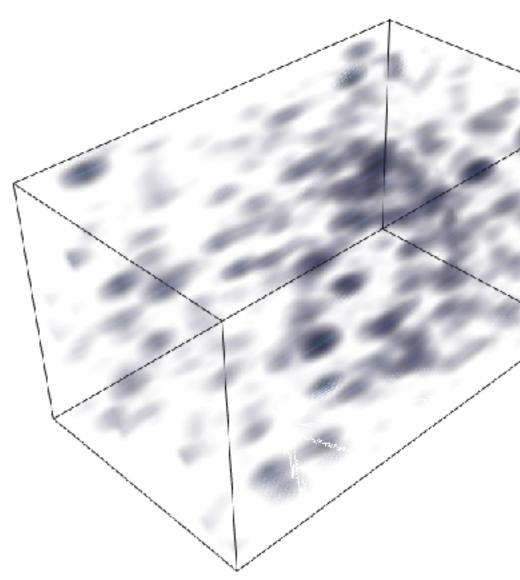
Generative models for large-scale structures

Physics in the AI Era 24 - 27 Sep. 2024

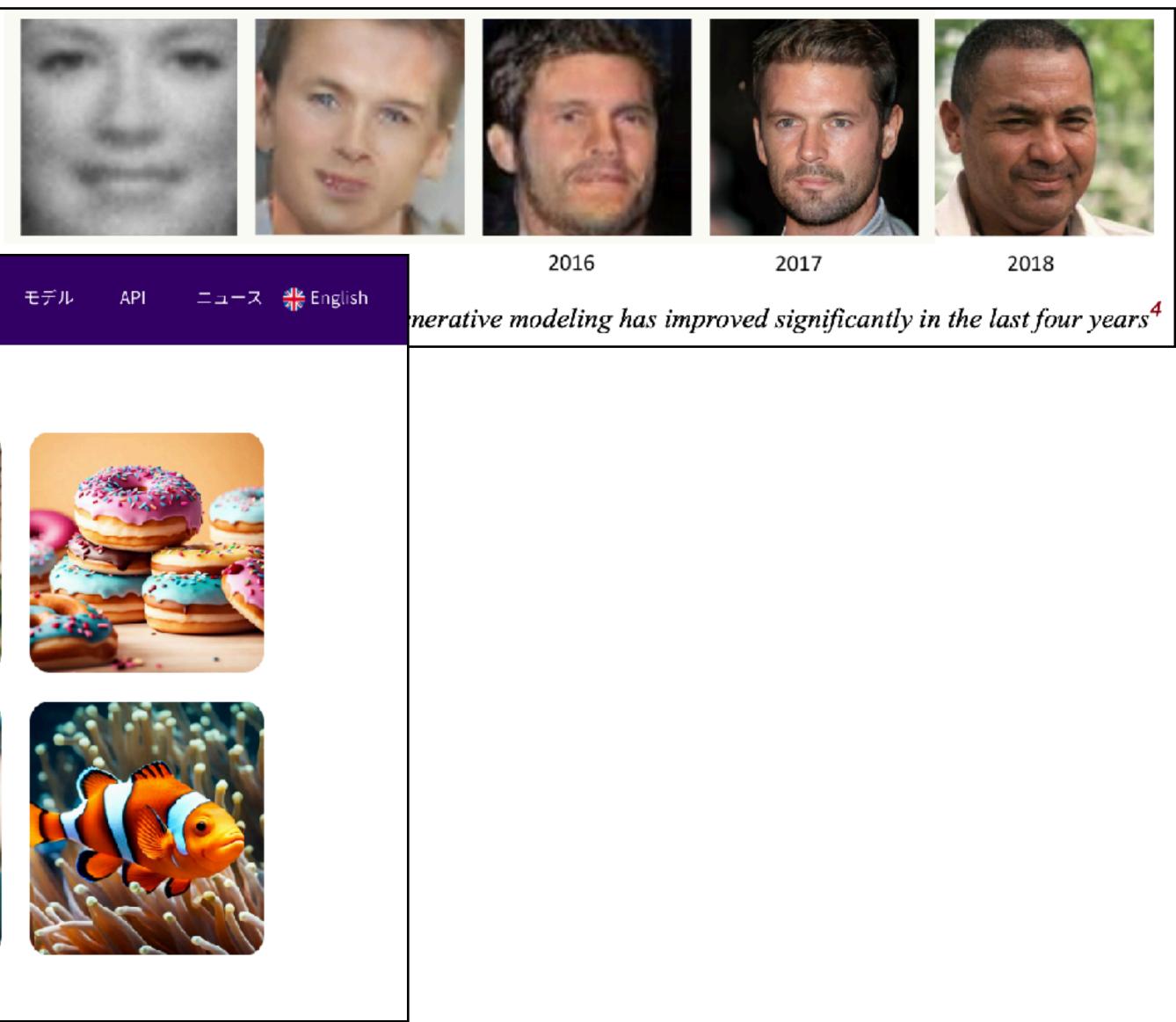
Kana Moriwaki (The University of Tokyo)







Introduction: generative models



stability.ai

Stable Diffusion XL

Create and inspire using the worlds fastest growing open source AI platform.

With Stable Diffusion XL, you can create descriptive images with shorter prompts and generate words within images. The model is a significant advancement in image generation capabilities, offering enhanced image composition and face generation that results in stunning visuals and realistic aesthetics.

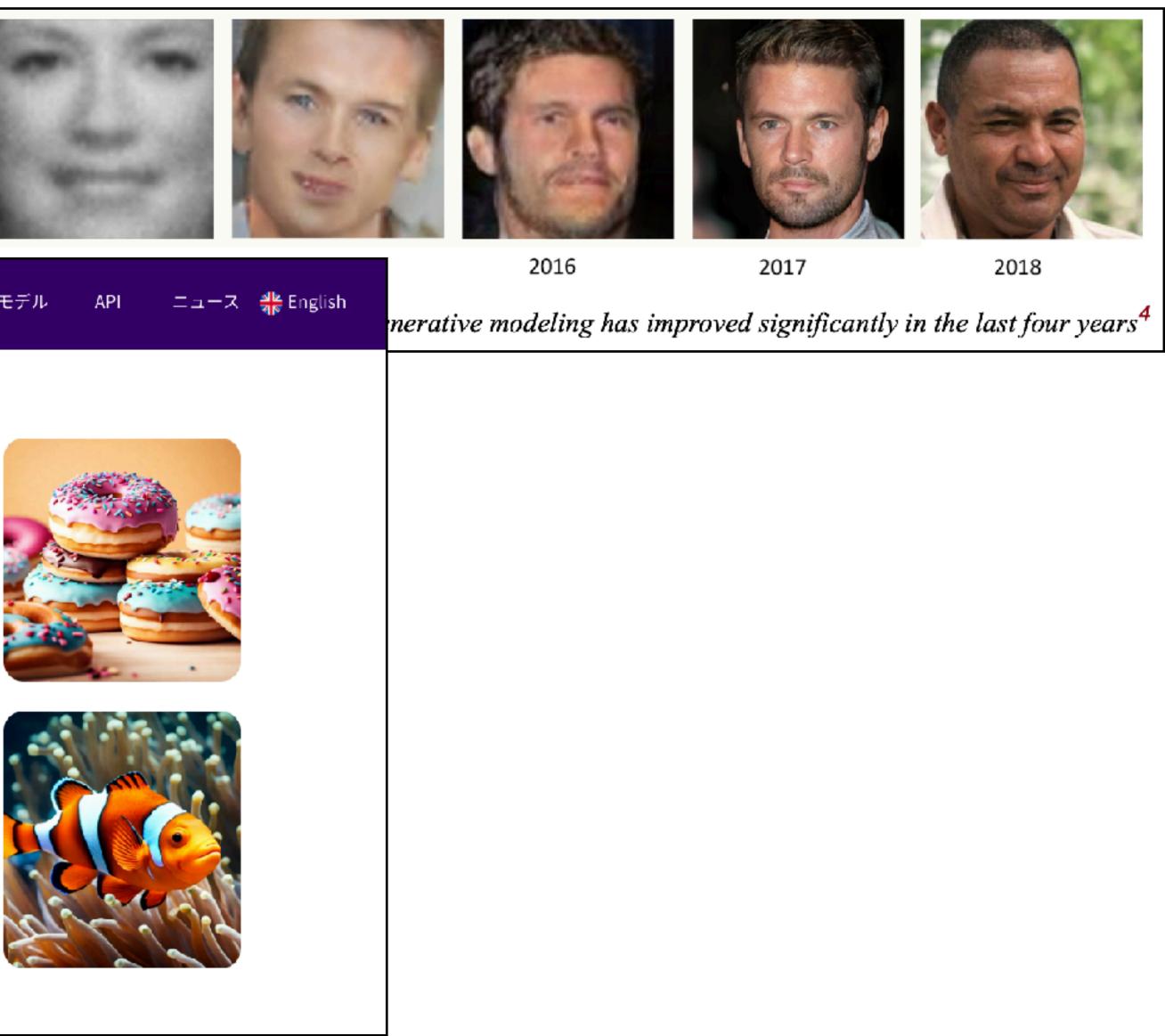
Stable Diffusion XL is currently in beta on DreamStudio and other leading imaging applications. Like all of Stability AI's foundation models, Stable Diffusion XL will be released as open source for optimal accessibility in the near future.



Stability AIについて

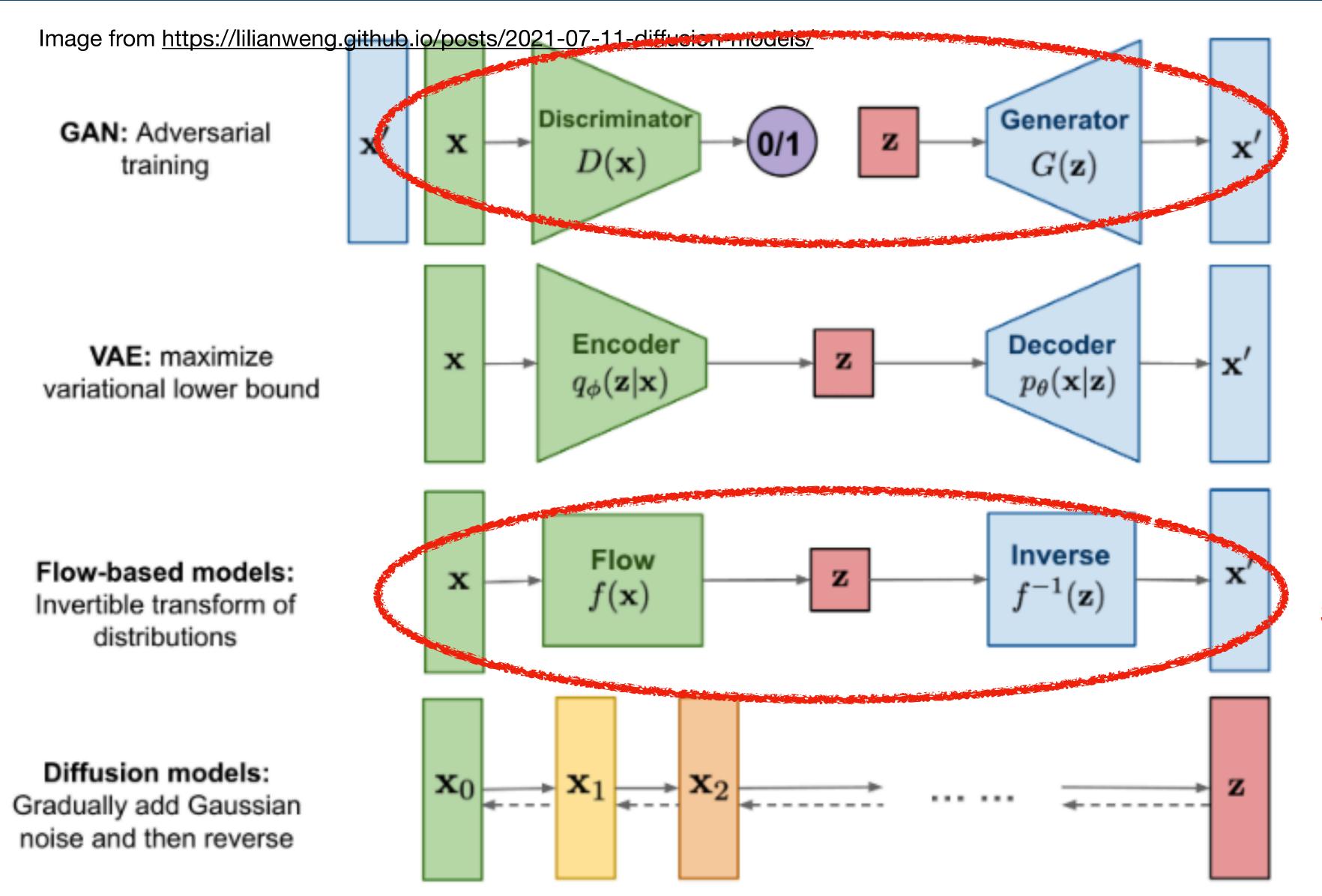






DreamStudio

There are several different generative models



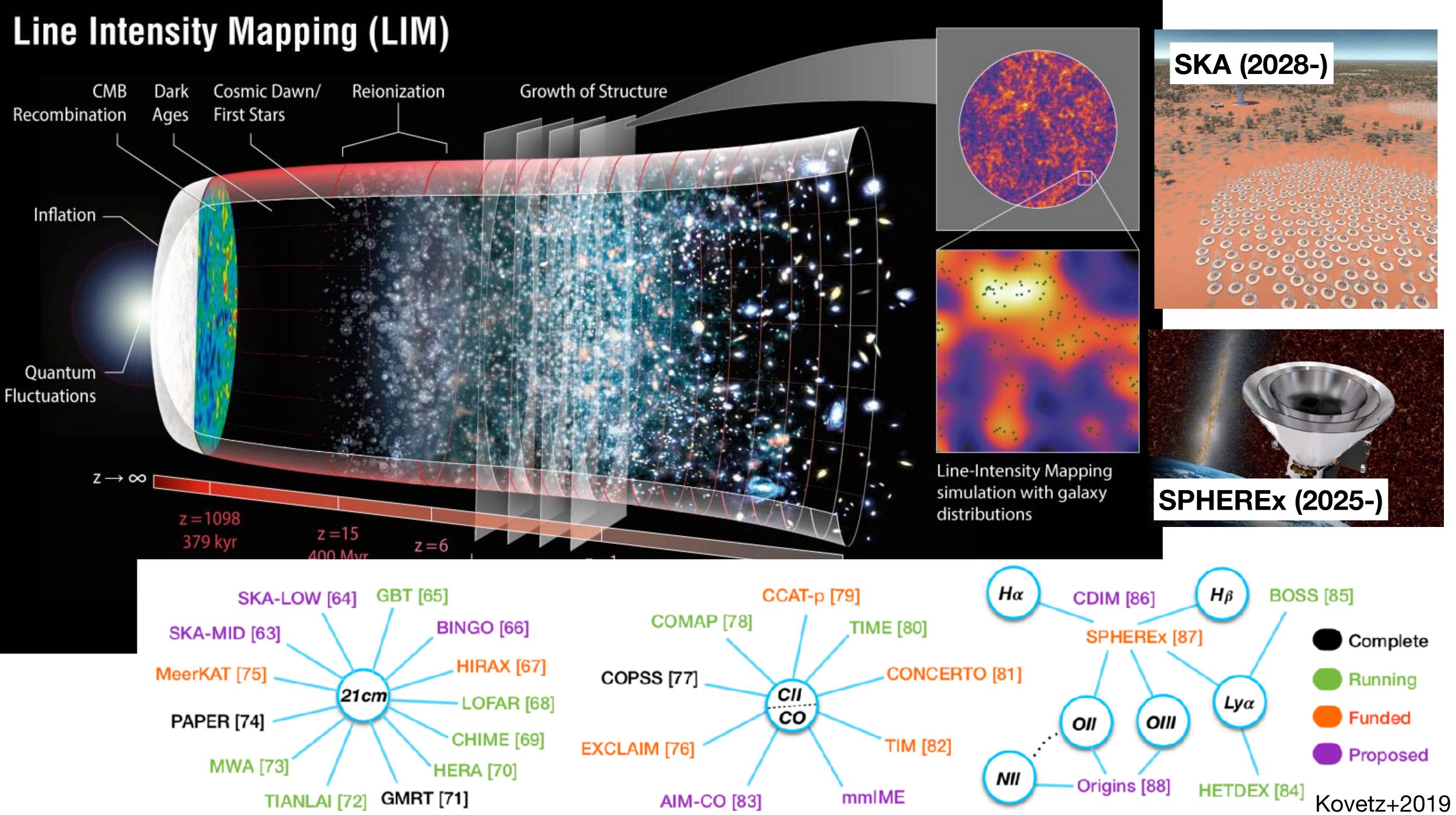
First topic: GAN for line intensity maps (Moriwaki et al. 2021)

Second topic: NF for EoR parameter inference (Moriwaki in prep)

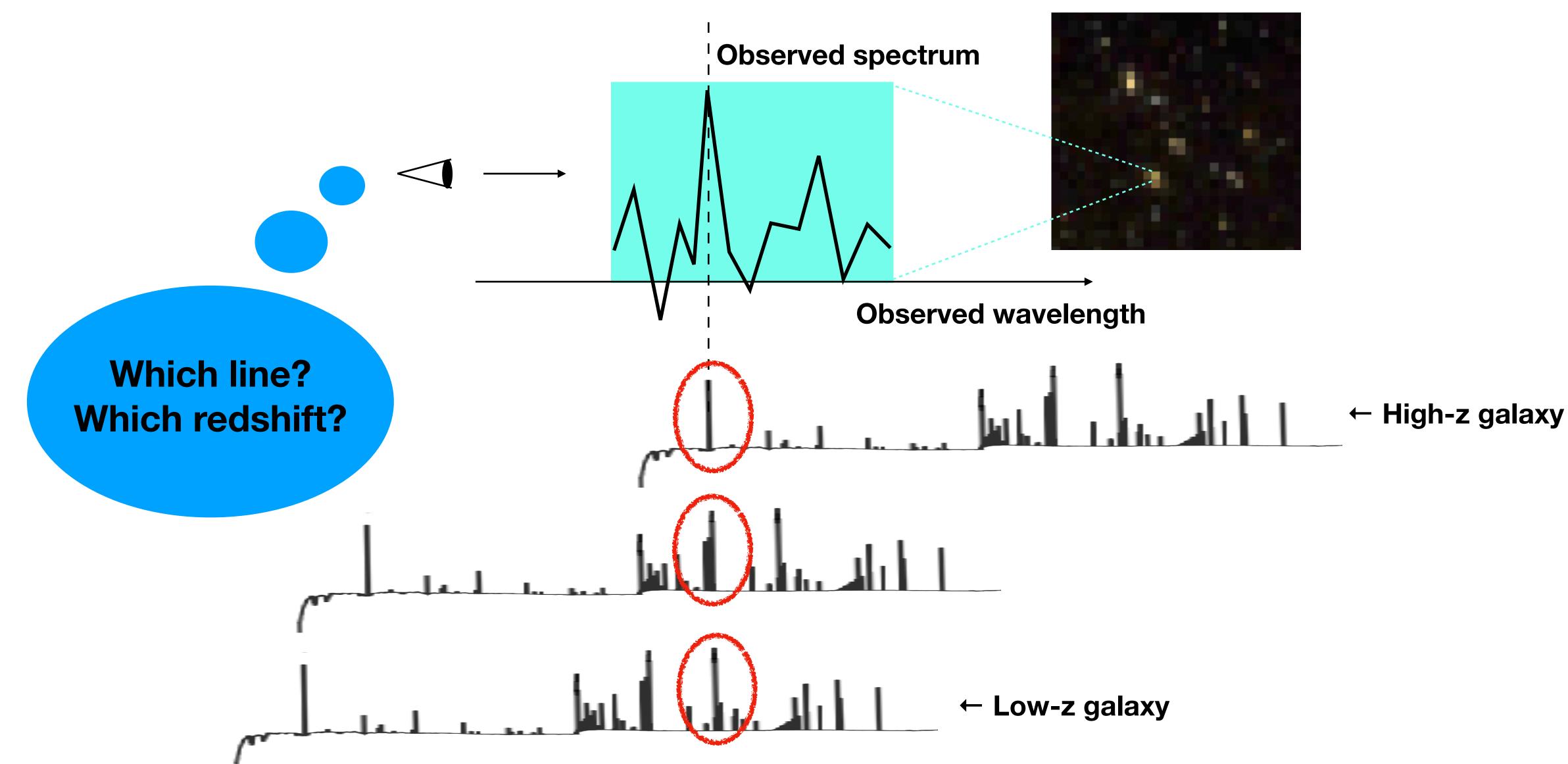


Conditional GAN for signal reconstruction from line intensity maps





A Problem: Line Confusion

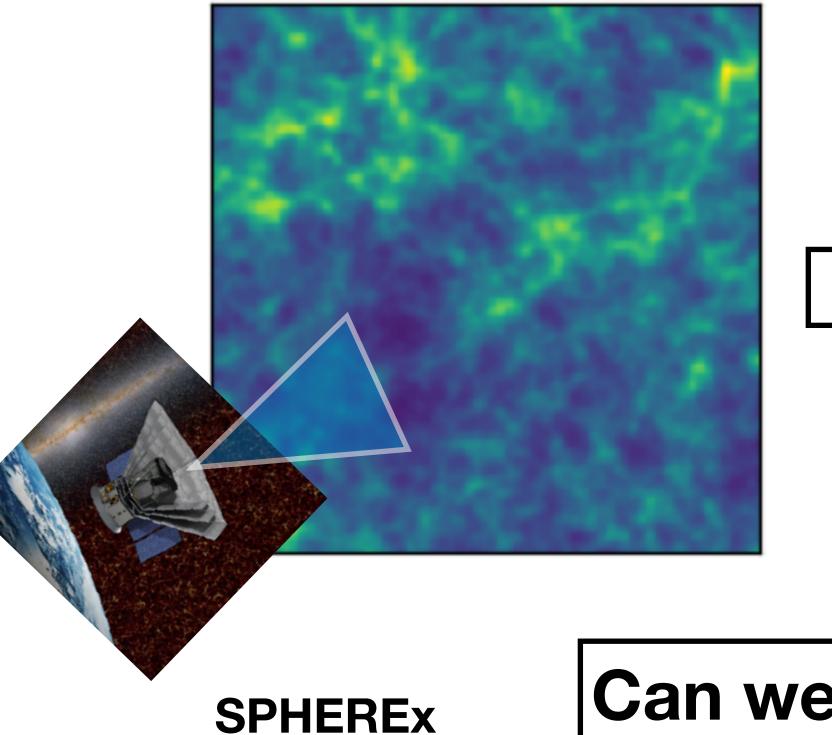


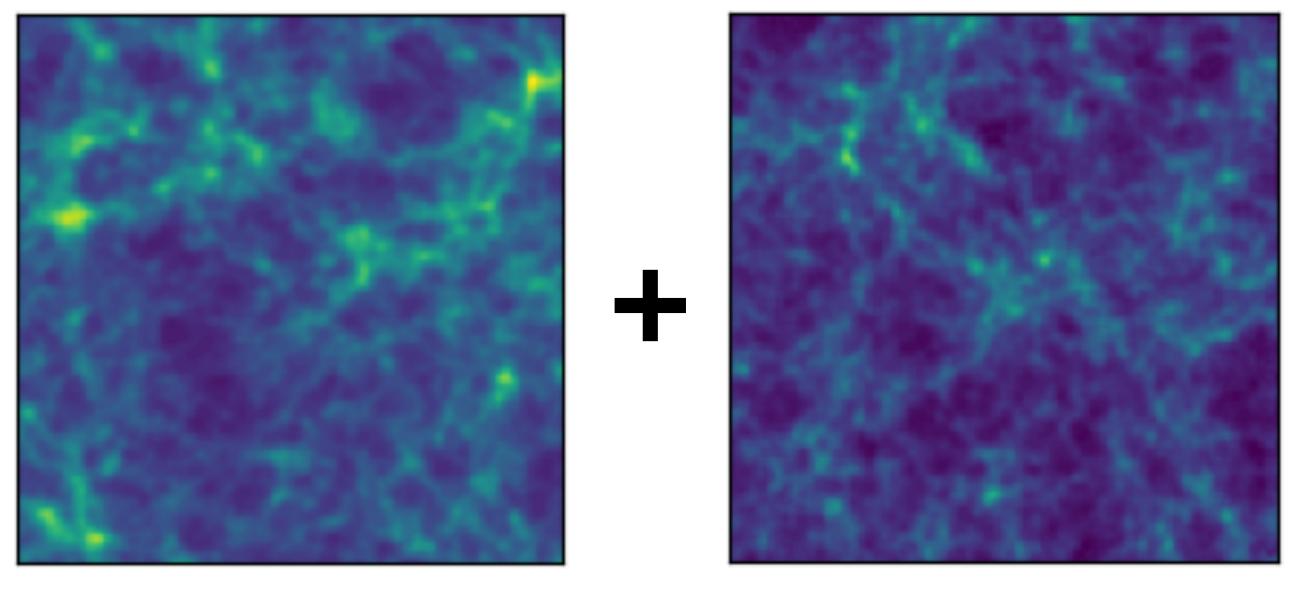




Example:

observed data at $\lambda = 1.5 \mu m$





Can we separate different signals on pixel-by-pixel basis?

A Problem: Line Confusion

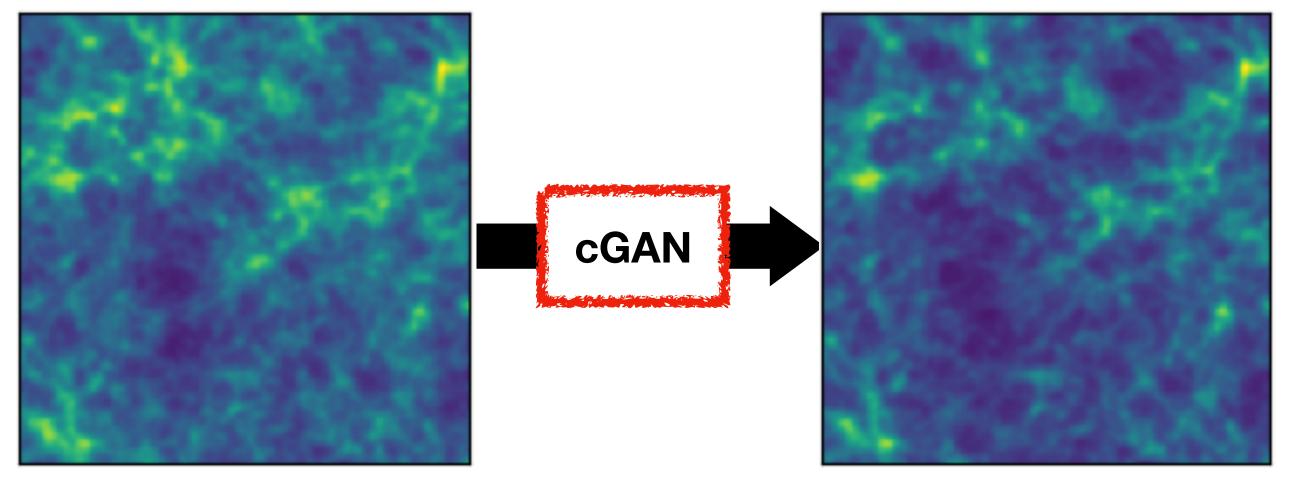
Ha intensity at z = 1.3

[OIII] intensity at z = 2.0



Our solution: deep learning

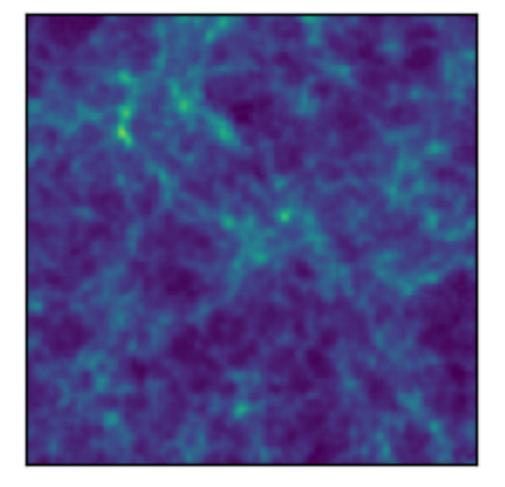
observed data at $\lambda = 1.5 \mu m$

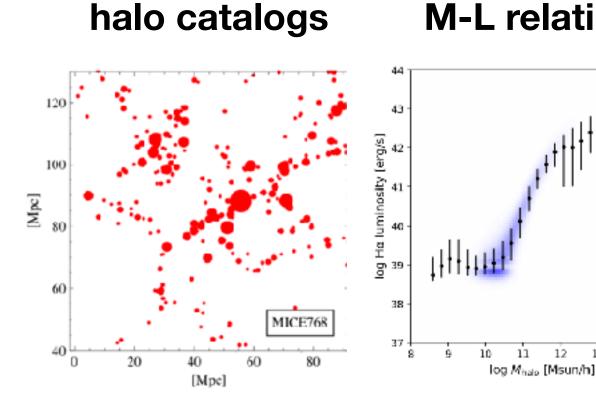


Generate ~30,000 mock observational maps using halo catalog generation code PINOCCHIO (Monaco+13) and halo mass vs line luminosity relation derived from a hydrodynamics simulation.

Ha intensity at z = 1.3

[OIII] intensity at z = 2.0



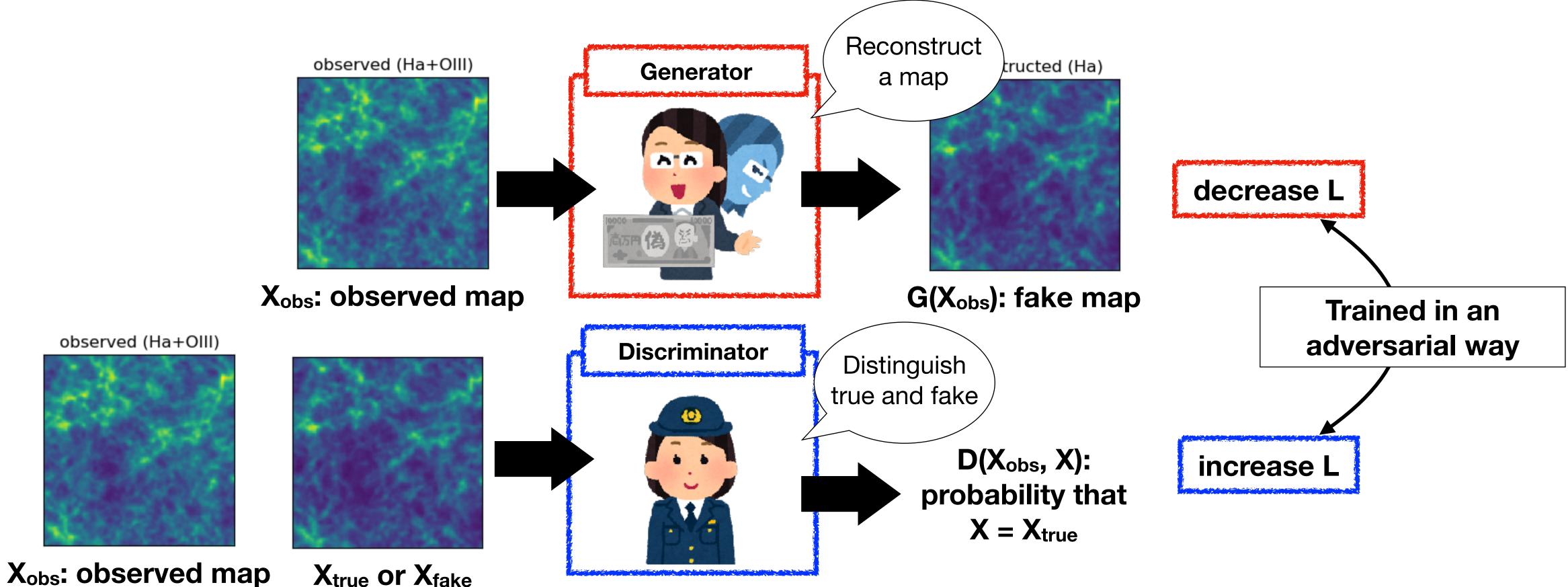




Conditional generative adversarial network

GAN: Generator and Discriminator are updated in an adversarial way.

observed (Ha+OIII)

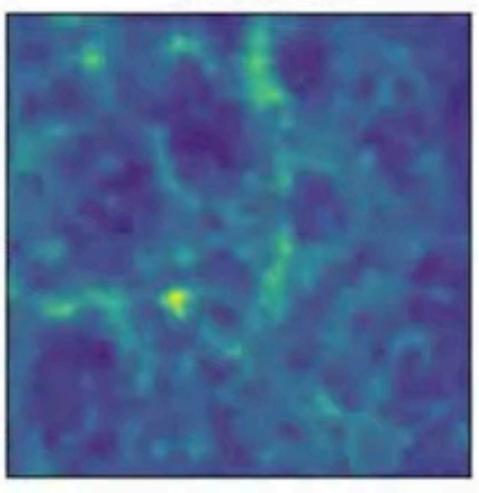


Loss function: $L[G, D] = \log D(X_{obs}, X_{true}) + \log[1 - D(X_{obs}, G(X_{obs}))] + \lambda \langle |X_{true} - G(X_{obs})| \rangle$

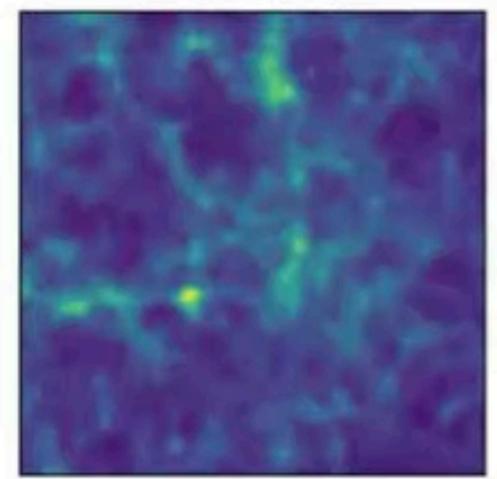


Reconstruction of the Large-Scale Distributions of Emission-Line Galaxies

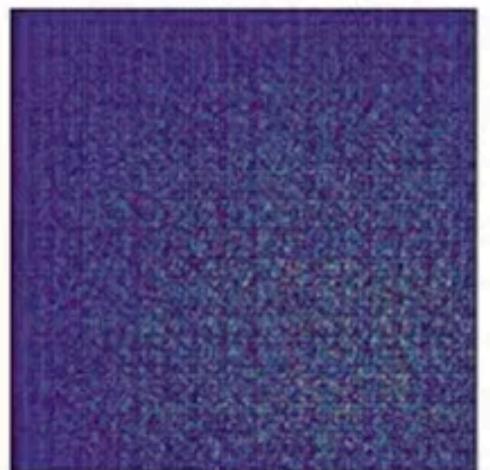
observed



CNN



+

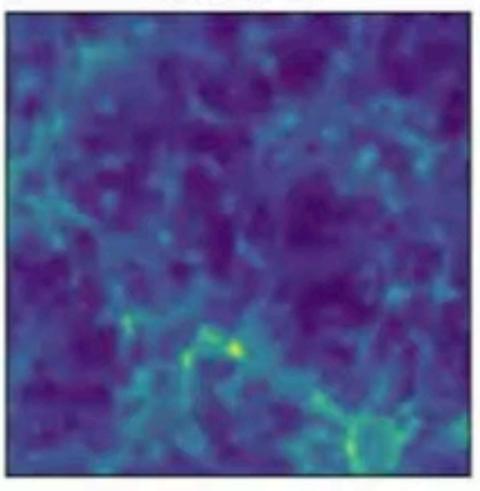


N: 1

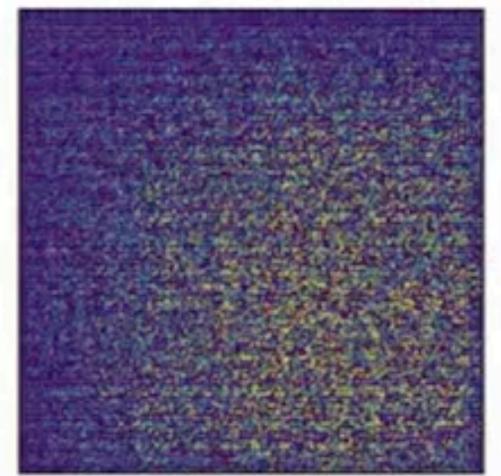
true (Ha)

reconstructed (Ha)

true (OIII)



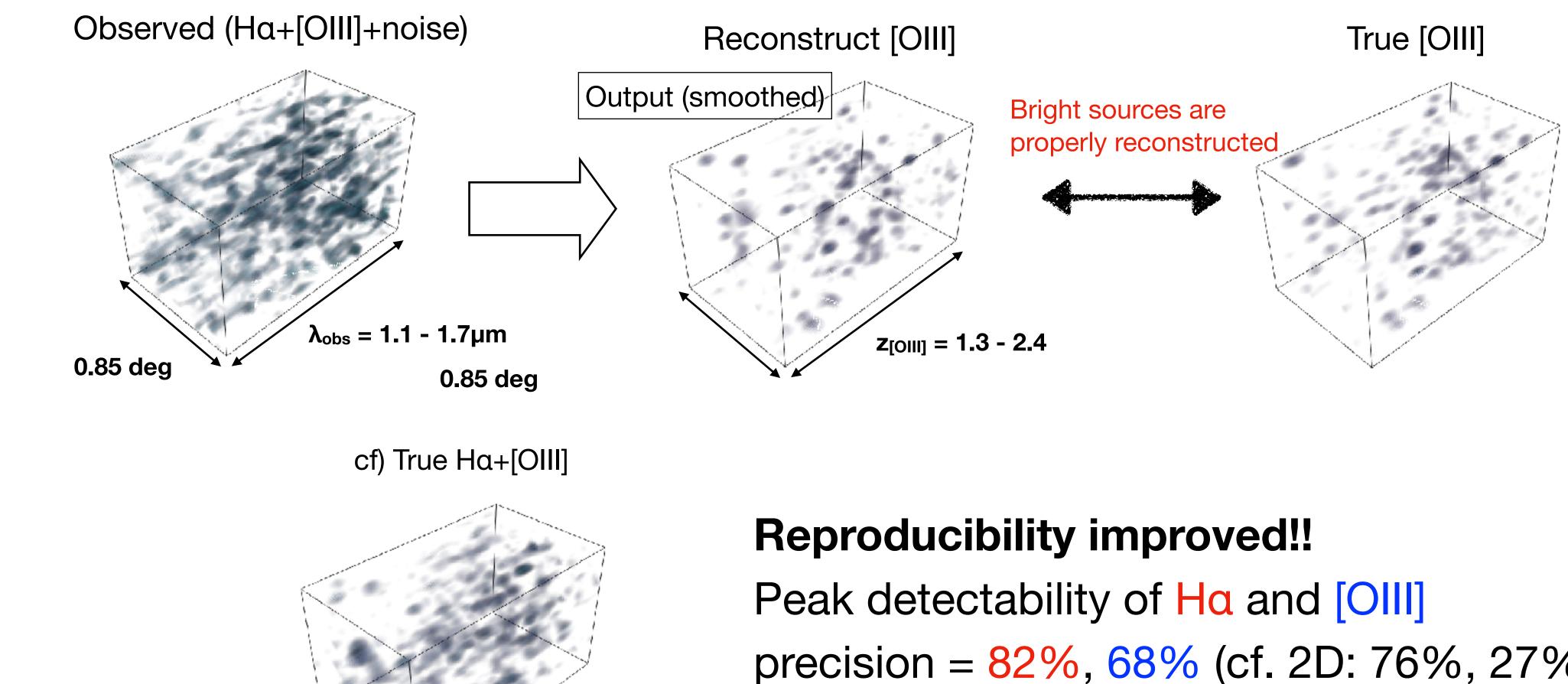
reconstructed (OIII)



https://youtu.be/J3c5Xk-5kT0



Result: reconstruction of 3D data cube



We are planning to apply this method to the future LIM observations.



precision = 82%, 68% (cf. 2D: 76%, 27%) recall = 80%, 77% (cf. 2D: 74%, 29%)

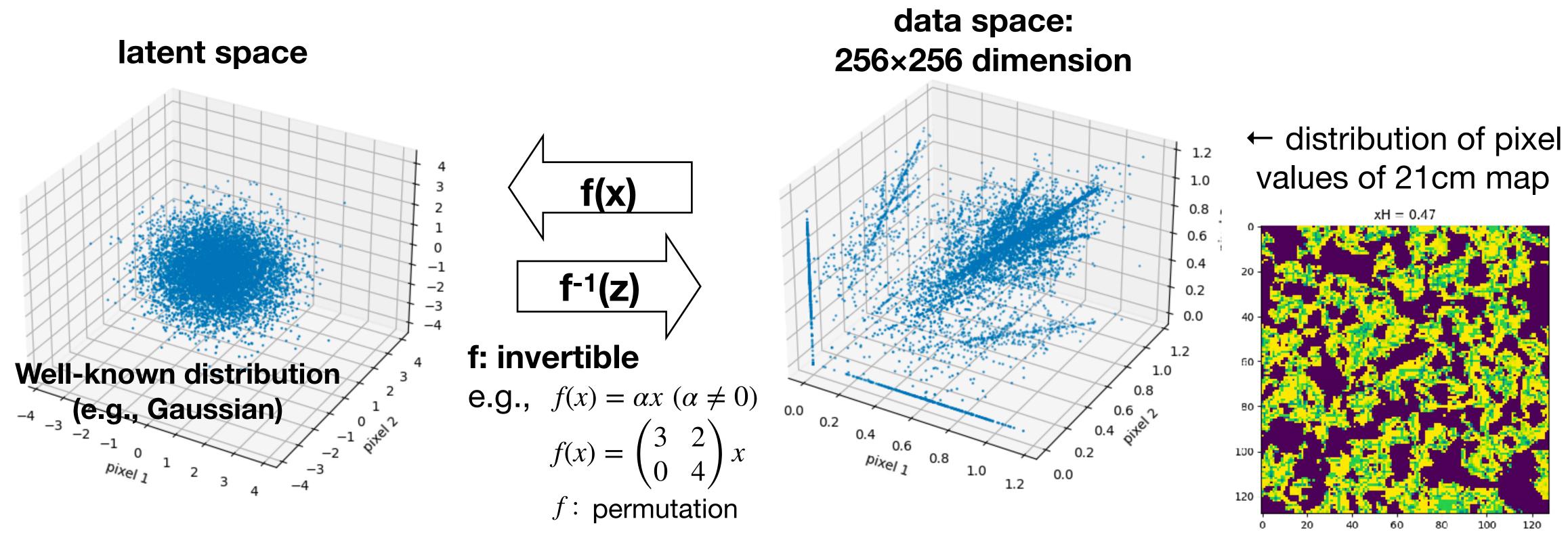


Normalizing flow for EoR parameter inference



Data space ⇔ Latent space

Flow-based models transfer data into latent space with invertible functions.

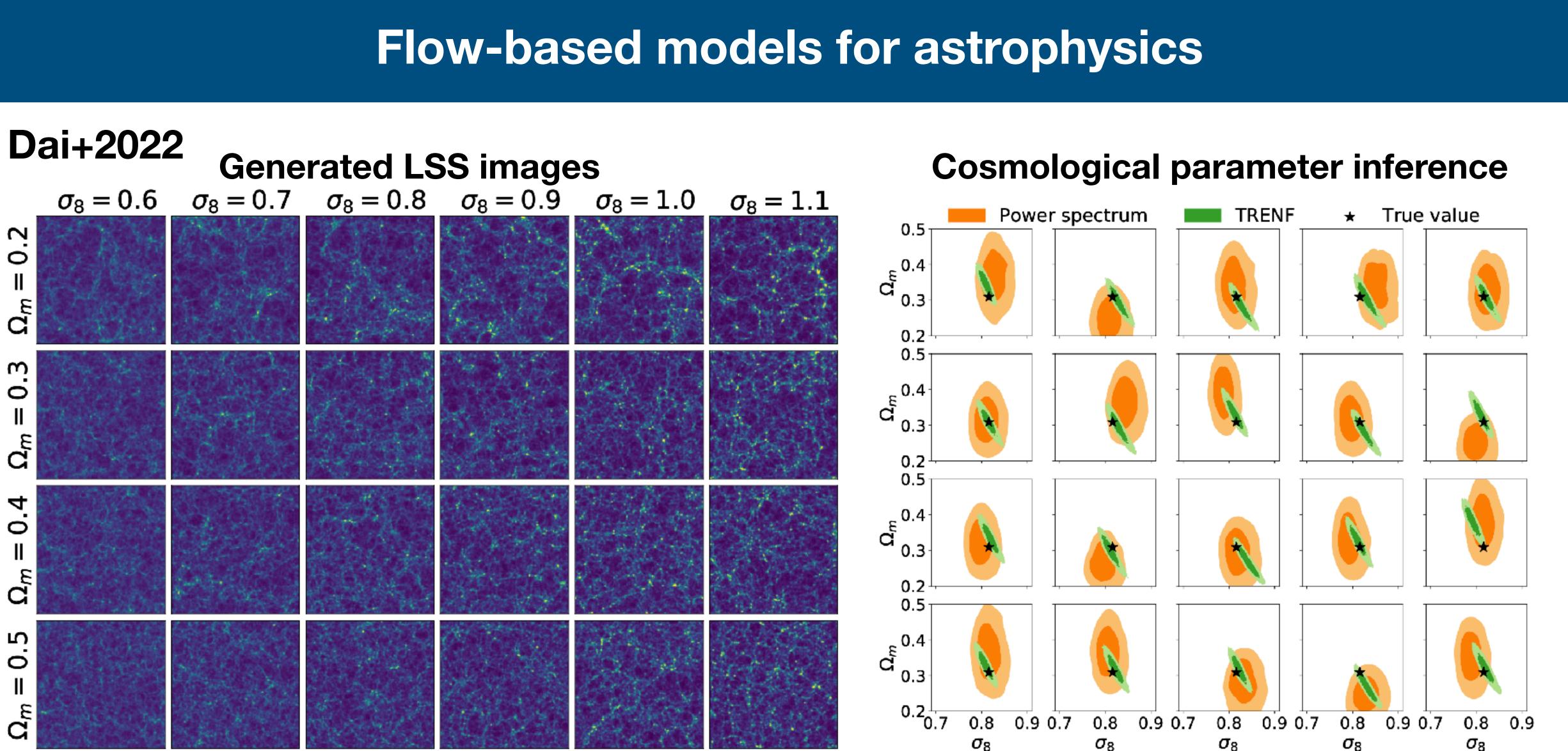


- Invertible functions can be used to infer the probability density of the data.

When generating a new data, one can sample a random point in the latent space and apply "f⁻¹"



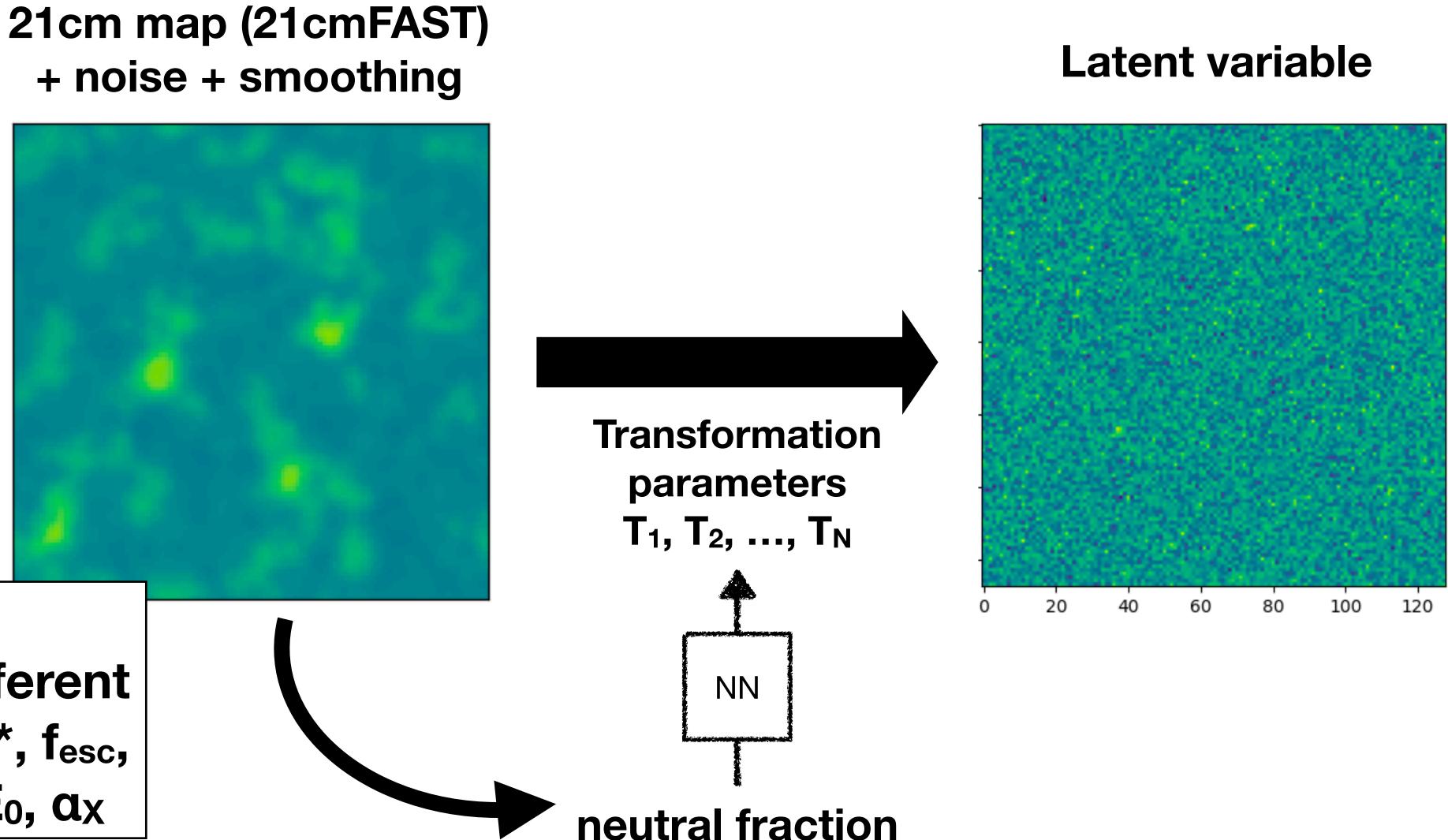
0.3 0.2



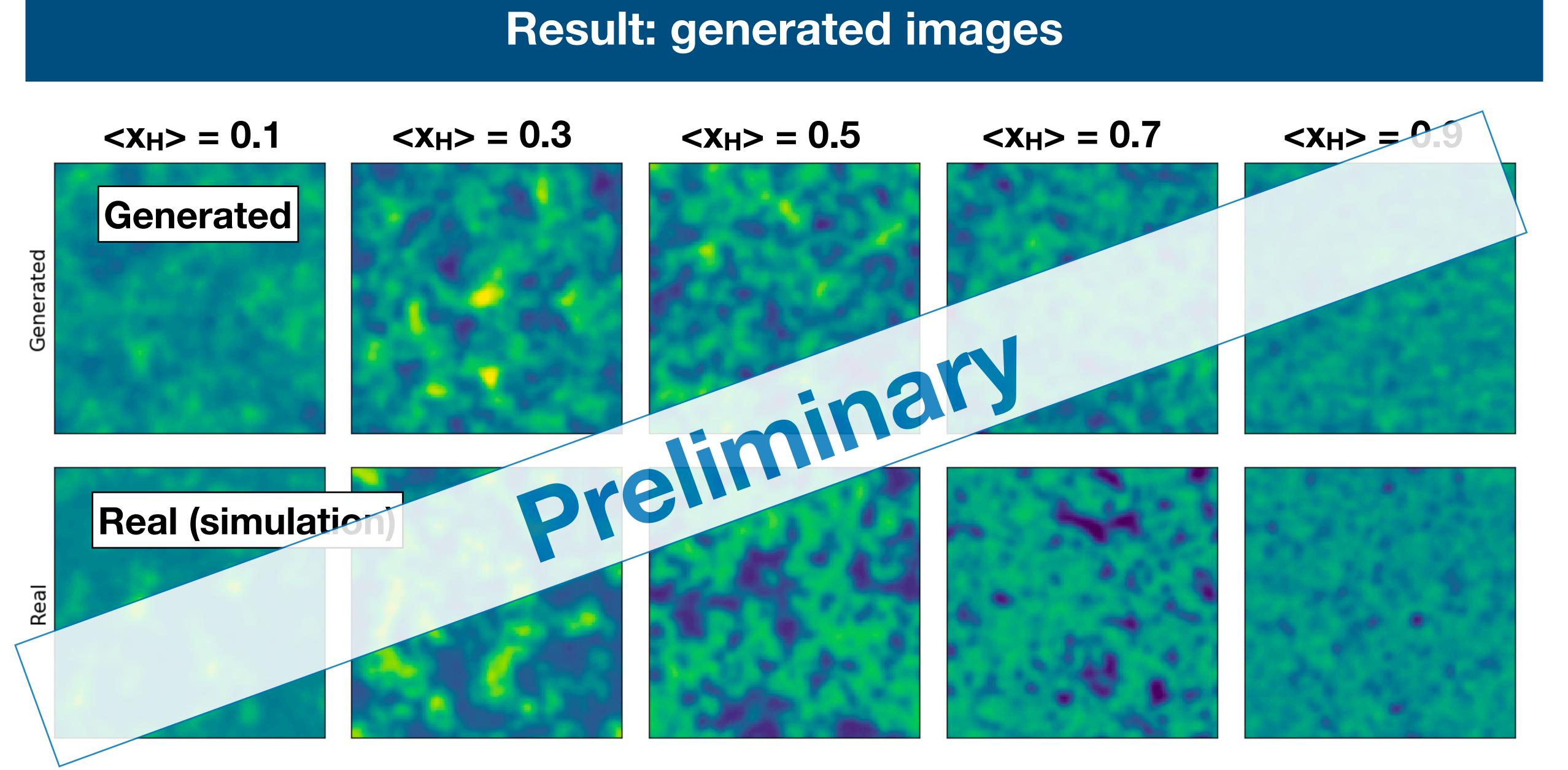
Dai+2022 use Translation and Rotation Equivariant Normalizing Flow (TRENF) See also Hassan et al. (2022) for application of flow-based model to post reionization 21cm maps

Let us use NF for EoR 21cm map!

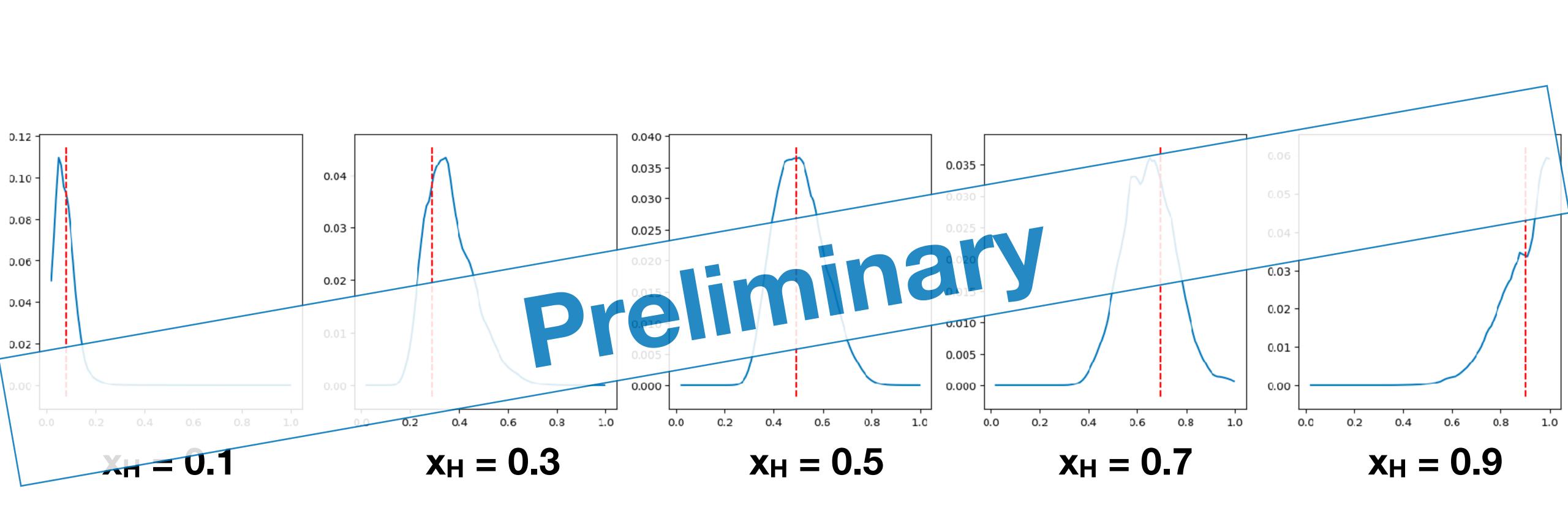
Training data



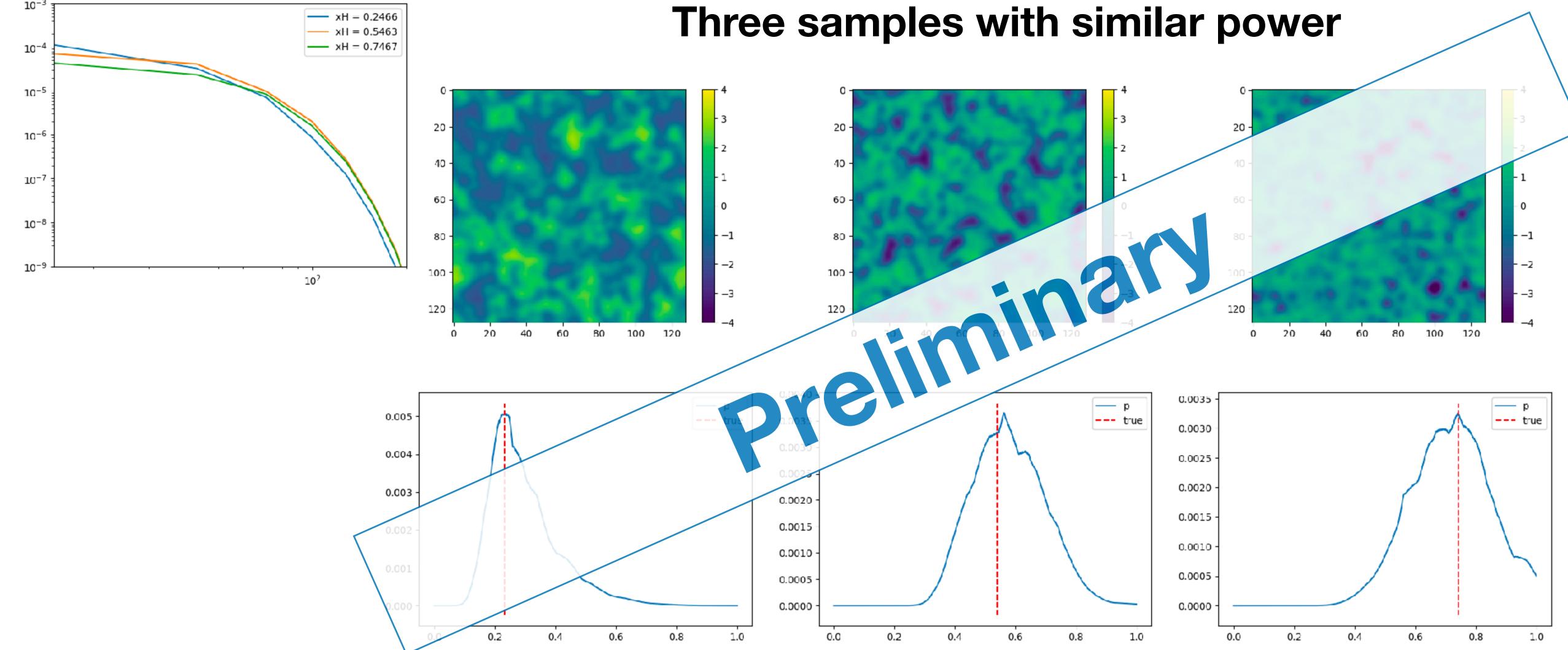
Training data: 21cmFAST with different parameters of f^{*}. α^{*}, f_{esc}, a_{esc} , t*, M_{turn}, L_X, E₀, a_X

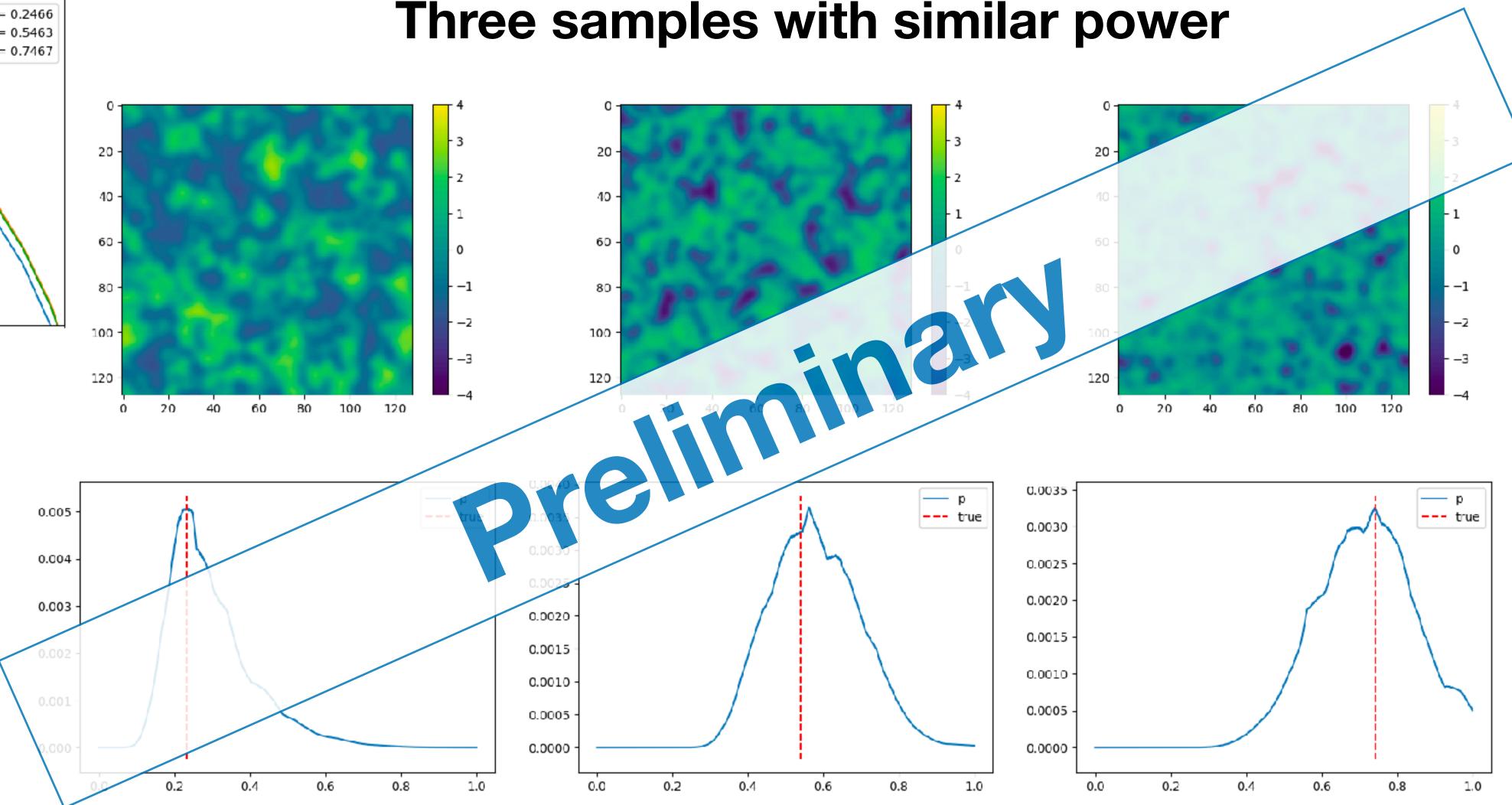


Result: parameter inference



Is it learning something beyond power spectrum?







cGAN

- For line interlopers in non-21cm LIM observations
- It could be useful when studying galaxy LIM × 21cm cross-correlation at the EoR
- Normalizing flow
 - For EoR parameter inference with 21cm maps
 - Compared to the other CNN-based methods, it could be more robust and flexible (need to be checked)
- **General Issues**
 - **Choice of training data (which simulation to use?)**
 - What is pros and cons in using ML?

Summary

