voxel to be a source of the detected photons.
- · A score in the segmented reconstruction volume is calculated by adding these weights.





Electron ID

used for electron identification in ECAL in addition to the longitudinal profile. We combine the following 13 variables into a ANN: (a) E/p; (b) fraction of total energy deposited in the layer 1; (c) fraction of total energy deposited in the layer 2; (d) fraction of total energy deposited in the layer 3; (e) fraction of total energy deposited in the layer 4; (f) fraction of total energy deposited in the layer 5; (g) asymmetry (max-min)/(max-min) in the energy fractions among the 5 layers; (h) energy deposited in the first layer; (i) maximal energy in a cell within the first layer; (l) total number of cells with deposited energy; (m) number of cells in the first layer; (n) number of cells in the last layer. Figure 147 shows the distribution of the NN output for electrons and pions and the corresponding sensitivity as a function of the NN cut. An electron efficiency of 90% corresponds to a pion efficiency of about 6.4%.





Proton/Pion

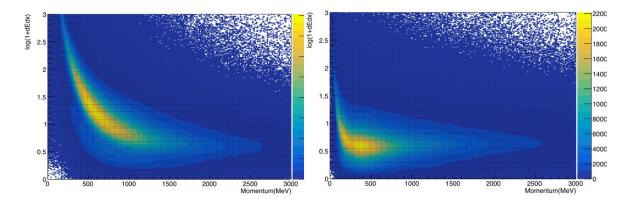


Figure 148: Distribution of $\log(1 + dE/dx)$ as a function of the momentum for protons (left plot) and pions (right plot) in STT. The energy deposition in the gas mixture Xe/CO₂ (or Ar/CO₂ for modules with graphite targets) of each straw crossed by the particle is used. Reconstruction effects are taken into account in the plots.

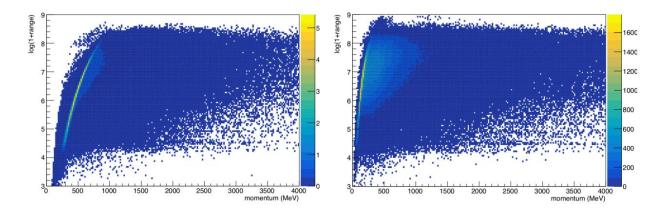


Figure 150: Distribution of log(1 + range) as a function of the momentum protons (left plot) and pions (right plot) in STT. The range includes the various passive targets.



Proton ID with TOF and ECAL

 $m = p/(\beta\gamma)$. We combined the following 7 variables into a ANN: (a) $\ln \lambda_{dE/dx}^{p/\pi}$ from dE/dx as described above; (b) total range; (c) momentum measured in STT; (d) β ; (e) reconstructed mass m; (f) flag determining if the track reaches ECAL; (g) maximal number of cells in ECAL. Figure 152 shows the distributions of the corresponding NN output for protons and pions. With a 90% proton efficiency we obtain a pion efficiency of about 1.1%. The same NN can be used to veto protons in the kinematic tagging of the leading CC leptons described in Sec. 5.8.1. For this application we obtain a proton efficiency of 0.7% with a muon efficiency of 95% (Fig. 152).

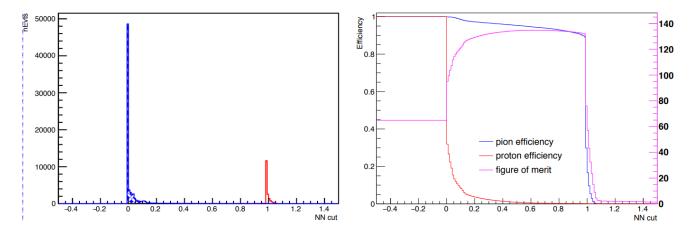


Figure 152: Distribution of the NN output for proton identification (left plot) and corresponding sensitivity as a function of the NN cut (right plot).



Muon ID (I)

surface, while a significant fraction of pions stop or interact within the first 4 ECAL layers. We subdivide the charged tracks in two categories: (i) tracks reaching the outermost layer 4; (ii) tracks stopping or interacting in layers 0-3. For both samples, we initially disregard the pions crossing all 5 ECAL layers without interacting and focus on the ones either stopping or interacting in ECAL. We start our identification algorithm from the first sample and select 10 discriminant variables: (a) maximal energy in a cell; (b) asymmetry in the cell energy (max-min)/(max+min); (c) total number of cells; (d) mean energy among the 5 layers; (e) RMS of energy among the 5 layers; (f) asymmetry in layer energy (max-min)/(max+min); (g) energy in outermost layer 4; (h) maximal energy in layers; (i) minimal energy in layers; (l) maximal number of cells in layers. Figure 154 shows the distributions of these variables for muon and pion tracks. We combine the 10 variables into an ANN and train it with all muon tracks (signal) and with the sub-sample of pions stopping or interacting in ECAL (background), as illustrated in Fig. 155. We select tracks with NN>0.28 as muon candidates, with an efficiency of 98% for actual muons and 7.5% for pions (Fig. 156).

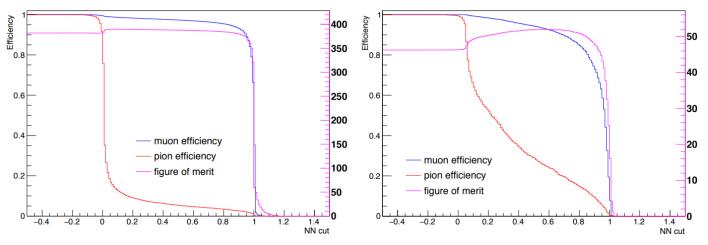
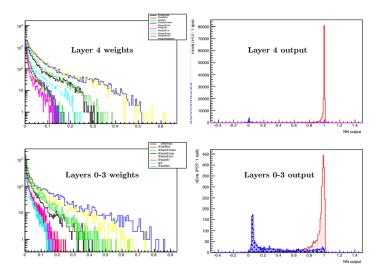


Figure 156: Muon and pion efficiencies and sensitivity $S/\sqrt{S+B}$ as a function of the NN cut for tracks with outermost energy in layer 4 (left plot) and the ones stopping or interacting in layers 0-3 (right plot).



Muon ID (II)

We apply a similar procedure for the second sample of tracks stopping or interacting within the first 4 ECAL layers. The following 8 discriminant variables are combined into an Artificial Neural Network (ANN): (a) maximal energy in a cell; (b) total number of cells; (c) mean energy among the layers; (d) asymmetry in layer energy (max-min)/(max+min); (e) maximal energy in layers; (f) minimal energy in layers; (g) range inside ECAL; (h) reconstructed momentum in STT. Figure 155 shows the ANN output. We select the cut NN>0.49 based on the global sensitivity $S/\sqrt{S+B}$ including the events from the other sample passing the cut in layer 4 (Fig. 156). The combined muon efficiency is 98% and the pion efficiency is 10.9%. So far we have ignored the pions crossing all the 5 ECAL layers – total thickness about one interaction length λ – without interacting. Figure 157 shows the distribution of the layer 4 NN output for this sample. The same NN cut above rejects about 43% of this pion sample, mainly due to the energy deposition in the ECAL layers. The total fraction of pions passing the NN selection in ECAL is 23.7%.



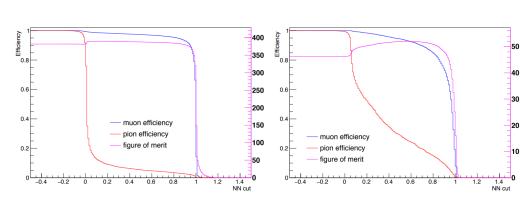


Figure 156: Muon and pion efficiencies and sensitivity $S/\sqrt{S+B}$ as a function of the NN cut for tracks with outermost energy in layer 4 (left plot) and the ones stopping or interacting in layers 0-3 (right plot).

Litter Radoule di Fisia Nuclear

Figure 155: Weights of ANN variables (left plots) and ANN output (right plots) for muons and pions with outermost energy in layer 4 (top plots) and for the ones stopping or interacting in layers 0-3 (bottom plots).

system, since the total visible momentum vector is fixed (three constraints). We select the following four kinematic variables [23]:

- p_T^l : transverse momentum of the track candidate;
- $\theta_{\nu l}$: angle of the track candidate with respect to beam direction;
- y_{Bj} : ratio between the energy of the "hadron system" (visible energy minus track energy) and the total visible energy;
- R_{Q_T} : ratio between the transverse size of the of the "hadron system" $\langle Q_T^2 \rangle_H$ and that of the full event $\langle Q_T^2 \rangle$, where Q_T component of the track momentum perpendicular to the total visible momentum.

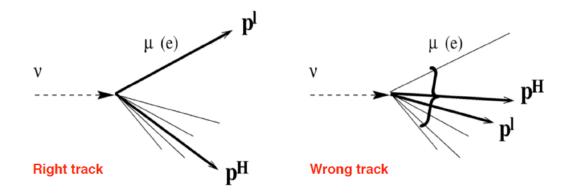


Figure 174: Illustration of the kinematic tagging in CC interactions. See text for details.



We combine the four kinematic variables into an ANN, which is trained with the true muon tracks (signal) and random hadron tracks from ν_{μ} ($\bar{\nu}_{\mu}$) CC interactions in the FHC (RHC) beam with a number of possible candidate tracks ≥ 2 . In order to take into account the kinematic bias introduced by the magnet yoke we perform two separate trainings: (i) NN₁ using all candidate tracks; (ii) NN₂ using only candidate tracks not reaching the outer magnet yoke. Figure 177 shows the distributions of both the NN₁ and NN₂ outputs for true muons and random hadrons in ν_{μ} CC events.

The fist step of the muon tagging algorithm is the listing of all possible candidate tracks with the desired charge within the same event. We veto tracks which are interacting within the STT tracking volume and exclude them from the list of candidate tracks. Similarly, for the μ^+ tagging we apply a proton veto on all positive tracks not reaching the outer magnet yoke. This veto is based on a loose cut on the ANN for proton identification described in Sec. 5.4.2 and is required since protons typically have small momentum and are emitted at large angles, similarly to the muons not reaching the outer magnet yoke.

For events in which more than one candidate track is present, we then calculate the value of the tagging ANN for each candidate track. To this end, we use either the NN₁ training or the NN_2 training, depending on whether the track reaches the outer magnet yoke or not. In order to compare the numerical values of both trainings we multiply NN₂ by a scale factor c = 15, which was optimized by maximizing the overall muon tagging efficiency. We then rank all candidate tracks in descending order of the calculated value of the tagging NN. We select the most likely muon candidate as the single track with the highest rank in the list of all possible candidate tracks. Table 22 summarizes the resulting muon tagging efficiencies. Overall, we correctly select the true primary muon in 99.1% of the ν_{μ} CC events in the FHC beam and 99.3% of the $\bar{\nu}_{\mu}$ CC in the RHC beam. Figures 178 and 179 show the dependence of the tagging efficiency from the muon momentum.



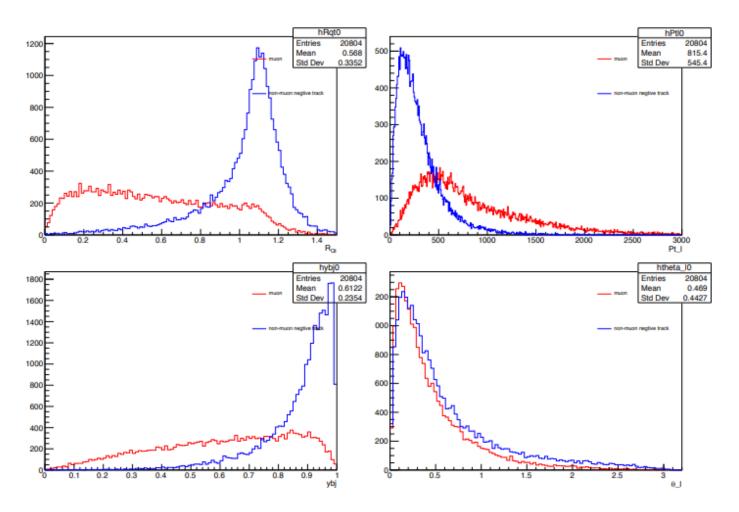


Figure 175: Kinematic tagging of μ^- in ν_{μ} CC from STT fiducial volume in the FHC beam: distribution of the kinematic variables used in NN₁ for all CC events with ≥ 2 negative tracks. See text for details.



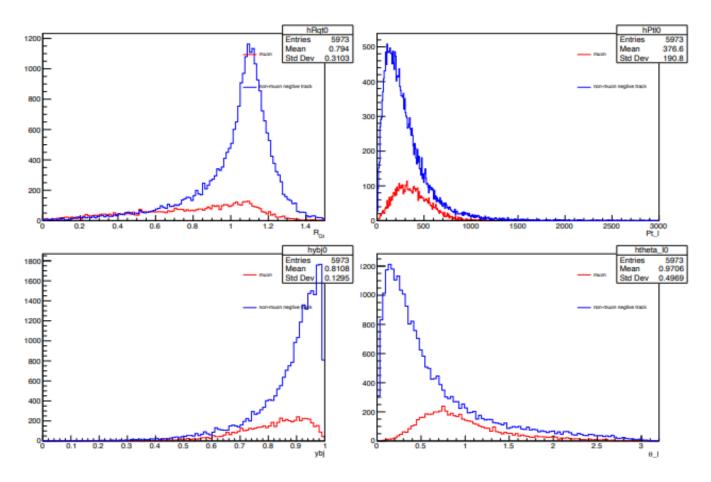


Figure 176: Kinematic tagging of μ^- in ν_{μ} CC from STT fiducial volume in the FHC beam: distribution of the kinematic variables used in NN₂ for all CC events with ≥ 2 negative tracks not reaching the outer yoke. See text for details.



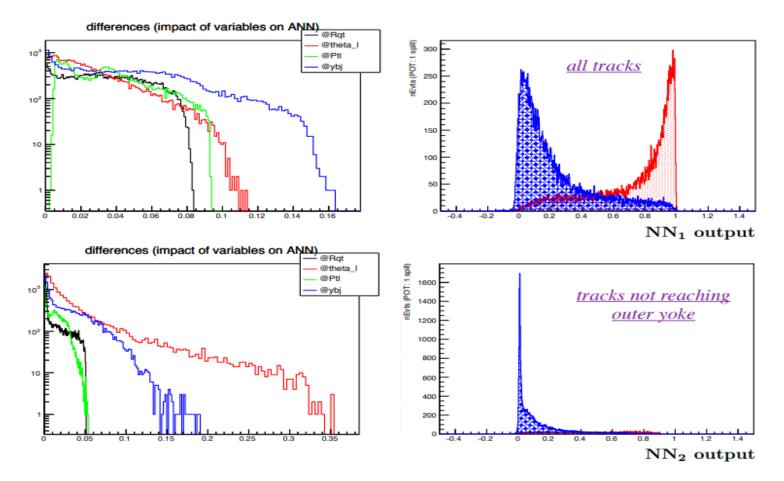


Figure 177: Weights of ANN variables (left plots) and ANN output (right plots) for μ^- (red) and random h^- hadrons from ν_{μ} CC interactions in FHC beam. Top plots: all tracks from CC events with ≥ 2 negatively charged candidates. Bottom plots: sub-sample of tracks not reaching the outer magnet yoke from CC events with ≥ 2 negatively charged candidates. See text for details.



Kinematical tagging of leading electron

The kinematic tagging of e^{\pm} follows closely the algorithm described above for μ^{\pm} . We list all possible track candidates with the correct charge within the same event, excluding tracks interacting within the STT volume. We apply a proton veto on positive tracks after re-training the corresponding NN for proton identification (Sec. 5.4.2) for the specific e/p separation, in order to take into account the different energy loss of electrons and pions/muons. For events with more than one candidate track, we then rank the e^{\pm} candidates in decreasing order of the tagging NN₁. We use a single training since in the case of e^{\pm} no kinematic bias is expected from the magnet yoke. To this end, we do not re-train the tagging ANN, but rather use the same training obtained from $\nu_{\mu}(\bar{\nu}_{\mu})$ CC events. While slightly reducing the achievable tagging efficiency, this choice is primarily intended to reduce systematic uncertainties on the ν_e/ν_{μ} and $\bar{\nu}_e/\bar{\nu}_{\mu}$ ratios (Sec. 6.4). We select the most likely electron candidate as the single track with the highest rank. Table 22 summarizes the resulting electron tagging efficiencies. Overall, we correctly select the true primary electron in 98% of the ν_e CC events in the FHC beam and 98.6% of the $\bar{\nu}_e$ CC in the RHC beam.

