## Probabilistic Inference and Applications to Frontier Physics – Part 2 –

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## What is probability?



# What is probability?

"How much we believe something"

Versione velocizzata per MAPSES 2011  $\rightarrow$  slide mancanti sulla pagina web dedicata

G. D'Agostini, Probabilistic Inference (MAPSES - Lecce 23-24/11/2011) - p

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<sup>1</sup>While in ordinary speech "to come true" usually refers to an event that is envisaged before it has happened, we use it here in the general sense, that the verbal description turns out to agree with actual facts.



A reminder

Forse vale la pena di ricordare la famosa citazione di Einstein

La geometria, quando è certa, non dice nulla del mondo reale, e, quando dice qualcosa a proposito della nostra esperienza, è incerta.

Chi vuole attenersi al regno del certo è meglio che si occupi di matematica che di fisica.

#### An helpful diagram

The previous diagram seems to help the understanding of the concept of probability



#### An helpful diagram



• Figure 2-1. Graphical abstraction of probability as a measure of information (adapted from "Probability and Measurement Uncertainty in Physics" by D'Agostini, [1995]).

(... but NASA guys are afraid of 'subjective', or 'psychological')

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- $\Rightarrow$  intrinsic subjective nature.
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- $\Rightarrow$  intrinsic subjective nature.
  - No negative meaning: only an acknowledgment that several persons might have different information and, therefore, necessarily different opinions.
  - "Since the knowledge may be different with different persons or with the same person at different times, they may anticipate the same event with more or less confidence, and thus different numerical probabilities may be attached to the same event" (Schrödinger)

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Probability is always conditional probability

 $P(E)' \longrightarrow P(E \mid I) \longrightarrow P(E \mid I(t))$ 

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• "Thus whenever we speak loosely of 'the probability of an event,' it is always to be understood: probability with regard to a certain given state of knowledge" (Schrödinger)

• Wide range of applicability

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- Probability statements all have the same meaning no matter to what they refer and how the number has been evaluated.
  - $\circ$  *P*(rain next Saturday) = 68%
  - $\circ P($ Juventus will win Italian champion league) = 68%
  - $\circ P$ (free neutron decays before 17 s) = 68%
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- You might agree or disagree, but at least You know what this person has in his mind. (<u>NOT TRUE with "C.L.'s"!</u>)
- If a person has these beliefs and he/she has the chance to win a rich prize bound to one of these events, he/she has no rational reason to chose an event instead than the others.

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- Probability not bound to a single evaluation rule.
- In particular, combinatorial and frequency based 'definitions' are easily recovered as evaluation rules under well defined hypotheses.
- Keep separate concept from evaluation rule.

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## Siamo uomini o caporali?

#### Summary on probabilistic approach

- Probability means how much we believe something
- Probability values obey the following basic rules

1. 
$$0 \le P(A) \le 1$$
  
2. 
$$P(\Omega) = 1$$

3. 
$$P(A \cup B) = P(A) + P(B)$$
 [if  $P(A \cap B) = \emptyset$ ]

- 4.  $P(A \cap B) = P(A | B) \cdot P(B) = P(B | A) \cdot P(A)$ ,
- All the rest by logic
- $\rightarrow$  And, please, be coherent!



## Inference

# $\Rightarrow$ How do we learn from data in a probabilistic framework?

Our original problem:



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Our conditional view of probabilistic causation

$$P(E_i \mid C_j)$$

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Our conditional view of probabilistic causation

$$P(E_i \mid C_j)$$

Our conditional view of probabilistic inference

$$P(C_j \mid E_i)$$

Our original problem:



Our conditional view of probabilistic causation

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Our conditional view of probabilistic inference

 $P(C_j \mid E_i)$ 

The fourth basic rule of probability:

 $P(C_j, E_i) = P(E_i | C_j) P(C_j) = P(C_j | E_i) P(E_i)$ 

#### Symmetric conditioning

Let us take basic rule 4, written in terms of hypotheses  $H_j$  and effects  $E_i$ , and rewrite it this way:

$$\frac{P(H_j \mid E_i)}{P(H_j)} = \frac{P(E_i \mid H_j)}{P(E_i)}$$

"The condition on  $E_i$  changes in percentage the probability of  $H_j$  as the probability of  $E_i$  is changed in percentage by the condition  $H_j$ ."
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Got 'after'

Calculated 'before'

(where 'before' and 'after' refer to the knowledge that  $E_i$  is true.)

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"post illa observationes"

"ante illa observationes"

(Gauss)

Application to the six box problem



Remind:

- $E_1 = White$
- $E_2 = \mathsf{Black}$

Our tool:

$$P(H_j | E_i, I) = \frac{P(E_i | H_j, I)}{P(E_i | I)} P(H_j | I)$$

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- $P(H_j \mid I) = 1/6$
- $P(E_i | I) = 1/2$
- $P(E_i \mid H_j, I)$  :

 $P(E_1 | H_j, I) = j/5$  $P(E_2 | H_j, I) = (5-j)/5$ 

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 $\sim$  Our prior belief about  $H_j$ 

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- Probability of  $E_i$  under a well defined hypothesis  $H_j$ It corresponds to the 'response of the apparatus in measurements.

 $\rightarrow$  likelihood (traditional, rather confusing name!)

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→ Probability of  $E_i$  taking account all possible  $H_j$ → How much we are confident that  $E_i$  will occur.

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- Probability of  $E_i$  taking account all possible  $H_j$   $\rightarrow$  How much we are confident that  $E_i$  will occur. Easy in this case, because of the symmetry of the problem. But already after the first extraction of a ball our opinion about the box content will change, and symmetry will break.

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'decomposition law':  $P(E_i | I) = \sum_j P(E_i | H_j, I) \cdot P(H_j | I)$ ( $\rightarrow$  Easy to check that it gives  $P(E_i | I) = 1/2$  in our case).

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$$P(H_j \mid I) = 1/6$$

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# We are ready! $\longrightarrow$ Let's play with our toy

Naming the method

Some 'remarks' on formalism and notation.

(But nothing deep!)

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From now on it is only a question of

- experience and good sense to model the problem;
- patience;
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Moving to continuous quantities:

- transitions discrete→continuous rather simple;
- prob. functions  $\rightarrow$  pdf
- learn to summarize the result in 'a couple of meaningful numbers' (but remembering that the full answer is in the final pdf).

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Neglecting the background state of information *I*:  $P(H_i | E_i) \qquad P(E_i | H_j)$ 

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Neglecting the background state of information *I*:

$\frac{P(H_j \mid E_i)}{P(H_i)}$	—	$\frac{P(E_i \mid H_j)}{P(E_i)}$
$P(H_j \mid E_i)$	=	$\frac{P(E_i \mid H_j)}{P(E_i)} P(H_j)$
$P(H_j   E_i)$	=	$\frac{P(E_i \mid H_j) \cdot P(H_j)}{\sum_j P(E_i \mid H_j) \cdot P(H_j)}$
$P(H_j \mid E_i)$	$\propto$	$P(E_i   H_j) \cdot P(H_j)$

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Different ways to write the

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Sequential use of Bayes theorem

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Old posterior becomes new prior, and so on

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$$\propto P(E^{(2)} | H_j) \cdot P(H_j | E^{(1)})$$
  
$$\propto P(E^{(2)} | H_j) \cdot P(E^{(1)} | H_j) \cdot P_0(H_j)$$

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$$P(H_{j} | E^{(1)}, E^{(2)}) \propto P(E^{(2)} | H_{j}, E^{(1)}) \cdot P(H_{j} | E^{(1)})$$
  

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$$\propto P(E^{(2)} | H_{j}) \cdot P(E^{(1)} | H_{j}) \cdot P_{0}(H_{j})$$
  

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$$\propto P(E^{(1)}, E^{(1)} | H_{j}) \cdot P_{0}(H_{j})$$

$$P(H_{j} | data) \propto P(data | H_{j}) \cdot P_{0}(H_{j})$$

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$$P(H_{i} | data) \propto P(data | H_{i}) \cdot P_{0}(H_{i})$$

# Bayesian inference

Let us repeat the experiment:

1

Sequential use of Bayes theorem

Old posterior becomes new prior, and so on

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$$\propto P(E^{(2)} | H_{j}) \cdot P(H_{j} | E^{(1)})$$

$$\propto P(E^{(2)} | H_{j}) \cdot P(E^{(1)} | H_{j}) \cdot P_{0}(H_{j})$$

$$\propto P(E^{(1)}, E^{(1)} | H_{j}) \cdot P_{0}(H_{j})$$

$$P(H_{j} | data) \propto P(data | H_{j}) \cdot P_{0}(H_{j})$$

Learning from data using probability theory

**Exercises and discussions** 

- Continue with six box problem [ $\rightarrow$  AJP 67 (1999) 1260]  $\rightarrow$  Slides
- <u>Home work 1</u>: AIDS problem  $\rightarrow P(HIV | Pos)$ ?

 $P(\mathsf{Pos}\,|\,\mathsf{HIV}) = 100\%$ 

 $P(\mathsf{Pos} | \overline{\mathsf{HIV}}) = 0.2\%$ 

 $P(\text{Neg} | \overline{\text{HIV}}) = 99.8\%$ 

• <u>Home work 2</u>: Particle identification:

A particle detector has a  $\mu$  identification efficiency of 95%, and a probability of identifying a  $\pi$  as a  $\mu$  of 2%. If a particle is identified as a  $\mu$ , then a trigger is fired. Knowing that the particle beam is a mixture of  $90\%\pi$  and  $10\%\mu$ , what is the probability that a trigger is really fired by a  $\mu$ ? What is the signal-to-noise (S/N) ratio?

# Odd ratios and Bayes factor

$$\begin{aligned} \frac{P(\mathsf{HIV} \mid \mathsf{Pos})}{P(\mathsf{\overline{HIV}} \mid \mathsf{Pos})} &= \frac{P(\mathsf{Pos} \mid \mathsf{HIV})}{P(\mathsf{Pos} \mid \overline{\mathsf{HIV}})} \cdot \frac{P_{\circ}(\mathsf{HIV})}{P(\overline{\mathsf{HIV}})} \\ &= \frac{\approx 1}{0.002} \times \frac{0.1/60}{\approx 1} = 500 \times \frac{1}{600} = \frac{1}{1.2} \\ \Rightarrow P(\mathsf{HIV} \mid \mathsf{Pos}) &= 45.5\% \,. \end{aligned}$$

### Odd ratios and Bayes factor

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We just make a comparison of any couple of hypotheses!

-Bayes factor is usually much more inter-subjective, and it is often considered an 'objective' way to report how much the data favor each hypothesis.
# Further comments on first meeting

The three models example

Choose among  $H_1$ ,  $H_2$  and  $H_3$  having observed x = 3:

In case of 'likelihoods' given by pdf's, the same formulae apply: " $P(\text{data} \mid H_j)$ "  $\longleftrightarrow$  " $f(\text{data} \mid H_j)$ ".



 $BF_{j,k} = \frac{f(x=3 \mid H_j)}{f(x=3 \mid H_k)}$ 

 $BF_{2,1} = 18$ ,  $BF_{3,1} = 25$  and  $BF_{3,2} = 1.4 \rightarrow$  data favor model  $H_3$  (as we can see from figure!), but if we want to state how much we believe to each model we need to 'filter' them with priors.

Assuming the three models initially equally likely, we get final probabilities of 2.3%, 41% and 57% for the three models.

A last remark on model comparisons

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- But until you don't have an alternative and credible model to explain the data, there is little to say about the "chance that the data come from the model", unless the data are really impossible.
- Why do frequentistic test often work?  $\rightarrow$  Think about... (Just by chance – no logical necessity)

What was the mistake of people saying  $P(\overline{\text{HIV}} | \text{Pos}) = 0.2$ ?

We can easily check that this is due to have set  $\frac{P_{\circ}(HIV)}{P_{\circ}(HIV)} = 1$ , that, hopefully, does not apply for a randomly selected Italian.

- This is typical in arbitrary inversions, and often also in frequentistic prescriptions that are used by the practitioners to form their confidence on something:
- $\rightarrow$  "absence of priors" means in most times uniform priors over the all possible hypotheses
  - but they criticize the Bayesian approach because it takes into account priors explicitly !

Better methods based on 'sand' than methods based on nothing!

## Inferring a rate of a Poisson process



## Inferring a rate of a Poisson process

$$f(r_s, r_b \mid x, x_0, T, T_0) \propto f(x, x_0 \mid r_s, rb, T, T_0) \cdot f_0(r_s, r_b) \\ \propto f(x \mid (r_s + r_b) \cdot T) \cdot f(x_0 \mid r_b \cdot T_0) \cdot f_0(r_s) \cdot f_0(r_s) \\ \propto f(x \mid (r_s + r_b) \cdot T) \cdot f(x_0 \mid r_b \cdot T_0) \cdot f_0(r_s) \cdot f_0(r_s) + f_0(r_s) \cdot f_0(r_s) + f$$

## Inferring a rate of a Poisson process

# Making the model more realistic



**Upper/lower limits** 

"Ogni limite ha una pazienza" (Totò)

**Upper/lower limits** 

# "Ogni limite ha una pazienza" (Totò)

A very simple problem:

- counting experiment described by a binomial of unkown p;
- our aim is to 'get' p, in the sense of evaluating f(p | data);
- we make n trials and get x = 0 successes.

**Upper/lower limits** 

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Bayes' theorem:

$$f(p \mid n, x = 0, \mathcal{B}) = \frac{f(x = 0 \mid n, \mathcal{B}) f_0(p)}{\int_0^1 f(x = 0 \mid n, \mathcal{B}) f_0(p) dp}$$

with

$$f(x=0 \mid n, \mathcal{B}) = (1-p)^n$$

Bernoulli trials  $\Rightarrow N$  boxes  $\rightarrow \infty$ 

Conceptually exactly equivalente to the 6-box problem:

- "success" ↔ "white ball"
- $p \leftrightarrow$  "proportion of white balls"
- $f(p \mid x, n) \leftrightarrow P(H_i \mid x, n)$

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- as log as we continue to extract only black boxes we get more and more convinced ('confident') that Nature has presented us H<sub>0</sub>, although we cannot exclude H<sub>1</sub>, a bit less H<sub>2</sub>, etc.

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$$P(H_N | n, x = 0) = 0 \quad \leftrightarrow \quad f(p = 1 | n, x = 0) = 0$$

Using flat prior, i.e.  $f_0(p) = k$   $f(p \mid n, x = 0, \mathcal{B}) = (n+1)(1-p)^n$   $p_{max} = 0$   $E(p) = \frac{1}{n+2} \rightarrow \frac{1}{n}$   $\sigma(p) = \sqrt{\frac{(n+1)}{(n+3)(n+2)^2}} \rightarrow \frac{1}{n}$  $p_{95\%UL} = 1 - \sqrt[n+1]{(0.05)}$ 

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As n increases, we get more and more convinced that p has to be very small



$$f(p \mid n, x = 0, \mathcal{B}) = (n+1)(1-p)^n$$
$$p_{95\%UL} = 1 - \sqrt[n+1]{0.05}.$$



Seems not problematic at all, but we have to remember that it relies on

$$f(x = 0 | n, \mathcal{B}) = (1 - p)^n$$
  
$$f_0(p) = k$$

When likelihoods are non 'closed'

Where is the problem? (Flat priors are regulary used, and are often assumed in other approaches, e.g. ML methods)

When likelihoods are non 'closed'

The major problem is not in  $f_0(p)$ , but rather in the likelihood f(x = 0, |n, B) that does not go to zero on both sides!

When likelihoods are non 'closed'

The major problem is not in  $f_0(p)$ , but rather in the likelihood f(x = 0, |n, B) that does not go to zero on both sides! A different representation of the likelihood (properly rescaled) helps:



A probabilistic lower bound for the Higgs?

A similar think happens with the direct searches of the Higgs particle at LEP



(1999 figure, but substance Unchanged)

A probabilistic lower bound for the Higgs?

Impossible to express our confidence in probabilistic terms, unless we define an upper cut!



A probabilistic lower bound for the Higgs?

# Confidence limit $\Rightarrow$ Sensitivity bound



### Conclusions

- Probabilistic reasoning helps ...
  - ... at least to avoid conceptual errors.
- Probabilistic statements can attributed, quantitatively and consistently, to all 'objects' respect to which we are in condition of uncertainty
- ...allowing us to make meaninful statements concerning true values.
- In particular uncertainties due to systematic errors can be easily included
- Several 'standard' methods (like Least Square, etc.) can be easily recovered under well defined assumptions.
- But if this is not the case, nowdays there are no longer excuses to avoid the more general approach.
- Bayesian networks are a powerful conceptual and computational tool.

# Are Bayesians 'smart' and 'brilliant'?

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