

Requirements for the layer0 of the SuperB-SVT:

- ❖ excellent position resolution
- ❖ low material budget
- ❖ limited occupancy

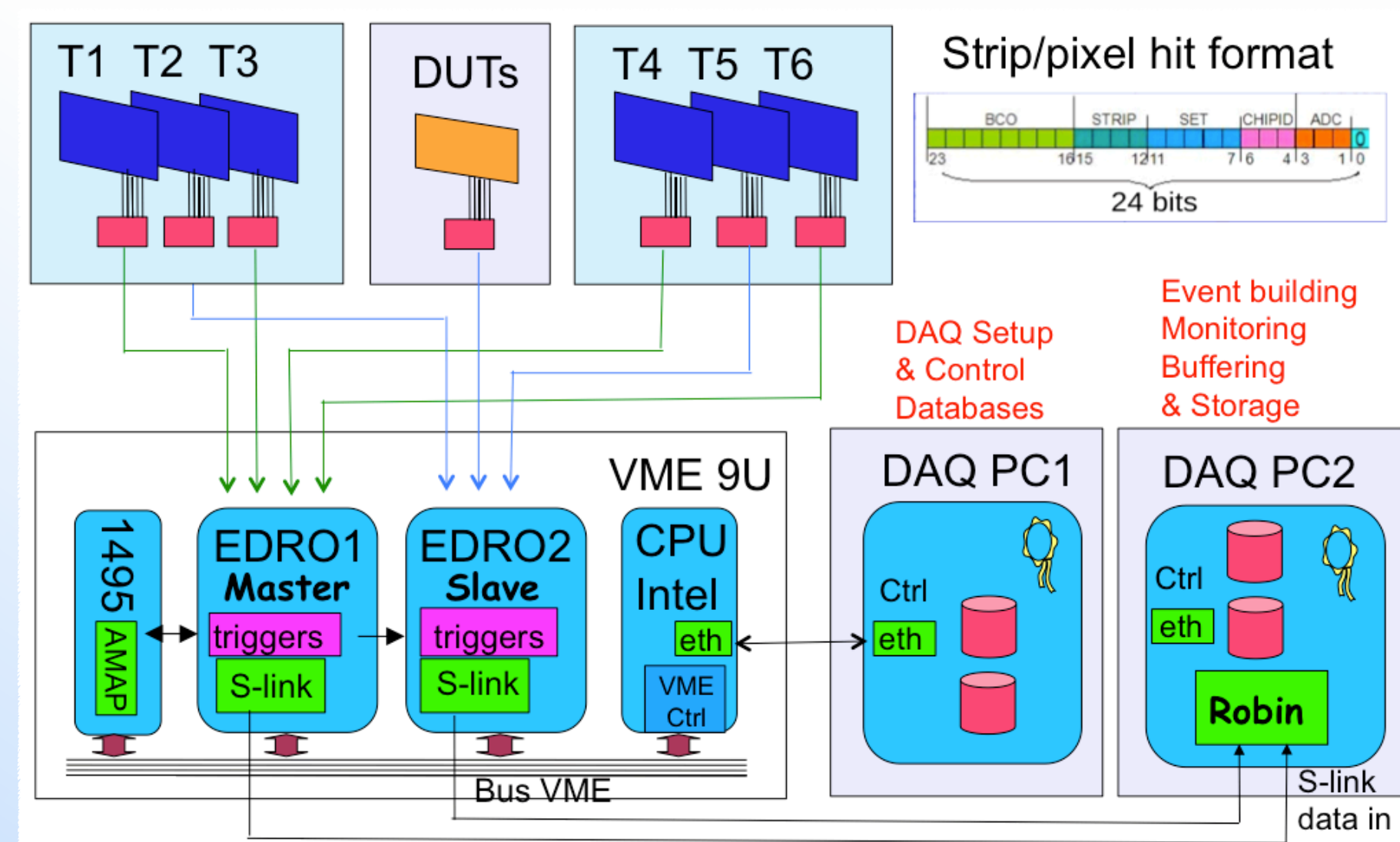
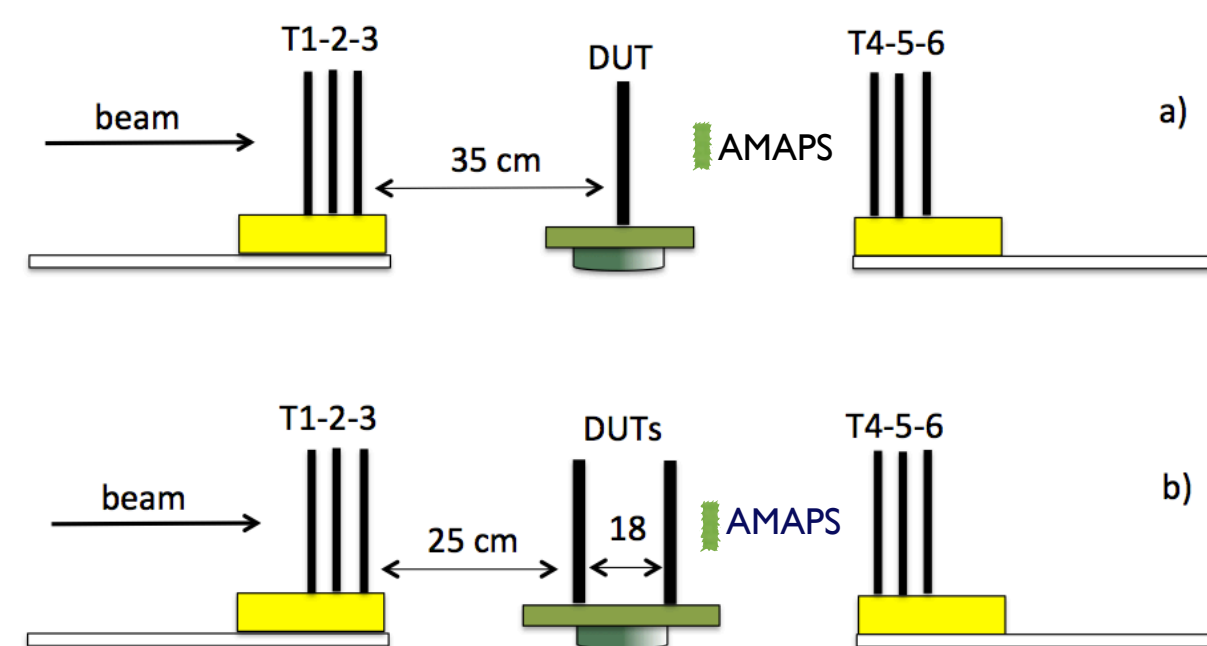
- ❖ high radiation tolerance
- ❖ high-speed readout
- ❖ good time resolution

Striplets in layer0 for the first years; detector upgrade at high luminosity to cope with higher rate

Prototypes of a new hybrid pixel detector and a high resistivity detector with short strips, developed by the VIPIX collaboration and aimed at equipping the layer0 of the SuperB vertex detector, have been tested in September 2011 with a 120 GeV pion beam at the SPS H6 beam line at CERN. They are placed at the center of a reference telescope consisting of six planes of silicon detector with double-sided strip readout. Both the telescope and the detector under test (DUTs) are supplied with a custom-design, data-push digital readout. The core of the trigger and data acquisition system are two custom-design VME boards (EDRO) organized in a master-slave configuration and responsible for programming the front-end chips of both the telescope and the DUTs. The master distributes synchronization clocks to all devices, as well as triggers to the slave and a small analog-maps detector placed behind the DUTs and equipped with an independent readout. Both EDROs act as event-fragment builders, packing data from the telescope and the DUTs in fragments that are then sent out to a remote PC for event building, buffering and storage.

Beam Test Setup

- ❖ 120 GeV/c pion beam;
- ❖ beam width at DUT $\sim 8 \times 4$ mm rms
- ❖ ~ 9 s spill duration;
- ❖ 6 planes of double-sided silicon strip detectors with 50 μ m readout pitch and 2×2 cm² area with data driven digital readout;
- ❖ data driven, digital readout DUTs on motorized table with remote control;
- ❖ analog maps with independent readout but participating to the trigger



Main Electronics

Two custom VME 9U boards for Event Dispatch and Read-Out (EDRO):

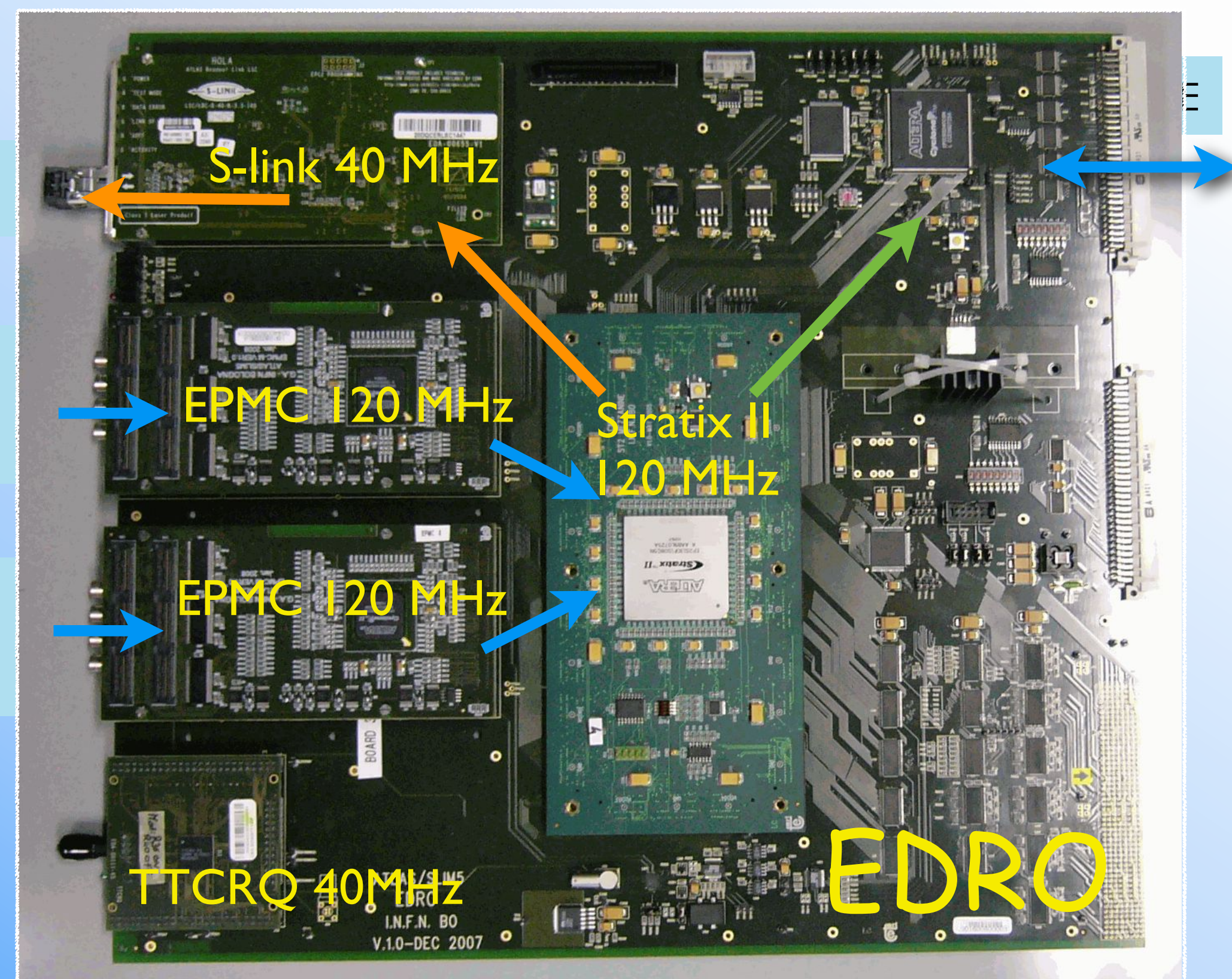
- ❖ flexible, fully programmable;
- ❖ able to configure the front-end chips of both the telescope and the DUTs (SuperPix0 and Striplets)
- ❖ able to collect, format and dispatch data
- ❖ organized in master-slave configuration
- ❖ the master builds and provides triggers to the slave and the analog maps, and distributes clock and time-stamps to all devices

One Robin PCI card (developed by ATLAS) in a remote PC connected to the EDRO via optical link for fast data reception and buffering

To Robin
160 MB/s

8 Gbits/s
Hits from DUTs
or telescope

8 Gbits/s
Hits from DUTs
or telescope



Trigger

Fully configurable logic based on either telescope or analog maps information

Telescope logic

- ❖ selectable sub-regions
- ❖ selectable number of layers (up to eight in four double-sided planes)
- ❖ selectable multiplicity per layer

Analog maps trigger

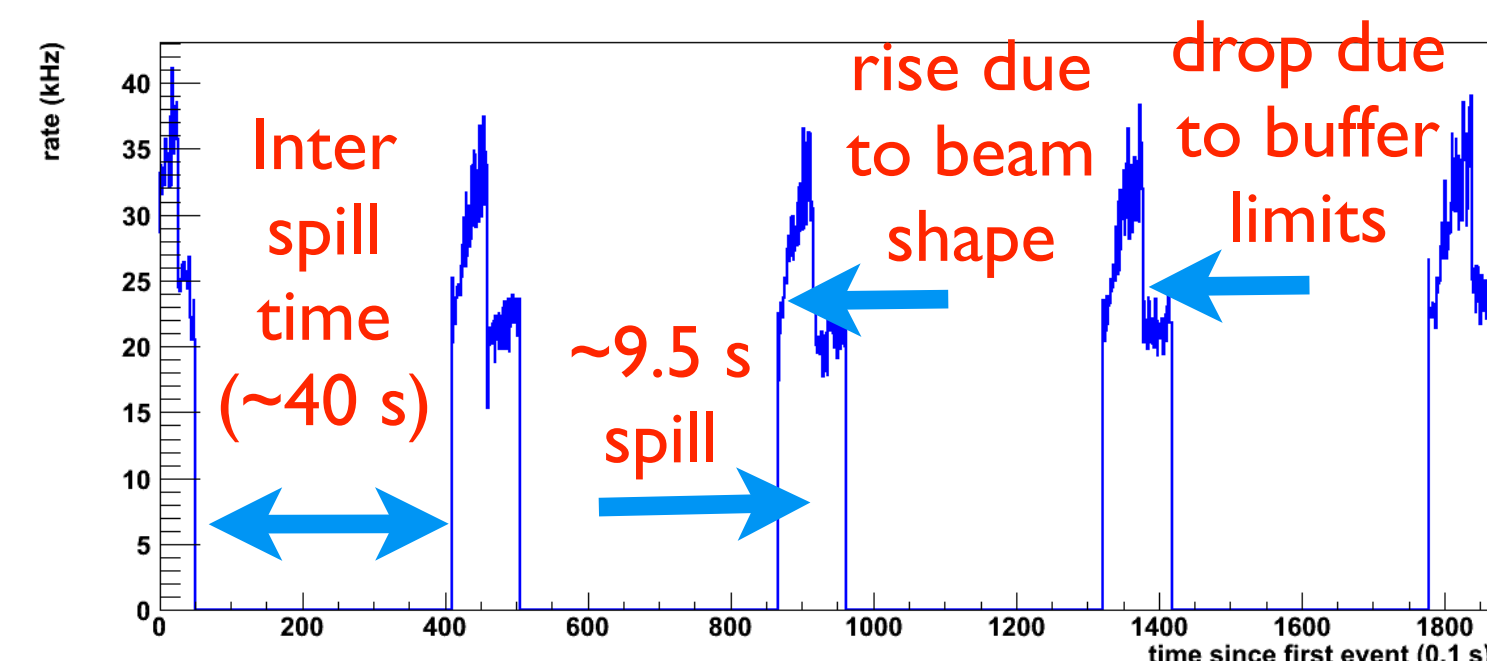
- ❖ find the $\sim 150 \times 300 \mu\text{m}^2$ analog maps projection on the telescope layers (region-of-interest trigger to be then sent to analog maps)

SW Infrastructure

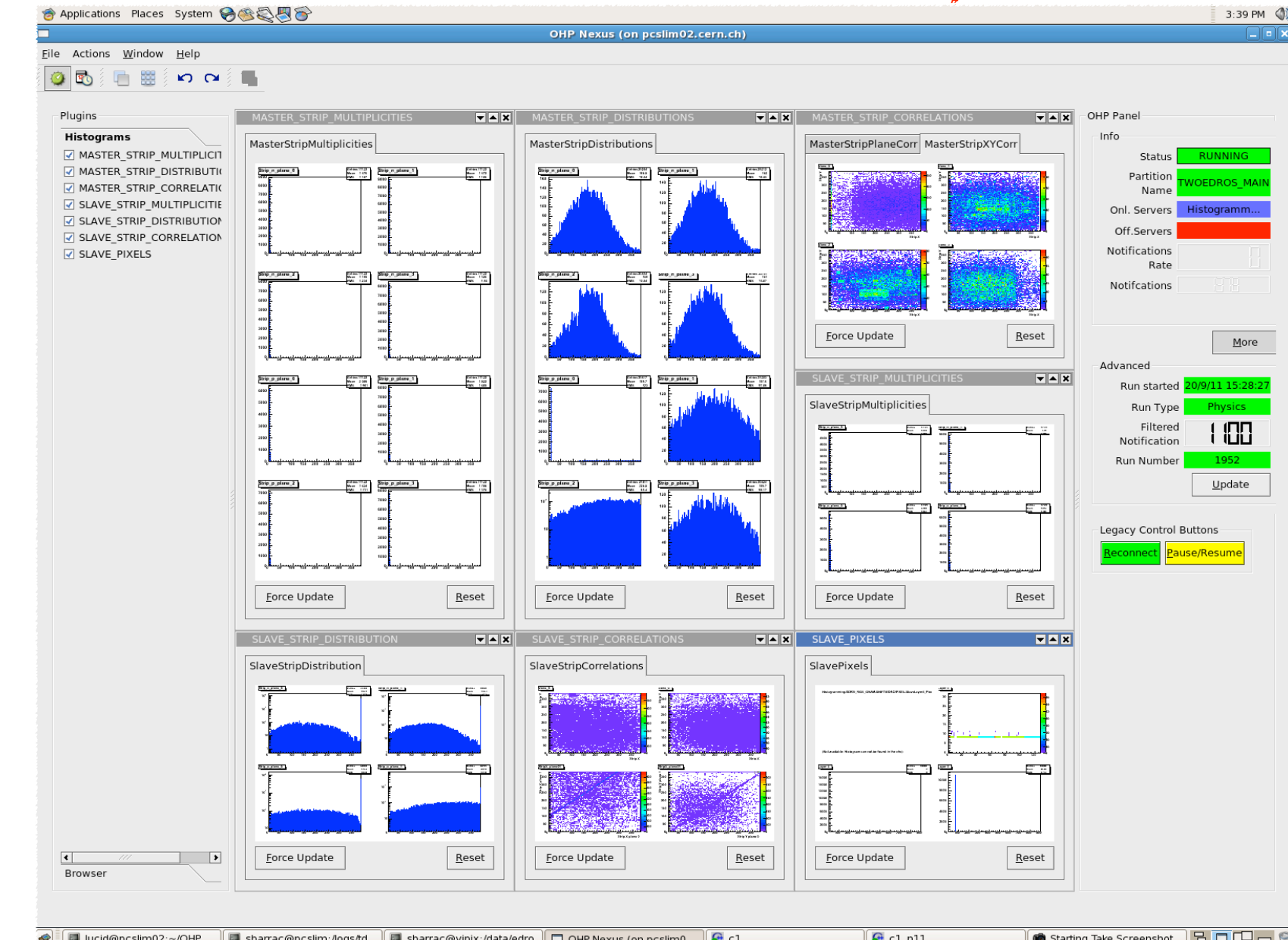
- ❖ final state machine transitions
- ❖ OKS configuration DB (select different numbers and types of chips to be configured and readout)
- ❖ ELOG (run summaries, operators entries)
- ❖ online DAQ monitoring/data analysis on event subsample
- ❖ Histogram presenter
- ❖ MySQL condition DB (store details of each run configuration)

DAQ Rates and Beam Profile

- ❖ maximum observed ~ 40 kHz
- ❖ limited by final data writing to disk
- ❖ first half of each spill dead-time free (events buffered in Robin)
- ❖ second half of spill limited to 20 kHz (Robin buffer full)
- ❖ 550 GB stored data (~ 50 M striplet and ~ 350 M pixel events)



Online Monitoring



- ❖ beam profiles with telescope data
- ❖ DUT hit multiplicity
- ❖ DUT hit-map
- ❖ DUT-telescope spatial correlations