Taming IBPs with Transverse Integration @ High precision for hard processes



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HP2 2024, 12/09/2024





Precision era • @ colliders

- High-Lumi upgrade of LHC :
- theory and experiments must have comparable uncertainties
 - needed: %-level accuracy:
 - perturbation theory @ NNLO and often N3LO
 - diagrams with increasing no. of loops, legs & mass scales
- $O(\partial_s^2)$:



Precision physics as

- test of the Standard model
- gate to new physics





Part O: Background





A dictionary for Feynman integrals

- LEGO[®] blocks of perturbative QFT beyond tree level
- Key ingredient of phenomenological predictions
- Rich and interesting mathematical structures

Integral Family : defined by a list of generalised

Integral belonging to a family

$$I_{F;\vec{a}}[N] = I_{F;a_1\cdots a_n}[N] = \int \prod_{j=1}^{\ell} d^D k_j \frac{N}{\prod_{j=1}^n D_{F,j}^{a_j}}, \quad N = \text{ polynomial in } k_i$$

Numerators are removed via tensor reduction

 $\rightarrow N = 1$ for IBPs

denominators
$$F \leftrightarrow \{D_{F,1}, ..., D_{F,n}\}$$

$$I_{F;\vec{a}} = \int \prod_{j=1}^{\ell} d^D k_j \frac{1}{\prod_{j=1}^{n} D_{F,j}^{a_j}} \qquad D_{F,j} = l_j^2 - m_j^2$$
$$l_j \text{ linear combination}$$

We distinguish:

- Proper denominators: D_F
- Irreducible scalar products

- Corner integral of a sector: integral with $a_i \in \{0,1\}$

Generalised denominators have the form

$$D_{F,j} = l_j \cdot v_j - m_j^2$$

of k_i , v_j linear combination of p_j

s (ISPs):
$$D_{F,j}$$
 such that $a_j > 0$
s (ISPs): $D_{F,j}$ such that $a_j \le 0$

• Sectors, $S_{F,\vec{a}}$: integrals with the same set of proper denominators

Iteratively, one can define also subsectors/parent sectors







- Extremely large number of integrals contributing to an amplitude
- Properties/symmetries of an amplitude manifest only after the reduction
- Important for the calculation of the integrals

Integral decomposition

Integral decomposition

Reduction into a basis of linearly independent master integrals $\{G_i\} \subset \{I_i\}$

$$I_{j} = \sum_{k} c_{jk} G_{k \text{ int}}^{\text{mas}}$$

$$k \text{ rational}_{\text{coefficients}}$$

minimal linearly independent set $\{G_i\}$



ter egrals





Feynman integrals in dimensional regularization obey linear relations, e.g. Integration By Parts identities + Lorentz Invariance ids, symmetry relations, ...

$$\int \left(\prod_{i=1}^{\ell} d^{\mathrm{D}} k_i\right) \frac{\partial}{\partial k_i^{\mu}} \left(\frac{v_j^{\mu}}{D_1^{a_1} \dots D_n^{a_n}}\right) = 0, \qquad v^{\mu} = \begin{cases} p_i^{\mu} = \text{external}\\ k_i^{\mu} = \text{loop} \end{cases}$$

reduction as solution of a large and sparse system of identities

Laporta algorithm

[Chetyrkin, Tkachov (1981), Laporta (2000)]

Computational bottleneck in state-of-the-art calculations



Part 1: The main idea



Transverse integration id.s

- A way to simplify the identities in the Laporta system
- Formulation in terms of angular integrations in [Mastrolia, Peraro, Primo 2017]

- Already used in tensor/ integrand reduction and numerical unitarity
- Impact on IBP reduction still unexplored

- Idea:
- Given a family, map its sectors with fewer external legs (or that are factorizable into fewer loops products) to new families having fewer invariants & fewer irreducible scalar products \Rightarrow simpler identities

Application/1 \rightarrow tested on cutting edge examples



Application/ $2 \rightarrow$ only tested in simple cases (for now!)







Part 2: Practical example





Practical example

Double box family with one external mass integral

$$s = (p_1 + p_2)^2$$
, $t = (p_1 + p_3)^2$, $m^2 = p_4^2$, $p_1^2 = p_2^2 = p_3^2 = 0$

Top sector $S_{db;111111100}$



Double box (db)

$$D_{db,1} = k_1^2 \qquad D_{db,2} = (k_1 + p_1)^2$$
$$D_{db,4} = (k_1 + k_2)^2 \qquad D_{db,5} = k_2^2$$
$$D_{db,7} = (k_2 - p_1 - p_2)^2 \qquad D_{db,8} = k_2 \cdot p_1$$

9 generalised den.s 7 proper denominators 2 ISPs 3 invariants

$$D_{db,3} = (k_1 + p_1 + p_2)^2$$
$$D_{db,6} = (k_2 - p_1 - p_2 - p_3)^2$$
$$D_{db,9} = k_1 \cdot (-p_1 - p_2 - p_3)$$

Sector *S*_{db:11110100}

BUT if we consider the boxtriangle as a NEW family = TI family ...

Box triangle (bt) $D_{bt,1} = k_1^2$

- $D_{bt,4} = (k_1 + k_2)^2$
- $D_{\text{bt},2} = (k_1 + p_1)^2$ $D_{\text{bt},3} = (k_1 + p_1 + p_2)^2$ $D_{bt,5} = k_2^2$ $D_{\mathbf{bt},7} = k_2 \cdot p_2$

Sector with fewer ext legs

9 generalised den.s 6 proper denominators **3 ISPs** 3 invariants

$a_{6,8,9} \leq 0.$

7 generalised den.s 6 proper denominators 1 ISPs 1 invariant

 $D_{\text{bt.6}} = (k_2 - p_1 - p_2)^2$







- Numerator needs to be mapped to generalised denominators of new family bt
- Mapping can be done via transverse integration

We have the map...

 $I_{\mathrm{db};a_1a_2a_3a_4a_5a_6a_7a_8a_9} = I_{\mathrm{bt};a_1a_2a_3a_4a_5a_70} [D_{\mathrm{db},6}^{-a_6} D_{\mathrm{db},8}^{-a_8} D_{\mathrm{db},9}^{-a_9}]$





How to do transverse integration

$$v^{\mu} = v^{\mu}_{\parallel} + v^{\mu}_{\perp}, \quad v^{\mu}_{\parallel} =$$

$$R^{\mu}_{\mu} = R^{\mu}_{\mu} + v^{\mu}_{\mu}, \quad v^{\mu}_{\parallel} =$$

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$v_{\perp} \cdot p_i = 0, \qquad v \cdot p_i = v_{\parallel} \cdot p_i$

 $p_{1,\perp}^{\mu} = p_{2,\perp}^{\mu} = 0$

Decomposition of a vector in parallel and transverse component

 $c_1 p_1^{\mu} + c_2 p_2^{\mu}$

Parallel space spanned by the external legs of the new bt family





Coefficients of the parallel space decomposition found as $\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \frac{2}{s} \begin{pmatrix} p_2 \cdot v \\ p_1 \cdot v \end{pmatrix} \qquad v_{\parallel}^{\mu} = c_1 p_1^{\mu} + c_2 p_2^{\mu}$

 $V = V_{II} + V_{L}$



In practice

First, rewrite the extra scalar products of db as functions of the ones of bt



We are left with integrals of the family bt of the form

 $I_{\text{bt};\vec{a}}[(k_1 \cdot p_3)^{\beta_1} (k_2 \cdot p_3)^{\beta_2}]$

 $D_{db.6} = m^2 - s + D_{bt.6} - 2(k_2 \cdot p_3)$ $D_{db,8} = s/2 + D_{bt,5}/2 - D_{bt,6}/2 - D_{bt,7}$ $D_{db,9} = s/2 + D_{bt,1}/2 - D_{bt,3}/2 - (k_1 \cdot p_3)$



Rewrite the scalar products as

 $(k_1 \cdot p_3) = (k_1 \cdot p_{3,\parallel}) + (k_{1,\perp} \cdot p_3)$ $(k_2 \cdot p_3) = (k_2 \cdot p_{3,\parallel}) + (k_{2,\perp} \cdot p_3)$

First RHS term becomes

 $(k_i \cdot p_{3,\parallel}) = \frac{2}{c} \left((k_i \cdot p_1)(p_2 \cdot p_3) + (k_i \cdot p_2)(p_1 \cdot p_3) \right)$



$$I_{\mathsf{bt};\vec{a}}[(k_{1,\perp} \cdot p_3)^{\beta_1}(k_{2,\perp} \cdot p_3)^{\beta_2}] = p_{3\,\mu_1} \cdots p_{3\,\mu_{\beta_1}} p_{3\,\nu_1} \cdots p_{3\,\nu_{\beta_2}} I_{\mathsf{bt};\vec{a}}[k_{1,\perp}^{\mu_1} \cdots k_{1,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\nu_2} \cdots k_{2,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\mu_{\beta_2}}k_{2,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\mu_{\beta_2}}k_{2,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\mu_{\beta_2}}k_{2,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\mu_{\beta_2}}k_{2,\perp}^{\mu_{\beta_$$



 $I_{\mathbf{bt};\vec{a}}[k_{1,\perp}^{\mu_1}\cdots k_{1,\perp}^{\mu_{\beta_1}}k_{2,\perp}^{\nu_1}\cdots$

Only scalar products remaining are $(k_{1,\perp} \cdot p_3) \& (k_{2,\perp} \cdot p_3)$

Tensor integrals can be decomposed in products of tensors and form factors





After this step we have only scalar products of $(k_{i,\perp} \cdot k_{j,\perp})$

with
$$(k_{i,\parallel} \cdot k_{j,\parallel}) = \frac{2}{s} \left((k_i \cdot p_1)(k_j \cdot p_2) + (k_i \cdot p_2)(k_j \cdot p_1) \right)$$

Successfully mapped db in bt



That we can rewrite using $(k_{i,\perp} \cdot k_{j,\perp}) = (k_i \cdot k_j) - (k_{i,\parallel} \cdot k_{j,\parallel})$





Flowchart < Ext.Legs Ext. Legs f(Dens(Dens × (Ki·Pj), Pj¢Ext.Legs($K_i \cdot P_j = \frac{K_i \cdot P_j}{f_j} + K_{i1} \cdot P_j$



 $(K_{i1}, P_j) = K_{i1}K_{i1} \cdots P_{in}P_{jn}$ $K_{i1} K_{i1} \cdots = Z_{ij} C_j T_j^{\mu \nu \cdots}$ Ki1·Kj1 KiIKjI = KiKj - KiIKjI

Part 3: Implementation & benchmarks





FiniteFlow implementation





Speedup vs traditional Laporta: 2.3x

Breakdown:





ttH pentabox

TI families with 4 external legs



- \star solving the simplified Laporta IBP system: 48%
- \star evaluating the coefficients of the TI identities: 22%
- \star evaluating the solution of the IBP system for the TI families: 23%

3%	

More examples ...



Conclusions...

- IBP reduction: key point ingredient of calculations
- Bottleneck for state-of-the-art precision predictions
- Transverse integration
 - Build simpler identities to feed into the IBP system
 - Map into a new family with fewer invariants and fewer ISPs :
 - \Rightarrow easier identities
 - Substantial performance improvements in cutting-edge examples
- ...& outlook
- Combination with syzygy techniques Implementation of factorizable sectors
- Optimizations + release of public package





Thank you for your attention!

