## EHT imaging of the shadows of supermassive black holes. III. VLBI with mm telescopes, calibration!

### Today



#### • Overall Objective

•Introduce the practices of our trade: what it takes to measure the shadow of supermassive black holes

### • Understanding your telescope

- Locations
- Dishes
- Receivers
- Digitisation
- Transport
- Correlation
- Data products
- Instrument calibration
- •On sky calibrators
- Self calibration
- Closure properties
- Polarisation
- Last lecture:
  - Interpretation, calibrating gravity





### Event Horizon Telescope

- 8 telescopes at best sites
  - working together
  - •Not positioned for this purpose
- Recording high bandwidth
  - •32 Giga bit per sec
  - •64 Gbps later
- Good weather • around the world





### EHT members at telescopes

















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### High sites, small dishes

#### · Atmosphere blocks millimeter waves

- $\cdot$  Mostly pressure broadened water and ozone lines
- $\cdot$  Observing conditions characterised by water vapour column
  - $\cdot$  halfway space...

#### · Other requirements:

- $\cdot$  Dishes need to be very precise
- $\cdot \operatorname{Receivers}$  very small and delicate

#### $\cdot$ In addition for EHT

- $\cdot$  Accurate (and expensive) maser clocks
- $\cdot$  We must observe close to horizon very regularly
- $\cdot \operatorname{Requires}$  good weather
  - $\cdot\, across$  the globe
- $\cdot$  Some of our telescopes are interferometers





## More telescopes

- GLT added to 2018 campaign
  - NOEMA, Kitt Peak in 2021, 2022
  - 2025+ possibly more observatories:
    - Owens Valley, Haystack, South-Korea, Africa Millimeter Telescope (Dutch project!), Llama (Argentina)
  - ngEHT project to build dedicated telescopes
- Option to use higher frequency in 2024
  - 345 GHz: 1.5x better resolution
  - Time sampled images
- To space for more targets and photon rings







African Millimeter Telescope projected on Gamsberg, Namibia

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### Lucky in 2017

- Observe strategy
  - •Central go/no-go decisions based on local weather

#### • Interleave BH target with other source

• For calibration purposes (and science)

### Good weather

- •Still results in 10s coherence times
- Every 10s the phases fluctuate to destroy signal





Table 1				
Median Zenith Sky Opacities (1.3 mm) at EHT Sites during the 2017 April Observations	_			
Median Zenith $\tau_{1.3 \text{ mm}}$				

Station	Median Zenith $\tau_{1.3 \text{ mm}}$				
	Apr 5	Apr 6	Apr 7	Apr 10	Apr 11
ALMA/APEX	0.06	0.04	0.05	0.03	0.06
SMA/JCMT	0.10	0.07	0.09	0.05	0.08
PV	0.18	0.13	0.14	0.10	0.15
LMT	0.13	0.16	0.21	0.26	0.24
SMT	0.21	0.28	0.23	0.19	0.16
SPT	0.04	0.05	0.07	0.08	0.07

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### All telescopes require same receiver bands

#### · Millimeter bands require mixing before amplification

- $\cdot\,\text{Receivers}$  and LO generation very delicate
- $\cdot \operatorname{Mixes}$  down to frequency for digitiser
- $\cdot$  4 x 4GHz output for each receiver



- $\cdot\,$  Often double for 2 circulair polarisations
- $\cdot$  but linear at ALMA...



Figure 2.15: Block diagram of Band 9 cartridge (left) and a schematic image (right). Note that there are only two IF outputs, one from each polarization in this DSB receiver. The Band 9 receiver was built at SRON in the Netherlands.

### Then digitise...

#### • Must capture large BW for sensitivity • But only useful when same bandwidth at all telescopes • Digitise before transport • Example: • 4GHz (at IF band) • Requires 8 GHz sampling (Nyquist) • Requires 16 Gbps (2 bit sampling!) • In 8hr: 52TB receiver maser & 10 MHz L.C distribution (1 LCP, 1 RCP) (1 LCP, 1 RCP) LSB USB BDC BDC GPS receiver synthesizer low Rx LSB high low Rx USB high & distribution (2.048 GHz) ×2 (1 LCP, 1 RCP) (1 LCP, 1 RCP) 2 GHz each (1 LCP, 1 RCP) (1 LCP, 1 RCP) 2 GHz each 2 GHz each GHz each R2DBE R2DBE R2DBE R2DBE Rx LSB, BDC high Rx USB, BDC low Rx USB, BDC high Rx LSB, BDC low ×2 8 Gbps each ×2 8 Gbps each ×2 8 Gbps each 8 Gbps each Mark 6 Mark 6 Mark 6 Mark 6 Rx USB, BDC low Rx USB, BDC high Rx LSB, BDC low Rx LSB, BDC high BDCs, R2DBEs, ----- analog control 1 GbE Mark-6s timing computer switch communication - data





Figure 8. EHT digital VLBI backend as installed at the Institut de Radioastronomie Millimétrique (IRAM) PV 30 m telescope in Spain. The



### Correlator

- Correlators must deal with data from telescopes
  - $\cdot$  Must keep up with data rate
- $\cdot$  Deliver user product
  - $\cdot\,\text{May}$  determine sensitivity of interferometer
  - $\cdot$  Spectral resolution
  - $\cdot$  Time resolution
  - $\cdot\,\text{And}$  resulting Field of view



live

OINT INSTITUTE FOR VLBI IN EUROP

### **Correlator principle**

Ce Lag domain Strong 1 EPO41B Strong 1 Strong 1

#### Frequency



## • Put in range of 'test' delays, correlate, accumulate

 $\cdot \operatorname{Results}$  in delay spectrum, or FT to frequency



Continuum source

### Stringent constrains on geometry

- $\cdot$  Same errors affect phase rate and delay
  - $\cdot$  1° of phase over 16 MHz = 173ps (ps = 10<sup>-12</sup>s)
  - · To keep both clocks stable over 10min and 500 MHz  $\approx$  1:1015
    - $\cdot$  Expensive maser clocks to make atmosphere limiting factor
  - ·And 16ps  $\approx$  5mm required accuracy over 1000km
- The natural fringe rate is high for long baselines

$$\phi_{LO} = \omega_{LO} \hat{\tau_g} = \omega_{LO} \frac{d\tau_g}{dt} t = \omega_{LO} \frac{d\vec{B} \cdot \vec{s} / c}{dt} t$$

- $\cdot$  This comes out at 100 kHz for VLBI
- $\cdot Small \ errors \ in \ model \ leave \ mHz \ fringe \ rate$ 
  - $\cdot$  And more at high frequency
  - $\cdot$  Example small few mas position error

Adapted from Sovers, Fanselow, and Jacobs Reviews of Modern Physics, Oct 1998

Item	Approx Max.	Time scale
Zero order geometry.	6000 km	1 day
Nutation	$\sim 20$ "	< 18.6 yr
Precession	$\sim 0.5 \operatorname{arcmin/yr}$	years
Annual aberration.	20"	1 year
Retarded baseline.	20 m	1 day
Gravitational delay.	$4 \text{ mas} @ 90^{\circ} \text{ from sun}$	1 year
Tectonic motion.	10 cm/yr	years
Solid Earth Tide	50 cm	12 hr
Pole Tide	2 cm	$\sim 1 \text{ yr}$
Ocean Loading	2 cm	12 hr
Atmospheric Loading	2 cm	weeks
Post-glacial Rebound	several mm/yr	years
Polar motion	0.5 arcsec	$\sim 1.2$ years
UT1 (Earth rotation)	Several mas	Various
Ionosphere	$\sim 2 \text{ m at } 2 \text{ GHz}$	All
Dry Troposphere	2.3 m at zenith	hours to days
Wet Troposphere	0-30 cm at zenith	All
Antenna structure	<10 m. 1cm thermal	
Parallactic angle	0.5 turn	hours
Station clocks	few microsec	hours
Source structure	$5~\mathrm{cm}$	years

### **Output data**

#### · Usually presented to astronomer as $V_{ij}(v,t)$

- $\cdot$  Cross (and auto) correlation spectra
- ·Sampled at visibility dump time, integration time
  - $\cdot$  Can be quite long 10 30s for short baselines

# $\cdot$ Need a lot of overhead information to be used for calibration and processing

- · IF labels, and polarizations
- $\cdot$  Time tags
- · frequency information, edge and increment
- ·Antenna indexes
- $\cdot$ u,v,w coordinates
- ·Telescope pointing and source labeling
- · Maybe other details of correlator model
- · Format for transport: FITS
  - But calibration software depends critically on content...



### Calibration

- $\cdot$  Three levels of calibration, and editing also important
- · A priori and built in:
  - $\cdot$  Pointing, antenna gain, system temperatures
  - ·Antenna positions, time, frequency
  - $\cdot$  Geometrical model, delay, uv coordinates

#### $\cdot$ Cross calibration

- $\cdot$  Known sources, bright, simple structure, accurate position
- $\cdot$  Often making assumptions on stability instrument, sky
- $\cdot$  Sometimes done by observatory, sometimes astronomer

 $\cdot \operatorname{Can}$  be critical for the succes of the experiment

### $\cdot$ Self-calibration

- $\cdot$  Iterative process done by astronomer
- ·Let's say it is 'heuristic'...



### Antenna based calibration

- Want to measure the visibility produced by the sky intensity
- Practice is signals corrupted by instrumental and propagation effects

 $\tilde{V}_{ij}(t) = G_{ij}V_{ij}(t) + \varepsilon_{ij} + \eta_{ij}$ 

• Assume G being dominated by antenna based effects:

$$G_{ij} = g_i(t) g_j^*(t) = a_i(t) a_j(t) e^{i(\theta_i(t) - \theta_j(t))}$$

 $\cdot$  There should be no baseline-based error for robust correlators

• Use known source to solve for complex antenna gains

 $\cdot$  Intuitive to talk about antenna amplitude and phase

- $\cdot$  Point source (unresolved) with known (or constant) flux
- ·With N antennas need to solve for 2N-1 unknowns
  - $\cdot$  And we have N(N-1) measurements (complex)
  - $\cdot$  S/N considerations and coherence time



For N=4, 6 baselines responses are measured: r<sub>12</sub>, r<sub>13</sub>, r<sub>14</sub>, r<sub>23</sub>, r<sub>24</sub>, r<sub>34</sub>

Normal practices include iterative self-calibration

### **Closure quantities**

· Important property when effects are antenna based  $V_{ij} = g_i \cdot g_j^* \hat{V}_{ij}$ 

 $\cdot$  Both instrumental and atmospheric phases:

$$\phi_{ij} = \hat{\phi}_{ij} + \eta_i - \eta_j$$

- $\cdot \, \text{Can}$  form closure phase on triangle
  - $\cdot\,\text{All}$  antenna-based errors drop out

$$C_{ijk} = \phi_{ij} + \phi_{jk} + \phi_{ik} = \hat{\phi}_{ij} + \hat{\phi}_{jk} + \hat{\phi}_{ik}$$

- · Similar for amplitude and 4 tels
- Important constraint for
  - $\cdot$  self-calibration
  - $\cdot$  hybrid mapping
  - RML methods can work directly with this • But require pos and total flux to be fixed
  - · Data quality control



## Example comparison 2017 vs 2018



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#### • Comparing old an new software

- •Some non-standard processing
- Amplitudes from overlapping uv-tracks
- Constrained estimates of zero-spacing

#### • Several engineering releases FITS-IDI (correlator output)







#### Flagging bad data is a major effort in this process "Bad data is worse than no data"

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120 /41

### Polarization

- EM waves (including radio) have E- and B components
- In radio interferometry measure two orthogonal E-field components
  - $\cdot$  circular (RL) or linear (XY)
  - · Linear polarization:  $E_x$  and  $E_y$  are unequal
  - ·Circular polarization:  $\vec{E}$  rotates
  - · Combined:  $\vec{E}$  traces an ellipse
- $\cdot$  Form Stokes I,Q,U,V from cross hands
- · For example in circular basis:

$$I = \left\langle E_r E_r^* \right\rangle + \left\langle E_l E_l^* \right\rangle = \left\langle A_r^2 \right\rangle + \left\langle A_l^2 \right\rangle$$
$$Q = \left\langle E_r E_l^* \right\rangle - \left\langle E_l E_r^* \right\rangle = \left\langle 2A_r A_l \cos(\delta_{rl}) \right\rangle$$
$$U = -i \left\langle E_r E_l^* \right\rangle + i \left\langle E_l E_r^* \right\rangle = \left\langle -2A_r A_l \sin(\delta_{rl}) \right\rangle$$
$$V = \left\langle E_r E_r^* \right\rangle - \left\langle E_l E_l^* \right\rangle = \left\langle A_r^2 \right\rangle - \left\langle A_l^2 \right\rangle$$



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### **More Stokes**

- $\cdot$  Stokes I measures total intensity
- Stokes Q and U measure linear polarization
  - . Fractional linear polarization:  $p = \sqrt{Q^2 + U^2}/I \le 1$
- Stokes V measures circular polarization
  - Fractional circular polarization:  $v = ||V||/I \le 1$
- $\cdot$  Degree of polarization:

 $P = \sqrt{Q^2 + U^2 + V^2}/I$ 

- $\cdot$  Very relevant for AGN studies
  - $\cdot$  Synchrotron intrinsically polarised
  - $\cdot$  Jet collimination
  - $\cdot$  Jet launching





### **Polarisation in the EHT**

- · Particularly challenging
- ALMA has linear feeds, most other telescopes circular

· Current solution: calculate from correlator output

- $\cdot$  Using ALMA internal calibration
- Other antennas have various mount configurations
  - $\cdot$  Rotating their polarised beams differently on the sky
  - $\cdot$  Occasionally even one channel may be missing

#### Polarisation calibration

- $\cdot \, \text{Requires}$  unpolarised sources
- $\cdot$  and/or source of known polarisation
- $\cdot$  Developed method of self-polarisation calibration
  - $\cdot$  Using polarimetric closure properties



#### THE ASTROPHYSICAL JOURNAL LETTERS, 910:L12 (48pp), 2021 March 20

## EHT results

- Published 2y after Stokes I...
- Significantly polarised
  - Mostly azimuthal
  - With some significant evolution
- A simple model has:
  - $n_e \sim 10^{4-7} \, cm^{-3}$
  - B = 1 30 G
  - $T_e = 10^{10-11} \text{ K}$
- Polodial/Vertical organised
- MAD models favoured

Event Horizon Telescope



THE ASTROPHYSICAL JOURNAL LETTERS, 910:L13 (43pp), 2021 March 20





Figure 7. Fiducial M87 average images produced by averaging results from our five reconstruction methods (see Figure 6). Method-average images for all four M87 observation days are shown, from left to right. These images show the low-band results; for a comparison between these images and the high-band results, see Figure 28 in Appendix I. We employ here two visualization schemes (top and bottom rows) to display our four method-average images. The images are all displayed with a field of view of 120  $\mu$ as. Top row: total intensity, polarization fraction, and EVPA are plotted in the same manner as in Figure 6. Bottom row: polarization "field lines" plotted atop an underlying total intensity image. Treating the linear polarization as a vector field, the sweeping lines in the images represent streamlines of this

## Even did stokes V

- Some low level circular pol detected
  - But not really imaged at 5%
- Faraday rotation of linear pol
  - Probably not a good measure of physical conditions





## Many 'official' results

- 187 Papers in 6 years
  - >100 individual first authors
  - Theory, simulation, i
  - maging,
  - methodology,
  - data analysis,
  - technical development
  - other targets
  - pulsar search
  - ALMA polarisation properties





# End of lecture III