

STATUS OF RECONSTRUCTION CODE

G. Dho

GENERAL STATUS

- The reconstruction code is technically working, but has some issues and needs development for the future requirements

- LATEST BRANCH

- WHAT TO TACKLE NOW

- WHAT TO TACKLE THEN

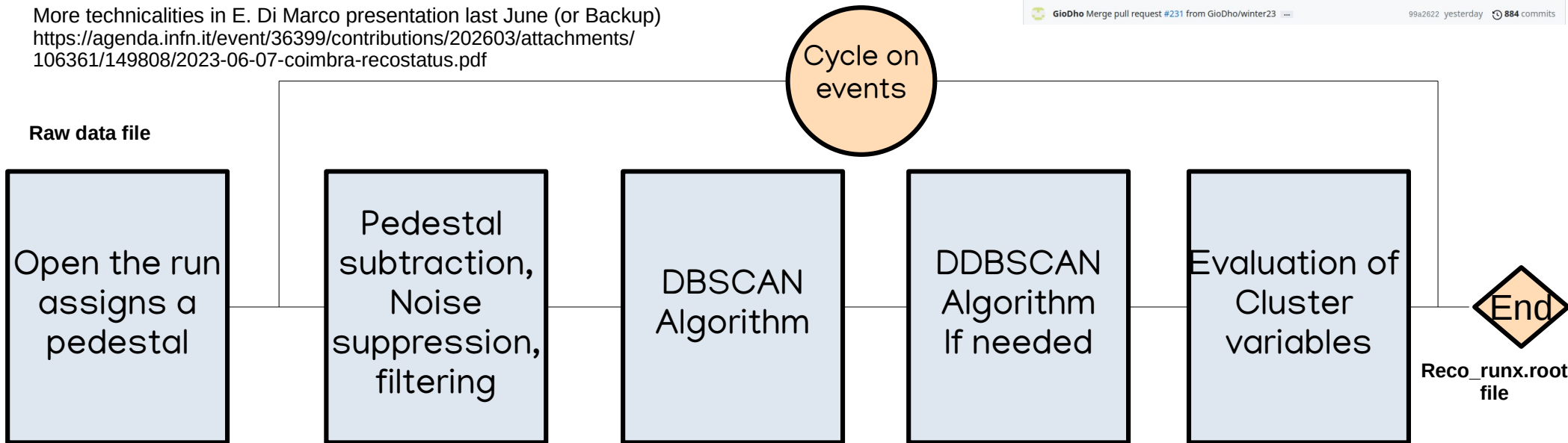
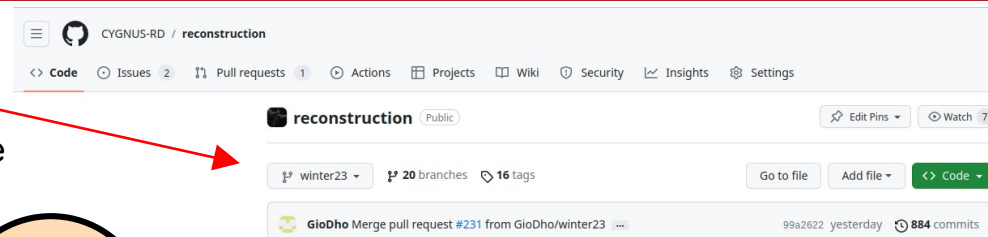
- WHAT TO TACKLE IN THE FUTURE



LATEST BRANCH

- The current more updated branch is **Winter23**.
- Some small new updates, but main structure is the same

More technicalities in E. Di Marco presentation last June (or Backup)
<https://agenda.infn.it/event/36399/contributions/202603/attachments/106361/149808/2023-06-07-coimbra-recostatus.pdf>



- The **goal** is to provide a single reconstruction code for all groups (MC, autoreco, analysis of LIME, MANGO etc... and PMT)

LATEST BRANCH NEW CHANGES

- There have been some updates in the last month:
 - Now the code correctly runs on ROOT and midas data files (no h5 format yet)

LATEST BRANCH NEW CHANGES

- There have been some updates in the last month:
 - Now the code correctly runs on ROOT and midas data files (no h5 format yet)
 - Environmental variables included (also not crashing for the “Renga-bugged” runs)

LATEST BRANCH NEW CHANGES

- There have been some updates in the last month:
 - Now the code correctly runs on ROOT and midas data files (no h5 format yet)
 - Environmental variables included (also not crashing for the “Renga-bugged” runs)
 - Git hash saving corrected for future runs

LATEST BRANCH NEW CHANGES

- There have been some updates in the last month:
 - Now the code correctly runs on ROOT and midas data files (no h5 format yet)
 - Environmental variables included (also not crashing for the “Renga-bugged” runs)
 - Git hash saving corrected for future runs
 - Pedestal and run search updated working both with .csv file from sql database and manual txt file with range for those who do not have a sql database (MC, MANGO)

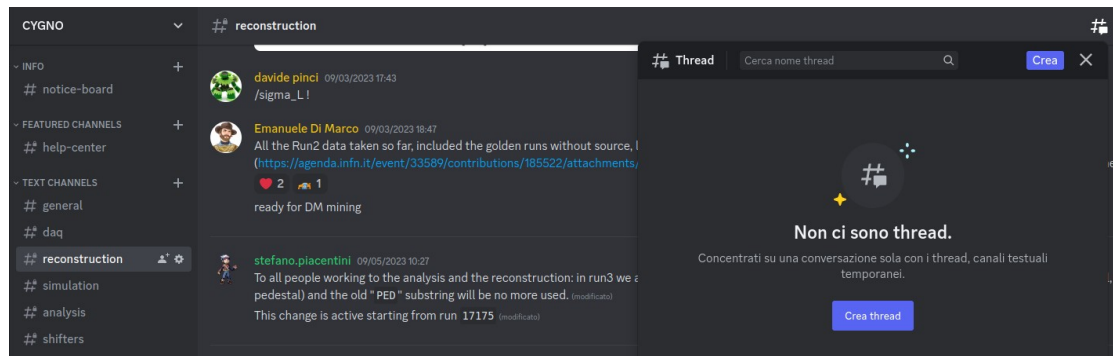
LATEST BRANCH NEW CHANGES

- There have been some updates in the last month:
 - Now the code correctly runs on ROOT and midas data files (no h5 format yet)
 - Environmental variables included (also not crashing for the “Renga-bugged” runs)
 - Git hash saving corrected for future runs
 - Pedestal and run search updated working both with .csv file from sql database and manual txt file with range for those who do not have a sql database (MC, MANGO)
 - Speeding the debug mode for midas files (3 min → 30 s per image (if event<50))
- This means: minimal stability is available for all users (I know PMT people, I am soon working for you too), so **stop manually changing the code** for yourself in an untraceable way → we will lose track and have 100 versions.

DISCORD BUG REPORT

- But what if the code does not run or I find a bug?

Contact experts in the
reconstruction channel on
Discord



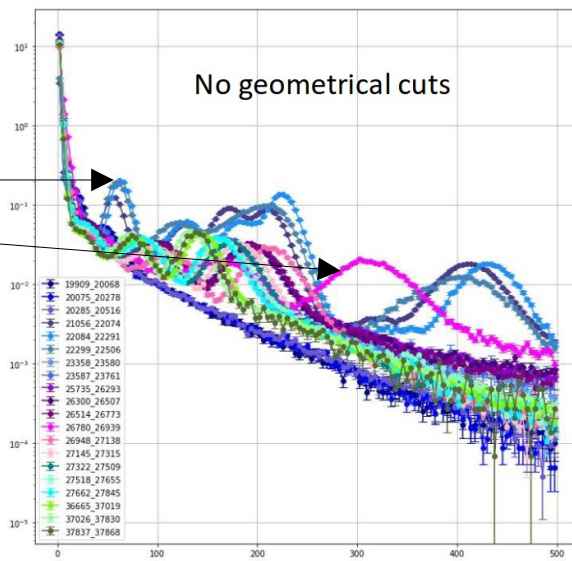
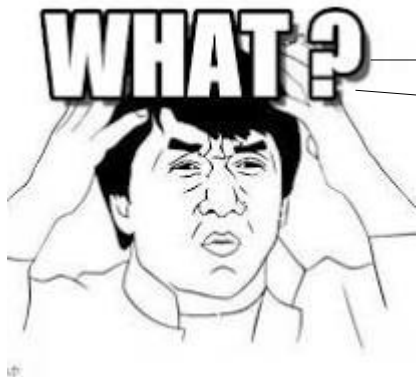
Discord threads on bug reports can be opened so that the bug can be fixed as soon as one finds it

- But what if a new development or piece of code wants to be added to main repository?
 - 1) Fetch your fork, check for compatibility with latest version and open a PR
 - 2) A check on the code will be performed
 - 3) Some plots and tests on test runs will be required

Let's minimize errors

WHAT TO TACKLE NOW

- The main first order problem is to provide reliable data for LIME analysis and MC comparison



From Di Giambattista's simulation presentation

- A detailed history of the reconstruction parameters and conditions should be assessed

Might be impossible due to lack of some information

We plan to rerun on all Run3 a new more stable version of the code

WHAT TO TACKLE NOW II

- Since we want to rerun on all data, we need a stable version which needs to have:

Saving of parameters

Somewhat userfriendly
and hardly hackable

Correction of rotation

In the end, we are a
directional detector, we
need to know the
orientation of the detector

Decision on sensor border

What to do with the
camera noisy parts

WHAT TO TACKLE NOW II

- Since we want to rerun on all data, we need a stable version which needs to have:

Saving of parameters

Somewhat userfriendly
and hardly hackable

Correction of rotation

In the end, we are a
directional detector, we
need to know the
orientation of the detector

Decision on sensor border

What to do with the
camera noisy parts

Inclusion of PMT variables

Do not forget about PMT



WHAT TO TACKLE NOW IIb

- Decision on borders:

I would add a flag on config file
to remove them or keep them

```
47  
48 'scfullinfo'           : True,  
49 'save_MC_data'         : False,  
50  
51 'tip'                   : '3D',  
52 'saturation_corr'       : False,  
53  
54 # Superclusters parameters are hardcoded  
55 'calibrate_clusters'    : False,  
56  
  'Remove_border'        : True,
```

WHAT TO TACKLE NOW IIB

- Decision on borders:

I would add a flag on config file to remove them or keep them

```
47
48 'scfullinfo'           : True,
49 'save_MC_data'         : False,
50
51 'tip'                   : '3D',
52 'saturation_corr'       : False,
53
54 # Superclusters parameters are hardcoded
55 'calibrate_clusters'    : False,
56
    'Remove_border'       : True,
```

- Save the parameters.. Still open question

Just githash:

- Ok for the version of the code,
- But
- it would require to make new commits for every change of parameters
 - No guarantees parameters will not be chaged

Save param inside recofile:

- Does not hurt. Hard to hack
- The self reco made by Giovanni could store them in Grafana
- But
- Something could be harder to save (vignetting map)

At runtime create a file with all save in s3 and store link in sql table:

- Almost no possibility to hack it
- But
- Still to be determined how this file can be saved

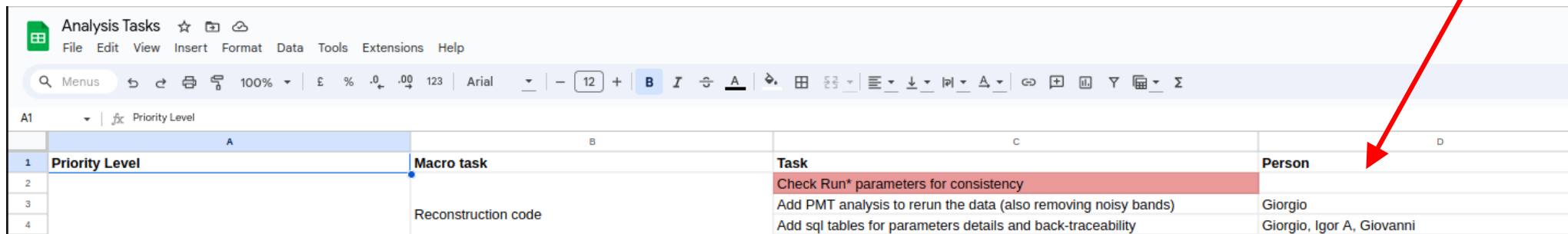
WHAT TO TACKLE NOW III

- When it is time to rerun everything with all these features, it is important to check randomly runs along Run3 to check that the same parameters work for all sets

↓
If not they need to be changed
to correctly reconstruct (i.e. Ba,
Eu)

→ Check for sc_integral
consistency

- This is an important task



	A	B	C	D
1	Priority Level	Macro task	Task	Person
2			Check Run* parameters for consistency	
3			Add PMT analysis to rerun the data (also removing noisy bands)	Giorgio
4		Reconstruction code	Add sql tables for parameters details and back-traceability	Giorgio, Igor A, Giovanni

- Only then reconstruct all data (PMT will be included)

WHAT TO TACKLE THEN

- For the near future some updates are planned to improve the code and to move towards CYGNO-04:

Pedestal Reconstruction

Automatic reconstruction of pedestal runs with itself (evaluate fake clusters) and with previous pedestal, to monitor the sensor evolution

Noise filtering techniques:

Already discussed in E. Di Marco presentation in June:

Convolutional method by I. Pains,

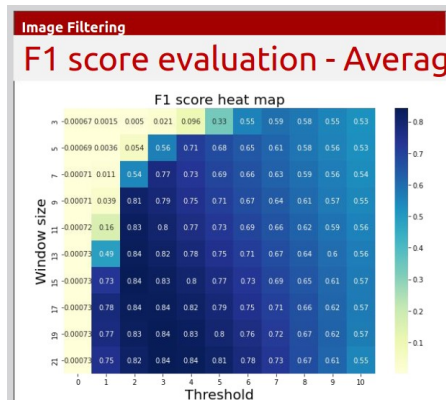
U-Net, optimised median filter

(<https://agenda.infn.it/event/32788/contributions/181084/attachments/97228/134158/Filtering%20CYGNO.pdf>)

Adapt for QUEST:

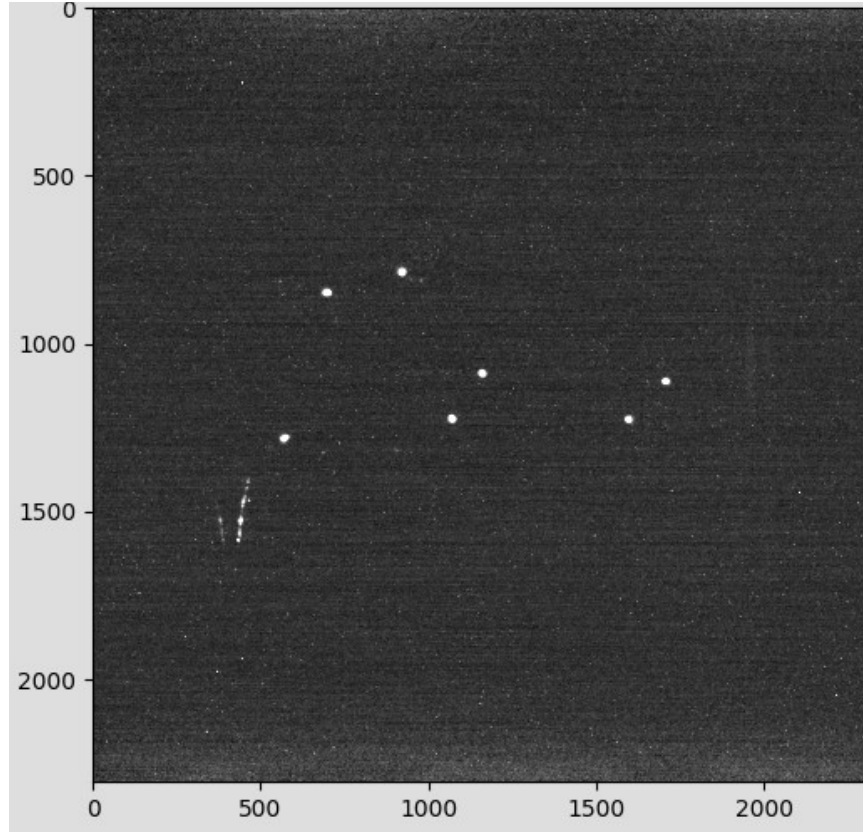
Not only a matter of different counting and pixel number

But can we improve the noise treatment?



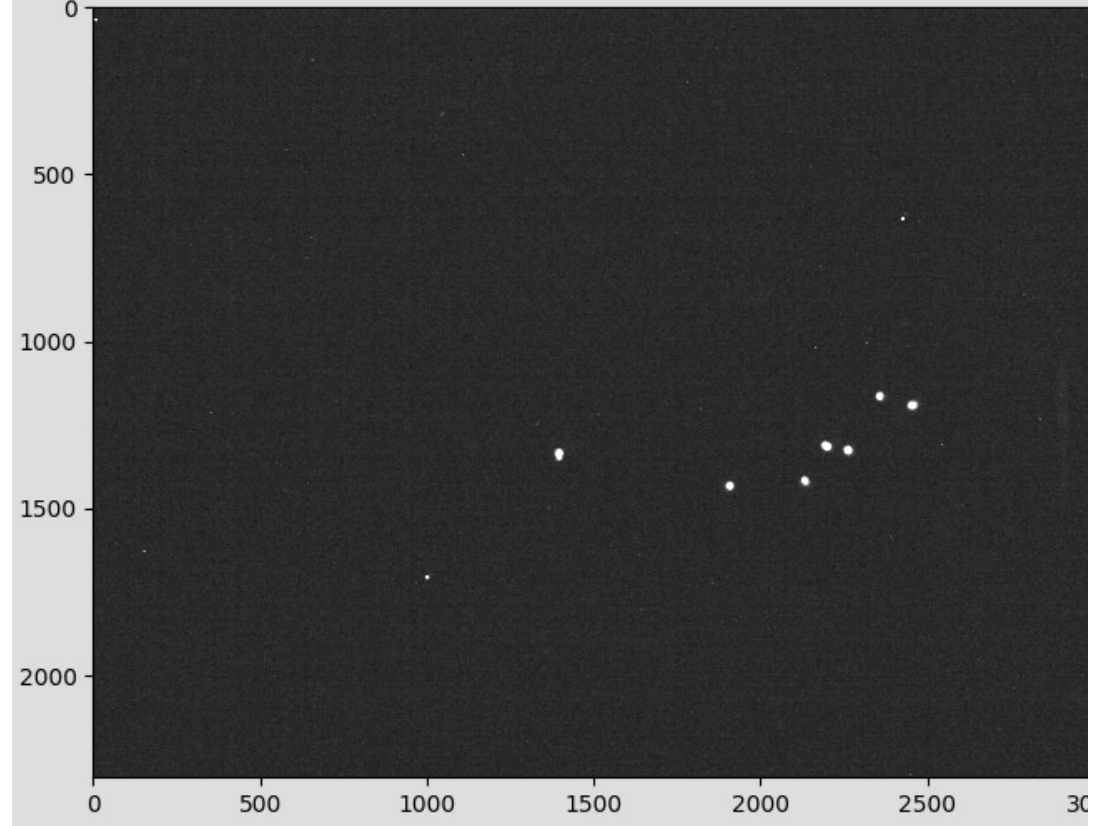
(FUSION VS QUEST)

Fusion



G. Dho

Quest



9

05/12/2022

WHAT TO TACKLE THEN II

- Also for analysed data users, the idea is to provide tools to simplify life:

Provide opening data scripts

C++ and python scripts with all necessary tools and libraries to access all info contained in recoed files

middleware / conf / analyzer / dev / reco-analyzer.py

```
gmazzitelli reco example

Code Blame Executable File · 95 lines (85 loc) · 3.52 KB

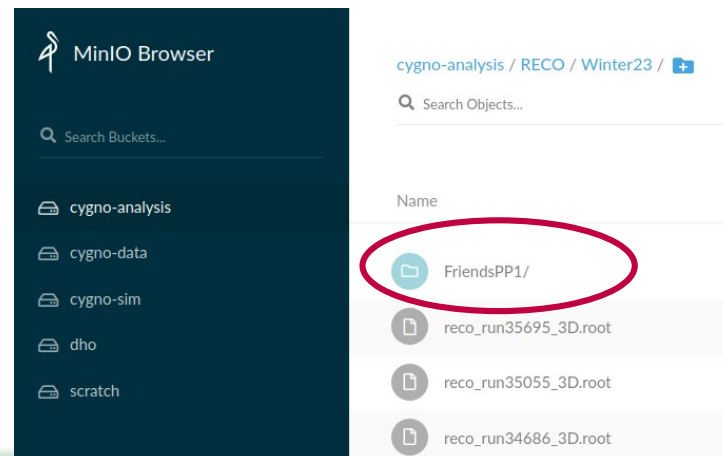
1 #!/usr/bin/env python3
2 #
3 # G. Mazzitelli 2022
4 # versione DAQ LINGS/LNF per midas reco-analyzer
5 #
6 import numpy as np
7 import uproot
8 import pandas as pd
9 import os
10
11 def GetLY(tf, verbose):
12     df_A = tf['Events'].arrays(['sc_rms', 'sc_tgaussigma', 'sc_width', 'sc_length', 'sc_xmean',
13                               'sc_ymean', 'sc_integral'], library = 'pd')
14
15     if verbose: print(df_A)
16     sel = df_A[
17         (df_A['sc_rms'] > 6) & (0.152 * df_A['sc_tgaussigma'] > 0.5) &
18         (np.sqrt((df_A['sc_xmean'] - 2364/2)**2 + (df_A['sc_ymean'] - 2364/2)**2) < 800) &
19         (df_A['sc_integral'] > 30000) & (df_A['sc_integral'] < 300000)
20     ].copy()
21
22     p = np.array([7.5126685e-02, -1.3249211e+03])
23
24     return p[0]*np.mean(sel['sc_integral'])+p[1], p[0]*np.std(sel['sc_integral']) / np.sqrt(len(sel))
25
26
27 def get_epoch(file_url):
28     import requests
29     from datetime import datetime
30     r = requests.get(file_url)
31     utc_time = datetime.strptime(r.headers['last-modified'], "%a, %d %b %Y %H:%M:%S %Z")
32     epoch_time = (utc_time - datetime(1970, 1, 1)).total_seconds()
33     return epoch_time
34
```

Automatise post-reco routines

Important analyses which cannot be performed on run by run basis

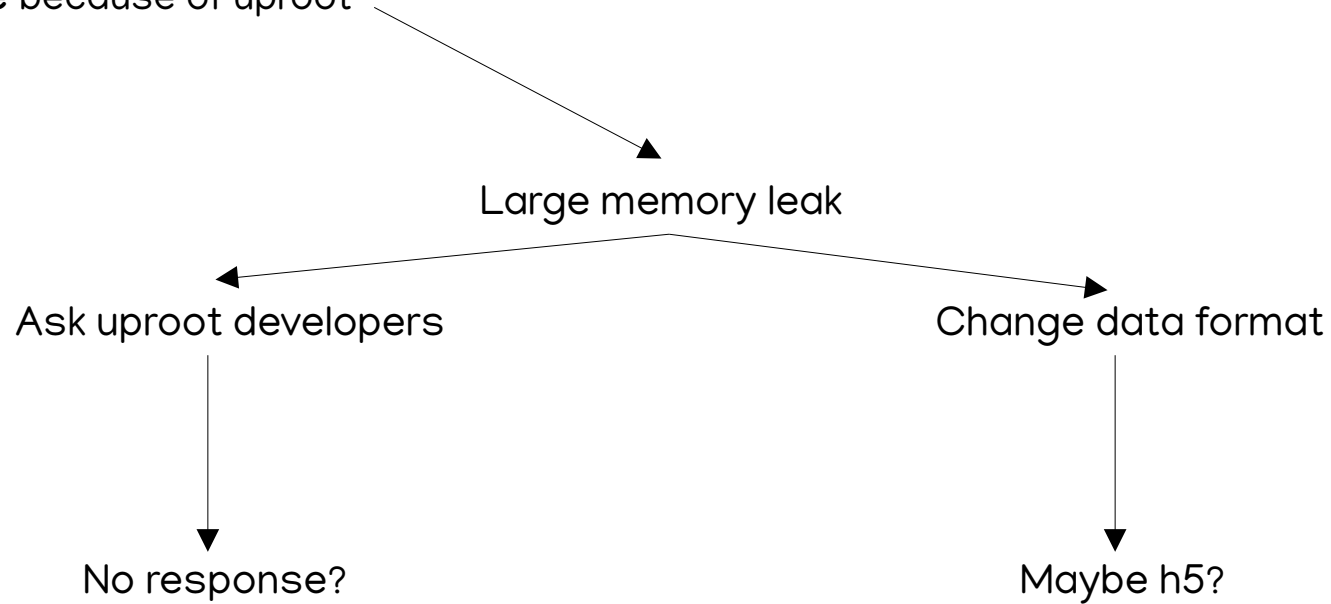
– ^{55}Fe and Rita factor data correction

– Emanuele's Regression analysis
And root friend files



WHAT TO TACKLE THEN III

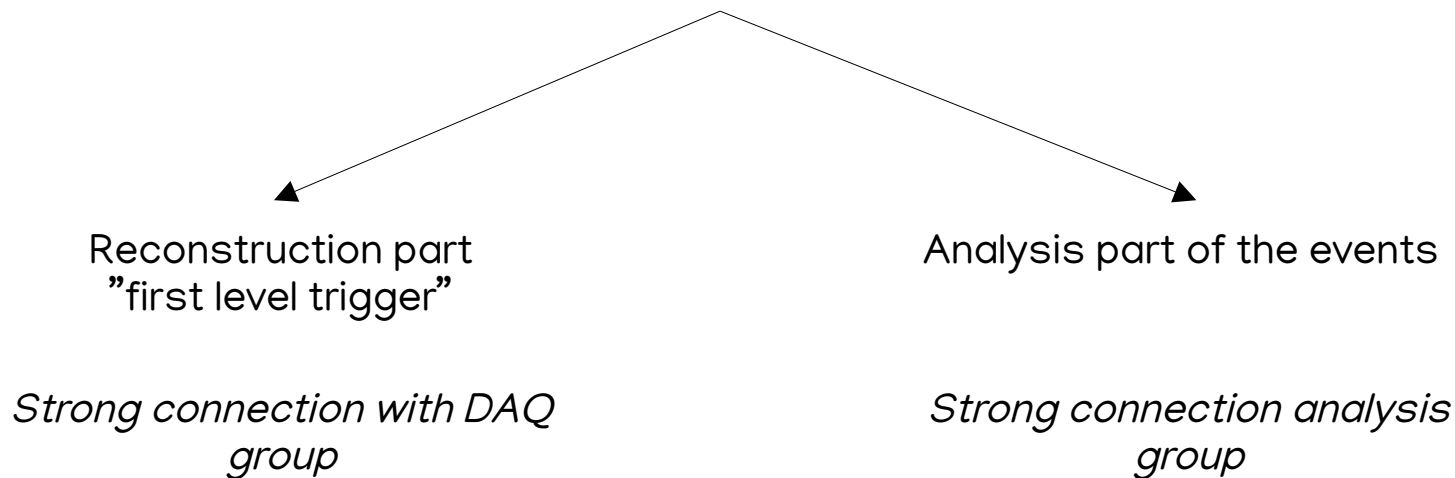
- For MC big issue because of uproot



PLEASE LET'S WORK
TOGETHER

WHAT TO TACKLE IN THE FUTURE

- For CYGNO-04 the reconstruction structure needs some rework
- The data output of 4 QUEST cameras prevents from saving full resolution images
- The reconstruction code should be made modular



WHAT TO TACKLE IN THE FUTURE II

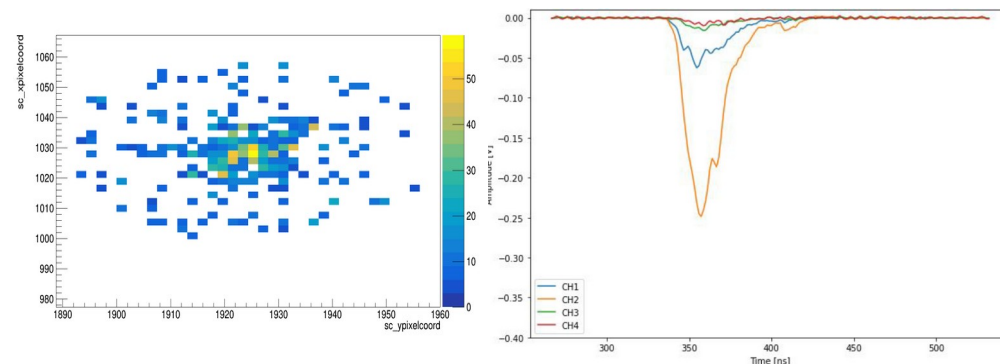
Reconstruction part

- 1) Images from cameras and waveforms from PMT continuously taken.
- 2) Live coarse selection of only interesting pixels (exploit the work on GPU and trigger algorithms developed by Brazilian group)
- 3) Clustering algorithm applied to the selected pixels
- 4) Bayesian fit (or something else) of PMT waveforms used to match PMT event with clusters
- 5) Output file contains **Event = track + corresponding waveforms**

No interaction needed by the analysis user who is no more involved in the track recognition part

<https://agenda.infn.it/event/38032/contributions/213585/attachments/111926/159830/Trigger%20Proposal%20Status.pdf>

May be written in CUDA and or C++



WHAT TO TACKLE IN THE FUTURE III

Analysis part

- The output of the reco part is accessible to everyone to perform any type of analysis desired
- Almost no analysis is performed in the first part (just integral, position and time of the cluster)
- An automatic analysis will be performed similar to the one made now
- More complex analyses (directionality) can start from the event generated by the reco without the need to reconstruct the raw original data (faster also for the analysis guy)

CONCLUSIONS

- Reconstruction code along with reconstruction flow is working fine
- Clearly there are issues as anyone could expect
- New version of the code is out which should be stable for all users
- Rereconstruction of Run3 is foreseen
- More control will be put in new developments and Discord bug report threads is instantiated
- The development for CYGNO-04 future data output requires strict work with DAQ personnel
 - Modular structure
 - First part: pure reconstruction exploiting Brazilian group software trigger
 - Second part of pure analysis on reduced data

BACKUP

RECO-CODE FLOW

