

Substructures of the Weyl group

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Harmonic Weyl

[O’Raifeartaigh, Sachs and Wiesendanger, ‘96; Edery and Nakayama, 2014]

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$$g_{\mu\nu} \rightarrow g'_{\mu\nu} = \Omega^2 g_{\mu\nu}, \quad \text{with}$$
$$H_g(\Omega) = \square_g \Omega + \frac{d-4}{2\Omega} g^{\mu\nu} \partial_\mu \Omega \partial_\nu \Omega = 0$$

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Closure

$$\begin{cases} g'_{\mu\nu} = (\Omega_1)^2 g_{\mu\nu} \\ H_g(\Omega_1) = 0 \end{cases} \circ \begin{cases} g''_{\mu\nu} = (\Omega_2)^2 g'_{\mu\nu} \\ H_{g'}(\Omega_2) = 0 \end{cases} \Rightarrow \begin{cases} g''_{\mu\nu} = (\Omega_1 \cdot \Omega_2)^2 g_{\mu\nu} \\ H_g(\Omega_1 \cdot \Omega_2) = 0 \end{cases}$$

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NOT inverse

$$H_g(\Omega) = 0 \Rightarrow H_{\Omega^2 g} \left(\frac{1}{\Omega} \right) = 0, \quad \text{However} \quad H_g \left(\frac{1}{\Omega} \right) \neq 0$$

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A solution of $H_g(\Omega) = 0$ is inherently non-linear unless $d = 4$. Perturbatively we find

$$\Omega = 1 + \varepsilon \omega_1 + \varepsilon^2 \omega_2 + \dots$$

$$\square_g \omega_1 = 0, \quad \square_g \omega_2 = \frac{4-d}{2} g^{\mu\nu} \partial_\mu \omega_1 \partial_\nu \omega_1 \dots$$

Harmonic Weyl

- Ricci scalar transforms homogeneously under h.W. [Kühnel and Rademacher, '95]

$$R \rightarrow R' = \Omega^{-2} \left(R - 2(d-1)\Omega^{-1} H_g(\Omega) \right)$$

In $d = 4$ we have that $\sqrt{g} (\alpha R^2 + \beta W^2)$ is an invariant density.

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- We can think about R as a partial gauge fixing [Oda, 2020; Edery, 2023]

Consider the BRST action

$$\delta_B g_{\mu\nu} = 2cg_{\mu\nu}, \quad \delta_B c = 0, \quad \delta_B \bar{c} = b, \quad \delta_B b = 0,$$

Then, we can find a gauge fixing action can be find in the standard way

$$S_{\text{gf}} + S_{\text{gh}} = \delta_B \int d^4x \sqrt{g} \bar{c} \left(R - \frac{\alpha}{2} b \right) \stackrel{!}{=} \frac{1}{2\alpha} \int d^4x \sqrt{g} R^2 + 6 \int d^4x \sqrt{g} \bar{c} \square_g c$$

We can see h.d. gravity [Stelle, '77] as gauge fixed agravity [Salvio and Strumia, 2014]

$$S = S_{\text{wg}} + S_{\text{gf}} + S_{\text{gh}} = \int d^4x \sqrt{g} \left\{ \frac{1}{2\lambda} W^2 + \frac{1}{2\eta} E_4 + \frac{1}{2\alpha} R^2 \right\} + 6 \int d^4x \sqrt{g} \bar{c} \square_g c$$

Invariant matter

- If we are give an invariant action of matter fields coupled to gravity

$$\Delta S[g, \psi] = S[\Omega^2 g, \Omega^{w_\psi} \psi] - S[g, \psi] = \int d^d x \sqrt{g} \Phi H_g(\Omega)$$

At linear level

$$\frac{\delta}{\delta \omega_1} \int d^d x \sqrt{g} \Phi \square \omega_1 = 2\omega_1 g_{\mu\nu} \frac{\delta S}{\delta g_{\mu\nu}} + w_\psi \psi \frac{\delta S}{\delta \psi} \stackrel{!}{=} -\sqrt{g} \omega_1 T_\mu^\mu$$
$$T_\mu^\mu = -\square \Phi \quad \text{on-shell}$$

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- e.g. scalar φ with $w_\varphi = -1$

$$S[g, \varphi] = \int d^4 x \sqrt{g} \left\{ \frac{1}{2} \partial_\mu \varphi \partial^\mu \varphi + \frac{\xi}{2} R \varphi^2 + \frac{1}{4!} \lambda \varphi^4 \right\},$$
$$\square_g \varphi = \xi R \varphi + \frac{\lambda}{6} \varphi^3, \quad T^\mu_\mu = \square_g \left\{ 3 \left(\xi - \frac{1}{6} \right) \varphi^2 \right\}$$

General formalism

Generalize the framework. Consider a generic tensor \mathcal{T} with the following transformation

$$\mathcal{T}(g) \xrightarrow{\Omega} \mathcal{T}(\Omega^2 g) = \Omega^{-\Delta} (\mathcal{T}(g) + O_g(\Omega)) ,$$

- Impose $O_g(1) = 0$
- Impose closure for two consecutive transformations Ω_1 and Ω_2

$$O_g(\Omega_1 \Omega_2) = O_g(\Omega_1) + \Omega_1^\Delta O_{\Omega_1^2 g}(\Omega_2) = O_g(\Omega_2) + \Omega_2^\Delta O_{\Omega_2^2 g}(\Omega_1) .$$

- Constrain the form of the trace of the EMT

$$\frac{\delta}{\delta \omega_1} \int d^d x \sqrt{g} \Phi O_{\text{lin}}(\omega_1) \stackrel{!}{=} -\sqrt{g} \omega_1 T_\mu^\mu \quad \Rightarrow \quad T_\mu^\mu = -O_{\text{lin}}^\dagger(\Phi)$$

- Deduce the anomaly

$$\langle T_\mu^\mu \rangle = -\langle O_{\text{lin}}^\dagger(\Phi) \rangle + \mathcal{A} + \beta\text{-terms}$$

Non-local nature of restricted symmetries

Consider a 1-dimensional toy-model with scale invariance [Glavan, Noris and Zlošnik, 2024]

$$S[\sigma] = \int_{t_a}^{t_b} dt \left(\frac{\ddot{\sigma}}{\sigma} - \frac{\dot{\sigma}^2}{2\sigma^2} \right)^2 , \quad \begin{cases} \sigma(t) \rightarrow \Sigma(t) = \omega^{-2}(t)\sigma(t) , \\ \mathcal{D}\omega = \left(\frac{d}{dt} + \frac{\dot{\Sigma}}{\Sigma} \right) \frac{d}{dt}\omega = 0 \end{cases}$$

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Note that even if the action is invariant, equations of motion do transform

$$0 = \mathcal{E}(\sigma) \quad \longrightarrow \quad \mathcal{E}(\Sigma) = 2\dot{\omega}\Sigma \frac{d}{dt}A(\Sigma, \omega)$$

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The non-locality of ω changes the boundary value problem

$$\begin{cases} \delta\sigma(t_a) = \delta\dot{\sigma}(t_a) = 0 , \\ \delta\sigma(t_b) = \delta\dot{\sigma}(t_b) = 0 , \end{cases} \quad \rightarrow \quad \begin{cases} \delta\Sigma(t_a) = \delta\dot{\Sigma}(t_a) = 0 , \\ \delta\Sigma(t_b) = 2\Sigma_b^2 \frac{\omega_b}{\omega_b} \int_{t_a}^{t_b} dt \frac{\delta\Sigma(t)}{\Sigma^2(t)} , \\ \delta\dot{\Sigma}(t_b) = 2\Sigma_b^2 \frac{\omega_b}{\omega_b} \left(\frac{\dot{\Sigma}_b}{\Sigma_b} + \frac{\dot{\omega}_b}{\omega_b} \right) \int_{t_a}^{t_b} dt \frac{\delta\Sigma(t)}{\Sigma^2(t)} \end{cases}$$

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$$\boxed{\delta S = \int_{t_a}^{t_b} dt \frac{d}{dt} \left(\Sigma \frac{\dot{\omega}}{\omega} \Psi^2 \right)}, 0 = \mathcal{E}(\sigma, \psi) \rightarrow \mathcal{E}(\Sigma, \Psi) = 2\dot{\omega}\Sigma \frac{d}{dt} A(\Sigma, \omega) + \dots$$

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Add an interaction with a matter field

$$\frac{d}{dt} (\sigma \dot{\psi}) = 0 \rightarrow \frac{d}{dt} (\Sigma \dot{\Psi}) = 0; \begin{cases} \delta\psi(t_a) = 0, \\ \delta\psi(t_b) = 0, \end{cases} \rightarrow \begin{cases} \delta\Psi(t_a) = 0, \\ \delta\Psi(t_b) = -\frac{\Psi_b}{\omega_b} \int_{t_a}^{t_b} dt \frac{\dot{\omega}(t)}{\Sigma(t)} \delta\Sigma(t), \end{cases}$$

Classification: Two derivatives

- Scalar constraints

Most general constraint of degree two homogeneous in Ω and shift invariant

$$C_g(\Omega) = s_1 \Omega \square_g \Omega + s_2 g^{\alpha\beta} \partial_\alpha \Omega \partial_\beta \Omega,$$

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Closure and associativity enforce

- $s_1 \neq 0$: $C_g(\Omega)$ proportional to $\Omega H_g(\Omega)$
- $s_1 = 0$: $C_g(\Omega) = s_2 g^{\alpha\beta} \partial_\alpha \Omega \partial_\beta \Omega = 0$ light cone
- Adding non derivative terms projects on Ricci-scalar-flat spacetimes

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- Tensor constraints

Most general tensorial structure

$$C_{g,\mu\nu}(\Omega) = c_1 \Omega \nabla_\mu \partial_\nu \Omega + c_2 g_{\mu\nu} \Omega \square_g \Omega + c_3 \partial_\mu \Omega \partial_\nu \Omega + c_4 g_{\mu\nu} g^{\alpha\beta} \partial_\alpha \Omega \partial_\beta \Omega,$$

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Closure and associativity enforce

- $c_1 = 0$ implies $c_3 = 0 \Rightarrow$ scalar case
- $c_1 \neq 0 \Rightarrow c_2 = 0, -\frac{1}{d}$ and the constraint can be written as

$$C_{g,\mu\nu}(\Omega) = -\Omega^3 L_{g,\mu\nu}(\Omega) + g_{\mu\nu} \Omega \left(\frac{1}{d} + c_2 \right) H_g(\Omega),$$

$$L_{g,\mu\nu}(\Omega) = \left(\nabla_\mu \nabla_\nu - \frac{1}{d} g_{\mu\nu} \square_g \right) \Omega^{-1} = 0$$

$c_2 = 0$: tensor harmonic, $c_2 = -\frac{1}{d}$ Liouville-Weyl: $\tilde{K}_{\mu\nu} \rightarrow \tilde{K}'_{\mu\nu} = \tilde{K}_{\mu\nu} + \Omega L_{g,\mu\nu}(\Omega)$

[Kühnel and Rademacher, '95; Shaposhnikov and A. Tokareva, 2023]

Invariant scalar theories in $d = 4$

Harmonic Weyl invariant theories

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- scalar with $w_\varphi = -1$

$$(4\pi)^2 \mathcal{A} = \frac{1}{120} W_{\alpha\beta\mu\nu}^2 - \frac{1}{360} E_4 + \frac{1}{2} \left(\xi - \frac{1}{6} \right)^2 R^2 ,$$

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- higher derivatives scalar with $w_\varphi = 0$

$$S[\varphi, g] = \int d^4x \sqrt{g} \left\{ \frac{1}{2} \square_g \varphi \square_g \varphi - R^{\mu\nu} \partial_\mu \varphi \partial_\nu \varphi + \xi R \partial_\mu \varphi \partial^\mu \varphi + \lambda \partial_\mu \varphi \partial^\mu \varphi \partial_\nu \varphi \partial^\nu \varphi \right\}$$

$$T_\mu^\mu \stackrel{!}{=} 6 \left(\xi - \frac{1}{3} \right) \square (\partial^\mu \varphi \partial_\mu \varphi) \quad \Rightarrow \quad (4\pi)^2 \mathcal{A} = -\frac{1}{30} W_{\alpha\beta\mu\nu}^2 + \frac{7}{180} E_4 + \left(\tilde{\xi} - \frac{1}{3} \right)^2 R^2$$

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Liouville-Weyl invariant theories: $T_\mu^\mu \stackrel{!}{=} \nabla_\mu \nabla_\nu X^{\mu\nu}$, $X_\mu^\mu = 0$

- scalar with $w_\varphi = 0$

$$S[\varphi, g] = \int d^4x \sqrt{g} \left\{ \frac{1}{2} \square_g \varphi \square_g \varphi - \frac{1}{6} R \partial_\mu \varphi \partial^\mu \varphi + \tilde{\zeta} \tilde{R}^{\mu\nu} \partial_\mu \varphi \partial_\nu \varphi + \tilde{\lambda} \partial_\mu \varphi \partial^\mu \varphi \partial_\nu \varphi \partial^\nu \varphi \right\}$$

$$X_{\mu\nu} = 2(\tilde{\zeta} + 2) \left\{ \partial_\mu \varphi \partial_\nu \varphi - \frac{1}{4} g_{\mu\nu} \partial_\rho \varphi \partial^\rho \varphi \right\},$$

$$(4\pi)^2 \mathcal{A} = -\frac{1}{30} W_{\alpha\beta\mu\nu}^2 + \frac{7}{180} E_4 + \frac{1}{12} (2 + \tilde{\zeta})^2 \tilde{R}_{\mu\nu}^2$$

Higher derivatives, higher dimensions ($d \geq 4$)

Use the properties of Q -curvatures to construct constraints and invariant actions

$$Q_{4,g} = \frac{d}{2}\mathcal{K}^2 - 2K^{\mu\nu}K_{\mu\nu} - \square_g\mathcal{K}, \quad Q_{4,\Omega^2 g} = \Omega^{-4} [Q_{4,g} + O_{Q_{4,g}}(\Omega)]$$

with $O_{Q_{4,g}}(\Omega) = \dots$ *a very long expression ...*

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$$Q_{4,g} = \frac{d}{2}\mathcal{K}^2 - 2K^{\mu\nu}K_{\mu\nu} - \square_g \mathcal{K}, \quad Q_{4,\Omega^2 g} = \Omega^{-4} [Q_{4,g} + O_{Q_{4,g}}(\Omega)]$$

with $O_{Q_{4,g}}(\Omega) = \dots$ a very long expression ...

$$O_{Q_{4,g}}^{d=6}(\Omega) = \frac{1}{\Omega} \left[\square_g^2 + R_{\mu\nu} \nabla^\mu \nabla^\nu - \frac{1}{2} R \square_g \right] \Omega$$

$$O_{\text{lin},g}(\omega_1) = \left[\square_g^2 - \frac{d^2 - 4d + 8}{2(d-2)(d-1)} R \square_g + \frac{4}{d-2} R^{\mu\nu} \nabla_\mu \nabla_\nu - \frac{d-6}{2(d-1)} \nabla^\mu R \nabla_\mu \right] \omega_1$$

Higher derivatives, higher dimensions ($d \geq 4$)

Use the properties of Q -curvatures to construct constraints and invariant actions

$$Q_{4,g} = \frac{d}{2}\mathcal{K}^2 - 2K^{\mu\nu}K_{\mu\nu} - \square_g \mathcal{K}, \quad Q_{4,\Omega^2 g} = \Omega^{-4} [Q_{4,g} + O_{Q_{4,g}}(\Omega)]$$

with $O_{Q_{4,g}}(\Omega) = \dots$ a very long expression ...

$$O_{Q_{4,g}}^{d=6}(\Omega) = \frac{1}{\Omega} \left[\square_g^2 + R_{\mu\nu} \nabla^\mu \nabla^\nu - \frac{1}{2} R \square_g \right] \Omega$$

$$O_{\text{lin},g}(\omega_1) = \left[\square_g^2 - \frac{d^2 - 4d + 8}{2(d-2)(d-1)} R \square_g + \frac{4}{d-2} R^{\mu\nu} \nabla_\mu \nabla_\nu - \frac{d-6}{2(d-1)} \nabla^\mu R \nabla_\mu \right] \omega_1$$

Construct a quadratic invariant action for a scalar with $w_\varphi = \frac{4-d}{2}$

$$S[\varphi, g] = \frac{1}{2} \int d^d x \sqrt{g} \varphi (\Delta_4 + \xi Q_4) \varphi,$$

$$\Delta_4 = \square_g^2 + \nabla_\mu [4K^{\mu\nu} - (d-2)g^{\mu\nu} \mathcal{J}] \nabla_\nu + \frac{d-4}{2} Q_4$$

for which

$$T_\mu^\mu = \frac{\xi}{2} O_{\text{lin},g}(\varphi^2) + \frac{d-4}{2} \varphi (\Delta_4 + \xi Q_4) \varphi$$

Conclusions and outlook

Summary

- We classified groupoids with two derivatives
- Gave examples of higher derivative constraints
- Found the expression for the classical trace of the EMT and its 1-loop anomaly

Outlook

- Understand the geometry the metric space constrained by the restricted symmetries
- Clarify the role of such symmetries for gravitational theories
- Clarify the issues due to non-localities