

X-ray methods for cultural heritage applications

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Developments of advanced X-ray methods for the non-invasive investigation of tangible cultural heritage

- MA-XRF /uXRF (mobile)

- MA-XRPD (mobile)

- Confocal XRF (mobile)

- TXRF/GIXRF (mobile)

- XANES/EXAFS (lab.)
- PIXE (lab.)
- PAA (lab.)

E-RIHS: European Research Infrastructure on Heritage Science



Access to advanced portable equipment and related competences, for in-situ non-destructive measurements on artworks.



MA-XRF developments at XRAYLab in Catania



NO real time technology step by step scanning 1 -SDD detector



Real time technology & imaging continuous scanning at 100mm/s 2 -SDD detectors with TLIST



Real time technology & imgaing Rotational continuous scanning 2-SDD detectors with TLIST



2021

Real time technology and imaging continuous scanning at 150 mm/s
6-SDD detectors with fast-mapping

Spectrometric head



6 SDDs (VIAMP layout):

- 50mm² collimated to 40mm² for a total active area of 240mm²
- **125 eV @ Mn-K**α energy resolution
- 90-45deg measurement geometry

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X-Hodoscope detector composed of 6-SDDs

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Spectrometric head

Advantages:

- maximizing the measured vs.
 input count rate while minimizing
 the dead time with respect to a
 single detector setup under a
 beam intensity (about) x6 higher;
- increasing sensitivity and LoD;
- **controlling** surface topology of samples

6 SDDs hodoscope







The 3D detector array allows us to increase the throughput of the fluorescence radiation ensuring enough statistics for pixel XRF spectra at short dwell-time

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Sensitivity and LoD

The 6 SDD hodoscope allows a steep improvement of the overall sensitivity



Figure of merit of the upgraded system in comparison with a typical single-detector set-up available in a synchrotron facility (Karydas, et al. Journal of Synchrotron Radiation 25.1 (2018): 189-203)

By using MicromatterTM reference single metal evaporation (50μ g/cm²) (live time 300 sec at 50kV and 600μ A)

Possibility analyze one single detector per time and to correct the elemental distribution images for the surface topology of the art object





Mechatronics



The new scanner in use for the MOLAB (a) Peggy Guggenheim Museum in Venice for a painting by Mondrian Scanning area: 120×90×20cm³

- MCA, fast-mapping and TLIST acquisition capabilities
- Max. scanning speed 150mm/sec (e.g., 5ms dwell-time for 1mm pixel size)
- Laser sensor for **dynamic correction** of the focus distance
- Vertical/Horizontal configuration

The new scanner in horizontal configuration in use @ the Biblioteca Nazionale in Naples for Herculaneum papyri



Mechatronics



The new scanner in use for the MOLAB (a) Peggy Guggenheim Museum in Venice for a painting by Mondrian

The Control Processing Unit (CPU) is developed in a multi-node design and programmed in a real-time environment



- All measurement parameters are entered and monitored by the users through an interactive dashboard
- XRF pixel spectra are fitted in real-time by using a fast-fitting (Pymca) or AI/ML models.
 Deconvoluted elemental distribution maps are available on the fly.

New dashboard for analysis (Real-time/Off-line): use of classical fast-fitting (PyMCA) or Artificial Intelligence



Advantages of the new MA-XRF system

The 6 SDD hodoscope allows a steep improvement of the overall sensitivity



Have been detected for the first time in situ even very small traces of metallic elements in degraded and brittle materials, such as the carbonized Herculaneum papyri!

PHerc. 1420, cornice 2 Scanning step 250um Dwell time 10ms





calcium distribution Papyrus structure and conservation state

Additionally, metals (Fe, Zn, Cu, etc.) are heterogeneously distributed on the surface

MA-XRF mapping : benefit of high resolution



Vergine by Raffaello (1500-01, 51 x 41 cm²) at the Museo di Capodimonte in Napoli

lateral resolution 50 µm

MA-XRF mapping : benefit in the creative process

Ritratto del cardinale by Raffaello at the Museo di Capodimonte in Napoli

Scanning Step: 500 µm - Dwell time per pixel: 10ms

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Scannin Dwell tir Pb

Pb

High resolution 1D/3D confocal XRF



EXPERIMENTAL SET-UP

E, keV

Focus size *, µm

Intensity gain**

- Mo/Rh anode X-ray source (30W) focused by micro-lens (7 μ m @ Rh-K)
- SDD1 for micro-XRF (FWHM 130eV @5.9keV)
- SDD2 + micro-lens (10μm @ Rh-K) for confocal XRF
- DXP operated in TLIST/Mapping for continuous scanning

6336

- Long range microscope (optical resolution 2.2 μ m)
- XYZ travel range system (50x50x20 cm³)

3276

X-ray source

PARAMETERS OF FOCUS

E, keV	3-5	5-7.5	7.5-10	10-15	15-20	20-25	25-30
Focus size *, μm	13	13	13	11	8	7	7
Intensity gain**	3677	6416	9693	7223	4667	1303	219

Detector

PARAMETERS OF FOCUS 3-5 5-7.5 7.5-10 10-15 15-20 18 19 17 14 11

7102

5257

2835

20 - 25

10

1130

25-30

10

135

1D CXRF on carbonized Herculaneum papyri

Ca map from MA-XRF shows structure and conservation state after the mechanical unrolling



Ca-Kα fluorescence signal along the stratigraphy for the identification of overlaid/underlaid layers



3D CXRF for evidencing delamination process in paint layers

High resolution 3D confocal XRF

- **Source** 50kV & 600μA
- Scanning step XY: 50µm
- Scanning step Z: 3μm
- Dwell-time per pixel: 500ms
- Scanning area: 5mmx5mmx200µm
- GPU Rendering of 3 models (cubic)





Fe map (XY view)

Fe scaled on Z (Z scaling applied for evidencing intra layer structure)

Mobile MA-XRPD for specific analysis of polycrystalline

materials



- * X-ray Source: Cu-anode | Ni filter
- **X-ray Optic:** mini-lens 186μm | 109mrad div.
- Collimation: rectangular slit 0.6x10mm²
- XRD detector: 1280 Si-strip, 50μmx8mm, hybrid photon-counting
- XRF detector: SDD (not visible in the schematic),
 50mm² active-area
 - Laser sensor distance: correct sample-source distance dynamically during scanning to have same focus for all pixels





FWHM (20) 0.2-0.25deg

Instrumental set-up



Scanning parameters (typical):

- Step mode
- 1mm pixel-size
 - 3s dwell-time
 - Angular range: 28deg 2 θ

During scanning painting is in a fixed position. The XRD/XRF measurement-head is moved in front to cover the area under investigation

Scanning capabilities: XYZ linear motorized, with travel range of $50x50x20 \text{ cm}^3$, $\pm 50 \text{ cm}$ mechanical adjustment on the vertical axis is possible facilitating the alignment on painting of large dimensions

CPU: Real-time programmed. It controls mechatronics, detectors and laser; it provides a TTL gate to synchronize XRD and XRF acquisition in the same spot; it acquire XRD patterns and XRF spectra

MA-XRF/MA-XRD on paintings









Area: 16cmx15cm Step size : 1mm Time/step : 3sec Total n. pixel: 24k Time: 20h

MA-XRF defines the phases to be included in the model





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Thanks!





