

Status of SAND Simulations

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DUNE ITALIA

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Content

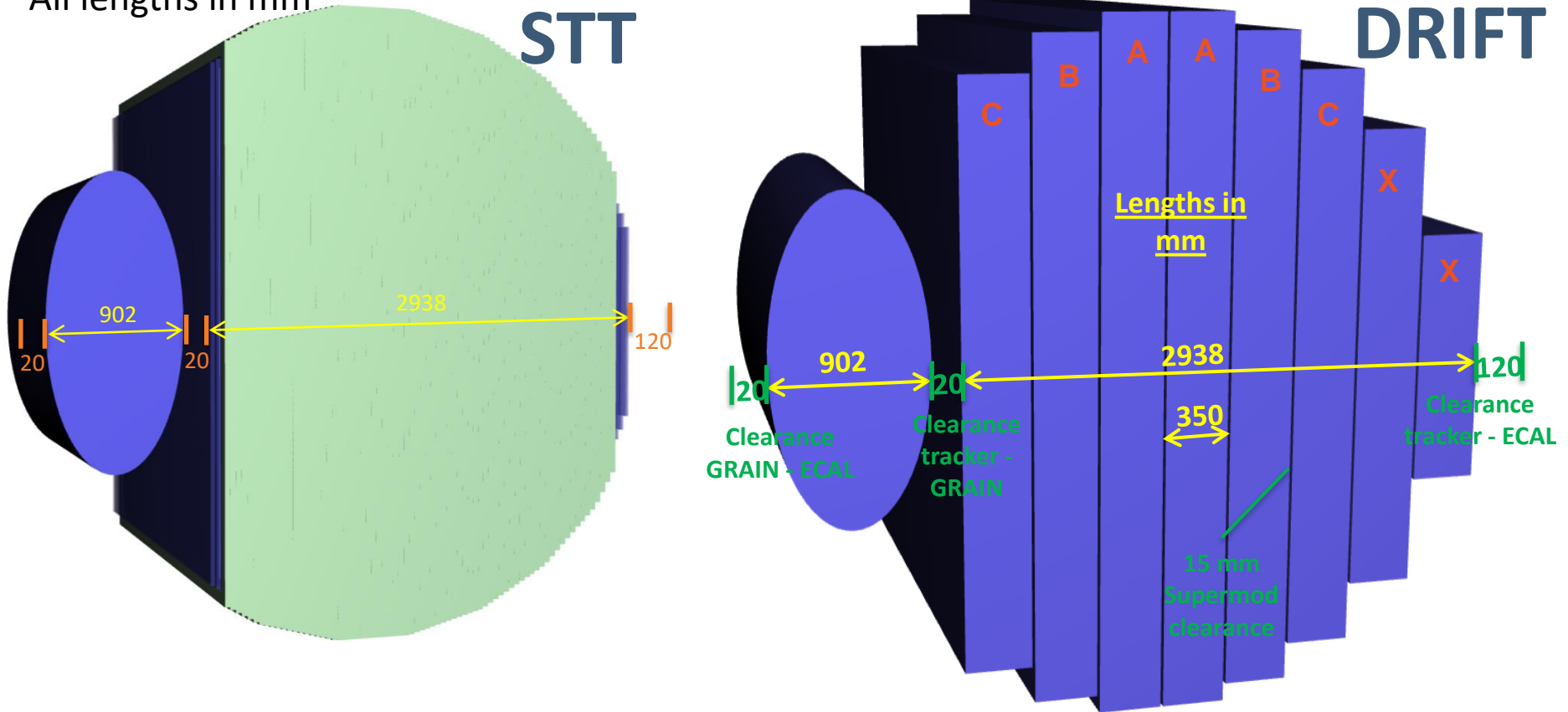
- Status of Simulated Geometry
 - STT tracker
 - Drift Chamber
- Digitization
- Reconstruction
 - Track fit
 - Kalman Filter
- Future Prospects

Updates on SAND Geometry

- **GRAIN dimensions** have been updated following the foreseen prototype
- Latest simulation accounts for engineering requirements about **clearances** between GRAIN, STT and ECAL
- Basic STT design left untouched, with fewer modules
- Additional SAND geometry based on **drift chamber**
- Repo : <https://github.com/DUNE/dunendggd.git>
- Generate: `./build_hall.sh sand_opt3_STT1`

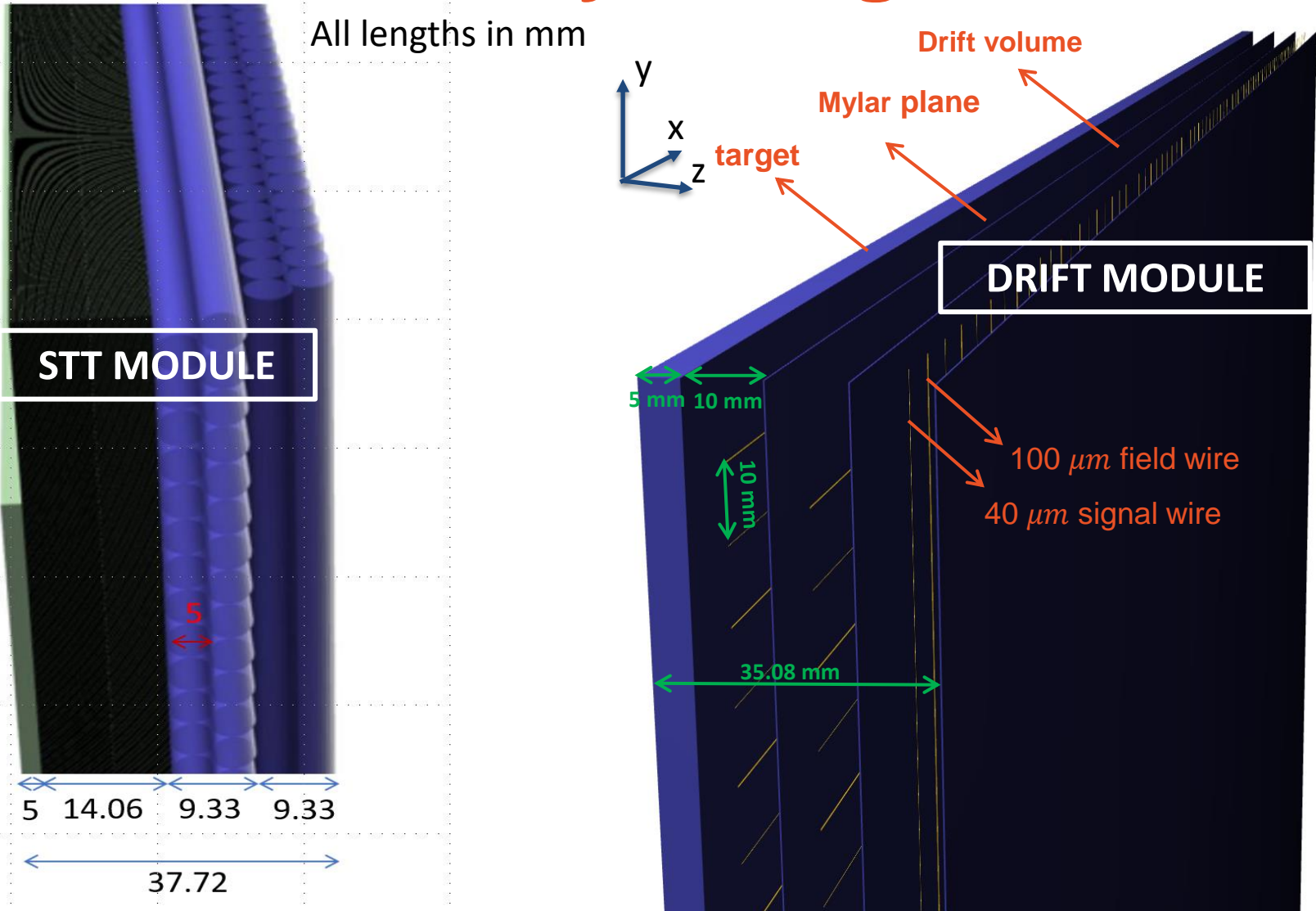
SAND Geometry

All lengths in mm



	# C3H6	# C	Mass C3H6	Mass C	Mass Radiator	Mass Mylar	gas	density [g/cm ²]	L0 [m]
STT *	65	8	3.1 t	0.7 t	1.3 t	-	0.1 t	0.17	2.7
DRIFT	72	8	3.4 t	0.7 t	-	0.1 t	0.1 t	0.15	3.0

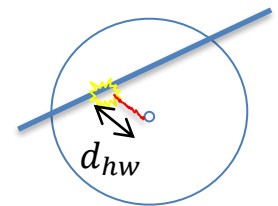
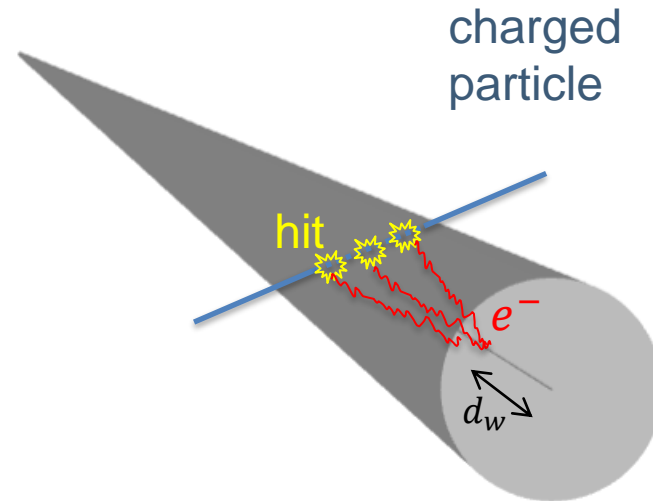
SAND Geometry – single module



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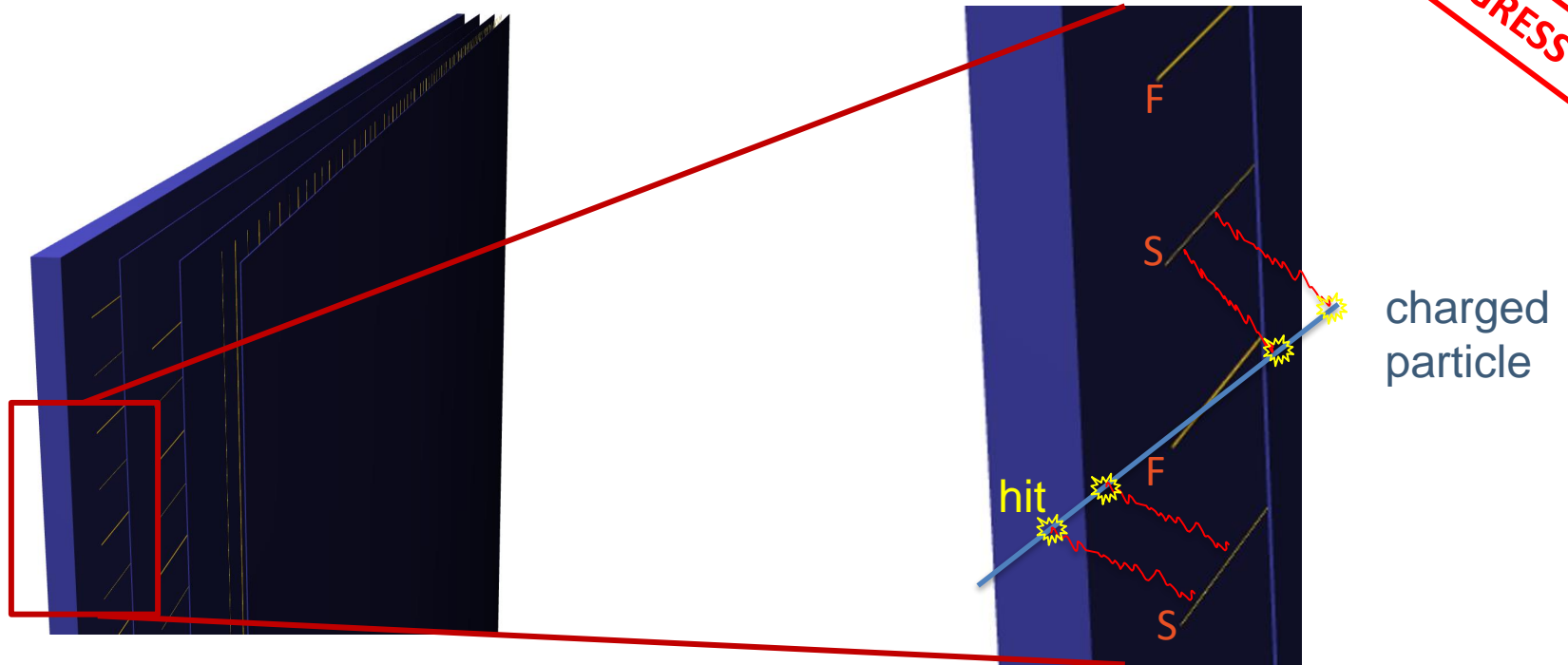
Digitization – Straw Tube



- $ADC = \sum_{hits} E_{hit}$ ← Hit energy deposit (MC truth)
- $TDC = t_{hit} + d_{hw}/v_{drift} + d_w/v_{signal} + Gauss(1\ ns)$
 Hit time (MC truth) e^- drift velocity Signal propagation velocity along the wire

Digitization – Drift Module

WORK IN PROGRESS



- $ADC = \sum_{hits} E_{hit}$ ← Hit energy deposit (MC truth)
- $TDC = t_{hit} + d_{hw}/v_{drift} + d_w/v_{signal} + Gauss(1\text{ ns})$
 - ← Hit time (MC truth)
 - ← e^- drift velocity
 - ← Signal propagation velocity

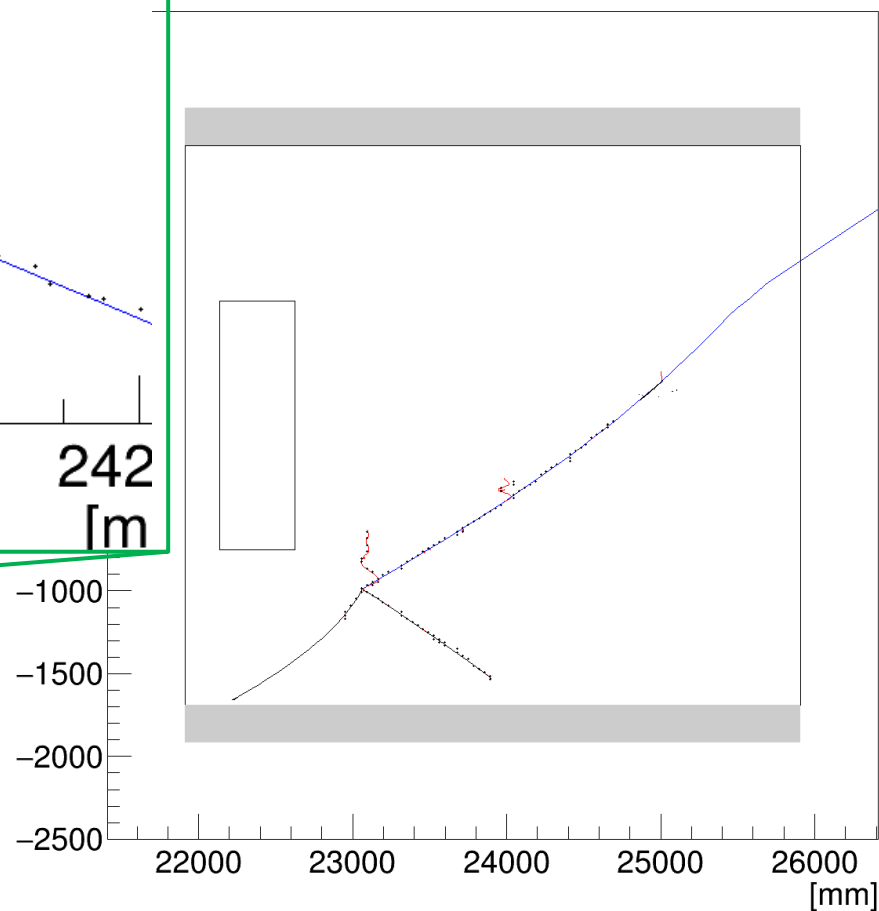
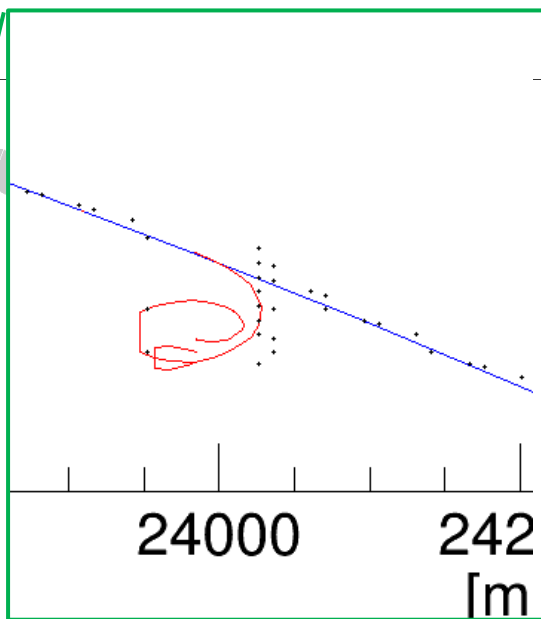
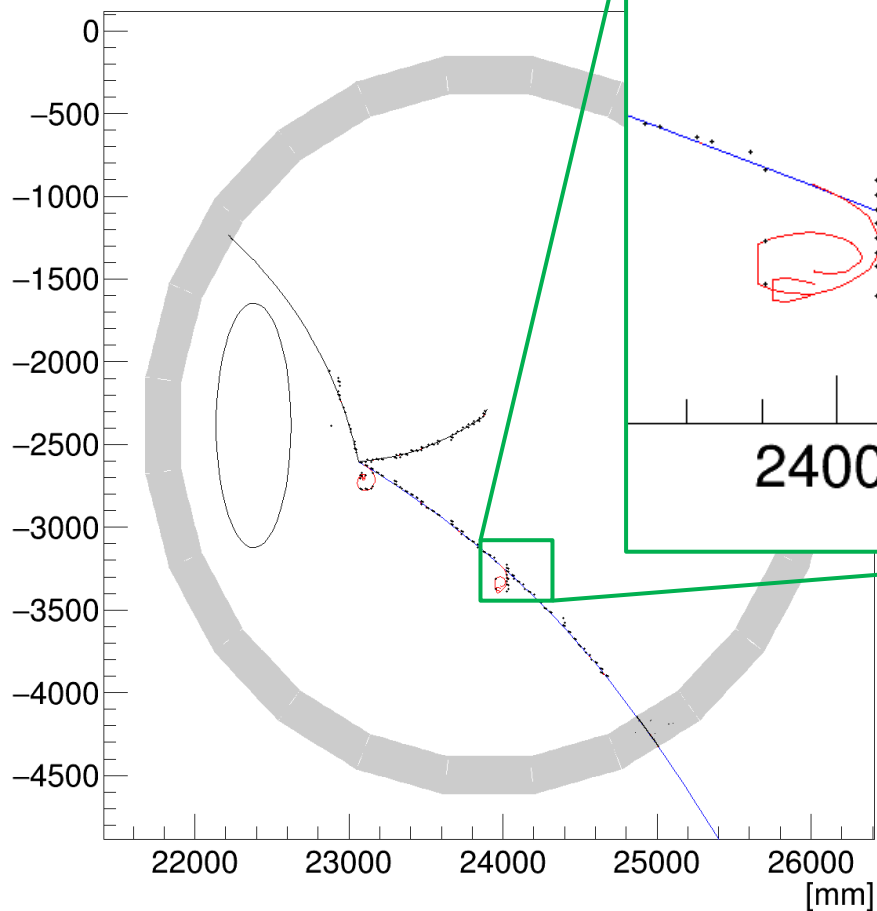
Digitization – Drift

WORK IN PROGRESS

MC tracks VS fired wires position

ZY (side)

XZ (top)

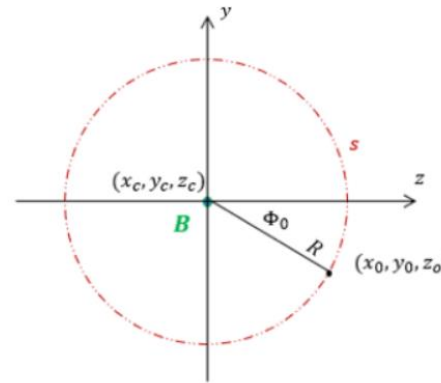
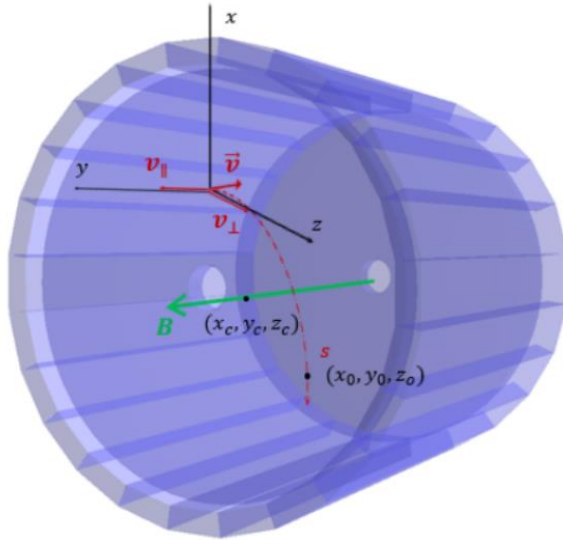


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Track Reconstruction

ECAL, GRAIN see dedicated talks



- **Input:** STT hits position
- Assume helicoidal motion
- Circular fit on y-z plane → R curvature
- Linear fit on x-z plane → λ dip angle
- **Output:** reconstructed particle momentum

$$\begin{cases} p_x = p_T \tan \lambda \\ p_y = p_T \sin(\pi/2 - \Phi_0) \\ p_z = p_T \cos(\pi/2 - \Phi_0) \end{cases}$$

$$p_T [MeV/c] = 0.3 \times B [T] R [m]$$

Track Reconstruction

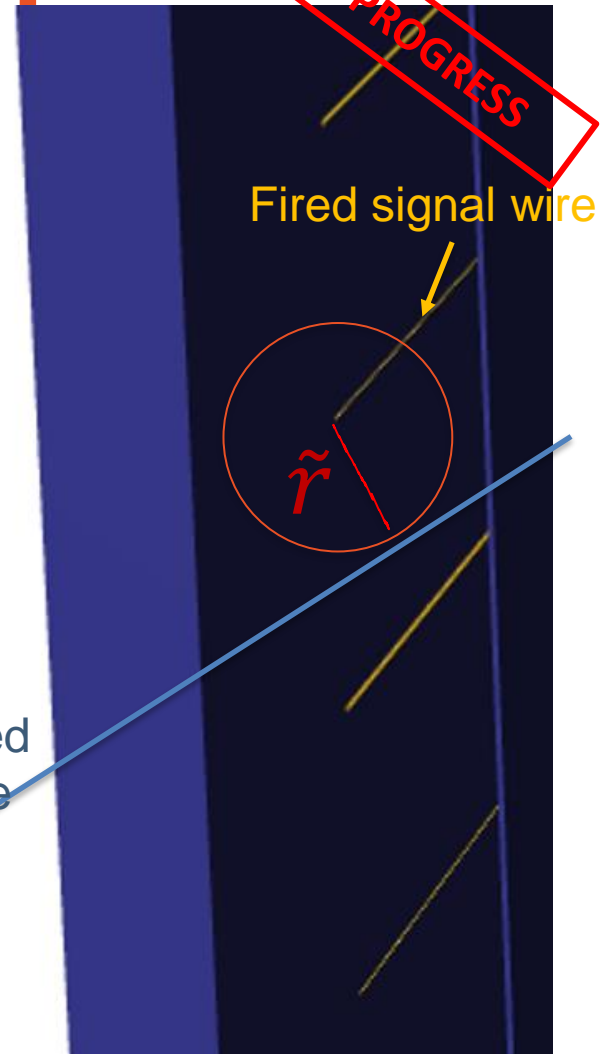
- Assuming charged particles moves along a helix, the **impact parameter** is the minimum distance between the helix and the fired wire
- \tilde{r}_i expected impact parameter provided by i^{th} wire TDC
- r_i inferred impact parameter from NLL method:

$$NLL = \sum_i \frac{(r_i - \tilde{r}_i)^2}{\sigma_r^2}$$

i runs over the fired wires

Expected space resolution for single hit $200 \mu m$

charged particle



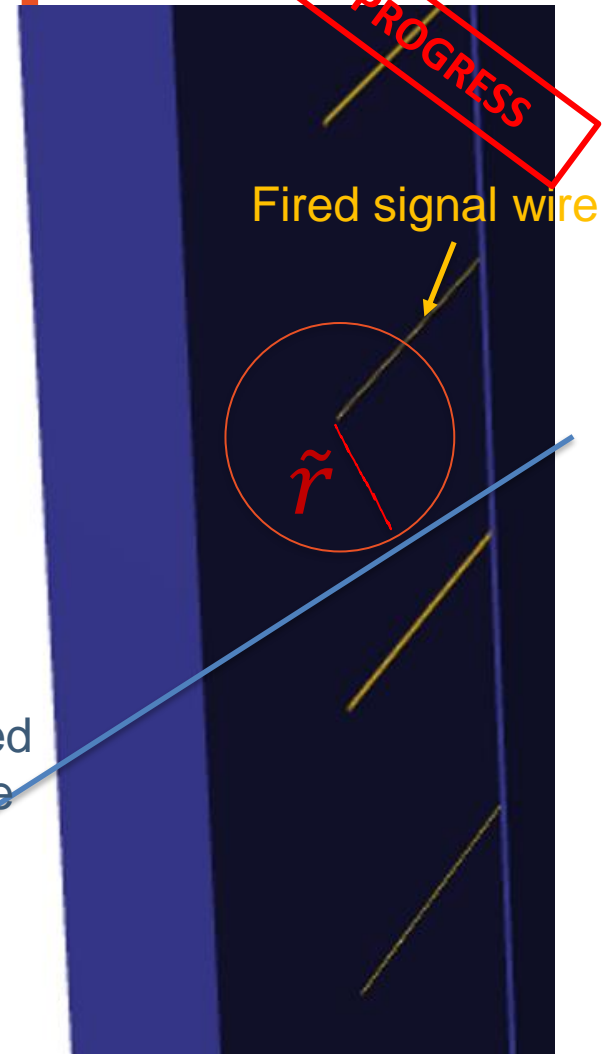
Track Reconstruction

- r_i inferred impact parameter from NLL method:

$$NLL = \sum_i \frac{(r_i - \tilde{r}_i)^2}{\sigma_r^2}$$

- NLL minimization provides the helix parameter estimate
 - Φ_0, x_0 initial angle and position
 - R helix radius
 - λ dip angle
 - h helicity

charged particle



Kalman Filter - Motivation

VALERIO'S TALK

- The assumption that the particle's trajectory is a helix is not true when accounting for Coulomb scattering (**MCS**) and **energy loss** during propagation
- KF reproduces the particle's trajectory by proceeding **step by step** and considering in each step the energy loss, MCS, measurement noise, etc.

Future Prospects

- We have SAND geometry simulation both for STT tracker and Drift Chamber
- A simulation campaign of **2 millions ν_{μ} CC** already produced (GENIE + edepsim + digitization) to get physics performances (muon momentum solution, neutron and proton detection efficiency...)
- Working on a charged **tracks reconstruction** to obtain SAND tracking performances and physics capabilities