

# A tale of three beams: towards stable and reproducible operation of the AWAKE facility

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## Abstract

The Advanced Wakefield Experiment (AWAKE) relies on proton-driven wakefields created in a laser-ionized plasma to accelerate electrons. Accurate measurement and control of the optics, trajectory and timing of the three

beams—proton, laser and electron—is a fundamental requirement for successful operation of the facility. Continuous advances in both instrumentation and methods are necessary to improve operational stability, reproducibility and efficiency. Since the three beams have drastically different characteristics, their performance is

limited by different sources (such as thermal effects, magnetic hysteresis, current ripples, phase locking), requiring dedicated approaches. Recent improvements and measurement campaigns are described, highlighting the lessons learned. Finally, the challenges expected in future upgrades of the AWAKE facility are discussed.

### PROTONS (400 GeV)

#### Trajectory

Measurements are essential to position the proton beam on the right trajectory. BTV screens are used instead of BPM due to their higher resolution

#### Optics

Dedicated proton bunch optics were developed using MAD-X and validated with envelope measurements. These optics were used for wide-beam studies [3] and current filamentation studies [4,5].

#### Trajectory Jitter

Positions of the bunch centroids at the waist. The left plot includes the drift of the bunch centroid with the time of the measurement. The right plot shows the same data with subtracted time drift [1]

### ELECTRONS (20 MeV)

#### Trajectory

Orthogonal steering exploits two correctors to adjust the central beam position and angle at plasma entrance.

**Streamline procedure:**

- Add a final corrector to avoid accounting for fields of last quadrupole
- Fast demagnetisation cycles ( $I_{min}$ ,  $I_{max}$ ,  $I_{set}$ ) to compensate for hysteresis

#### Optics

Emittance measurements are performed using a quadrupole scan in a dispersion-free region at the entrance of the beam line. A parabolic fit is effective for Gaussian distributions but loses accuracy for non-Gaussian beams.

**New approach**

- Quadrupole scan can be approached as a classical phase-space-tomography problem, equivalent to a rotation [8]
- Maximum Likelihood Maximum Expectation algorithm developed and commissioned using simulated beams and then validated with data [7]
- Non-Gaussian beams can be fully described and then used to develop beam line optics

### LASER (100 mJ, 100 fs)

#### 4 laser lines: Plasma, Virtual, Electrons, Streak

#### Final beamline alignment

Challenging steering: jitter of laser trajectory is dominated by thermal fluctuations, preventing convergence at larger sample sizes. Accept this limitation, relax steering requirements, and rely on a wide beam to create a large plasma column.

VLC 5, mm	RMS all data	RMS for 100 shot average	RMS for 500 shot average	RMS for 5000 shot average
y actual	0.2741	0.1038	0.0832	0.0766
y random	0.2741	0.0274	0.0123	0.0039
x actual	0.2772	0.0553	0.0281	0.0155
x random	0.2772	0.0277	0.0124	0.0039

Standard deviation of all shots and 100-, 500-, 5000-shot averages on virtual line, compared to expected RMS from random fluctuations [6]

Use virtual line for aligning/monitoring main line. Understand drifts between main/virtual drifts.

### FUTURE CHALLENGES

#### Protons

A good understanding of the sources of beam jitter is essential to predict the waist jitter in Run 2c.

#### Electrons

The experience gained operating the 18 MeV electron line together with the developed tools will set the foundations for the much more challenging operation of Run2c electron lines at 18 and 150 MeV

#### 150 MeV electron line

#### Proton trajectory jitter

Correlate proton trajectory with power converter jitter, to reach required precision (10  $\mu$ m)

Magnet class	Current r.m.s. jitter (ppm)	Beam r.m.s. jitter ( $\mu$ m)
B190	50	6.9
MBG	90	71.5
MBHC	100	22.0
Quadrupole	50-200	-
MSB-4	100	28.8

Measured magnet current jitter and corresponding beam position jitter propagated to the injection point [10]

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