PSD firmware status

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Working on the implementation of missing features, and fixing the problems encountered during the beam tests:

- Implementation of the timing information for the Beta channels pre-triggers, with a resolution of 1.25ns.
 Status: implemented in the current version of the firmware and under testing.
- **Data acquisition problems during the beam tests:**
 - Shift in ADC channels information and trigger map/I2C information.
 Status: should be solved with the current version of the firmware, but we need to test it extensively.
 - □ Majority trigger not working properly (only working as 4over4).
 - Data corruption after 23k events.
 - From GammaMeV beam test at SPS-H8: problems with TTL/I2C acquisitions; many events were missed (note: conflict between majority trigger and TTL/I2C trigger).
 - Implementation of CAEN modules for remote HV control, LED for calibration Status: not implemented yet.

Status: reproduced in the lab; to be solved with the new firmware version.







Timing resolution: implementation



Trigger defining the time window:

- If a majority is created; it is the majority trigger (no matter of what is used in the acquisition). If more than one majority is created, the first majority that is issued counts.
- If there is no majority, it is the TTL or I2C trigger, depending on which one is used in the acquisition.



Timing resolution: implementation



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What to do in the case the majority is not created (e.g. for PSD inefficiency)? What is the delay of the I2C trigger? Is the 40ns sampling window good?



- Pulses and trigger generated with a high-precision pulse generator: Agilent 81160A
- Compare the delay put in the pulse generator and observed at the oscilloscope, with the timing read-out by the FPGA.





Timing resolution: testing





Timing resolution: testing





Jitter with SiPMs

- In a real-file system with SiPMs, the timing will be different for different values of produced photo-electrons.
- Since the trigger is a time-over-threshold of the pre-amplifier, the timing and the jitter will depend on the combination of signal and threshold level. The higher the signals and the lower the threshold, the lower the jitter is.
- Calibration of the system needs to be done very carefully.



Note: this is a SiPM used in FIT, not the SiPM for PSD.



Jitter with SiPMs

HERD Measurements : Laser n-PTR measurements



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- First priority is to solve the problems related to the data acquisition (freezing for the moment the time resolution implementation).
- Implement the missing features (CAEN modules, LED...).