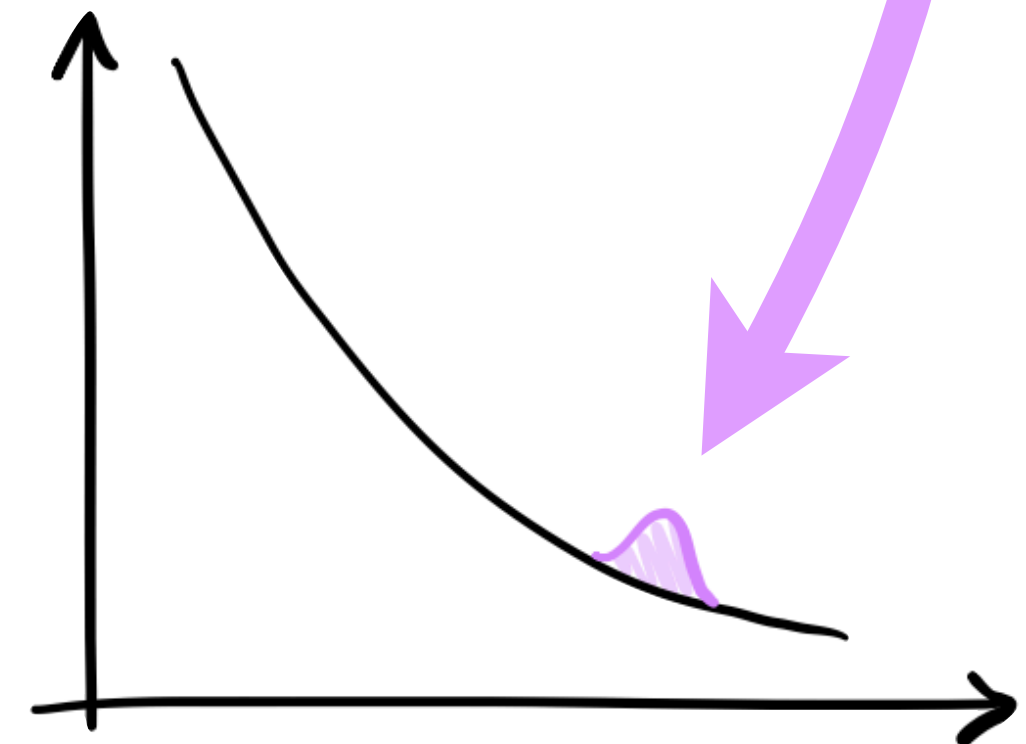


# New Physics and how to find it (in ATLAS with ML tools)

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Young@INFN  
24/04/24



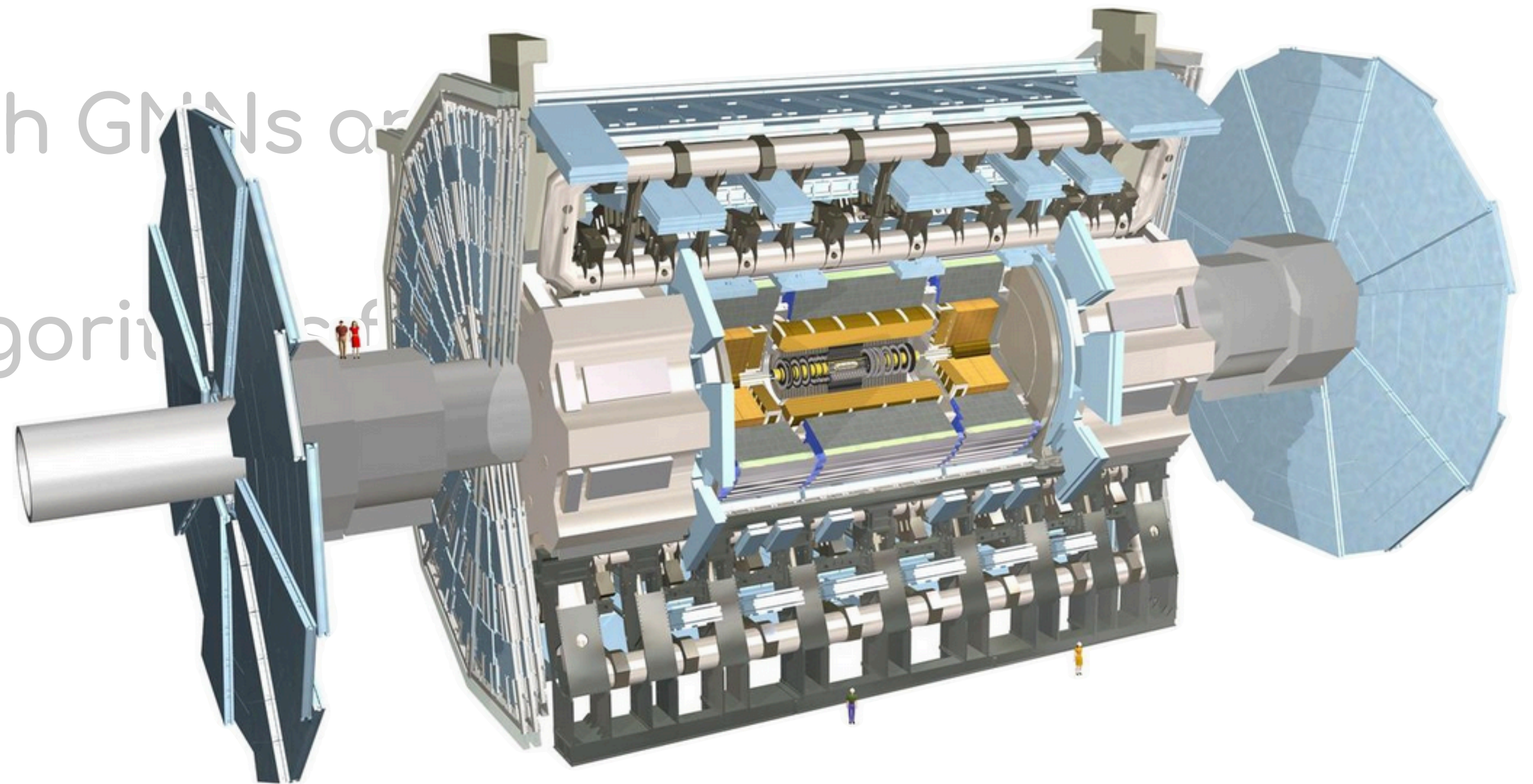
# Structure of the talk

1. Basics of collision experiments (ATLAS)
2. Anomaly Detection with GNNs analysis
3. CNN-based trigger algorithms for ATLAS upgrade



# Structure of the talk

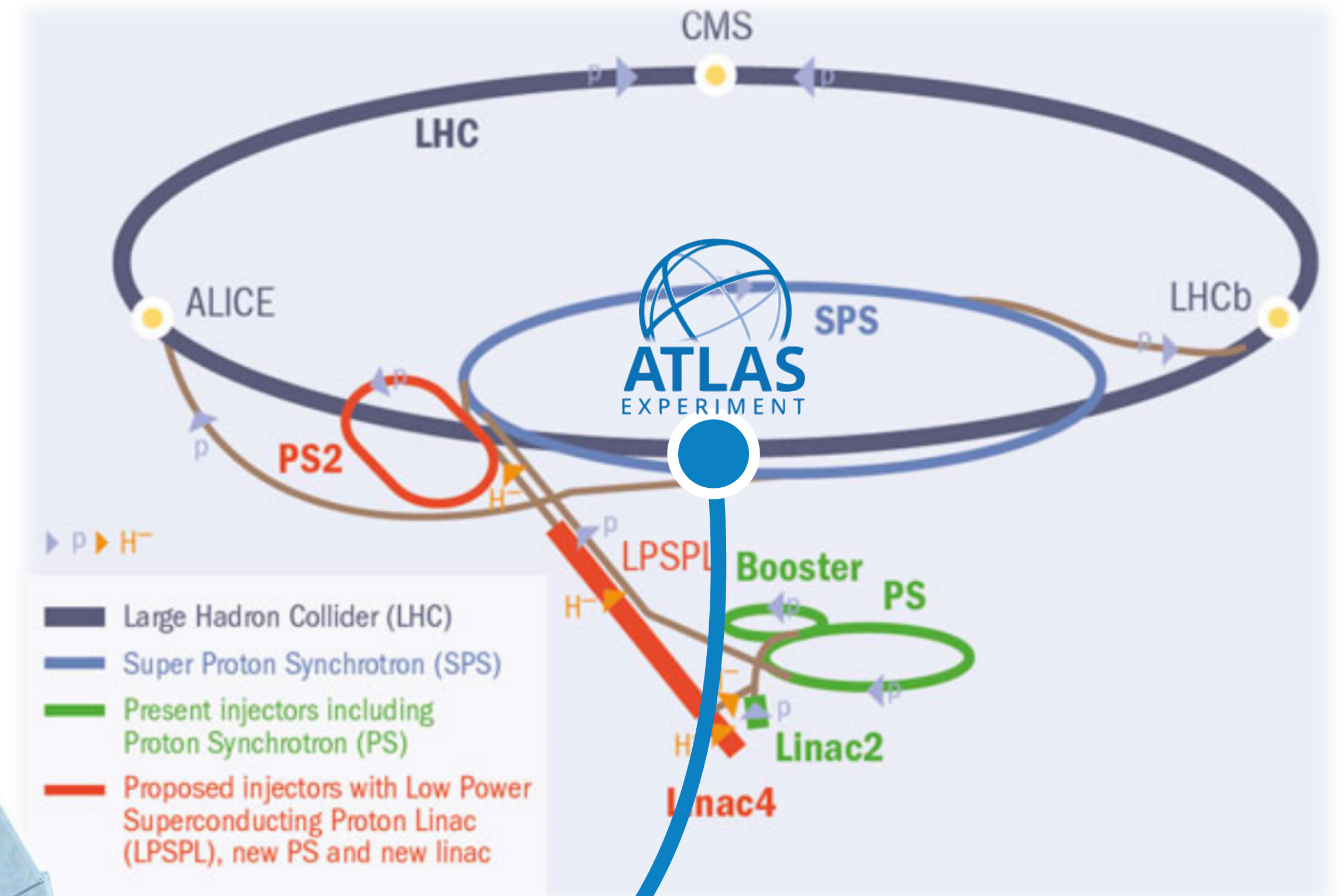
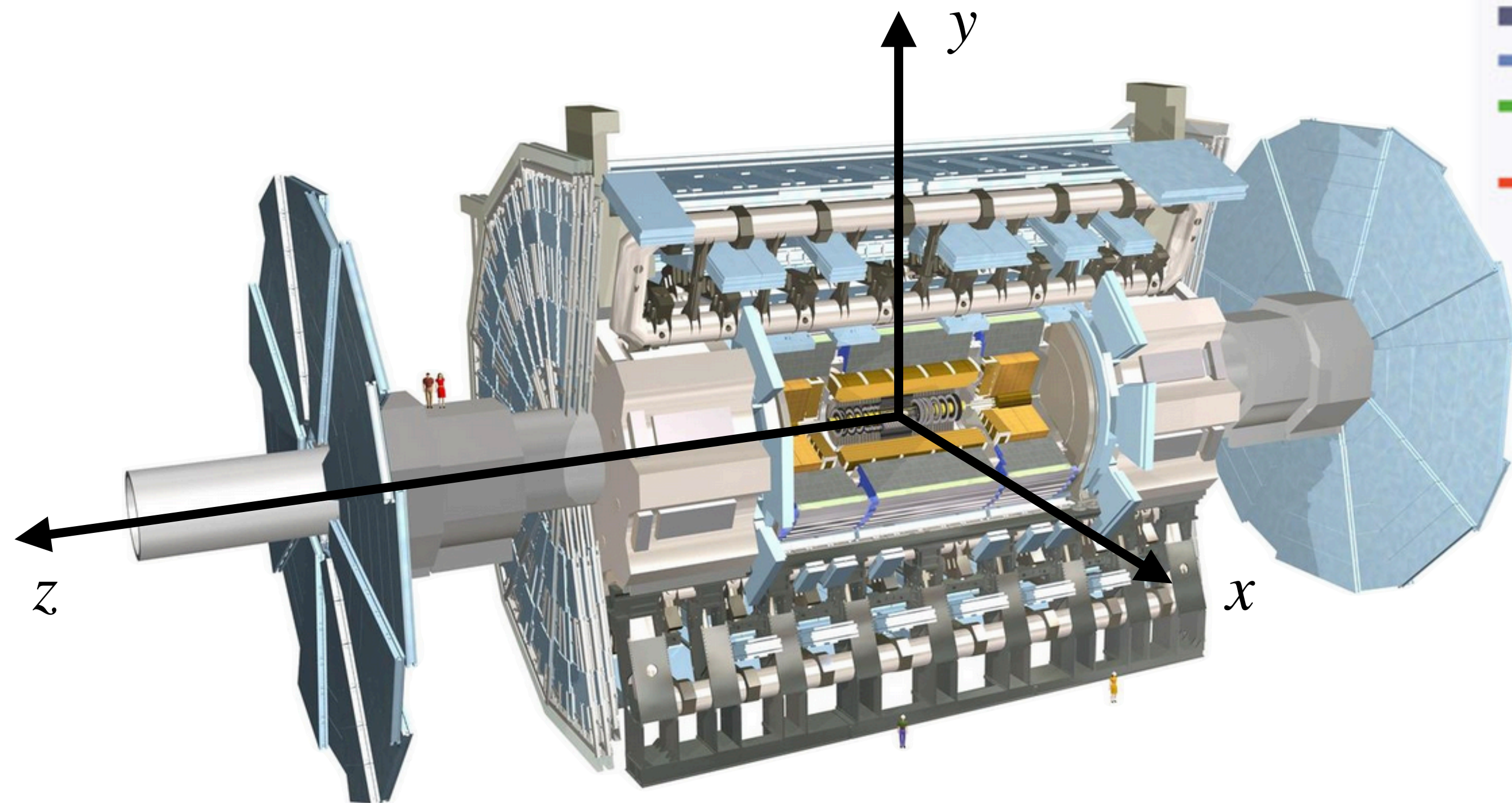
1. Basics of collision experiments (ATLAS)
2. Anomaly Detection with GNNs and GraphSAGE
3. CNN-based trigger algorithm





# LHC accelerator

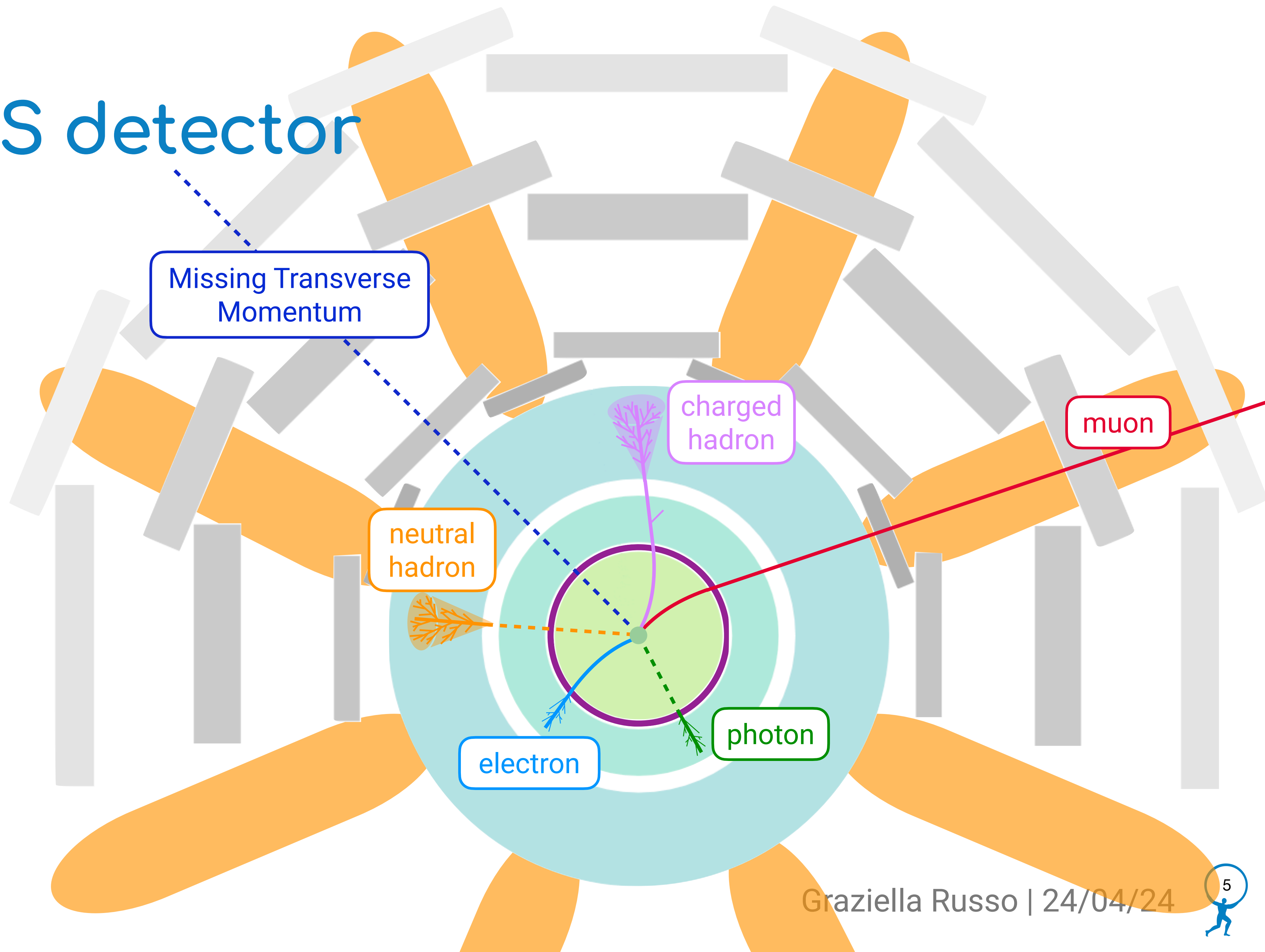
- LHC = Large Hadron Collider
- proton-proton collisions at  $\sqrt{s} = 13.6 \text{ TeV}$
- 4 interaction points  $\rightarrow$  4 experiments: **ATLAS**, CMS, Alice, LHCb





# The ATLAS detector

- Inner Detector
- solenoid magnet
- EM calorimeter
- Hadronic calorimeter
- Muon Spectrometer
- toroidal magnets





# The trigger system

$1.7 \cdot 10^9$  collisions  
every second @ LHC =  
60 TB per second

1 over 1M events  
are stored

## ATLAS trigger system

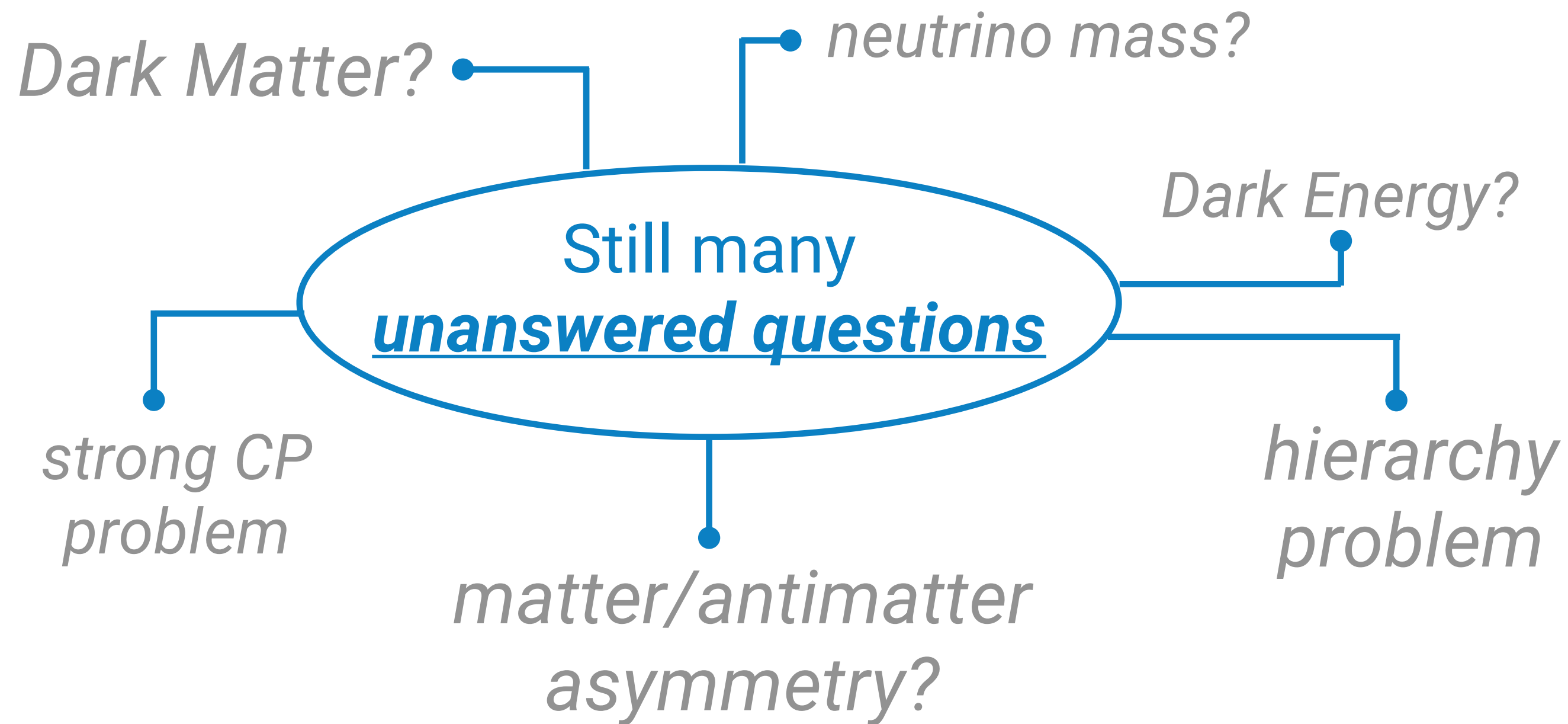
- **Level1**  
hardware trigger; only subset of detector are considered; 100k events accepted per second
- **High Level Trigger**  
software trigger; 1k events accepted per second






# Starting from the theory

- up to 2012 the Standard Model was not complete
- 2012: discovery of the Higgs boson 



	$\approx 2.2 \text{ MeV}/c^2$ $\frac{2}{3}$ $\frac{1}{2}$ <b>u</b> up	$\approx 1.28 \text{ GeV}/c^2$ $\frac{2}{3}$ $\frac{1}{2}$ <b>c</b> charm	$\approx 173.1 \text{ GeV}/c^2$ $\frac{2}{3}$ $\frac{1}{2}$ <b>t</b> top	0 0 1 <b>g</b> gluon	 SCALAR BOSONS	
QUARKS	$\approx 4.7 \text{ MeV}/c^2$ $-\frac{1}{3}$ $\frac{1}{2}$ <b>d</b> down	$\approx 96 \text{ MeV}/c^2$ $-\frac{1}{3}$ $\frac{1}{2}$ <b>s</b> strange	$\approx 4.18 \text{ GeV}/c^2$ $-\frac{1}{3}$ $\frac{1}{2}$ <b>b</b> bottom	0 0 1 <b><math>\gamma</math></b> photon		
	$\approx 0.511 \text{ MeV}/c^2$ -1 $\frac{1}{2}$ <b>e</b> electron	$\approx 105.66 \text{ MeV}/c^2$ -1 $\frac{1}{2}$ <b><math>\mu</math></b> muon	$\approx 1.7768 \text{ GeV}/c^2$ -1 $\frac{1}{2}$ <b><math>\tau</math></b> tau	$\approx 91.19 \text{ GeV}/c^2$ 0 1 <b>Z</b> Z boson		GAUGE BOSONS VECTOR BOSONS
	$< 1.0 \text{ eV}/c^2$ 0 $\frac{1}{2}$ <b><math>\nu_e</math></b> electron neutrino	$< 0.17 \text{ MeV}/c^2$ 0 $\frac{1}{2}$ <b><math>\nu_\mu</math></b> muon neutrino	$< 18.2 \text{ MeV}/c^2$ 0 $\frac{1}{2}$ <b><math>\nu_\tau</math></b> tau neutrino	$\approx 80.433 \text{ GeV}/c^2$ $\pm 1$ 1 <b>W</b> W boson		

# Where is New Physics?

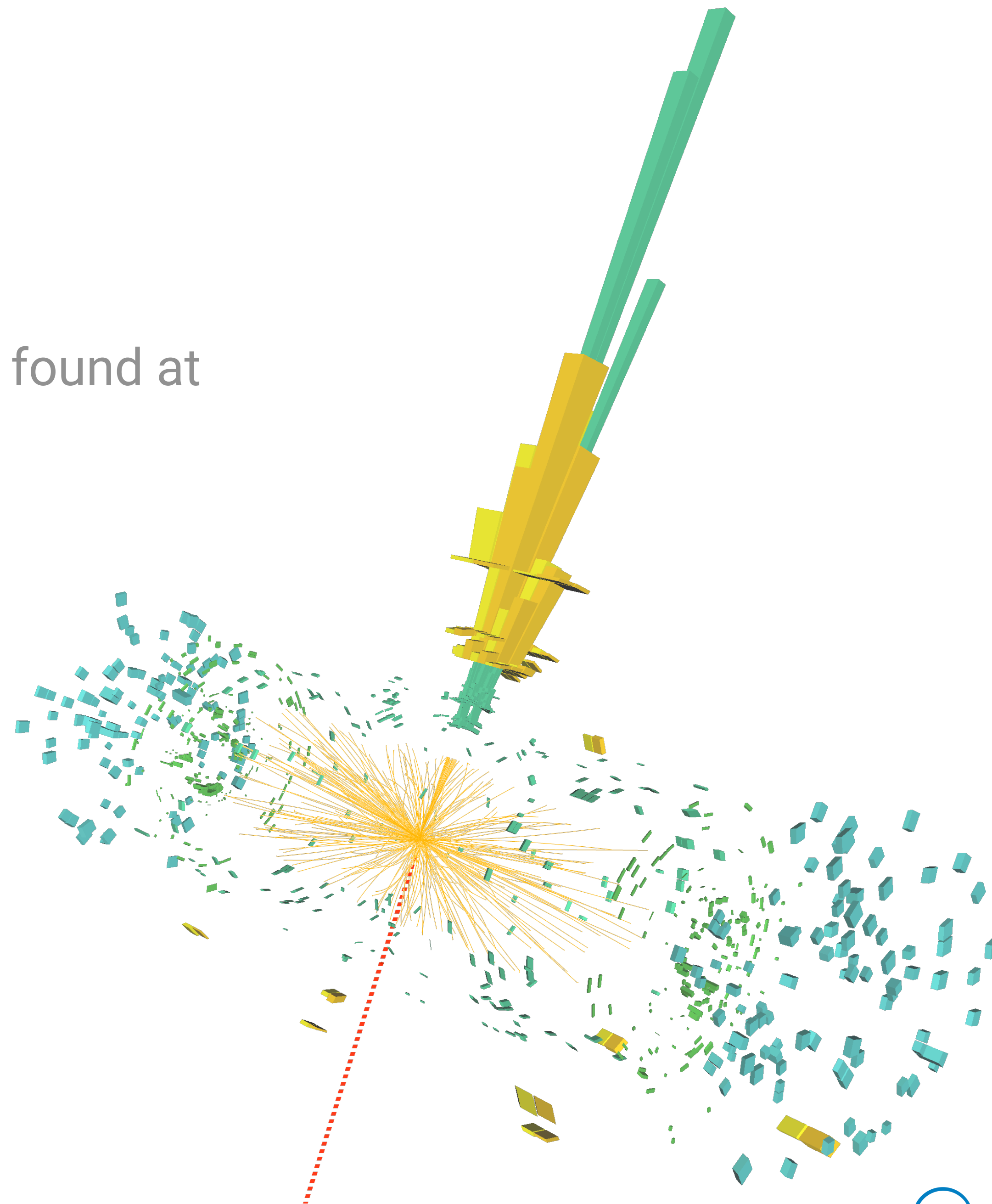
from 2012 no evidence of New Physics (NP) has been found at LHC experiments

## @ analysis level:

are we looking at the right discriminating variable?

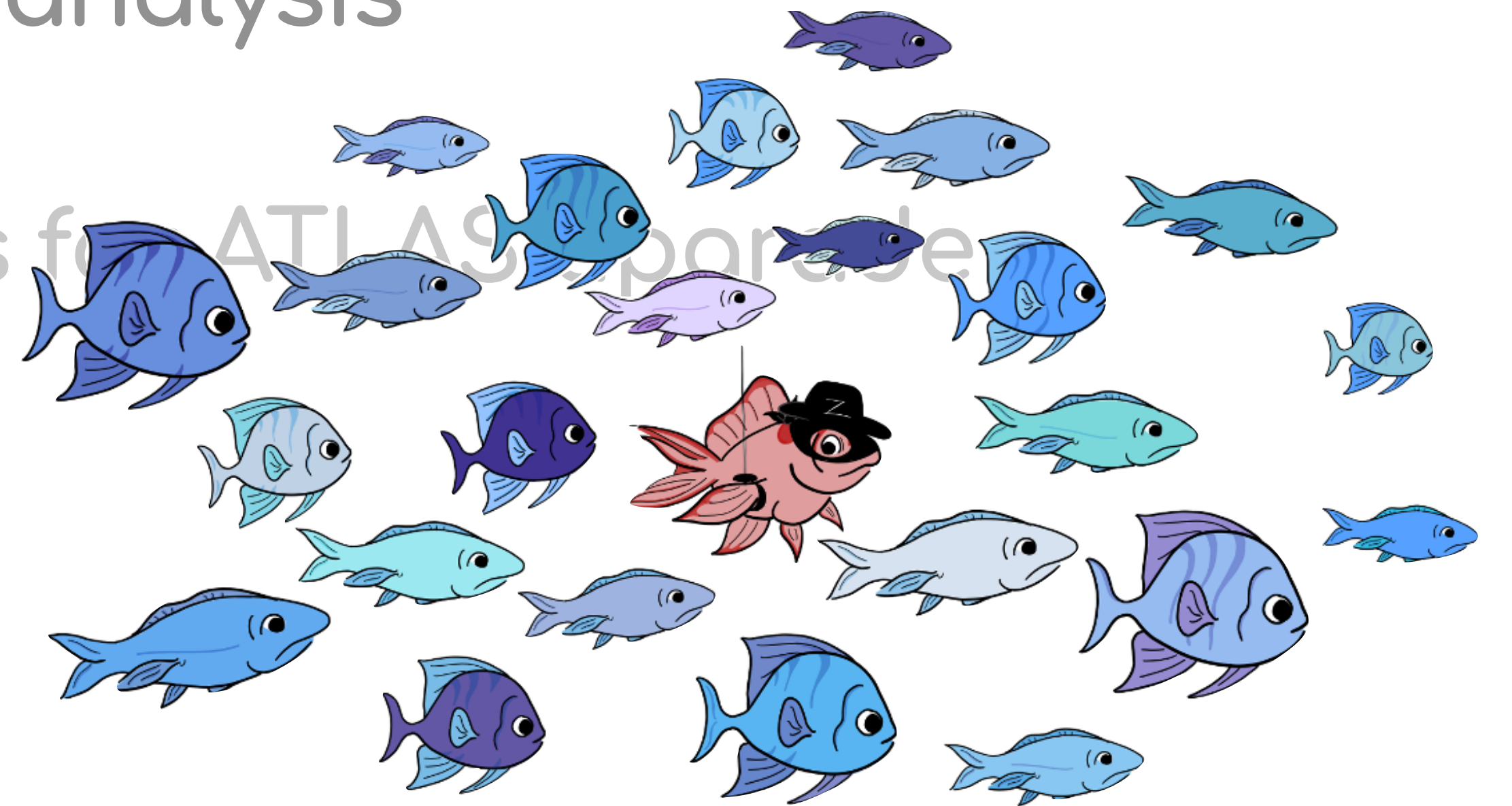
## @ trigger level:

are we storing all the interesting events and not discarding Beyond the Standard Model (BSM) events?



# Structure of the talk

1. Basics of collision experiments (ATLAS)
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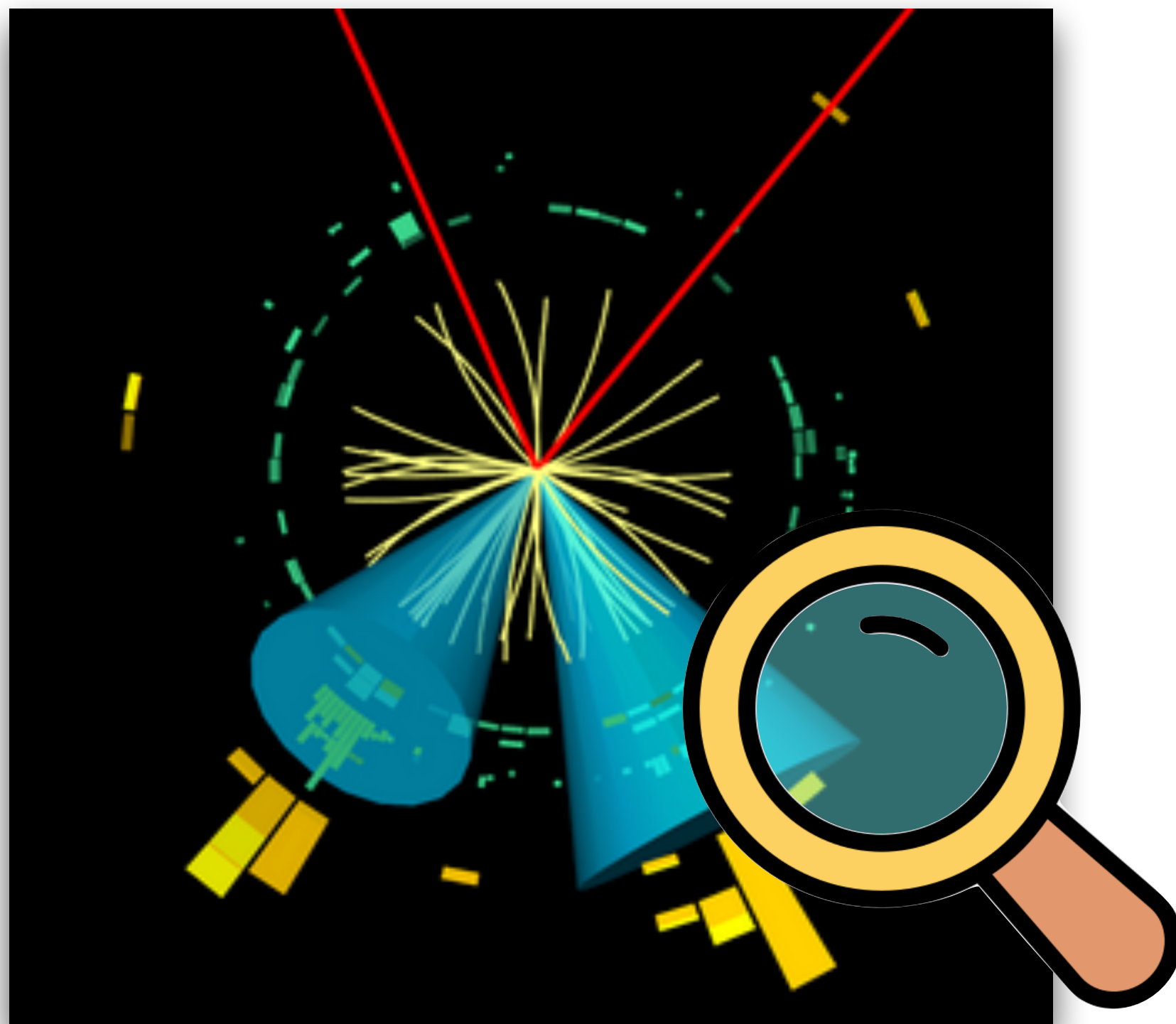
# The idea behind

NP should consist in a *small deviation* from Standard Model data, otherwise we would have seen it before



**Anomaly Detection (AD)** is an AI technique to identify anomalous behaviours among established, standard patterns. AD does not require a specific theoretical model, it looks directly on data

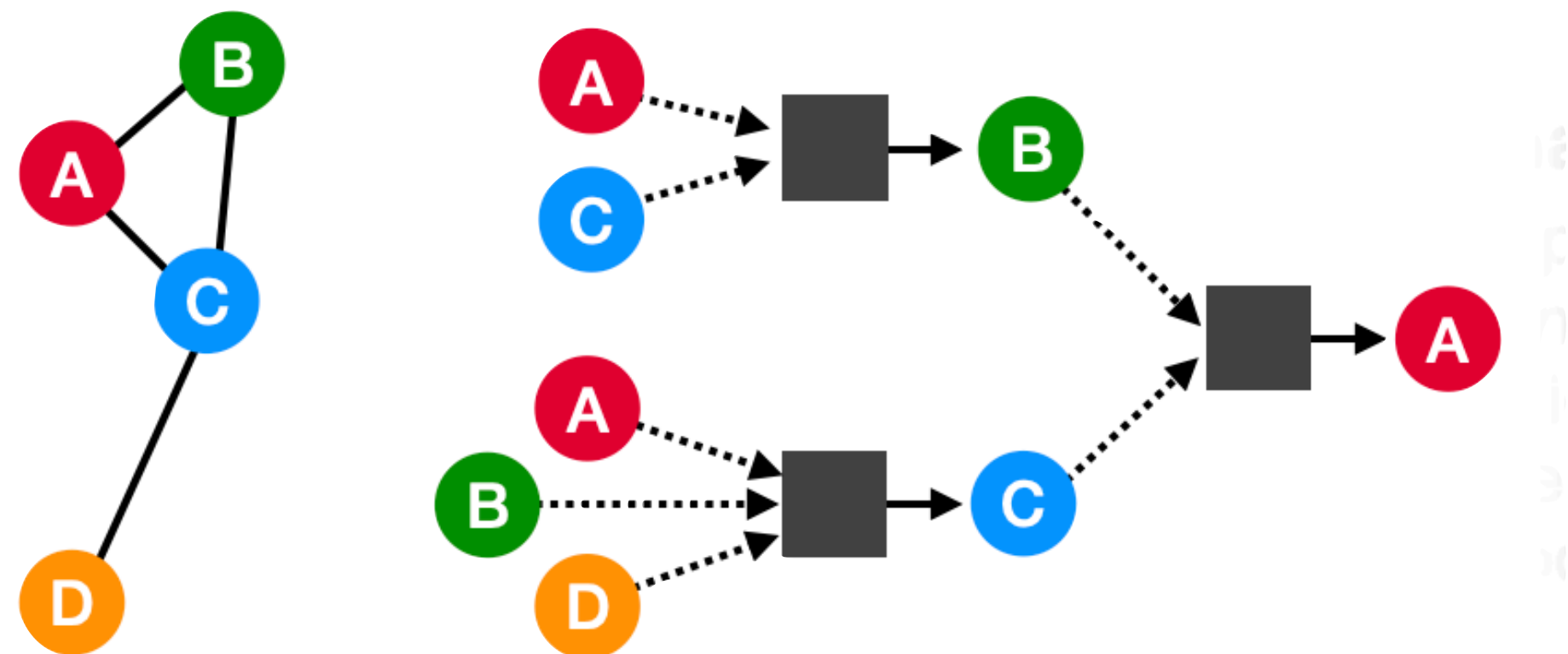
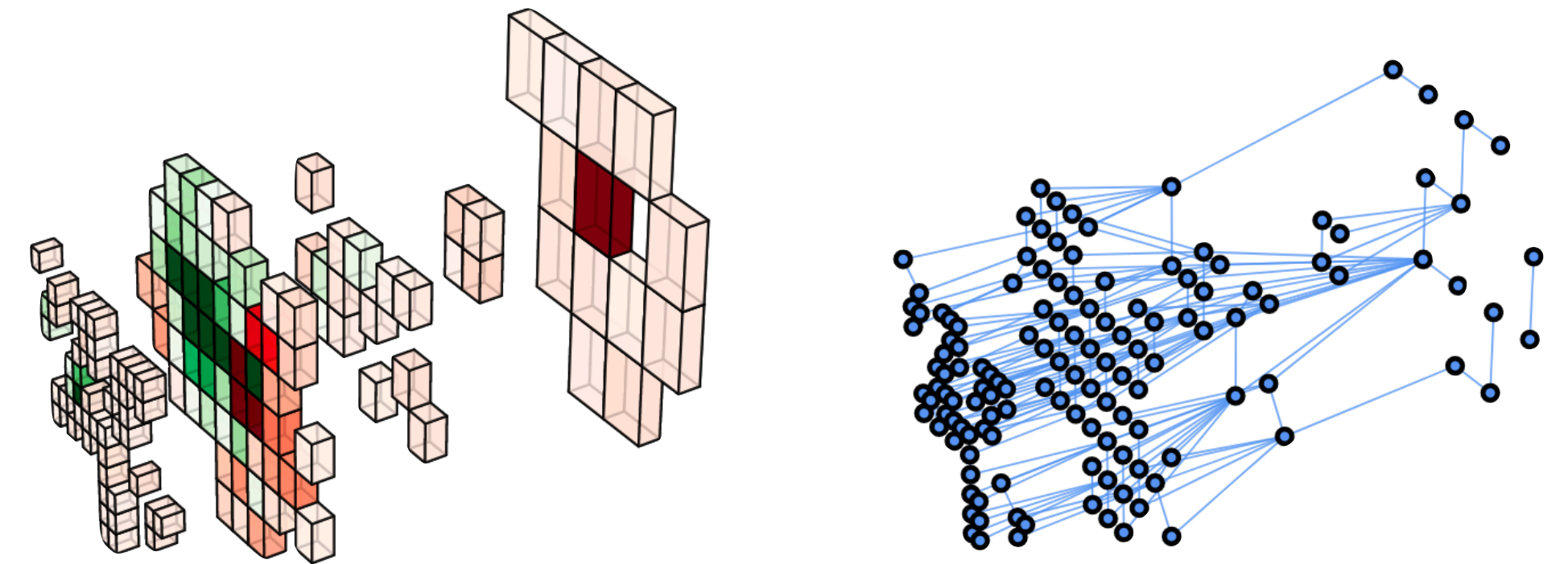
**Jets** have very complex substructure that can potentially hide NP





# Graph Neural Networks (GNNs)

- GNN is any ML algorithm that handles graph structured data
- **message passing** is a useful way to embed the information from the neighbouring nodes



jets have very sparse structure, suitable for graph representation

# Jets and graphs

A graph is a set of points (**nodes**) that can be connected by **edges**

- **what is a node?**

- each constituent is a node
- node features:  $p_T frac, \eta, \phi$

- **when are nodes connected?**

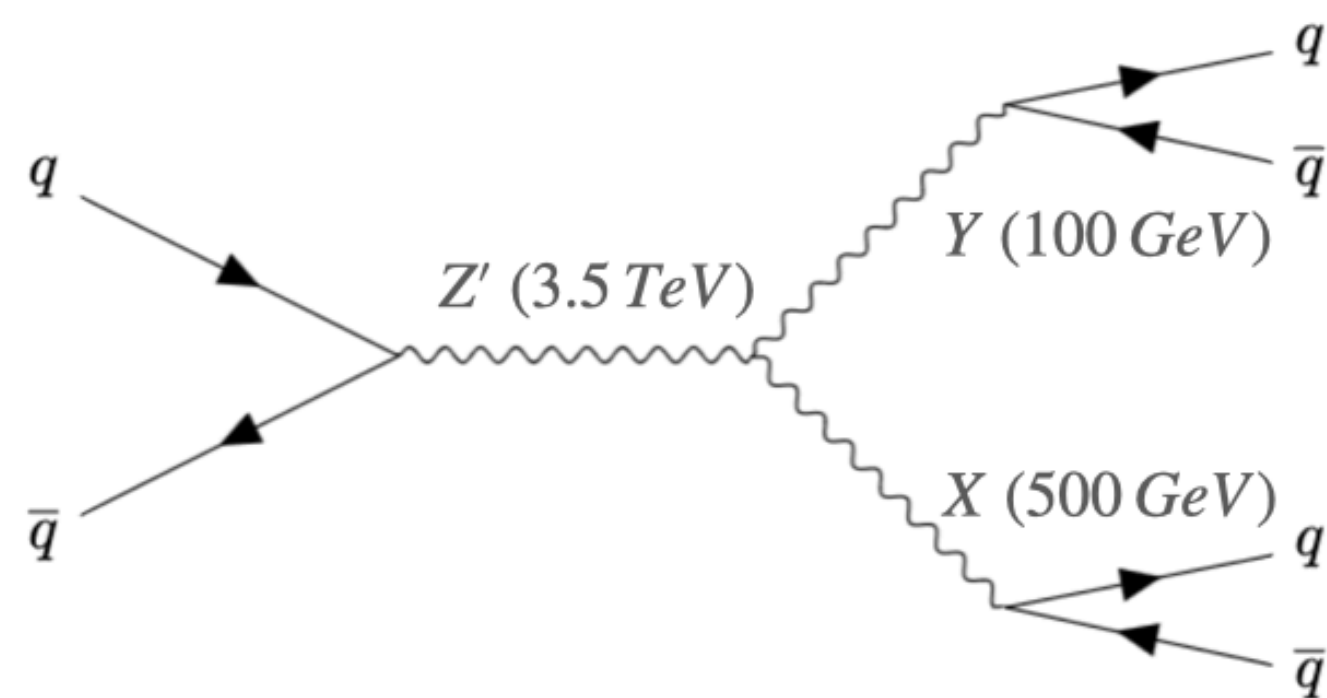
- edge features  $\frac{1}{\Delta R(const_i, const_j)}$
- distance-based

## **Transformation** applied for data augmentation and model robustness reasons

- ML algorithms rely a lot on the mass of the signature used in training, need to decorrelate AD score from S/B discriminants, e.g. mass
- rescaling of the four momenta ( $m_{jet} = m_0 = 0.25 GeV$ )
- boost so that  $E_{jet} = E_0 = 1 GeV$
- further rotation of constituents along jet axis

## toy model

- R&D [LHC Olympics](#) dataset
  - $Z' \longrightarrow XY \longrightarrow qqqq$  events
  - $m_{Z'} = 3.5 \text{ TeV}, m_X = 500 \text{ GeV}, m_Y = 100 \text{ GeV}$
  - reconstructed as large radius jets



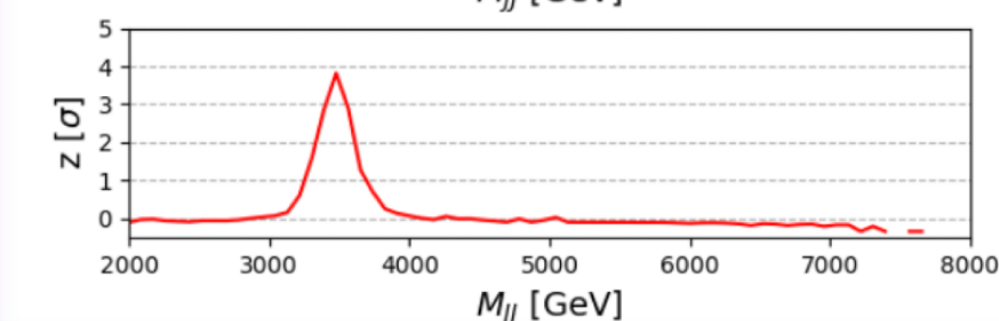
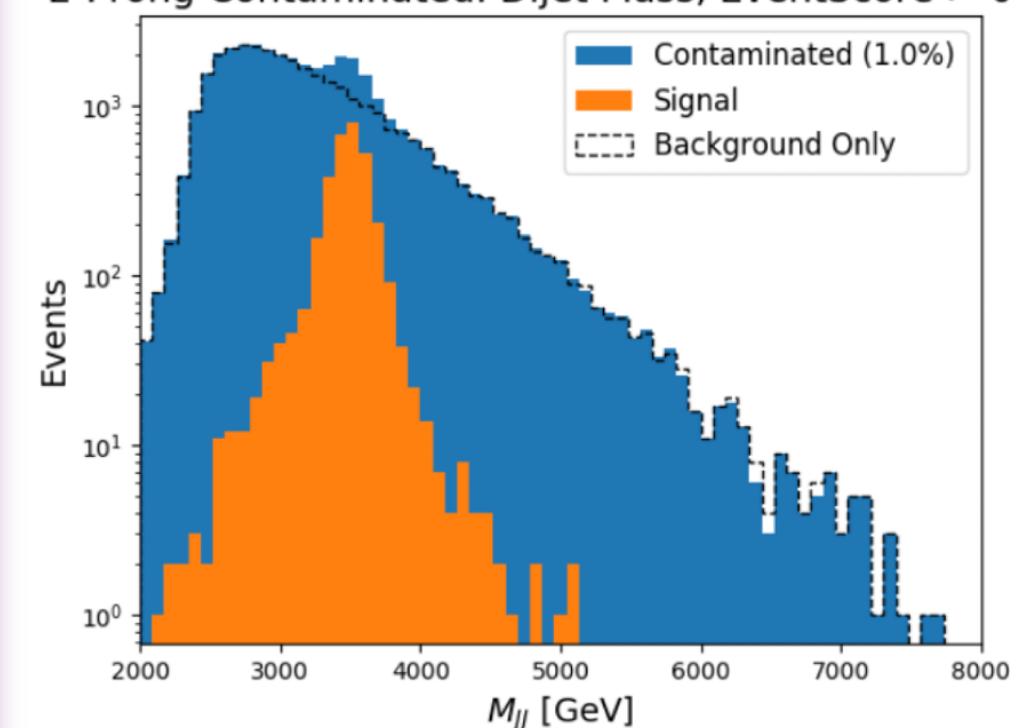
## benchmarks

- ML tasks
  - output (jet-level) can be used to build event-level Anomaly Score (AS)
  - trained both supervised and unsupervised models
- to test the models, apply to benchmark physics
  - test on data for W boson rediscovery

## final goal

- Run3 di-jet fully hadronic search
  - completely model agnostic
  - 2 large-R jets
  - event selection based on AS cut
  - data-driven background estimation
  - bump hunt/framework fit for the AS distribution

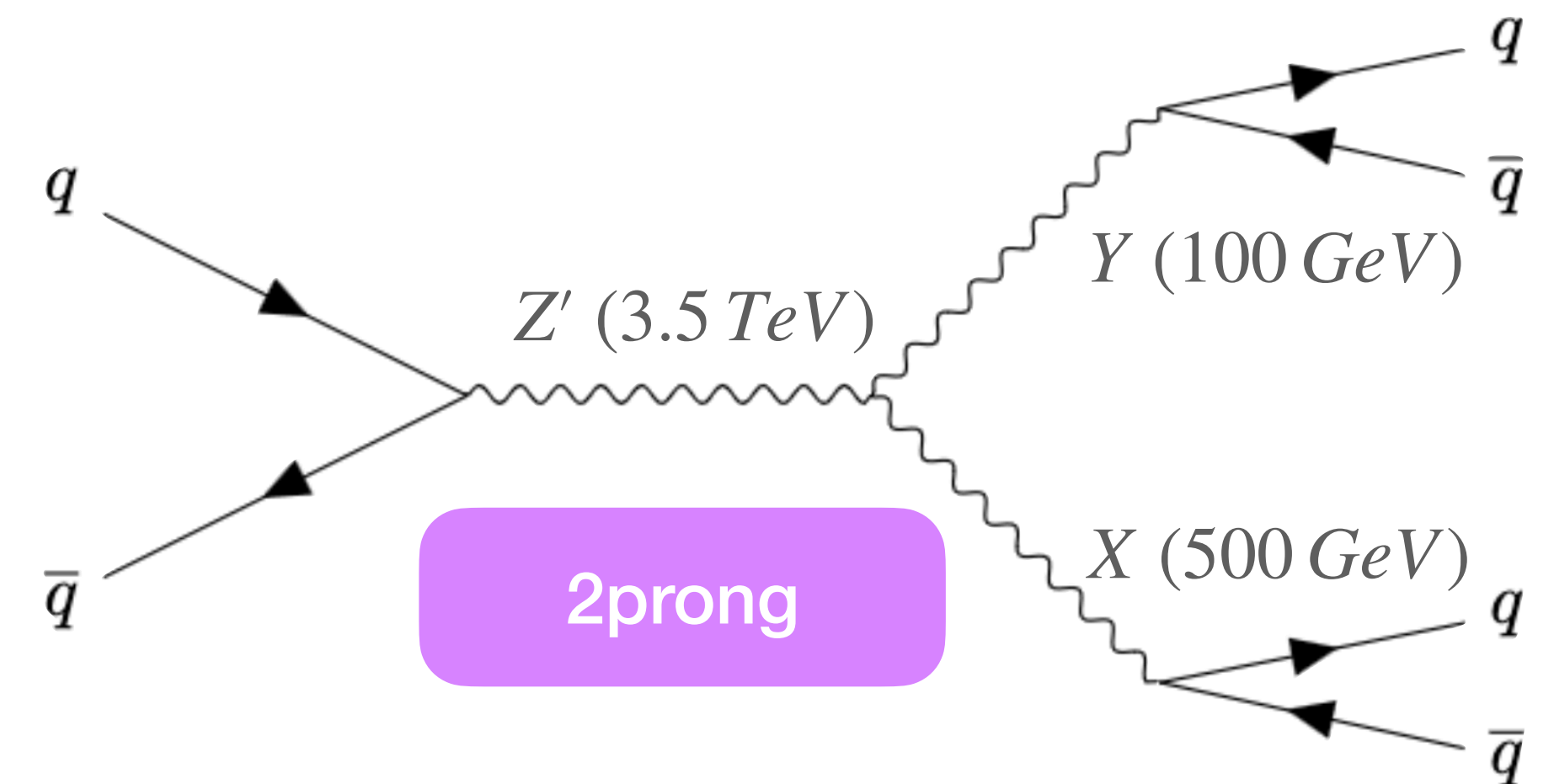
2-Prong Contaminated: Dijet Mass, EventScore > 0.65



# ML dataset and models

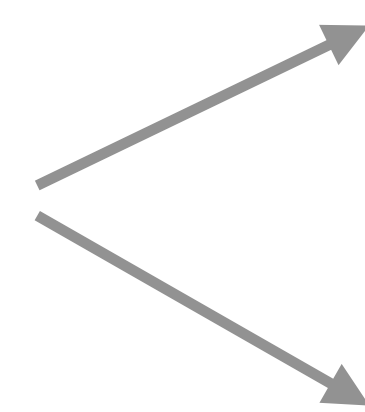
LHC Olympics dataset contains:

- 1M QCD events (background) + 100k signal events
- **Event** = up to 2 large R jets
- **Jet** = up to 50 constituents
- **Constituent** =  $[p_T \text{ frac}, \eta, \phi]$ , distance-based edges



Transformer

Graph Neural Networks



Graph Isomorphism Network ([GIN](#)) layer

Edge Graph Attention Transformer ([EGAT](#)) layer



# GNN trainings

## jet-level AD = model loss

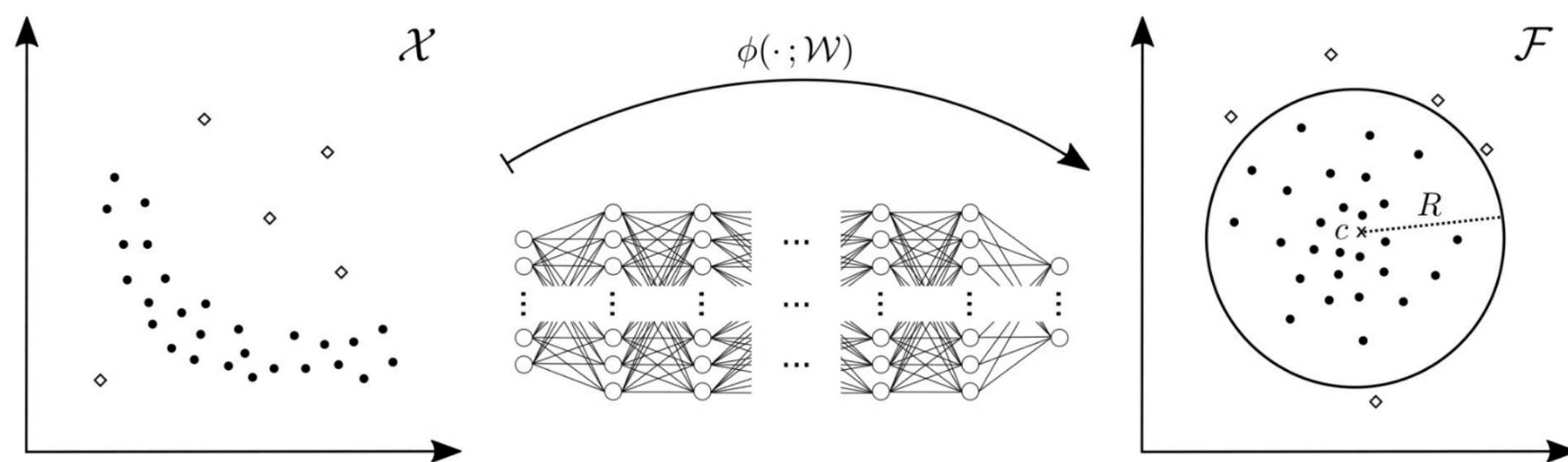
- using the DeepSVDD unsupervised loss
- optimizing the radius of hypersphere in the hidden representation space to contain all standard events

objective

$$\min_W \frac{1}{N} \sum_{i=1}^N \|\text{GIN}(G_i; W) - c\|^2 + \frac{\lambda}{2} \sum_{l=1}^L \|W^l\|_F^2 \quad W = \{W^1, \dots, W^L\}$$

$$s(\mathbf{x}) = \|\phi(\mathbf{x}; \mathcal{W}^*) - c\|^2$$

**Anomaly Score**



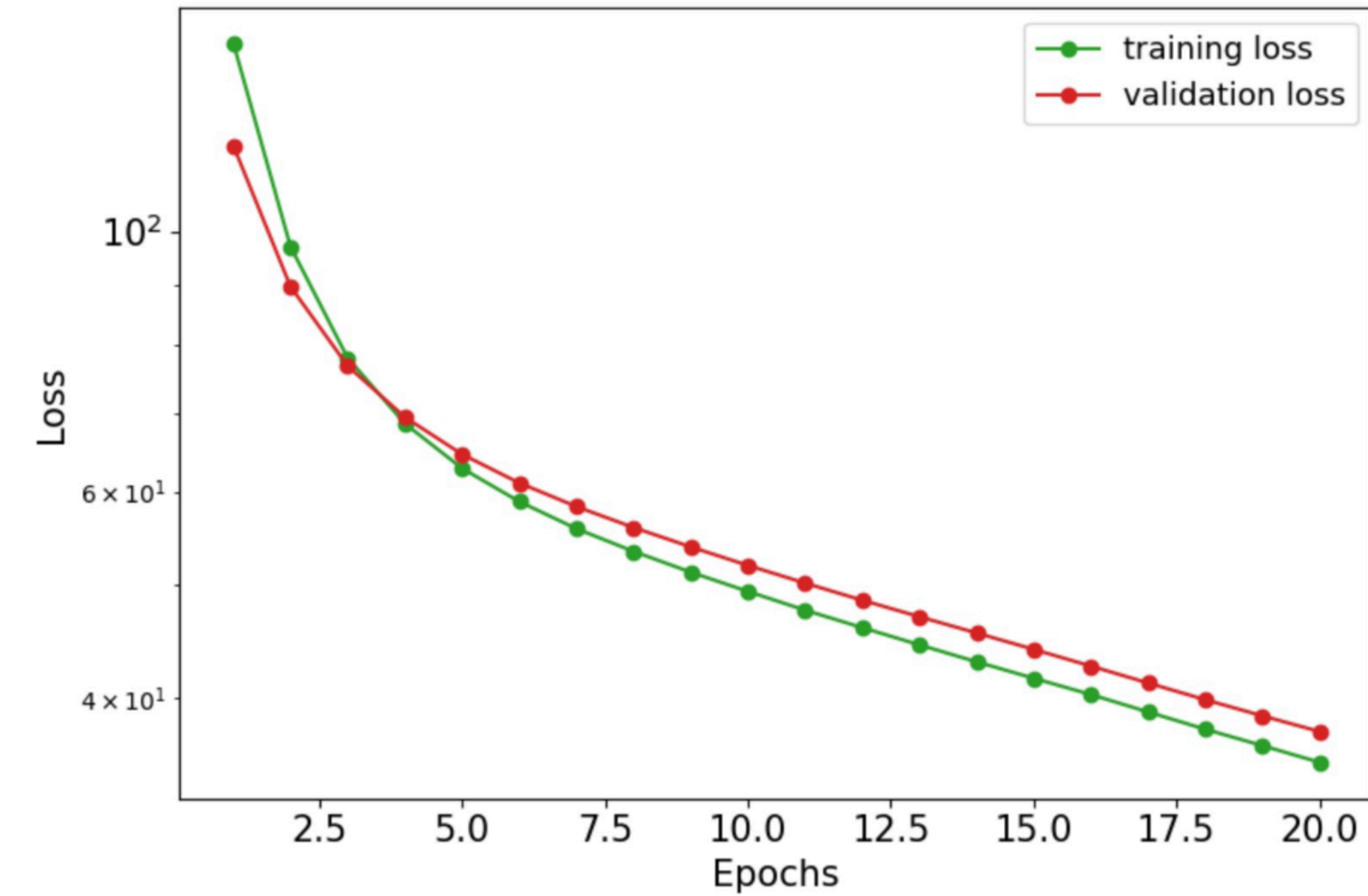
**supervised** = trained on balanced dataset with signal and background  
**unsupervised** = trained only on background events

## event-level AD strategy:

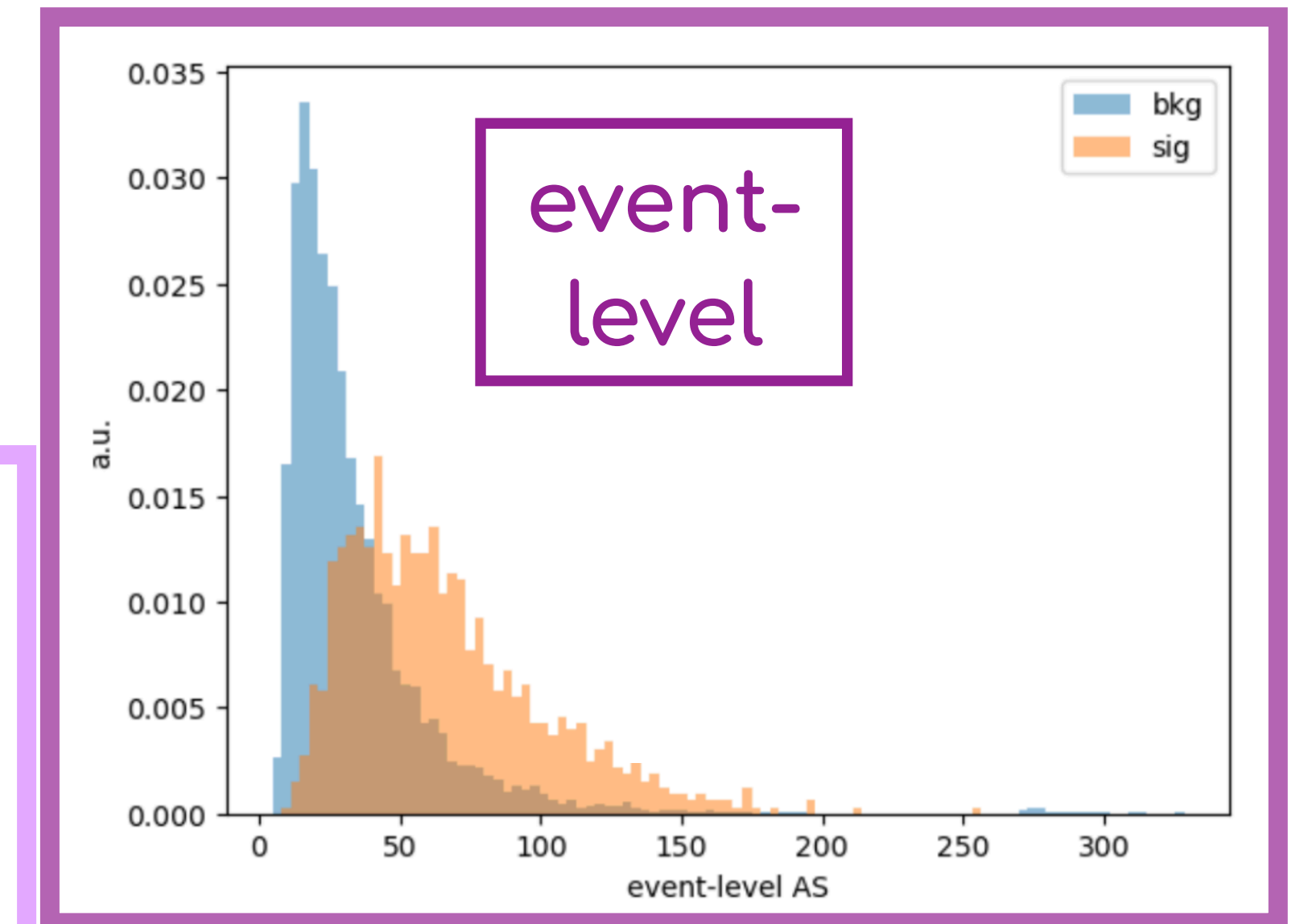
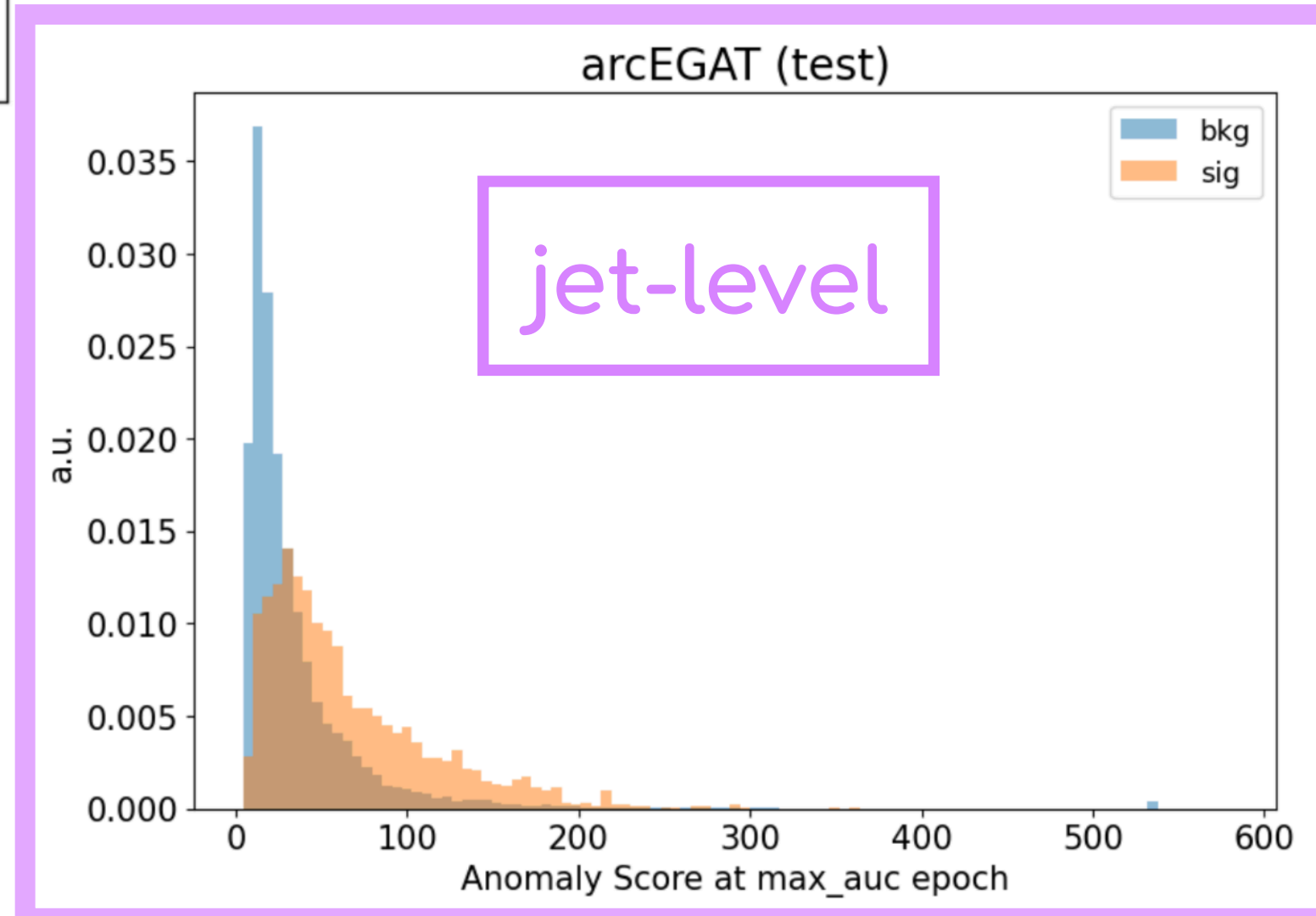
- possibility of recombining the AS of each jet of the event
- sum of the AS of single jets

# UNsupervised EGAT training





Train and validation loss VS epochs  
arcEGAT







- more stable training, no overtraining reached
- AUC jet-level: **75.5%**
- AUC event-level: **81.8%**



# Model summary

Model	Transformer supervised	GIN supervised	EGAT supervised	Transformer <i>unsupervised</i>	GIN <i>unsupervised</i>	EGAT <i>unsupervised</i>
loss	CrossEntropy	CrossEntropy	CrossEntropy	MSE	DeepSVDD	DeepSVDD
AUC jet-level 2prong	91.3%	90.2%	89.9%	75.5%	73.7%	75.5%
AUC event-level 2prong		96.5%	96.5%		79.6%	81.8%
AUC jet-level 3prong	86.8%	75.5%	84.8%	69.1%	52.6%	67.2%
AUC event-level 3prong		84.1%	92.4%		54%	74.3%

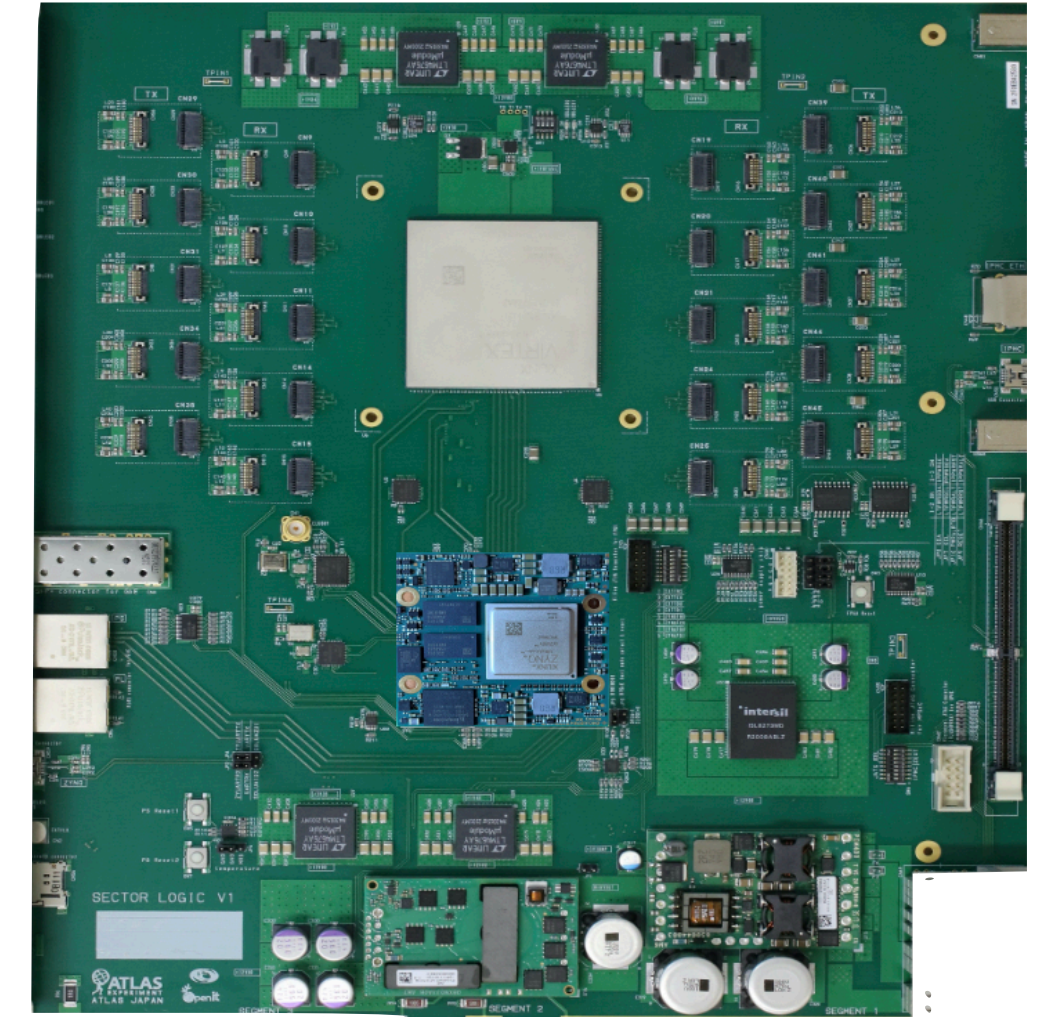
# Model summary

Model	Transformer supervised	GIN supervised	EGAT supervised	Transformer <i>unsupervised</i>	GIN <i>unsupervised</i>	EGAT <i>unsupervised</i>
loss	CrossEntropy	CrossEntropy	CrossEntropy	MSE	DeepSVDD	DeepSVDD
AUC jet-level 2prong	91.3%	90.2%	89.9%	75.5%	73.7%	75.5%
AUC event-level 2prong		96.5%	96.5%		79.6%	81.8%
AUC jet-level 3prong	86.8%	75.5%	84.8%	69.1%	52.6%	67.2%
AUC event-level 3prong		84.1%	92.4%		54%	74.3%



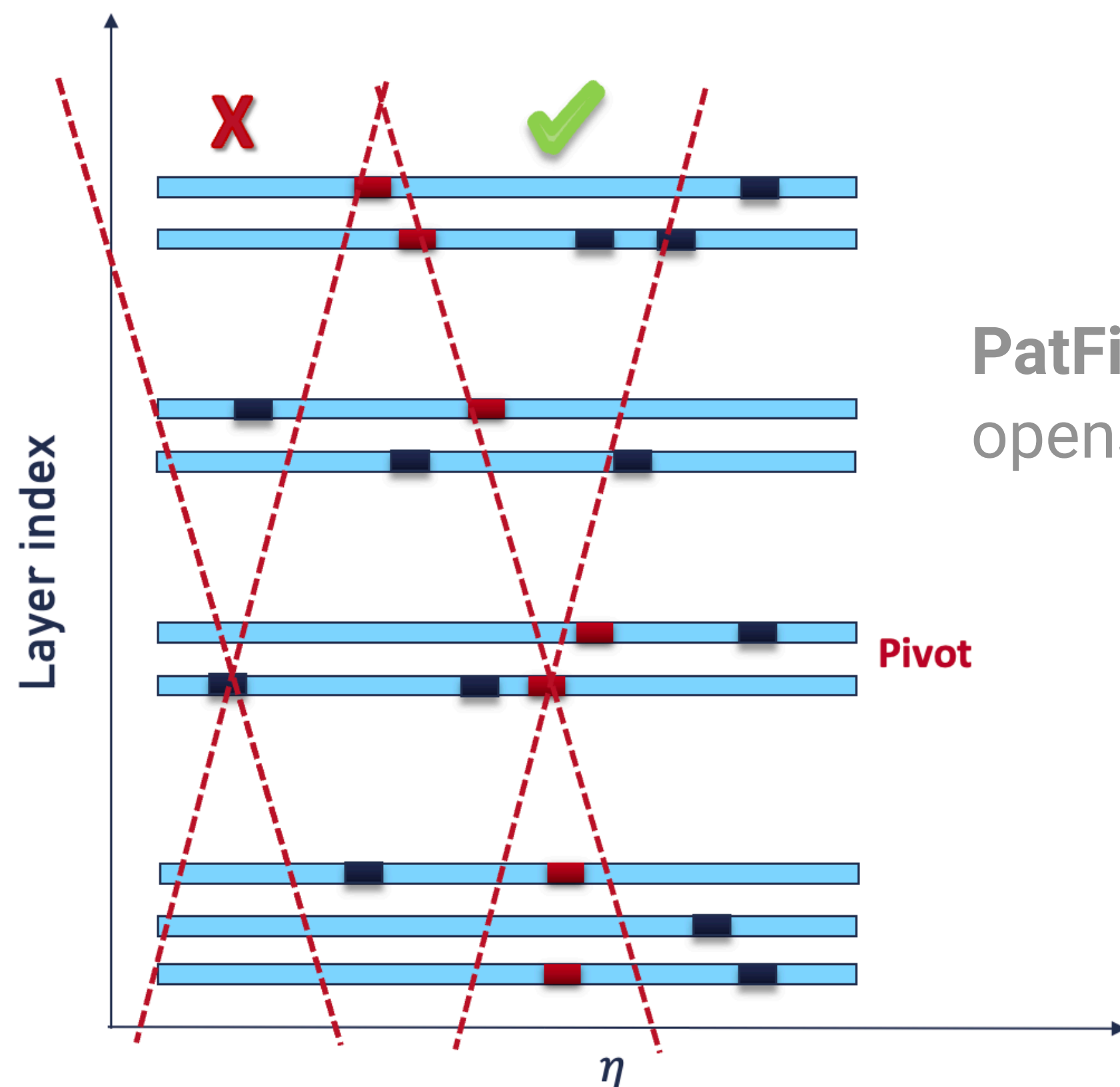
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# L0 muon trigger

- based on 3 stations, 6 layers of Resistive Plate Chambers (RPCs)
- Phase II upgrade (2026-29): **additional RPC inner station** (4 stations, 9 layers) + Field Programmable Gate Array (**FPGA**)-based **sector logic** for fast inference  $o(100 \text{ ns})$

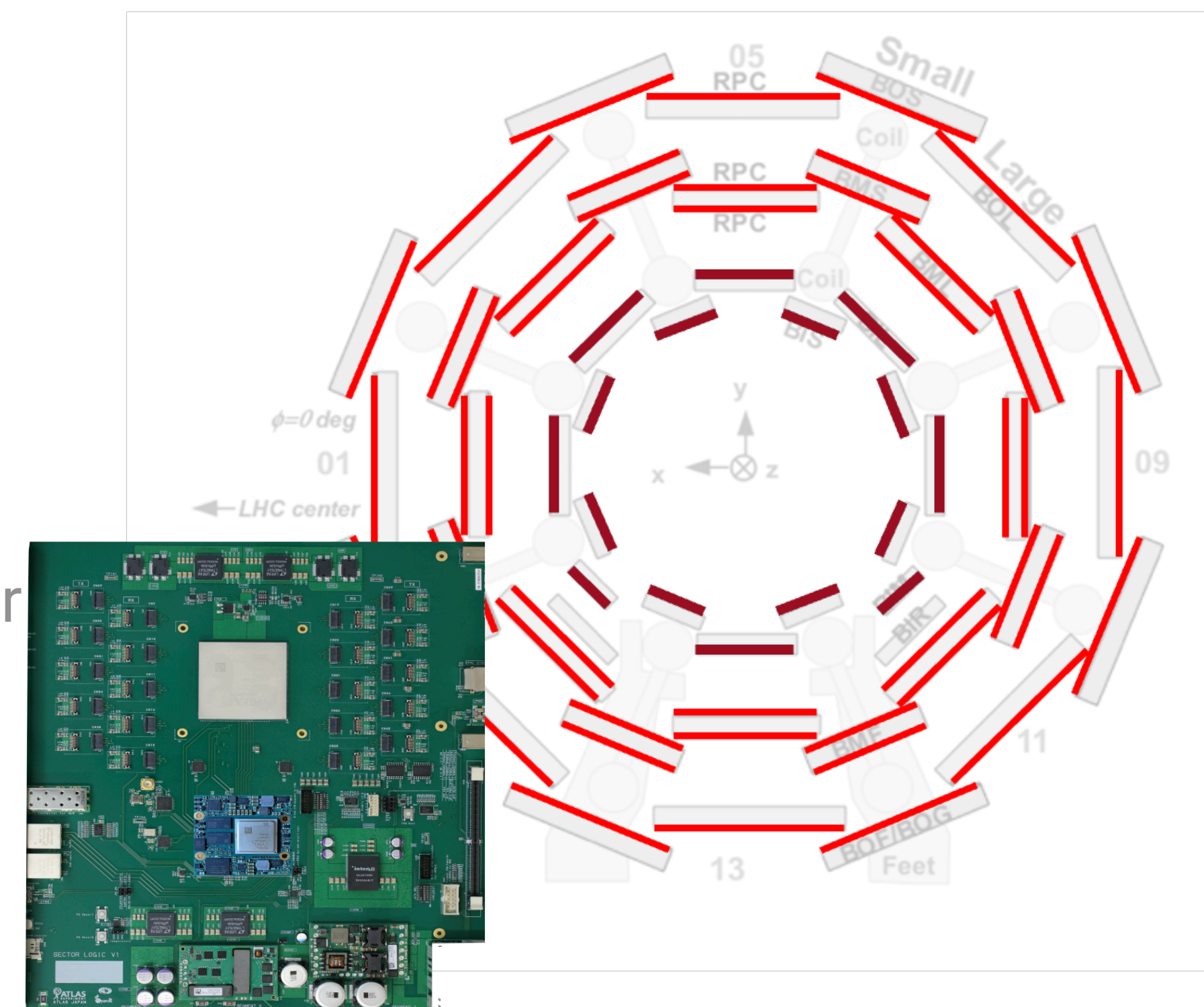


PatFinder, the traditional algorithm

opens  $p_T$ -dependent  $\eta$  and  $\phi$  windows and searches for a muon pattern

**BUT** relies on detector geometry!

- efficiency saturation
- windows fine tuning
- primary vertex muons only
- partial tracks?

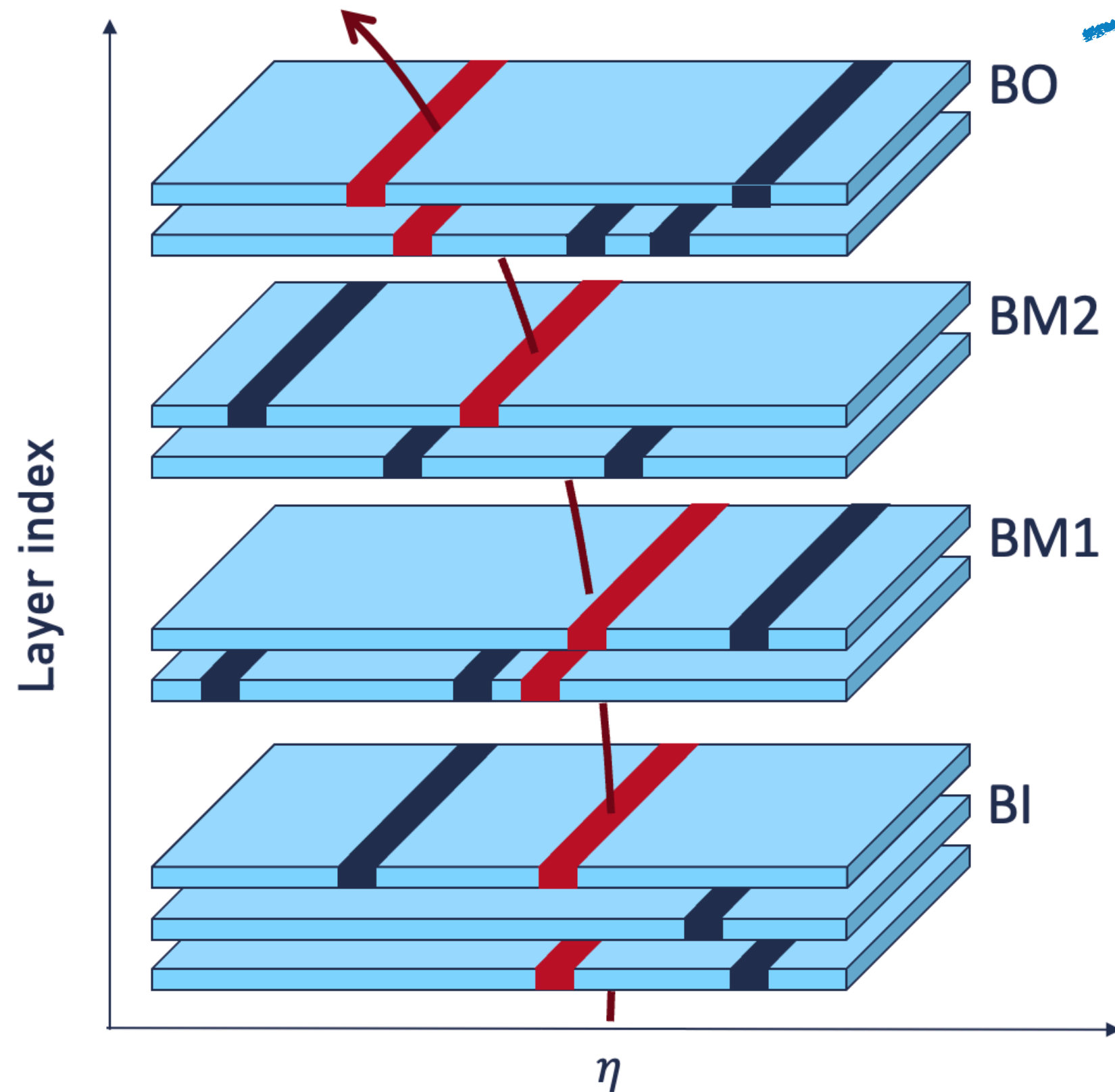




# ML approach

**Trick:** muon track reinterpreted as a black-and-white image

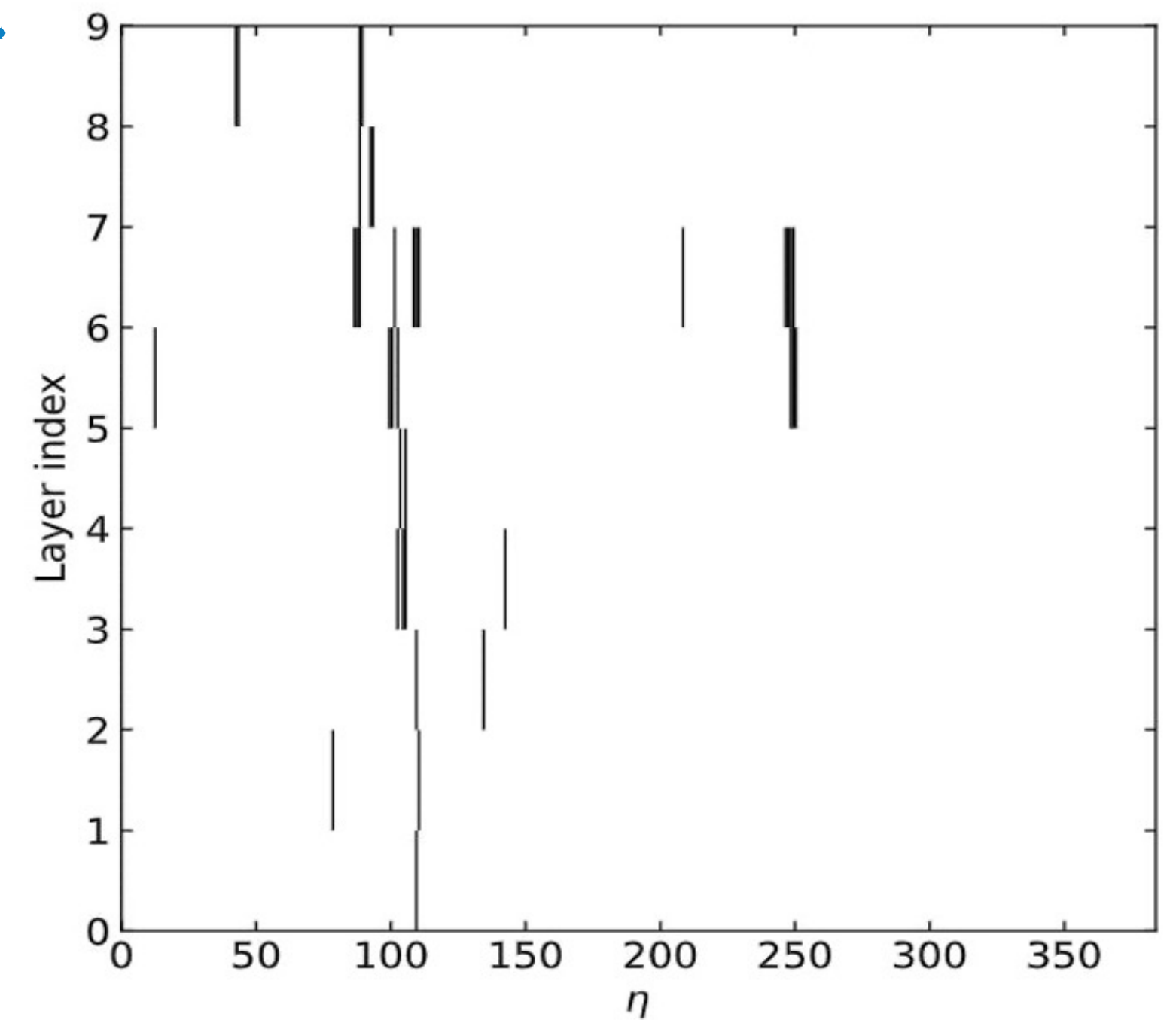
and used for a Convolutional Neural Network (CNN)



Dataset of  $\sim 200k$  images with:

- random noise-only hits
- single muon tracks ( $p_T \in [2.5, 20]$  GeV) + noise hits

Target label:  
 $p_T, \eta, (q)$

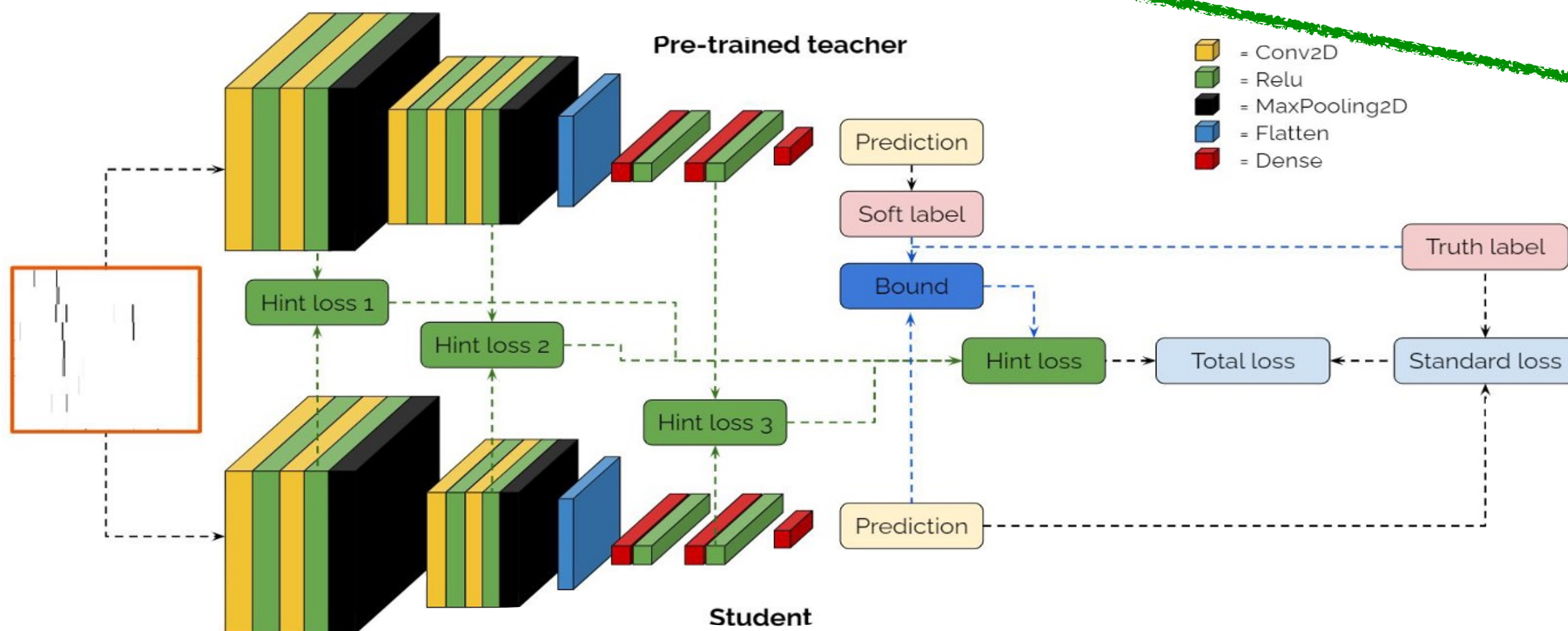


# Compression techniques

## Experimental requirements

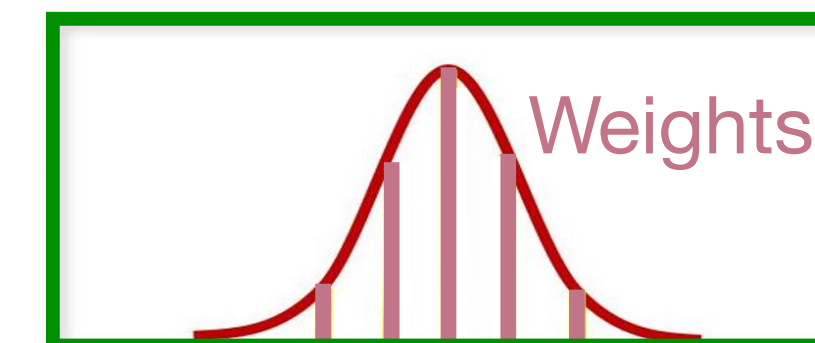
- Fit within the Virtex UltraScale+ 13 FPGA resources;
- Maximum latency (= time interval of algorithmic response) allowed of  $\sim 400$  ns;
- Fake efficiency (= trigger efficiency on noisy events)  $< 2\%$

Train a CNN model (VGG-like)  
+ help from compression techniques



## Quantization

QKeras



## Knowledge Distillation

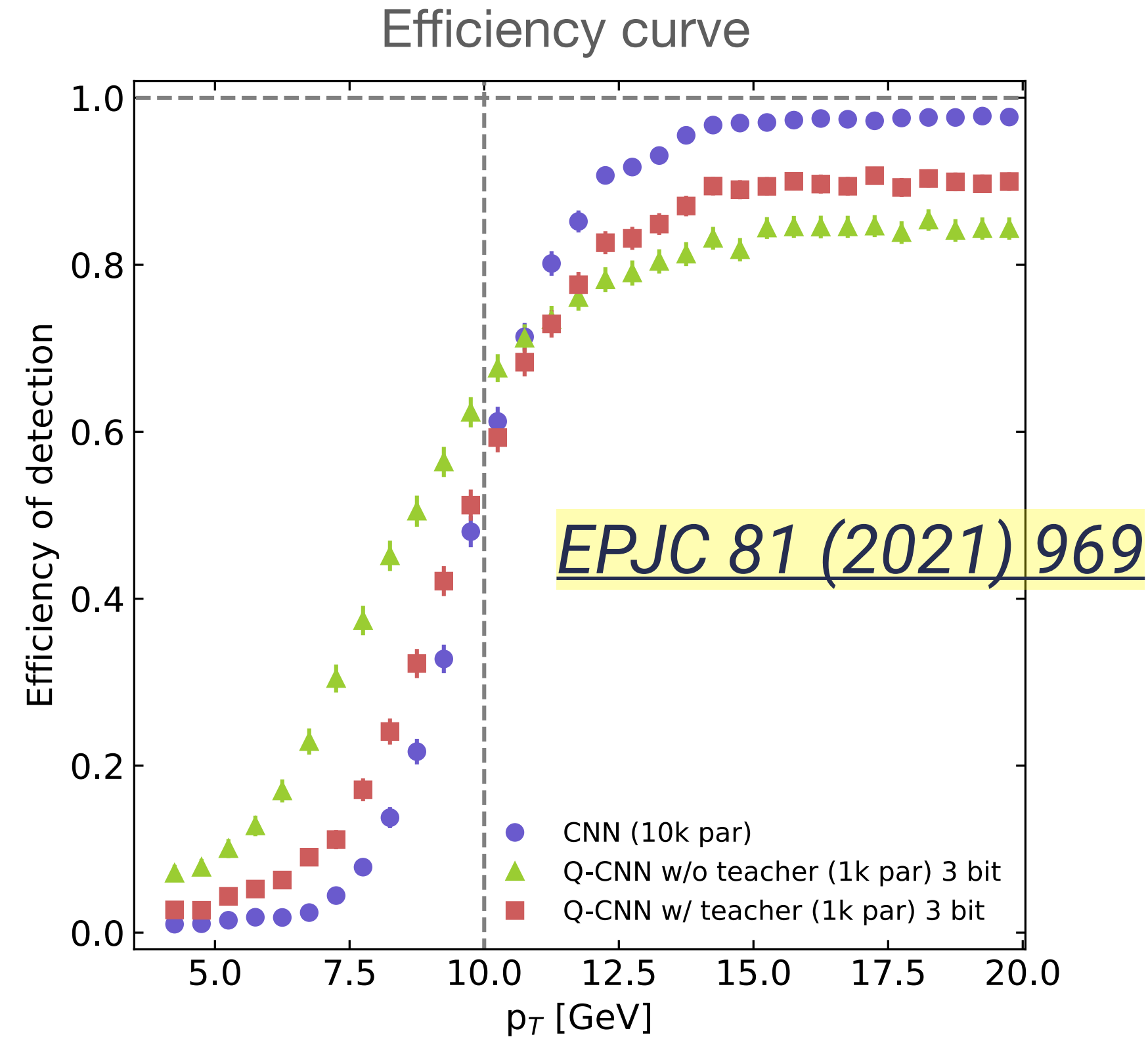
[arXiv:1711.05852](https://arxiv.org/abs/1711.05852)

[arXiv:1804.03235](https://arxiv.org/abs/1804.03235)

# Single muon results

ultra-small CNN models  
~700 parameters

synthesis on XCV13P FPGA performed by using [HLS4ML](#) library and by-hand VHDL implementation



	GPU Tesla V100	FPGA XCV13P with hls4ml	FPGA XCV13P with VHDL implementation
Latency	5 ms	438 ns	84 ns

**Requirements are all satisfied thanks to the compression**

- Resources occupancy: mix of quantization and KD
- Maximum latency: KD and VHDL implementation
- Fake efficiency < 2‰: quantization

# Conclusion & perspectives

## Anomaly Detection analysis

- model independent search, more general
- finalising the best ML model
- moving to Run3 ATLAS data, adding the tracks information

## L0 ML muon trigger algorithm

- ML algorithm sensitive to larger range of physics
- successful single muon results, moving to 2 muons with  $p_T$ ,  $\eta$ , charge and #muons prediction

LHC experiments are big data factories, large improvements in using ML tools



A woman with dark hair is wearing a white Petzl helmet with a headlamp. She is smiling slightly and looking towards the camera. The background is a complex, dimly lit tunnel or cavern filled with a dense network of white and blue cables, metal structures, and various pieces of equipment. The lighting is focused on the woman, with the rest of the scene in shadow.

Thanks for the  
attention!



# More on the trigger system

[ATLAS TDAQ public page](#)

The billions of collisions in ATLAS have a combined data volume of more than 60 million megabytes per second – that’s equivalent to **5400 simultaneous streams of 4K video**. However, only some of these events will contain interesting characteristics that might lead to new discoveries. To reduce the flow of data to manageable levels, ATLAS uses a special event selection system – the “trigger” – which picks events with distinguishing characteristics for physics analyses.

## The ATLAS trigger system carries out the selection process in two stages.

1

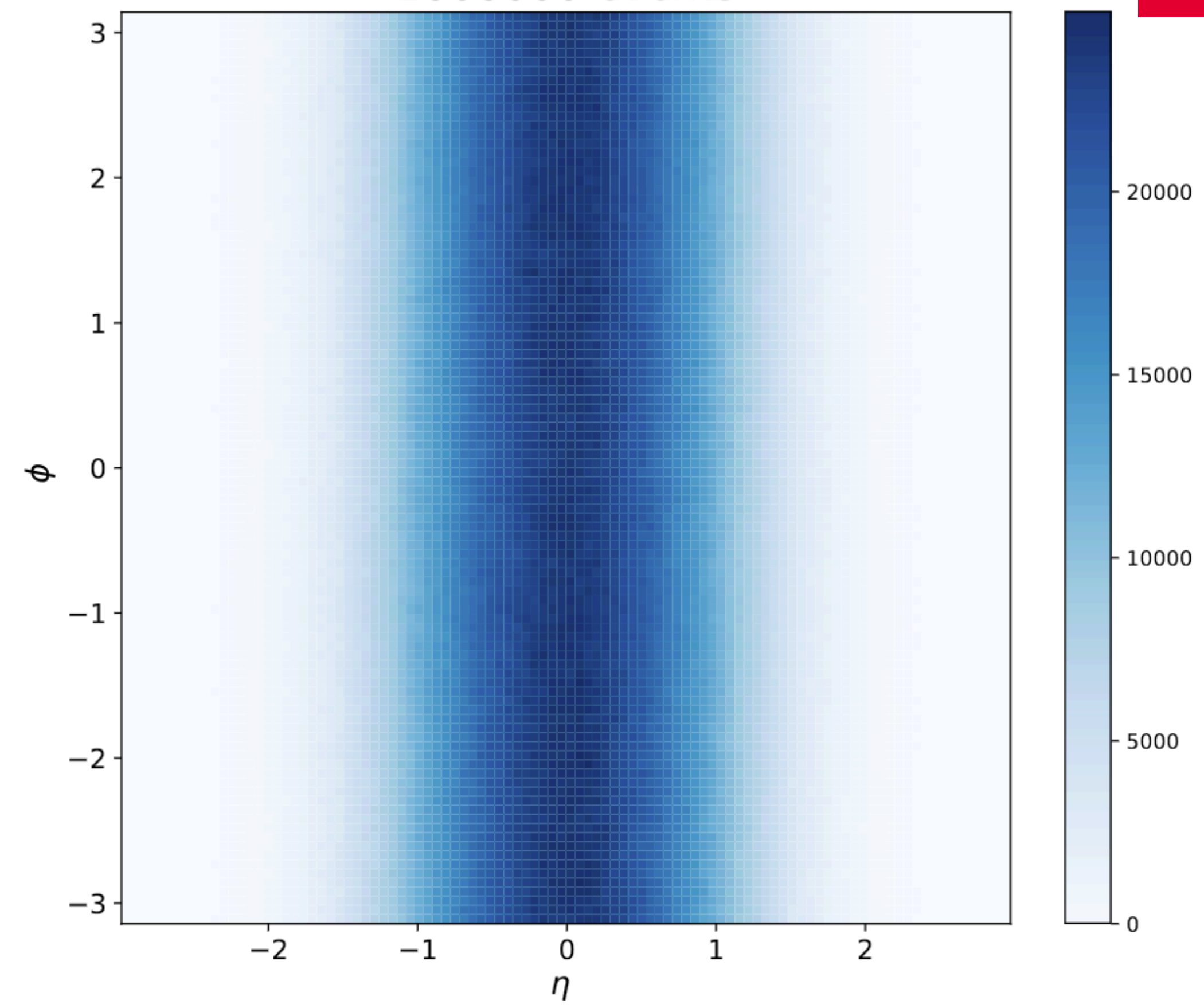
The first-level hardware trigger, constructed with custom-made electronics located on the detector, works on a subset of information from the calorimeters and the Muon Spectrometer. The decision to keep the data from an event is made less than **2.5 microseconds** after the event occurs. During this time the event data is kept in storage buffers. If the event is selected it is passed on to the second-level trigger, which can accept up to **100,000 events per second**.

2

The second-level software trigger operates from a large farm of about **40,000 CPU cores**. In just 200 microseconds, it conducts very detailed analyses of each collision event, examining data from specific detector regions. The second-level trigger finally selects about **1000 events per second** and passes them on to a data storage system for offline analysis.

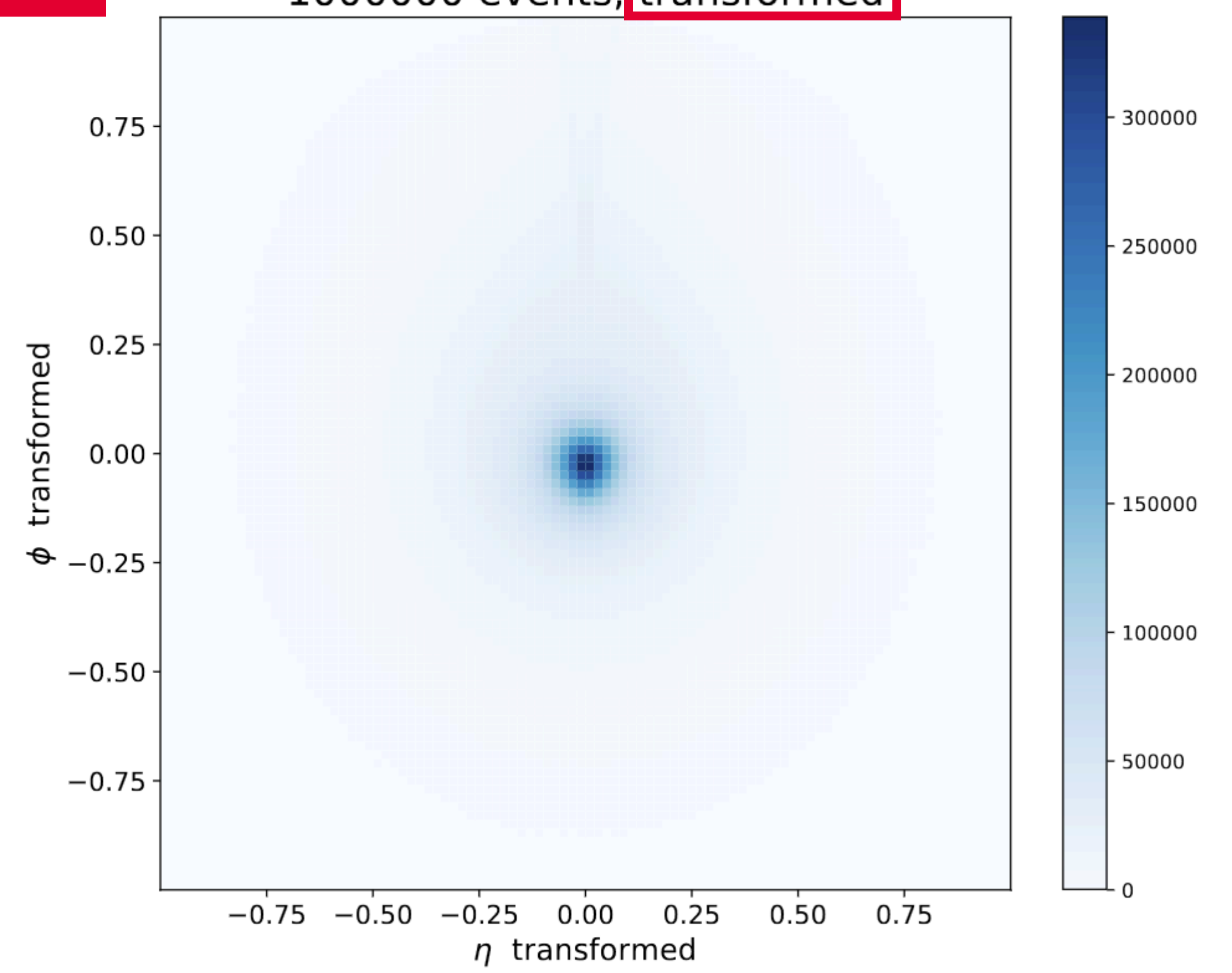


QCD background spatial distribution  
1000000 events

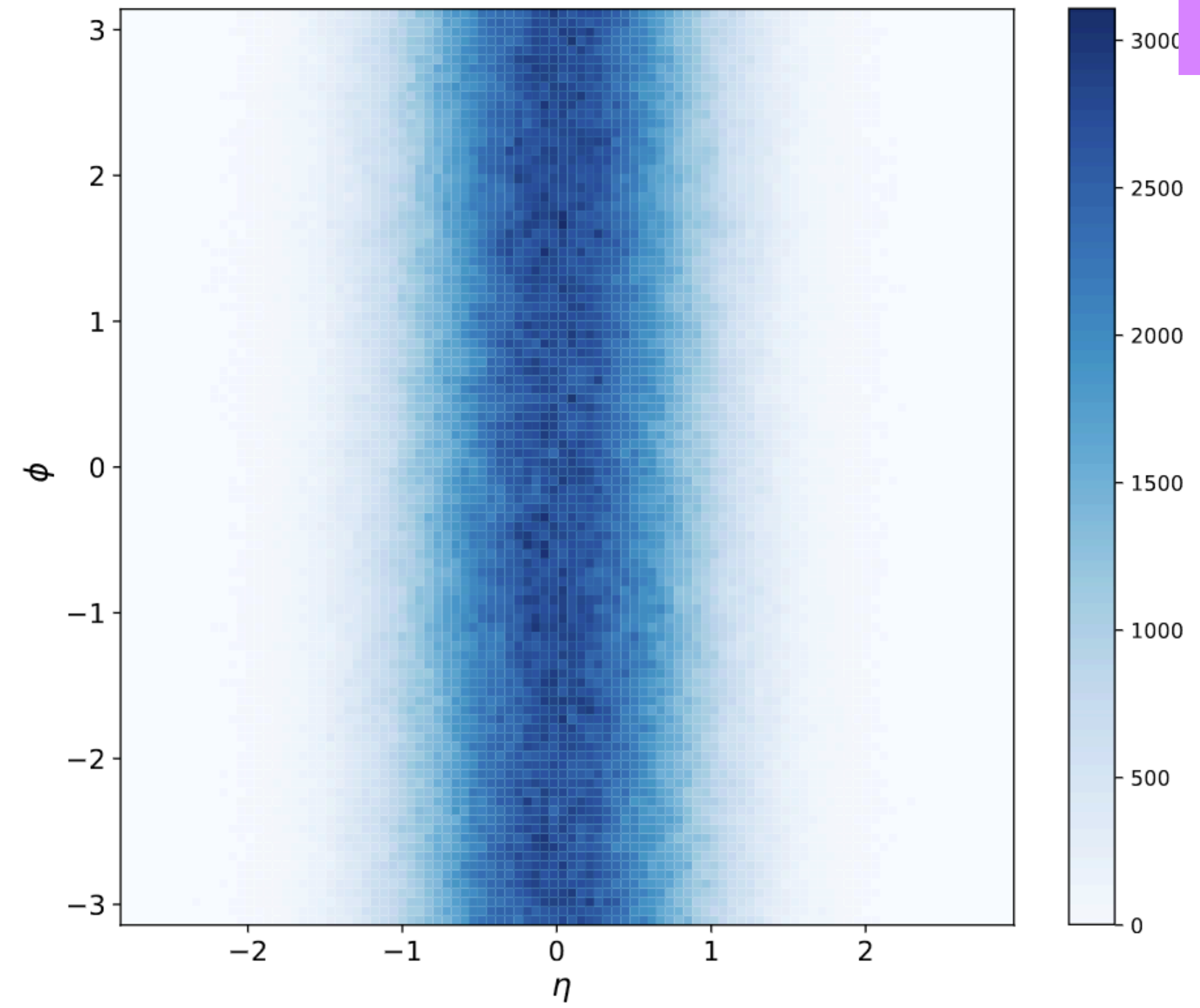


QCD

QCD background spatial distribution  
1000000 events, transformed

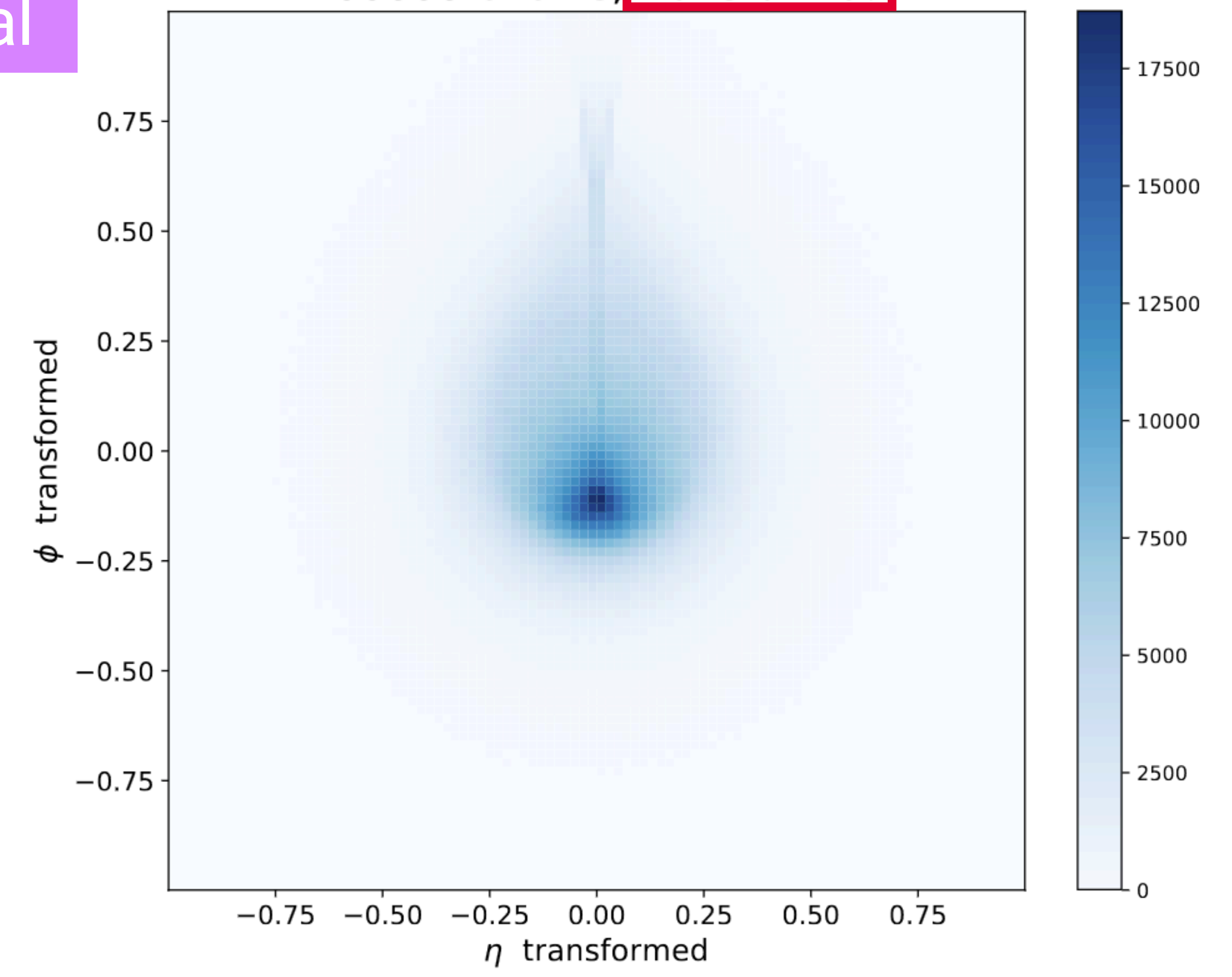


$Z' \rightarrow XY \rightarrow qqqq$  spatial distribution  
100000 events



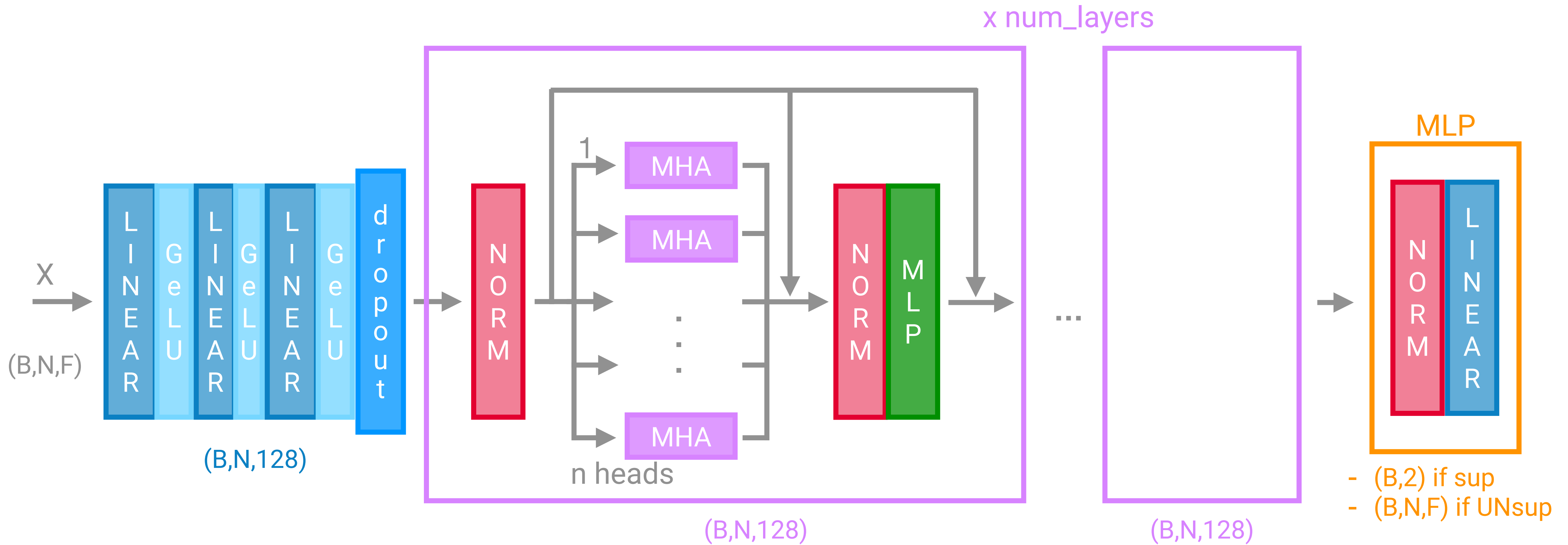
2prong  
signal

$Z' \rightarrow XY \rightarrow qqqq$  spatial distribution  
100000 events, transformed



# Transformer architecture

B = batch size  
N = #constituents (50)  
F = # features (3)



# Transformer trainings

**supervised loss:  
Cross Entropy loss**



Used as benchmark for comparison

$$L_{CE} = -(\mathbf{y} \log(\mathbf{p}) + (1 - \mathbf{y}) \log(1 - \mathbf{p}))$$



output of neural network

label of input

$$\mathbf{Anomaly\ Score} = \mathbf{Prob}(\mathbf{y} = \mathbf{1})$$

**unsupervised loss:  
MSE loss**



actual AD approach

$$L_{MSE} = \|\mathbf{x} - \mathbf{y}\|^2$$



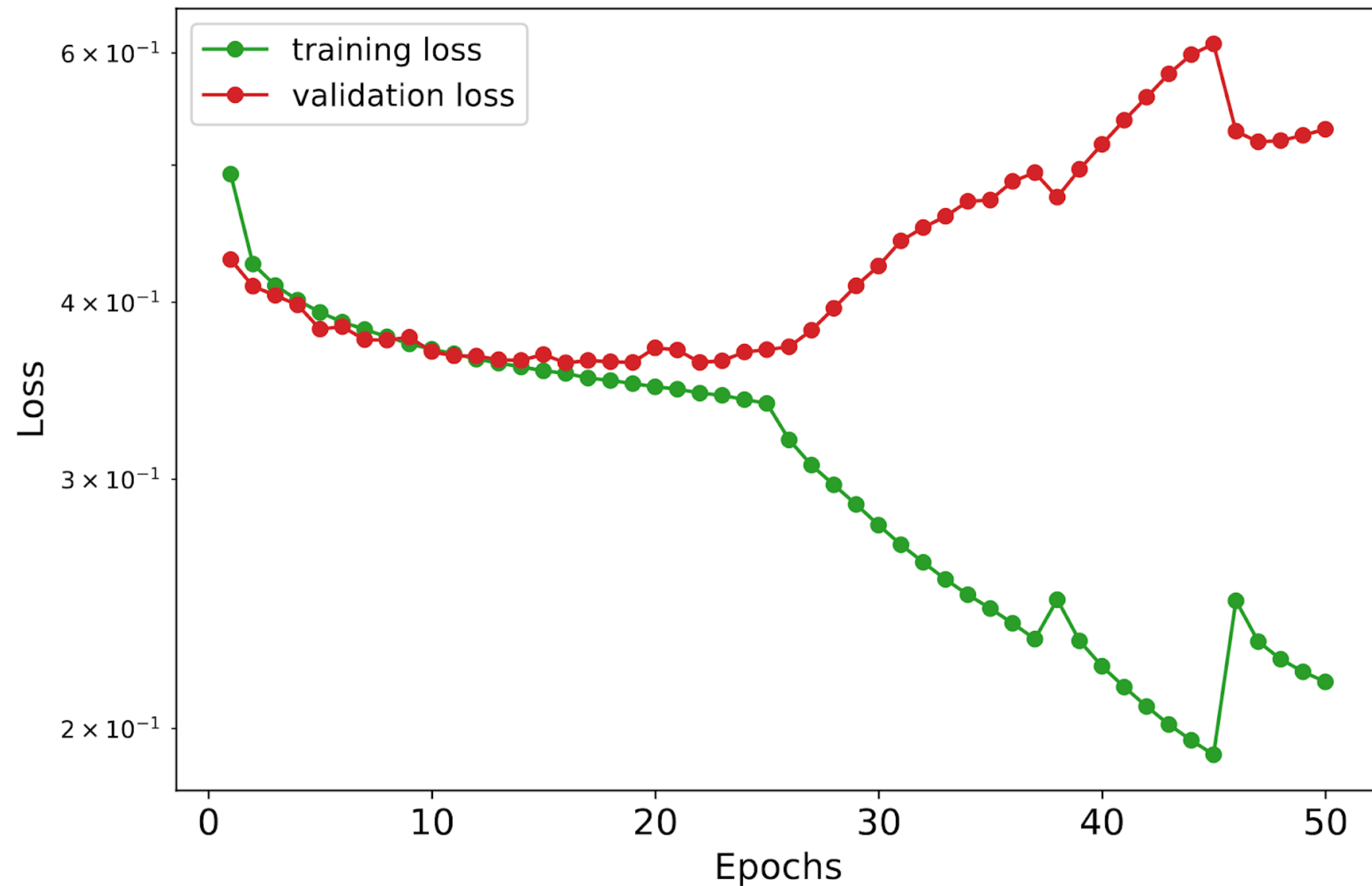
input of neural network

output of neural network

$$\mathbf{Anomaly\ Score} = \|\mathbf{x} - \mathbf{y}\|^2$$

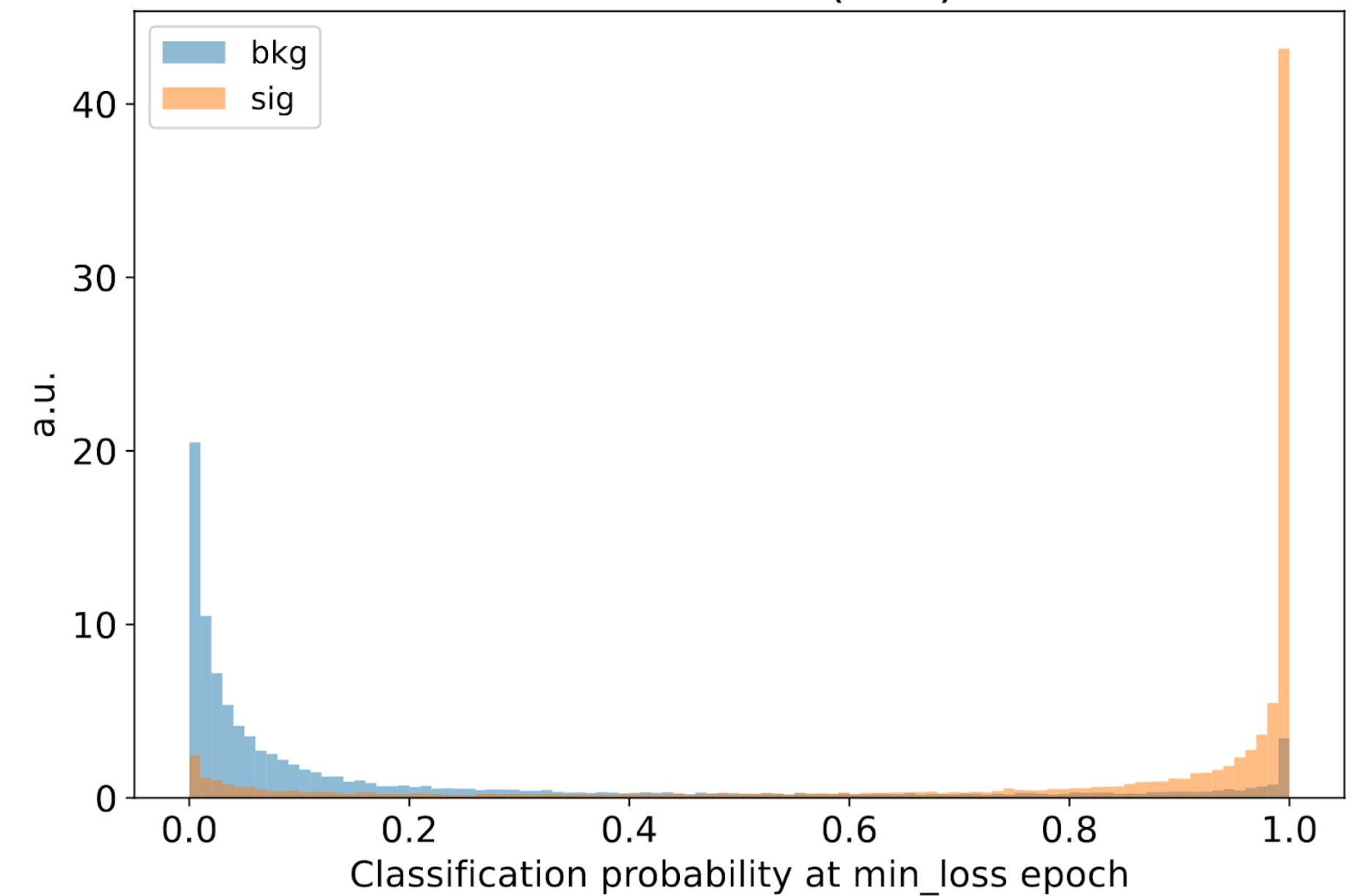
# Supervised Transformer training

Train and validation loss VS epochs  
Transformer



- unstable training, overtraining at epoch  $\sim 20$  but epoch with validation minimal loss is reached before
- AUC: **88.3%** (2prong)

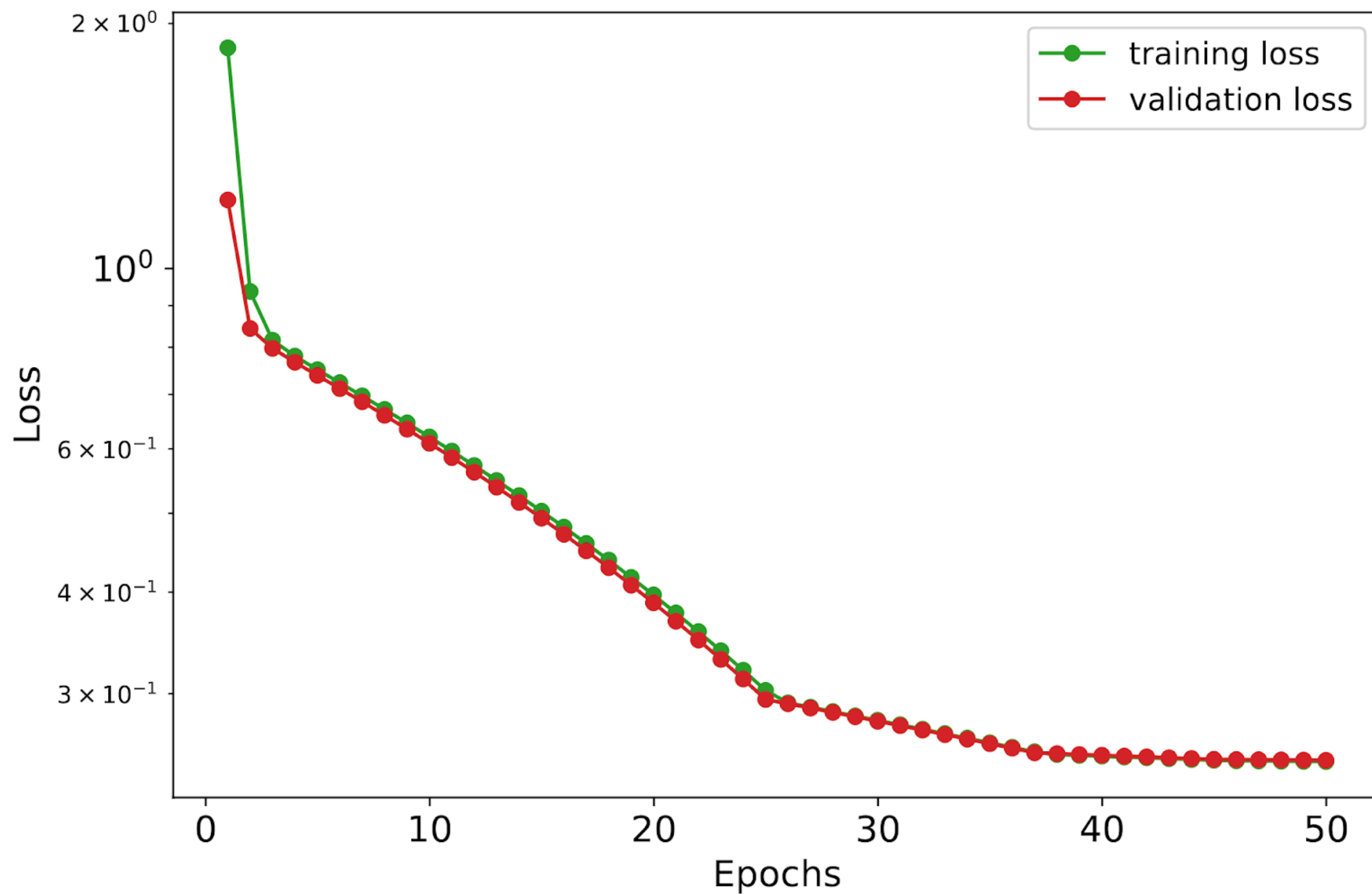
Transformer (test)





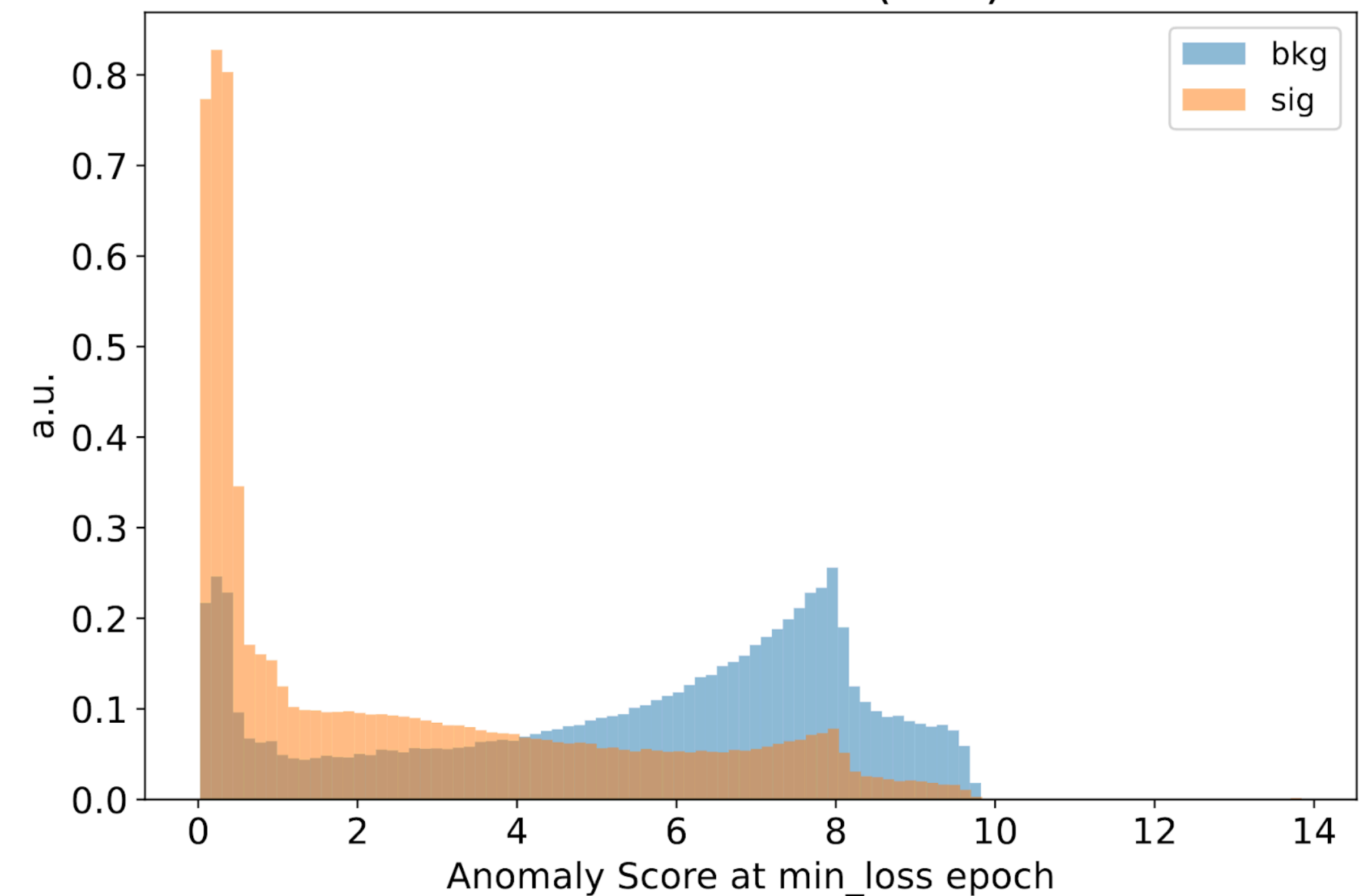
# UNsupervised Transformer training

Train and validation loss VS epochs  
TransformerAD



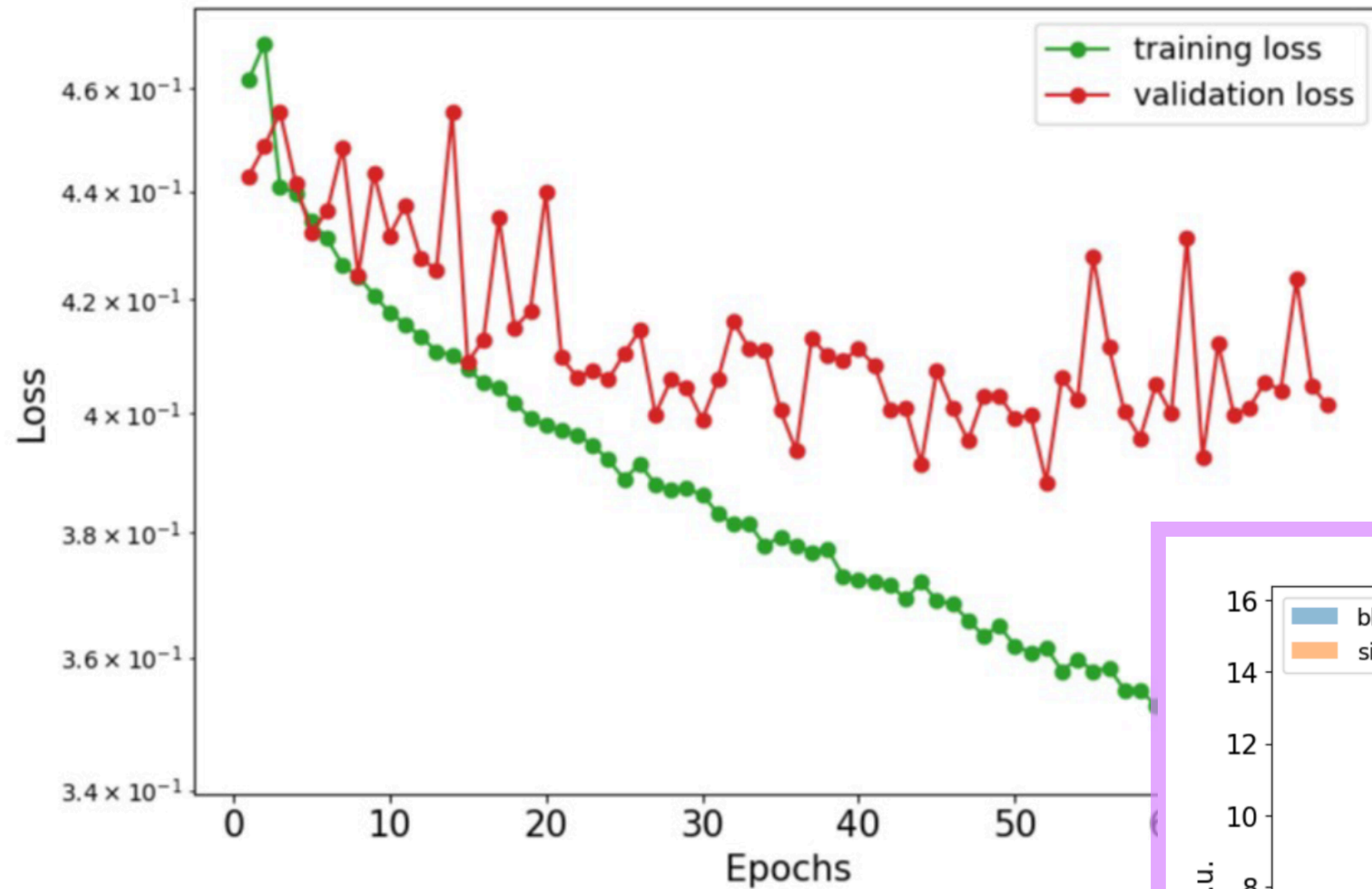
- stable training, almost no overtraining
- AUC: **75.5%** (2prong)

TransformerAD (test)

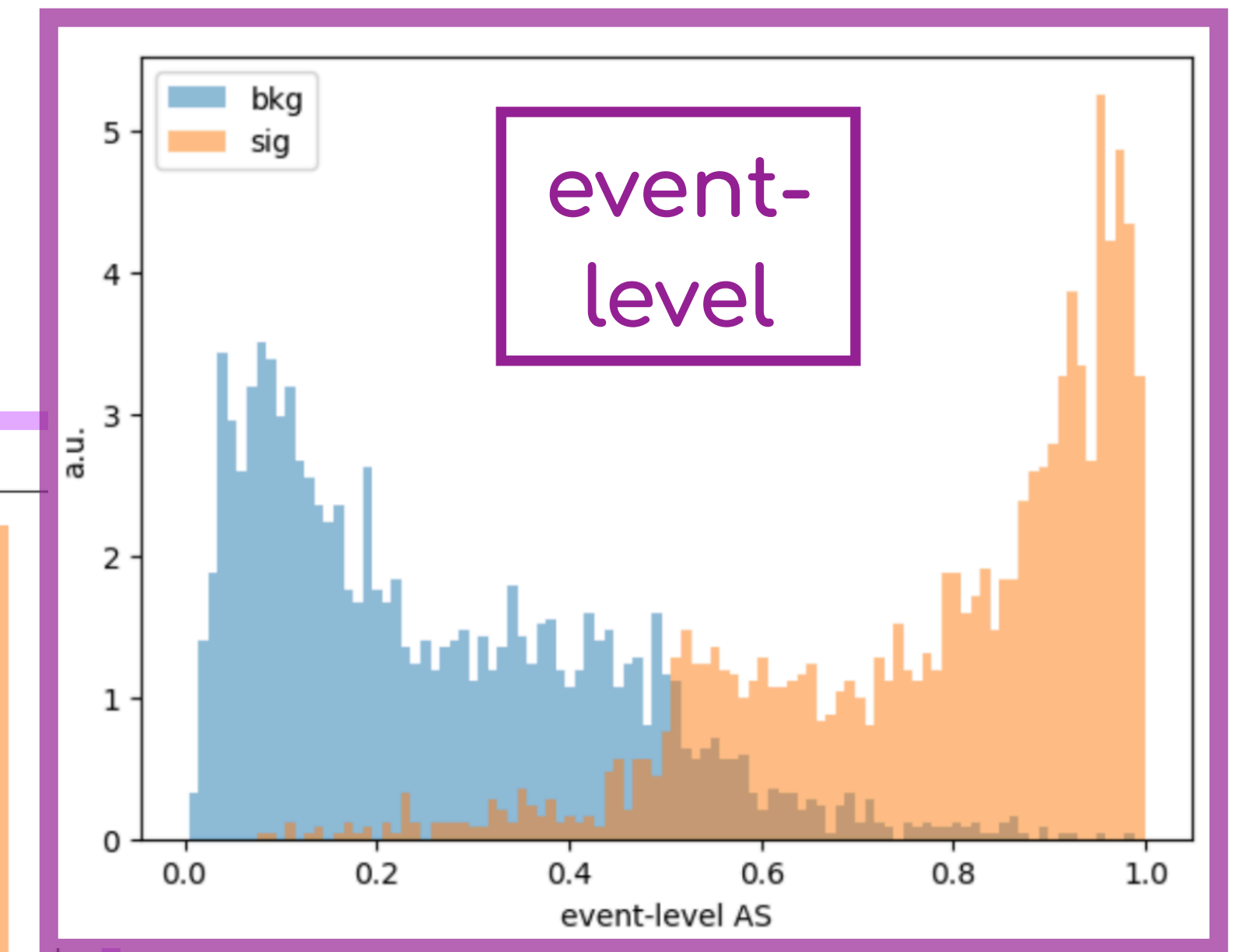
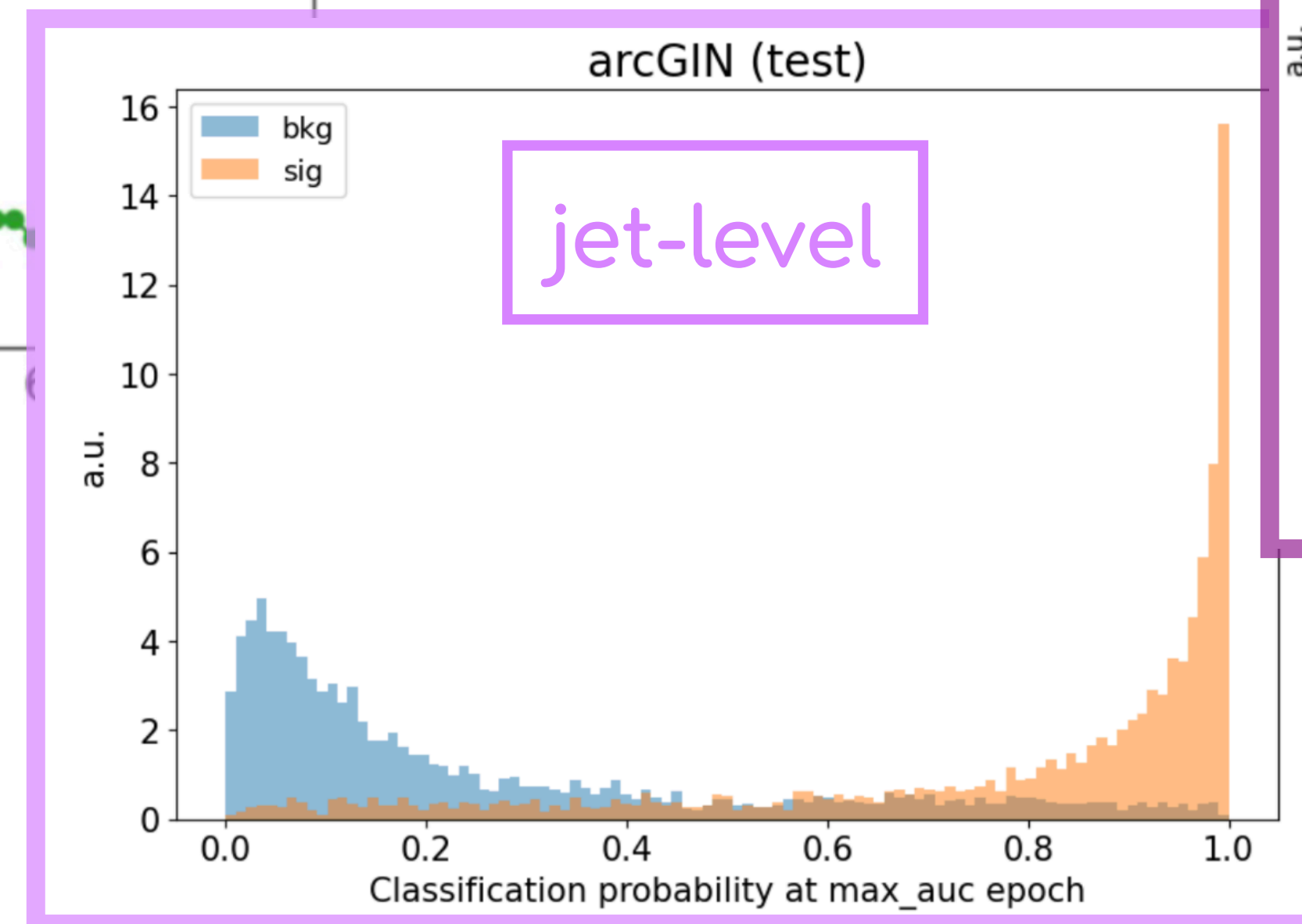


# Supervised GIN training

Train and validation loss VS epochs  
arcGIN

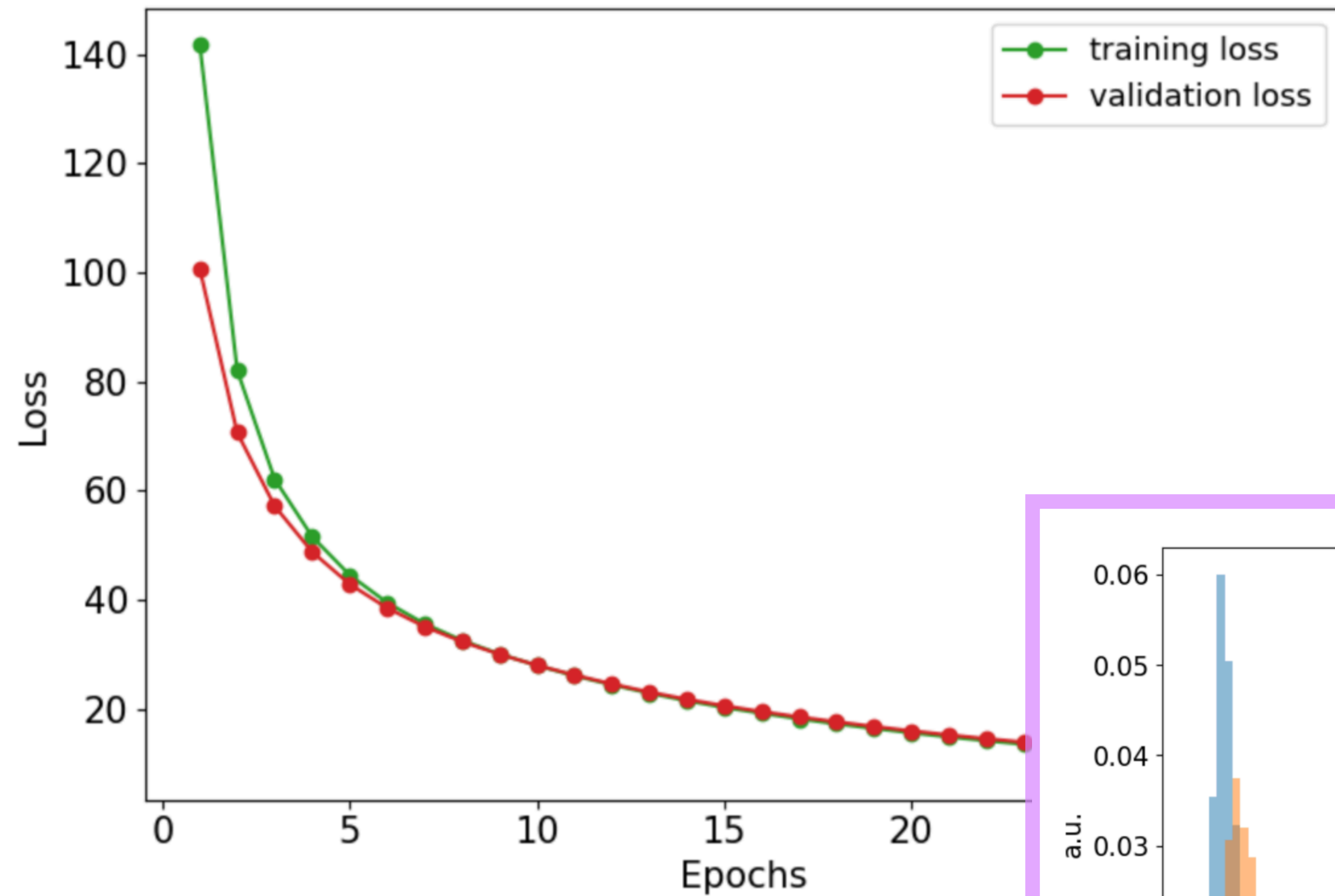


- quite stable training, very soon overtraining
- AUC jet-level: **90.2%** (2prong)
- AUC event-level: **96.5%** (2prong)

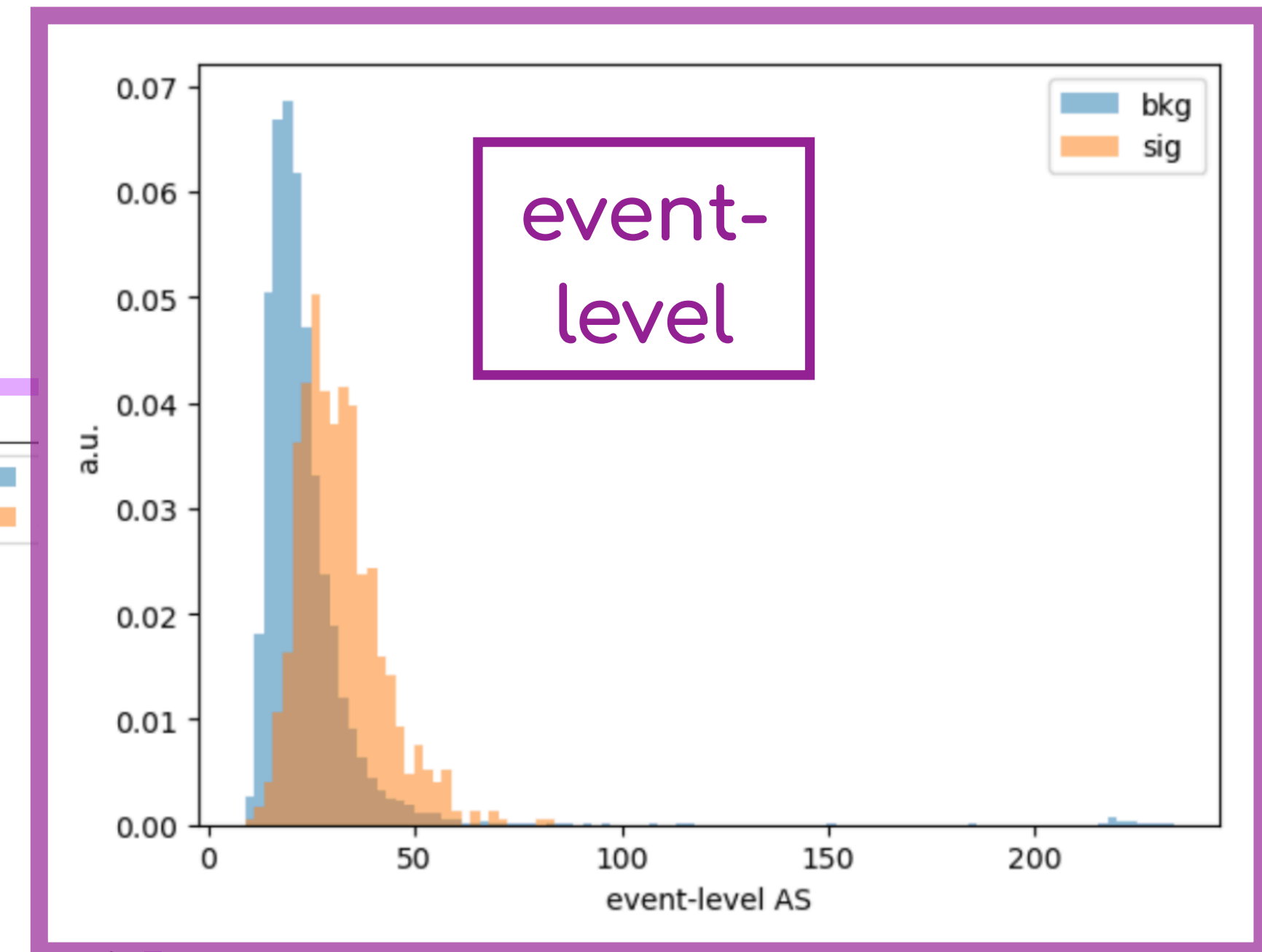
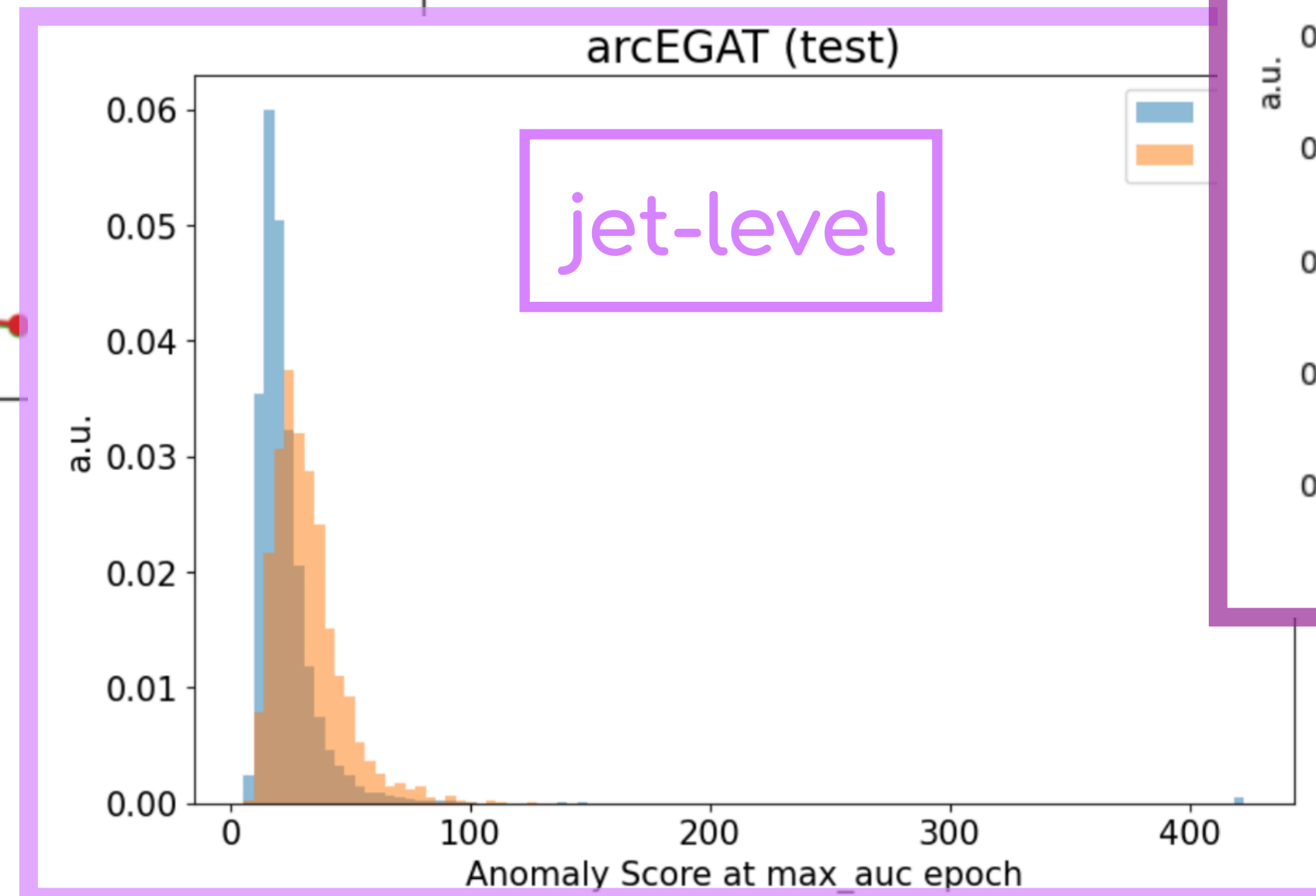


# UNsupervised GIN training

Train and validation loss VS epochs  
arcEGAT



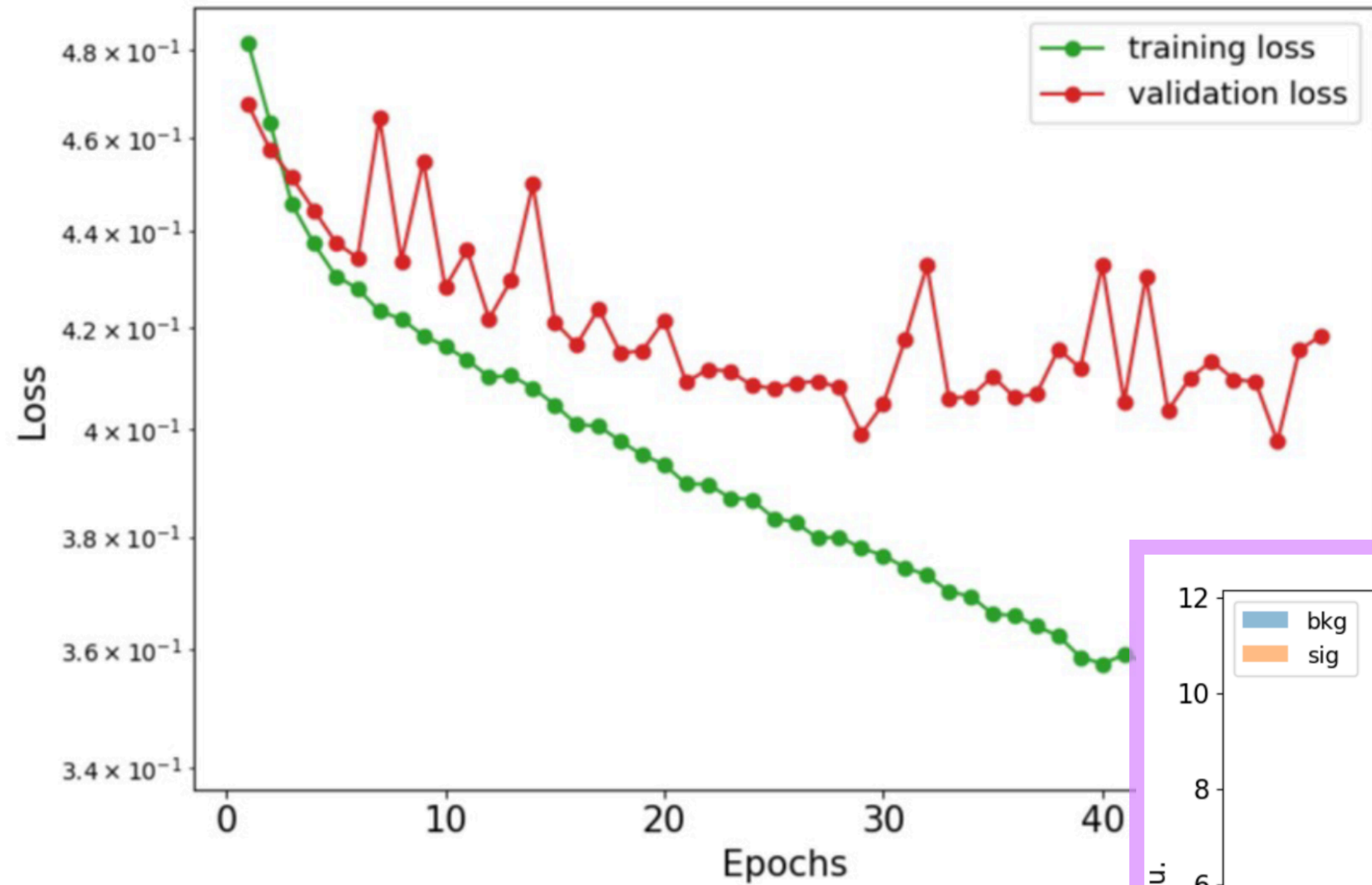
- very stable training, almost no overtraining
- AUC jet-level: **73.7%** (2prong)
- AUC event-level: **79.6%** (2prong)





# Supervised EGAT training

Train and validation loss VS epochs  
arcEGAT



- more stable training, overtraining at epoch  $\sim 25$
- AUC jet-level: **89.9%** (2prong)
- AUC event-level: **96.5%** (2prong)

