

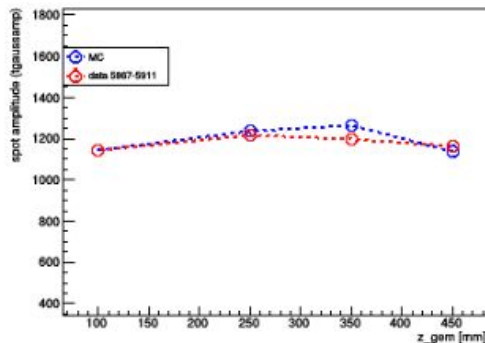
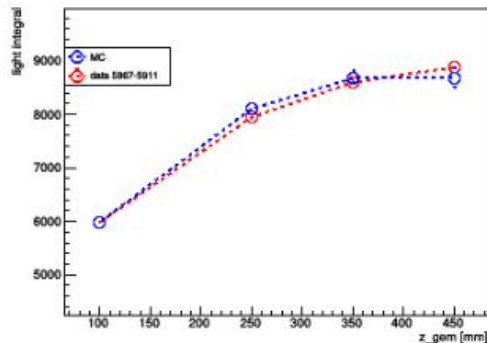
Status of digitization

16-10-2023

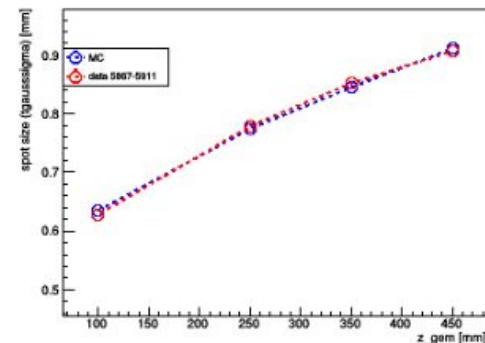
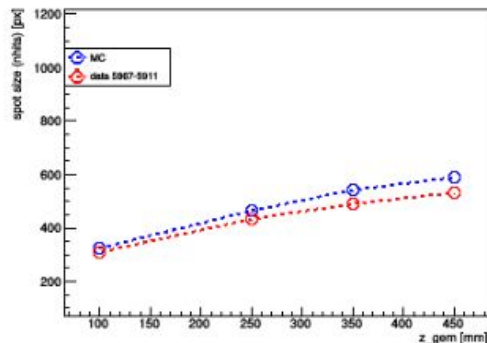
Pietro Meloni, Fabrizio, Petrucci, Davide Pinci

In 2022 we optimized the digitization on these LNF runs: 5867-5911

integral



tgaussigma



Parameters:

events per run= 100 events
detector dimensions = 346cm x 346cm
pixels = 2304 x 2304
pedestal = run 5861

beta= 1e-5

A= 1.52

z_vox_dim=0.1 mm

x_vox_dim= 346/2304 mm

y_vox_dim=346/2304 mm

abs_len= 1400mm

z_gem = 10, 25, 35, 45 cm

GEM1_HV= 440V

GEM2_HV= 440V

GEM3_HV= 440V

random_z = 0

diff_const_sigma0T= 0.1225 mm² (350 μm)
diff_coeff_T= 0.013225 [mm/sqrt(cm)]² (115 μm/sqrt(cm))

diff_const_sigma0L= 0.0676 mm² (260 μm)
diff_coeff_L= 0.00978 [mm/sqrt(cm)]² (99 μm/sqrt(cm))

ion_pot = 0.0462 keV
photons_per_el = 0.07
counts_per_photon = 2.,

But GEM gain varies a lot

So far, we have used the GEM gains measured at LNF.

But now we know that the gain is highly dependent on the humidity, and other environmental factor

```
## fit from Fernando Amaro's single GEM gain measurement
GEM1_gain = 0.0347 * np.exp((0.0209) * opt.GEM1_HV)
GEM2_gain = 0.0347 * np.exp((0.0209) * opt.GEM2_HV)
GEM3_gain = 0.0347 * np.exp((0.0209) * opt.GEM3_HV)
print("GEM1_gain = %d" % GEM1_gain)
print("GEM2_gain = %d" % GEM2_gain)
print("GEM3_gain = %d" % GEM3_gain)

## dividing Fernando's to Francesco&Karolina's single GEM gain measurement
extraction_eff_GEM1 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM1_HV)
extraction_eff_GEM2 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM2_HV)
extraction_eff_GEM3 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM3_HV)
print("extraction eff GEM1 = %f" % extraction_eff_GEM1)
print("extraction eff GEM2 = %f" % extraction_eff_GEM2)
print("extraction eff GEM3 = %f" % extraction_eff_GEM3)
```

Let's keep the gain free and check if we can reproduce LNGS data adjusting its value.

We do a scan in z and gain values and we'll find the best gain for a given calibration run at LNGS.

```
## fit from Fernando Amaro's single GEM gain measurement
GEM1_gain = 0.0347 * np.exp((0.0209) * opt.GEM1_HV)
GEM2_gain = 0.0347 * np.exp((0.0209) * opt.GEM2_HV)
GEM3_gain = 0.0347 * np.exp((0.0209) * opt.GEM3_HV)
print("GEM1_gain = %d" % GEM1_gain)
print("GEM2_gain = %d" % GEM2_gain)
print("GEM3_gain = %d" % GEM3_gain)
```

```
GEM1_gain = opt.GEM1_gain
GEM2_gain = opt.GEM2_gain
GEM3_gain = opt.GEM3_gain
print("GEM1_gain = %d" % GEM1_gain)
print("GEM2_gain = %d" % GEM2_gain)
print("GEM3_gain = %d" % GEM3_gain)
```

No dependency on HV anymore

```
## dividing Fernando's to Francesco&Karolina's single GEM gain measurement
extraction_eff_GEM1 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM1_HV)
extraction_eff_GEM2 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM2_HV)
extraction_eff_GEM3 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM3_HV)
print("extraction eff GEM1 = %f" % extraction_eff_GEM1)
print("extraction eff GEM2 = %f" % extraction_eff_GEM2)
print("extraction eff GEM3 = %f" % extraction_eff_GEM3)
```

```
## dividing Fernando's to Francesco&Karolina's single GEM gain measurement
extraction_eff_GEM1 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM1_HV)
extraction_eff_GEM2 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM2_HV)
extraction_eff_GEM3 = 0.87319885 * np.exp(-0.0020000000 * opt.GEM3_HV)
print("extraction eff GEM1 = %f" % extraction_eff_GEM1)
print("extraction eff GEM2 = %f" % extraction_eff_GEM2)
print("extraction eff GEM3 = %f" % extraction_eff_GEM3)
```

The best gain will be the one that minimize the root-mean-square difference between data and MC.

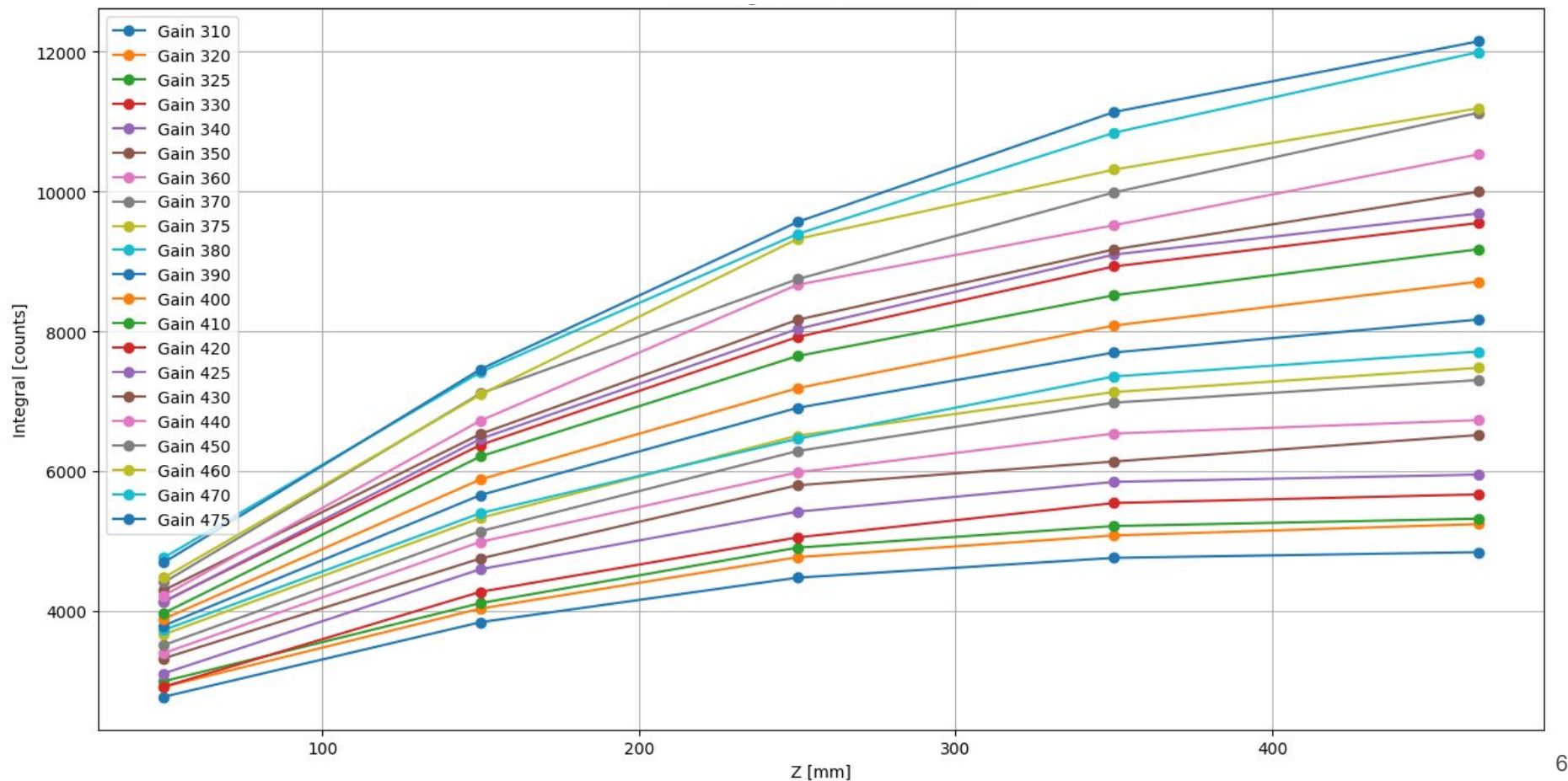
Two important notes:

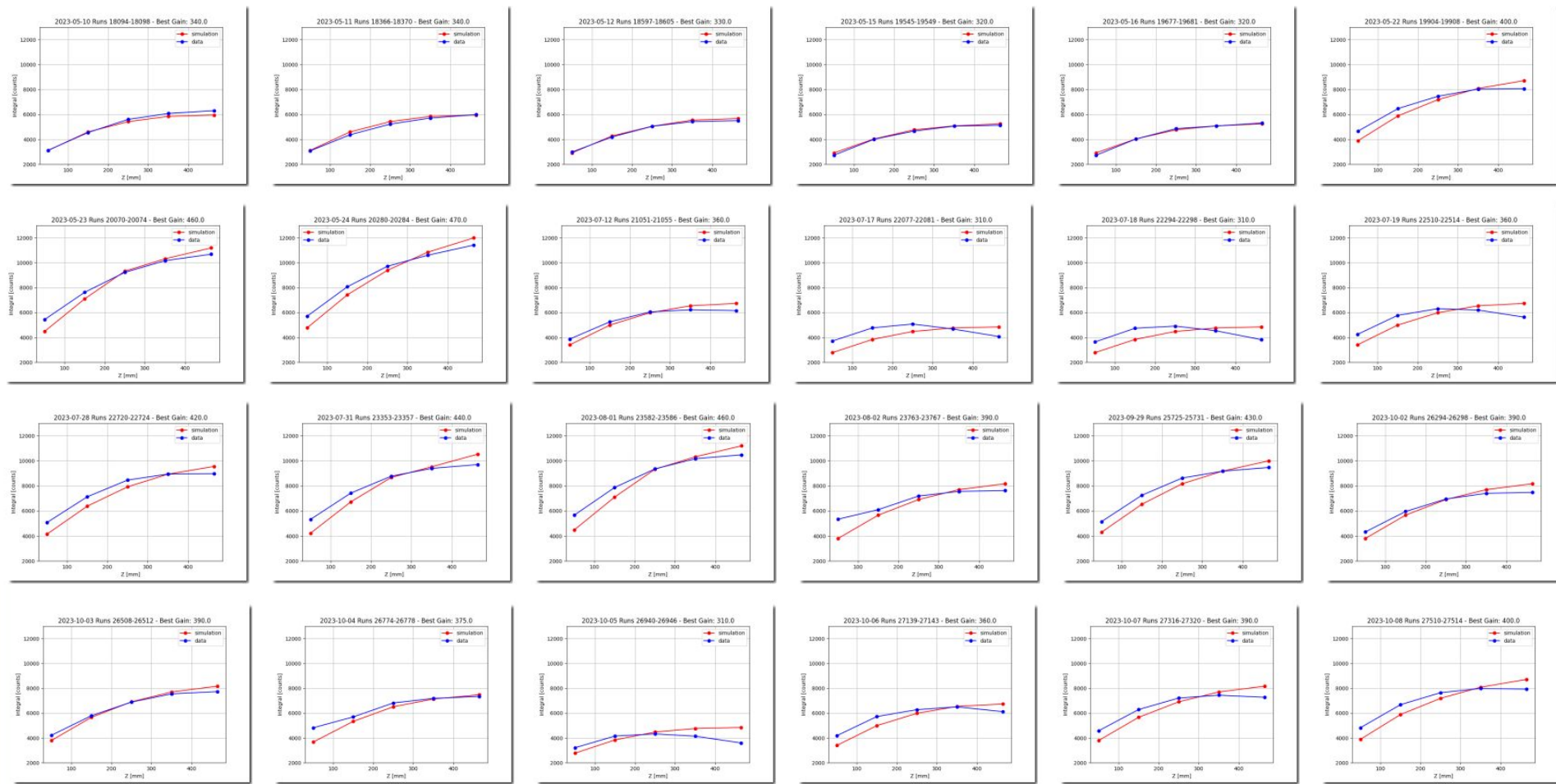
2. Saturation parameter A (normalization factor) is now set to 1. In fact, the A parameter was set to 1.52 to reproduce LNF data (since we fixed the gain).

$$G_3 = A \sum_{\text{voxels}} \frac{e^{\alpha \Delta V}}{1 + \beta n_0 e^{\alpha \Delta V}}$$

2. Now we are setting the drift field to 800 V/cm (still using diffusion parameters simulate in Garfield by Francesco Renga). Previously, we were using 1000 V/cm, but the working point underground is at 800 V/cm.

NOTE: **gain(440 V) = 342** and **gain(420 V) = 225** (measured at LNF)

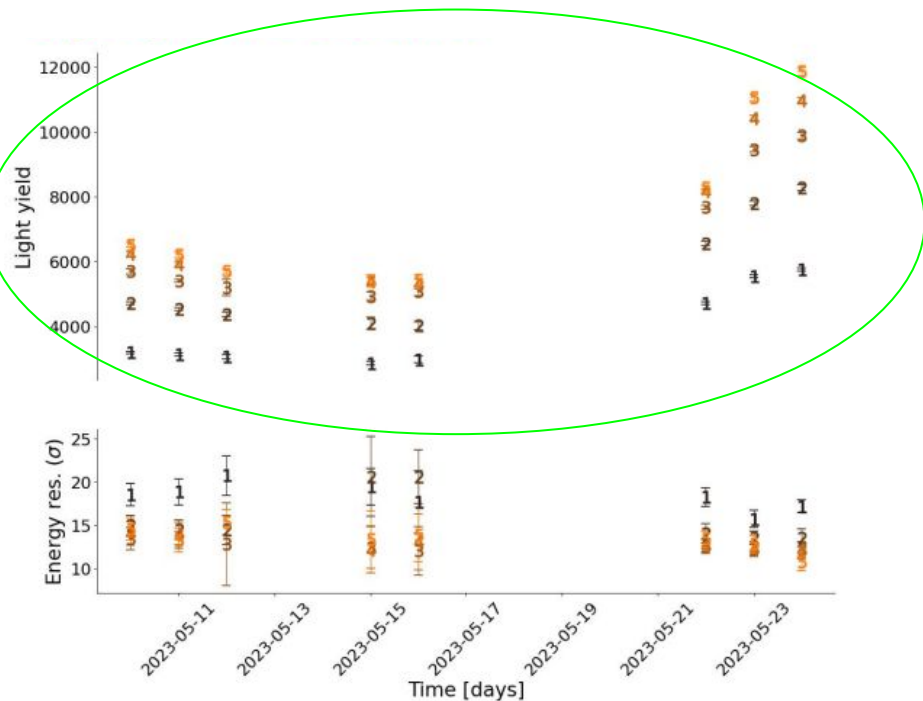




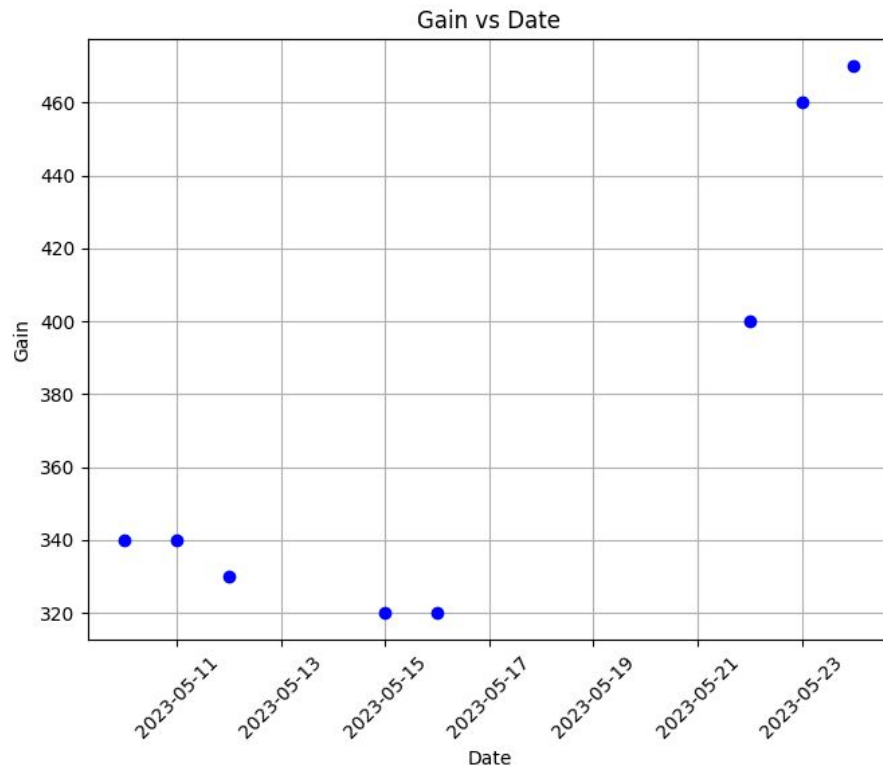
The simulation reproduces really well data in May, then it worsens a bit: especially at high z where MC is higher. Maybe we have a different attenuation due to the change in humidity? (I'll come back to this)

In May 2023 the best gain parameter has the same trend as the LY in data

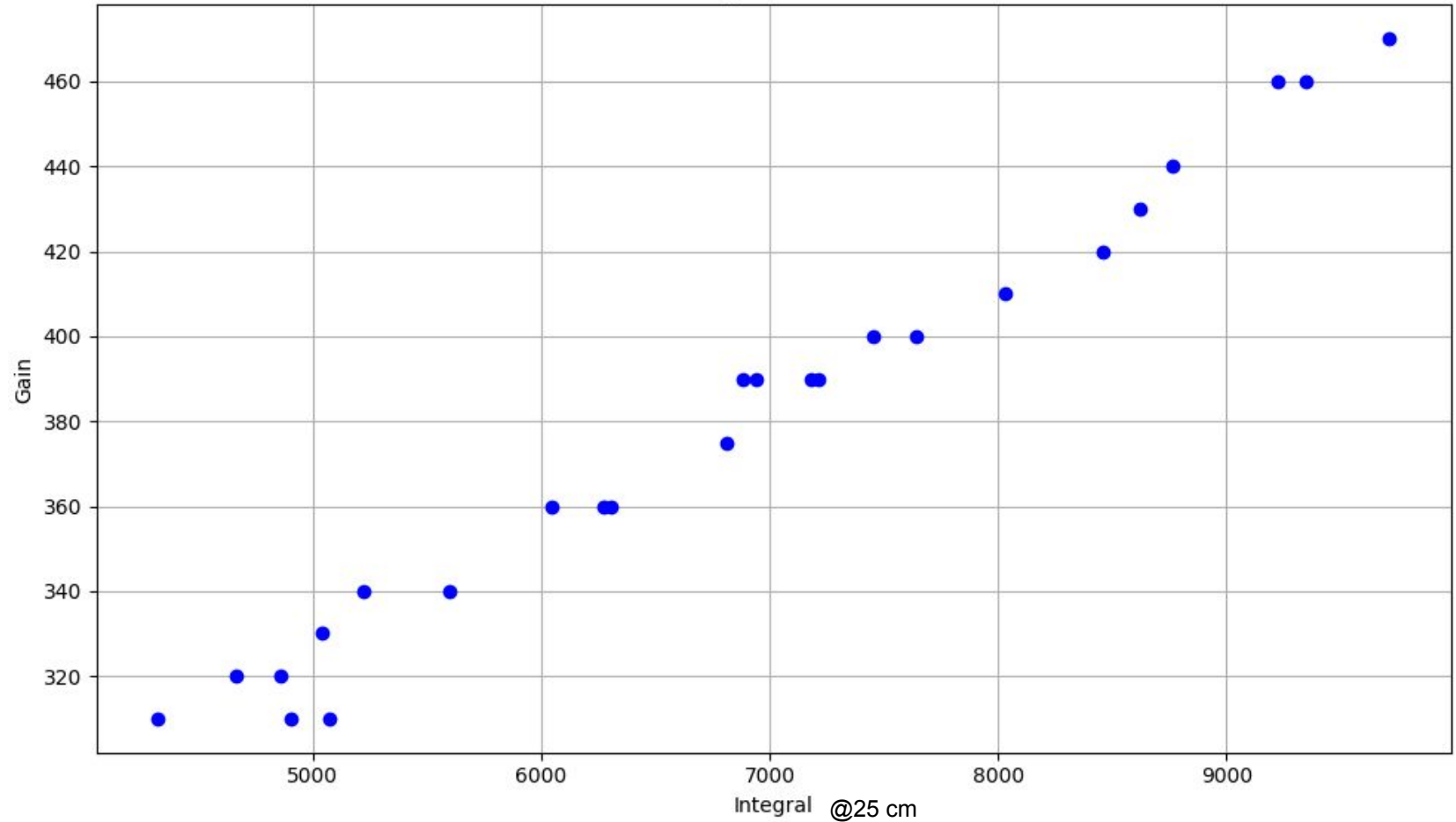
Rita Roque analysis (Coimbra 2023)



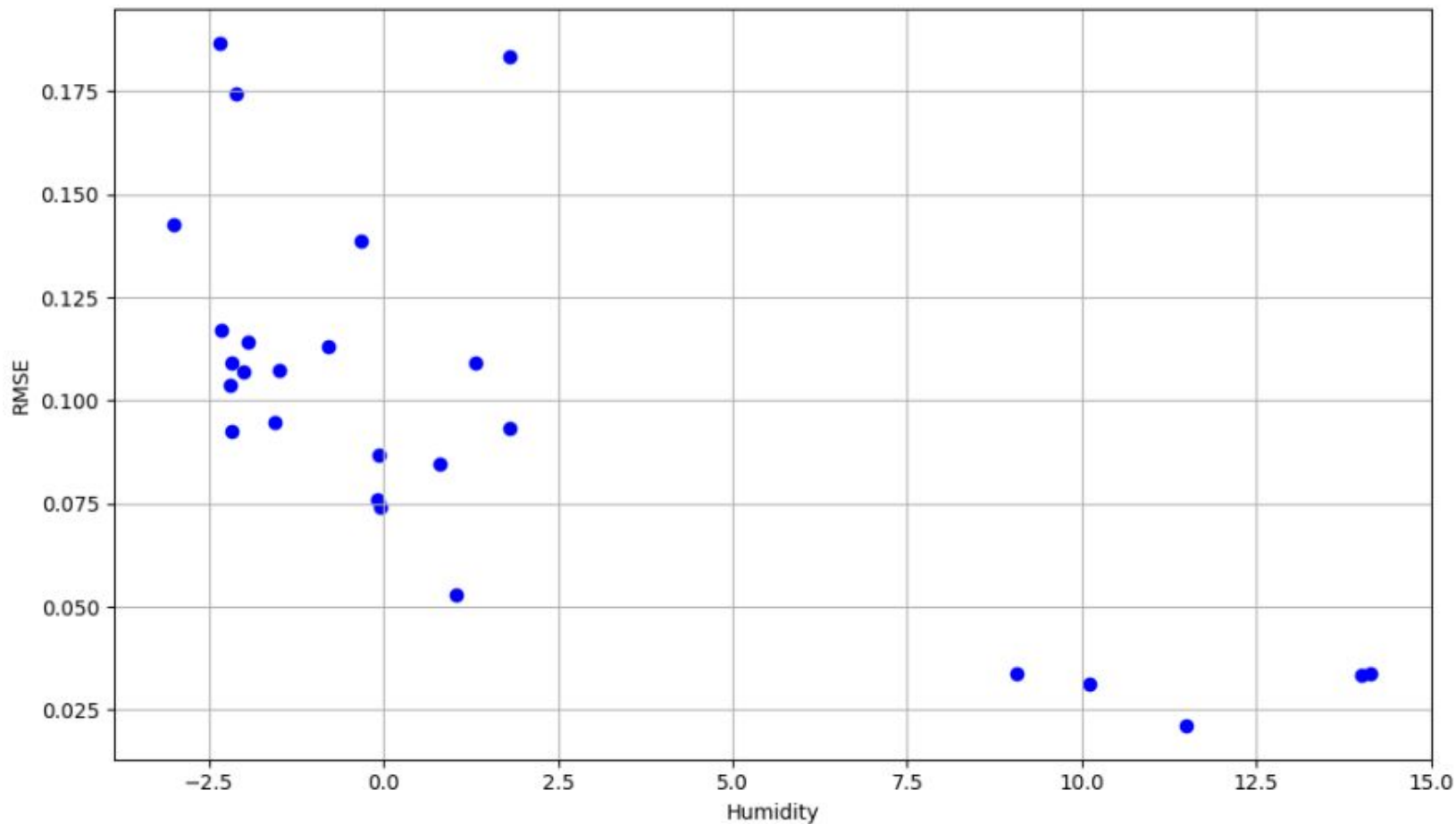
Best gain parameters for digitization



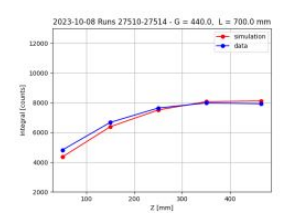
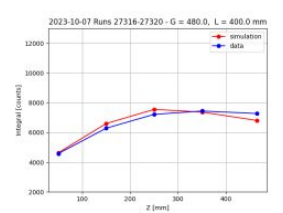
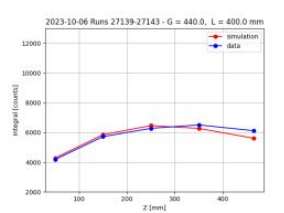
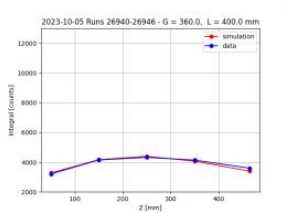
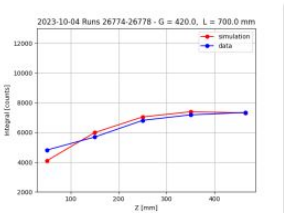
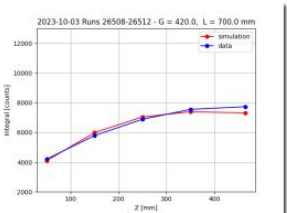
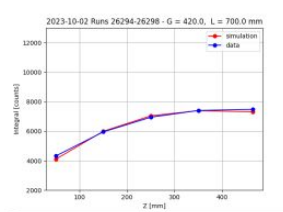
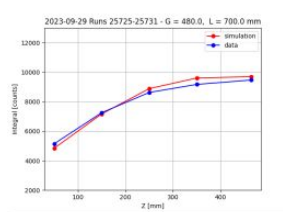
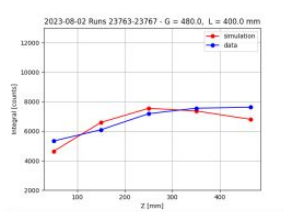
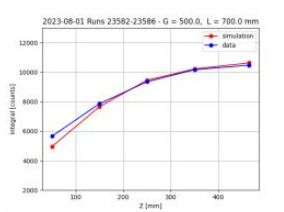
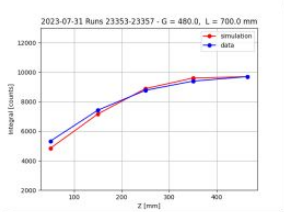
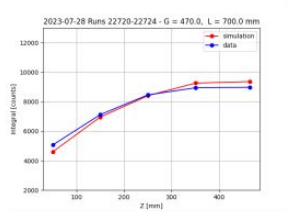
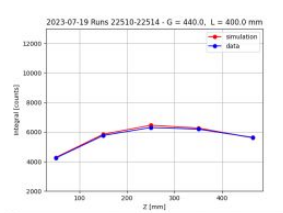
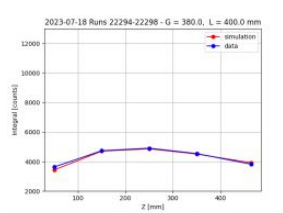
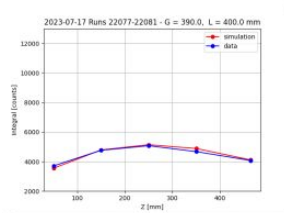
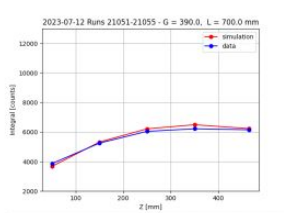
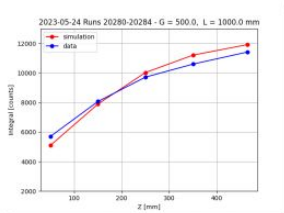
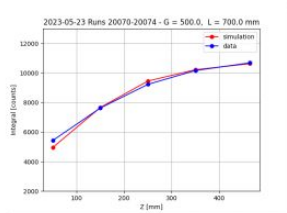
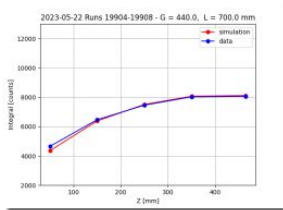
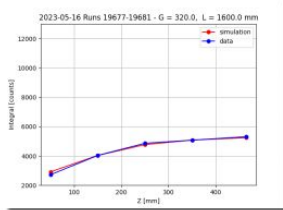
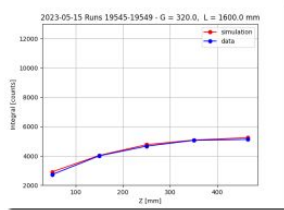
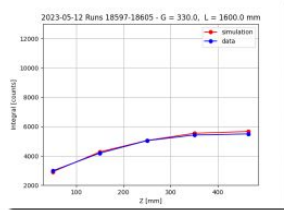
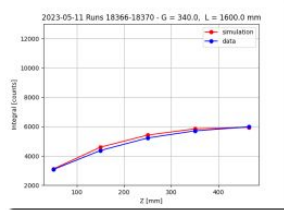
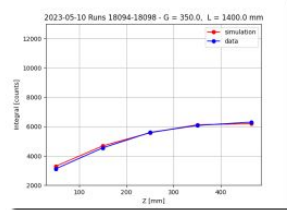
As expected, the integral @ 25 cm (data) increase with the best gain paramter



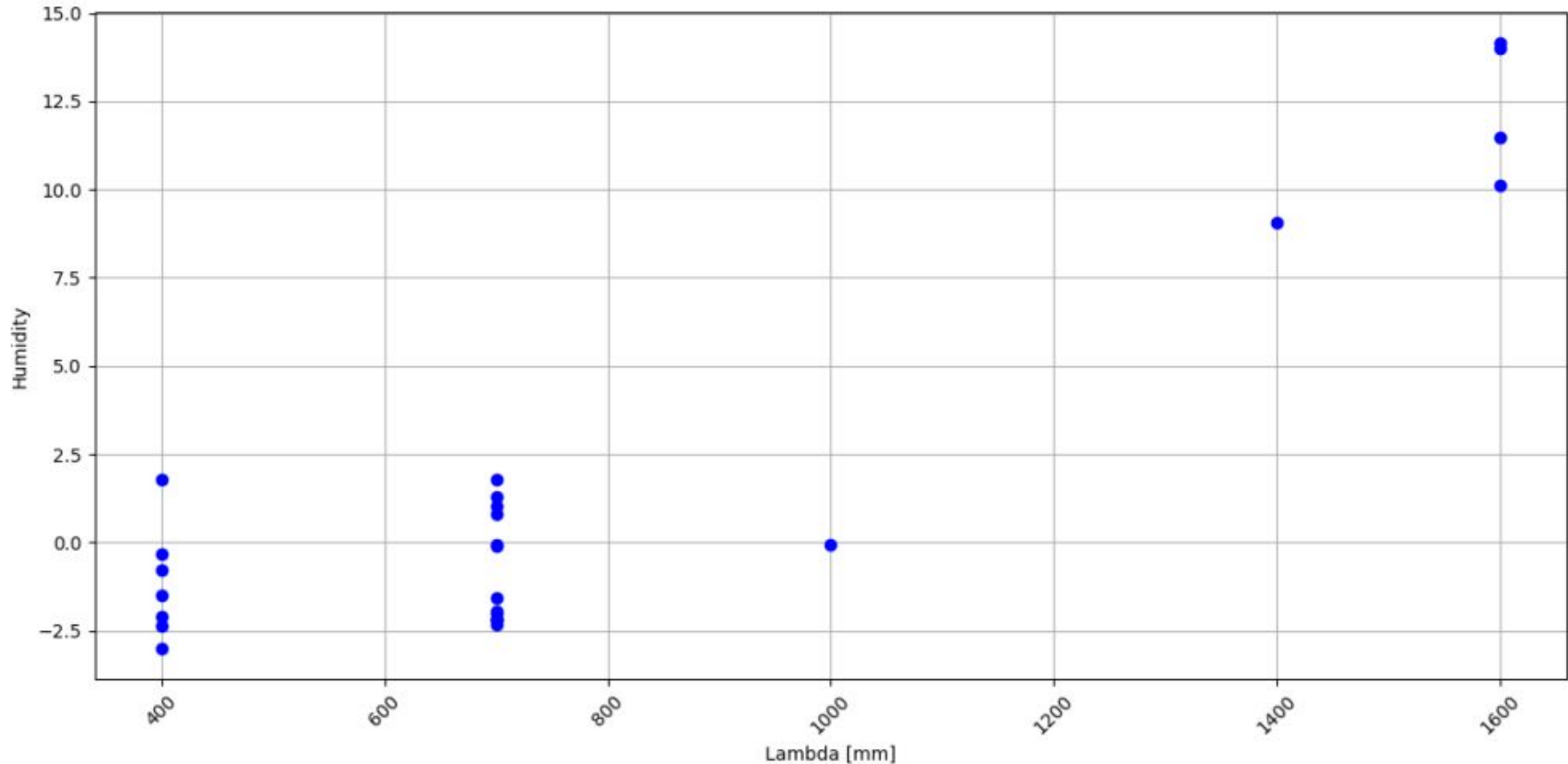
Strangely, the simulation appears to better match the data in low humidity environment.
Is this true because we tuned the digitization on data with high humidity at LNF?



Let's try to find the best pair (gain, abs_length)...
(to improve simulation at high z)



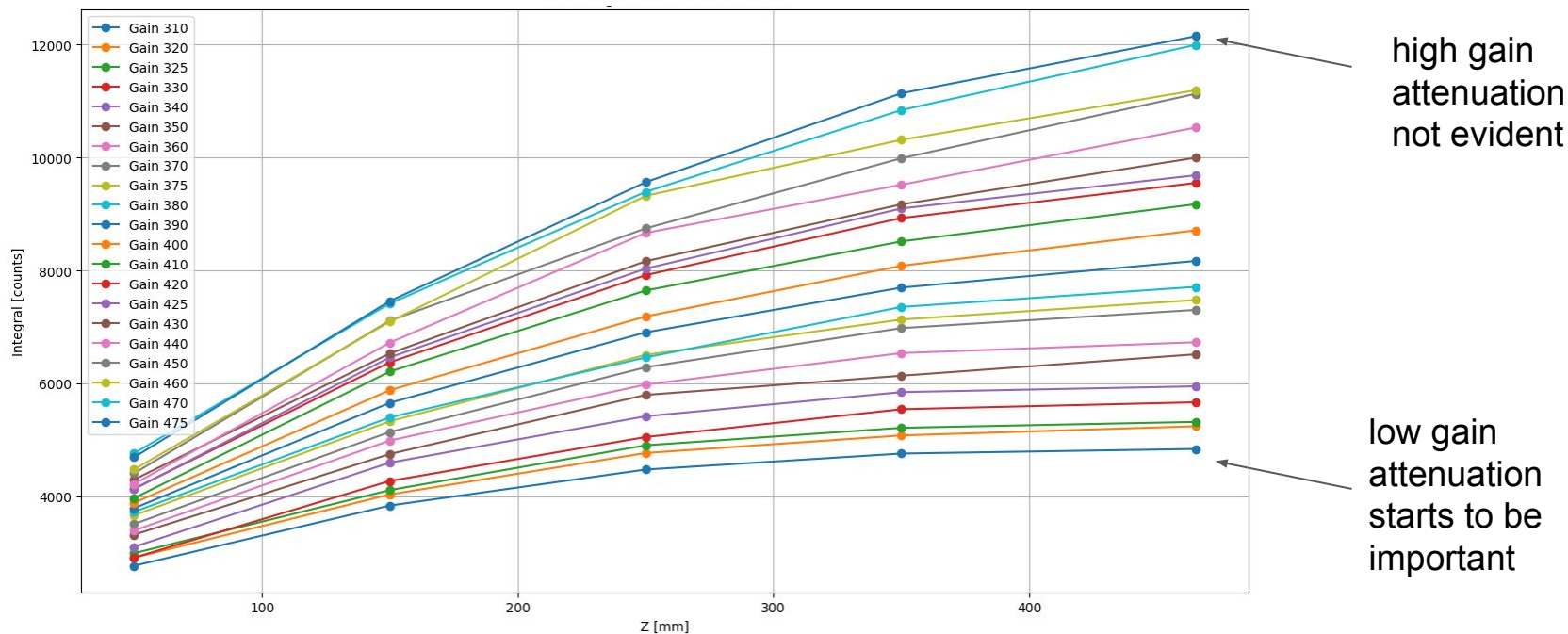
In theory, we expect more attenuation at high humidity. But it seems to be the other way around.



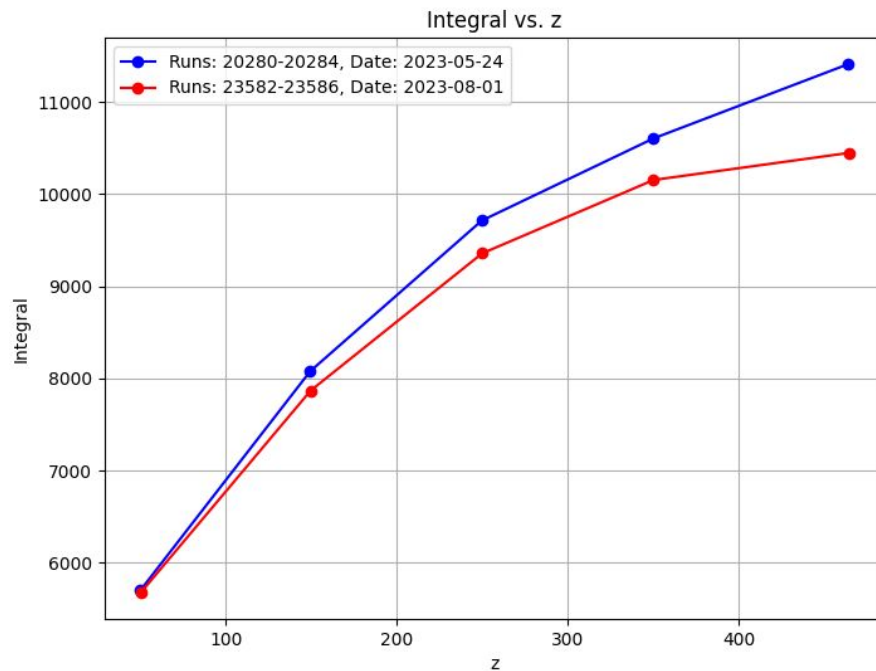
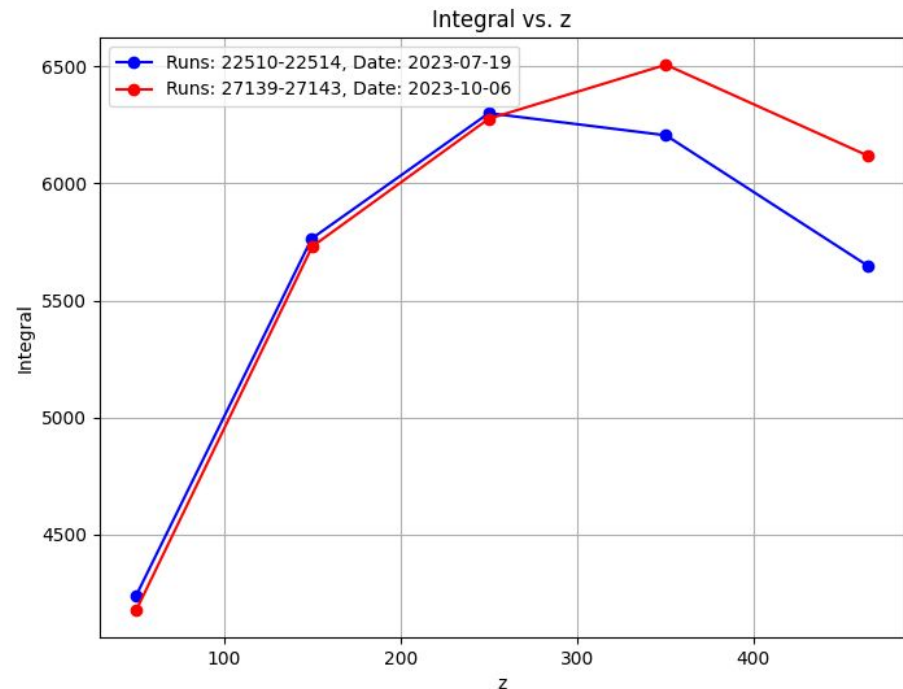
Also, we don't expect such a big difference in attenuation

Maybe the difference is not due to attenuation?

As you see, different LY/gains can make the attenuation more evident.



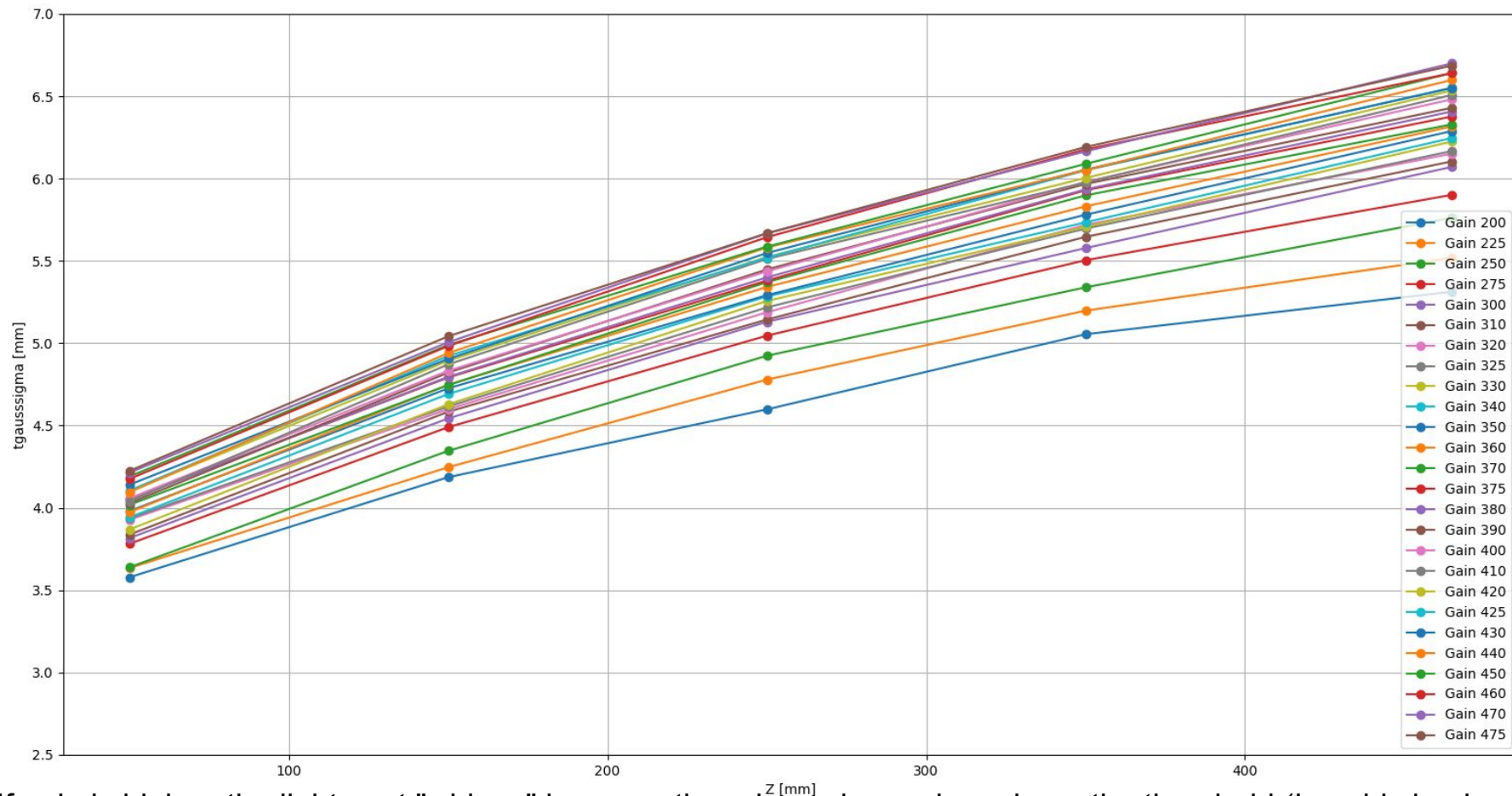
However, we have pairs of runs (data) that saturates in the same way and then diverge. So it really seems to be a difference in attenuation.



So, we can't reproduce these different behaviors in MC without changing the attenuation

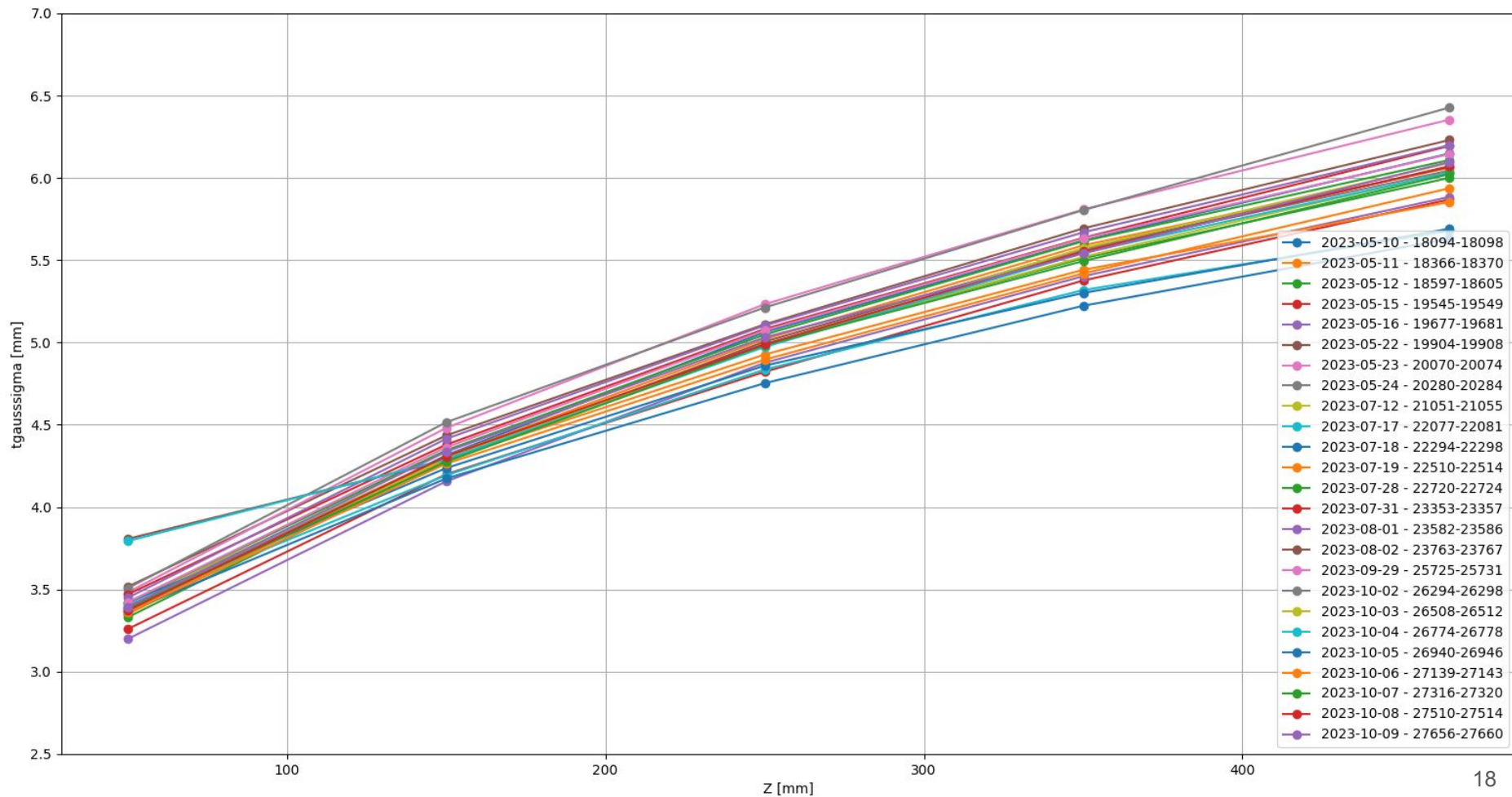
Let's looking at tgausssigma (spotsize)....
Forgetting the attenuation problem

Simulated data

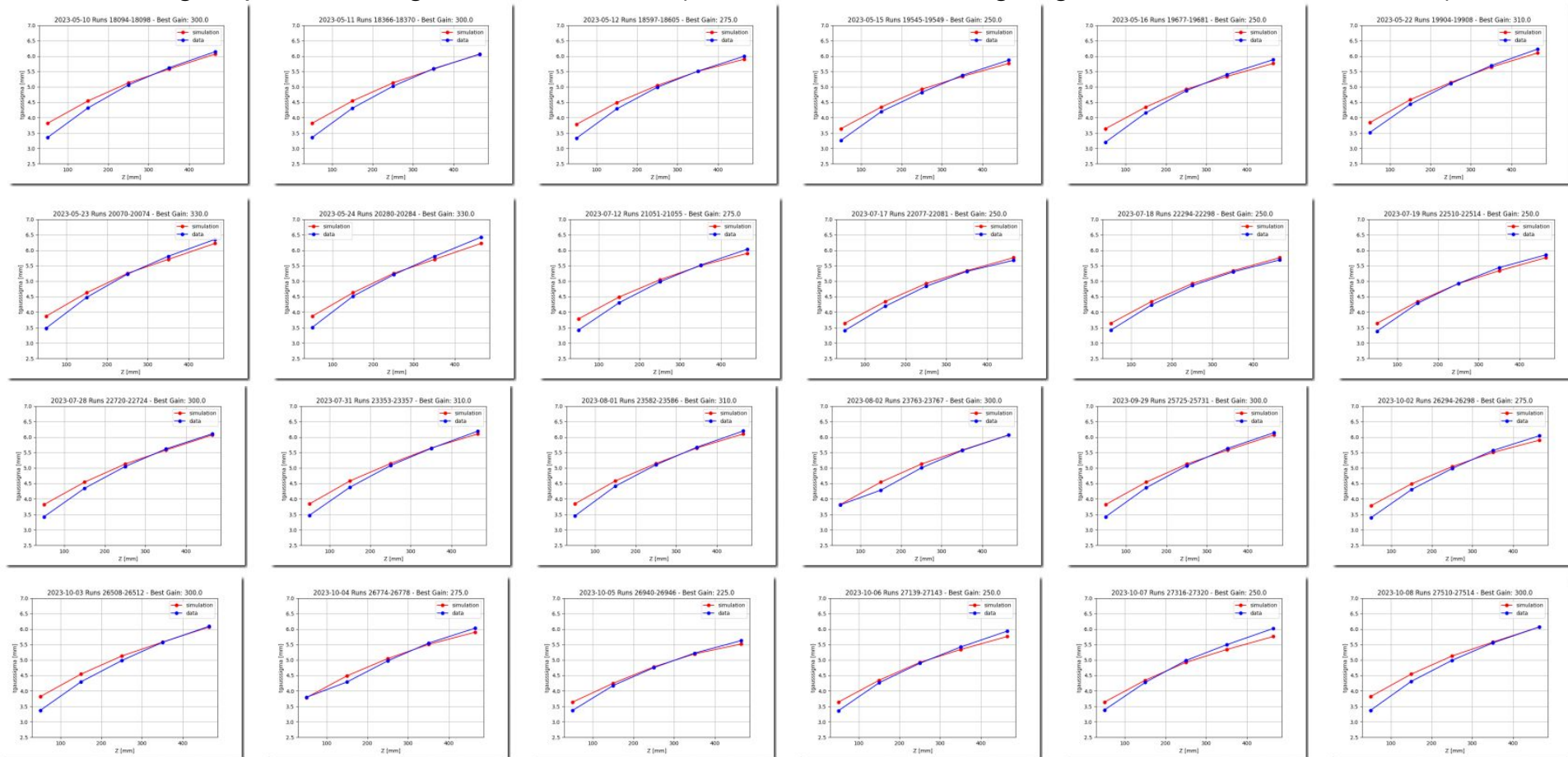


If gain is higher, the light spot "widens" because the edges also end up above the threshold (I could check if this doesn't happen when not applying camera noise and reconstruction)

Real data



Now, best gain parameters go from **225 to 330** (while the fit on the integral gave values from **310 to 470**)

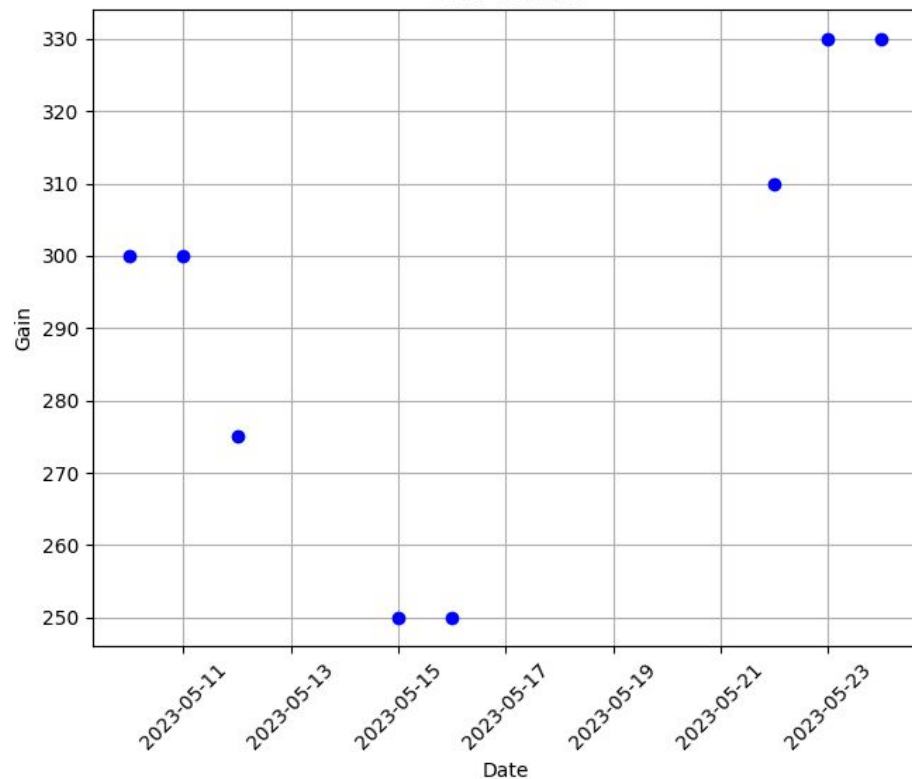
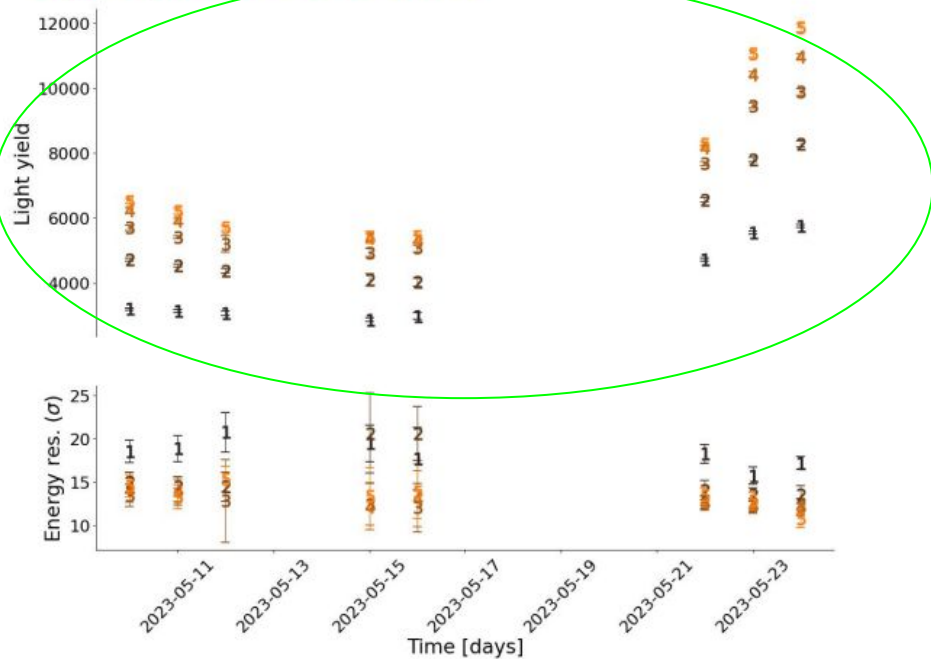


Discrepancies at low z mean we diffuse too much in the GEM. Discrepancies between the range of 'best gains' also mean the GEM diffusion in real data is less than in MC.

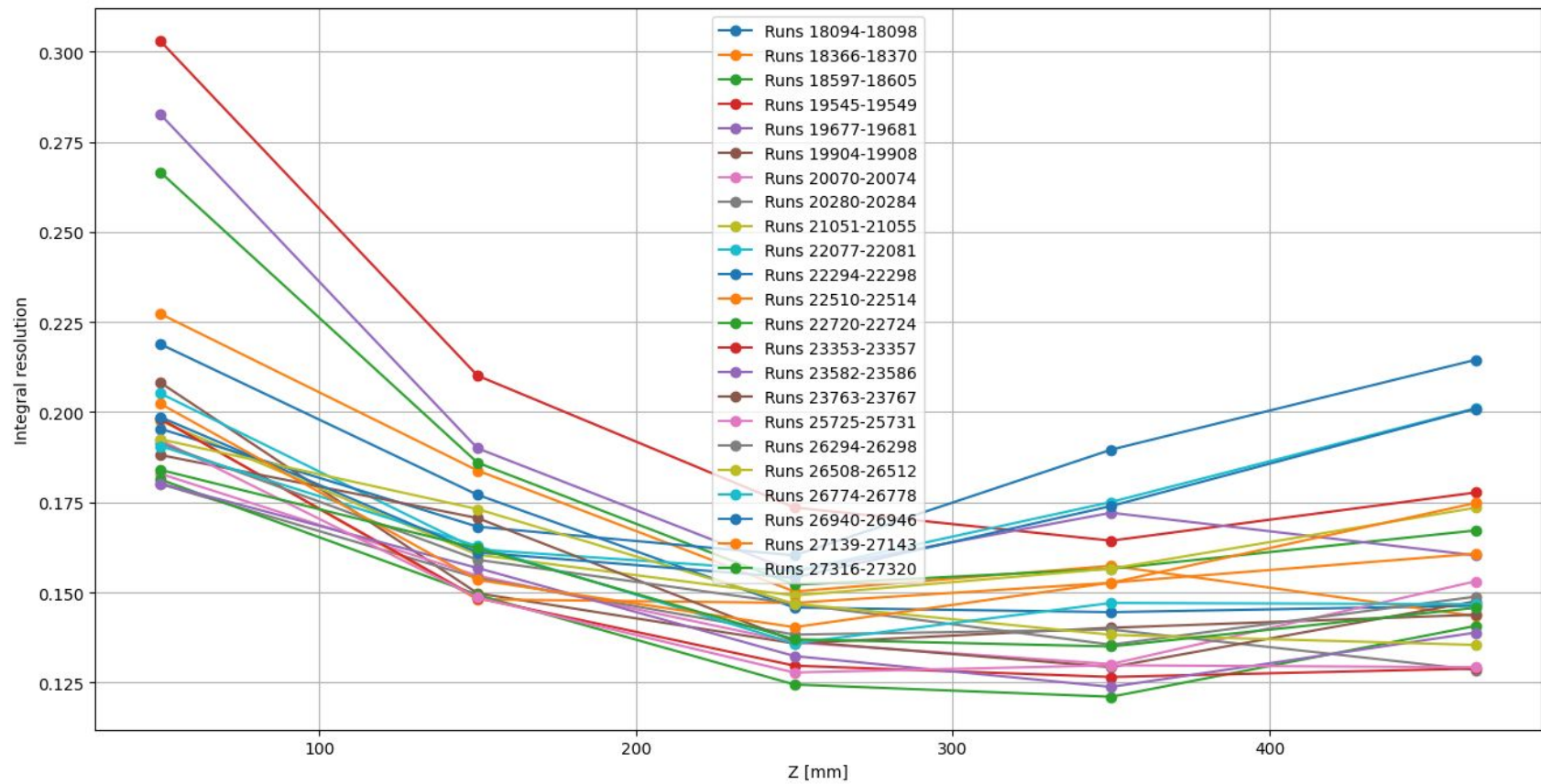
In May 2023 the best gain parameter has the same trend as the LY in data

Best gain parameters for digitization

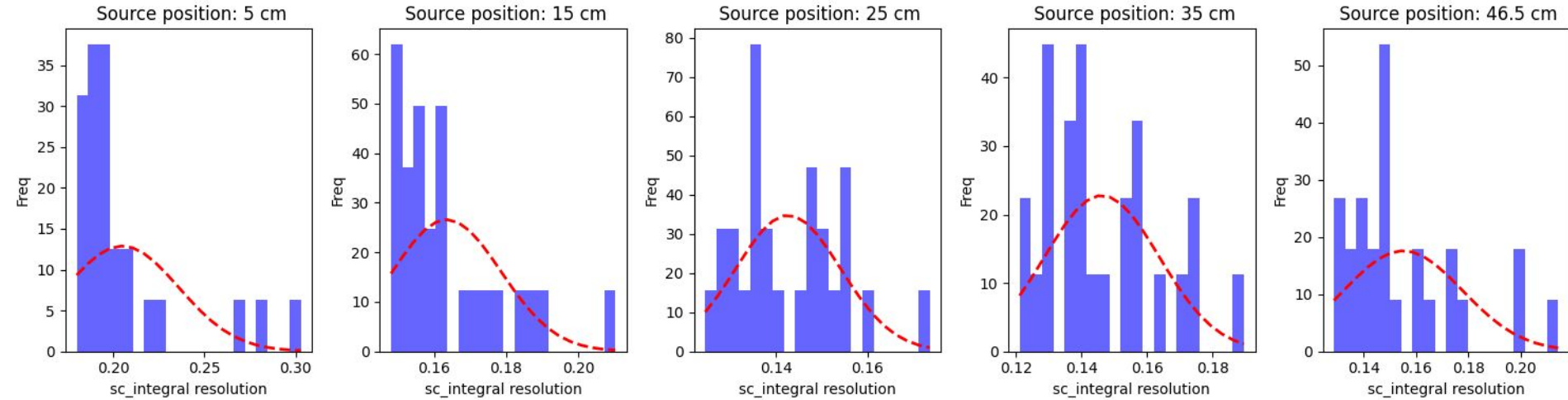
Rita Roque analysis (Coimbra 2023)



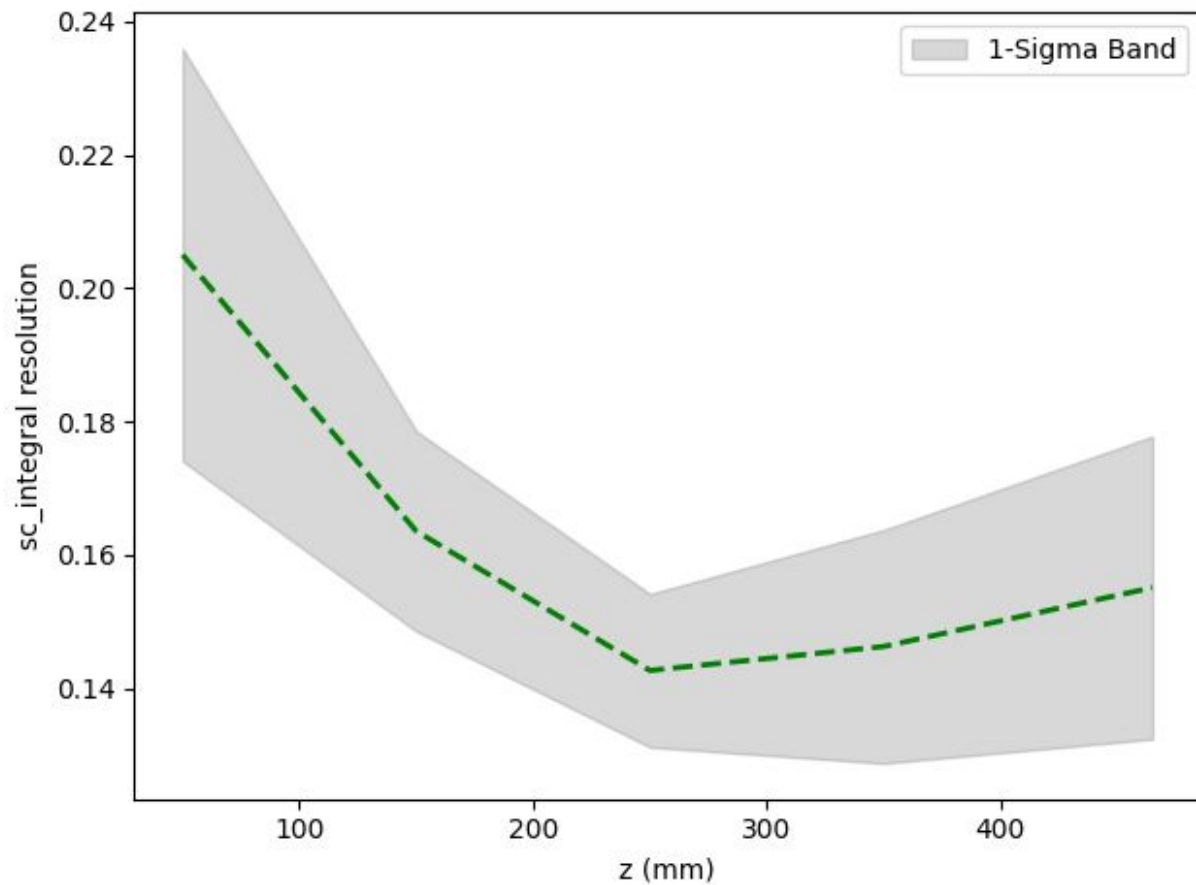
Let's have a look at the integral resolution vs z ...

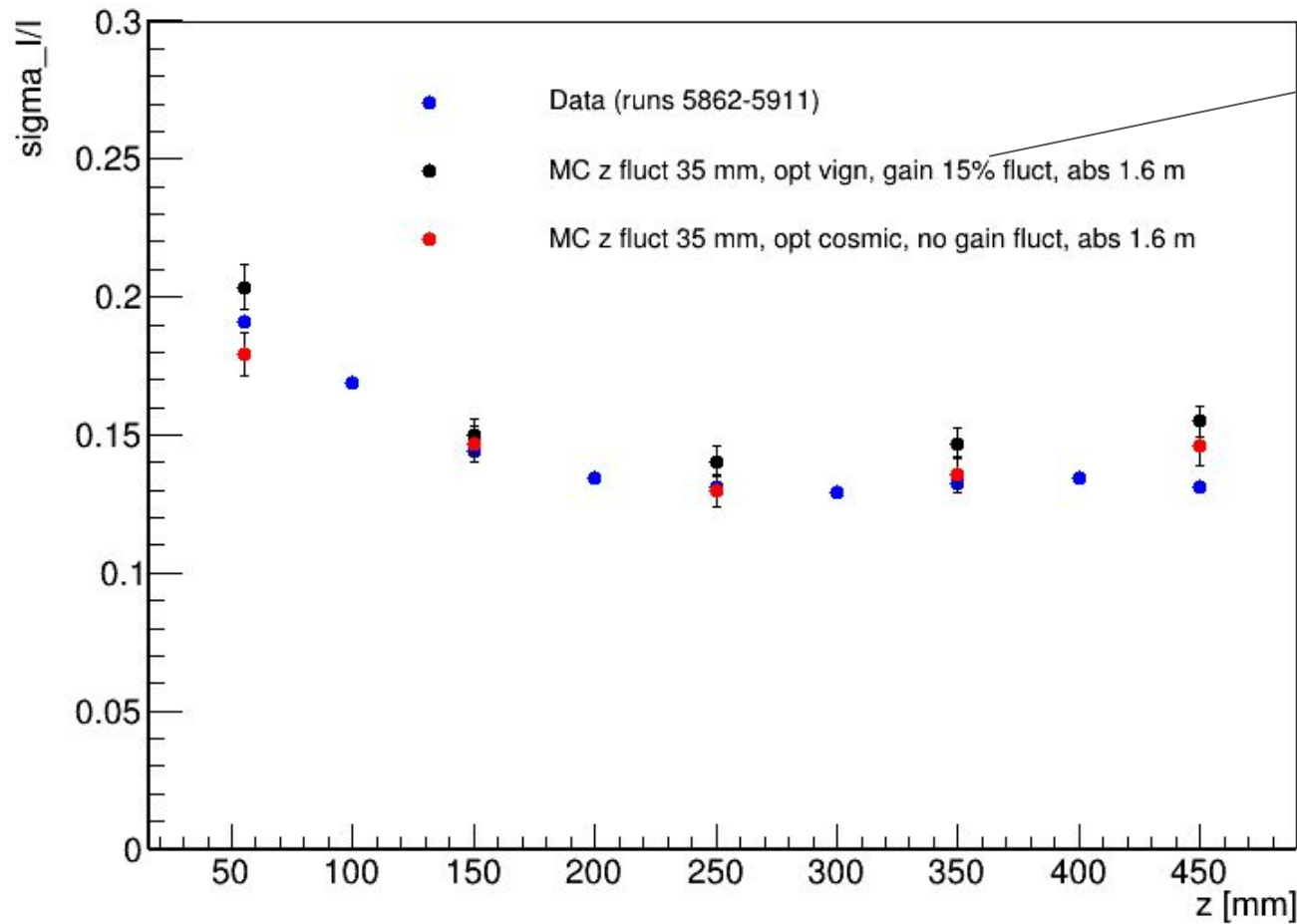


Gaussian fit on the 23 resolution values at given z:



We build a 1-sigma band, that we should use for comparison with MC





Gain fluctuations to
simulate gain
disuniformities

The band created with LNGS data overlaps well with both LNF data and the MC

Conclusions

1. The good comparison between data/MC at LNF was obtained by keeping the GEM gain fixed (as measured at LNF) and by adjusting the normalization parameter in the saturation A
2. We now know gain fluctuates a lot, so we can't keep it fixed in MC.
3. As soon as we have a measurement of the absolute gain/LY in data we should use this information to set the gain in digitization
4. There are still things we don't understand in data (attenuation)
5. Diffusion in GEM is probably overestimated in MC
6. Integral resolution also varies a lot -> we should consider those fluctuations when comparing with MC, in simulation paper