

## Vertex and Inner Tracker summary

### FOOT tracker mechanical setup:

- Final mechanical design available
- Electronic system support table ordered. We'll give start production beginning 2023.
- Inner Tracker readout electronics (Terasic boards) mechanical support under design.

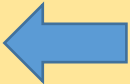
### Magnet system:

- Delivery foreseen june/july 2023

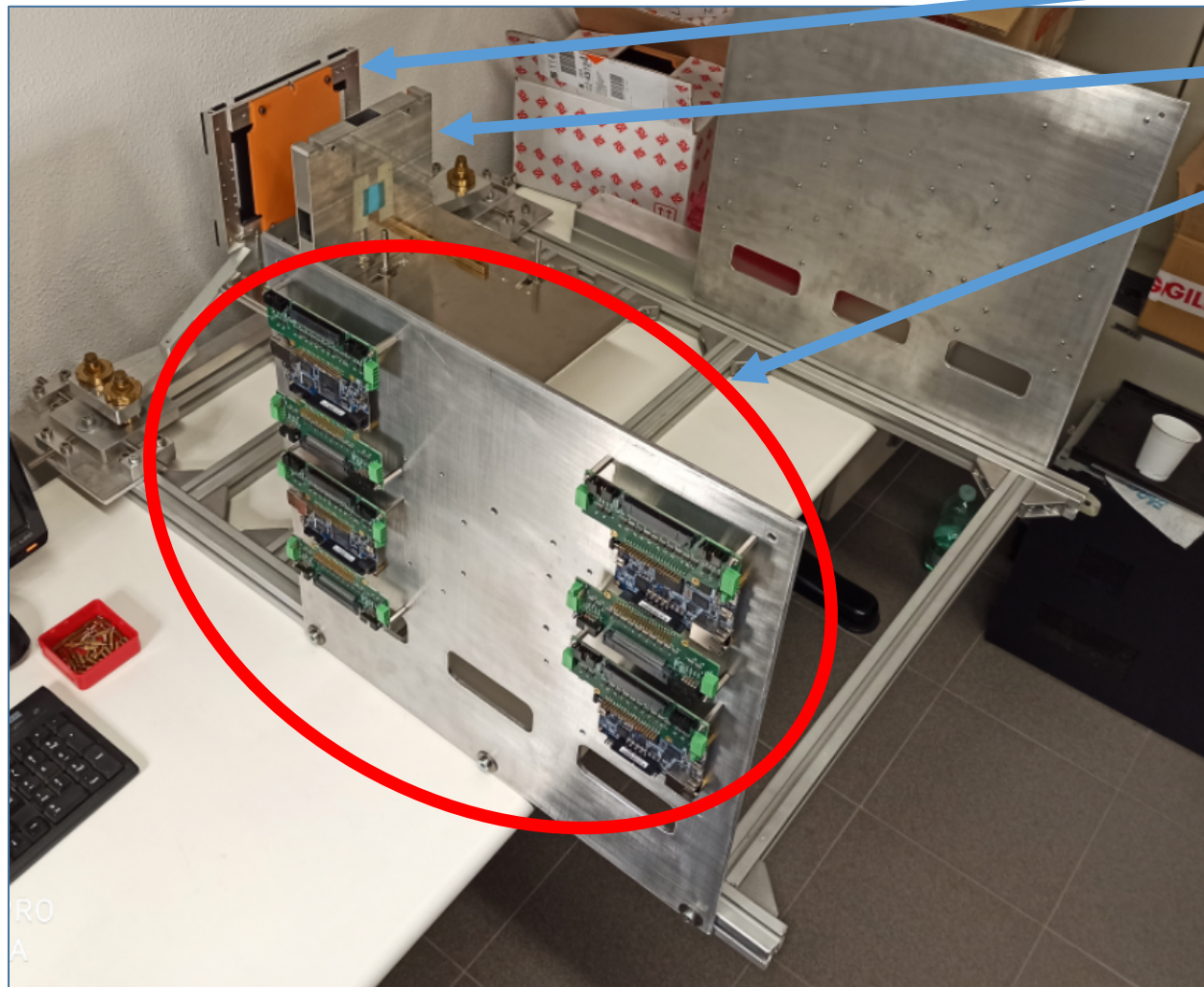
### Pixel vertex detector:

- Used at GSI and at CNAO (last november) see 30 november Christian presentation.
- New Vertex readout board under production (DEOnano board compatible)

### Inner Tracker:

- Plume ladder assembly process definition concluded in Strasbourg
- All production tools available
- **First module tested at LNF, wrong bonding discovered (bonding plan modified)**
- 10 modules assembled
- 1 ladder (out of 5) assembled ( **problems in dead sensors!!!** )  SHOWSTOPPER
- All needed hardware/software pieces available
- Intermediate PC readout software (event building) written and tested at CNAO (for 2 channels out of 8 – extension to 8 not a problem)

# FOOT pixel tracker status



Inner tracker mechanical support

Vertex mechanical support

Readout boards

- **Four final ladders in Frascati**  
( one tested )
- Fifth ladder (spare) to be assembled  
in Strasbourg
- Cabling to be done:
  - control cables
  - trigger cables
  - power cables
  - console USB cables

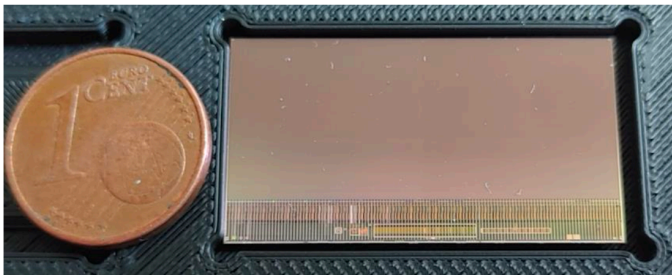
**Overall arrangement  
(not final) foreseen for test beam**

# PRIN 2022 ( Approved )

«High performance DMAPS (Depleted Monolithic Active Pixel Sensor) for hadrontherapy»

«.....we propose this project with the aim of significantly **improving the capabilities of the pixel tracker**, particularly in terms of the **amount of data that can be collected for the same amount of time and spatial resolution**, which for obvious statistical reasons allows for greater accuracy of the measurements to be made.....»

We propose to improve the detection characteristics of the FOOT experiment's **vertex detector** by **using the MIMOSIS sensor**, recently developed for the CBM experiment by the In2p3 research group in Strasbourg.



MIMOSIS-1 chip - full scale prototype of one CMOS sensor

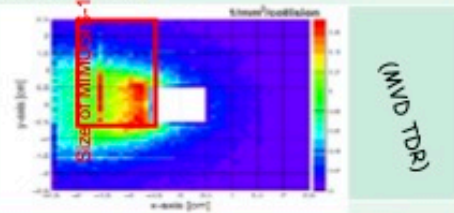
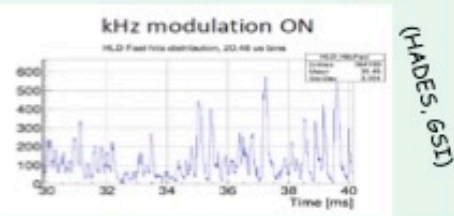
- ✓ Matrix dimension: 1024 columns. X 504 rows
- ✓ Pixel dimension: 26.88  $\mu\text{m}$  (height) x 30.24  $\mu\text{m}$  (width)
- ✓ Fabricated with Tower Semiconductor, 180 nm technology

## A. Dorokhov (VCI 2022)

- ✓ Full-scale prototype of the sensor, MIMOSIS-1, extensively tested at lab and in beam, preliminary results for non-irradiated sensors:
  - Fake hit rate  $< 10^{-5}$
  - Detection efficiency  $> 99\%$  at  $< 220 e$
  - Resolution  $\sim 5 \mu\text{m}$
  - AC pixels show similar to DC pixels performances
  - Possible advantages of AC pixels:
    - tune charge collection efficiency within same technology/split
    - more freedom to improve pixels in another technologies
    - applications beyond CBM, Cremlin+, future e+e- colliders

# PRIN 2022 ( Approved )

## MIMOSIS: requirements for the sensor

	Target requirement	comments/complications
Spatial resolution	~5 $\mu\text{m}$	
Radiation length	~ 0.3 % $X_0$ (first station) ~ 0.5 % $X_0$ (other stations)	thickness ~50 $\mu\text{m}$
Power dissipation	< 200 mW/cm <sup>2</sup>	operates at vacuum - cooling
Operation temperature	- 40°C to +30°C	temperature gradient 5 K
Heavy Ion tolerance	10 Hz/mm <sup>2</sup>	
Rate (average/peak)	150/700 kHz/mm <sup>2</sup>	Fake hit rate < 10 <sup>-5</sup> pix / 5 $\mu\text{s}$
Time resolution	~5 $\mu\text{s}$	
Radiation hardness	~ 7x10 <sup>13</sup> n <sub>cq</sub> /cm <sup>2</sup> ~ 5 Mrad	radiation gradient 100% over one sensor area
Occupancy gradients in space		 (MVD TDR)
Beam intensity fluctuations in time		 (HADES, GSI)

Vienna Conference on Instrumentation, 2022

A. Dorokhov, IPHC, Strasbourg, France

### Key points

Time resolution

- MIMOSIS 5  $\mu\text{s}$
- Ultimate (M28) 185,6  $\mu\text{s}$

MIMOSIS – global shutter  
Ultimate (M28) – rolling shutter

MIMOSIS active area:  
Active area: 30.935x13.520 mm<sup>2</sup>  
Pixel pitch: 26.88 x 30.24  $\mu\text{m}^2$

two sensors per plane:  
Active area: about 30x30 mm<sup>2</sup>  
(similar to FIRST vertex arrangement)

Add one station before target.

MIMOSIS2 arriving in Strasbourg those days