

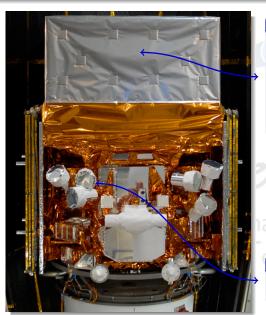
# THE SILICON STRIP TRACKER OF THE FERMI LARGE AREA TELESCOPE

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on behalf of the Fermi LAT collaboration

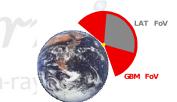
RD11, Firenze, July 6 2011

#### THE FERMI OBSERVATORY



#### Large Area Telescope (LAT)

- ▶ Pair conversion telescope.
- ► Energy range: 20 MeV-> 300 GeV
- ► Large field of view (≈ 2.4 sr): 20% of the sky at any time, all parts of the sky for 30 minutes every 3 hours.
- ► Long observation time: 5 years minimum lifetime, 10 years planned, 85% duty cycle.



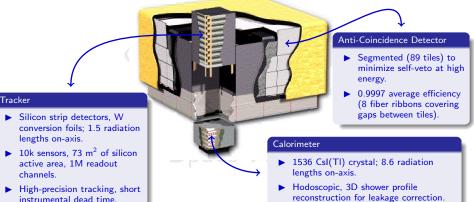
#### Gamma-ray Burst Monitor (GBM)

- ▶ 12 Nal and 2 BGO detectors.
- ► Energy range: 8 keV-40 MeV.

# THE LARGE AREA TELESCOPE

#### Large Area telescope

- ▶ Overall modular design.
- ▶ 4 × 4 array of identical towers (each one including a tracker and a calorimeter module).
- ► Tracker surrounded by an Anti-Coincidence Detector (ACD)



# Instrument design drivers

#### ► Science design drivers

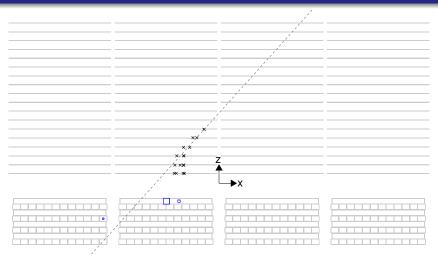
- ▶ Effective area and angular resolution: design of the tracker converter
- ▶ Energy range and resolution: thickness and design of the calorimeter
- Charged particle background rejection: mainly driving the ACD design, but also impacts the tracker and calorimeter design, along with the trigger and data flow

#### ► Mission design drivers

- ► Launcher vehicle: instrument footprint (1.8 × 1.8 m²)
- ► Mass budget (3000 kg): maximum depth of the calorimeter
- Power budget (650 W overall): maximum number of electronics channels in the tracker—i.e. strip pitch and number of layers
- Launch and operation in space: sustain the vibrational loads during the launch, sustain thermal gradients, operate in vacuum

# TRACKER RECONSTRUCTION: LOW ENERGY

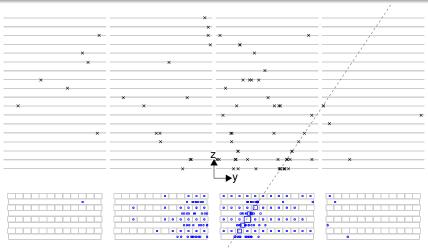
Simulated 80 MeV gamma-ray



- ► Angular resolution dominated by multiple scattering
  - ► Call for thin converters...
  - ...but need material to convert the gamma-rays!

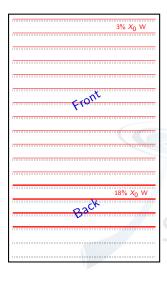
# Tracker reconstruction: high energy

SIMULATED 150 GEV GAMMA-RAY



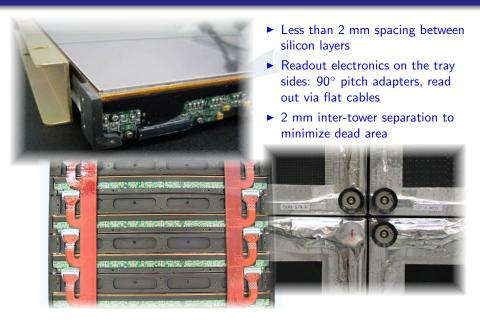
- ► Angular resolution determined by hit resolution and lever arm
  - ► Call for fine SSD pitch, but power consumption is a strong constraint
- ▶ Backsplash from the calorimeter also a potential issue

#### Basic tracker design



- ▶ 19 tray structures
  - Basic mechanical framework
- ► 18 x-y detection planes
  - Single sided SSDs, below the W foils
- ► Front: 12 planes with 0.03 X<sub>0</sub> converter
  - ▶ Best angular resolution
- ▶ Back: 4 planes with 0.18 X<sub>0</sub> converters
  - Increase the conversion efficiency
- ▶ Bottom: 2 planes with no converter
  - ► Tracker trigger needs at least 3 *x-y* layers
- ▶ Total depth:  $1.5 X_0$  on axis

# Tracker design: mechanics

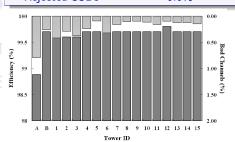


# THE SILICON STRIP DETECTORS



- ► 18 flight towers integrated and tested in 9 months
  - ► Flight Module A suffering from some processing issues during the set up of the assembly chain

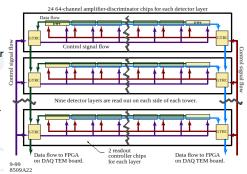
Coupling	AC
Outer size	$8.95 \times 8.95~\mathrm{cm}^2$
Strip pitch	228 $\mu$ m
Thickness	400 $\mu$ m
Depletion voltage	< 120 V
Leakage current	a few $nA/cm^2$ 150 V
Breakdown voltage	> 175 V
Bad channels	$\approx 10^{-4}$
# SSD tested	12500
# single strip tests	$\approx$ 30M
Rejected SSDs	0.6%



# THE TRACKER ELECTRONICS SYSTEM

#### ▶ Basic design

- ► 24 front-end chips and 2 controllers handle one Si layer
- Data can shift left/right to either of the controllers (can bypass a dead chip)
- Zero suppression takes place in the controllers (hit strips + layer OR TOT in the data stream)
- ► Two flat cables complete the redundancy



#### ► Key features

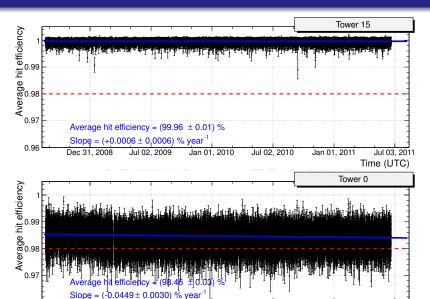
- ▶ Low power consumption ( $\approx 200 \ \mu \text{W/channel}$ )
- ▶ Low noise occupancy ( $\approx 1$  noise hit per event in the full LAT)
- ► Self-triggering (three *x*−*y* planes in a row, i.e. sixfold coincidence)
- Redundancy, Si planes may be read out from the right or from the left controller chip
- On board zero suppression

#### THE LAUNCH

THE SCIENCE MISSION JUST TURNED THREE



# HIT EFFICIENCY



Jan 01, 2010

Jul 02, 2010

Jan 01, 2011

Jul 03, 2011

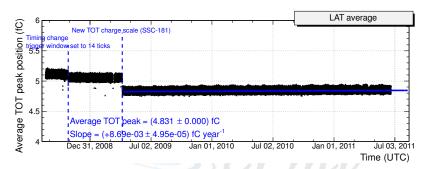
Time (UTC)

0.96

Dec 31, 2008

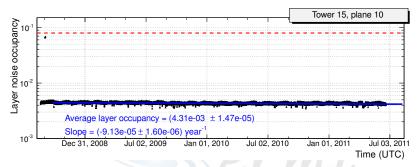
Jul 02, 2009

#### TIME OVER THRESHOLD



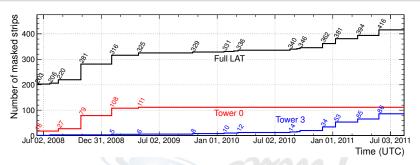
- ► Long term trending of the position of the MIP peak in the Tracker Time Over Threshold (averaged over the LAT)
- ► The two noticeable discontinuities are due to hardware/software changes
  - Analog signal remarkably stable (within much less than 1%) since the last of the two changes.

#### Noise occupancy



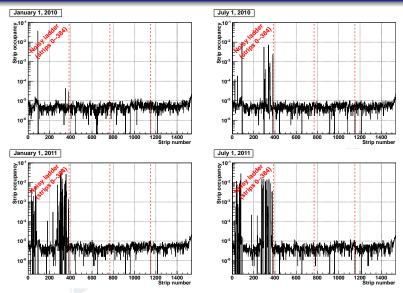
- ▶ Long term trending of the noise occupancy for a typical silicon layer
  - Measured accumulating counts on the silicon layers far from triggering towers (and cross-checked with dedicated periodic triggers)
- ▶ Noise occupancy at the level of  $4 \times 10^{-3}$  for a layer (1536 strips)
  - ▶ Translating into  $2-3 \times 10^{-6}$  at the single strip level (dominated by accidental coincidences)...
  - ... or 2-3 noise hits per event in the full LAT

# STRIP MASKS TRENDING



- ► Some 200 noisy strip masked prior to launch (0.02%)
- ▶ 213 additional noisy strips masked over the first three years of mission, for a total of 416 (0.05%)
- ► Two major contributors
  - Tower 0 (Fligth Module A): the first one being assembled, suffering from some processing issues—showed some evolution throughout the first year
  - ► Tower 3 (Flight Module 15): noise issue in one ladder—more on that later

#### A MINOR HARDWARE ISSUE



- ▶ Noise in one silicon ladder steadily increasing since January 2010
  - ► Really only one of the 2304 silicon ladders in the LAT

#### A minor hardware issue

To be debugged in space

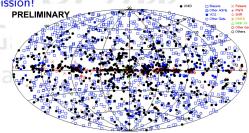


- One power supply per tower
  - We only monitor the currents at the tower level (i.e. each HV line is biasing  $36 \times 4 = 144$  silicon ladders)
  - ► Not trivial to measure a relative increase in the leakage current at the level of a single ladder
- ► Test runs with reduced bias HV (40, 60, 80 V vs. nominal 105 V)
  - Normal data taking, charge injection calibration
- ▶ No obvious root cause identified
  - ▶ Even if we lose the entire ladder it's less than 0.05% of the tracker
  - No evidence of similar phenomena in any other part of the LAT

# CONCLUSIONS

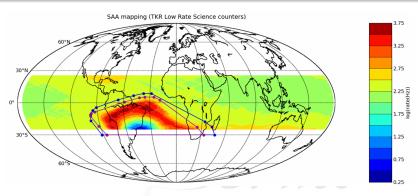
- The LAT tracker is the largest solid-state tracker ever built for a space application
  - ▶ 73 m² of single-sided silicon strip detectors
  - ► Almost 900,000 independent electronics channels
- ► All design goals met with large margins
  - ► Single-plane hit efficiency in excess of 99%
  - ▶ Noise occupancy at the level of 1 channel per million
  - ▶ 160 W of power
- ▶ It has served beautifully the science of the first three years
  - ▶ No noticeable degradation of performance observed

► Fermi is a 5 to 10 years mission!



# SPARE SLIDES

#### Mapping of the SAA



- ► The South Atlantic Anomaly is a region with a high density of trapped particles (mostly low-energy protons)
- ► We do not take physics data in the SAA (ACD HV is lowered) but we do record the trigger rate from CAL and TKR
- ► The mapping of the SAA was one of the goals of the commissioning phase, now routinely monitored

#### Trigger

#### ► Hardware trigger at the single tower level

- All subsystems contribute
- TKR: three consecutive xy planes in a row hit
- ► CAL\_LO: single CAL log with more than 100 MeV (adjustable)
- ► CAL\_HI: single CAL log with more than 1 GeV (adjustable)
- ROI: MIP signal in one of the ACD tiles close to the triggering TKR tower
- ► CNO: heavy ion signal in one of the ACD tiles

#### ► Event readout

- Each particular combination of trigger primitives is mapped into a so called trigger engine (determines hardware prescale factors, and readout mode)
- Upon a valid L1 trigger the entire detector is read out

# Onboard filter

#### Filter basics

- Need software onboard filtering to fit the data volume into the allocated bandwidth
- ▶ Full instrument information available to the onboard processor
- Flexible, fully configurable (the following reflects the nominal science data taking setting)

#### ► Nominal implementation

- ► Each event is presented to up to 4 (adjustable) different filters
- ► GAMMA: rough photon selection (main source of science data)
- ► HIP: heavy ions (continuously collected for calibration purposes)
- MIP: used in calibration runs
- DGN: configured to provide a prescaled (×250) unbiased sample of all trigger types
- Final gamma selection performed on ground (see the following)