Taming IBPs with Transverse Integration @ High precision for hard processes

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Precision era @ colliders

• Precision physics as

- test of the Standard model
- gate to new physics

- High-Lumi upgrade of LHC :
- theory and experiments must have comparable uncertainties
	- needed: %-level accuracy:
		- perturbation theory @ NNLO and often N3LO
		- diagrams with increasing no. of loops, legs & mass scales

Part 0: Background

$$
I_{F;\vec{a}}[N] = I_{F;a_1\cdots a_n}[N] = \int \prod_{j=1}^{\ell} d^D k_j \frac{N}{\prod_{j=1}^n D_{F,j}^{a_j}}, \quad N = \text{ polynomial in } k_i
$$

- LEGO® blocks of perturbative QFT beyond tree level
- Key ingredient of phenomenological predictions
- Rich and interesting mathematical structures

Integral Family : defined by a list of generalised

• Integral belonging to a family

A dictionary for Feynman integrals

Numerators are removed via tensor reduction

 \rightarrow $N=1$ for IBPs

denominators
$$
F \leftrightarrow \{D_{F,1}, ..., D_{F,n}\}
$$

• Iteratively, one can define also subsectors/parent sectors

$$
D_{F,j} \text{ such that } a_j > 0
$$

ucts (ISPs):
$$
D_{F,j} \text{ such that } a_j \le 0
$$

$$
I_{F;\vec{a}} = \iiint_{j=1}^{l} d^D k_j \frac{1}{\prod_{j=1}^{n} D_{F,j}^{a_j}}
$$

$$
l_j \text{ line}
$$

We distinguish:

- Proper denominators: D_F
- Irreducible scalar products

- \bullet Sectors, $S_{F, \vec{a}}$: integrals with the same set of proper denominators
	-
- Corner integral of a sector: integral with $a_j \in \{0,1\}$

$$
D_{F,j} = l_j^2 - m_j^2
$$

$$
D_{F,j} = l_j \cdot v_j - m_j^2
$$

ear combination of k_j , v_j linear combination of p_j

• Generalised denominators have the form

Integral decomposition

- Extremely large number of integrals contributing to an amplitude
- Properties/symmetries of an amplitude manifest only after the reduction
- Important for the calculation of the integrals

why?

Integral decomposition

Reduction into a basis of linearly independent master integrals {*Gj* } ⊂ {*Ij* }

$$
I_j = \sum_{k} c_{jk} G_k^{\text{mas}}
$$

$$
k_{\text{rational coefficient}}
$$

 ${G_i}$ = minimal linearly independent set $\} =$

ter egrals

Computational bottleneck in state-of-the-art calculations

Laporta algorithm

reduction as solution of a large and sparse system of identities

Feynman integrals in dimensional regularization obey linear relations, e.g. Integration By Parts identities + Lorentz Invariance ids, symmetry relations, …

[Chetyrkin, Tkachov (1981), Laporta (2000)]

$$
\int \left(\prod_{i=1}^{\ell} d^D k_i\right) \frac{\partial}{\partial k_i^{\mu}} \left(\frac{v_j^{\mu}}{D_1^{a_1} \dots D_n^{a_n}}\right) = 0, \qquad v^{\mu} = \begin{cases} p_i^{\mu} = \text{ external} \\ k_i^{\mu} = \text{loop} \end{cases}
$$

Part 1: The main idea

Transverse integration id.s

- A way to simplify the identities in the Laporta system
- Formulation in terms of angular integrations in [Mastrolia, Peraro, Primo 2017]

- Already used in tensor/ integrand reduction and numerical unitarity
- Impact on IBP reduction still unexplored
- Idea :
- Given a family, map its sectors with fewer external legs (or that are factorizable into fewer loops products) to new families having fewer invariants & fewer irreducible scalar products ⇒ simpler identities

$Application/1 \rightarrow tested$ on cutting edge examples

Application/2 \rightarrow only tested in simple cases (for now!)

Part 2: Practical example

Practical example

Double box family with one external mass integral

9 generalised den.s 7 proper denominators 2 ISPs 3 invariants

$$
s = (p_1 + p_2)^2, \quad t = (p_1 + p_3)^2, \quad m^2 = p_4^2, p_1^2 = p_2^2 = p_3^2 = 0
$$

Top sector $S_{db};111111100$

Double box (db)

$$
D_{\text{db},1} = k_1^2
$$

\n
$$
D_{\text{db},2} = (k_1 + p_1)^2
$$

\n
$$
D_{\text{db},7} = (k_1 + k_2)^2
$$

\n
$$
D_{\text{db},7} = (k_2 - p_1 - p_2)^2
$$

\n
$$
D_{\text{db},8} = k_2 \cdot p_1
$$

$$
D_{\text{db},2} = (k_1 + p_1)^2 \qquad D_{\text{db},3} = (k_1 + p_1 + p_2)^2
$$

\n
$$
D_{\text{db},5} = k_2^2 \qquad D_{\text{db},6} = (k_2 - p_1 - p_2 - p_3)^2
$$

\n
$$
D_{\text{db},8} = k_2 \cdot p_1 \qquad D_{\text{db},9} = k_1 \cdot (-p_1 - p_2 - p_3)
$$

Sector $S_{db};111110100$

BUT if we consider the boxtriangle as a NEW family = TI family ...

Sector with fewer ext legs

9 generalised den.s 6 proper denominators 3 ISPs 3 invariants

 $a_{6,8,9} \leq 0.$

7 generalised den.s 6 proper denominators 1 ISPs 1 invariant

 $D_{\text{Dt},6} = (k_2 - p_1 - p_2)^2$

Box triangle (bt)

- $D_{\text{bt},1} = k_1^2$
- $D_{\text{bt,4}} = (k_1 + k_2)^2$
- $D_{\text{DL},2} = (k_1 + p_1)^2$ $D_{\text{DL},3} = (k_1 + p_1 + p_2)^2$ $D_{\text{bt},5} = k_2^2$ $D_{\mathbf{b} \mathbf{t},7} = k_2 \cdot p_2$

db,6 D_{ab}^{a} db,8 D_{ab}^{a} $\begin{array}{c} -a_9 \\ db, 9 \end{array}$

We have the map…

- Numerator needs to be mapped to generalised denominators of new family bt
- Mapping can be done via transverse integration

How to do transverse integration

$$
v^{\mu} = v_{\parallel}^{\mu} + v_{\perp}^{\mu}, \quad v_{\parallel}^{\mu} =
$$

$v_{\perp} \cdot p_i = 0, \qquad v \cdot p_i = v_{\parallel} \cdot p_i \qquad \text{for } i = 1,2$

Decomposition of a vector in parallel and transverse component

 $= c_1 p_1^{\mu} + c_2 p_2^{\mu}$

 p_1^{μ} 1,⊥ $= p_2^{\mu}$ 2,⊥

Parallel space spanned by the external legs of the new bt family

$\sqrt{2}$ *c*1 $\begin{pmatrix} 1 \\ 2 \end{pmatrix} =$ 2 *s* ($p_2 \cdot v$ $p_1 \cdot v)$ Coefficients of the parallel space decomposition found as v_{\parallel}^{μ} ∥ $= c_1 p_1^{\mu} + c_2 p_2^{\mu}$

 $\sqrt{\frac{\mu}{\epsilon}} \sqrt{\frac{\mu}{\mu}} + \sqrt{\frac{\mu}{\epsilon}}$

In practice

First, rewrite the extra scalar products of db as functions of the ones of bt

We are left with integrals of the family bt of the form

 $I_{\mathbf{b} \mathbf{t};\vec{a}}[(k_1 \cdot p_3)^{\beta_1} (k_2 \cdot p_3)^{\beta_2}]$

 $D_{\text{db,6}} = m^2 - s + D_{\text{bt,6}} - 2(k_2 \cdot p_3)$ $D_{db,8} = s/2 + D_{bt,5}/2 - D_{bt,6}/2 - D_{bt,7}$ $D_{\text{db},9} = s/2 + D_{\text{bt},1}/2 - D_{\text{bt},3}/2 - (k_1 \cdot p_3)$

 $(k_i \cdot p_{3, ||}) =$ 2 $\frac{1}{s}((k_i \cdot p_1)(p_2 \cdot p_3) + (k_i \cdot p_2)(p_1 \cdot p_3)$)

Rewrite the scalar products as

 $(k_1 \cdot p_3) = (k_1 \cdot p_{3,||}) + (k_{1,\perp} \cdot p_3)$ $(k_2 \cdot p_3) = (k_2 \cdot p_{3,||}) + (k_{2,1} \cdot p_3)$

First RHS term becomes

$$
I_{\mathbf{D} \mathbf{t};\vec{a}}[(k_{1,\perp} \cdot p_3)^{\beta_1} (k_{2,\perp} \cdot p_3)^{\beta_2}] = p_{3\mu_1} \cdots p_{3\mu_{\beta_1}} p_{3\nu_1} \cdots p_{3\nu_{\beta_2}} I_{\mathbf{D} \mathbf{t};\vec{a}}[k_{1,\perp}^{\mu_1} \cdots k_{1,\perp}^{\mu_{\beta_1}} k_{2,\perp}^{\nu_2} \cdots k_2^{\nu_{\beta_{\beta_2}}}]
$$

*I*bt;*^a* $[k_1^{\mu_1}]$ \perp ⋯*k μβ*1 $\chi_{1,1}^{\mu_{\beta_{1}}} k_{2,\perp}^{\nu_{1}}$

Only scalar products remaining are $(k_{1,\perp} \cdot p_3)$ & $(k_{2,\perp} \cdot p_3)$

$$
K_i^{\mu} N_j \cdots = \sum_j C_j \prod_j^{\mu \nu} \sum_{\substack{q_{e_{n_{s_{o_{r}}}}}} \\ \eta_{o_{r}} \neq \eta_{o_{s_{o_{r}}}} \\ \eta_{o_{r}} \neq \eta_{o_{s_{o_{r}}}} \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \vdots \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \vdots \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \vdots \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \vdots \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \vdots \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \eta_{o_{r}} \neq \eta_{o_{r}} \\ \vdots \\ \eta_{o_{
$$

Tensor integrals can be decomposed in products of tensors and form factors

After this step we have only scalar products of $(k_{i,\perp} \cdot k_{j,\perp})$ That we can rewrite using

with
$$
(k_{i,||} \cdot k_{j,||}) = \frac{2}{s} ((k_i \cdot p_1)(k_j \cdot p_2) + (k_i \cdot p_2)(k_j \cdot p_1))
$$

Successfully mapped db in bt

 $(k_{i,\perp} \cdot k_{j,\perp}) = (k_i \cdot k_j) - (k_{i,\parallel} \cdot k_{j,\parallel})$

Flowchart < Ext. Legs 11 $(K_{i1}.P_{j})^{2} = K_{i1}^{2} K_{i1}^{2} \cdots P_{j1}^{2} P_{j2} \cdots$ Ext. Legs $K''_{i1} K'_{i1} ... = \sum_{j}^{l} C_{j} T'^{k}$ $f(Dens)$ Dens D $\int_{-x}^{y} \left(K_i \cdot P_j\right) P_j \notin \text{Ext-Legs}\left(\frac{1}{2}K_i\right)$ $Ki_1 \cdot kj_1$ Kilkj $L = K_i K_j - K_i y K_j y$ $K_i \cdot P_{\hat{g}} = K_i \cdot P_{\hat{g}} / \gamma + K_{i\perp} \cdot P_{\hat{g}})$

Part 3: Implementation & benchmarks

FiniteFlow implementation

ttH pentabox

Speedup vs traditional Laporta: 2.3x

Breakdown:

- ★ solving the simplified Laporta IBP system: 48%
- ★ evaluating the coefficients of the TI identities: 22%
- ★ evaluating the solution of the IBP system for the TI families: 23%

TI families with 4 external legs

More examples …

Conclusions…

- IBP reduction: key point ingredient of calculations
- Bottleneck for state-of-the-art precision predictions
- Transverse integration
	- Build simpler identities to feed into the IBP system
	- Map into a new family with fewer invariants and fewer ISPs :
		- ⇒easier identities
	- Substantial performance improvements in cutting-edge examples
- …& outlook
- Combination with syzygy techniques • Implementation of factorizable sectors
-
- Optimizations + release of public package

Thank you for your attention!

