Reconstruction in the DUNE Near Detector Muon Spectrometer

version text

Asa Nehm (they/them) for the DUNE collaboration asa.nehm@uni-mainz.de



DUNE – Deep Underground Neutrino Experiment

Next generation long baseline neutrino experiment based at Fermilab, USA

- Precision measurements of v oscillation (sin²θ₂₃), origin of matter (CP violation), unification of forces (proton decay), black hole formation (SN neutrinos)
- Near detector complex with on-axis (SAND) and off-axis movable components (ND-LAr, TMS) with the PRISM method



TMS – The Muon Spectrometer • Detect and measure **muons** not stopped within

upstream ND-LAr

- Magnetic field of 1T by coils
- Alternating steel and plastic scintillator (100 layers each)
- Steel in 3 plates, 2 cm gaps in between plates
- Upstream 40 layers 1.5 cm thin
- Downstream 60 layers 4 cm thick
- Scintillator in <mark>4 panels</mark> each with 48 bars
- Readout by WLS fibers and top-mounted SiPMs





(1) Cluster hits in time (time slicing)

2) Hough transformation – calculate Hough lines

- Point in image space is line in parameter space
- All slopes and intercepts that can result in this point
- **Points** on **same line** in image space are lines with one crossing in parameter space



[1]

[2]

- Representing the image space line's slope and intercept

3) A* algorithm – shortest path from start to end

- **Two costs** to determine most efficient path from start to end - Heuristic cost: 'how far away is the end?'
- **Connection/ground cost**: 'how far away is the next potential cell?' • Each cell has inherent heuristic cost
- For each connection the **connection/ground cost** is **calculated** Choose connection with lowest sum of both costs







Adding a third orientation

To allow for studies of different geometries the reconstruction was adapted to also use **hits from X** (90°) layers in the matching. This allows for a much finer reconstruction of the y position of a track.





Different geometry layouts – why?





Status of reconstruction after Hough and A* Separate reconstructions for the different oriented layers (±3°)



The **stereo layout** with ±3° (U/V) layers has advantages in bend direction (x) but disadvantages in up/down (y) Good for charge ID

- Determined by curvature/deviation from straight line

Bad for stopping vs exiting muon

- $\frac{1}{6}$ · Charge ID - Missing/vague information for some down-pointing tracks
- Good and bad for track length reconstruction
- Good in x, bad in y. Both should be taken into account for a correct reconstruction
- Adding 90° rotated (X) layers could help with disadvantages of layout.

Hits to be

indicate the magnetic field direction

Momentum **Bottom exiting** reconstruction vs. stopping μ **DUNE work-in-progress**

More X layers

4) Extrapolation at starts and ends of tracks

- Use **heuristic cost** for determination of how far away hit is from end of track
- Use only hits that are **within 2 or 4 bar widths** from direction line to be added
- If suitable hit found, connect with **A* algorithm** up to certain **limit**
- Higher z than end of track a.t.m. for direction and within certain distance from end of track
- Hit within 2 or 4 bar widths from direction line
- **Up to** sum of both limits



Influence of X layers on y reconstruction



Hits in

1 GeV simulated µ⁺