

# Stochastic Optimisation Framework using CIL and SIRF for PET Reconstruction

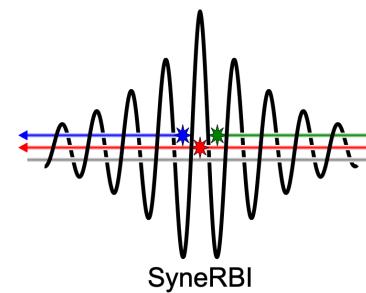
10th Conference on PET, SPECT, and MR Multimodal Technologies  
Total Body and Fast Timing in Medical Imaging

Evangelos Papoutsellis - Finden Ltd, University of Manchester

**Finden**

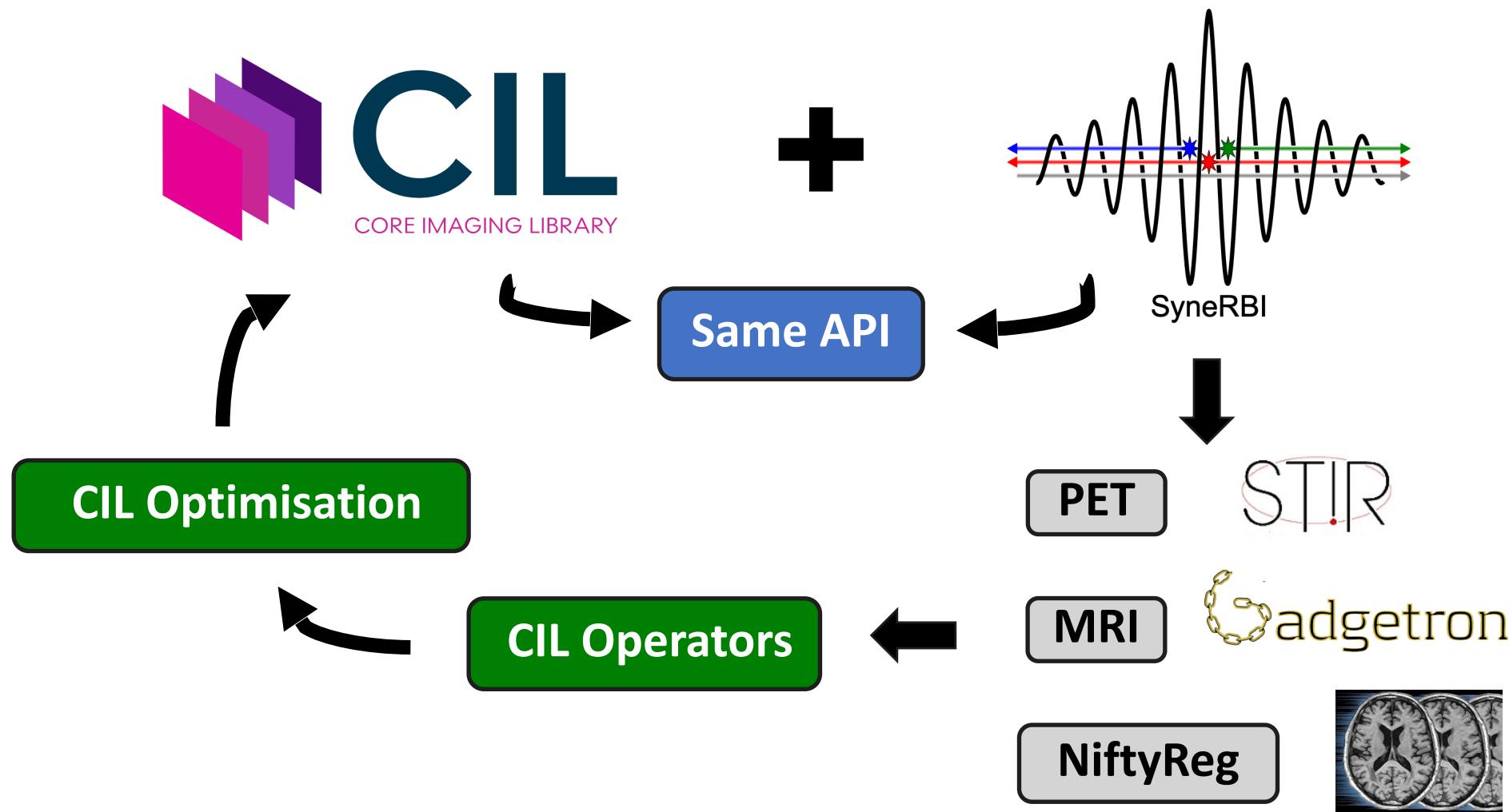


Innovate UK  
KTN



[epapoutsellis@gmail.com](mailto:epapoutsellis@gmail.com)

# Overview: CIL and SIRF



Jørgensen. et al. 2021, Core Imaging Library - Part I: a versatile Python framework for tomographic imaging

Papoutsellis et al. 2021, Core Imaging Library - Part II: multichannel reconstruction for dynamic and spectral tomography

Ovtchinnikov et al. 2017, SIRF: Synergistic Image Reconstruction Framework

# Optimisation in CIL

CIL Optimisation



Functions



Operators

Algorithms

name	description
CGLS	conjugate gradient least squares
SIRT	simultaneous iterative reconstruction technique
GD	gradient descent
FISTA	fast iterative shrinkage-thresholding algorithm
LADMM	linearized alternating direction method of multipliers
PDHG	primal dual hybrid gradient
SPDHG	stochastic primal dual hybrid gradient

Chambolle et al 2017, Stochastic Primal-Dual Hybrid Gradient Algorithm with Arbitrary Sampling and Imaging Applications

Chambolle et al 2010, A First-Order Primal-Dual Algorithm for Convex Problems with Applications to Imaging

Beck et al 2009, A Fast Iterative Shrinkage-Thresholding Algorithm for Linear Inverse Problems

# Optimisation in CIL

$$\min_x f(x) , \quad f : \text{L-smooth}$$

$f, g$  convex

→  $\min_x f(x) + g(x) , \quad f : \text{L-smooth} , \quad g : \text{proximable}$

$$\min_x f(Kx) + g(x) , \quad f : \text{proximable} , \quad g : \text{proximable} , \quad K \text{ linear operator}$$

## PET reconstruction

with Relative  
Difference Prior

$$\min_u \sum Au - b \log(Au + \eta) + \text{RDP}(u) + \mathbb{I}_{\{u>0\}}(u)$$

## CT reconstruction with TV regularisation

$$\min_u \frac{1}{2} \|Au - b\|^2 + \alpha \|\nabla u\|_{2,1} + \mathbb{I}_{\{u>0\}}(u)$$

## TGV denoising Salt and Pepper Noise

$$\min_u \frac{1}{2} \|u - b\|_1 + \alpha \|\nabla u - w\|_{2,1} + \beta \|\mathcal{E}w\|_{2,1}$$

# Stochastic Project

→ **Extend CIL Optimisation (Deterministic) framework to Stochastic Optimisation**

Organised: [CCP SyneRBI](#) , [CCPi](#) , [PET++](#)

- **1<sup>st</sup> Hackathon:** November 23-26, 2021
- **2<sup>nd</sup> Hackathon:** April 4-7, 2022
- **Finden Ltd - Analysis for Innovators (A4i):** Denoising of chemical imaging and tomography data. In collaboration with National Physical Laboratory (05/2023 - 09/2023)

**Joint work:** Kris Thielemans, Gillman Ashley, Tang Junqi, Zeljko Kereta, Imraj Singh, Gemma Fardell, Evgueni Ovtchinnikov, Matthias Ehrhardt, Laura Murgatroyd, Robert Twyman, Edoardo Pasca, Claire Delplancke, Georg Schramm, Daniel Deidda, Jakob Jørgensen, Sam Porter, Margaret Duff, Antony Vamvakeros, Simon Jacques, Casper da Costa-Luis

# Stochastic Project

→ Extend CIL Optimisation (Deterministic) framework to Stochastic Optimisation

- Implement splitting for CIL/SIRF DataContainers: CT, PET, SPECT, MRI data
- Implement randomized algorithms in CIL, e.g., SGD, SAG, SAGA, SVRG and more
- Improve CIL optimisation functionality, e.g., step size, preconditioning

$$\min_x f(x) + g(x) \quad , \quad \min_x f(Kx) + g(x)$$

$$\min_x \sum_{i=1}^n f_i(x) + g(x) \quad , \quad \min_x \sum_{i=1}^n f_i(K_i x) + g(x)$$

Defazio et al. 2014, SAGA: A Fast Incremental Gradient Method With Support for Non-Strongly Convex Composite Objectives

Schmidt et al. 2017, Minimizing finite sums with the stochastic average gradient

Johnson et al., 2013, Accelerating Stochastic Gradient Descent using Predictive Variance Reduction

# Stochastic Optimisation in CIL

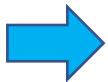
$$\min_x f(x) + g(x)$$

GD	PGA/ISTA	APGA/FISTA
$x_{k+1} = x_k - \gamma_k \nabla f(x_k)$	$x_{k+1} = \text{prox}_{\gamma_k g}(x_k - \gamma_k \nabla f(x_k))$	$x_{k+1} = \text{prox}_{\gamma_k g}(y_k - \gamma_k \nabla f(y_k))$ $\alpha_{k+1} = \frac{1 + \sqrt{1 + 4\alpha_k^2}}{2}$ $y_k = x_k + \frac{\alpha_k - 1}{a_{k+1}}(x_k - x_{k-1})$

# Stochastic Optimisation in CIL

$$\min_x \sum_{i=1}^n f_i(x) + g(x)$$

- Avoid computing the full gradient per iteration, i.e., gradient for all  $n$ .



- Select a random index  $i_k \in \{1, \dots, n\}$  and compute  $\nabla f_{i_k}$  per iteration.

GD	PGA/ISTA	APGA/FISTA
$x_{k+1} = x_k - \gamma_k \nabla f_{i_k}(x_k)$	$x_{k+1} = \text{prox}_{\gamma_k g}(x_k - \gamma_k \nabla f_{i_k}(x_k))$	$x_{k+1} = \text{prox}_{\gamma_k g}(y_k - \gamma_k \nabla f_{i_k}(y_k))$ $\alpha_{k+1} = \frac{1 + \sqrt{1 + 4\alpha_k^2}}{2}$ $y_k = x_k + \frac{\alpha_k - 1}{a_{k+1}}(x_k - x_{k-1})$

# Stochastic Optimisation in CIL

GD	PGA/ISTA	APGA/FISTA
$x_{k+1} = x_k - \gamma_k \nabla f_{i_k}(x_k)$	$x_{k+1} = \text{prox}_{\gamma_k g}(x_k - \gamma_k \nabla f_{i_k}(x_k))$	$x_{k+1} = \text{prox}_{\gamma_k g}(y_k - \gamma_k \nabla f_{i_k}(y_k))$ $\alpha_{k+1} = \frac{1 + \sqrt{1 + 4\alpha_k^2}}{2}$ $y_k = x_k + \frac{\alpha_k - 1}{a_{k+1}}(x_k - x_{k-1})$

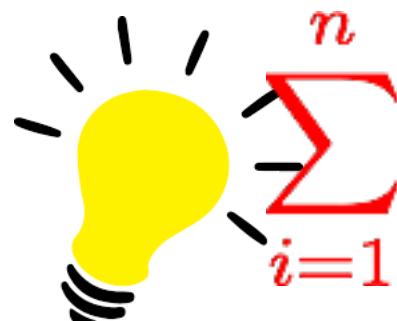
SGD

Prox-SGD

Acc-Prox-SGD

ApproximateGradientSumFunction

StochasticOptimizationDesign



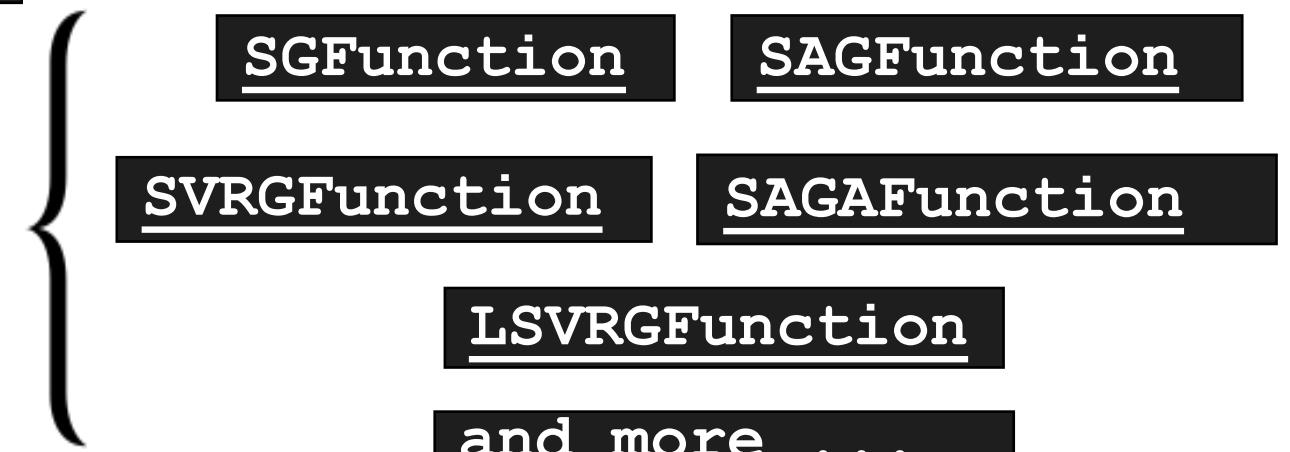
- No direct implementation of Stochastic Gradient Functions in CIL.
- Selects randomly, e.g., SGD.  $\{1, \dots, n\}$
- Use a deterministic algorithm, e.g., GD, already available in CIL.
- Implements a Stochastic Gradient "Functions" or Variance-Reduced "Functions"
- Example SGD := GD (CIL Algorithm) + SGFunction (CIL Function)

# Stochastic Optimisation in CIL

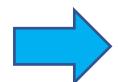
GD	ISTA	FISTA
$x_{k+1} = x_k - \gamma_k \tilde{\nabla} f_{i_k}(x_k)$	$x_{k+1} = \text{prox}_{\gamma_k g}(x_k - \gamma_k \tilde{\nabla} f_{i_k}(x_k))$	$x_{k+1} = \text{prox}_{\gamma_k g}(y_k - \gamma_k \tilde{\nabla} f_{i_k}(y_k))$ $\alpha_{k+1} = \frac{1 + \sqrt{1 + \alpha_k^2}}{2}$ $y_{k+1} = x_k + \frac{\alpha_k - 1}{\alpha_{k+1}}(x_k - x_{k-1})$

## ApproximateGradientSumFunction

$$\sum_{i=1}^n f_i(x)$$



# Stochastic Optimisation in CIL



## Plug and Play Framework - Different Stochastic Gradient Functions

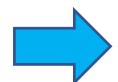
Algorithms	GD	ISTA	FISTA
Stochastic Function			
SGFunction	SGD	Prox-SGD	Acc-Prox-SGD
SAGFunction	SAG	Prox-SAG	Acc-Prox-SAG
SAGAFunction	SAGA	Prox-SAGA	Acc-Prox-SAGA
SVRGFunction	SVRG	Prox-SVRG	Acc-Prox-SVRG
LSVRGFunction	LSVRG	Prox-LSVRG	Acc-Prox-LSVRG



```
gd = GD(initial=initial, objective_function=f, step_size=step_size,
         update_objective_interval=1, max_iteration=10)
gd.run(verbose=1)

pgd = ISTA(initial=initial, f=f, g=g, step_size=step_size,
            update_objective_interval=1, max_iteration=10)
pgd.run(verbose=1)
```

# Stochastic Optimisation in CIL



## Plug and Play Framework - Different Stochastic Gradient Functions

Algorithms	GD	ISTA	FISTA
Stochastic Function			
SGFunction	SGD	Prox-SGD	Acc-Prox-SGD
SAGFunction	SAG	Prox-SAG	Acc-Prox-SAG
SAGAFunction	SAGA	Prox-SAGA	Acc-Prox-SAGA
SVRGFunction	SVRG	Prox-SVRG	Acc-Prox-SVRG
LSVRGFunction	LSVRG	Prox-LSVRG	Acc-Prox-LSVRG



```
sgd = GD(initial=initial, objective_function=SGFunction(fi), step_size=step_size,
          update_objective_interval=1, max_iteration=10)
sgd.run(verbose=1)

prox_sgd = ISTA(initial=initial, f=SGFunction(fi), g=g, step_size=step_size,
                 update_objective_interval=1, max_iteration=10)
prox_sgd.run(verbose=1)
```

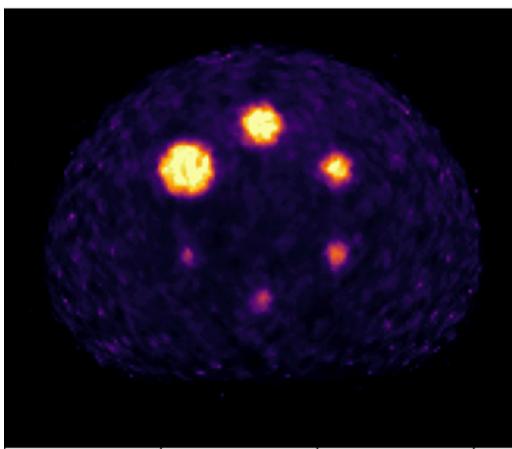
# Stochastic Utilities/Improvements

- ✓ Data splitting methods for AcquisitionData (CIL + SIRF).
- ✓ Sampling methods used by Stochastic Functions, i.e., select the next function  $f_{i_k}$
- ✓ Callable Classes to improve functionality of CIL Algorithms
- ✓ Proximal Gradient Algorithm (PGA) : Base class for Proximal Gradient Algorithms, e.g., GD, ISTA, FISTA
- ✓ CIL + SIRF fully compatible --> SIRF Functions can be used with CIL Algorithms

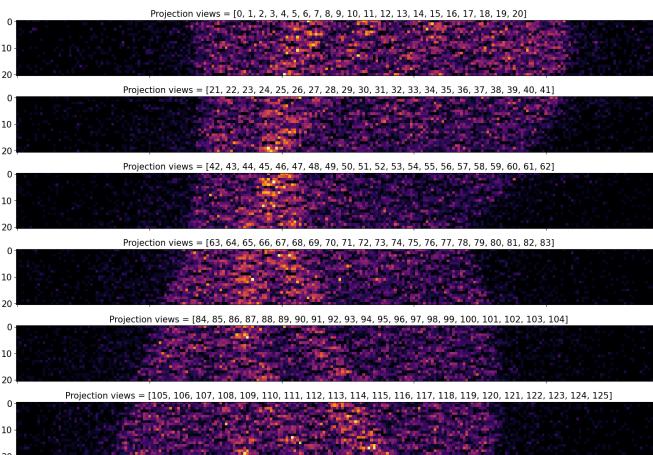
# Stochastic Utilities

✓ Example: Data splitting methods for `AcquisitionData (CIL + SIRF)`

NEMA dataset



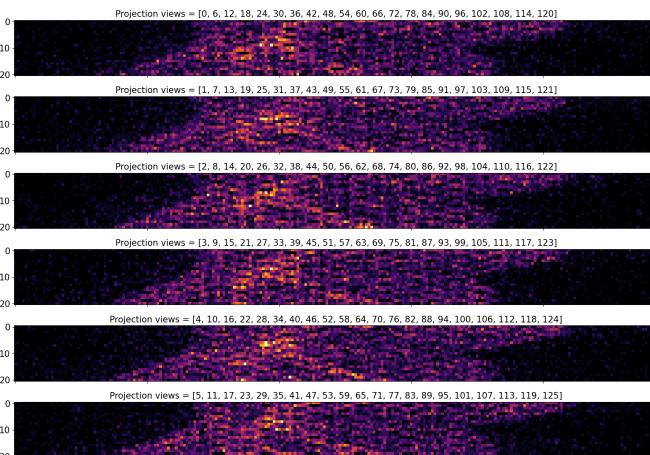
Ordered (Step\_size=1)



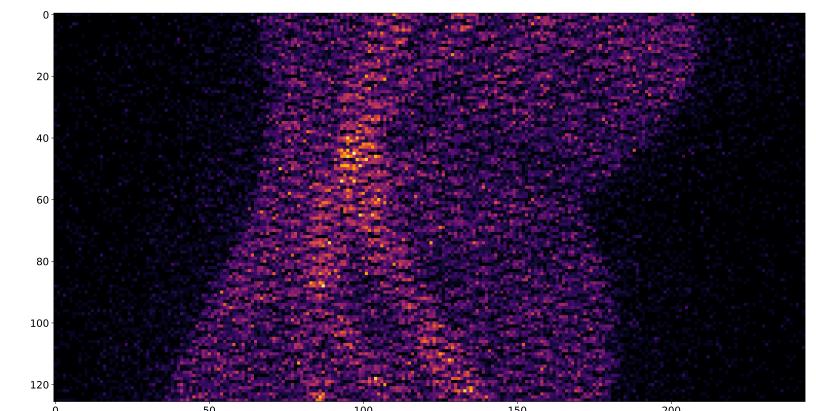
Split to 6 subsets



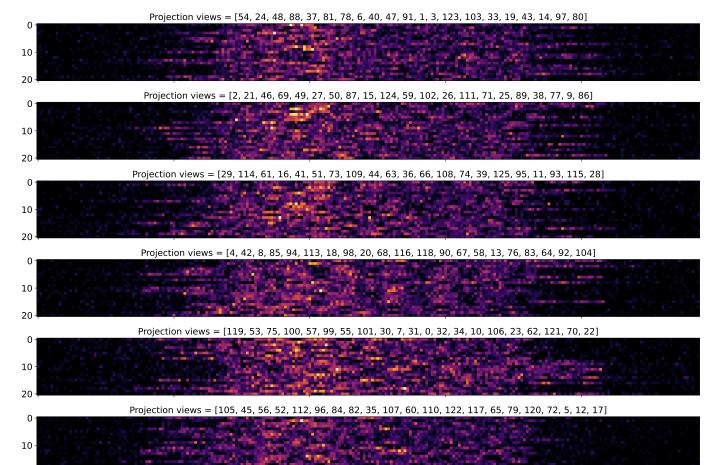
Ordered (Step\_size= NumSubsets )



126 projection views



Random



# Stochastic Utilities

✓ Example: Sampling methods used from Stochastic Functions

Uniform Sampling (With replacement) n=6

<u>Iteration</u>	0	1	2	3	4	5	6	7	8	9	10	11
<u>Function</u>	$f_3$	$f_4$	$f_0$	$f_5$	$f_1$	$f_4$	$f_3$	$f_1$	$f_4$	$f_0$	$f_0$	$f_1$

RandomShuffle (Without replacement)

<u>Iteration</u>	0	1	2	3	4	5	6	7	8	9	10	11
<u>Function</u>	$f_3$	$f_1$	$f_0$	$f_2$	$f_4$	$f_5$	$f_4$	$f_1$	$f_0$	$f_2$	$f_5$	$f_3$

SingleShuffle (Without replacement)

<u>Iteration</u>	0	1	2	3	4	5	6	7	8	9	10	11
<u>Function</u>	$f_3$	$f_2$	$f_4$	$f_0$	$f_1$	$f_5$	$f_3$	$f_2$	$f_4$	$f_1$	$f_5$	$f_3$

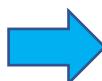
HermanMeyer

<u>Iteration</u>	0	1	2	3	4	5	6	7	8	9	10	11
<u>Function</u>	$f_0$	$f_3$	$f_1$	$f_4$	$f_2$	$f_5$	$f_0$	$f_3$	$f_1$	$f_4$	$f_2$	$f_5$

# CIL Improvements

## ✓ Example: Proximal Gradient Algorithm (PGA) Base Class

$$x_{k+1} = \text{prox}_{\gamma_k g}(x_k - \gamma_k D(x_k) \nabla f(x_k))$$



$$x_{k+1} = \text{prox}_{\gamma g}(x_k - \gamma \nabla f(x_k))$$

```
class Preconditioner(ABC)
class StepSizeMethod(ABC)
```

Nocedal and Wright "Numerical Optimisation"

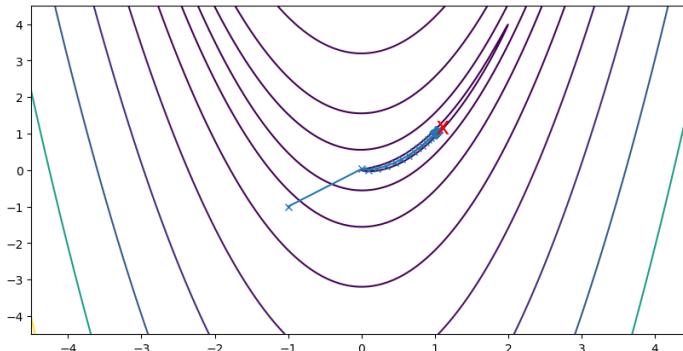
Choose  $\bar{\alpha} > 0$ ,  $\rho \in (0, 1)$ ,  $c \in (0, 1)$ ; Set  $\alpha \leftarrow \bar{\alpha}$ ;  
repeat until  $f(x_k + \alpha p_k) \leq f(x_k) + c\alpha \nabla f_k^T p_k$   
     $\alpha \leftarrow \rho\alpha$ ;  
end (repeat)

Armijo condition

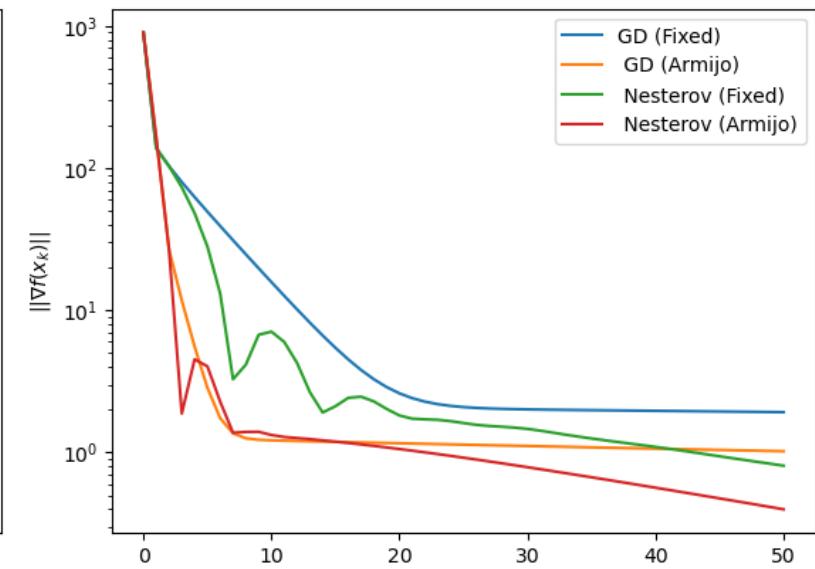
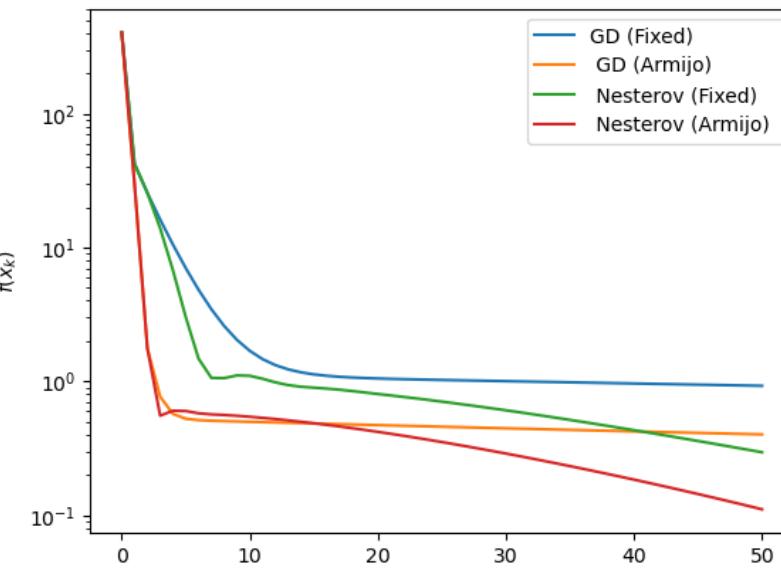
Terminate with  $\alpha_k = \alpha$ .

Rosenbrock Function: minimum at  $(x,y) = (1,1)$

$$f(x, y) = (1 - x)^2 + 100(y - x^2)^2$$



```
armijo = ArmijoStepSize(initial = 1., rho = 0.5, c = 1e-4, iterations=50)
gd = GD(initial = initial, objective_function = f, step_size = armijo,
         max_iteration = 100, update_objective_interval = 1)
gd.run(verbose=1)
```



# CIL Improvements



CIL + SIRF fully compatible



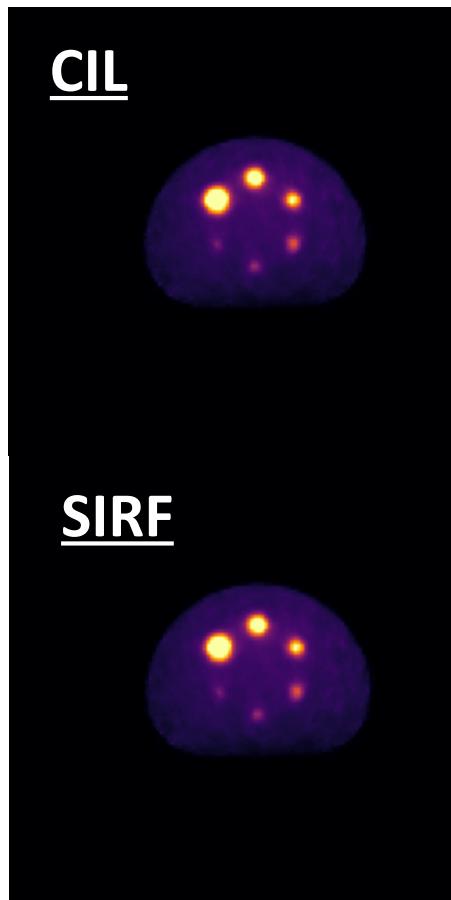
```
class ObjectiveFunction(object)  
class Prior(object)
```

$$f(x) = \text{KL}(b, Ax) + \alpha \text{RDP}(x) \rightarrow x_{k+1} = \mathbb{P}_{\geq 0}(x_k - \gamma_k D(x_k) \nabla f(x_k))$$

$$\alpha = 0, \gamma_k = 1$$

$$D(x_k) = \frac{x_k}{A^T \mathbf{1}}$$

$$\rightarrow x_{k+1} = \frac{x_k}{A^T \mathbf{1}} A^T \left( \frac{d}{Ax_k} \right) \quad (\text{MLEM})$$



```
objective = make_Poisson_loglikelihood(d)  
objective.set_acquisition_model(A)  
objective.set_prior(RelativeDifference)
```

SIRF

```
recon = OSMAPOSLReconstructor()  
recon.set_objective_function(objective)  
recon.set_num_subsets(1)  
recon.set_num_subiterations(50)  
recon.set_up(initial)  
recon.set_current_estimate(initial)  
recon.process()
```



CIL

```
D = AdaptiveSensitivity(A)  
pgd = ISTA(initial = initial, f = objective, g = IndicatorBox(lower=0.),  
            preconditioner = D, step_size = -1.,  
            update_objective_interval=1, max_iteration=50)  
pgd.run(verbose=1)
```

# CIL Improvements

## ✓ Example: Callable Classes to improve functionality of CIL Algorithms

```
from cil.optimisation.utilities import MetricsDiagnostics, StatisticsDiagnostics, RSE
from skimage.metrics import structural_similarity as SSIM
from skimage.metrics import normalized_root_mse as NRMSE

cb1 = MetricsDiagnostics(reference_image = fista_1000.solution, verbose=1,
                         metrics_dict={'mae': MAE, 'ssim': SSIM, 'nrmse': NRMSE})
cb2 = StatisticsDiagnostics(verbose=1, statistics_dict={'mean': (lambda x: x.mean())})

fista = FISTA(initial = initial, f = fidelity, g=G, update_objective_interval = 1,
              max_iteration = 5)
fista.run(verbose=1, callback=[cb1, cb2])
```

- **Access to all attributes of the Algorithm**
- **Define custom metrics (images and/or ROI)**
- **Define new stopping criteria**
- **Integrate with Weights and Biases**

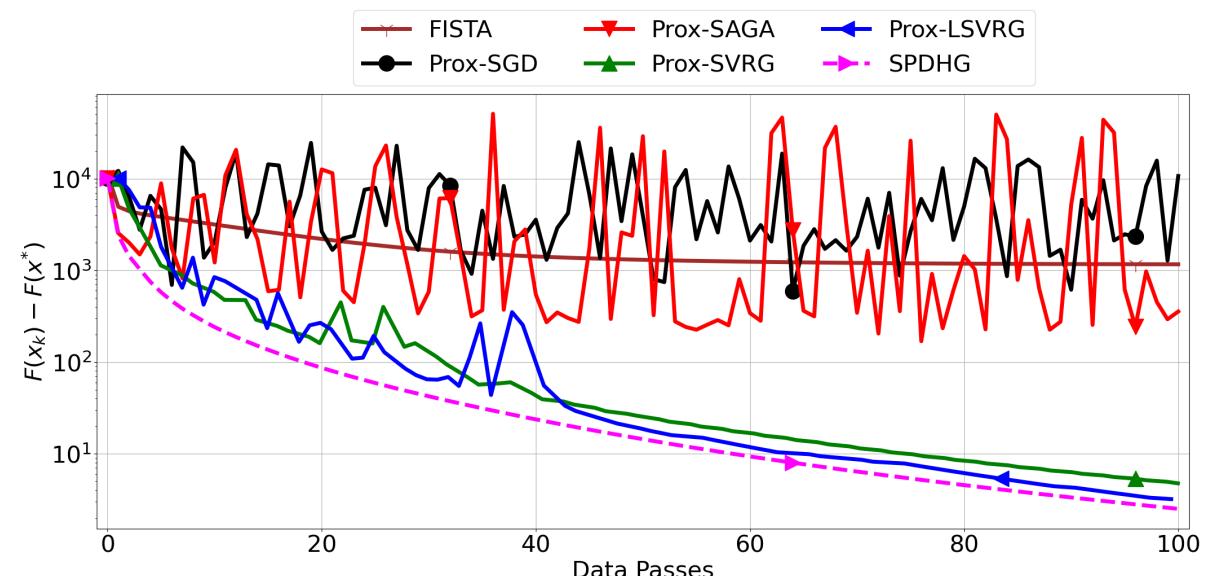
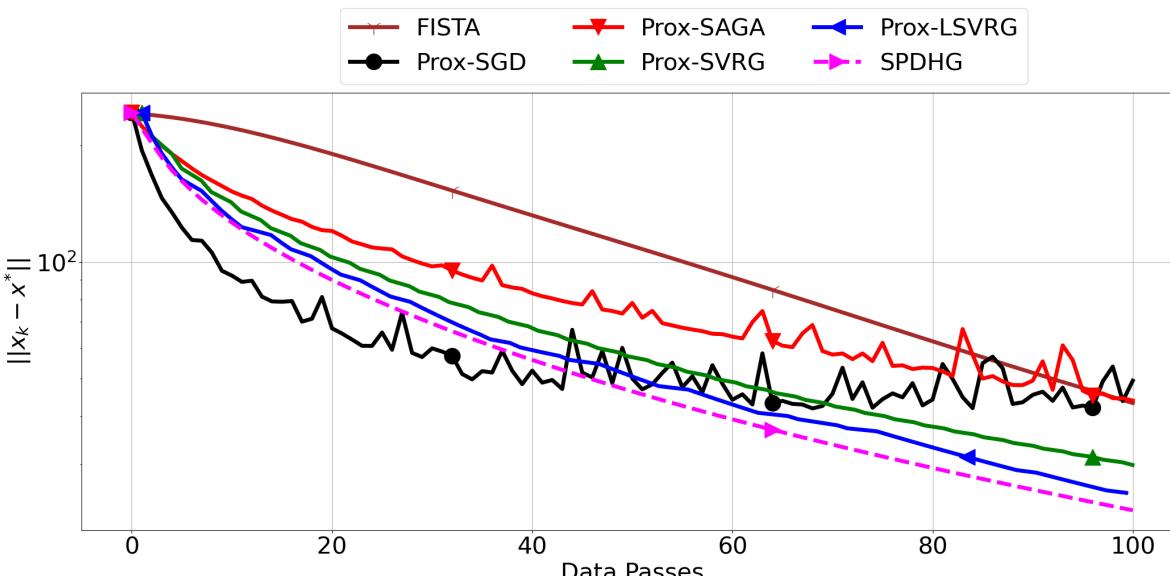
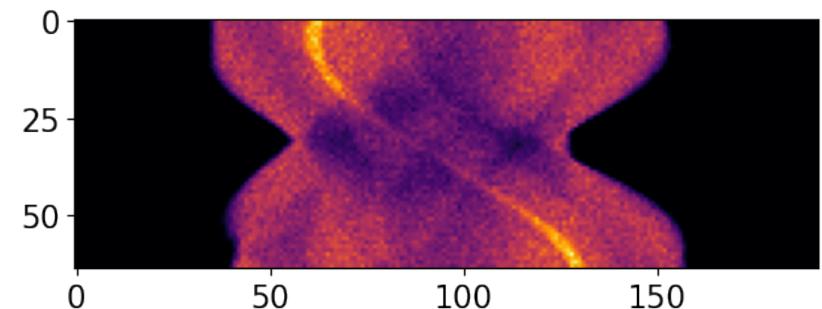
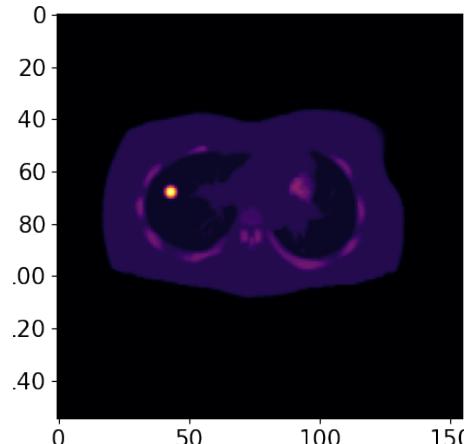
Iter	Max Iter	Time(s)/Iter	Objective	mae	ssim	nrmse	mean
0	5	0.000	8.17946e+02	6.51097e-05	5.05983e-01	1.00000e+00	0.00000e+00
1	5	0.542	9.93983e+01	7.07093e-05	2.84027e-01	7.29477e-01	0.00000e+00
2	5	0.391	7.81449e+01	6.34461e-05	3.14256e-01	6.82127e-01	7.00874e-05
3	5	0.329	6.22991e+01	5.61340e-05	3.50318e-01	6.37522e-01	6.89979e-05
4	5	0.297	5.16572e+01	4.95575e-05	3.92073e-01	5.98112e-01	6.79314e-05
5	5	0.330	4.49825e+01	4.41283e-05	4.37438e-01	5.63993e-01	6.69932e-05

Stop criterion has been reached.

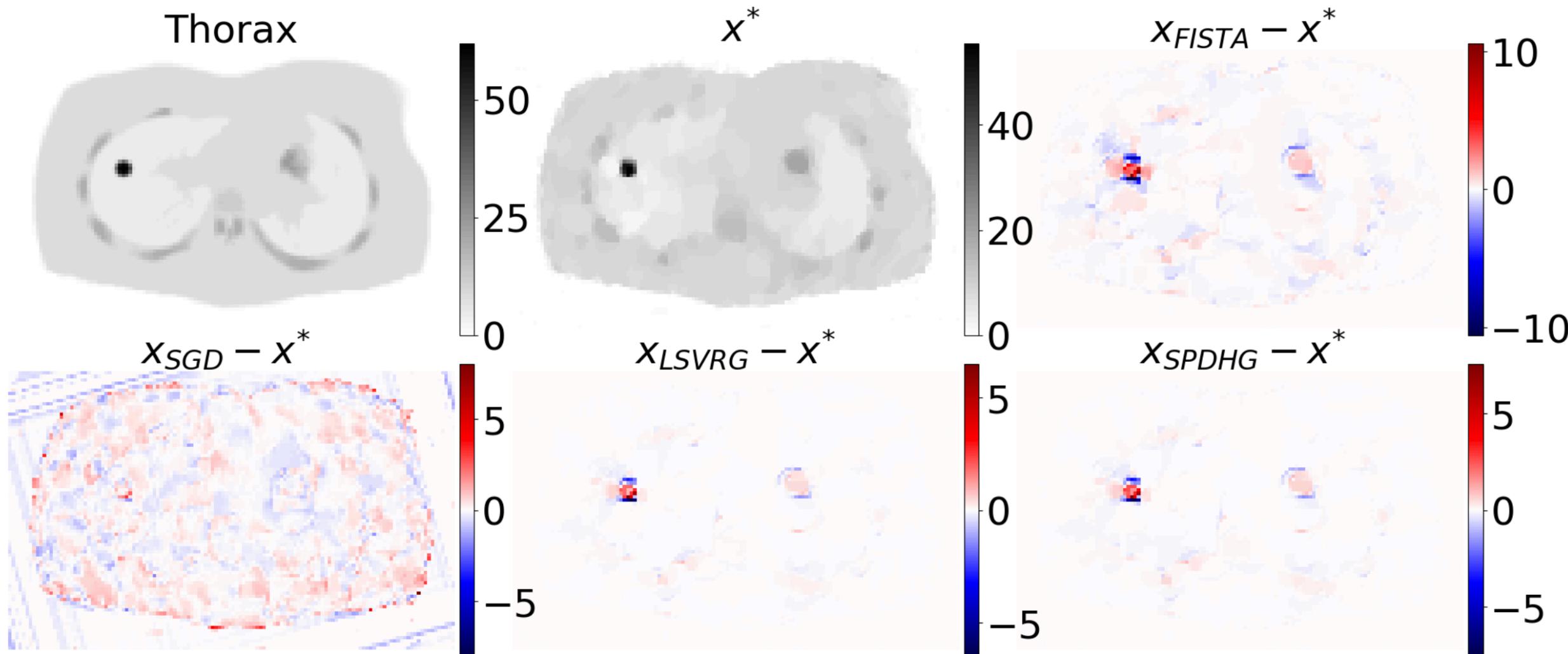
# Applications (PET - Non Smooth optimisation)

- **Splitting Method:** Ordered (64 projections), Subsets = 32
- **Sampling Method (Functions):** Random with replacement
- **Optimal Solution:** SPDHG-32 subsets, 500 epochs
- **Step size:**  $\gamma_k = \gamma$

$$\operatorname{argmin}_u \sum Au - b \log(Au + \eta) + \alpha \|\nabla u\|_{2,1} + \mathbb{I}_{\{u>0\}}(u)$$



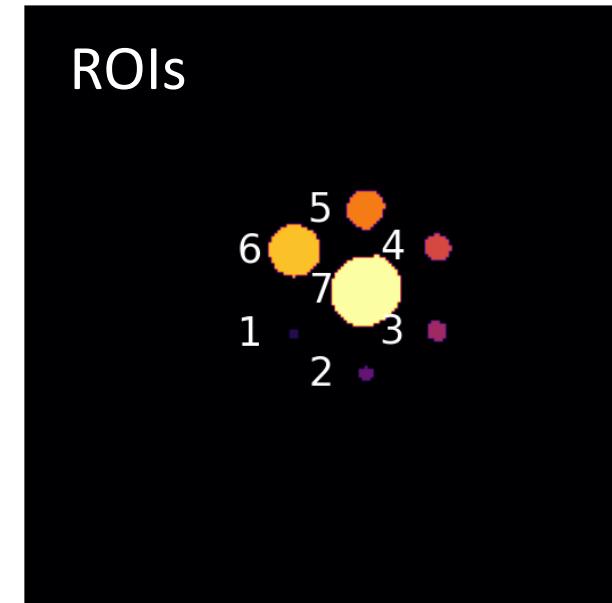
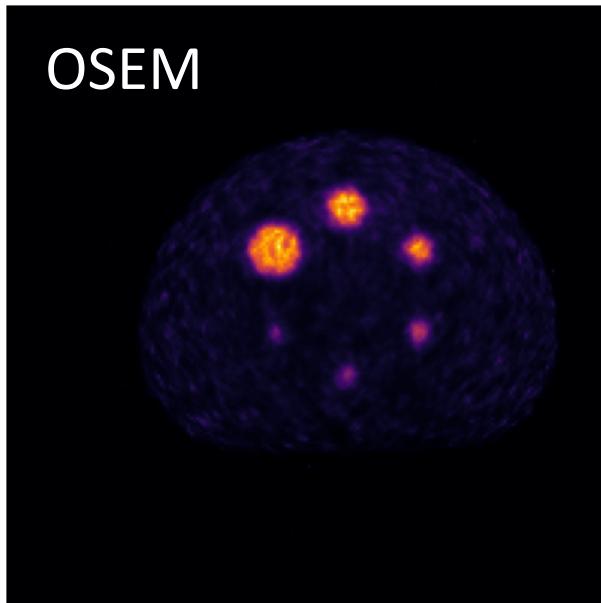
# Applications (PET - Non Smooth optimisation)



# Applications (PET - Smooth optimisation)

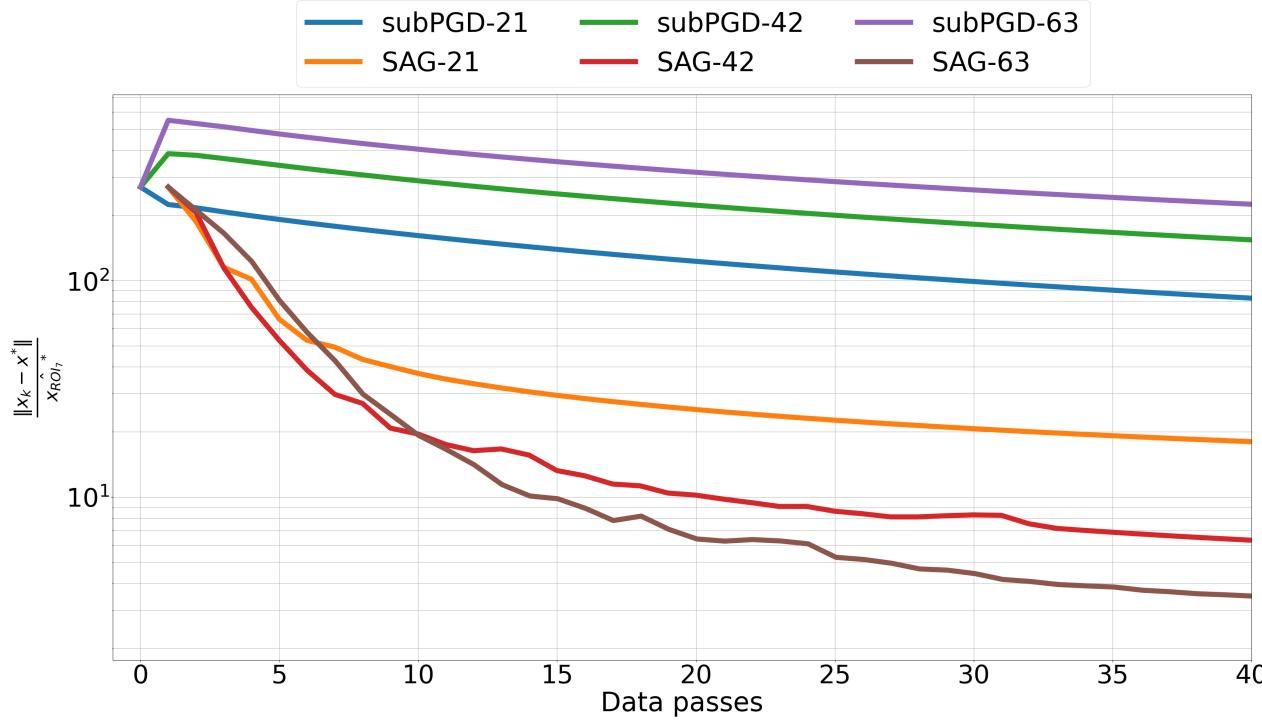
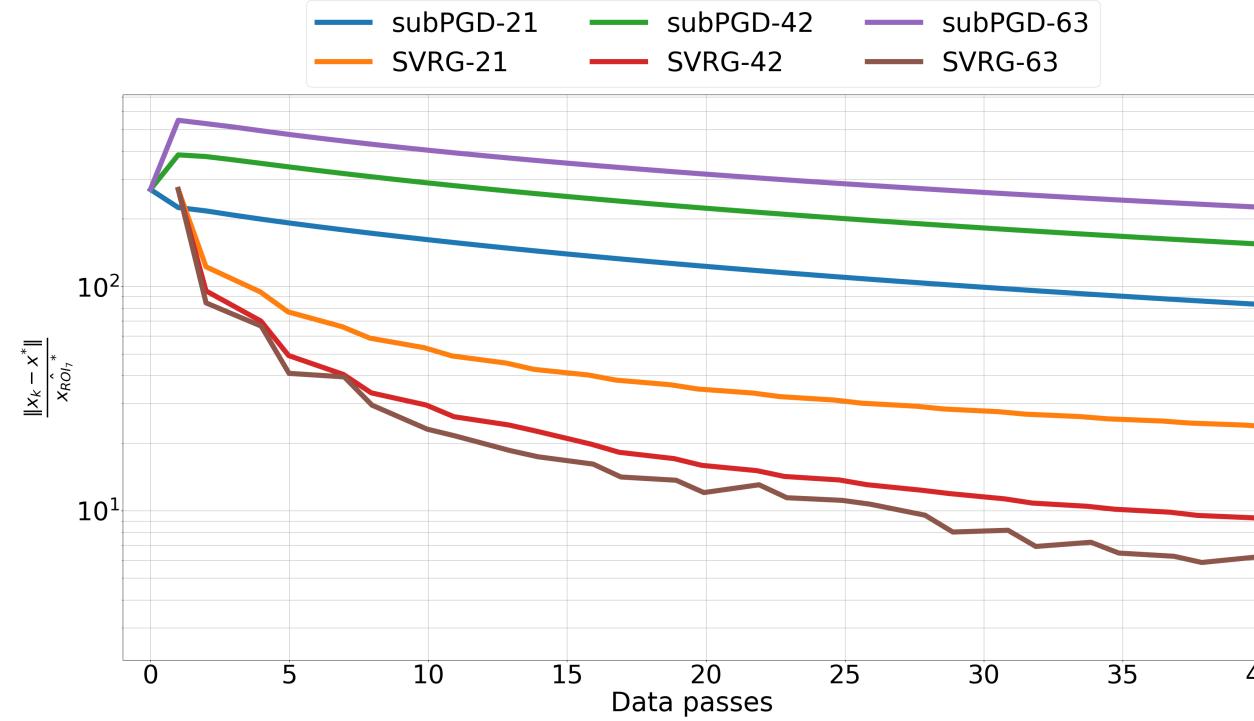
$$\min_u \sum Au - b \log(Au + \eta) + \text{RDP}(u) + \mathbb{I}_{\{u>0\}}(u)$$

- **Splitting Method:** Ordered (126 projections), Subsets = 21, 42, 63
- **Sampling Method (Functions):** Random with replacement
- **Optimal Solution:** (subset) Preconditioned Gradient Descent with relaxed step size, 7 subsets (20000 iterations)
- **Preconditioning:**  $D(x_k) = \frac{x_{OSEM} + \varepsilon}{A^T 1}$
- **Initial:** OSEM

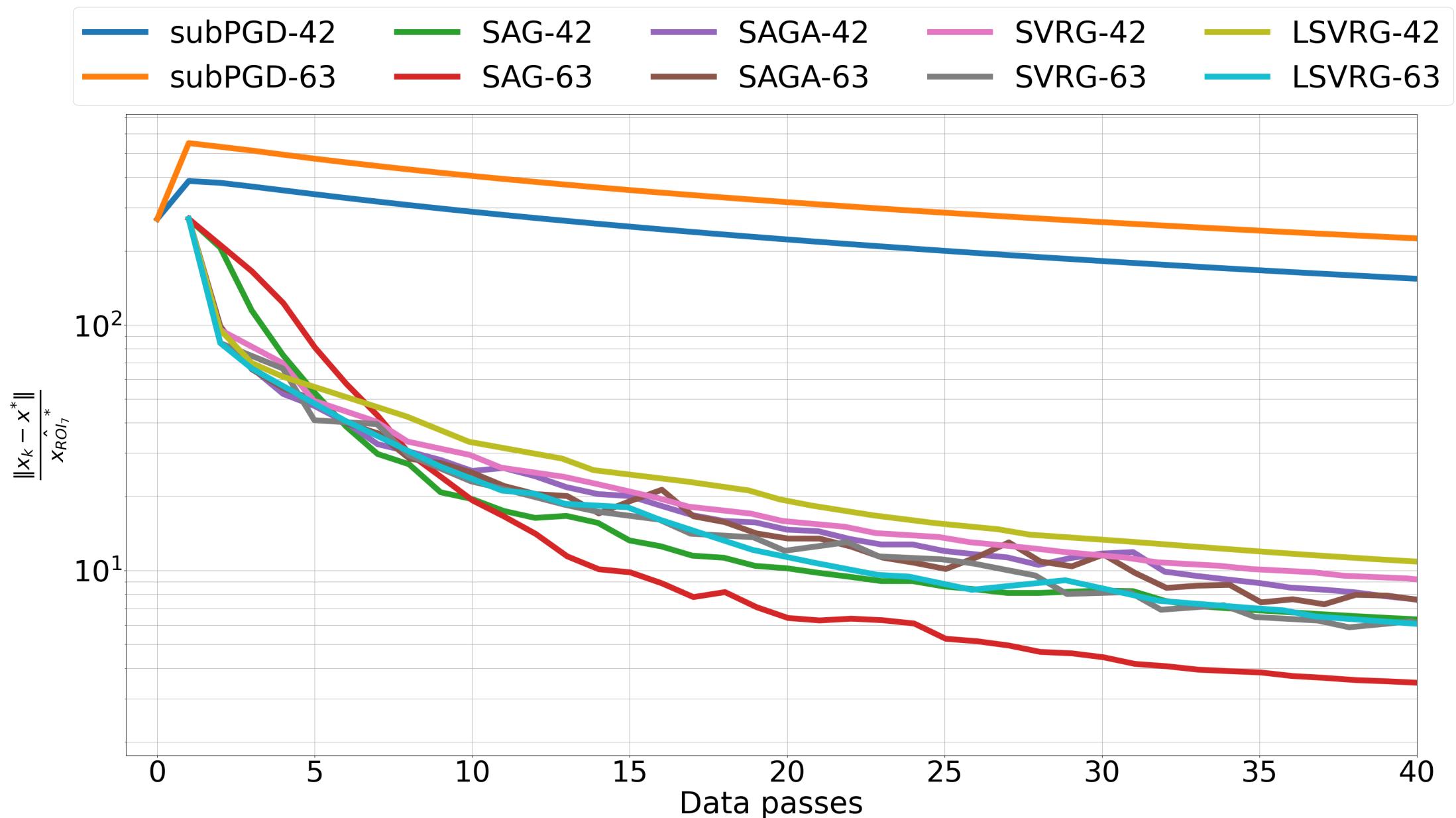


**Step size:**  $\gamma_k = \frac{1}{1 + \eta \left( k // (n/2) \right)}$

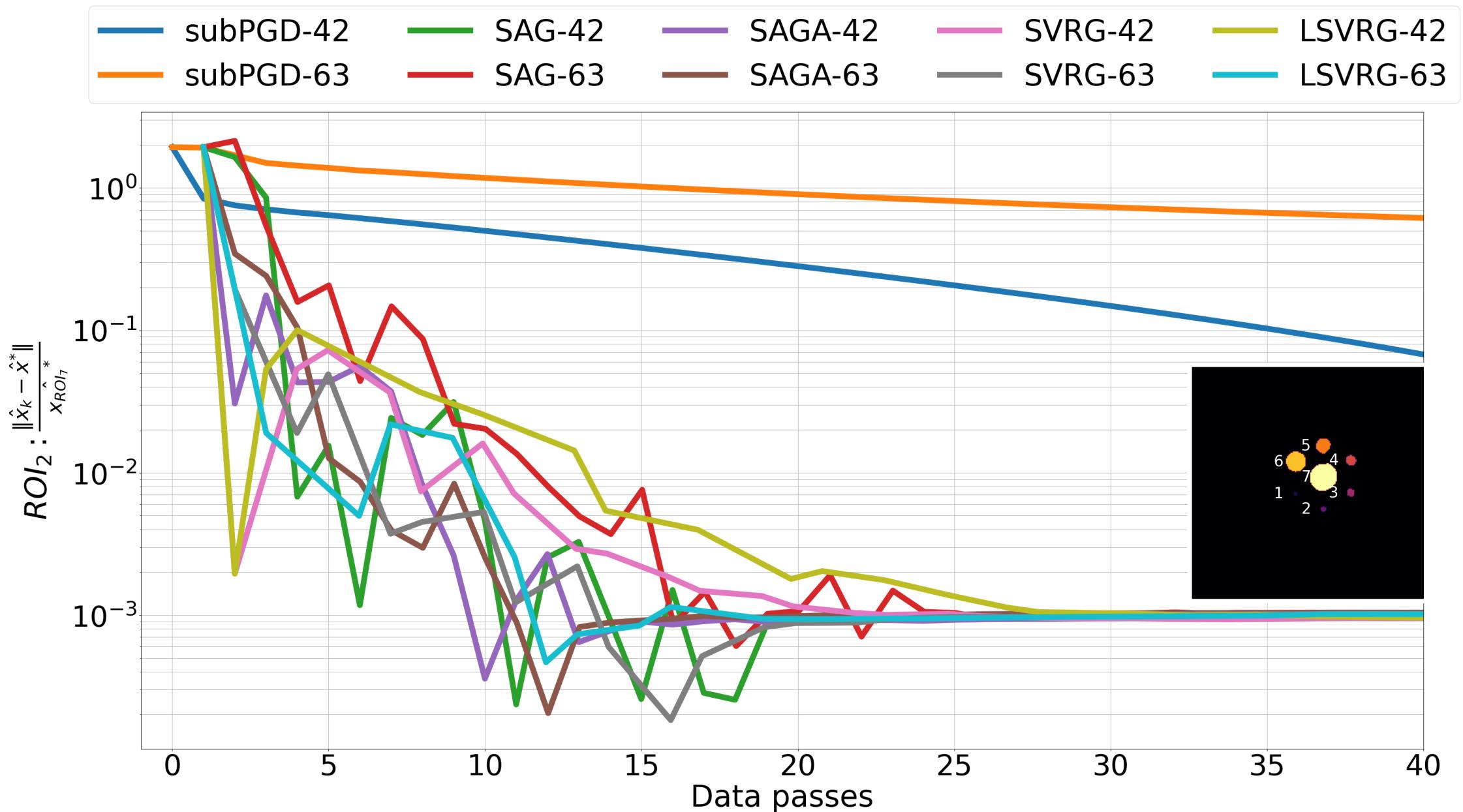
# Applications (PET - Smooth optimisation)



# Applications (PET - Smooth optimisation)

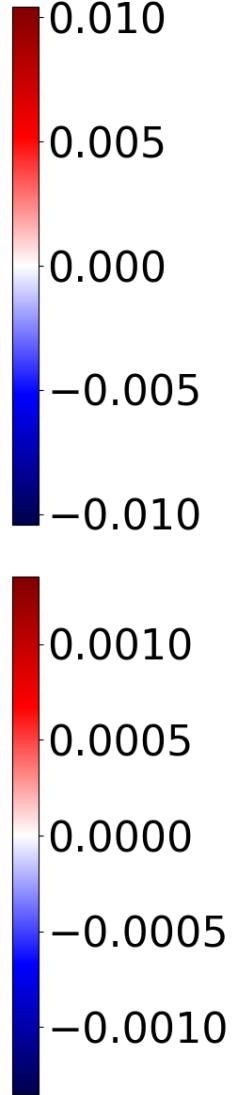
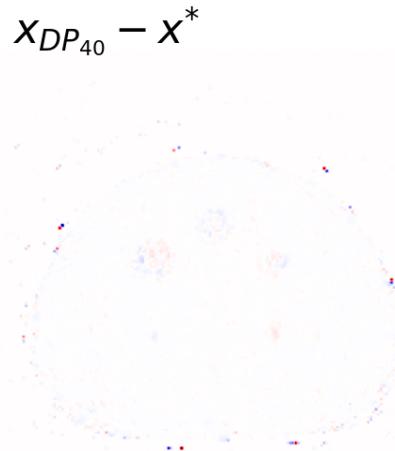
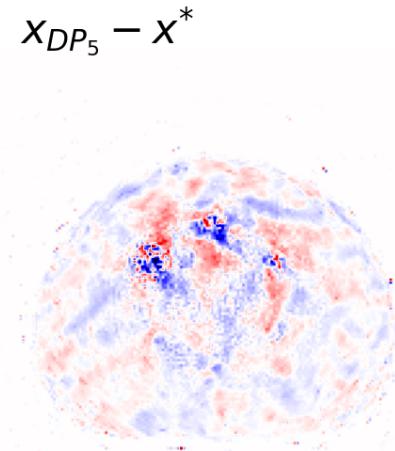
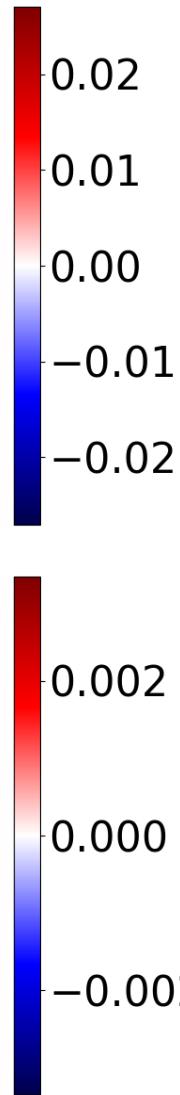
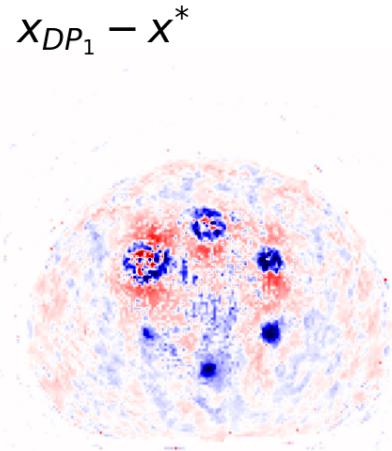
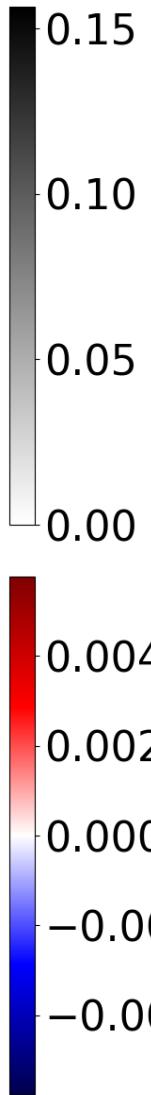
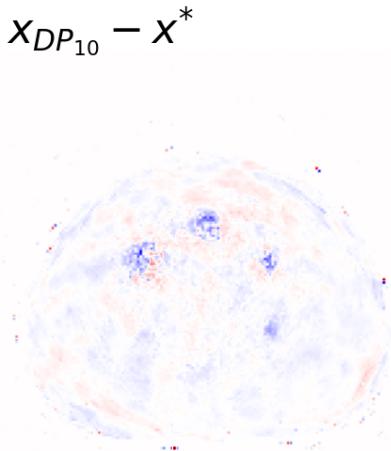
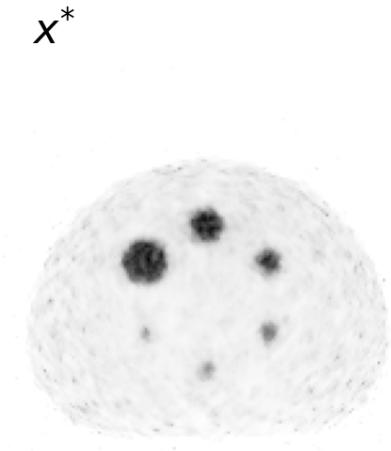


# Applications (PET - Smooth optimisation)



# Applications (PET - Smooth optimisation)

SAG-63



# Summary

- Stochastic Optimisation Framework in CIL
  - Flexible and user friendly design with Plug and Play Stochastic Estimators
  - Different modalities CT, PET, SPECT, MRI
  - Improvements for CIL Optimisation Module
- 
- Website <https://www.ccpi.ac.uk/CIL>
  - Docs <https://tomographicimaging.github.io/CIL/nightly/index.html>
  - Discord <https://discord.gg/kmBcU2kebB>

Thank you for your attention