Development of Position Reconstruction in the LUX-ZEPLIN Outer Detector

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LUX-ZEPLIN

- LUX-ZEPLIN (LZ) is the world's most sensitive direct dark matter detection experiment, aiming to discover Weakly Interacting Massive Particles (WIMPs).



Outer Detector Position Reconstruction

- Current OD position reconstruction uses a centre of gravity (CoG) method.
 - Positions are being largely misreconstructed.
- Motivation:
 - Additional quantities for background discrimination.
 - Light collection efficiency mapping.
 - Equivalent energy thresholds.
 - Reduced neutron veto dead-time.



WIMP Mass [GeV/c²]

Figure 1: Combined WS2022 + WS2024 power constrained sensitivity limit (black line) for spin-independent WIMP cross-sections vs WIMP mass. The 1 σ and 2 σ sensitivity bands are shown in green and yellow. [1, 2]

- LZ utilises:

- Dual-phase liquid Xe (LXe) time projection chamber (TPC).
- $\odot\,$ LXe skin veto detector.
- Gd-loaded liquid scintillator (GdLS) outer detector (OD).

Time Projection Chamber

- 7t of liquid xenon (LXe), gas phase with 8mm of gaseous xenon (GXe).
- Primary scintillation (S1) and ionisation e⁻'s produced by interactions with LXe.
- Secondary scintillation (S2) signal from electroluminescence.



A machine learning approach has been investigated, utilising convolutional neural network (CNN) algorithms.

> *Figure 4:* Event positions in XY (left) and RZ (right) from *a,b)* preWS2024 ²²⁸Th calibration data using CoG method, *c,d)* photon bomb simulations using truth positions.

Convolutional Neural Networks

- CNN designed to make predictions of event positions in (R, θ , Z) within the OD scintillator tanks.
- Two channel input.
 - \odot OD PMT pulse areas.
 - \odot OD PMT pulse timings.
- $Timing = Time_{Channel Peak} Time_{5\% Area Fraction}$





Figure 6: Plotted differences between the truth and model predicted



Figure 2: Schematic Diagram of the LZ TPC.

- Particle discrimination S1:log(S2).
- 3D position reconstruction:
 - (X,Y) from S2 hit pattern.
 - Z from drift time.

Outer Detector

- 17t of GdLS across 10 tanks of varying geometry.
- Cylindrical array of 120 PMTs. [3]
- Primary focus:

Figure 5: Schematic diagram of CNN. Channel 1 is the PMT pulse area, channel 2 is the respective PMT pulse timing information.

- Custom loss function:

$$\text{Loss} = \frac{1}{N} \sum_{i=1}^{N} \left(\frac{|\Delta R_i|}{\sigma_R} + \frac{|\Delta \theta_i|}{\sigma_\theta} P_{\theta,i} + \frac{|\Delta Z_i|}{\sigma_Z} \right)$$

$$P_{\theta,i} = \begin{cases} 1 \text{ if } \theta_{pred,i} \in [-\pi, +\pi] \\ \\ \frac{\theta_{pred} - \pi}{\pi} + 1 \text{ if } \theta_{pred,i} \notin [-\pi, +\pi] \end{cases}$$

event positions in **a**) R (blue) and Z (orange), and in **b**) Theta θ (blue). μ is the mean, and σ is the standard deviation describing the position resolution across the LZ outer detector.







- Veto single scatter neutrons with an efficiency of 89±3%.
- Characterise the neutron background.



Figure 3: Fully assembled LUX-ZEPLIN Outer Detector

- N is the number of samples in a batch. ○ $\Delta y_i = y_{true,i} - y_{pred,i}$.
- $\bigcirc P_{\theta,i}$ is the angular penalty.
- $\circ \sigma_x$ is a pre-defined position resolution.
- Obtained an overall OD scintillator tank (R, θ, Ζ) position resolution of (8.35 cm, 0.16 rad, 12.89cm)

Future Work

- Expand training data provided to the CNN.
 Flat OD gamma simulations.
 - Calibration data.
- Add a fourth output, (R, θ, Z) → (R, θ, Z, E).
 Energy dependent component loss denominators.

Figure 8: Fraction of events at their truth position which differ from their corresponding model predicted position by greater than 20cm or 90 degrees (π /2 rad) in **a**) RZ space and in **b**) θ Z space. These indicate regions of poor model predictions within the OD.

References

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