

Statistical Physics and Ecology are they a good match?

~~(Probably Not)~~



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PhD Seminars: Season 8, Episode 2

Roma La Sapienza, 22 November 2023



SAPIENZA
UNIVERSITÀ DI ROMA



Introduction



Why **theoretical physics** and **ecology**?

An ecosystem is a system made of **large** number of **interacting** species

Many open challenges:

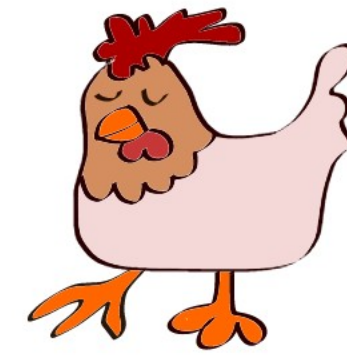
- Effect of new species addition, mutation or alien
(*i.e.*, blue crab, grey vs red squirrel, Nile perch in Lake Victoria, plant invasion)
- Effect of change in ecological parameters
(due to human intervention or climate change)
- Role of **biodiversity** and effect of its reduction

Example of ecological model: **Lotka-Volterra**

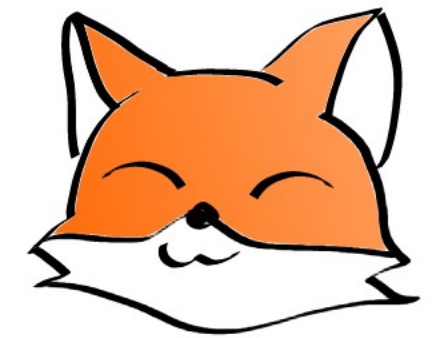
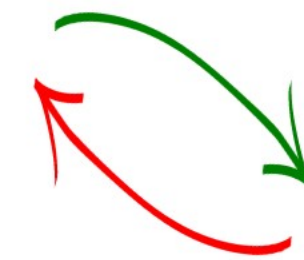
Lotka-Volterra Model

$$\left\{ \begin{array}{l} \frac{dx}{dt} = Ax - Bxy \\ \frac{dy}{dt} = -Cy + Dxy \end{array} \right.$$

Prey

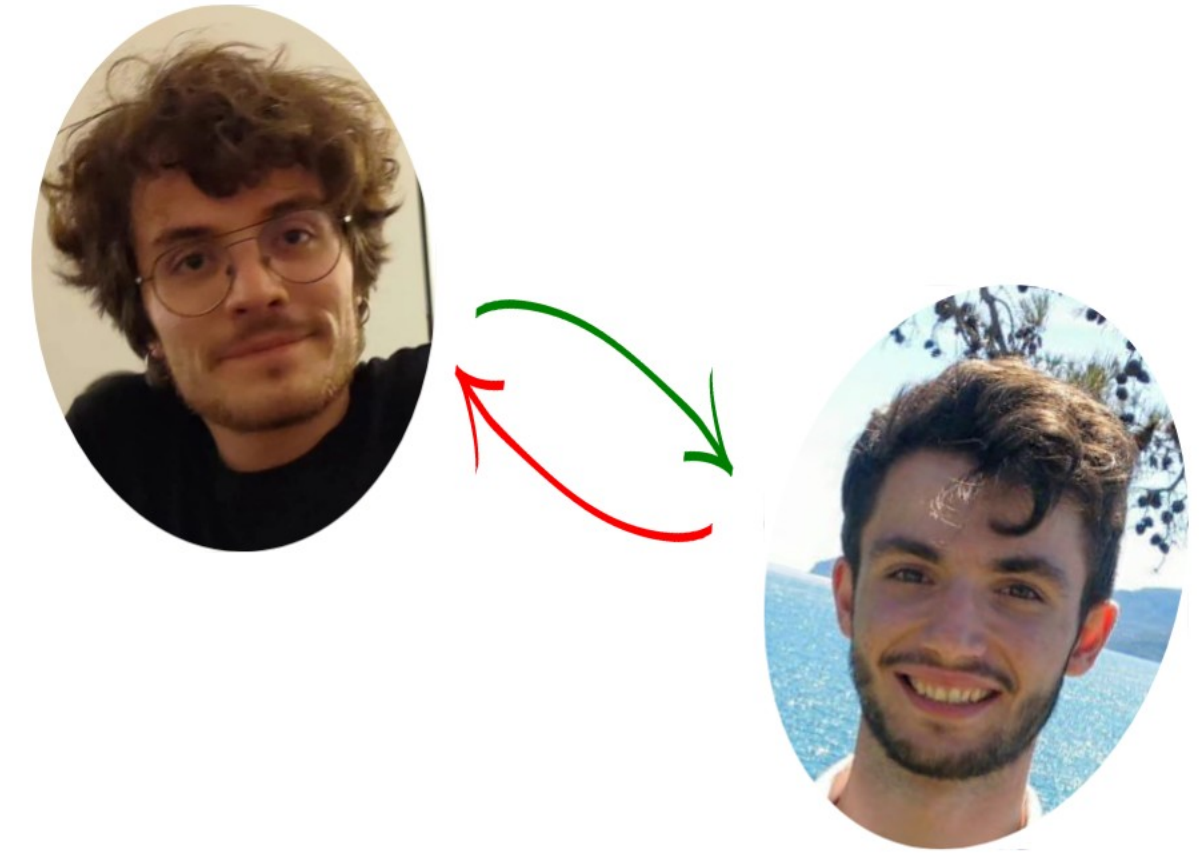


Predator



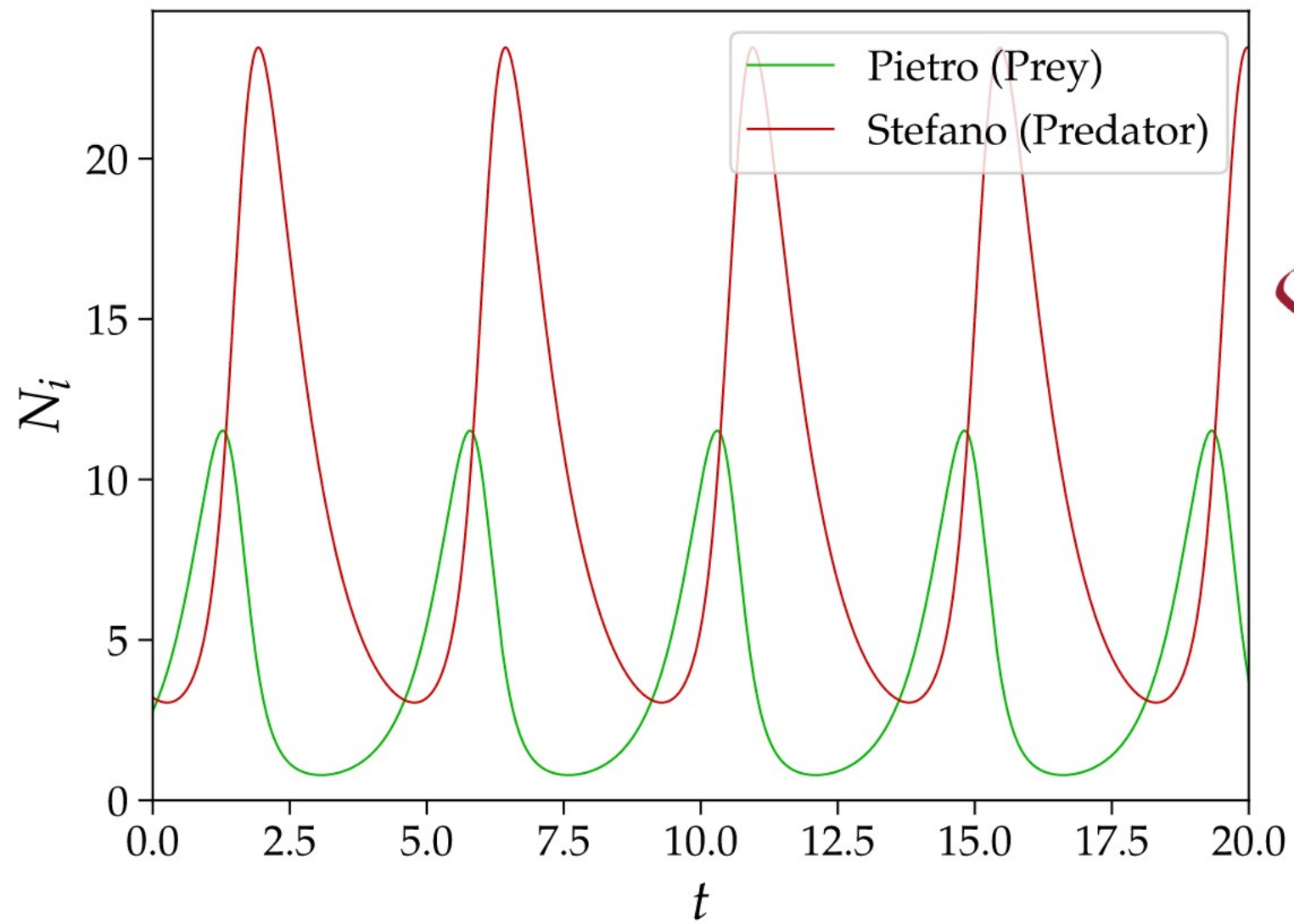
Lotka-Volterra Model

$$\begin{cases} \frac{dx}{dt} = Ax - Bxy & \text{Prey} \\ \frac{dy}{dt} = -Cy + Dxy & \text{Predator} \end{cases}$$

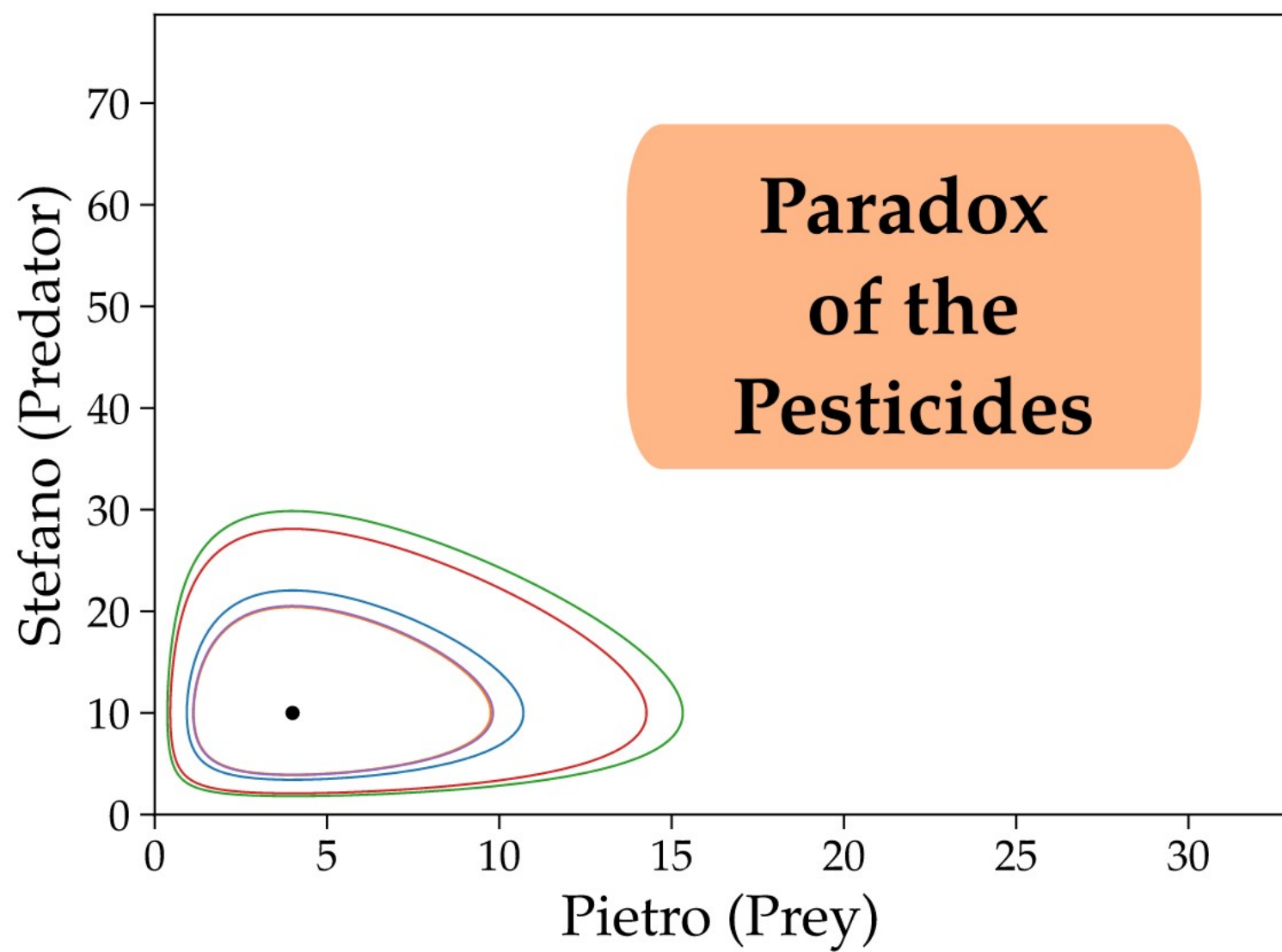


- A : prey growth rate
- C : predator mortality rate
- B and D : effect of interaction on prey and predator

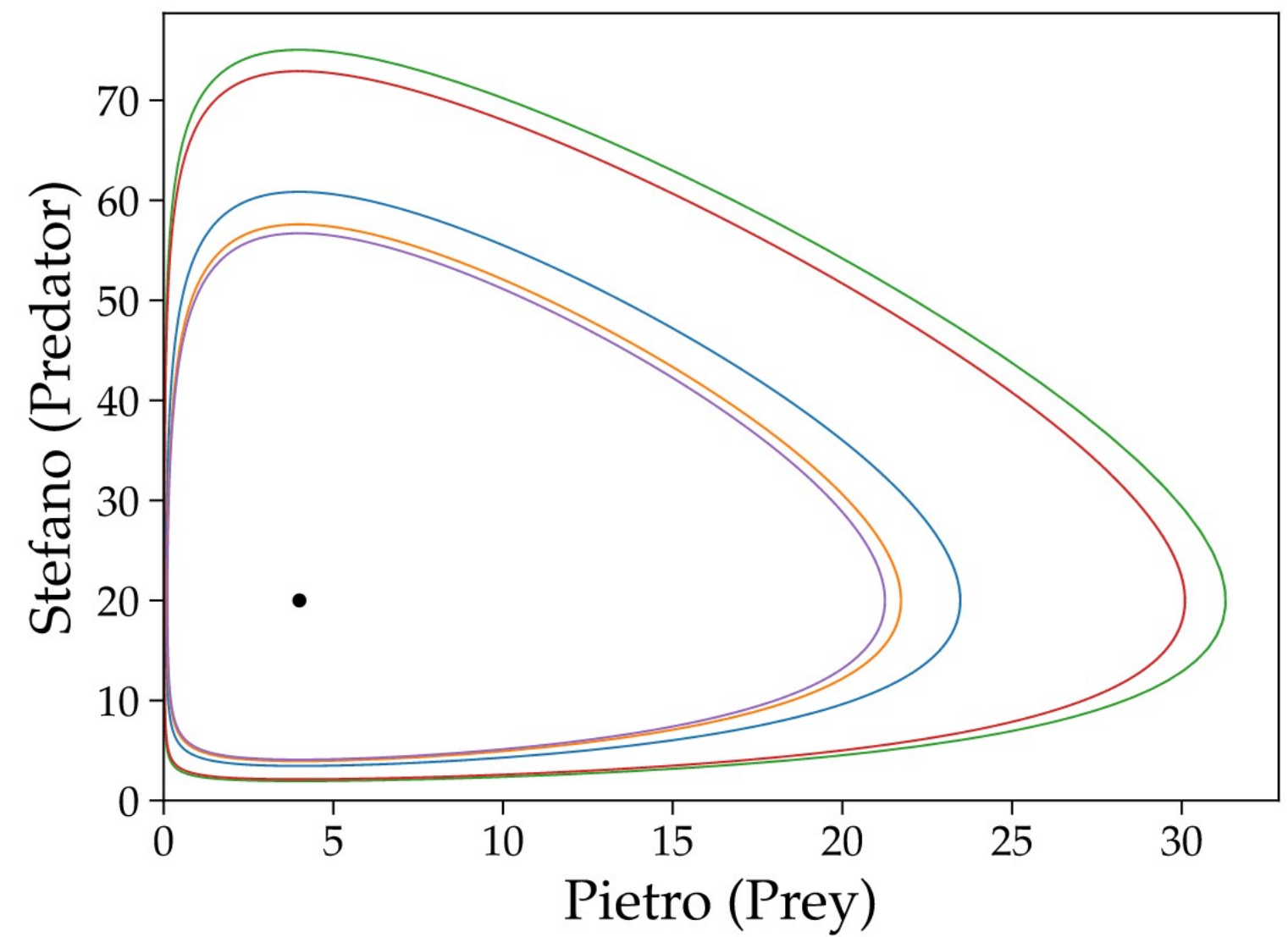
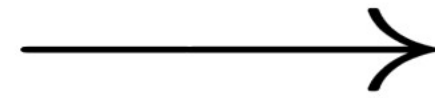
↳ Many strong assumptions and approximations!



Oscillations in the number of preys and predators



Increasing
prey growth
rate A



Generalized Lotka-Volterra Model

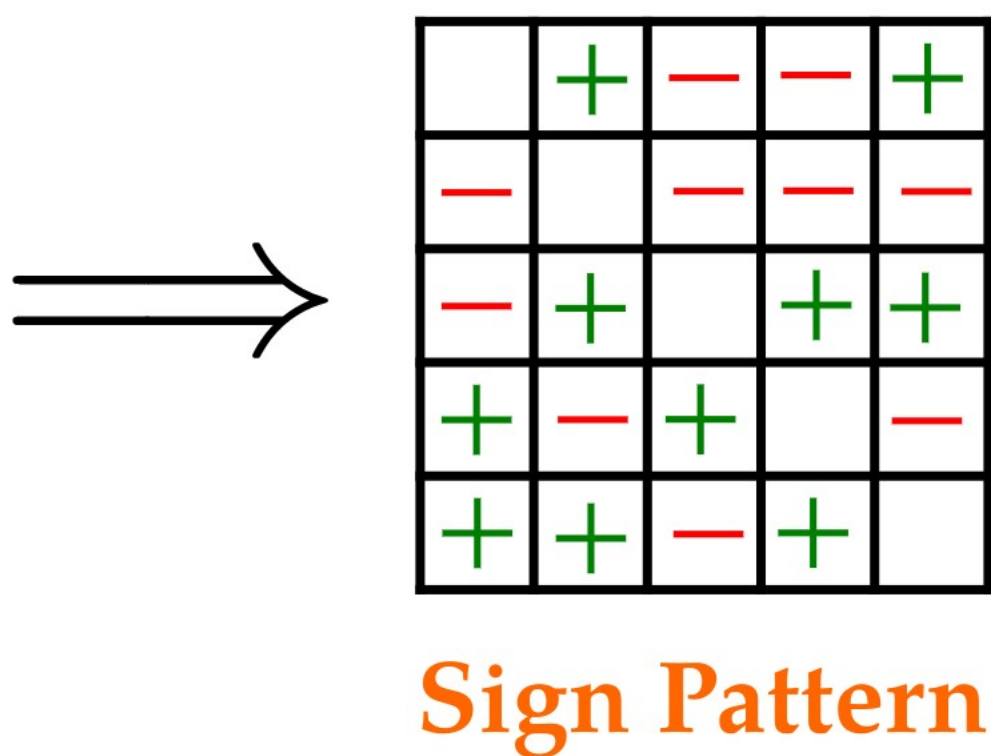
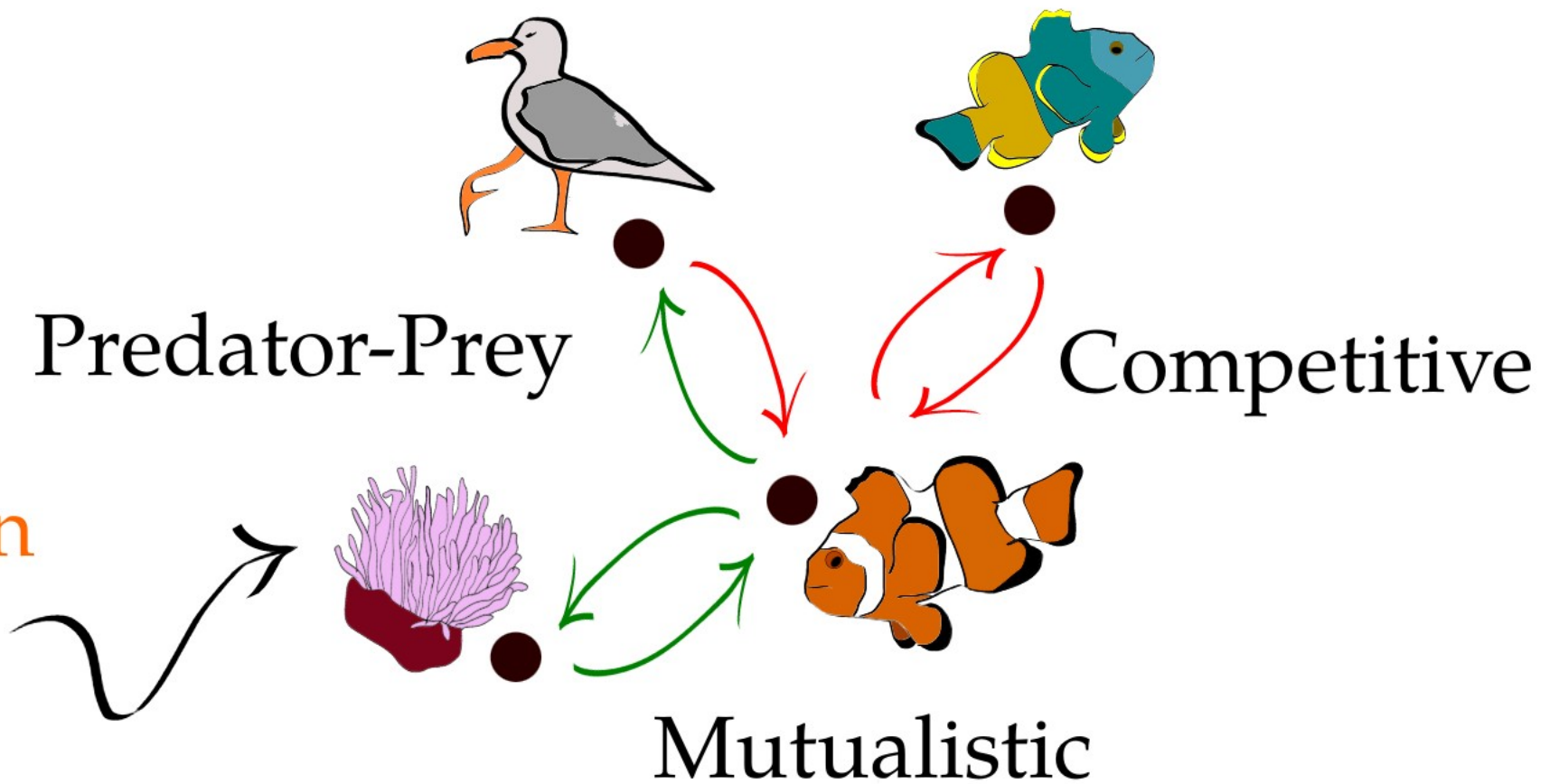
$$\frac{dx_i}{dt} = x_i \left[\left(r_i - \frac{x_i}{K_i} \right) - \sum_{j=1}^N A_{ij} x_j \right]$$

Species' Abundance x_i

Growth Rate r_i

Carrying Capacity K_i

Interaction Matrix A_{ij}

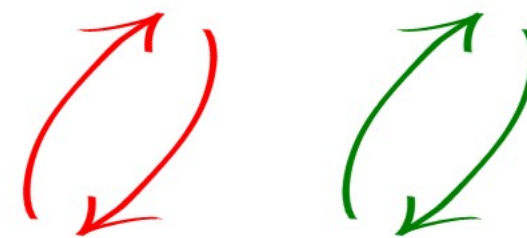


Antagonistic Model



100%

Competitive-Mutualistic Model

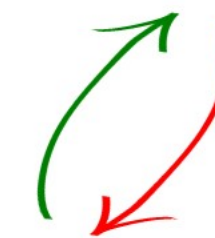


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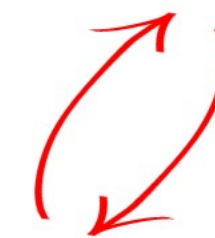


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Mixture Model



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Feasibility: existence of ecologically meaningful equilibrium populations

Surviving
Equilibrium
Population

$$\vec{x}^* = \mathbf{B}^{-1} \vec{r} \longrightarrow$$

$$B_{ij} = \frac{\delta_{ij}}{K_i} + A_{ij}^*$$

Structural stability: sensitivity of equilibrium populations to changes in ecological parameters

$$r_i \longrightarrow r_i + \zeta_i \implies \frac{\partial x_i^*}{\partial \zeta_j} = (\mathbf{B}^{-1})_{ij} \implies \lambda_i(\mathbf{B}) \neq 0 \quad \forall i = 1, \dots, N$$

Linear stability: stability with respect to small perturbations around fixed point population

$$\implies \Re(\lambda_i(\mathbf{J})) < 0 \quad \forall i = 1, \dots, N$$

Jacobian

$$J_{ij}^* = x_i^* B_{ij}$$

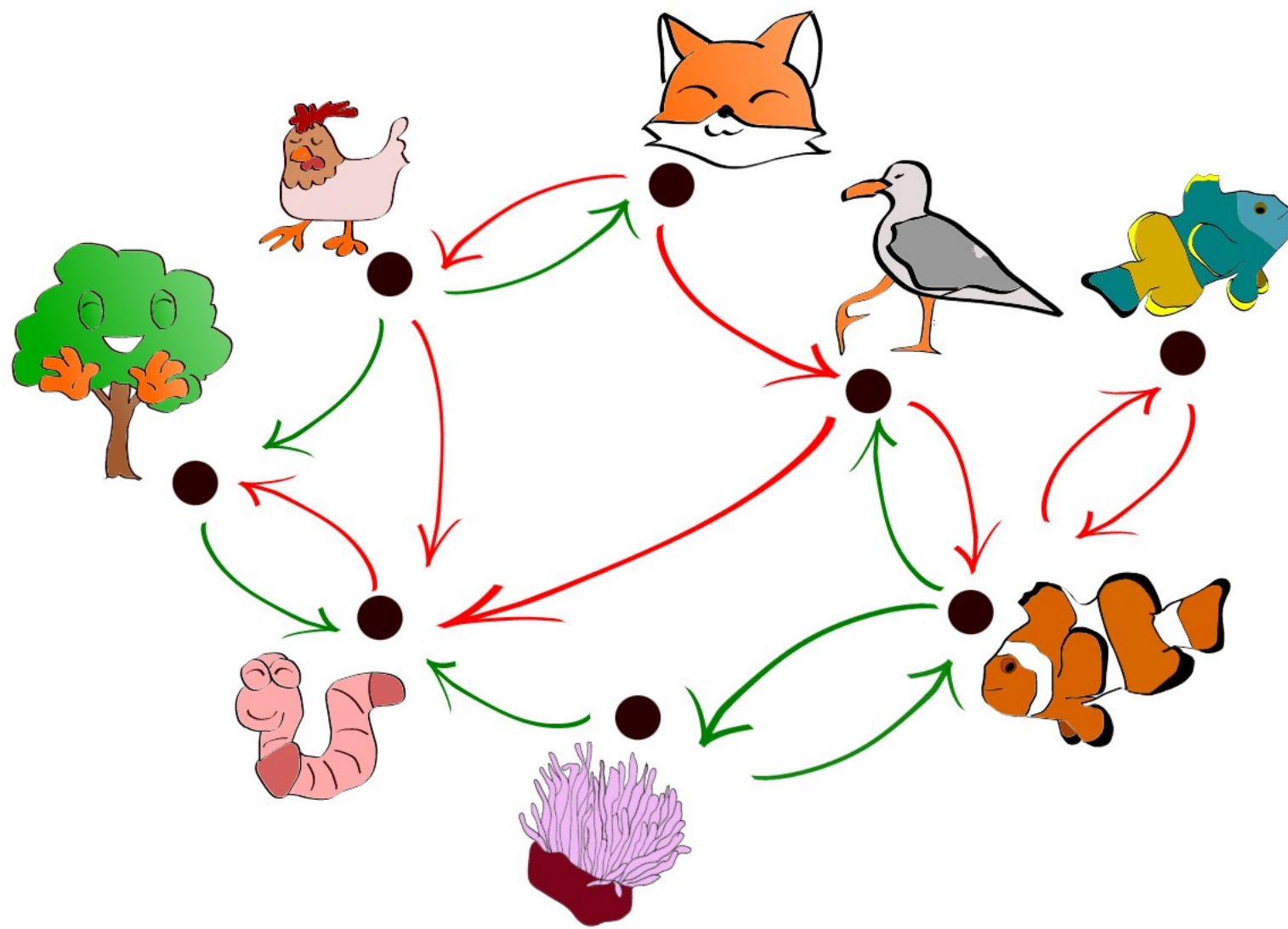
•

11	12	13	14	15
21	22	23	24	25
31	32	33	34	35
41	42	43	44	45
51	52	53	54	55

=

11	12	13	14	15
21	22	23	24	25
31	32	33	34	35
41	42	43	44	45
51	52	53	54	55

Stripy
Structure



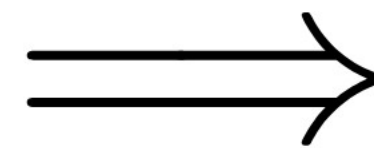
$$\frac{dx_i}{dt} = x_i \left[\left(r_i - \frac{x_i}{K_i} \right) - \sum_{j=1}^N A_{ij} x_j \right]$$

Different types of stability related to **spectral properties** of B and J

$$B_{ij} = \frac{\delta_{ij}}{K_i} + A_{ij}^* \quad , \quad J_{ij} = x_i^* B_{ij}$$

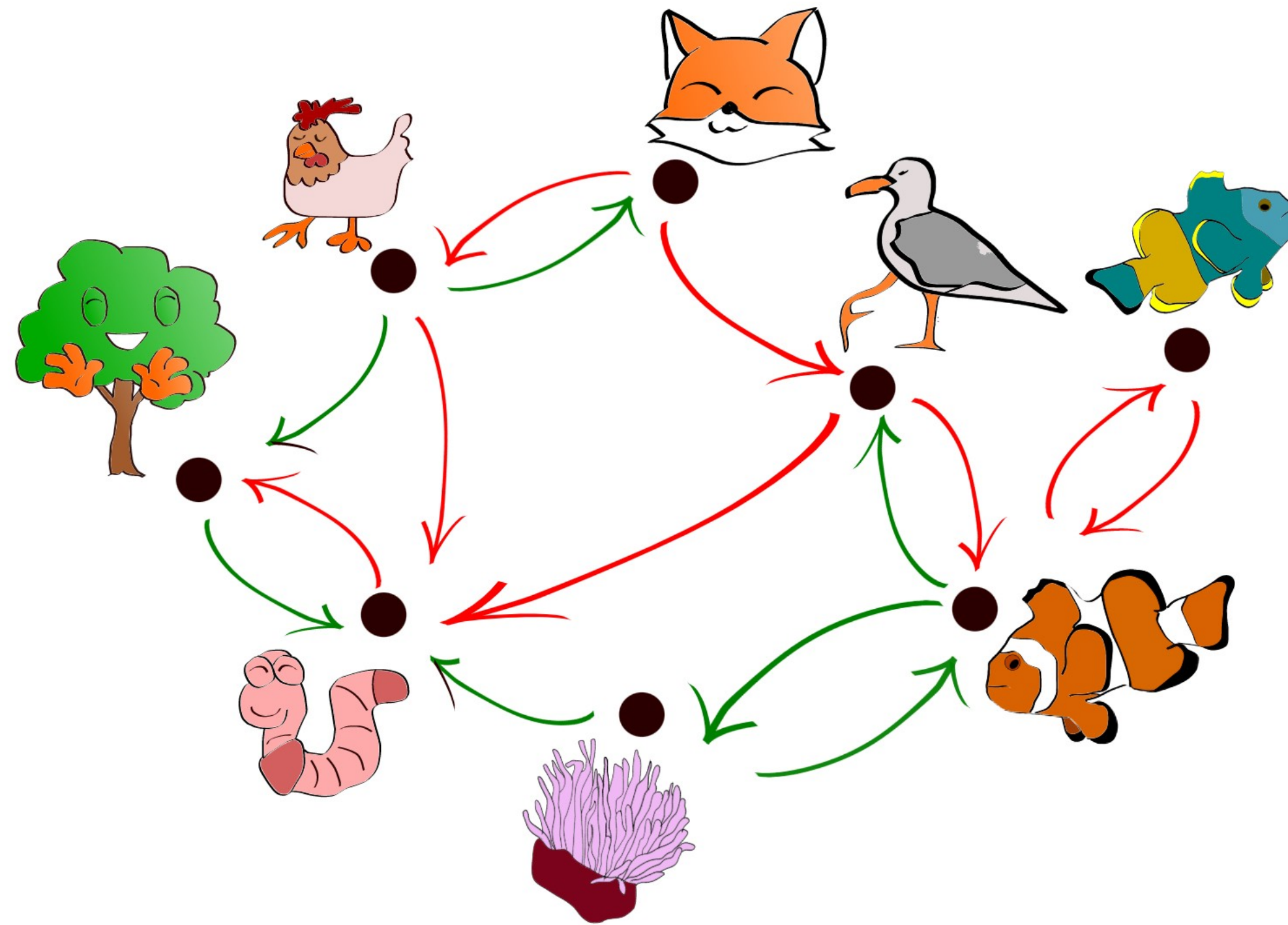
Easy to identify network and kind of interaction
Hard to quantify strength of interactions

+



**Random Matrix
Approach**

We focus on the **macroscopic** behaviour
 we do not expect all the details to matter



Ecology



Classical results on stability

Ecological parameters \longrightarrow **Random variables** [R. M. May, *Nature* (1972)]

\longrightarrow A_{ij} i.i.d. with $\langle A_{ij} \rangle = 0$, $\langle A_{ij}^2 \rangle = \sigma^2$ and $A_{ij} = A_{ji}$ while $K_i = 1$

\implies **Wigner Semicircle Law**

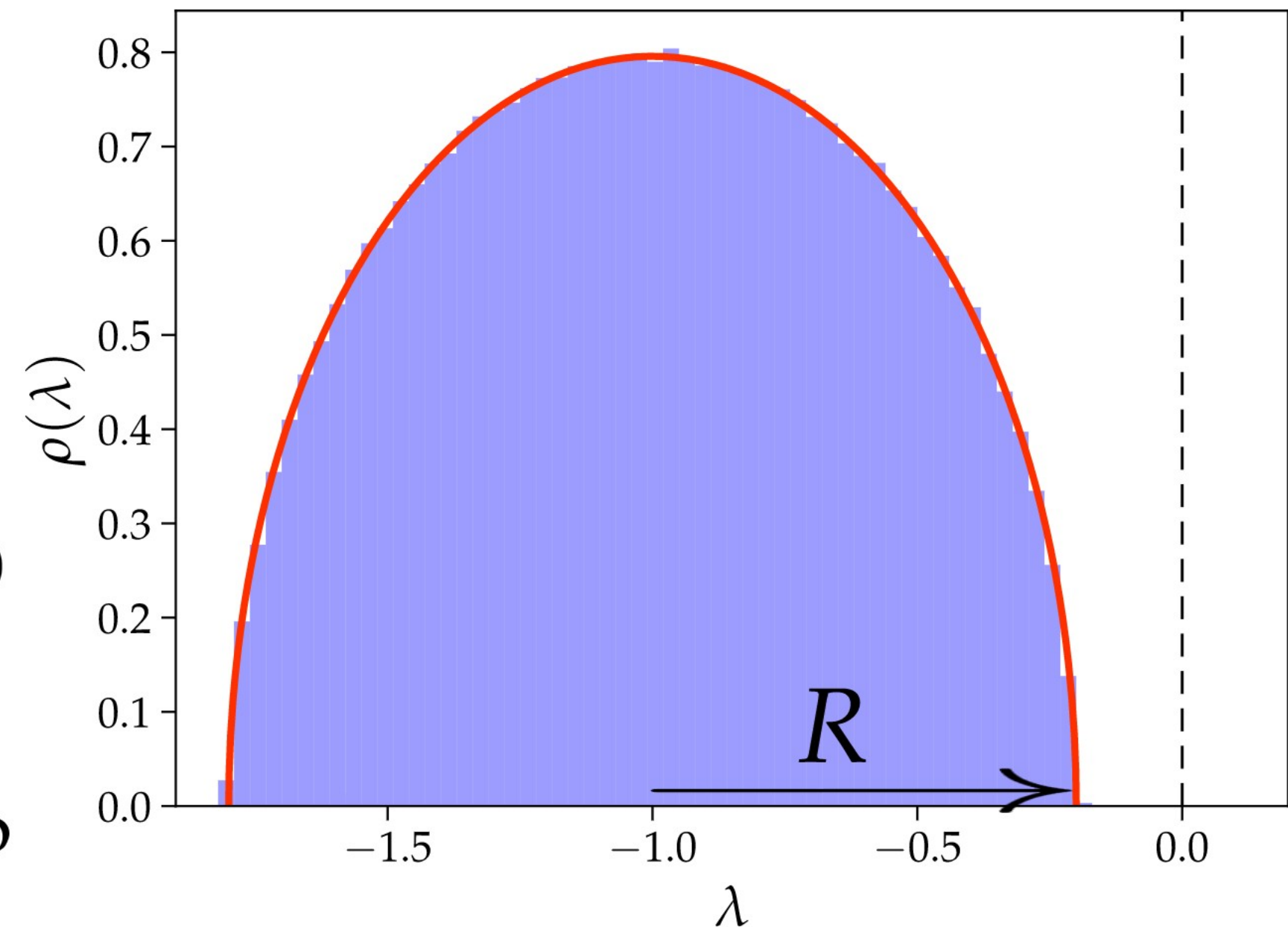
$$R = 2\sigma\sqrt{N}$$

Complexity-Stability trade-off

(**May's Paradox:** Size-dependent Stability)

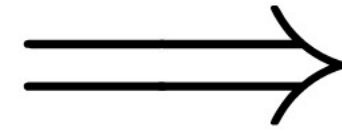
\curvearrowright No complexity–stability relationship
in empirical ecosystems

[C. Jacquet et al., *Nature Communications* (2016)]



Going beyond symmetry ($A_{ij} \neq A_{ji}$)

+



Specifying nature of the **interactions**

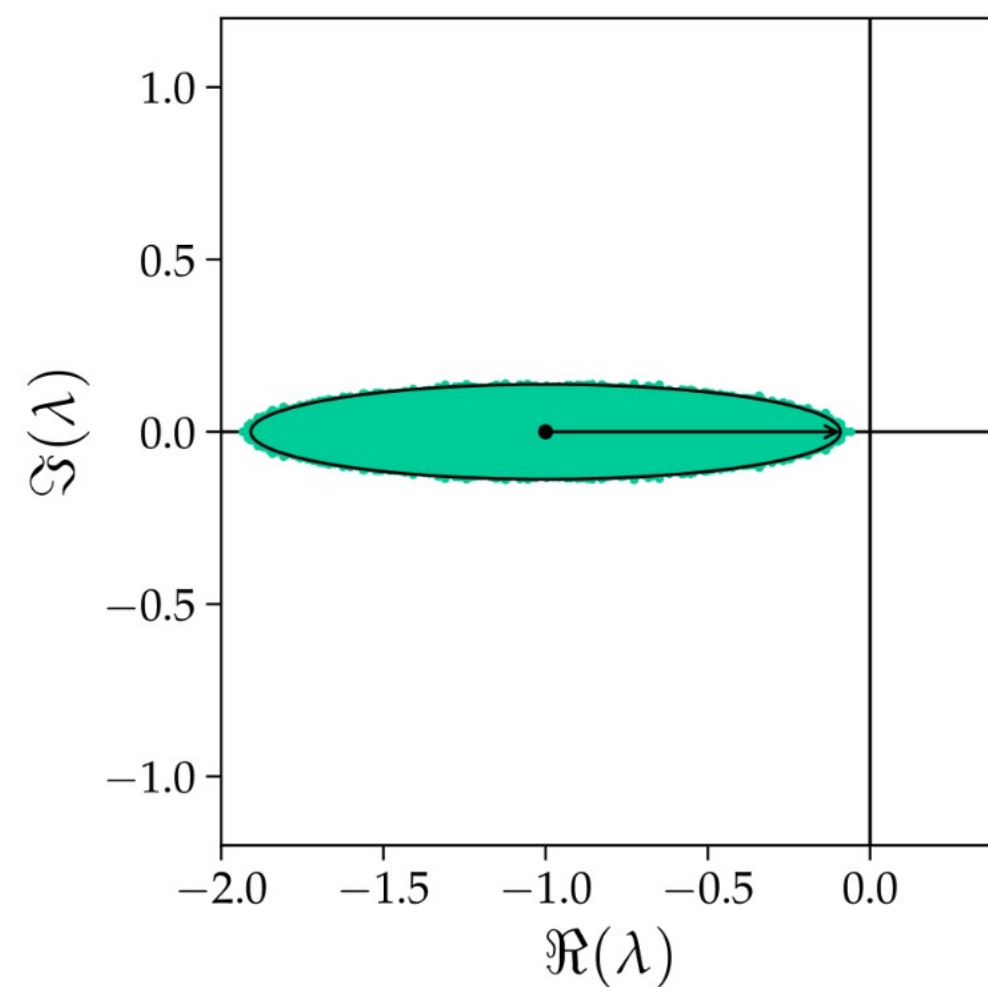
$$\frac{\langle A_{ij}A_{ji} \rangle}{\sigma^2} = \tau$$

Elliptic Law

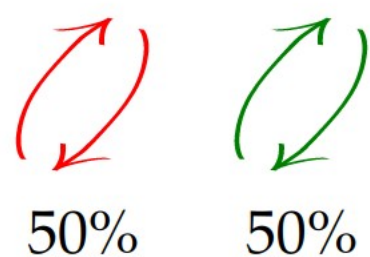
$$R = \sigma(1 + \tau)\sqrt{N}$$

Interactions have **quantitative** effect
Same **qualitative** behaviour

[S. Allesina, S. Tang, *Nature* (2012)]

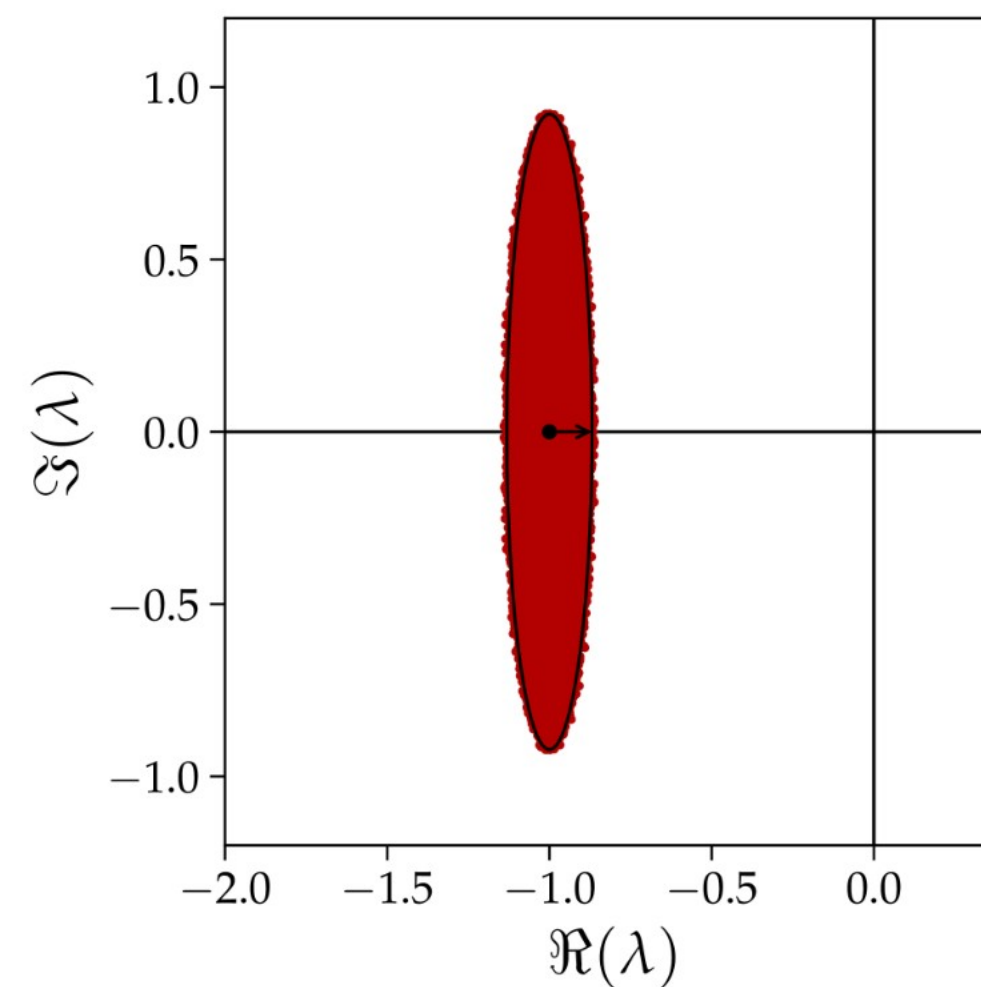


Competitive-Mutualistic



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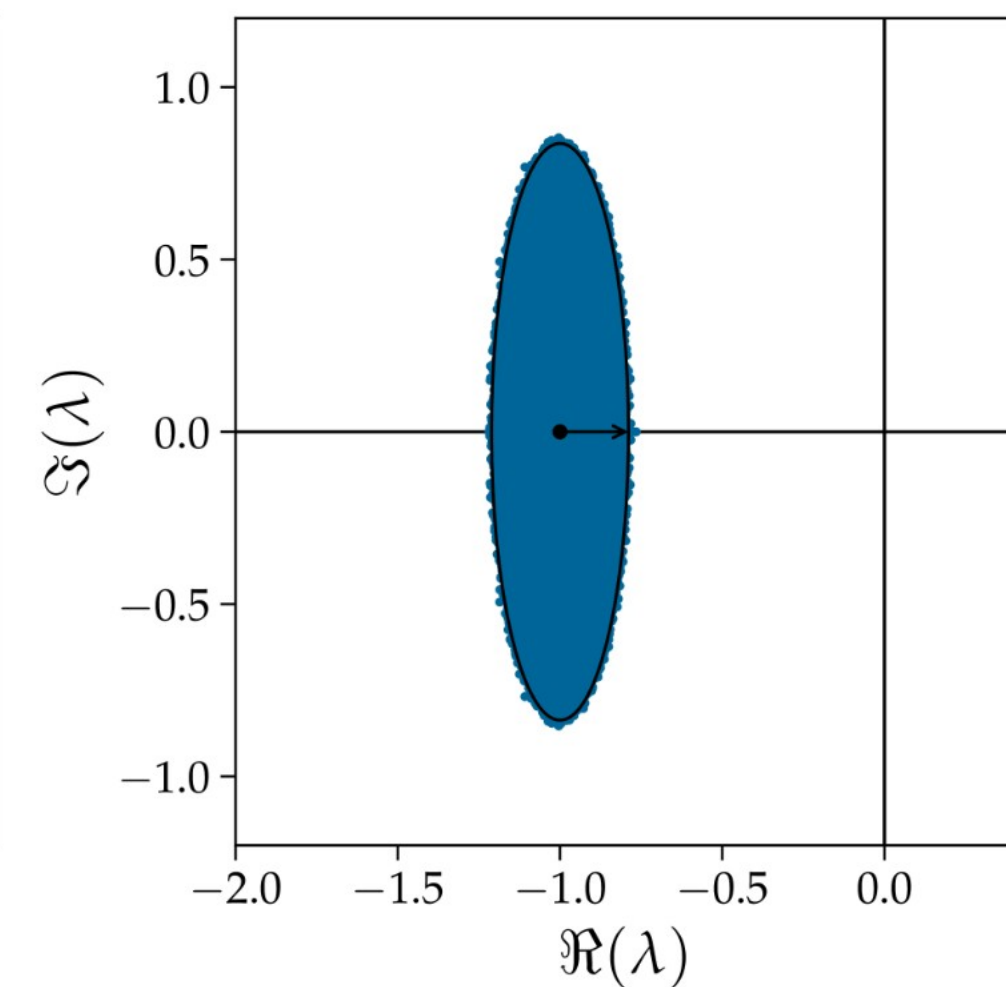
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Antagonistic



100%



Mixture



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Sign Stability

A matrix \mathbf{M} is **sign stable** if any matrix \mathbf{M}' with the same topology and sign pattern is stable, independently from the absolute value of their non-zero elements:

$$\mathbf{M} \text{ is sign stable} \iff \Re(\lambda_i(\mathbf{M}')) < 0 \quad \forall \mathbf{M}' : M'_{ij} = y_{ij}M_{ij}$$

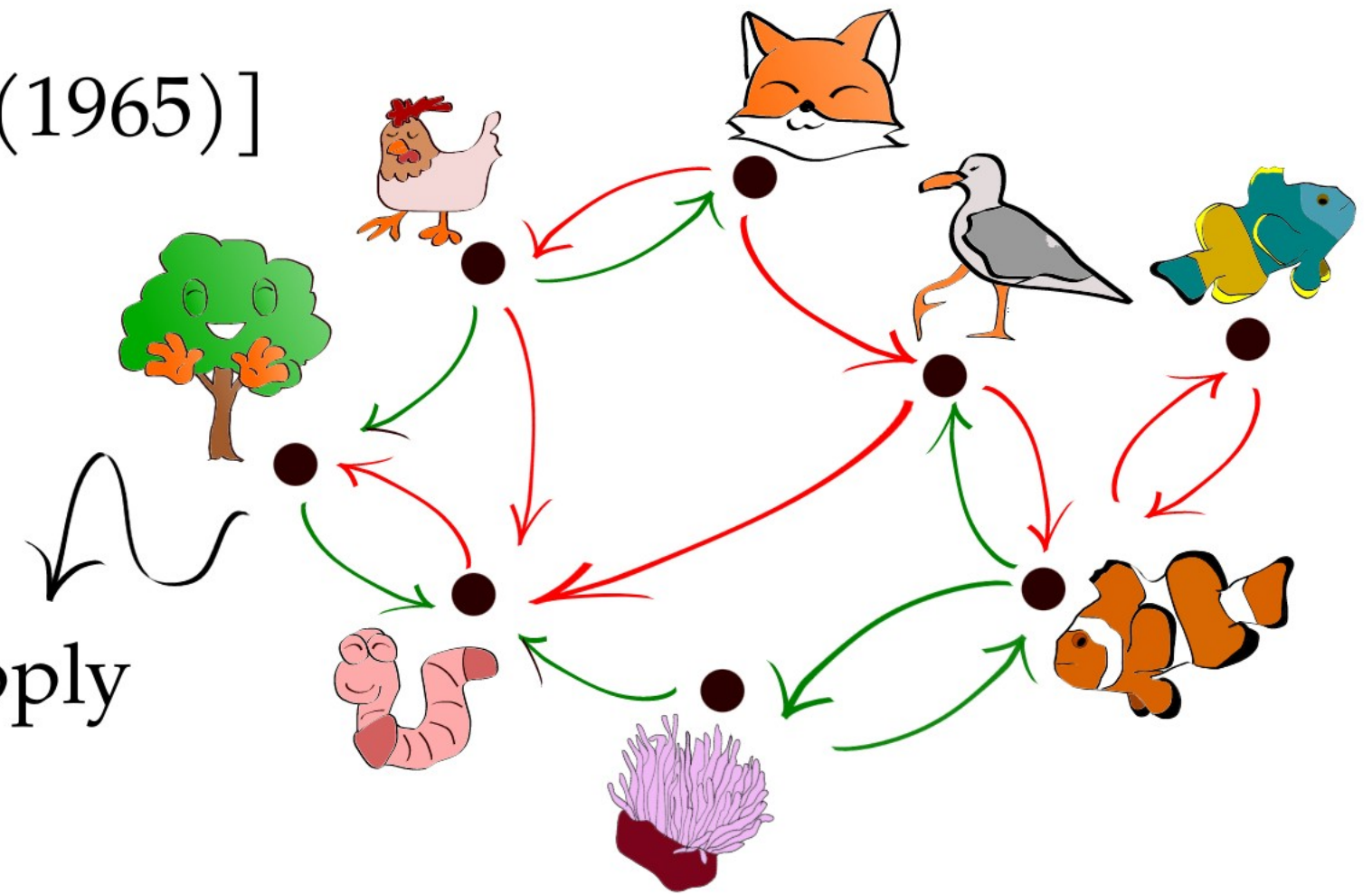
Apply to all matrices in equivalence class:

$$\mathcal{M}(\mathbf{M}) := \left\{ \mathbf{M}' \in \mathbb{R}^{N \times N} : \text{sign}(M'_{ij}) = \text{sign}(M_{ij}) \right\}$$

[J. Quirk, R. Ruppert, *The Review of Economic Studies* (1965)]

\implies Interesting applications in **ecology**:

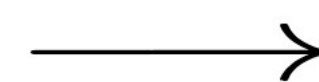
Sign stability can apply
to this cartoon!



Sign stability can appear a too strong condition to be useful.

Conditions (necessary and sufficient) in the case $M_{ii} < 0$:

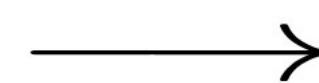
$$1. M_{ij}M_{ji} \leq 0, \quad \forall i \neq j$$



Sign pattern

$$2. M_{i_m i_1} = 0, \quad \forall i_1 \neq i_2 \neq \dots \neq i_m,$$

such that $M_{i_1 i_2} M_{i_2 i_3} \dots M_{i_{m-1} i_m} \neq 0$



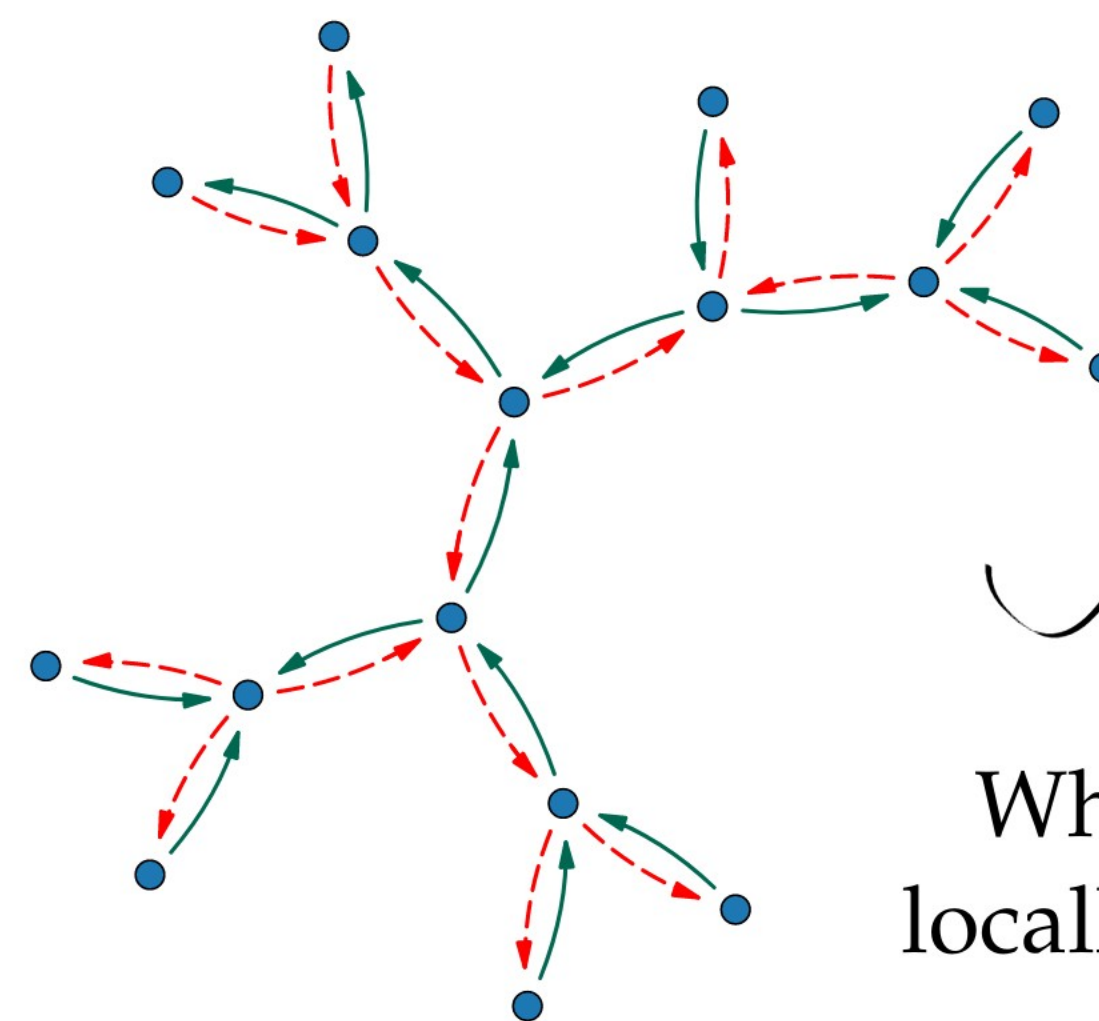
Network
Topology

\implies **Antagonistic trees** are sign stable

Antagonistic trees can be mapped into
antisymmetric trees:

- Imaginary spectrum (no diagonal)
- With negative (disordered) diagonal are stable irrespective of system size

\implies **Absolute Stability**



What about
locally tree-like
graphs?

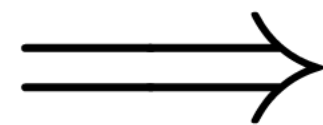
Local Sign Stability

Let's extend this idea to matrices that are only locally sign-stable: a matrix M is **locally sign stable** if its finite neighbourhoods are, almost certainly, sign stable.

Example: **antagonistic** graph which is **locally** like a **tree** (loops are typically long).

Criterion:

\mathbf{M}_N is (strongly)
locally sign stable



$$\lim_{N \rightarrow \infty} \langle \Re[\lambda_1(\mathbf{M}_N)] \rangle < \infty$$

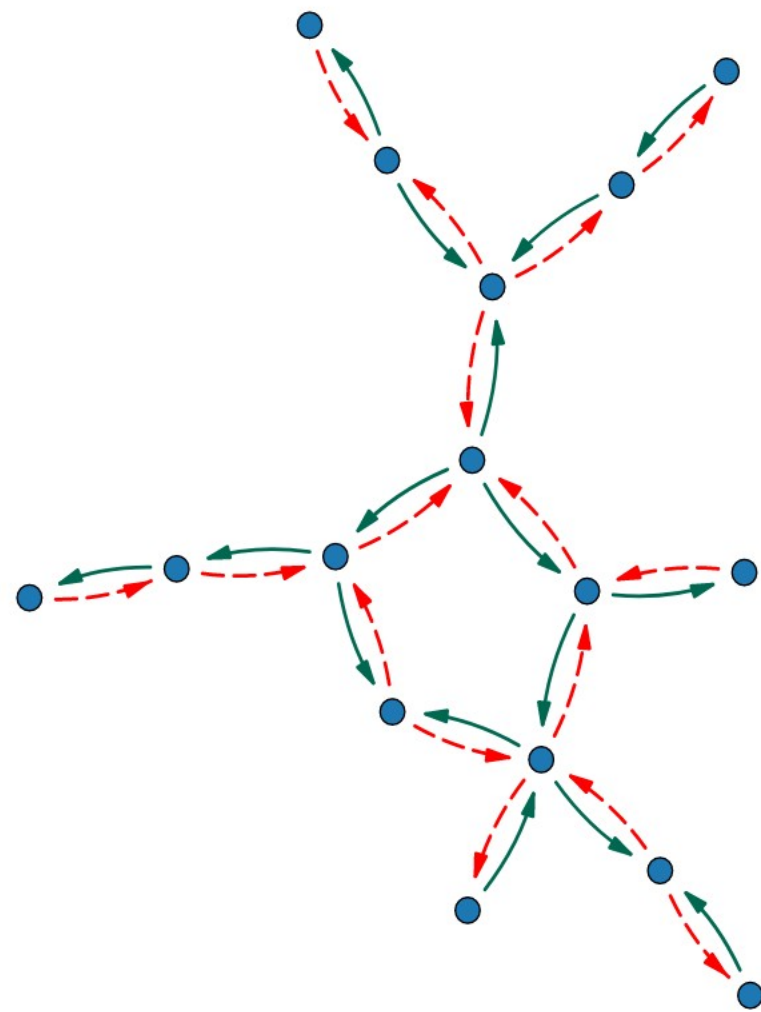
(**Absolute stability**)

[P. Valigi, C. Cammarota, I. Neri, arXiv:2303.09897 (2023)]

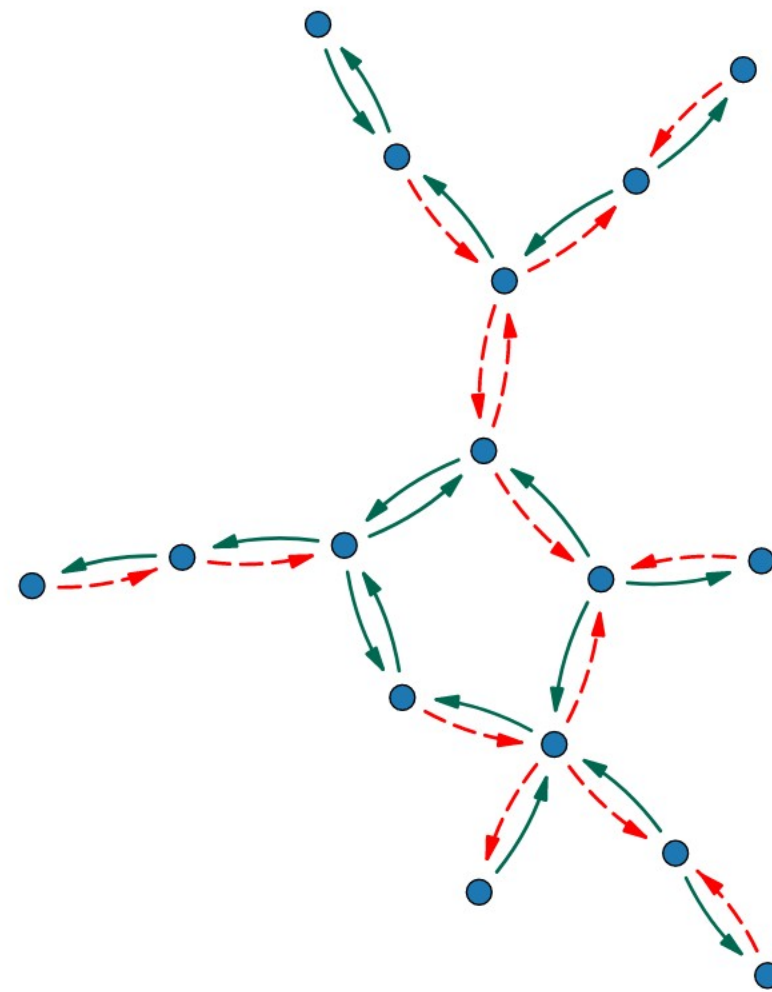
Numerical tests

(Local) sign stability $\left\{ \begin{array}{l} \text{predator-prey interactions} \\ \text{no directed cycles (no feedback loops)} \end{array} \right.$

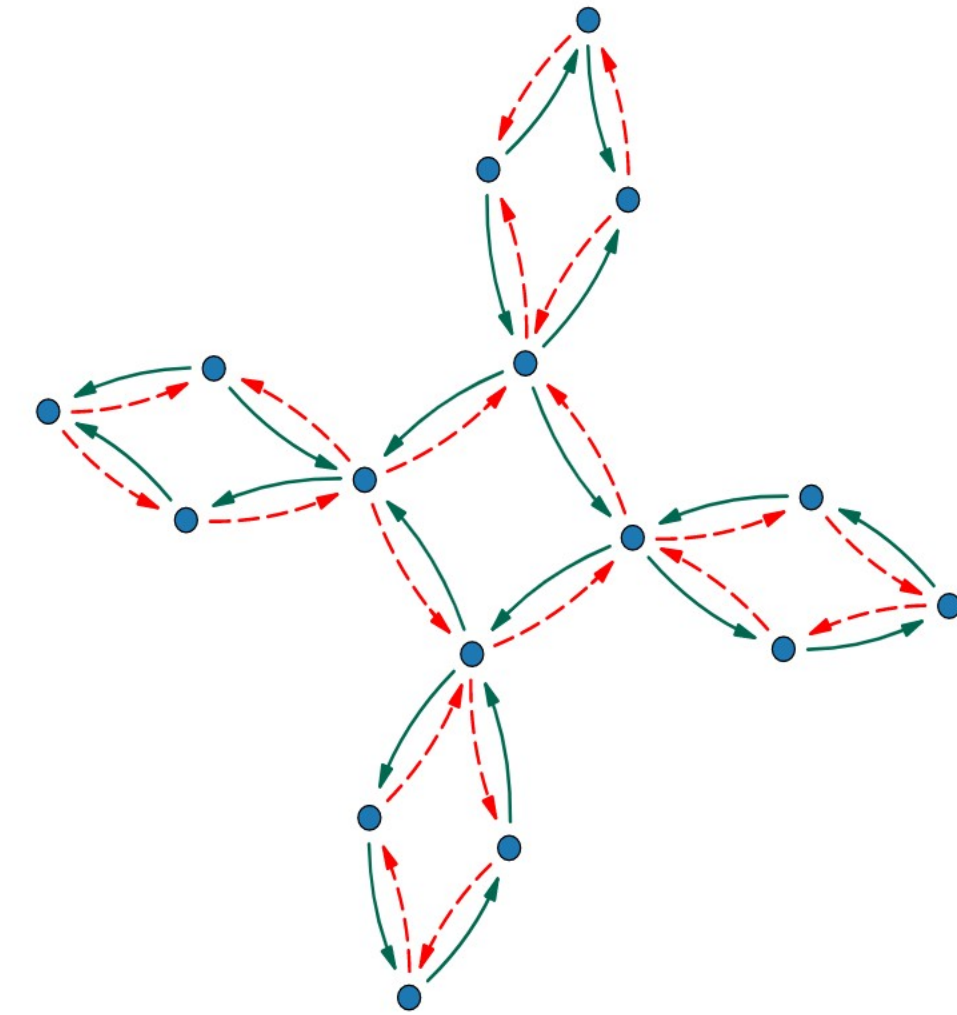
Antagonistic
Erdős-Renyi
(**SLSS**)



Mixture
Erdős-Renyi
(Not LSS)

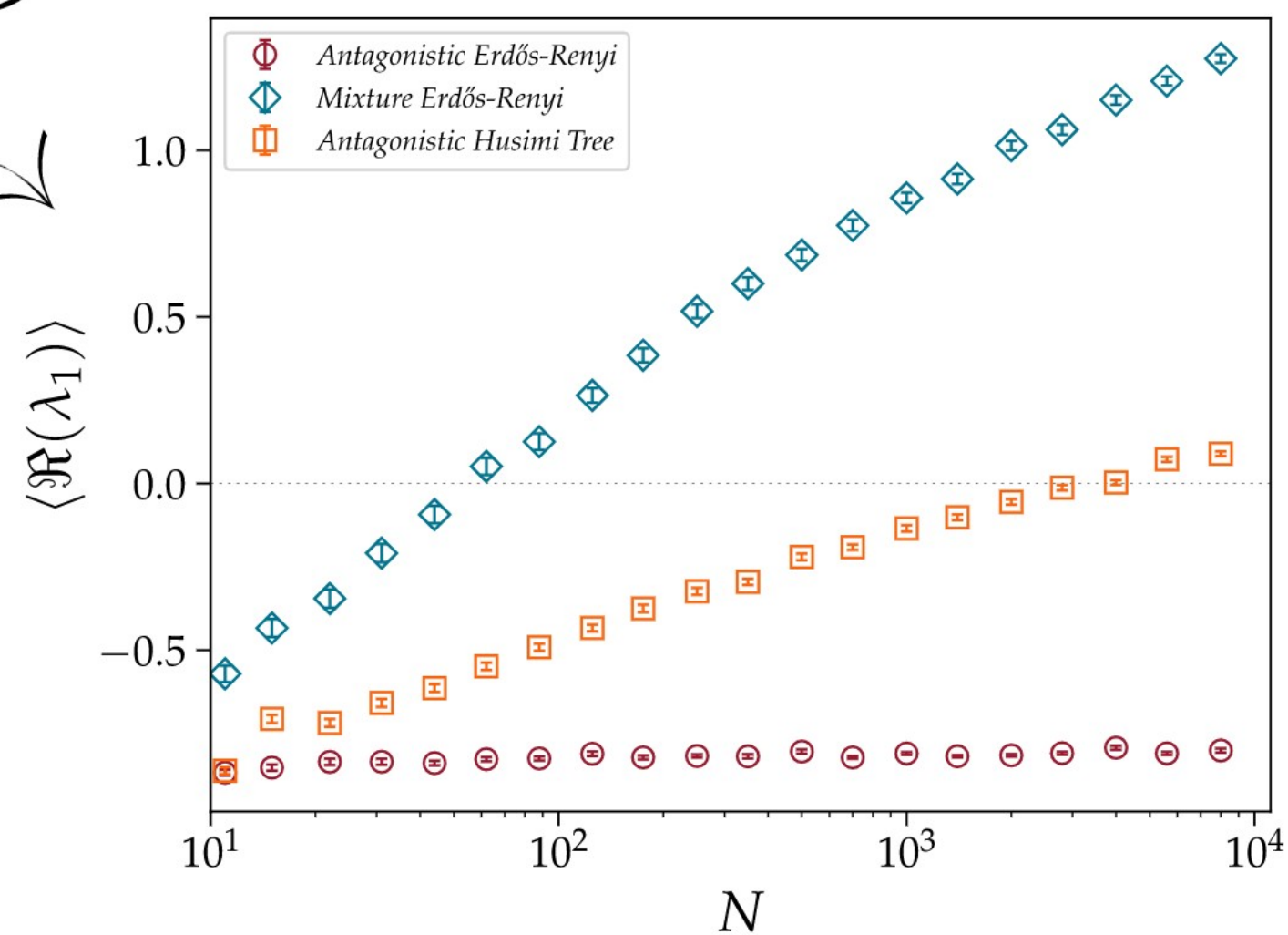
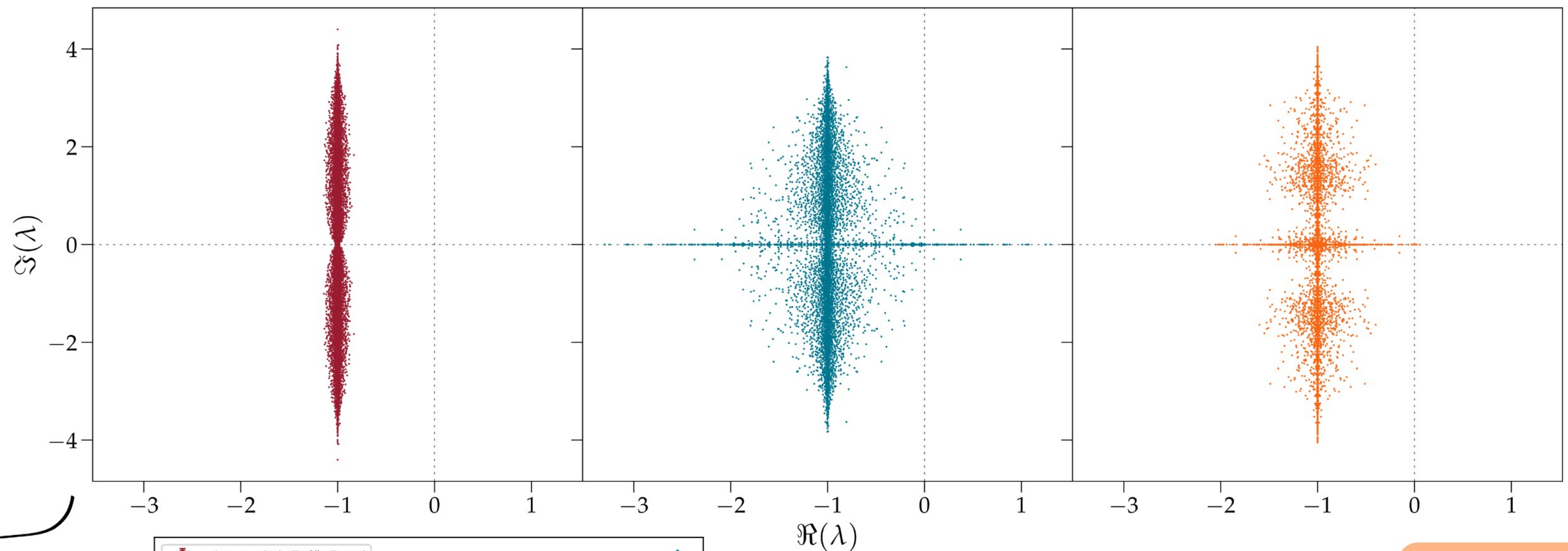


Antagonistic
Husimi Tree
(Not LSS)



We consider 3 **matrix structures** inspired by ecological stability

$\mathbf{B}_{\text{Id}} = \mathbf{A} - \mathbf{1}$ Shifted Interaction-like



SLSS $\implies \lim_{N \rightarrow \infty} \langle \Re[\lambda_1] \rangle < \infty$
absolute stability

Not LSS $\implies \lim_{N \rightarrow \infty} \langle \Re[\lambda_1] \rangle = \infty$
size-dependent stability

**No
Complexity
Stability
trade-off**

Conclusions



- Including nontrivial structure can bring out **qualitatively new** features in spectra of sparse random matrices
- Strong local sign stability enable the **Complexity-Stability trade-off** to be overcome and can be employed in ecosystems models

Take-Home Message

- **Physicists** can (try to) make a contribution to improve our understanding of **ecosystems** behaviour

Thank you!

