# Towards Pixel-Based Imaging of Transverse Momentum Distributions

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#### Traditional model based approach "Model calibration"

$$f_{1NP}(x, \boldsymbol{b}_{T}^{2}; \zeta, Q_{0}) = \frac{g_{1}(x) e^{-g_{1}(x) \frac{\boldsymbol{b}_{T}^{2}}{4}} + \lambda^{2} g_{2}^{2}(x) \left[1 - g_{2}(x) \frac{\boldsymbol{b}_{T}^{2}}{4}\right] e^{-g_{2}(x) \frac{\boldsymbol{b}_{T}^{2}}{4}} + \lambda_{2}^{2} g_{3}(x) e^{-g_{3}(x) \frac{\boldsymbol{b}_{T}^{2}}{4}}}{g_{1}(x) + \lambda^{2} g_{2}^{2}(x) + \lambda_{2}^{2} g_{3}(x)}$$

$$D_{1NP}(z, \boldsymbol{b}_{T}^{2}; \zeta, Q_{0}) = \frac{g_{4}(z) e^{-g_{4}(z) \frac{\boldsymbol{b}_{T}^{2}}{4z^{2}} + \frac{\lambda_{F}}{z^{2}} g_{5}^{2}(z) \left[1 - g_{5}(z) \frac{\boldsymbol{b}_{T}^{2}}{4z^{2}}\right] e^{-g_{5}(z) \frac{\boldsymbol{b}_{T}^{2}}{4z^{2}}}}{g_{4}(z) + \frac{\lambda_{F}}{z^{2}} g_{5}^{2}(z)}$$

- Injects model biases
- Fitting TMDs are more about calibrating the model
- Uncertainties are a combination between data and TMD model

#### Pixel based approach





- TMDs as D-dimensional "pictures"
- Discretize using a grid
- Fit/tune each pixels of the grid
- Free of parametrization bias
- Well-suited for Neural Networks

#### **Pixelization of TMDs**

- Pixelization of non-perturbative part
- Q<sup>2</sup> dependence dictated by evolution equations

#### **Pixelization of TMDs**

We can calculate the variation of the  $\chi^2$  w.r.t. the variation of each single pixel



- Case study: TMD fitting from SIDIS multiplicities from COMPASS experiment.
- What information can be extracted about PDFs and FFs?
- We will focus on a specific subset of the data.

$$egin{aligned} &rac{d^2 M^h(x,Q^2,z,P_{hT}^2)}{dz dP_{hT}^2} = \left(rac{d^4 \sigma^h}{dx dQ^2 dz dP_{hT}^2}
ight) \Big/ \left(rac{d^2 \sigma^{DIS}}{dx dQ^2}
ight) \ &rac{d\sigma}{dx dy d\psi dz d\phi_h dP_{h\perp}^2} = rac{lpha^2}{xyQ^2}rac{y^2}{2(1-\epsilon)} \left(1+rac{\gamma^2}{2x}
ight) F_{UU,T} \ &= -\epsilon f dh \pi \end{aligned}$$

$$F_{UU}(x,z,q_T) = x \sum_q e_q^2 \int rac{db_T}{2\pi} b_T J_0(b_T q_T) ilde{f}_1(x,b_T) ilde{D}_1(z,b_T)$$

$Q^2$	$> 2.4  GeV^2$
had	$h^+$
z	< 0.6
$p_T$	> 0.2  GeV
$q_T/Q$	< 0.25



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 $\chi^2_{pts} \approx 1$ 



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 $\chi^2_{pts} \approx 1$ 

What information can we extract from this single data point?



$$F_{UU}(x,z,q_T) = x \sum_q e_q^2 \int rac{db_T}{2\pi} b_T J_0(b_T q_T) ilde{f}_1(x,b_T) ilde{D}_1(z,b_T)$$

- We can obtain information about the area of this integral.
- We can extract information about the PDF at this specific x-value and the FF at this specific z-value.

The TMD PDF is not well-constrained at this specific x, and a more robust reconstruction requires additional data points at different pT values.



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By adding more points in pT, we can better constrain the PDF.





# Why do we need multidimensional analysis?

- SIDIS cross sections, multiplicities, and asymmetries involve multiple variables (x, Q<sup>2</sup>, PT, z).
- A one-dimensional analysis might overlook crucial dependencies
- Multi-dimensional analysis allows for more comprehensive understanding of these dependencies.
- It allows us to better constrain TMDs and understand them for a wider range of x, z values, as well as test evolution equations.
- It allows us to better disentangle FFs from PDFs.

## Why do we need multidimensional analysis?

"multi-D" with available statistics

From Bakur's talk



Raphael "Madonna del Prato" (poor resolution)

## Why do we need multidimensional a

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#### 3.5 3.0 $b_T$ 2.0 -1.5 -1.0 0.02 0.04 0.08 0.10 0.12 0.06 0.16 $\overset{x}{\widetilde{D}}(z,b_T)$ - 2.5 - 2.0 $b_T$ -1.5 -1.0- 0.5 0.34 0.48 0.36 0.38 0.44 0.46 0.40 0.42 2

 $\widetilde{f}(x, b_T)$ 

#### Thanks for the attention!