Deep inverse problems – a novel approach to MRI image reconstruction







- 1. Background: a short introduction on MRI
- 2. Al-based MR image reconstruction
- 3. DeepMR framework

Versatile imaging technique based on the interaction of nuclear spins within the human body with magnetic fields

- ✓ Excellent soft tissue contrast
- ✓ It is non invasive! (non-ionizing radiation)
- Relatively slow due to the characteristics of MR signal encoding







 $B(r) = B_0 \hat{z} + G(t) \cdot r$ Spatial encoding





Wang, X., Tan, Z., Scholand, N., Roeloffs, V., & Uecker, M. (2021). Physics-based reconstruction methods for magnetic resonance imaging. Philosophical Transactions of the Royal Society A, 379(2200), 20200196

n = noise



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n = noise

Encoding operator Direct inversion Reconstructed

 $\hat{\mathbf{x}} = F^H(\mathbf{y})$ Acquired image data

Encoding operator Direct inversion $\hat{\chi} = F^H(y)$ Reconstructed Acquired image data



Encoding operator Direct inversion $\hat{\chi} = F^H(y)$ Reconstructed Acquired image data











Al-based MR reconstruction

Al-recon classification

Supervised



Both ground-truth and undersampled data are available

Al-recon classification

Supervised



Both ground-truth and undersampled data are available

Self-Supervised





Undersampled data only are available

Al-recon classification

Supervised



Both ground-truth and undersampled data are available

Self-Supervised





Undersampled data only are available

Unsupervised





Neither are available (single subject)

Supervised DL models

Ground truth image is available → can compute loss both in measurement and image space





Cross-domain enhancement

Unrolled optimization

Image restoration



Can rely on rich body of literature on CNN-based denoising (also from nonmedical context) – e.g., U-Net



Aliasing should have noise-like pattern → does not apply well to common undersampling artifact

Kofler et al., (2020)

K-space completion



More closely related to the natural representation of MR data (k-space)

More complicated data preprocessing and overall architecture



Cheng et al., (2018)

Direct mapping



Can capture (and correct) artifacts related to system imperfections

High memory footprint – limited to low dimensional data



Zhu et al., (2018)

Cross-domain enhancement



Improved performances by exploiting highly coupled information between the image and k-space domains

Increased complexity





Eo et al., (2018)

Unrolled optimization



Recursive formulation



Unrolled architecture with end-to-end training



Require less data for training

Involve potentially inefficient conventional image encoding operators

Aggarwal et al., (2018)

Self-/un-supervised DL models

Ground truth image not available → can compute loss both in measurement space only

In the limit case of $N_{train} = 1$, training is performed during reconstruction itself

• Example: PnP reconstruction



PREDATOR project

Aim 1:

- Development of an open-source framework for development of advanced qMR reconstruction
- Acquisition of high-quality data for Deep Learning based qMR reconstruction

Aim 2:

 Application to real-world MR acquisition (healthy + patients), either retrospectively on previously acquired data (MR Fingerprinting) and prospectively (QSM)

Aim 3:

- Implement on-line reconstruction on MR scanner
- Measure scalability of the algorithms on low-end hardware (consumer-level PCs, single-board computers) for low-income countries



O PyTorch Zenodo



$|/\bigcirc$

- Raw data loading
- Dicom Export

Linear Operators

- FFT
- NUFF
- Wavelet Transform
- ...

Regularization Operators

- L1 Wavelet
- Total Variation
- Local Low Rank
- PnP denoisers

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Solvers

- Gradient Method
- Conjugate Gradient
- ADMM

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Parametric-mapping

- Pytorch-based EPG simulator (T1, T2, MT, chemical exchange, slice profile...)
- NN-based inference

NN-utils

- Pre-defined architectures
- Utils as data-loaders, schedulers...



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Pytorch implementation based on Extended Phase Graphs formalism

- Effect of RF pulse and spin relaxation is represented by matrix-matrix product operations
- Effect of gradient is represented in the Fourier space as a shift between different (discrete) states representing different dephasing orders

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- Effect of gradient is represented in the fourier space as a shift between different (discrete) states representing different dephasing orders

Features:

- Include all main MR related parameters (relaxation, diffusion, chemical exchange, magnetization transfer, system imperfections)
- Highly parallelized (both on CPU and GPU)
- Supports gradient calculation via forward automatic differentiation (enable backpropagation in NN training, efficient parameter fitting and optimization of acquisition parameters)

Validation:

- Acquisition: Variable Flip Angle unbalanced SSFP with 1000 echoes (TR=8.5ms)
- Virtual Object: Three representative tissues:
 - White Matter (T1=500ms; T2=70ms)
 - Gray Matter(T1=833ms; T2=83ms)
 - CSF (T1=2569ms; T2=329ms)

Benchmark: comparison of computations time against *sycomore* (state-of-the-art C++ implementation) on a batch of tissue species of size 65536

Sequence scheme





No differences compared to the reference implementation

- : reference implementation
- : deepmr implementation



P: sampling operatorF: Fourier TransformM: Bloch response

PF: Non-Uniform Sparse FFT

y = PFM(x) + n

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M is often replaced with a projection on a linear subspace for speedup

→ jointly perform P, F and M!

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Implementation: Pytorch + Numba

- Can operate both on CPU and GPU
- Efficient backpropagation noticing that, for linear operators, backward pass is equivalent to adjoint operator

Validation:

- Acquisition: Fast Spin-Echo with 1000 echoes and goldenangle incremented 2D radial sampling (100 spokes / echo)
- Virtual Object: Shepp-Logan phantom with three regions:
 - White Matter (T2=70ms)
 - Gray Matter(T2=83ms)
 - CSF (T2=329ms)
- Basis determination: SVD of an ensemble of 300 signal evolution (T2:1 329ms)
- K-Space data: calculated via forward NUFFT from *torchkbnufft*

Benchmark: comparison of both forward and adjoint NUFFT computations time against *torchkbnufft* implementation

Signal equation Trajectory K-Space trajector $S(TE) = \exp(-\frac{TE}{T2})$ -100 -75 -50 -25 25 kx [a.u.] **Basis** determination SVD Signal ensemble Low-rank subspace basis 1.0 -0.20 signal magnitude [a.u.] signal magnitude [a.u.] 200 400 600 # frames # frames



No differences compared to the reference implementation



One order of magnitude of speed-up compared to the reference implementation

qMR database creation

qMR database creation

M2. Creation of training qMRI database of healthy volunteers (31 Dec 2023): Generation of sub-millimetric TI, T2, T2*/susceptibility maps of at least 10 subjects.

Protocol

Sequence Type	Parameter	FA [deg]	RF phase inc [deg]	TE [ms]	TR [ms]	FoV [mm]	Resolution [mm]	Acceleratio n factor	Scan Time [min:sec]
SPGR	T1	3, 11, 28	quadratic	3.3	8.5	224x224x160	0.8 iso	4	9:06
bSSFP	Т2	10, 20, 30, 35	0, 180	2	4	224x224x160	0.8 iso	4	6:00
ME-GRE	T2*, B0, QSM	15	quadratic	3.9, 8.5, 13.1, 17.7	30	224x224x160	0.8 iso	4	5:06

Protocol also include a B1+ calibration scan (Bloch-Siegert) (whole-brain, 4x4x5 mm³ resolution)

Dataset

• 1 healthy volunteer (Male, 34 years old)

qMR database creation

M2. Creation of training qMRI database of healthy volunteers (31 Dec 2023): Generation of sub-millimetric TI, T2, T2*/susceptibility maps of at least 10 subjects.





• Al-based approaches have great potential in accelerating MR acquisition and reconstruction

• The DeepMR framework will contribute to the field providing easy-to-use, extensible and efficient tools to develop novel reconstruction approaches





Thank you for your attention!



