



Software infrastructure for developing superattenuator prototypes

Virgo-ET Pisa internal workshop
2024/05/23

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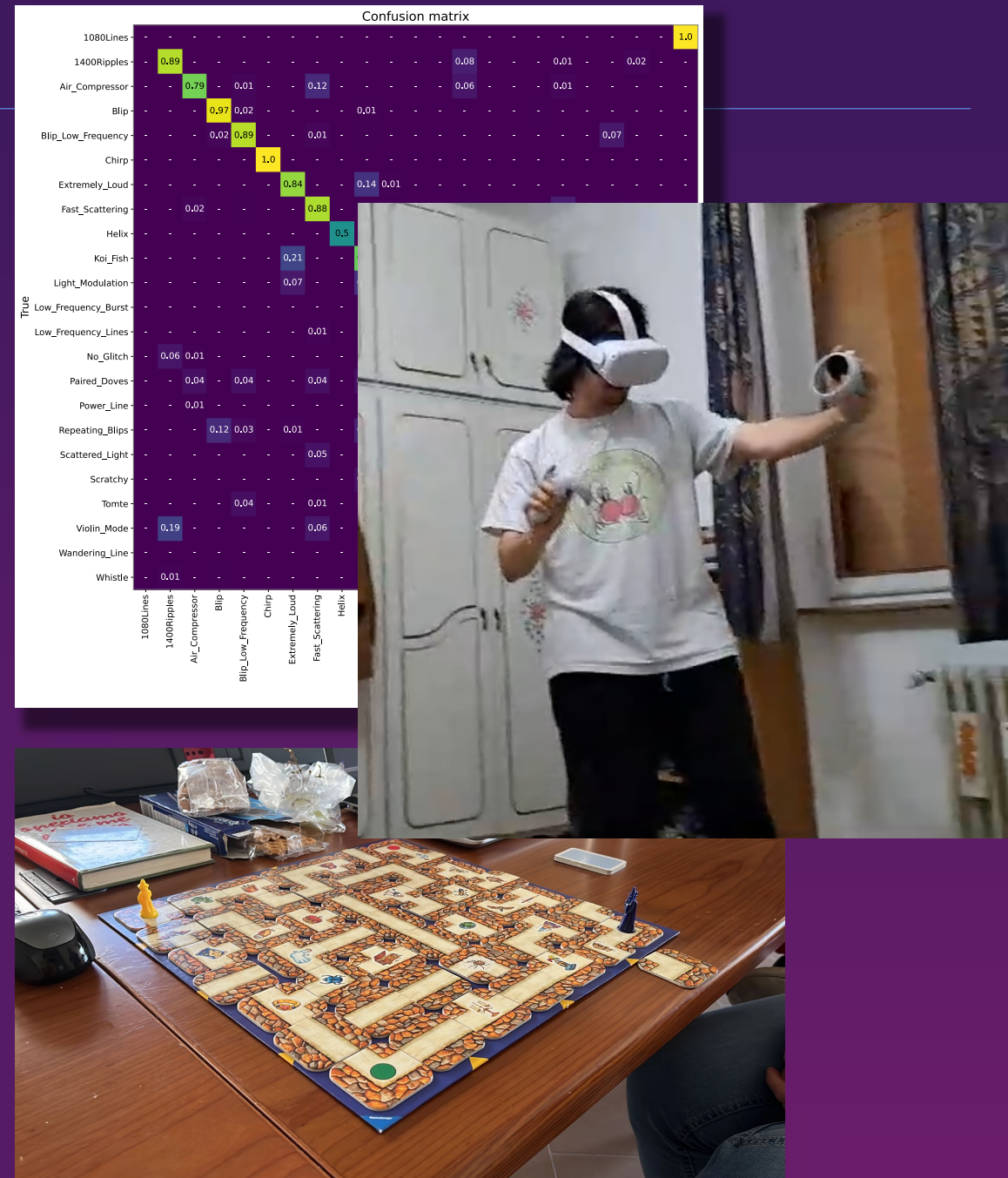
Me in a nutshell

About me:

- PhD student (38th cycle) with Massimiliano and Francesco, PNRR-ETIC fundings
- Very much *Pisano* (Bachelor and Master degrees, now PhD)
- Worked on DetChar (glitches) with machine learning
- Now moving to the **study of seismic noise attenuation**
- Participating in RRT shifts, LOC for GWADW23 and GraSP23

Also about me:

- Board games, RPGs, TV-series, hiking
- Cheat code to befriend me: **Food**



My past and current work: laboratory database

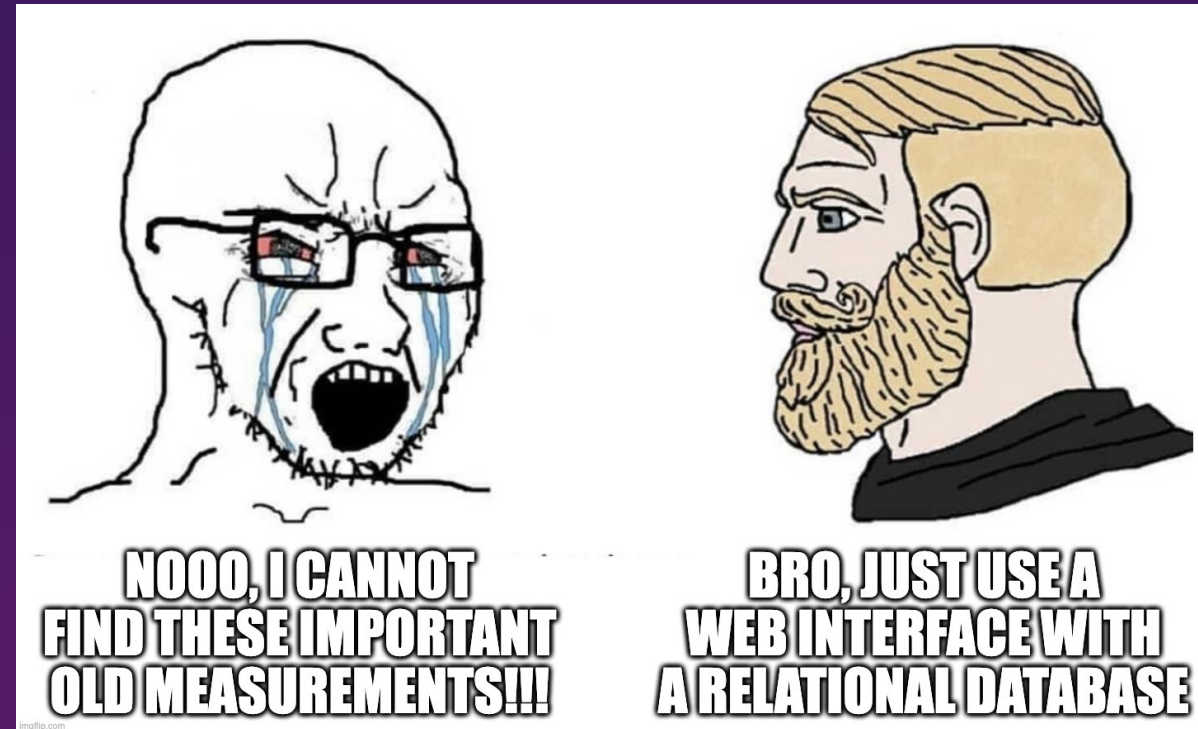
Work in collaboration with Lorenzo, Alessio, Massimiliano and Francesco

Motivations:

- Support **development of suspension-related prototypes** such as the PIP (see e.g. Francesco and Lorenzo's talks).
- **Track components** for prototypes and their history.
- Useful to **sort datasets, media, projects** etc...

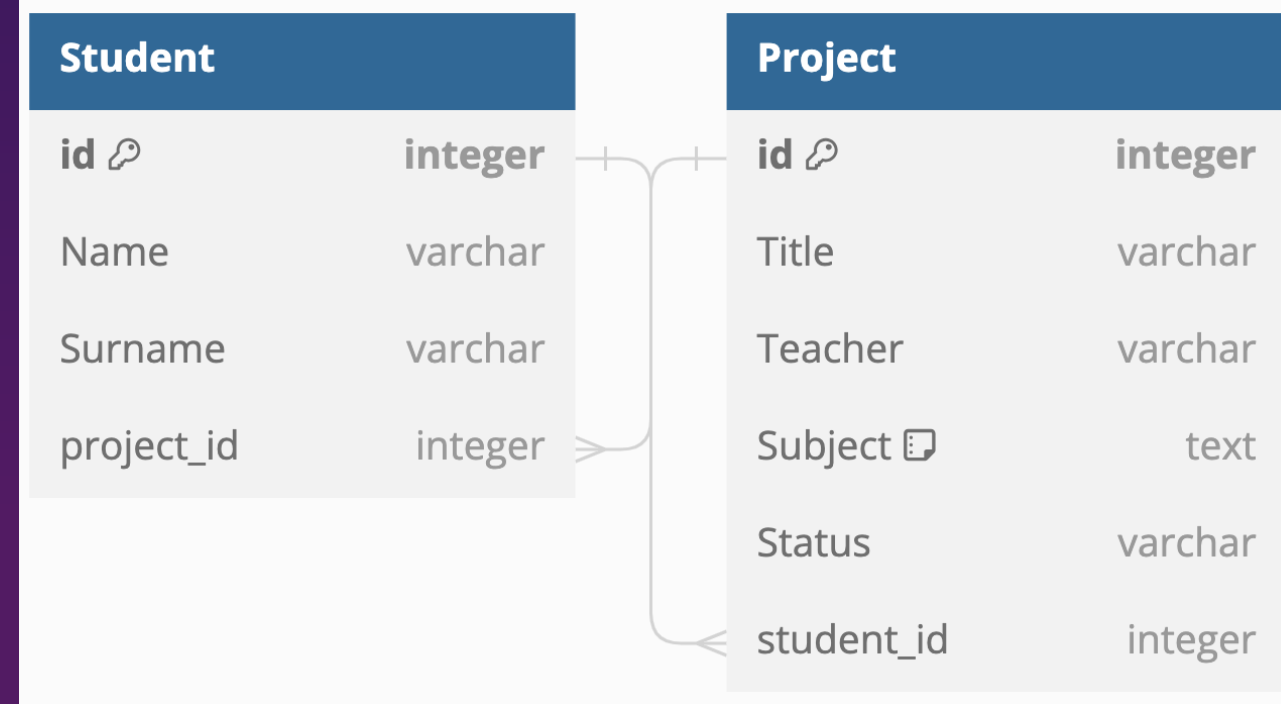
Main features:

- Developed with **Flask**, maps URLs to Python functions.
- Utilities for handling **HTTP, security** and templates.
- **Hosted on virtual machine**, code is on GitLab (in production now!).



Pills on Relational Databases

- **Structured Query Language (SQL)**: defining, querying and manipulating data. Provides a standardized way to interact with data.
- **Data Integrity**: constraints between tables (primary and foreign keys, triggers) ensure that data is consistent and allow to represent complex relationships.
- **Security**: robust security features, including user authentication, access control, and encryption.



Users:

- Name, email
- Affiliation
- Privileges

Components:

- Physical data
- Relationships with other comps
- Media and history

Media:

- Type (png, pdf, csv)
- Notes

History:

- Author
- Actions performed
- Related database entities

Report:

- Author(s)
- Activities
- Related comps, media etc...

Overview of component "PIP_001"

Component Type: PIP
Materials: al
Weight (Kg): 200.0
Designer: All
Arrival Date: 2024-03-15

List of subcomponents:

Label	Component Type	Weight (Kg)	Materials	Mounted on
IP_Leg_003	IP_Leg	0.0	Alluminium, steel	PIP_001
IP_Leg_002	IP_Leg	0.0	Aluminium, steel	PIP_001
IP_Leg_001	IP_Leg	0.0	Aluminium, steel	PIP_001

Overview of component "IP_Leg_003"

Component Type: IP_Leg
Materials: Aluminium, steel
Weight (Kg): 0.0
Designer: Andrea Basti
Arrival Date: 2023-10-26

Notes:

The IP_Leg_003 is composed by several components. It is installed on the support and we are collecting data.

Mounted on:

Label	Component Type	Weight (Kg)	Materials	Mounted on
PIP_001	PIP	200.0	al	None

List of subcomponents:

Label	Component Type	Weight (Kg)	Materials	Mounted on
Campana_003	Campana	0.0	Alluminium	IP_Leg_003
Colonna_003	Colonna	8.6	Stainless steel	IP_Leg_003
Giunto_003	Giunto	0.0	Maraging steel	IP_Leg_003
Flangia1_003	Flangia1	0.748	Stainless steel	IP_Leg_003
Flangia2_003	Flangia2	0.724	Stainless steel	IP_Leg_003
Gamba_003	Gamba	1.531	Alluminium	IP_Leg_003
Cover_003	Cover	0.779	Alluminium	IP_Leg_003
TestComp2	Cover	1.0	al	IP_Leg_003

Overview of component "Colonna_003"

Component Type: Colonna
Materials: Stainless steel
Weight (Kg): 8.6
Designer: Andrea Basti
Arrival Date: 2023-10-26

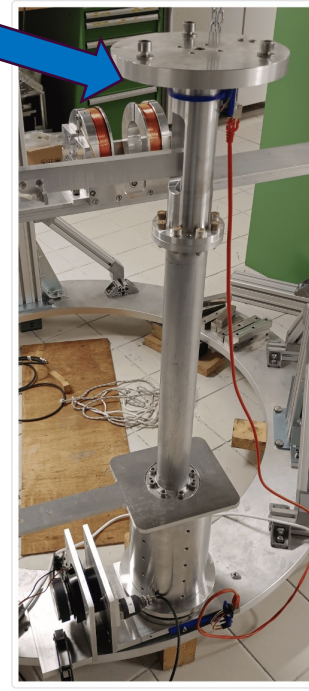
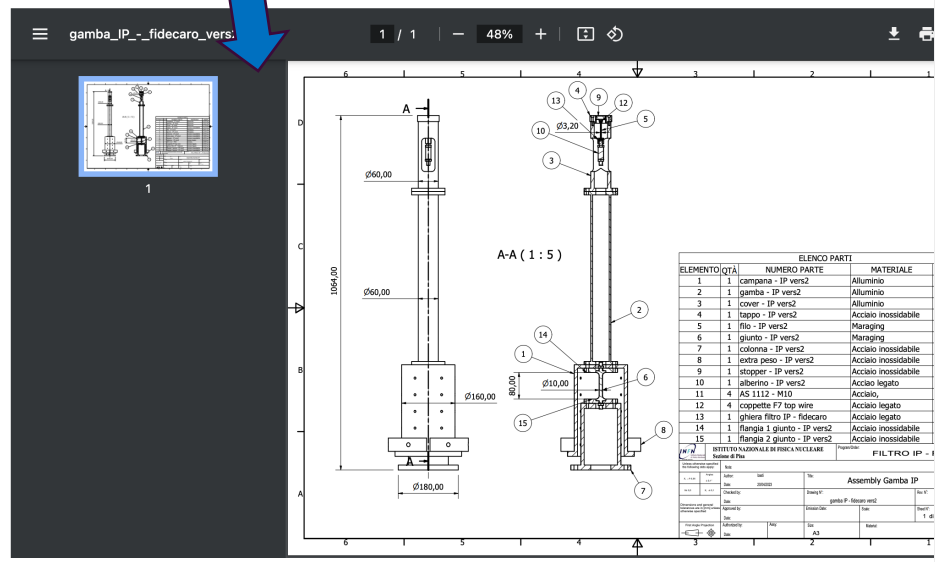
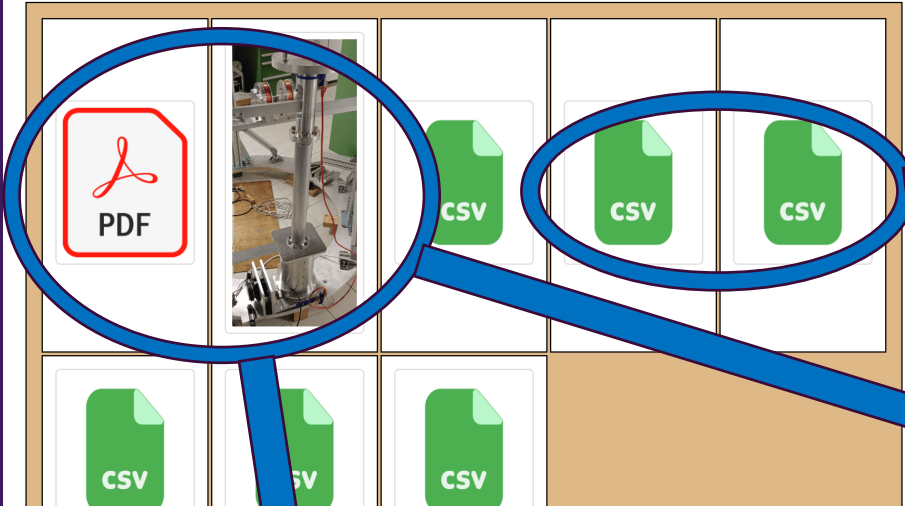
Mounted on:

Label	Component Type	Weight (Kg)	Materials	Mounted on
IP_Leg_003	IP_Leg	0.0	Alluminium, steel	PIP_001

Overview of component "IP_Leg_003"

Media Gallery (click on picture to see more info):

[Upload New Media](#)



Authors: Matteo Baratti
Date: 2023-11-10

Description:
First IP leg



% Moku:Pro Data Logger					
A1	A	B	C	D	F
1	% Moku:Pro Data Logger				
2	% Input 1 (off) - Ramp, 50.000 000 000 kHz, 500.0 mVpp, offset 0.000 0 V, phase 0.000 000 deg, symmetry 90.00 %				
3	% Input 2 (off) - Ramp, 50.000 000 000 kHz, 500.0 mVpp, offset 0.000 0 V, phase 0.000 000 deg, symmetry 90.00 %				
4	% Input 3, DC coupling, 1 MOhm impedance, 4 Vpp range				
5	% Input 4, DC coupling, 1 MOhm impedance, 4 Vpp range				
6	% Acquisition rate: 5.000000000e+02 Hz, Precision mode				
7	% Output 1 (off) - Sine, 10.000 000 000 000 MHz, 1.000 0 Vpp, offset 0.000 0 V, phase 0.000 000 deg, output termination 50 Ohm				
8	% Output 2 (off) - Ramp, 50.000 000 000 kHz, 500.0 mVpp, offset 0.000 0 V, phase 0.000 000 deg, symmetry 90.00 %				
9	% Output 3 (off) - Square, 80.000 000 000 000 MHz, 1.000 0 Vpp, offset 0.000 0 V, phase 0.000 000 deg, duty cycle 50.00 %				
10	% Output 4 (off) - Pulse, 10.000 000 000 kHz, 200.0 mVpp, offset 0.000 0 V, phase 0.000 000 deg, width 1.000 us, edge 2.000 ns				
11	% Internal 10 MHz clock				
12	% Acquired 2024-02-09 T 18:35:54 +0100				
13	% Sweep from 100mHz to 100 Hz in 5s. Vpp=2V. Inpu1: WG, Input2: LS, Input3: GLVDT, Input4: TLVDT. noRing				
14	% Time (s), Input 1 (V), Input 2 (V), Input 3 (V), Input 4 (V)				
15	0.000000000e+00, -8.1890449017e-01, -1.5455149548e+00, 4.4880433248e-02, -2.4067456286e-02				
16	2.000000000e-03, -8.5896832794e-01, -1.6210900629e+00, 4.4957755934e-02, -2.4029233152e-02				

[Sweep_12Kg_noRing_20240209_183554.csv](#)
Authors: Lorenzo Bellizzi
Date: 2024-02-09

Description:
Frequency sweep IP_Leg with no top rings



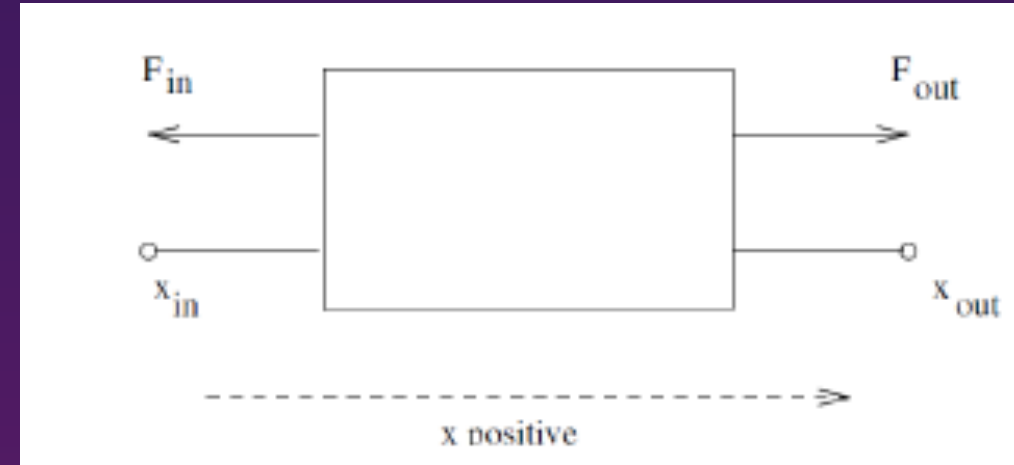
Accurate depiction of us learning HTML:
<https://imgur.com/a/volume-control-eWbBK>

My future work: Octopus simulations

Developed within the PRIN BHETSA, to provide a user-friendly simulator (M. Razzano et al 2024 in prep)

Goal: find the **transfer function** of complex systems with **impedance matrix** approach (G. Cella & A. Vicerè 2001, Ruggi et al to be published)

$$\begin{pmatrix} \vec{x}_{out}(\omega) \\ \vec{F}_{out}(\omega) \end{pmatrix} = \begin{pmatrix} A(\omega) & B(\omega) \\ C(\omega) & D(\omega) \end{pmatrix} \begin{pmatrix} \vec{x}_{in}(\omega) \\ \vec{F}_{in}(\omega) \end{pmatrix}$$



Graphical User Interface

Configuration

Mechanical Network Representation

Solve network

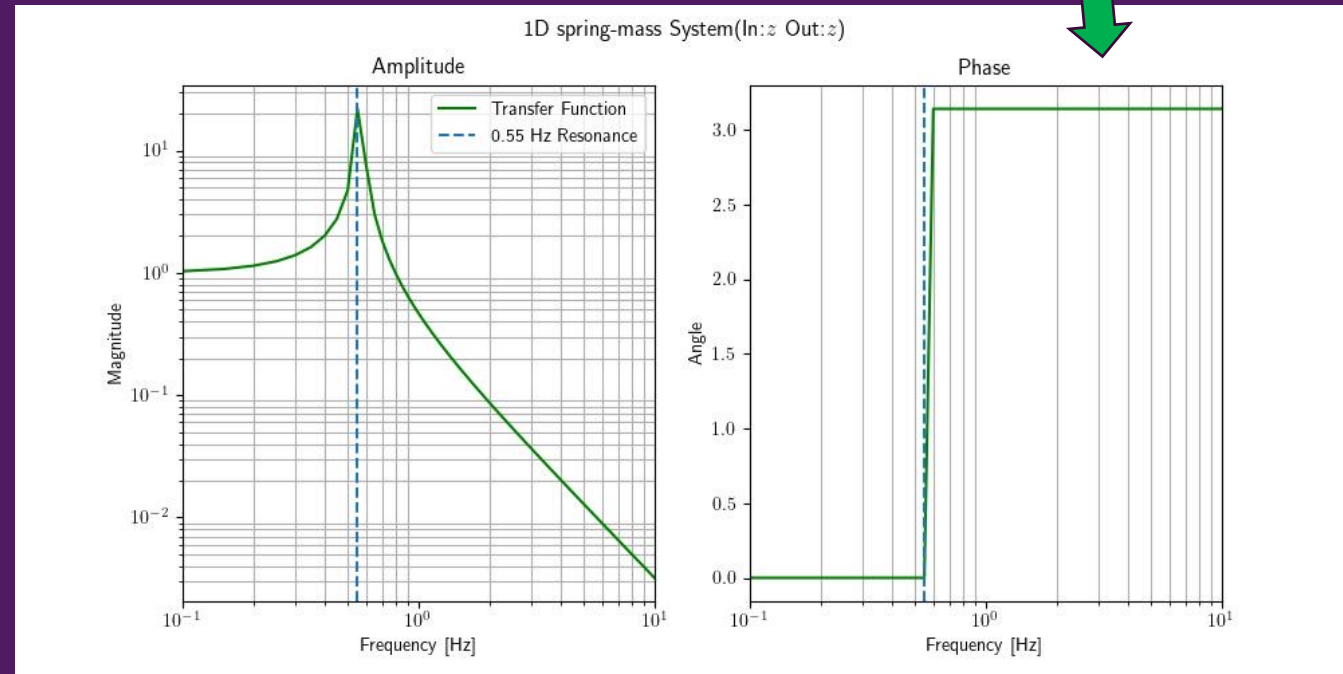
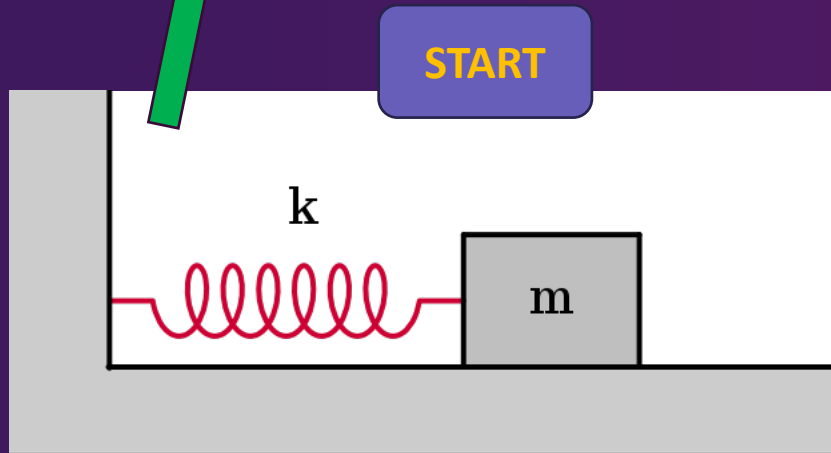
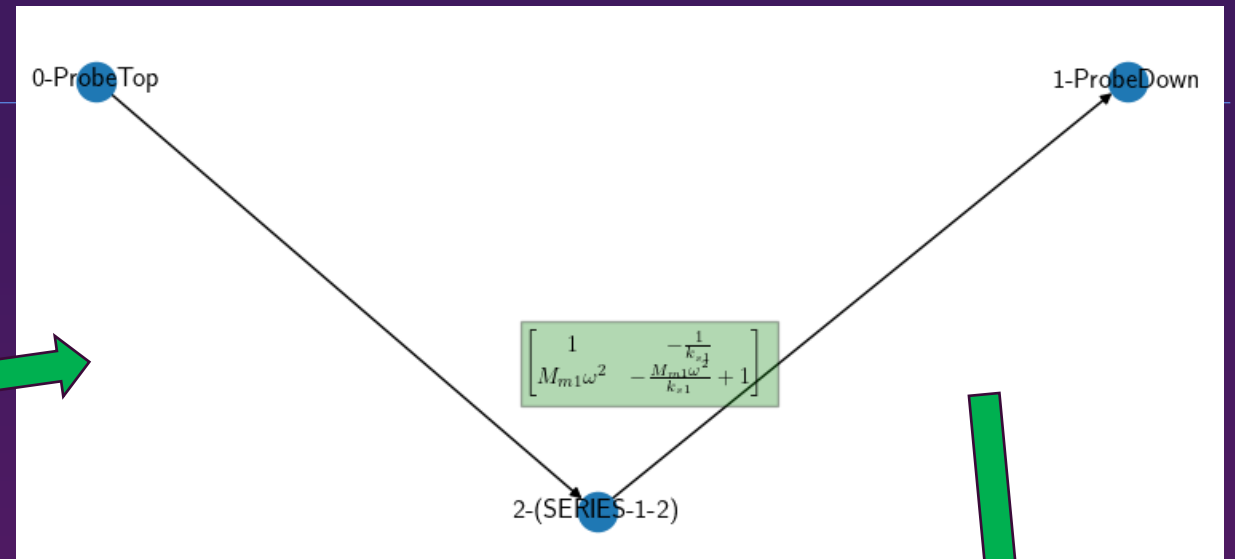
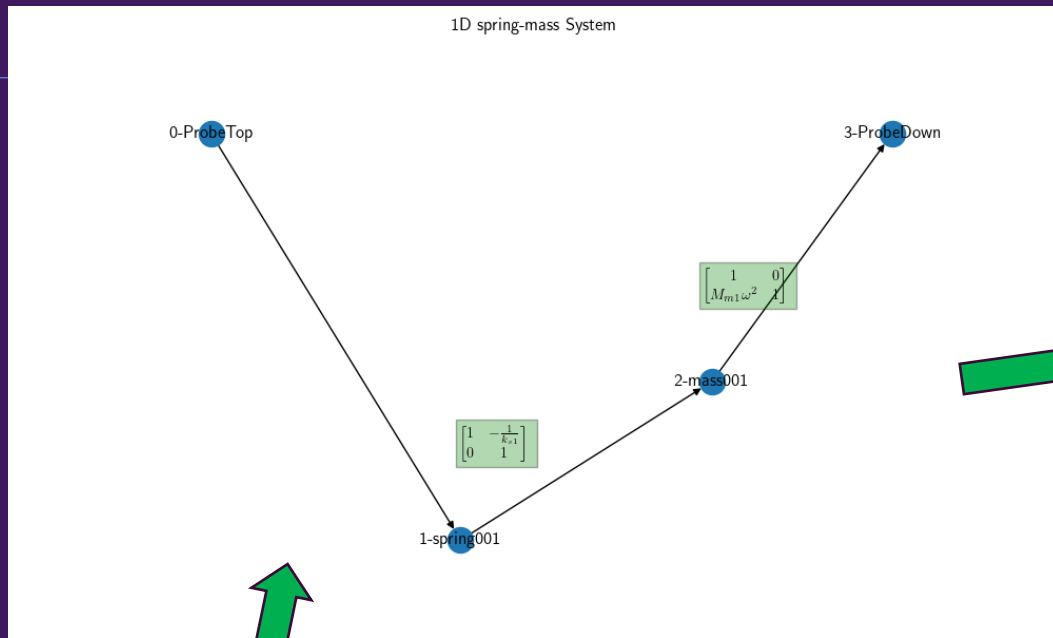
$$T(\omega) = \frac{\vec{x}_{out}(\omega)}{\vec{x}_{in}(\omega)} = [{}^tD(\omega)]^{-1}$$

Transmission Matrix $Z(\omega)$

Transfer Function(s) $T(\omega)$

Optimization

Crosscheck with measurements



“Hey ChatGPT, resume Michele’s talk in one slide (and no memes...)”

Database-wise:

- Database implemented, 3-level development (local/staging/production)
- Python Web application **up and running**
- Already **filling with data and using to track activities**



IN THE FUTURE...

- Finalize **history and logbook**
- Complete structure for **groups and projects**
- Possibility to use it in other GW labs (discussing with CAOS)

Simulations-wise:

- Implemented **graph representation** and **symbolic calculation** to solve network and compute transfer functions
- Basic workflow done



- Refine simulations and apply to a full-scale PIP
- Develop **novel optimization techniques** (e.g. PINNs)

Suggestions for the group?

